Paper Reading

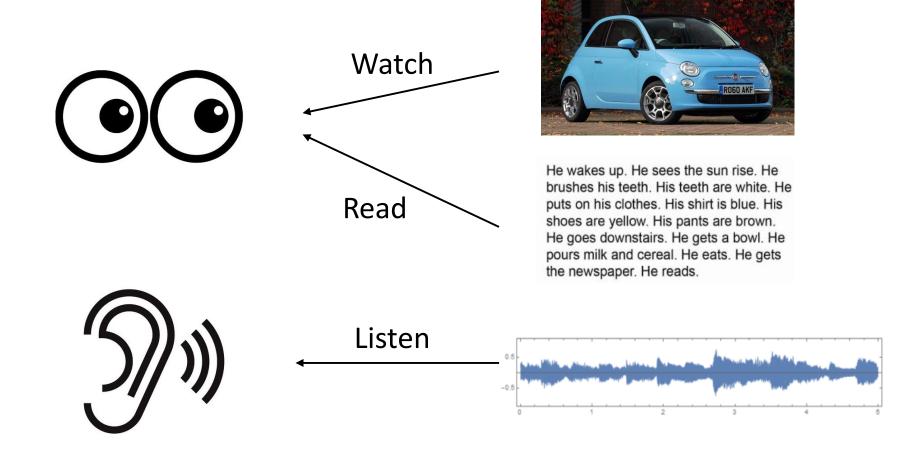
Learning to Combine Top-Down and Bottom-Up Signals in Recurrent Neural Networks with Attention over Modules (ICML2020)

Jianjie Luo

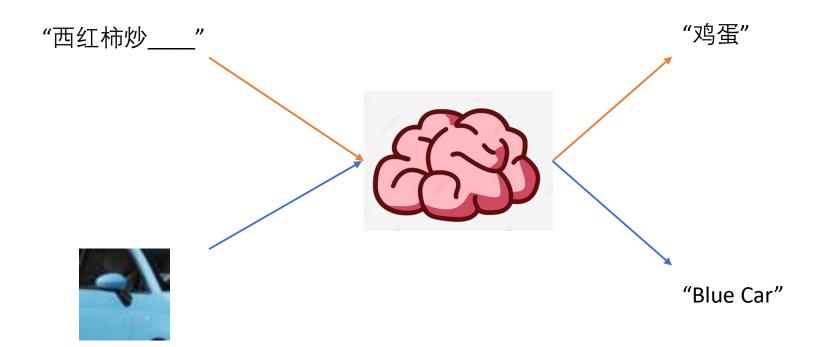
2020.12.18

In real life

What is Bottom-up(BU) Signal?



What is Top-down(TD) Signal?

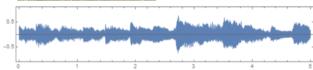


BU/TD Signals help us make Decision/Prediction

Why we need both BU&TD signals better?

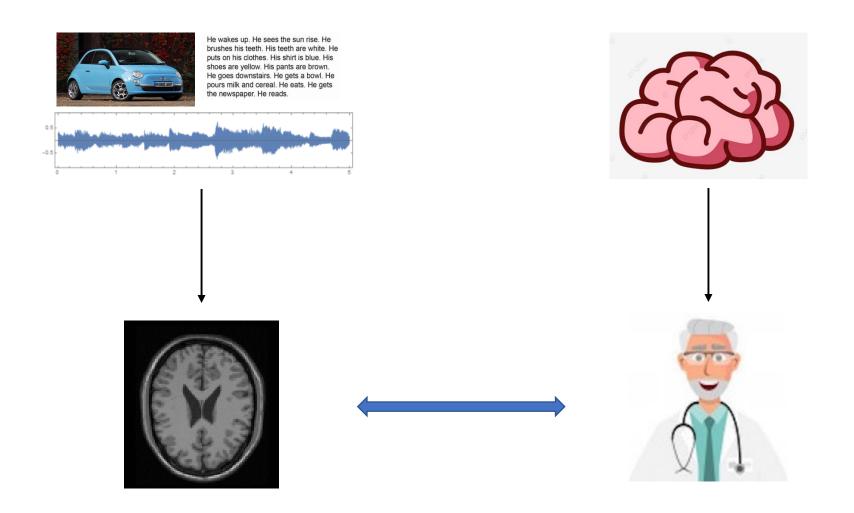


He wakes up. He sees the sun rise. He brushes his teeth. His teeth are white. He puts on his clothes. His shirt is blue. His shoes are yellow. His pants are brown. He goes downstairs. He gets a bowl. He pours milk and cereal. He eats. He gets the newspaper. He reads.

