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∞ Meta



RawlsGCN: Towards Rawlsian Difference Principle on Graph Convolutional Network



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² Meta AI

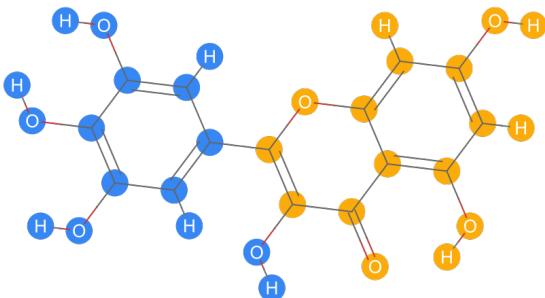
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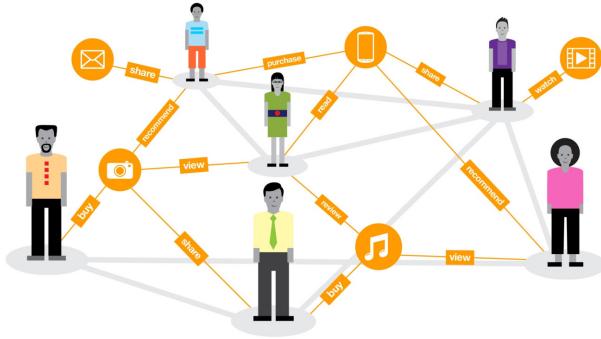
Ubiquity of Graphs



Social Network Analysis



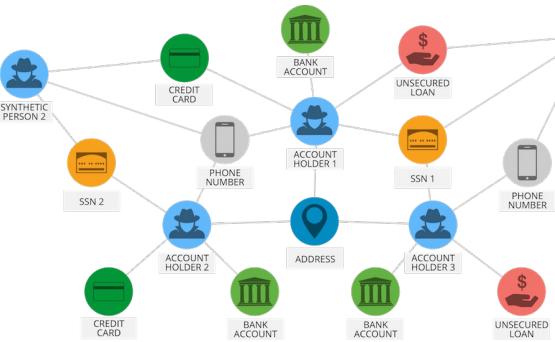
Drug Discovery



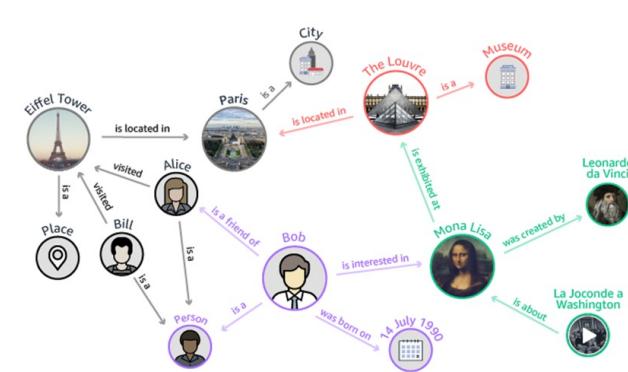
Recommendation



Traffic Prediction



Fraud Detection



Question Answering

Graph Convolutional Network (GCN)

