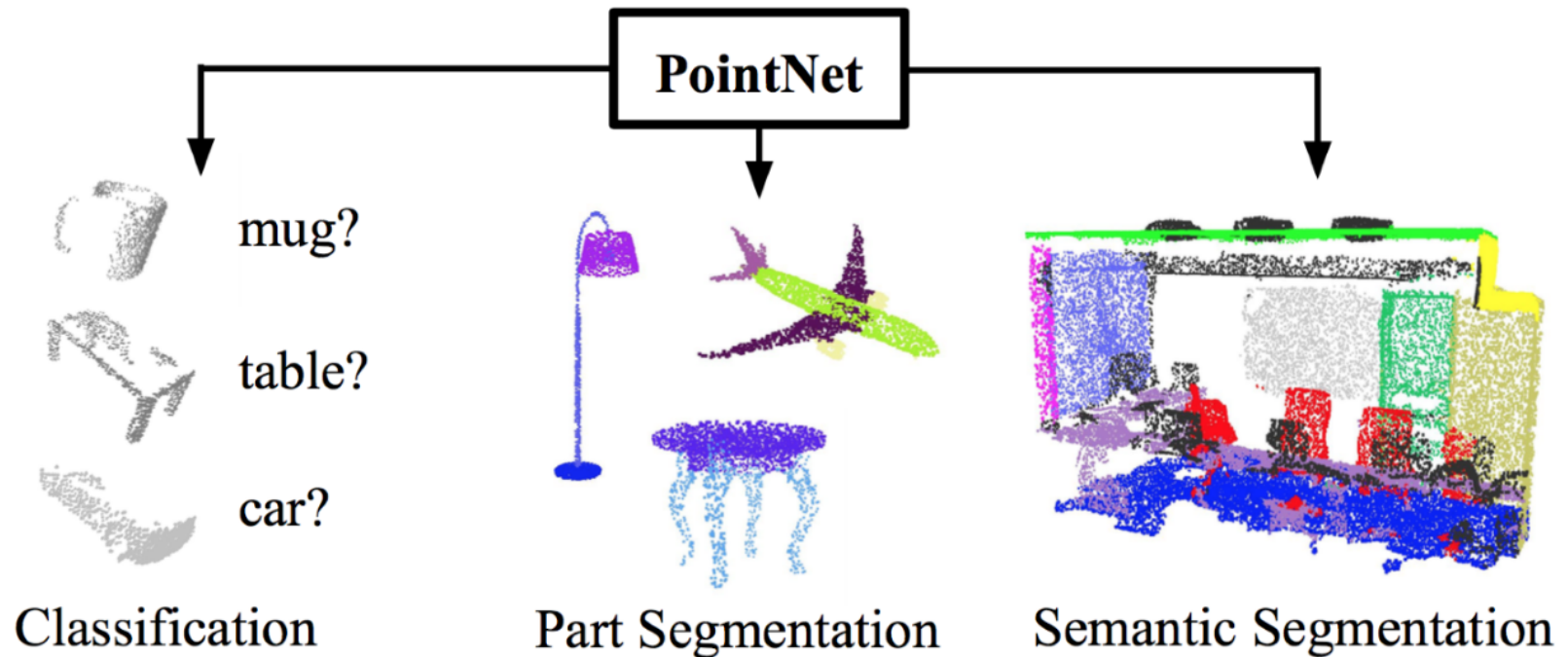


PointNet++: Deep Hierarchical
Feature Learning on Point Sets in a
Metric Space
NIPS 2017