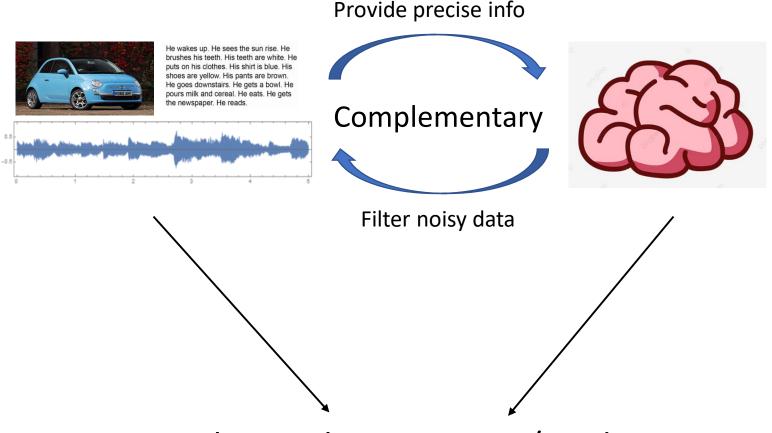




Why we need both BU&TD signals better?



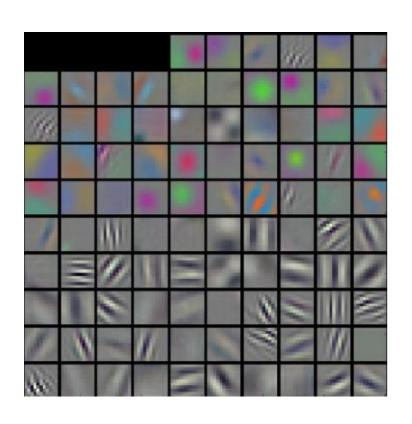
Why we need both BU&TD signals better?

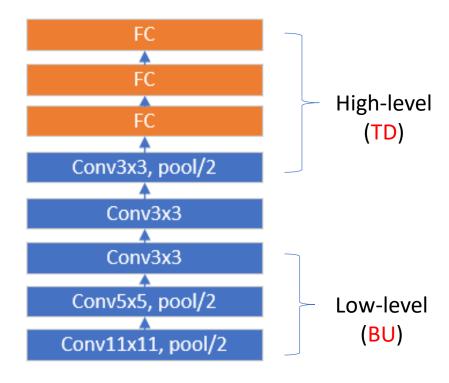


Making Robust Decision/Prediction

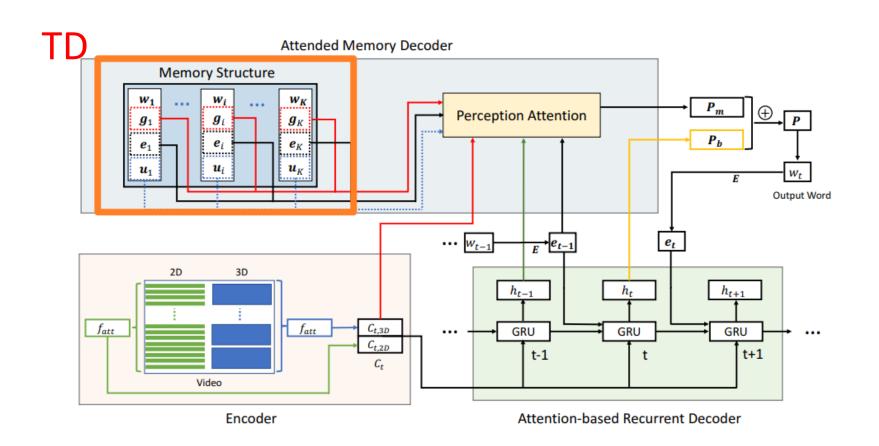
From real life to Neural Networks

Where are the BU&TD signals in Neural Networks?

