Geometric Measure Theory Notes

My two primary sources are [Mag12] and [Sim14]. Monica Torres also has very help notes on her webpage here.

1 Lebesgue equals Hausdorff (3.9.23)

We follow (Thm 2.9, [Sim14]). Recall the definitions of Lebesgue and Hausdorff measures.

$$\mathscr{L}^n(A) = |A| := \inf\{\sum_{j=1}^{\infty} |R_j| : R_j \text{ is a open rectangle}, A \subset \cup_{j=1}^{\infty} R_j\},$$

$$\mathscr{H}^n_\delta(A) := \inf\{\sum_{j=1}^{\infty} \omega_n \left(\frac{\operatorname{diam} C_j}{2}\right)^n : \operatorname{diam}(C_j) < \delta, A \subset \cup_{j=1}^{\infty} C_j\},$$

and $\mathscr{H}^n(A) := \lim_{\delta \searrow 0} \mathscr{H}^n_\delta(A)$.

Theorem 1.1. *For every $\delta > 0$ and $A \subset \mathbb{R}^n$,*

$$\mathscr{H}^n(A) = \mathscr{H}^n_\delta(A) = |A|.$$

Proof. Taking $\delta \searrow 0$, it suffices to show $\mathscr{H}^n_\delta = \mathscr{L}^n$. Since taking closure does not affect diameter, we may assume C_k are closed. Note also $|E| = 0 \implies \mathscr{H}^n_\delta(E) = 0$ since we may inscribe a ball B_j with diameter $< \delta$ in each rectangle R_j.

($\mathscr{H}^n_\delta \le \mathscr{L}^n$) The idea here is to "uniformly eat up" all the measure A with finitely many pairwise disjoint balls, then iterate this algorithm *ad infinitum*.[1] Fix an arbitrary cover $\{R_j\}$ of A by open rectangles.

Step $k = 1$. For each j, consider a disjoint family of cubes $\{I_k\}$[2] with $\operatorname{diam}(I_k) < \delta$ such that the interiors of I_k are pairwise disjoint and $\cup I_k = R_j$. This is possible since R_j is an open set (Thm 1.4, [SS05]). For each k, inscribe a *closed* ball B_k into I_k such that $\operatorname{diam}(B_k) > \frac{1}{2}s_k$ where s_k is the side length of I_k [Figure 1]. This is obviously not sharp, but it doesn't matter. What does matter is that the most measure we've left off out is

$$|I_k - B_k| \le s_k^n - \omega_n(\frac{s_k}{4})^n = (1 - \frac{\omega_n}{4^n})s^k.$$

[1] i.e. Step 1 leaves $\frac{1}{2}$ the measure, step 2 leaves $\frac{1}{4}$ the measure, etc (these are not the correct constants, but the idea is right).

[2] I_k depends on j also, which we suppress from the notation. Note that I_k^j may intersect $I_k^{j'}$ for $j \neq j'$ - the pairwise disjoint condition is with respect to a fixed rectangle.

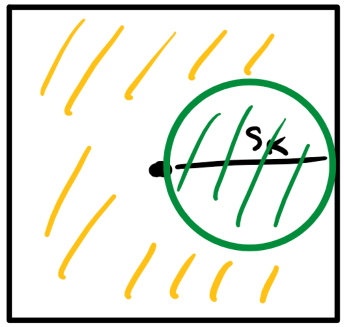

Figure 1: B_k must be bigger than the green ball.

Note the constant in front of s_k is uniform in k and strictly smaller than 1. Therefore,

$$|R_j - \cup_k B_k| = |\cup_k I_k - B_k| \leq (1 - \frac{\omega_n}{4^n}) \sum_k s^k = (1 - \frac{\omega_n}{4^n})|R_j|.$$

Thus, for each j, we may choose finitely many ball $B_j^1, ..., B_j^N$ such that the same inequality holds.

Step $k \geq 2$. For $k = 2$, we repeat the above argument but for $R_j - \cup_{k=1}^N B_j^k$ instead of R_j, which is *again an open set*. Repeat this construction for $k > 2$.

In total, for each j we get a countable disjoint collection of balls $\{B_j^k\}$ of R_j with radius $< \delta$ such that $|R_j - \cup_k B_j^k| = 0$, so $\mathscr{H}_\delta^n(R_j - \cup_k B_j^k) = 0$. Therefore,

$$\mathscr{H}_\delta^n(R_j) = \mathscr{H}_\delta^n(\cup_k B_j^k) \leq \sum_{k=1}^\infty \omega_n \left(\frac{\text{diam} B_j^k}{2} \right)^n = \sum_{k=1}^\infty |B_j^k| = |R_j|.$$

Thus

$$\mathscr{H}_\delta^n(A) \leq \sum_{j=1}^\infty \mathscr{H}_\delta^n(R_j) \leq \sum_{j=1}^\infty |R_j|,$$

and since R_j was an arbitrary cover, the result is shown.

($\mathscr{H}_\delta^n \geq \mathscr{L}^n$) The idea here is to use *Steiner symmetrization* to prove the isodiameteric inequality.

Lemma 1.2. *For any $A \subset \mathbb{R}^n$,*

$$|A| \leq \omega_n \left(\frac{diam A}{2} \right)^n.$$

Assuming the lemma, take C_j an arbitrary collection of sets which cover A, with $\text{diam}C_j < \delta$. Then,

$$|A| \leq |\cup_j C_j| \leq \sum_j |C_j| \leq \sum_j \omega_n \left(\frac{\text{diam}C_j}{2}\right)^n.$$

(of Lemma 1.2). It suffices to prove A compact since taking closure does not increase diameter. We sketch a symmetrization process as follows. For the hyperplane $H_i := \{x^i = 0\}$ for $i = 1, ..., n$, let $\xi_i \in H_i$ parameterize A in the sense that the fibers (under orthogonal projection to H_i) of A are at most 1-dimensional. We record the Lebesgue measure (length) of the fibers, the symmetrically distribute the length across ξ^i. This symmetrizes A across the hyperplane H_i, is diameter non-increasing, and the Lebesgue measure of A is constant. Furthermore, this preserves symmterizations across other hyperplanes. Thus, symmetrizing A across each hyperplane H_i produces a subset of the ball of radius $\frac{\text{diam}A}{2}$, proving the lemma. $\blacksquare$

Both inequalities are proven, and so the result follows. $\blacksquare$

2 Riesz Representation Theorem II (4.6.23)

We state and prove RRT.

Theorem 2.1. *If L is a bounded linear functional on $C_c(\mathbb{R}^n, \mathbb{R}^m)$, then its variation $|L|$ is a (scaler-valued) Radon measure on $\mathbb{R}^n$ and there exists a $|L|$-measurable function $g : \mathbb{R}^n \to \mathbb{R}^m$ such that $g = 1$ $|L|$-a.e., and for all $\phi \in C_c(\mathbb{R}^n, \mathbb{R}^m)$*

$$\langle L, \phi \rangle = \int_{\mathbb{R}^n} (\phi \cdot g) d|L|.$$

Moreover,

$$|L|(A) = \sup\{\int_{\mathbb{R}^n} \phi \cdot g d|L| : \phi \in C_c(A, \mathbb{R}^m), |\phi| \leq 1\}.$$

Proof. Recall the definition of the total variation (measure) of L.

$$|L| :=$$

Zack had previously shown that $|L|$ is Radon, and that a version of RRT holds for L^1. $\blacksquare$

3 Compactness and Regularization (4.27.23)

Maggi proves this by intertwining the functional analysis with the geometric measure theory. I think it's more clear to separate them out.

Let $(V, \|\cdot\|)$ be a normed linear space, and $B \subset V$ the unit ball defined by $\|\cdot\|$. Recall the following basic fact about the strong topology

Proposition 3.1. *A normed linear space V is finite dimensional iff the unit ball is compact.*

The proof is easy but irrelevant. What matters is the moral of the story - if we're out looking for compact sets in infinite dimensional space, the strong topology is not the correct one to look in. Even the most basic candidate for a compact set is not compact, so there are way too many open sets. We need a coarser topology.

Look not in V, but in its dual V^* together with its unit ball B^* defined by the operator norm. We see

$$B^* := \{\mu : V \to \mathbb{R} : |\mu(\phi)| \leq \|\phi\|\} = \{L : V \to \mathbb{R} : |\mu(\phi)| \leq 1 \text{ for } \|\phi\| \leq 1\}.$$

In other words, $\mu : B \to [-1, 1]$ and so $\mu \in [-1, 1]^B$; in other words, B^* canonically sits inside $[-1, 1]^B$, so it is compact in the subspace topology by Tychnoff's. However, the subspace topology agrees does *not* agree with the topology induced by the operator norm. The subspace topology oversees only that the evaluation pairing between V, V^* is continuous, and so it agrees with the weak star topology. That is, a sequence $\{\mu_i\}$ in V^* converges weak-$*$ to μ iff for every $\phi \in V$,

$$\mu_i \overset{*}{\rightharpoonup} \mu \iff \langle \phi, \mu_i \rangle \to \langle \phi, \mu \rangle,$$

where $\langle -, - \rangle$ denotes the evaluation pairing. This is known as *Banach-Alaoglu* and will serve as the backbone functional analysis tool for the compactness result for the space of Radon measures (which by RRT is dual to $V = C_c$ with a mildly strange topology). Truthfully, it's important that we have the sequential version of Banach-Alaoglu - this is true if V is *separable* (counterexamples exist otherwise) which is true in our case.