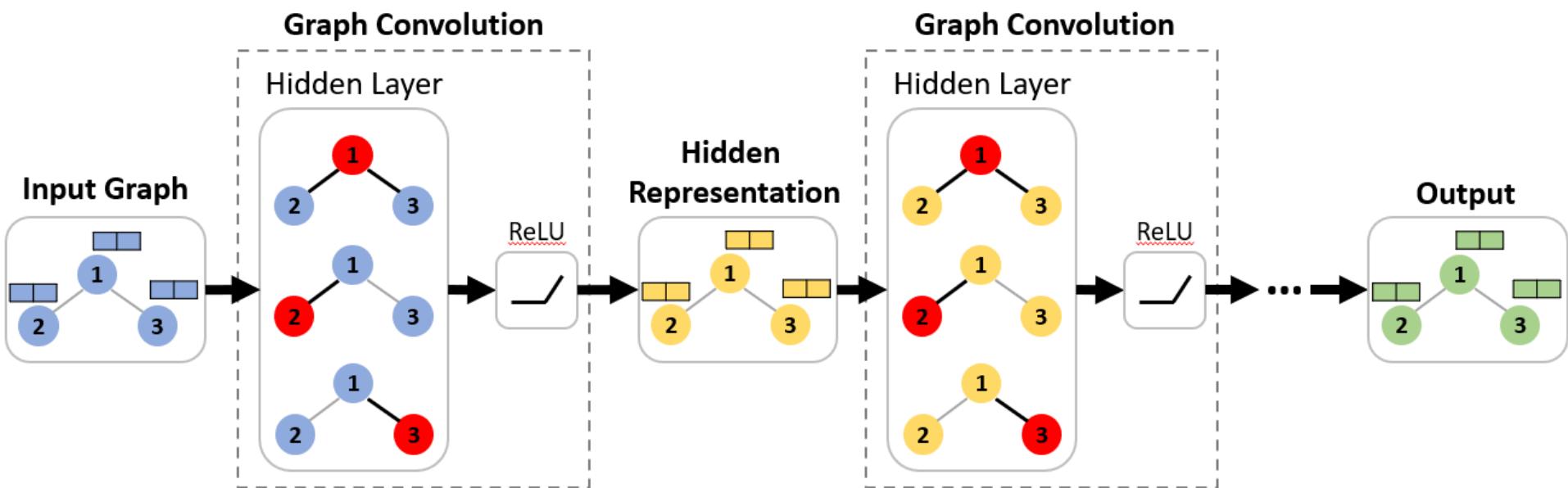
- **Key idea:** Learn node representations by aggregating information from the neighbors – a.k.a. graph convolution
- **GCN:** A stack of graph convolution layers

$$\mathbf{H}^{(l)} = \sigma(\hat{\mathbf{A}}\mathbf{H}^{(l-1)}\mathbf{W}^{(l)})$$

model weights

- $\hat{\mathbf{A}} = \tilde{\mathbf{D}}^{-\frac{1}{2}}(\mathbf{A} + \mathbf{I})\tilde{\mathbf{D}}^{-\frac{1}{2}}$
- $\tilde{\mathbf{D}}$ = degree matrix of $\mathbf{A} + \mathbf{I}$

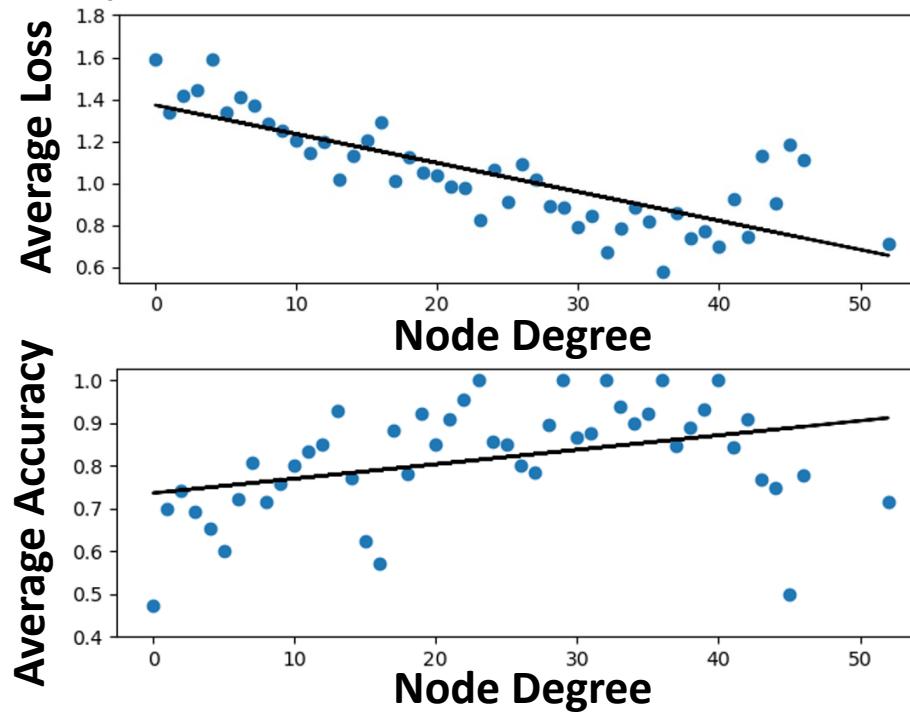
renormalized graph Laplacian



[1] Kipf, T. N., & Welling, M.. Semi-Supervised Classification with Graph Convolutional Networks. ICLR 2017.