Point Net

End-to-end learning for **scattered, unordered** point data

Unified framework for various tasks



Challenges

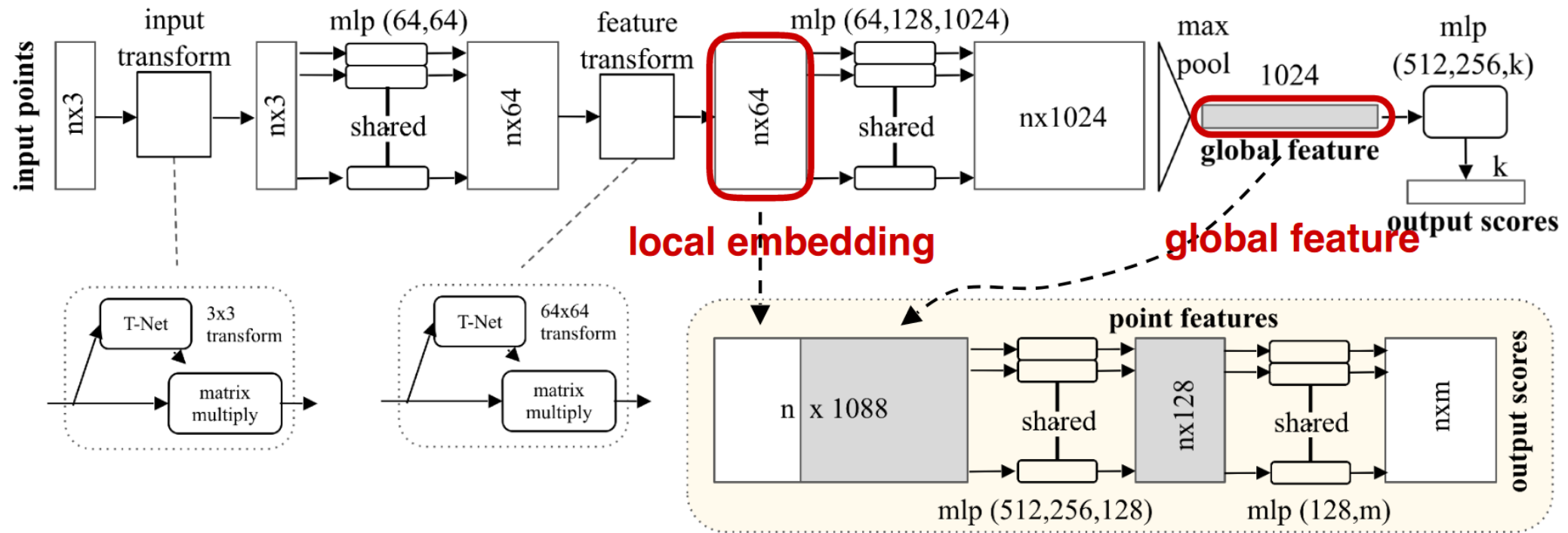
Unordered point set as input

Model needs to be invariant to $N!$ permutations.

Invariance under geometric transformations

Point cloud rotations should not alter classification results.

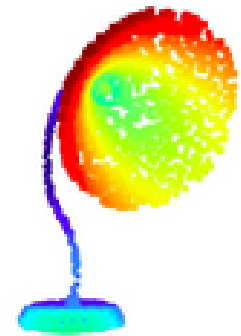
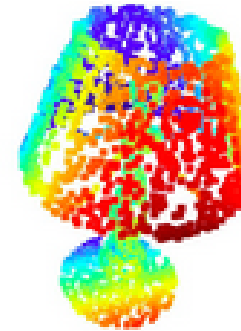
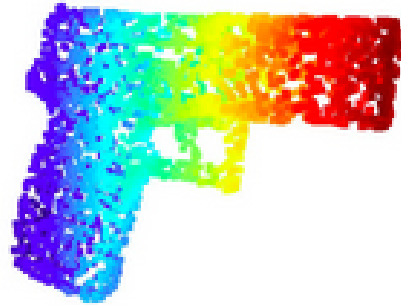
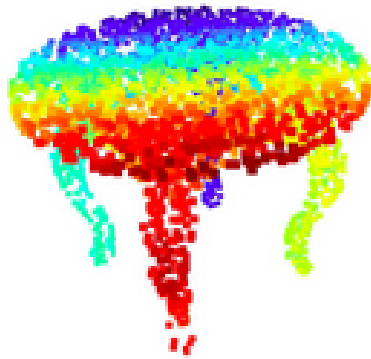
PointNet Network