Theorem 3.2. *Given a sequence $\{\mu_i\}$ of Radon measures which are locally uniformly bounded, i.e. for $K \subset \mathbb{R}^n$ compact*

$$\sup_i \mu_i(K) < \infty,$$

then there exists a subsequence, upon reindexing, $\{\mu_k\}$ which weak-$*$ converge to a Radon measure. That is, by RRT,

$$\int_K \phi d\mu_i \to \int_K \phi d\mu,$$

for each $\phi \in C_c(\mathbb{R}^n)$.

Proof. The idea is basically sequential Banach-Alaoglu and RRT. We first give a construction of $\{\mu_k\}$ via a diagonalization procedure. Consider an exhaustion of $\mathbb{R}^n$ by balls $\{B_j\}$ centered at 0. Define functionals

$$F_{i,j}(\phi) := \int_{B_j} \phi d\mu_i,$$

for $\phi \in C_c(B_j)$. Linearity of $F_{i,j}$ is clear, and boundedness follows from the local uniformity assumption as

$$|F_{i,j}(\phi)| \leq \sup \phi \cdot \mu_i(B_j) \leq C \sup \phi,$$

where $C = C(j)$. By sequential Banach-Alaoglu, there is a functional $F_j : C_c(B_j) \to \mathbb{R}$ and a subsequence $\{F_{i',j}\}$ such that $F_{i',j} \overset{*}{\rightharpoonup} F_j$. By extracting subsequences subsequently, then selecting the diagonal subsequence, we extract the desired $\{\mu_k\}$ upon relabeling. We claim that $F = \lim_k \mu_k$. By construction, this limit is well-defined. Furthermore, by RRT we have

$$F(\phi) := \int_{\mathbb{R}^n} \phi d\mu,$$

for some Radon measure μ. For $\phi \in C_c(\mathbb{R}^n)$, take $\operatorname{spt}\phi \subset B_j$. Linearity follows since $F(\phi) = F_j(\phi)$, and F_j is linear. Boundedness follows from

$$|F(\phi)| \leq \sup \phi \cdot \mu(B_j) \leq C \sup \phi.$$

Here $C = C(j)$; nonetheless the weird topology we put on $C_C(\mathbb{R}^n)$ allows us to consider F as a bounded functional. ■

A similar statement holds for $\mathbb{R}^m$-valued measures by applying the above to the positive and negative part of each component to extract an $\mathbb{R}^m$-valued measure.

We very briefly discuss regularization. The basic theory of regularization of functions extends to measures as one expects. Given a Radon measure μ, define the function $\mu_\epsilon := \rho_\epsilon * \mu$ as

$$\mu_\epsilon(x) := \int_{\mathbb{R}^n} \rho_\epsilon(x-y) d\mu(y),$$

where ρ is a *regularization kernel*. One then makes this a measure by considering it as a density wrt the Lebesgue measure $\mu_\epsilon(x)dx$. The basic proposition that holds here is the following.

Proposition 3.3. *With the above notation, and $B_\epsilon(E)$ the ϵ-ball (neighborhood) of E,*

1. $\mu_\epsilon \overset{*}{\rightharpoonup} \mu$,
2. $|\mu_\epsilon| \overset{*}{\rightharpoonup} |\mu|$,
3. $|\mu_\epsilon|(E) \leq \mu(B_\epsilon(E))$.

Proof. The one word proof of 1 and 3 is Fubini's. 2 is more complicated, requiring an exercise we skipped. ■

4 Area Formula I (6.1.23)

For $f : \mathbb{R}^n \to \mathbb{R}^m$ an *injective, Lipschitz* function (throughout the section, $n \leq m$), set the *Jacobian* of f to be

$$Jf(x) := \begin{cases} \sqrt{\det(\nabla f(x)^* \nabla f(x))} & f \text{ is differentiable} \\ \infty & f \text{ is not differentiable.} \end{cases}$$

By Rademacher's theorem, Jf is integrable, and the area formula (in the case without considering multiplicity) calculates for Lebesgue measurable E the measures of images in terms of Jf as

$$\mathcal{H}^n(f(E)) = \int_E Jf(x)\, dx. \tag{1}$$

A useful consequence is the following.

Theorem 4.1. *If $f : \mathbb{R}^n \to \mathbb{R}^m$ is an injective, Lipschitz function, and $g : \mathbb{R}^m \to [-\infty, \infty]$ is Borel and if $g \geq 0$ or $g \in L^1(\mathbb{R}^m, \mathscr{H}^n \llcorner f(\mathbb{R}^m))$, then $g \circ f$ is Borel and*

$$\int_{f(\mathbb{R}^n)} g \, d\mathscr{H}^n = \int_{\mathbb{R}^n} g(f(x)) Jf(x) \, dx.$$

There are two obvious requirements that need to hold for the above formula to be true. First, if $E := \{x \in \mathbb{R}^n : Jf(x) = 0\}$, then $\mathcal{H}^n(f(E)) = 0$ (injectivity is dropped for this statement). This is the content of Proposition 8.7. The second is that under the above assumptions, $f(E)$ had better be $\mathcal{H}^n$ measurable.

Proposition 4.2. *If E is Lebesgue measurable in $\mathbb{R}^n$ and $f : \mathbb{R}^n \to \mathbb{R}^m$ is an injective Lipschitz function, then $f(E)$ is $\mathcal{H}^n$ measurable in $\mathbb{R}^m$.*

Proof. Assume E is bounded, and exhaust E by a sequence of compact sets $\{K_i\}$ wrt $\mathcal{L}^n$, so $|E - \cup K_i|$. Since f is Lipschitz, it's continuous and so $f(K_i)$ is compact and $\cup f(K_i)$ is Borel. Then,

$$\mathcal{H}^n(f(E) - \cup f(K_i)) = \mathcal{H}^n(f(E - \cup K_i)) \leq \mathrm{Lip} f^n \cdot \mathcal{H}^n(E - \cup K_i) = \mathrm{Lip} f^n \cdot |E - \cup K_i| = 0.$$

Note that injectivity is used in the first equality. ∎

Here, we used that Lipschitz functions play nicely with the Hausdorff measure in the sense that $\mathcal{H}^s(f(E)) \leq \mathrm{Lip} f^s \mathcal{H}^s(E)$, and is equal to the Lebesgue measure. For future reference, recall also that Hausdorff measure plays nicely with scaling in that $\mathcal{H}^s(rE) = r^s \mathcal{H}^s(E)$.

The next statement is to prove that area formula holds on arbitrary (not necessarily injective) linear functions $T : \mathbb{R}^n \to \mathbb{R}^m$.

Proposition 4.3. *If $T : \mathbb{R}^n \to \mathbb{R}^m$ linear, then for every $E \subset \mathbb{R}^n$,*

$$\mathcal{H}^n(T(E)) = JT \cdot |E|.$$

For this, we must first recall some linear algebra. Set $\mathrm{Lin}(n, m) := \{T : \mathbb{R}^n \to \mathbb{R}^m : T \text{ linear}\}$ and $\mathrm{Isom}(n, m) : \{P \in \mathrm{Lin}(n, m) : \langle Px, Py \rangle = \langle x, y \rangle\}$. We think of $\mathrm{Isom}(n, m)$ as the set of linear isometric embeddings - clearly all must be injective.

Lemma 4.4. *For $P \in Isom(\mathbb{R}^n, \mathbb{R}^m)$, we have $P^*P = id_n$.*

Proof. Recall $P^* := (\mathbb{R}^m)^* \to (\mathbb{R}^n)^*$ is precomposition with P. The composition P^*P is understood as the following isomorphism:

$$\mathbb{R}^n \xrightarrow{P} \mathbb{R}^m \to (\mathbb{R}^m)^* \xrightarrow{P^*} (\mathbb{R}^n)^* \to \mathbb{R}^n$$

$$x \mapsto Px \mapsto \langle Px, - \rangle \mapsto \langle Px, P- \rangle \mapsto x$$

where the last map is justified since the covector $y \mapsto \langle Px, Py \rangle = \langle x, y \rangle$ is metrically equivalent to the vector $y \in \mathbb{R}^n$. ∎

Since $P \in \mathrm{Isom}(n, m)$ is an isometry, both P and its adjoint P^* (orthogonal projections) have Lipschitz constant 1. Recall also the spectral theorem - every symmetric real-valued matrix diagonalizes with real eigenvalues (and orthogonal eigenspaces) and the polar decomposition - every linear map $T : \mathbb{R}^n \to \mathbb{R}^m$ can be realized as

$$T = PS$$

with $S \in \mathrm{Lin}(n, n)$ symmetric and $P \in \mathrm{Isom}(n, m)$ (both S, T are given explicitly in terms of the diagonalization of T). It turns out linear isometric embeddings do not change the fine structure of the geometry, and in a sense we'll make precise, all the change in the geometry happens with S.