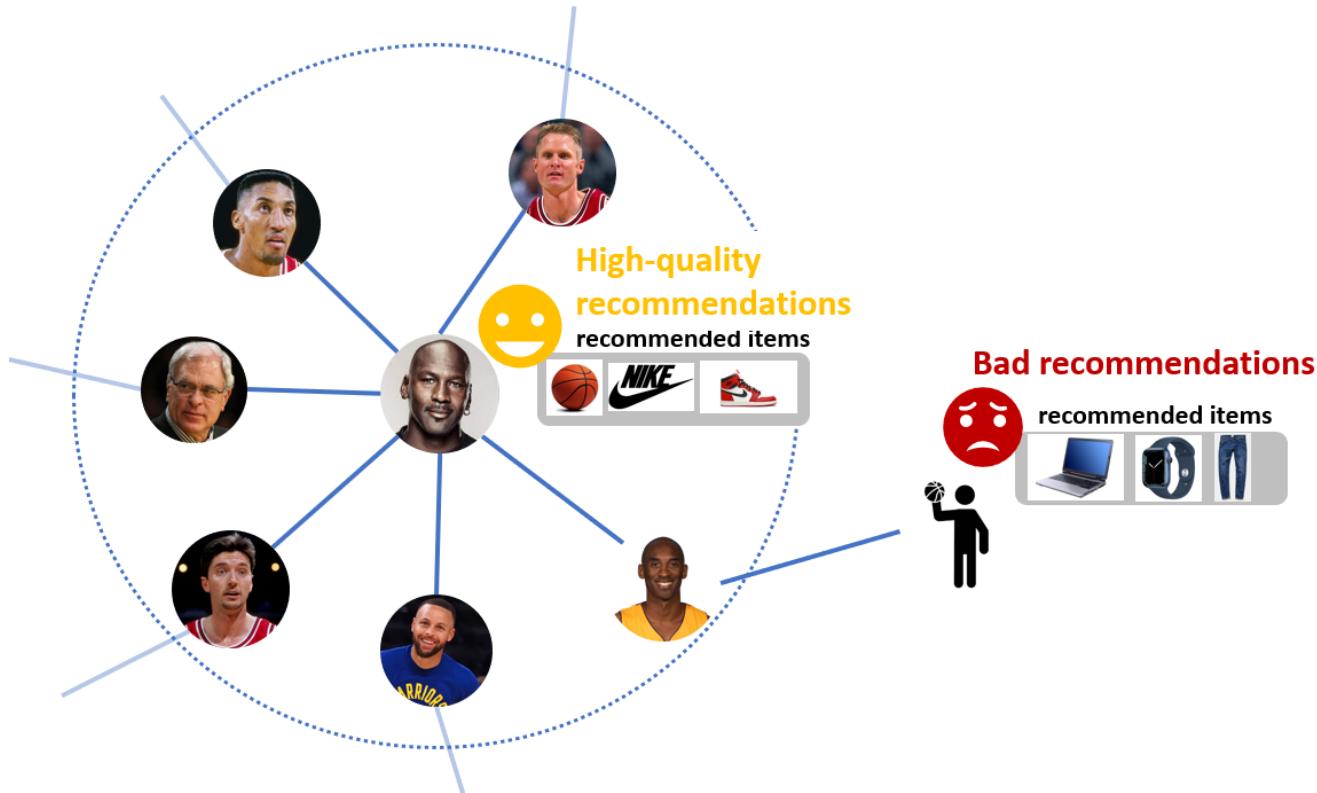
Degree-related Unfairness

- **Observation:** Low-degree node often has
 - High loss
 - Low predictive accuracy
- **Example:** Semi-supervised node classification