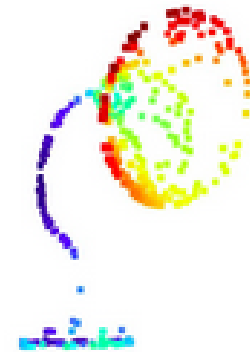
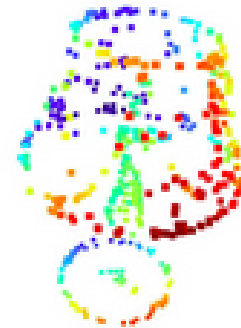
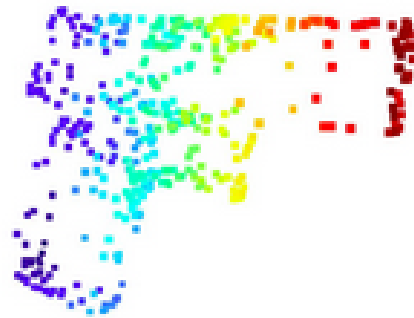
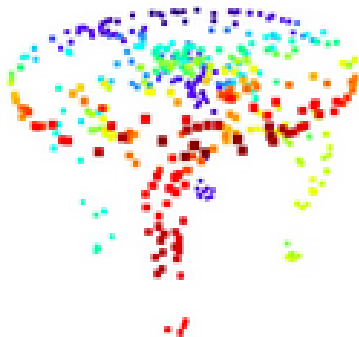
Limitations