(of 4.3.) Set $\kappa := D_{\mathcal{L}^n}\nu = \frac{\mathcal{H}^n(T(B))}{|B|}$ for $\nu(E) := \mathcal{H}^n(T(E))$ to be the density. The last equality is justified by scaling since for all $r > 0$,

$$\mathcal{H}^n(T(rB)) = r^n \mathcal{H}^n(T(B))$$
$$|rB| = r^n |B|.$$

It suffices to show the following two statements:

1. $\mathcal{H}^n(T(E)) = \kappa |E|$,
2. $JT = \kappa$.

First assume $\kappa = 0$ (T is non-injective). Then, $\mathcal{H}^n(T(B)) = 0 \implies \mathcal{H}^n(T(rB)) = 0$ for every $r > 0$ by linearity of T and so in the limit, $\mathcal{H}^n(\mathbb{R}^n) = 0$. By monotonicity of the measure, $\mathcal{H}^n(T(E)) = 0$ for every E.

Next, assume $\kappa > 0$ (T is injective). Since $E \mapsto \mathcal{H}^n(T(E))$ is Radon, by the decomposition theorem for measures, it suffices to show the equality is true on balls $B_r(x)$ for $r > 0$ and $x \in \mathbb{R}^n$. This follows by translation invariance and scaling, as

$$\begin{aligned}
\mathcal{H}^n(T(B_r(x)) &= \mathcal{H}^n(T(x + rB) \\
&= r^n \mathcal{H}^n(T(B)) \\
&= r^n \kappa |B| \\
&= \kappa |B_r(x)|,
\end{aligned}$$

which shows $\mathcal{H}^n(T(-)) \ll \mathcal{L}^n$ and identifies κ as the density.

Remark 4.5. For linear functions, non-injectivity is very easy to deal with as both sides evaluates to 0. We don't need to consider multiplicity for this case.

To show $JT = \kappa$, we first show for $T = PS$ and $S(Q) = E$ for a cube Q, we have $\frac{\mathcal{H}^n(P(E))}{|E|} = 1$, since

$$|E| = |P^* P(E)| \le Lip(P^*)^n |P(E)| = |P(E)| = \mathcal{H}^n(P(E)) \le Lip(P)^n |E| = |E|.$$

Therefore,

$$\kappa = \frac{\mathcal{H}^n(PS(Q))}{|Q|} = \frac{\mathcal{H}^n(P(E))}{|E|} \frac{|S(Q)|}{|Q|} = \frac{|S(Q)|}{|Q|}.$$

Note we can switch to other sets when defining density (Thm 3.22, [Fol13]). By homogeneity, we take Q to be the unit cube, so we must prove $JT = |S(Q)|$. Consider now the spectral decomposition of $Sv_i = \lambda_i v_i$. Using the fact that $\nabla T = T$ as T is linear, pullback is contravariant, and

$$\langle S^* S v_i, v_j\rangle = \langle S v_i, S v_j\rangle = \begin{cases} \lambda_i^2 & i = j \\ 0 & i \neq j, \end{cases}$$

we compute

$$JT = \sqrt{\det T^* T} = \sqrt{\det(S^* P^* P S)} = \sqrt{\det(S^* S)} = \sqrt{\prod_i |\lambda_i|^2} = |\det(S)| = |S(Q)|.$$

■

The next proof shows that the area formula does not see the *singular set* $\mathcal{S} := \{Jf = 0\}$. For notation, balls without mention to the dimension will be assumed to be dimension n, and without mention to the center will be assumed to be centered at the origin.

Proposition 4.6. *If $f : \mathbb{R}^n \to \mathbb{R}^m$ is Lipschitz, then on the singular set $\mathcal{S}$,*

$$\mathscr{H}^n(f(\mathcal{S})) = 0.$$

Proof. We will deduce $\mathscr{H}^n_\infty(f(\mathcal{S} \cap B_R)) = 0$ for arbitrary $R > 0$ (recall $\mathscr{H}^n \ll \mathscr{H}^n_\infty$). For $x \in \mathcal{S}$ and $1 > \epsilon > 0$,[3] by definition $\nabla f(x)$ is the linear map which satisfies the inequality

$$|f(x+v) - f(x) - \nabla f(x) v| < \epsilon |v|,$$

for $|v| < r(\epsilon, x)$. We can reinterpret the above (think of $f(x) = 0$.) in terms of small balls[4]: for $r = |v| < r(x, \epsilon)$, we have

$$f(B_r(x)) \subset f(x) + B_{\epsilon r}(\nabla f(x)(B_r)).$$

It would serve us well, therefore, to find a bound on the (translation-invariant) size of $B_{\epsilon r}(\nabla f(x)(B_r))$

Lemma 4.7. *For $0 < \epsilon < 1$ and $C = C(n, Lipf)$,*

$$\mathscr{H}^n_\infty(B_{\epsilon r}(\nabla f(x)(B_r))) \leq C r^n \epsilon.$$

The proof will use that $\mathcal{S}$ is singular by using a dimension drop argument, which produces the ϵ. Assuming this lemma, we get for $x \in \mathcal{S}$,

$$\mathscr{H}^n_\infty(f(B_r(x))) \leq C r^n \epsilon. \tag{2}$$

[3] As far as I can tell, the restriction to $1 > \epsilon$ is for polish.

[4] Compare this to the definition of continuity in terms of balls. f is continuous at x if for $r < r(\epsilon, x)$,

$$f(B_r(x)) \subset f(x) + B_\epsilon.$$

So if you can take a derivative, the information you gain is having a modulus of control over the error tolerance ϵr in terms on your parameter r.

We take the family $\mathcal{F}$ of balls with centers in $\mathcal{S} \cap B_R$,

$$\mathcal{F} := \{B_r(x) \subset \mathbb{R}^n : x \in \mathcal{S} \cap B_R, 0 < r < r(\epsilon, x)\}.$$

We cutoff $\mathcal{S}$ by B_R to have bounded centers; we may therefore apply Besicovitch covering theorem to extract subfamilies $\mathcal{F}_1, ..., \mathcal{F}_{\xi(n)}$ such that each $\mathcal{F}_i$ is countable, pairwise disjoint and $\mathcal{S} \cap B_R \subset \cup_{\xi(n)} \mathcal{F}_i$. By inequality 2,

$$\begin{aligned}
\mathscr{H}^n_\infty(f(\mathcal{S} \cap B_R)) &\leq \sum_{i=1}^{\xi(n)} \sum_{B_r(x) \in \mathcal{F}_i} \mathscr{H}^n_\infty(f(B_r(x))\\
&\leq C\omega_n \epsilon \sum_{i=1}^{\xi(n)} \sum_{B_r(x) \in \mathcal{F}_i} r^n\\
&\leq \frac{C\epsilon}{\omega_n} \sum_{i=1}^{\xi(n)} \sum_{B_r(x) \in \mathcal{F}_i} |B_r(x)|\\
&= \frac{C\epsilon}{\omega_n} \sum_{i=1}^{\xi(n)} \left| \bigcup_{B_r(x) \in \mathcal{F}_i} B_r(x) \right|\\
&\leq \frac{C\epsilon\xi(n)}{\omega_n} |B_1(\mathcal{S} \cap B_R)|.
\end{aligned}$$

Therefore, it suffices to prove the lemma.