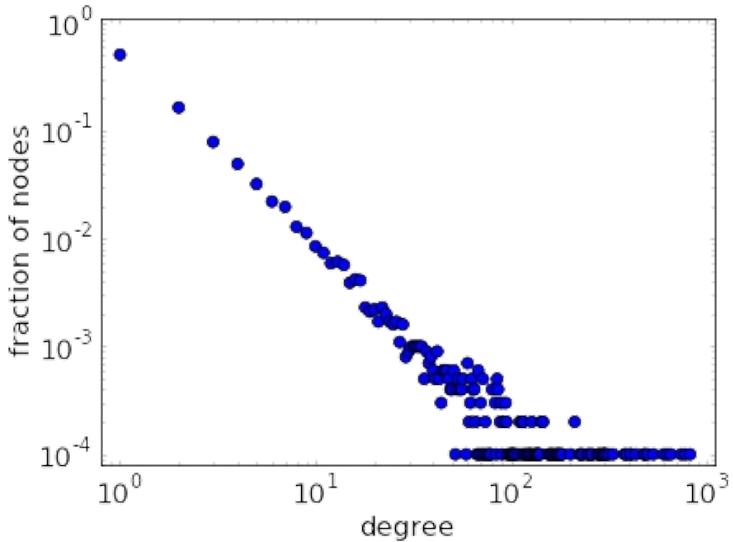
Degree-related Unfairness

- **Example:** Online advertising
 - Celebrities often enjoy high-quality recommendations
 - Grassroot users often suffer from bad recommendations



Degree Distribution

- Node degree distribution is often long-tailed



- GCN might
 - Benefit a relatively small fraction of high-degree nodes
 - Overlook a relatively large fraction of low-degree nodes

[1] Faloutsos, M., Faloutsos, P., & Faloutsos, C.. On Power-Law Relationships of the Internet Topology. CCR 1999.