Lack of local context

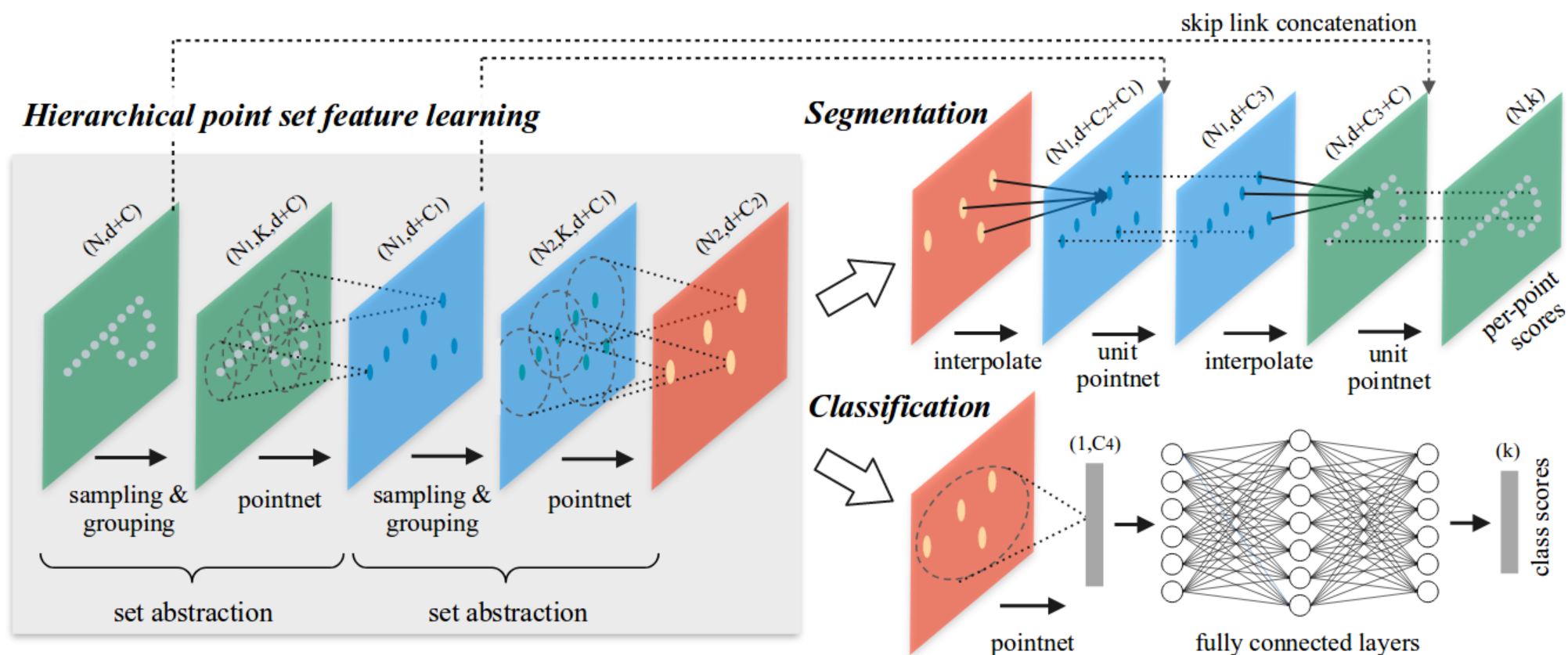
Original Shape



Critical Point Sets

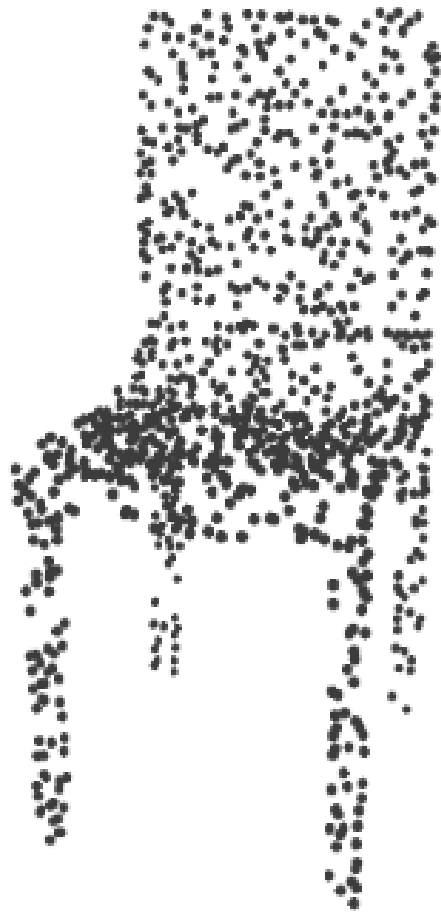


Farthest point sampling + Point net



Non-uniform sampling density

1024 points



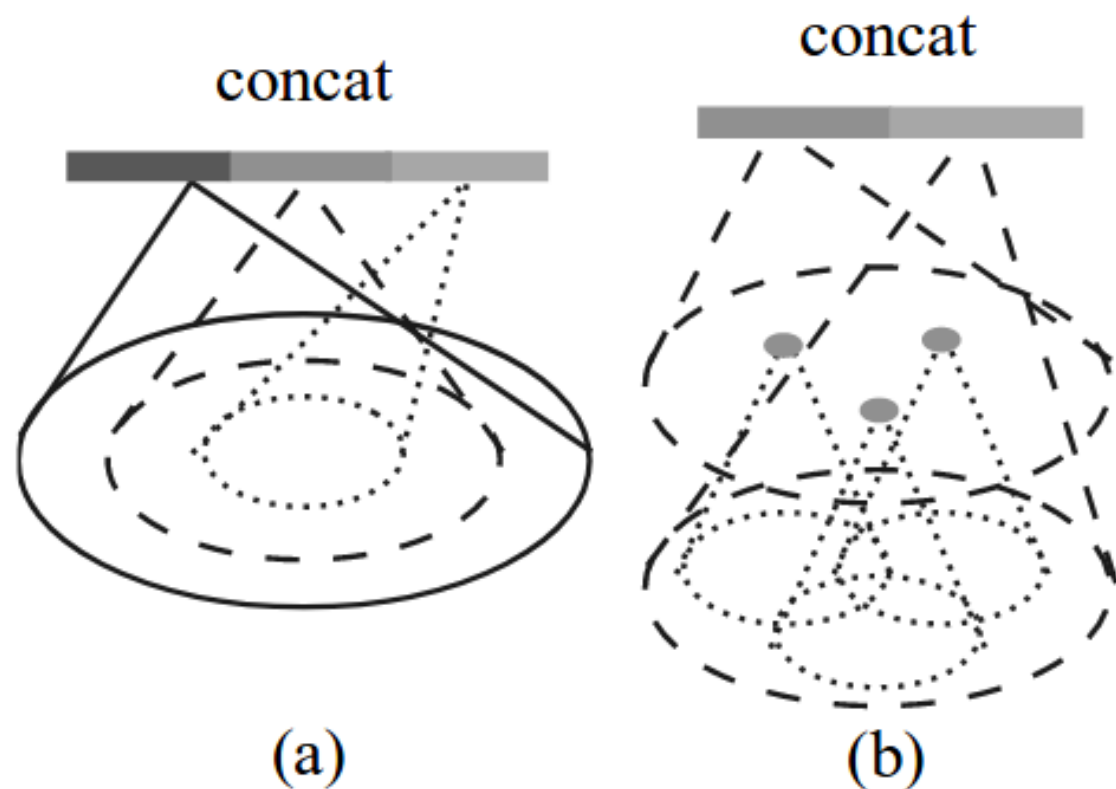
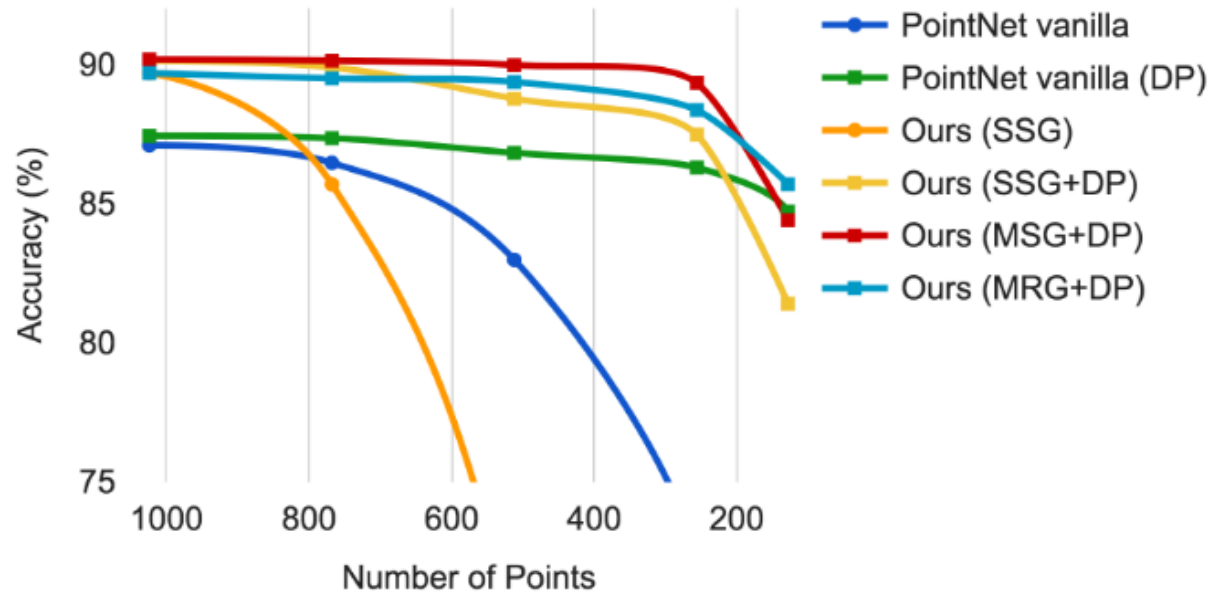


Figure 3: (a) Multi-scale grouping (MSG); (b) Multi-resolution grouping (MRG).

Classification results

| Method | Input | Accuracy (%) |
|-------------------------|-------|--------------|
| Subvolume [21] | vox | 89.2 |
| MVCNN [26] | img | 90.1 |
| PointNet (vanilla) [20] | pc | 87.2 |
| PointNet [20] | pc | 89.2 |
| Ours | pc | 90.7 |
| Ours (with normal) | pc | 91.9 |

Table 2: ModelNet40 shape classification.



Segmentation results