(of Lemma 4.7). We first identify that $\nabla f(x)(B_r) \subset B^m_{r\mathrm{Lip}f} \cap \nabla f(x)(\mathbb{R}^n)$, where the right hand side is a disk $D_{r\mathrm{Lip}f}$ of dimension $k < n$ since $x \in \mathcal{S}$. This follows from homogeneity and $\|\nabla f\| \leq \mathrm{Lip}f$, since we may characterize $\mathrm{Lip}f$ as

$$\mathrm{Lip}f = \sup_{x \neq y} \frac{|f(x) - f(y)|}{|x - y|}.$$

Therefore, we must obtain a bound of the form

$$\mathscr{H}^n_\infty(B_\epsilon(D_s)) \leq C(n, s)\epsilon, \tag{3}$$

since since taking a neighborhood of a disk is linear,

$$\begin{aligned}
\mathscr{H}^n_\infty(B_{\epsilon r}(\nabla f(x)(B_r))) &\leq \mathscr{H}^n_\infty(B_{\epsilon r}(B^m_{r\mathrm{Lip}f} \cap \nabla f(x)(\mathbb{R}^n)))\\
&\leq r^n \mathscr{H}^n_\infty(B_\epsilon(B^m_{\mathrm{Lip}f} \cap \nabla f(x)(\mathbb{R}^n)))\\
&\leq r^n C(n, \mathrm{Lip}f))\epsilon.
\end{aligned}$$

To obtain inequality 3, we produce a covering of $B_\epsilon(D_s) \subset \mathbb{R}^k \times \mathbb{R}^{m-k}$ by translates of

$$B^k_{\epsilon s} \times B^{m-k}_\epsilon \subset \mathbb{R}^k \times \mathbb{R}^{m-k}.$$

Note that we need $C\epsilon^{-k}$ number of translates to cover $B_\epsilon(D_s) \approx B^k_s \times B^{m-k}_\epsilon$ for small ϵ, since area of B^k_s grows like s^k.[5] By Pythagorean theorem,

$$\mathrm{diam}(B^k_{\epsilon s} \times B^{m-k}_\epsilon)^2 = \mathrm{diam}(B^k_{\epsilon s})^2 + \mathrm{diam}(B^{m-k}_\epsilon)^2 = 4\epsilon^2(1 + s^2).$$

[5] e.g. For 2-dimensional disks, need (up to a dimensional constant) one-hundred small disks $D_{1/10}$ to cover one big disk D_1.

Since $k < n$, we have

$$\begin{aligned}
\mathscr{H}^n_\infty(B_\epsilon(D_s)) &\le \omega_n \sum_{\#\text{ translates}} \left(\frac{\operatorname{diam}(B^k_{\epsilon s} \times B^{m-k}_\epsilon)}{2} \right)^n \\
&= \omega_n C \epsilon^{-k} (2\epsilon^2(1+s^2))^{\frac{n}{2}} \\
&= C(n,s)\epsilon^{n-k} \\
&\le C\epsilon.
\end{aligned}$$

■

By the lemma, $\mathscr{H}^n(\mathcal{S}) = 0$. ■

5 Approximate Tangent Spaces (9.20.23)

We primarily follow [Mag12] Chapters 10.1-10.2, but mix it with Chapter 3 of [Sim14].

Set $k \le n$. We say a set $M \subset \mathbb{R}^n$ is **k-rectifiable** if there are countably many Lipschitz maps $f_i : \mathbb{R}^k \to \mathbb{R}^n$ such that

$$\mathscr{H}^k(M \setminus \cup_{i=1}^\infty f_i(\mathbb{R}^k)) = 0.$$

The point is that a k-rectifiable set is a measure-theoretic version of a k-dimensional manifold. We say M is **locally k-rectifiable** if in addition, for every compact K, $\mathscr{H}^k(K \cap M) < \infty$. The point here is that $\mathscr{H}^k \llcorner M$ is Radon (not just Borel) iff M is locally k-rectifiable. By Kirezbraun theorem and regularity properties of Hausdorff measure, M is k-rectifiable iff there exists Borel M_0 which is $\mathscr{H}^k$-null such that

$$M = M_0 \cup \bigcup_{i=1}^\infty f_i(E_i),$$

where $E_i \subset \mathbb{R}^k$ are bounded, Borel sets, and f_i is Lipschitz. This decomposition is highly non-unique, and we will exploit this in the following lemma by asking for a decomposition with nice regularity properties. Namely, for each $i \in \mathbb{N}$, the pair (f_i, E_i) will form a regular Lipschitz image. We say (f, E) form a **regular Lipschitz image** if

1. f is injective and differentiable on E, and $Jf > 0$ (i.e. $Jf \ne 0$ anywhere) on E.[6]
2. All points in E form a point of density 1 for E.
3. All point in E are Lebesgue points of ∇f ($\implies$ all points are Lebesgue points of Jf).
4. There exists a lower bound for $\operatorname{Lip}(f)$ on E.

Morally speaking, this is saying (f, E) is a Lipschitz injective immersion with good C^1 control. Such a decomposition of a rectifiable set M always exists (Theorem 10.1) by a number of previous theorems. Here are the quoted ones from [Mag12].

[6] So f is an injective immersion on E, but ∇f is not necessarily continuous.

1. **Theorem 2.10:** Borel sets admit inner/outer approximations, if the measure is a locally finite Borel measure.

2. **Theorem 8.7:** Singular values of a Lipschitz function are $\mathscr{H}^k$-null.

3. **Theorem 8.8:** The regular points of a Lipschitz function admit a countable, almost flat partition, on the function is injective on each leaf.

4. **Rademacher's:** Lipschitz functions are differentiable almost everywhere.

5. **Theorem 5.16:** Almost every point of a $L^1_{\text{loc}}(\mu)$ function satisfies MVP, if μ is Radon.

The point of the above four axioms is that they are sufficient conditions to make the following lemma true. This lemma classifies the approximate tangent space for the image of a regular Lipschitz function. Observe that if f is an C^1 injective immersion, the conclusion is clear. So the key point here is te drop in regularity.

Lemma 5.1. *Suppose $M^k = f(E)$ with (f, E) a regular Lipschitz image. Then, then for any $x \in M$, the approximate tangent space is given by*

$$T_xM = (\nabla f|_z)(\mathbb{R}^k),$$

where $x = f(z)$.

Proof. Recall that the approximate tangent plane to M at x is the k-plane $T_xM \subset \mathbb{R}^n$ such that

$$\lim_{r\downarrow 0} \frac{1}{r^k} \int_M \phi\left(\frac{y-x}{r}\right) \, d\mathscr{H}^k(y) = \int_{T_xM} \phi(y) \, d\mathscr{H}^k(y),$$

for all $\phi \in C_c(\mathbb{R}^n)$. This is the measure-theoretic version of a tangent space. By pulling back along f, and using change of variables,

$$\begin{aligned} \frac{1}{r^k} \int_M \phi\left(\frac{y-x}{r}\right) \, d\mathscr{H}^k(y) &= \frac{1}{r^k} \int_E \phi\left(\frac{f(\tilde{\omega}) - f(z)}{r}\right) Jf(\tilde{\omega}) \, d\tilde{\omega} \\ &= \int_{\mathbb{R}^k} \underbrace{\mathbb{1}_E(z + rw) \cdot \phi\left(\frac{f(z+rw) - f(z)}{r}\right) Jf(z+rw)}_{:=u_r(w)} dw \end{aligned}$$

Since $z \in E$ is a point of density 1 for E,

$$\lim_{r\downarrow 0} \int_{\mathbb{R}^k} \mathbb{1}_E(z + rw) \, dw = \mathbb{1}_E(z) = 1.$$

Since $z \in E$ is Lebesgue point for Jf,

$$\lim_{r\downarrow 0} \int_{\mathbb{R}^k} Jf(z + rw) \, dw = J(z).$$

Take the limit as $r \downarrow 0$ on both sides. For the moment, take on faith that DCT can be justified, and switch $\lim_{r\downarrow 0}$ with $\int$. Since ϕ is continuous and f is differentiable at $z \in E$,

$$\phi\left(\frac{f(z+rw) - f(z)}{r}\right) \xrightarrow{r\downarrow 0} \phi\left(\nabla f|_z w\right).^{7}$

[7] *Type check:* note that $\nabla f|_z$ is a linear map from $\mathbb{R}^k \to \mathbb{R}^n$ (the Jacobian), and w is a vector in $\mathbb{R}^k$.

Altogether,[8]

$$\begin{aligned}
\lim_{r\downarrow 0}\int_{\mathbb{R}^k} u_r(w)\,dw &= \int_{\mathbb{R}^k}\phi(\nabla f|_z w)Jf(z)\,dw \\
&= \int_{\mathbb{R}^k}\phi(\nabla f|_z w)J(\nabla f|_z)(w)\,dw \\
&= \int_{\nabla f|_z(\mathbb{R}^k)}\phi\,d\mathscr{H}^k,
\end{aligned}$$

where the last step follows from area formula of injective, Lipschitz maps. Now to justify DCT. Observe the L^∞ (not pointwise, as values of Jf can take ∞ on a null set) upper bound

$$\|u_r\|_\infty \le \left(\sup_{\mathbb{R}^n}\phi\right)\cdot \mathrm{Lip}(f)^k,$$

and notice the RHS is a constant function. It suffices then to show that for all $r > 0$, $\mathrm{spt}u_r \subset B_R$, for some R which is independent of r. Since $\mathrm{spt}u_r := \overline{\{u_r > 0\}}$, and a set is bounded iff its closure is, it suffices to show $\{u_r > 0\} \subset B_R$. Take $w \in \{u_r > 0\}$, so that

$$0 < \mathbb{1}_E(z+rw)\cdot\phi\left(\frac{f(z+rw)-f(z)}{r}\right)Jf(z+rw);$$

in particular, $z + rw \in E$. Thus, last condition of a regular Lipschitz image immediately gives for some $\lambda = \lambda(E) > 0$,

$$|f(z+rw)-f(z)| \ge \lambda r|w|. \tag{4}$$

On the other hand, since

$$0 < \mathbb{1}_E(z+rw)\cdot\phi\left(\frac{f(z+rw)-f(z)}{r}\right)Jf(z+rw),$$

it follows that

$$\frac{f(z+rw)-f(z)}{r} \in \mathrm{spt}\phi.$$

Since $\mathrm{spt}\phi \subset B_\Lambda$ for some $\Lambda = \Lambda(\phi)$,

$$\left|\frac{f(z+rw)-f(z)}{r}\right| \le \Lambda. \tag{5}$$

Together, inequalities 4 and 5 together give the conclusion upon setting $R := \frac{\Lambda}{\lambda}$, as

$$\lambda r|w| \le r\Lambda \implies w \in B_{\frac{\Lambda}{\lambda}}.$$

■

[8] The gradient of the linear map $\nabla f|_z$ is $\nabla f|_z$. Thus

$$J(\nabla f|_z)(w) = \sqrt{\det((\nabla(\nabla f|_z)|_w)^*\cdot(\nabla(\nabla f|_z)|_w))} = \sqrt{\det(\nabla f|_z^*\cdot\nabla f|_z)} = Jf(z).$$