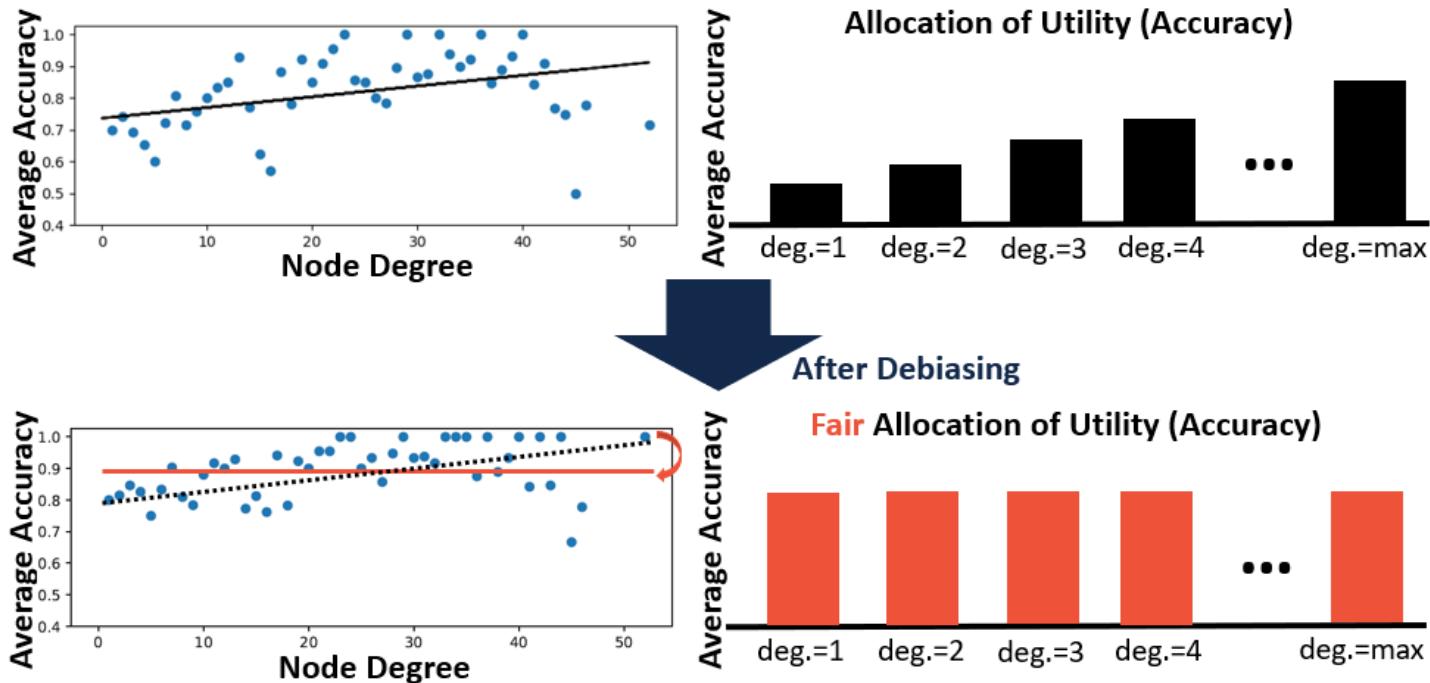
Prior Works

- **DEMO-Net**
 - **Degree-specific weight:** Learn degree-specific weights, randomly initialized
- **SL-DSGCN**
 - **Degree-specific weight:** Learn degree-specific weights, generated by RNN
 - **Self-supervised learning:** Generate pseudo labels for additional training signals
- **Tail-GNN**
 - **Neighborhood translation mechanism:** Infer missing neighborhood information of low-degree nodes
- **Limitation 1:** Additional number of weight parameters
 - DEMO-Net, SL-DSGCN
- **Limitation 2:** Change(s) to the GCN architecture
 - SL-DSGCN, Tail-GNN
- **Question:** How to mitigate degree-related unfairness without
 - Hurting the scalability of GCN
 - Changing the GCN architecture?



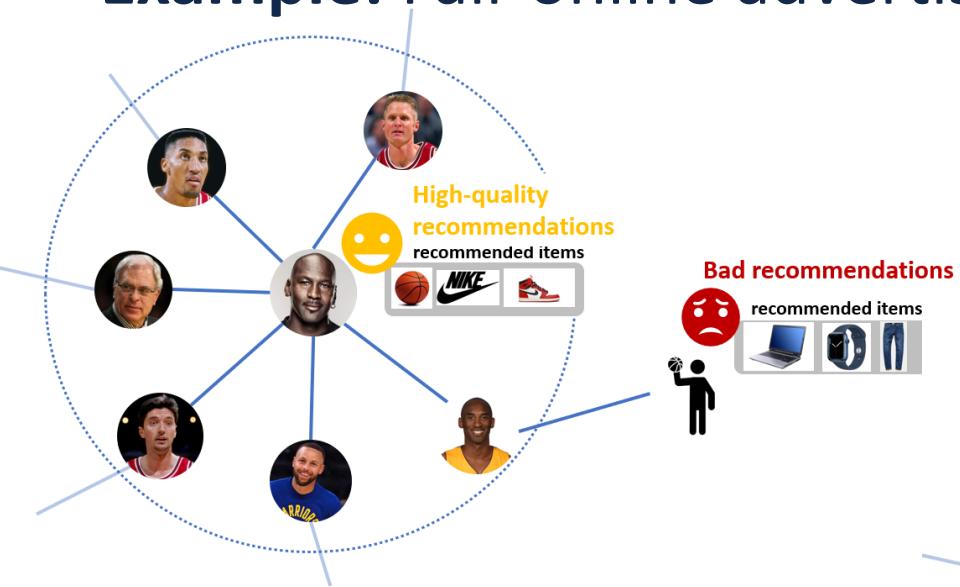
Fairness = Just Allocation of Utility

- **Intuition:** Utility = resource to allocate
- **Expected result:** Similar utility (accuracy) for all nodes regardless of their degrees
- **Example**