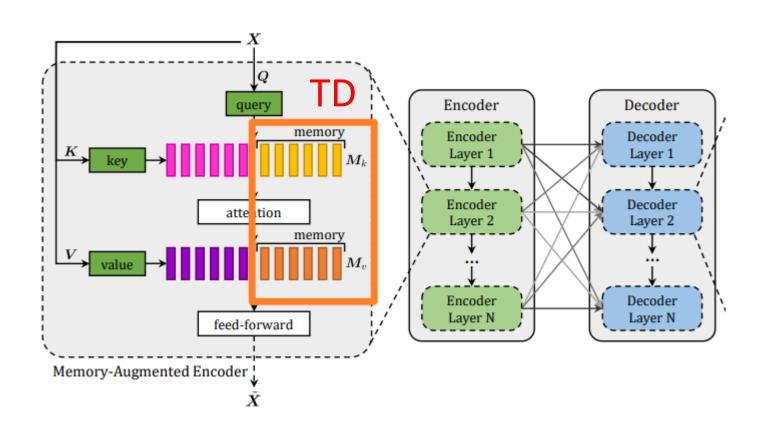




Where are the BU&TD signals in Neural Networks?



Where are the BU&TD signals in Neural Networks?



How to Combine BU&TD (in general)?

Every Fusion
Methods you
can imagine...

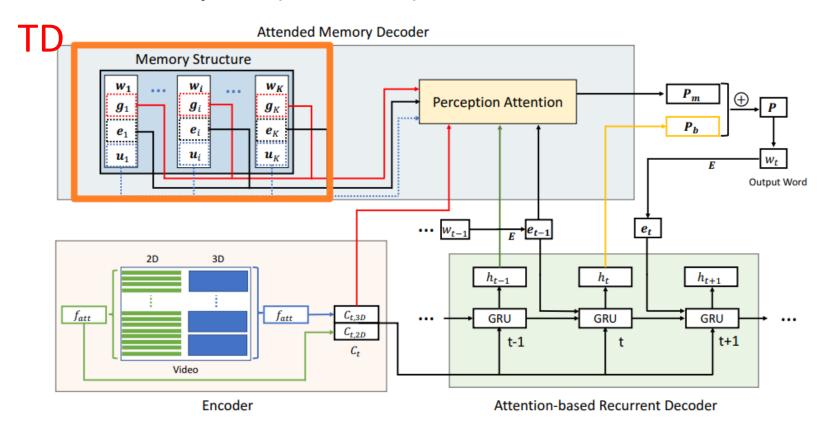
- Add Fusion
- Mean Fusion
- Hadamard product Fusion
- Concat Fusion
- Attention Fusion *
- •

How to Combine BU&TD (in RNN)?

 Other Papers (BUTD^[1]) Softmax h_t^2 $h_{t-1}^2 \cdots$ Language LSTM h² Top-Down Attention LSTM $\cdots \rightarrow h_t^1$ h_{t-1}^2 $W_e\Pi_t$ **R-CNN** Bottom-Up Top-Down

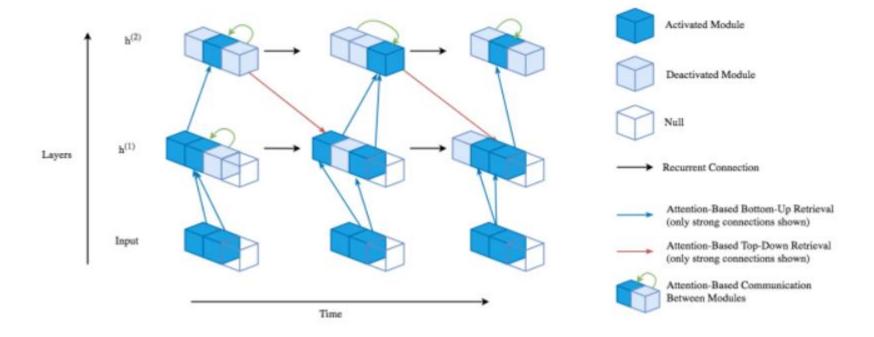
How to Combine BU&TD (in RNN)?

Other Papers (MARN^[1])



How to Combine BU&TD (in RNN)?

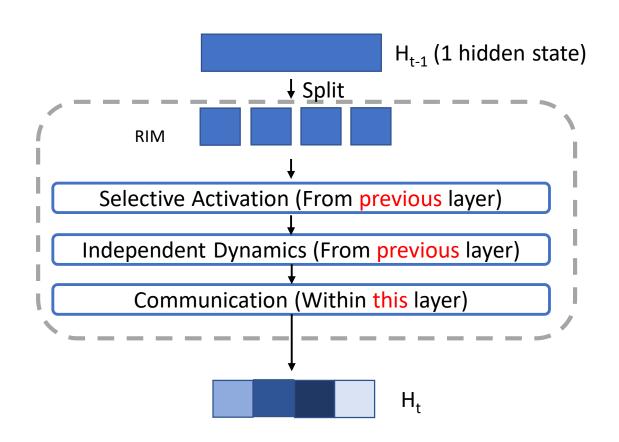
This Paper (BRIMs^[1])



