

Picard: Base Distribution



— SPT5\_T0\_R1\_R1

— SPT5\_T0\_R1\_R2

—— SPT5\_INPUT\_R1\_R2

—— SPT5\_INPUT\_R2\_R1

SPT5\_T15\_R2\_R1

—— SPT5\_T15\_R2\_R2

SPT5\_T15\_R1\_R2