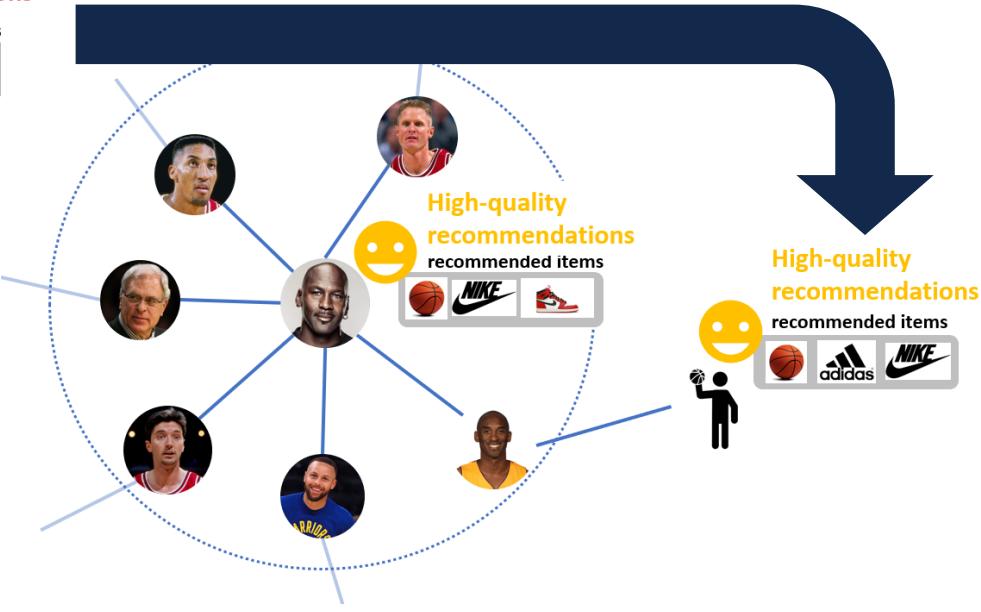


Example: Fair Allocation of Utility

- Example: Fair online advertising



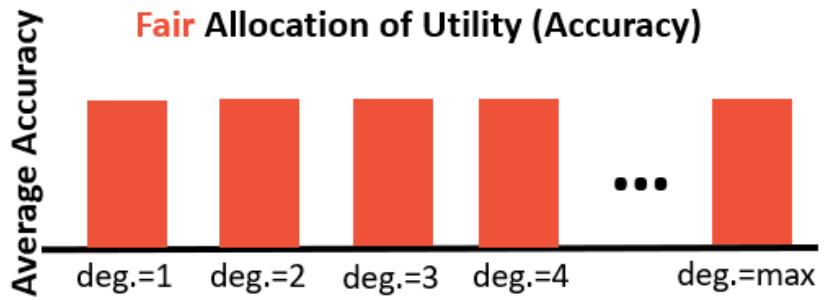
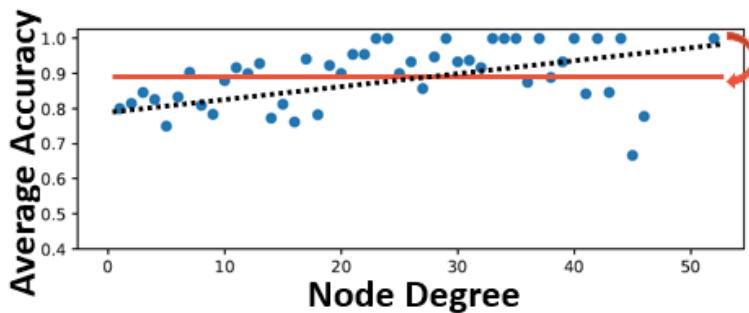
Debiasing



- Question: How to define such fairness?

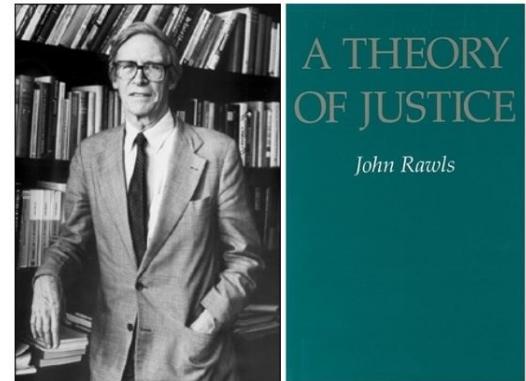
Problem Definition

- **Given**
 - An undirected graph $\mathcal{G} = (\mathbf{A}, \mathbf{X})$
 - An L -layer GCN with weights θ
 - A task-specific loss J
- **Find:** A well-trained GCN that
 - Minimizes the task-specific loss
 - Achieves a fair allocation of utility for the groups of nodes with the same degree
- **Key question:** When is the allocation of utility fair?



Rawlsian Difference Principle

- **Origin:** Distributive justice
- **Goal:** Find a fair allocation of social welfare



"Inequalities are permissible when they maximize [...] the long-term expectations of the least fortunate group."

-- John Rawls, 1971

- **Intuition:** Treat utility of GCN as welfare to allocate
 - Least fortunate group → group with the smallest utility
 - **Example:** Classification accuracy for node classification

[1] Rawls, J.. A Theory of Justice. Press, Cambridge 1971.