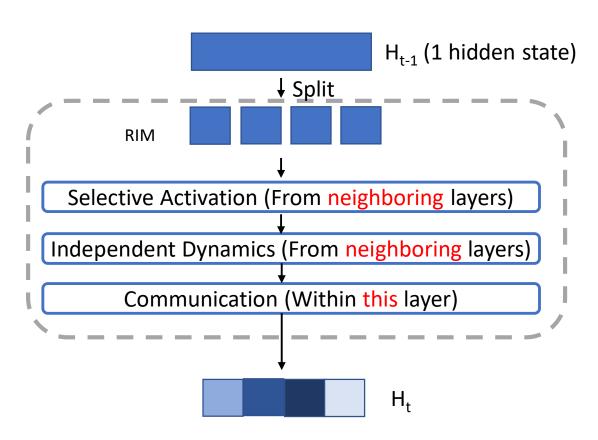
Preliminaries for BRIMs

- Multi-layer stacked RNN
- Key-Value Attention
- RIMs
 - Selective Activation
 - Independent Dynamics
 - Communication

Recurrent Independent Mechanisms(RIMs)



 Bidirectional Recurrent Independent Mechanisms(BRIMs)



Pseudo-Code for BRIMs

Algorithm 1: Single recurrent step for an L layered BRIMs model

Result: RNN Cell forward for L layered BRIMs

x: Input

 h_l : Hidden state of layer l represented as flat vector

 $h_l[k]$: Hidden state of k^{th} module of layer l

 n_l : Number of modules in layer l

 m_l : Number of modules kept active in layer l

 ϕ : Null vector

All Query, Key, Value networks are fully connected neural networks

 $\mathbf{Q}, \mathbf{K}, \mathbf{V}, \mathbf{A_S}, \mathbf{A_R}$ denote matrices

Note: Unless specified, all indexing start with 1

return h

 Pseudo-Code for BRIMs

```
Function BRIMsCell (x, h_1, ..., h_{n_t}):
    h_0 = x
    for l = 1 to L do
        for k = 1 to n_l do
             \mathbf{Q}[\mathbf{k}] = \text{Input Query}_{l,k}(h_l[k])
         end
         K[0], V[0] = Null Key Value_l(\phi)
                                                                      Selective Activation
         K[1], V[1] = Input Key Value_l(h_{l-1})
         K[2], V[2] = Top-Down Key Value_l(h_{l+1})
                                                                        (if available)
        \mathbf{A}_S = \text{Softmax}(\mathbf{Q}\mathbf{K}^T/\sqrt{d_{att}})
         \mathbf{A}_R = |\mathbf{A}_S| \mathbf{V}
         Sort A_S[:,0] and take lowest m_l as active
                                                                      Independent Dynamics
        for k s.t. module k is active do
             h_l[k] = \text{RNN}_{l,k}(\mathbf{A}_R[k], h_l[k])
                                                                (can use GRU or LSTM)
         end
                                                               Communication within layer
        for k = 1 to n_l do
             \mathbf{Q}[\mathbf{k}] = \text{Communication Query}_{l,k}(h_l[k])
             \mathbf{K}[\mathbf{k}] = \text{Communication Key}_{l,k}(h_l[k])
             V[k] = Communication Value_{l,k}(h_l[k])
         end
        \mathbf{A}_R = \text{Softmax}(\mathbf{Q}\mathbf{K}^T/\sqrt{d_{att}}) \mathbf{V}
         for k s.t. module k is active do
             h_l[k] += \mathbf{A}_R[k]
         end
    end
```

Differences between BRIMs and other network designs

	н	Α	В	M
LSTM	Optional	Optional	Optional	×
RMC ^[1]	×	٧	×	×
Transformer	٧	٧	٧	×
RIMs	Optional	٧	×	٧
BRIMs	٧	٧	٧	٧

Properties Notions:

H: Hierarchy

A: Attention

B: Bidirectional Information Flow

M: Modularity

How to Apply BRIMs?

ONLY focus on Network(RNN) Design.

Do ANYTHING the RNNs can!