In the next theorem, we ask that M be decomposed as

$$M = M_0 \sqcup \bigcup_{i=1}^{\infty} f_i(E_i),$$

where $\mathscr{H}^k(M_0) = 0$, and each (f_i, E_i) is a regular Lipschitz image.

Theorem 5.2. *Suppose $M \subset \mathbb{R}^n$ is a locally k-rectifiable set. Then for $\mathscr{H}^k$-a.e. point $x \in M$, there exists a unique k-dimensional plane T_xM such that:*

1. *The blow-up (defined below) of the measure $\mathscr{H}^k \llcorner M$ weak-star converges to $\mathscr{H}^k \llcorner T_xM$. That is, as $r \downarrow 0$,*
$$\mathscr{H}^k \llcorner \left(\frac{M - x}{r} \right) \overset{*}{\rightharpoonup} \mathscr{H}^k \llcorner T_xM.$$

2. *For $\mathscr{H}^k$-a.e. $x \in M$,*
$$\lim_{r \downarrow 0} \frac{\mathscr{H}^k(M \cap B_r(x))}{\omega_k r^k} = 1.$$

   More precisely, this happens whenever x admits an approximate tangent space.

Proof. In the proof, we will need the notion of a blow-up. For fixed $x \in M$ and $r > 0$, we set
$$\eta_{x,r}(y) = \eta(y) := \frac{y - x}{r},$$
which centers a chosen point $x \in M$ at the origin, then rescales (in fact, magnifies when $0 < r < 1$) a point of distance r to unit distance.

1. This would immediately follow from Lemma 5.1 upon setting $T_xM = \nabla f|_z(\mathbb{R}^k)$, if not for the $\mathscr{H}^k$-null set M_0. This will be taken care of by the *upper density theorem* which tells us for each i, as M_i is locally k-rectifiable, for a.e. $x \notin M_i$,

$$\lim_{r \downarrow 0} \frac{\mathscr{H}^k(M_i \cap B_r(x))}{\omega_k r^k} = 0.$$

   Note that since the RHS is 0, in fact the numerator and denominator need not decay at the same rate. So more generally, for any $R > 0$,

$$\lim_{r \downarrow 0} \frac{\mathscr{H}^k(RM_i \cap B_{rR}(x))}{\omega_k r^k} = 0.$$

   We use this as follows. Let $\phi \in C_c(\mathbb{R}^n)$ such that $\mathrm{spt}\phi \subset B_R(0)$. For $x \in M_i$, using elementary interactions of Hausdorff measure with symmetries,

$$\begin{aligned}
\left|\frac{1}{r^k}\int_{M\setminus M_i}\phi\circ\eta_{x,r}\ d\mathscr{H}^k\right| &= \left|\int_{\eta_{x,r}(M\setminus M_i)}\phi\ d\mathscr{H}^k\right| \\
&\leq \mathscr{H}^k(B_R(0)\cap\eta_{x,r}(M\setminus M_i))\cdot|\sup_{\mathbb{R}^n}\phi| \\
&= \omega_k|\sup_{\mathbb{R}^n}\phi|\cdot\frac{\mathscr{H}^k(B_{rR}(0)\cap(M\setminus M_i)-x)}{\omega_k r^k} \\
&= \omega_k|\sup_{\mathbb{R}^n}\phi|\cdot\frac{\mathscr{H}^k(B_{rR}(x)\cap(M\setminus M_i))}{\omega_k r^k} \\
&\xrightarrow{r\downarrow 0} 0.
\end{aligned}$$

2. This again follows from algebraic set-theoretic interactions of the blow-up with Hausdorff measure. Choose a sequence $\{\phi_i\}\subset C_c(\mathbb{R}^n)$ such that $\phi_i\xrightarrow{i\to\infty}\mathbb{1}_{B_1^n(0)}$. On one hand,

$$\lim_{r\downarrow 0}\frac{1}{r^k}\int_M\phi_i\circ\eta(y)\ d\mathscr{H}^k(y)=\lim_{r\downarrow 0}\int_{\eta M}\phi_i(y)\ d\mathscr{H}^k(y)\xrightarrow{i\to\infty}\lim_{r\downarrow 0}\mathscr{H}^k(\eta M\cap B_1^n(0)).$$

On the other hand,

$$\int_{T_xM}\phi_i(y)\ d\mathscr{H}^k(y)\xrightarrow{i\to\infty}\mathscr{H}^k(T_xM\cap B_1(0))=\mathscr{H}^k(B_1^k(0))=\omega_k.$$

As the two expressions are equal, we calculate

$$\begin{aligned}
1 &= \lim_{r\downarrow 0}\frac{\mathscr{H}^k(\eta M\cap B_1^n(0))}{\omega_k} \\
&= \lim_{r\downarrow 0}\frac{r^k\mathscr{H}^k(\eta M\cap B_1^n(0))}{\omega_k r^k} \\
&= \lim_{r\downarrow 0}\frac{\mathscr{H}^k((M-x)\cap B_r^n(0))}{\omega_k r^k} \\
&= \lim_{r\downarrow 0}\frac{\mathscr{H}^k(M\cap B_r^n(x))}{\omega_k r^k}.
\end{aligned}$$

■

Remark 5.3. This completes the forwards (easy) direction of the heuristic "measure-theoretic manifold iff admits measure-theoretic tangent planes".

As an application of Lemma 5.1, we can classify approximate tangent spaces of graphs of Lipschitz functions.

Corollary 5.4. *If $u:\mathbb{R}^n\to\mathbb{R}$ is a Lipschitz function and $f:\mathbb{R}^n\to\mathbb{R}^{n+1}$ is given by $f(z)=(z,u(z))$, then the graph of u, $\Gamma:=f(\mathbb{R}^n)$, is locally $\mathscr{H}^n$-rectifiable. Furthermore, for a.e. $z\in\mathbb{R}^n$,*

$$T_{f(z)}\Gamma=\nu^\perp|_z,$$

where $\nu|_z=(-\nabla u|_z,1)$.

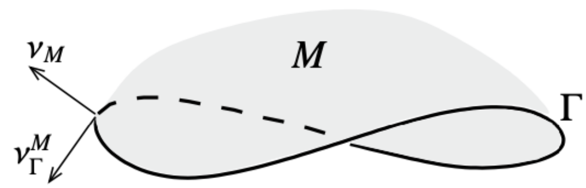

Figure 2: $\nu_{\partial M}^M$ as in Theorem 6.1.

Proof. We first show Γ is locally $\mathscr{H}^n$-rectifiable. Since u is Lipschitz, so is f; therefore, Γ is manifestly rectifiable. We argue Γ is locally n-rectifiable, that is, for all compact $K \subset \mathbb{R}^{n+1}$,

$$\mathscr{H}^n(K \cap \Gamma) < \infty.$$

Since Γ is closed since it's a graph, so $K \cap \Gamma$ is compact. Since $\mathscr{H}^n$ is Radon, $\mathscr{H}^n(K \cap \Gamma) < \infty$. Next, we characterize the approximate tangent space of Γ. By Lemma 5.1, we have (weakly)

$$T_{f(z)}\Gamma = \nabla f|_z(\mathbb{R}^n).$$

But $\nabla f|_z = \nabla(\tilde{z}, u(\tilde{z}))|_{\tilde{z}=z} = (1, \nabla u|_z)$. Note that for any $w \in \mathbb{R}^n$, we have

$$\nabla f|_z w \cdot \nu|_z w = (1, \nabla u|_z w) \cdot (-\nabla u|_z w, 1) = -\nabla u|_z w + \nabla u|_z w = 0.$$

The conclusion follows. ■

6 Gauss-Green on Hypersurfaces (10.17.23)

Following [Mag12] 11.3, but we shift indexing of dimensions by 1.