Key Challenge: Fair Allocation of Utility

- **Key idea:** Consider the stability of the Rawlsian difference principle
- **How to achieve the stability?**
 - Keep improving the utility of the least fortunate group
- **When do we achieve the stability?**
 - No least fortunate group
 - All groups have the balanced utility
- **Challenge:** Non-differentiable utility
 - **Workaround:** Use loss function as the proxy of utility
 - **Rationale:** Minimize loss in order to maximize utility
- **Goal:** Fair allocation of utility → balanced loss

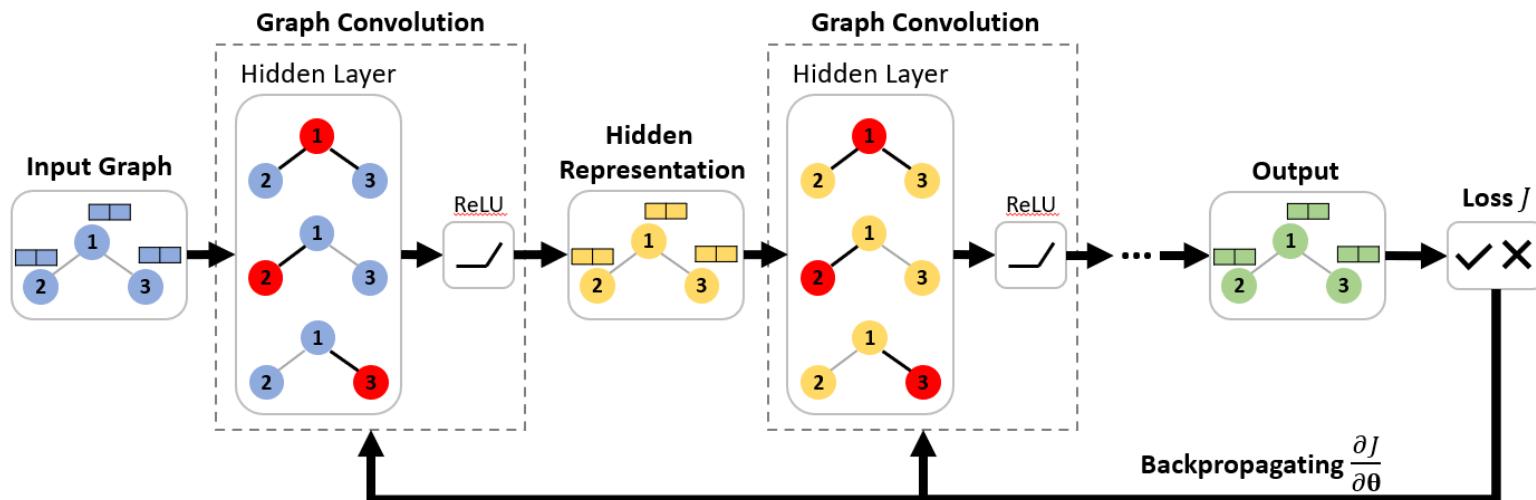


Roadmap

- Motivation
- Theory: Source of Unfairness
- Algorithms: RawlsGCN
- Experiments
- Conclusion

Theory: Source of Unfairness

- **Intuition:** Understand why the loss varies **after training**
- **What happens during training?**
 - Extract node representations
 - Predict the outcomes using the node representations
 - Calculate the task-specific loss J
 - Update model weights θ by **the gradient** $\frac{\partial J}{\partial \theta} \leftarrow$ key component for training
- **Question:** Is the unfairness caused by the gradient?



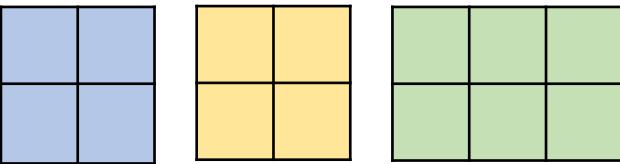
The Gradient of Model Weights

- Given

- An undirected graph $\mathcal{G} = (\mathbf{A}, \mathbf{X})$ with $\widehat{\mathbf{A}} = \widetilde{\mathbf{D}}^{-\frac{1}{2}}(\mathbf{A} + \mathbf{I})\widetilde{\mathbf{D}}^{-\frac{1}{2}}$
- An arbitrary l -th graph convolution layer
 - Weight matrix $\mathbf{W}^{(l)}$
 - Hidden representations before activation $\mathbf{E}^{(l)} = \widehat{\mathbf{A}}\mathbf{H}^{(l-1)}\mathbf{W}^{(l)}$
- A task-specific loss J
- The gradient of loss J w.r.t. weight $\mathbf{W}^{(l)}$