Experiments

Task Lists

- Sequential MNIST and CIFAR *
- Adding tasks
- Moving MNIST *
- Handling Occlusion in Bouncing Balls
- Language Modeling
- Reinforcement Learning

Sequential MNIST/CIFAR

- Dataset: MNIST / CIFAR
- Task descriptions: a classification task with a sequence length of T = 784 or 1024
- Input: One pixel at a time
- Output: 1 label

Sequential MNIST

Results

Algorithm	Properties	16×16	19×19	24×24
LSTM	_	86.8	42.3	25.2
LSTM	H	87.2	43.5	22.9
LSTM	H+B	83.2	44.4	25.3
LSTM	H+A	84.3	47.5	31.0
LSTM	H+A+B	83.2	40.1	20.8
RMC	A	89.6	54.2	27.8
Transformers	H+A+B	91.2	51.6	22.9
RIMs	A+M	88.9	67.1	38.1
Hierarchical RIMs	H+A+M	85.4	72.0	50.3
MLD-RIMs	H+A+M	88.8	69.1	45.3
BRIMs (ours)	H+A+B+M	88.6	74.2	51.4

Table 1. Performance on the **Sequential MNIST resolution generalization:** Test Accuracy % after 100 epochs. All models were trained on 14x14 resolution but evaluated at different resolutions; results averaged over 3 different trials.

Sequential CIFAR

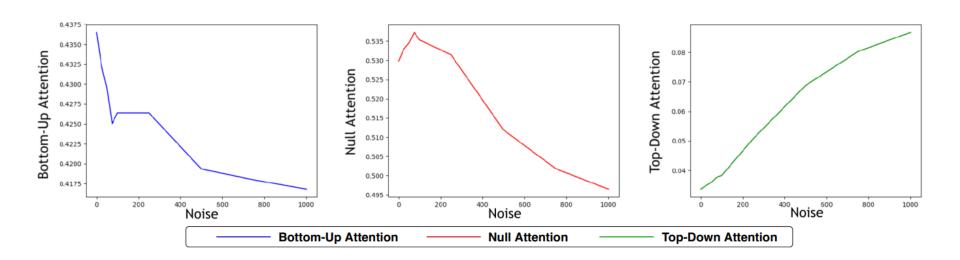
Results

Algorithm	Properties	19×19	24×24	32×32
LSTM		54.4	44.0	32.2
LSTM	H	57.0	46.8	33.2
LSTM	H+B	56.5	52.2	42.1
LSTM	H+A	56.7	51.5	40.0
LSTM	H+A+B	59.9	54.6	43.0
RMC	A	49.9	44.3	31.3
RIMs	A+M	56.9	51.4	40.1
Hierarchical RIMs	H+A+M	57.2	54.6	46.8
MLD-RIMs	H+A+M	56.8	53.1	44.5
BRIMs (ours)	H+A+B+M	60.1	57.7	52.2

Table 2. Performance on **Sequential CIFAR generalization:** Test Accuracy % after 100 epochs. Both the proposed and the Baseline model (LSTM) were trained on 16x16 resolution but evaluated at different resolutions; results averaged over 3 different trials.

Sequential CIFAR

Analysis of Top Down Attention



Moving MNIST

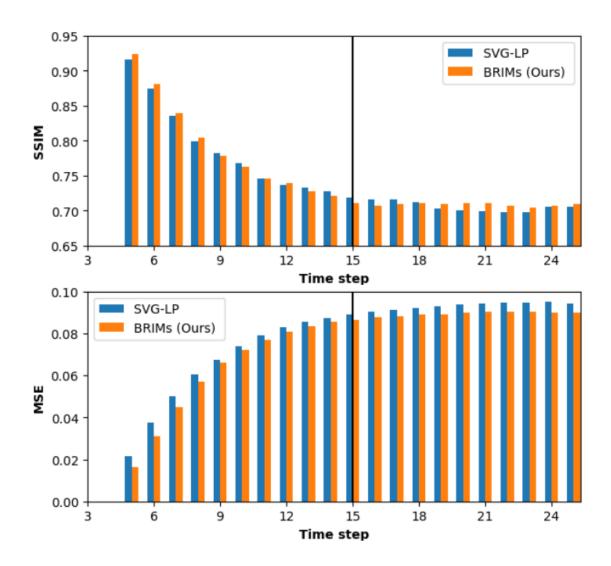
• Dataset: Moving MNIST



- Task descriptions: a video(seq) prediction task
- Input: 5 frames sampled on the fly from a video
- Output: predict the next 10 frames in the sequence

Moving MNIST

• Results



Conclusion

 Top-down and bottom-up information are both critical to robust and accurate perception

 The combination method used in BRIMs can get a more robust RNN model

Two Key points in BRIMs

The modular decomposition in hidden state features

 A new connection from High-level information to Low-level information, i.e. Top-down connection

Thanks