Theorem 6.1 (Gauss-Green)**.** *$M^n \subset \mathbb{R}^{n+1}$ is a C^2-hypersurface with boundary ∂M, then there exists a normal vector field $H_M \in C^0(M, \mathbb{R}^{n+1})$ and unit normal vector field $\nu_{\partial M}^M \in C^1(\partial M, \mathbb{S}^n)$ such that*

$$\int_M \nabla^M \phi \, d\mathscr{H}^n = \int_M \phi \mathbf{H_M} \, d\mathscr{H}^n + \int_{\partial M} \phi \nu_{\partial M}^M \, d\mathscr{H}^{n-1},$$

where $\phi \in C_c^1(\mathbb{R}^{n+1})$. Here, $\nu_{\partial M}^M \perp T$ for every vector field $T \in \mathbb{R}^{n+1} \to \mathbb{R}^{n+1}$ such that $T \perp M$.

Remark 6.2. Gauss-Green is an equality of vector fields in $\mathbb{R}^{n+1}$. This is also equivalent to a certain version of divergence theorem as

$$\int_M \mathrm{div}^M T \, d\mathscr{H}^n = \int_M T \cdot \mathbf{H_M} \, d\mathscr{H}^n + \int_{\partial M} T \cdot \nu_{\partial M}^M \, d\mathscr{H}^{n-1},$$

where $\mathrm{div}^M T := \mathrm{div} T - (\nabla T \nu_M) \cdot \nu_M$.

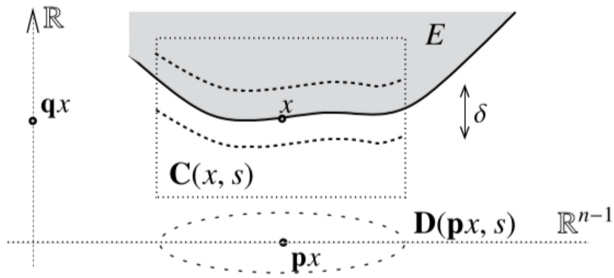

Figure 3: Hypersurface as graph of function.

Remark 6.3. There's no need for M to be orientable. The mean curvature vector field does not see orientation, but the scalar mean curvature H_M defined as

$$\mathbf{H_M} = H_M \nu_M$$

manifestly depends on choice of unit normal.

Remark 6.4. The last condition is since ∂M has codimension 2, so there are two normal directions, as in Figure 2. The condition specifies which normal direction $\nu_{\partial M}^M$ lies in, namely the one tangent to M. Since ν_M is assumed to be continuous, we (can and do) extend it to the boundary, so that the equation

$$\nu_{\partial M}^M \cdot \nu_M = 0$$

is well-defined on ∂M.

The basic idea, as with Aidan's talk last week, is to write M locally as a graph of a function, then pullback to a top-dimensional set to use divergence theorem/Gauss-Green.

To begin, we recall Corollary 11.7 which relates integration on graph and on its domain in low-regularity. As with a lemma in my previous talk, this is standard for high enough regularity.

Proposition 6.5. *Consider S is locally $\mathscr{H}^{n-1}$-rectifiable in $\mathbb{R}^n$, $u : \mathbb{R}^n \to \mathbb{R}$ is a Lipschitz function and $\Gamma := (z, u(z))$ is its graph. Then for any $g \geq 0$ or $g \in L^1(\mathbb{R}^n, \mathscr{H}^{n-1} \llcorner \Gamma)$,*

$$\int_\Gamma g \, d\mathscr{H}^{n-1} = \int_S \bar{g}\sqrt{1 + |\nabla^S u|^2} \, d\mathscr{H}^n,$$

where $\bar{g} = g(z, u(z))$.

This bar notation will be frequently used in the proof of Theorem 6.1. Think of this notation as "pulling back" an object on graph Γ to S along u.

Proof of 6.1. By partitions of unity and an action by the Euclidean group and homotheties, we normalize to take $\phi \in C_c^1(C)$, where $C := D^n \times [0, 1]$ is the cylinder over the unit hyperdisk. We assume that M is given locally as the graph of a C^2 function u over $\mathbb{D} \cap U$ for some open set $U \subset \mathbb{R}^n$. Namely,

$$C \cap M = \{(z, u(z)) : z \in \mathbb{D} \cap U\}$$
$$C \cap \partial M = \{(z, u(z)) : z \in \mathbb{D} \cap \partial U\}$$

where $U \subset \mathbb{R}^n$ is a set with (possibly empty) C^2 boundary as in Figure 3.

By modifying Corollary 5.4, we define the unit normal $\nu_M \in C^1(C \cap M, \mathbb{S}^n)$ as

$$\bar{\nu}_M = \frac{(-\nabla u, 1)}{\sqrt{1+|\nabla u|^2}} \text{ on } \mathbb{D} \cap U.$$

Define the (scalar) mean curvature by setting

$$\overline{H_M} = -\mathrm{div}\left(\frac{\nabla u}{\sqrt{1+|\nabla u|^2}}\right) \text{ on } \mathbb{D} \cap U.$$

■

Compute for $\phi \in C^1_c(\mathbb{R}^{n+1})$,

$$\begin{aligned} \nabla\phi \cdot \nu_M &= (\nabla\phi, \partial_n u) \cdot \frac{(-\nabla u, 1)}{\sqrt{1+|\nabla u|^2}} \\ &= \frac{-\nabla\phi \cdot \nabla u + \partial_{n+1}\phi}{\sqrt{1+|\nabla u|^2}} \end{aligned}$$

Pulling back to $\mathbb{D} \cap U$, we have for $\bar{\phi} \in C^1_c(\mathbb{D})$,

$$\overline{\nabla\phi \cdot \nu_M} = -\frac{\overline{\nabla\phi} \cdot \nabla u - \overline{\partial_{n+1}\phi}}{\sqrt{1+|\nabla u|^2}}.$$

For e_i the constant vector fields on $\mathbb{R}^{n+1}$, we calculate

$$e_i \cdot \nu_M := \begin{cases} \frac{1}{\sqrt{1+|\nabla u|^2}} & i = n+1 \\ -\frac{\partial_i u}{\sqrt{1+|\nabla u|^2}} & 1 \leq i \leq n \end{cases}$$

which suggests that we should separate out our analysis into two pieces, the vertical bit $i = n+1$ and the horizontal bits $1 \leq i \leq n$. Since we have $\nabla^M \phi = \nabla\phi - (\nabla\phi \cdot \nu_M)\nu_M$, we calculate for $1 \leq i \leq n$,

$$e_{n+1} \cdot \int_M \nabla^M \phi \, d\mathscr{H}^n = \int_{\mathbb{D}\cap U} \left(\overline{\partial_{n+1}\phi} + \frac{\overline{\nabla\phi} \cdot \nabla u - \overline{\partial_{n+1}\phi}}{1+|\nabla u|^2}\right) \sqrt{1+|\nabla u|^2} \, d\mathscr{H}^n, \tag{6}$$

$$e_i \cdot \int_M \nabla^M \phi \, d\mathscr{H}^n = \int_{\mathbb{D}\cap U} \left(\overline{\partial_i\phi} - \frac{\overline{\nabla\phi} \cdot \nabla u - \overline{\partial_{n+1}\phi}}{1+|\nabla u|^2} \partial_i u\right) \sqrt{1+|\nabla u|^2} \, d\mathscr{H}^n. \tag{7}$$

where the factors of $\sqrt{1+|\nabla u|^2}$ come from Proposition 6.5. We have the equality

$$\nabla\bar{\phi} = \overline{\nabla\phi} + \overline{\partial_{n+1}\phi}\nabla u, \tag{8}$$

which is immediate from chain rule for $1 \le i \le n$,

$$
\begin{aligned}
\nabla\bar{\phi}|_x &= \nabla\phi(x,u(x)) \\
&= \sum_i \frac{\partial\phi(x,u(x))}{\partial x^k}\frac{\partial x^k}{\partial x^i} + \frac{\partial\phi(x,u(x))}{\partial x^{n+1}}\frac{\partial u}{\partial x^i} \\
&= \sum_i \partial_i\phi(x,u(x)) + \partial_{n+1}\phi(x,u(x))\sum_i \partial_i u(x) \\
&= \overline{\nabla\phi}|_x + \overline{\partial_{n+1}\phi}|_x \nabla u|_x.
\end{aligned}
$$

Similarly, we record that

$$\partial_i\bar{\phi} = \overline{\partial_i\phi} + \overline{\partial_{n+1}\phi}\partial_i u.$$

We work on the vertical bit. Via equation 8, we rewrite the integrand of 6 as

$$
\begin{aligned}
\left(\overline{\partial_{n+1}\phi} + \frac{\overline{\nabla\phi}\cdot\nabla u - \overline{\partial_{n+1}\phi}}{1+|\nabla u|^2}\right)\sqrt{1+|\nabla u|^2} &= \frac{\nabla u\cdot\overline{\nabla\phi}}{\sqrt{1+|\nabla u|^2}} + \overline{\partial_{n+1}\phi}\sqrt{1+|\nabla u|^2} - \frac{\overline{\partial_{n+1}\phi}}{\sqrt{1+|\nabla u|^2}} \\
&= \frac{\nabla u\cdot\overline{\nabla\phi}}{\sqrt{1+|\nabla u|^2}} + \frac{\overline{\partial_{n+1}\phi}(1+|\nabla u|^2) - \overline{\partial_{n+1}\phi}}{\sqrt{1+|\nabla u|^2}} \\
&= \frac{\nabla u\cdot\overline{\nabla\phi}}{\sqrt{1+|\nabla u|^2}} + \frac{\overline{\partial_{n+1}\phi}|\nabla u|^2}{\sqrt{1+|\nabla u|^2}} \\
&= \frac{\nabla u}{\sqrt{1+|\nabla u|^2}}\cdot\overline{\nabla\phi} + \overline{\partial_{n+1}\phi}\nabla u \\
&= \frac{\nabla u}{\sqrt{1+|\nabla u|^2}}\cdot\nabla\bar{\phi}
\end{aligned}
$$

By $\phi \equiv 0$ on $\partial\mathbb{D}$, and product rule for divergences,

$$
\begin{aligned}
(6) &= \int_{\mathbb{D}\cap U} \frac{\nabla u}{\sqrt{1+|\nabla u|^2}}\cdot\nabla\bar{\phi}\, d\mathscr{H}^n \\
&= \int_{\mathbb{D}\cap U} \operatorname{div}\left(\frac{\bar{\phi}\nabla u}{\sqrt{1+|\nabla u|^2}}\right) - \bar{\phi}\operatorname{div}\left(\frac{\nabla u}{\sqrt{1+|\nabla u|^2}}\right)\, d\mathscr{H}^n \\
&= \int_{\mathbb{D}\cap\partial U} \frac{\bar{\phi}}{\sqrt{1+|\nabla u|^2}}\nabla u\cdot\nu_U\, d\mathscr{H}^{n-1} - \int_{\mathbb{D}\cap U}\bar{\phi}\operatorname{div}\left(\frac{\nabla u}{\sqrt{1+|\nabla u|^2}}\right)\, d\mathscr{H}^n \\
&= e_{n+1}\cdot\int_{\partial M}\phi\nu^M_{\partial M}\, d\mathscr{H}^{n-1} + \int_{\mathbb{D}\cap E}\bar{\phi}\bar{H}_M\, d\mathscr{H}^n \\
&= e_{n+1}\cdot\int_{\partial M}\phi\nu^M_{\partial M}\, d\mathscr{H}^{n-1} + e_{n+1}\cdot\int_M \phi\mathbf{H}_M\, d\mathscr{H}^n,
\end{aligned}
$$

where the second term in the last equality follows from a previous calculation of $e_{n+1}\cdot\nu_M$, while the first term follows from defining on $C\cap\partial M$

$$e_{n+1}\cdot\overline{\nu^M_{\partial M}} := \frac{\nabla u\cdot\nu_U}{\sqrt{1+|\nabla u|^2}\sqrt{1+|\nabla^S u|^2}},$$

where $S := \mathbb{D} \cap \partial U$.

Next, we work on the horizontal bit. For $1 \le i \le n$, we calculate by equation 7 divergence theorem, and $\bar{\phi} \equiv 0$ on $\partial\mathbb{D}$,

$$\begin{aligned}
e_i \cdot \int_M \phi \mathbf{H_M} \, d\mathscr{H}^n &= e_i \cdot \int_M \phi H_M \nu_M \, d\mathscr{H}^n \\
&= \int_{\mathbb{D}\cap U} \bar{\phi} \partial_i u \operatorname{div}\left(\frac{\nabla u}{\sqrt{1+|\nabla u|^2}}\right) \, d\mathscr{H}^n \\
&= \int_{\mathbb{D}\cap U} \operatorname{div}\left(\bar{\phi}\partial_i u \frac{\nabla u}{\sqrt{1+|\nabla u|^2}}\right) - \nabla(\bar{\phi}\partial_i u) \cdot \frac{\nabla u}{\sqrt{1+|\nabla u|^2}} \, d\mathscr{H}^n \\
&= \int_{\mathbb{D}\cap\partial U} \frac{\bar{\phi}\partial_i u}{\sqrt{1+|\nabla u|^2}} \nabla u \cdot \nu_U \, d\mathscr{H}^{n-1} - \int_{\mathbb{D}\cap U} \underbrace{\frac{\bar{\phi}}{\sqrt{1+|\nabla u|^2}} \nabla(\partial_i u) \cdot \nabla u}_{(*)} \, d\mathscr{H}^n \\
&\quad - \int_{D\cap U} \partial_i u \overline{\nabla\phi} \cdot \frac{\nabla u}{\sqrt{1+|\nabla u|^2}} + \frac{\partial_i u \overline{\partial_{n+1} u} |\nabla u|^2}{\sqrt{1+|\nabla u|^2}} \, d\mathscr{H}^n
\end{aligned}$$

and for $1 \le j \le n$, we calculate

$$\begin{aligned}
(*) &= \frac{\bar{\phi}}{\sqrt{1+|\nabla u|^2}} \sum_j u_{ij} u_j \\
&= \frac{\bar{\phi}}{2\sqrt{1+|\nabla u|^2}} \partial_i (\sum_j u_j^2) \\
&= \frac{\bar{\phi}}{2\sqrt{1+|\nabla u|^2}} \partial_i |\nabla u|^2 \\
&= \bar{\phi} \partial_i (\sqrt{1+|\nabla u|^2})
\end{aligned}$$

where subscripts in the above calculation denote partial derivatives. It follows that

$$\begin{aligned}
&e_i \cdot \int_M (\nabla^M \phi - \phi \mathbf{H_M}) \, d\mathscr{H}^n \\
&= \int_{\mathbb{D}\cap U} (\overline{\partial_i \phi} + \overline{\partial_{n+1}\phi}\partial_i u)\sqrt{1+|\nabla u|^2} + \bar{\phi}\partial_i(\sqrt{1+|\nabla u|^2}) \, d\mathscr{H}^n \\
&\quad - \int_{\mathbb{D}\cap\partial U} \bar{\phi}\partial_i u \frac{\nabla u \cdot \nu_U}{\sqrt{1+|\nabla u|^2}} \, d\mathscr{H}^{n-1} \\
&= \int_{\mathbb{D}\cap U} \partial_i \bar{\phi}\sqrt{1+|\nabla u|^2} + \bar{\phi}\partial_i(\sqrt{1+|\nabla u|^2}) \, d\mathscr{H}^n \\
&\quad - \int_{\mathbb{D}\cap\partial U} \bar{\phi}\partial_i u \frac{\nabla u \cdot \nu_U}{\sqrt{1+|\nabla u|^2}} \, d\mathscr{H}^{n-1} \\
&= \int_{\mathbb{D}\cap U} \underbrace{\partial_i(\bar{\phi}\sqrt{1+|\nabla u|^2})}_{\text{divergence quantity}} \, d\mathscr{H}^n - \int_{\mathbb{D}\cap\partial U} \bar{\phi}\partial_i u \frac{\nabla u \cdot \nu_U}{\sqrt{1+|\nabla u|^2}} \, d\mathscr{H}^{n-1} \\
&= \int_{\mathbb{D}\cap\partial U} \bar{\phi}(\sqrt{1+|\nabla u|^2} e_i - \frac{\partial_i u}{\sqrt{1+|\nabla u|^2}}\nabla u) \cdot \nu_U \, d\mathscr{H}^{n-1}.
\end{aligned}$$

On $\mathbb{D} \cap \partial U$, we set

$$e_i \cdot \overline{\nu^M_{\partial M}} := (\sqrt{1+|\nabla u|^2} e_i - \frac{\partial_i u}{\sqrt{1+|\nabla u|^2}}\nabla u) \cdot \frac{\nu_U}{\sqrt{1+|\nabla^S u|^2}}.$$

It suffices to check $\nu^M_{\partial M}$ defined in this way is unit and normal to ν_M and ∂M, but we stop here.

7 Compactness (9.14.23)

Theorem 7.1. *Suppose $\{E_i\}$ is a sequence of sets of finite perimeter in $\mathbb{R}^n$ such that*

1. *$E_i \subset B_R$ for some $R > 0$,*
2. *$P(E_i) \leq C$ for some constant uniform in i.*

Then, there E_i subsequentially converges to a set of finite perimeter $E \subset B_R$ and $\mu_{E_i} \overset{*}{\rightharpoonup} \mu_E$.

Proof. The compactness comes from a setup in a specific function space. The ambient is the complete metric space

$$X := \{E \in \mathcal{M}(\mathscr{L}^n) : P(E) < \infty\}/\sim,$$
$$d(E,F) := |E\Delta F| = \|\mathbb{1}_E - \mathbb{1}_F\|_{L^1(\mathbb{R}^n)}$$

where $\sim$ means up to measure 0 identification. Define subsets for $r, p > 0$,

$$Y_{r,p} := \{E \in \mathcal{M}(\mathscr{L}^n) : P(E) \leq p, E \subset B_r\},$$

and we claim these are compact ($\iff$ totally bounded + complete) subsets of X. The sets $Y_{r,p}$ are closed by lower semi-continuity of perimeter, so they are complete. It's clear that the conclusion follows upon showing $Y_{r,p}$ is totally bounded. That is, for every $\sigma > 0$, there is a finite collection $\{T_1, .., T_M\}$ such that for any $E \in Y_{r,p}$,

$$\min_j d(E, T_j) = \min_j |E\Delta T_j| \leq \sigma.$$

Therefore, the goal is to estimate $|E\Delta T_j|$ in terms of n, p and an extra parameter r to control the scale. For fixed $r > 0$, let $\{Q_i\}$ to be an enumeration of open cubes with vertices in $r\mathbb{Z}^n \subset \mathbb{R}^n$. $|E| < \infty$ by monotonicity and for only the first N cubes (up to reindexing), is E is contained in at least half the cube. That is, for $i \in \{1, ..., N\}$,

$$|Q_i \cap E| \geq \frac{r^n}{2}.$$

It follows for $i \geq N + 1$, over half Q_i does not see E. That is for $i \in \{1, ..., N\}$,

$$|Q_i \setminus E| \geq \frac{r^n}{2}.$$

We set $T := \cup_{i=1}^n Q_i$. From here, we derive the desired bound, assuming a corollary of the Poincare-Wirtinger inequality. For $\epsilon > 0$ and $u_\epsilon := \mathbb{1}_E * \rho_\epsilon$,

$$\sqrt{n}r \int_{\mathbb{R}^n} |\nabla u_\epsilon| = \sqrt{n}r \sum_{i\in\mathbb{N}} \int_{Q_i} |\nabla u_\epsilon| \geq \sum_{i\in\mathbb{N}} \int_{Q_i} |u_\epsilon - \bar{u}_{\epsilon,i}|,$$

where $\bar{u}_{\epsilon,i}$ denotes the average value of u_ϵ on Q_i. Taking $\epsilon \downarrow 0$, by L^1_{loc} convergence of mollification,

$$\begin{aligned}
\sqrt{n}rP(E) &\geq \sum_{i\in\mathbb{N}} \int_{Q_i} |\mathbb{1}_E - \bar{\mathbb{1}}_i| \\
&= \sum_{i\in N} \int_{Q_i} |\mathbb{1}_E - \frac{|Q_i \cap E|}{r^n}| \\
&= \sum_{i\in N} \underbrace{|E \cap Q_i|(1 - \frac{|Q_i \cap E|}{r^n})}_{\mathbb{1}_E=1} + \underbrace{|Q_i \setminus E|\frac{|Q_i \cap E|}{r^n}}_{\mathbb{1}_E=0} \\
&= \frac{|E \cap Q_i|}{r^n} \sum_{i\in\mathbb{N}} \underbrace{r^n - |Q_i \cap E|}_{|Q_i\setminus E|} + |Q_i \setminus E| \\
&= \sum_{i=1}^{N} \frac{2|E \cap Q_i||Q_i \setminus E|}{r^n} + \sum_{i=N+1}^{\infty} \frac{2|E \cap Q_i||Q_i \setminus E|}{r^n} \\
&\geq \sum_{N} |Q_i \setminus E| + \sum_{\infty} |Q_i \cap E| \\
&= \sum_{N} |T \setminus E| + |E \setminus T| \\
&= |E\Delta T|
\end{aligned}$$

With this inequality, we simply choose r such that $\sqrt{n}pr \leq \sigma$, and we apply the above inequality. The uniformity in E comes from the fact that $E \subset B_R$, so that we can immediately restrict to $\{Q_i\}$ (associated to scale r) to the finitely many cubes which intersect B_R. So then $M = M(r, R, n) = |\text{Pow}(S)|$ where S is the subset of cubes $\{Q_i\}$ which intersects B_R. The conclusion follows.

It remains to show the inequality on cubes $Q = x + (0, r)^n$ and $u \in C^1(\mathbb{R}^n)$,

$$\int_Q |u - \bar{u}_Q| \leq \sqrt{n} r \int_Q |\nabla u|.$$

Up to change of variable and normalizing the average to be 0, it suffices to show

$$\int_Q |u| \leq \int_Q |\nabla u|$$

where Q is the unit cube and $\bar{u}_Q = 0$. By Cauchy-Schwarz,

$$\sum_i |\partial_i u| \leq \sqrt{n} \sqrt{\sum_i (\partial_i u)^2} = \sqrt{n} \|\nabla u|,$$

so it suffices to show the Poincare inequality over the unit cube

$$\int_Q |u| \leq \sum_i \int_Q |\partial_i u|.$$

The proof proceeds by induction. For $n = 1$, by MVT and FTOC, there is some $x_o \in (0, 1)$ such that

$$\int_Q |u| \, dx = |u(x)| = |u(x) - u(x_o)| \leq \int_0^1 |u'(x)| \, dx.$$

For higher dimensions, consider (x^1, x) to be a decomposition of $\mathbb{R}^n = \mathbb{R} \times \mathbb{R}^{n-1}$. Set $v(x^1) := \int u(x^1, x) dx$, and note that $\int_0^1 v(x^1) \, dx^1 = 0$.

$$\begin{aligned}
\int_Q |u| &\leq \int_0^1 \int_{(0,1)^{n-1}} |u(x) - v(x^1)| \, dx dx^1 + \int_0^1 |v(x^1)| \, dx^1 \cdot \underbrace{\int_{(0,1)^{n-1}} dx}_{=1} \\
&\leq \int_0^1 \underbrace{\sum_{i=2}^n |\partial_i u|}_{\text{ind. hyp.}} \, dx dx^1 + \int_0^1 \underbrace{|v'|}_{n=1} \, dx^1 \\
&\leq \sum_{i=1}^n \int_Q |\partial_i u|.
\end{aligned}$$

■

Remark 7.2. Replacing uniformly bounded perimeter with uniformly bounded diameters, this still converges subsequentially to a set of finite perimeter. The difference here is that we get convergence up to translation, that is there is a sequence $\{x_i\} \subset \mathbb{R}^n$ such that subsequentially $x_i + E_i \xrightarrow{L^1} E, \mu_{x_i + E_i} \overset{*}{\rightharpoonup} \mu_E$

Lastly, we localize the compactness theorem.

Corollary 7.3. *Suppose E_i are sets of locally finite perimeter in $\mathbb{R}^n$ such that for any $R > 0$,*

$$\sup_i P(E; B_R) < \infty.$$

Then, there exists a set E of locally finite perimeter such that

$$E_i \to E, \mu_i \overset{*}{\rightharpoonup} \mu_E$$

subsequentially.

Proof. For each $j \in \mathbb{N}$, we apply the compactness theorem to the sequence $\{(E_i \cap B_j)\}_{i\in\mathbb{N}}$, which is justified by the inequality

$$P(E_i \cap B_j) \leq P(E_i; B_j) + P(B_j),$$

to be proved. By a standard diagonalization argument, we extract a for each j, a set of finite perimeter F_j. Furthermore, by construction $F_j \subset F_{j+1}$ and $E = \cup_\infty F_j$ will be a set of locally finite perimeter.

Let $0 \leq u_\epsilon, v_\epsilon \leq 1$ be convolutions of the indicator functions of $E, B_{R'}$ respectively, for $R' < R$. Taking $R' \uparrow R$ will give the result.

$$\begin{aligned}
P(E \cap B_{R'}) &\leq \underbrace{\liminf_{\epsilon\downarrow 0} \int_{\mathbb{R}^n} |\nabla(u_\epsilon v_\epsilon)|}_{\text{lower semi-continuity}} \\
&\leq \limsup_{\epsilon\downarrow 0} \int_{\mathbb{R}^n} u_\epsilon |\nabla v_\epsilon| + v_\epsilon |\nabla u_\epsilon| \\
&\leq \limsup_{\epsilon\downarrow 0} \int_{\mathbb{R}^n} |\nabla v_\epsilon| + v_\epsilon |\nabla u_\epsilon| \\
&\leq P(B_{R'}) + \limsup_{\epsilon\downarrow 0} \int_{B_{R'}} |\nabla u_\epsilon| \\
&\leq P(B_{R'}) + P(E; B_{R'})
\end{aligned}$$

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P. Tee, Department of Mathematics, University of Connecticut, Connecticut 06269

E-mail address, P. Tee: paul.tee@uconn.edu