$$\frac{\partial J}{\partial \mathbf{W}^{(l)}} = (\mathbf{H}^{(l-1)})^T \widehat{\mathbf{A}}^T \frac{\partial J}{\partial \mathbf{E}^{(l)}}$$

$$\frac{\partial J}{\partial \mathbf{W}^{(l)}} = (\mathbf{H}^{(l-1)})^T \widehat{\mathbf{A}}^T \frac{\partial J}{\partial \mathbf{E}^{(l)}}$$

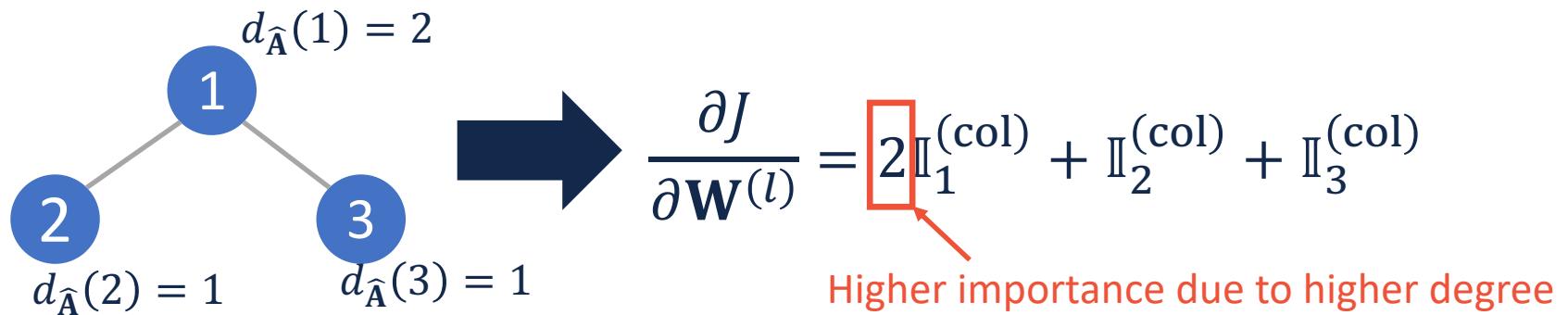


Source of Unfairness: Results

- $\frac{\partial J}{\partial \mathbf{W}^{(l)}}$ is a linear summation of node influence weighted by its degree in $\widehat{\mathbf{A}}$

$$\frac{\partial J}{\partial \mathbf{W}^{(l)}} = \sum_{i=1}^n d_{\widehat{\mathbf{A}}}(i) \mathbb{I}_i^{(\text{col})} = \sum_{j=1}^n d_{\widehat{\mathbf{A}}}(j) \mathbb{I}_j^{(\text{row})}$$

- $\mathbb{I}_i^{(\text{col})} = (\mathbb{E}_{j \sim \mathcal{N}(i)} [\mathbf{H}^{(l-1)}[j, :]])^T \frac{\partial J}{\partial \mathbf{E}^{(l)}[i, :]}$
- $\mathbb{I}_j^{(\text{row})} = (\mathbf{H}^{(l-1)}[j, :])^T \mathbb{E}_{i \sim \widehat{\mathcal{N}}(j)} \left[\frac{\partial J}{\partial \mathbf{E}^{(l)}[i, :]} \right]$
- $j \sim \widehat{\mathcal{N}}(i)$: Sampling node j from neighborhood of node i in $\widehat{\mathbf{A}}$
 - Sampling probability is proportional to $\widehat{\mathbf{A}}[i, j]$

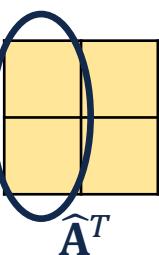


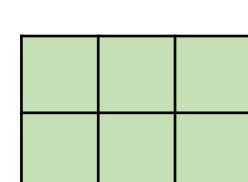
Source of Unfairness: Column-wise Influence

- $\frac{\partial J}{\partial \mathbf{W}^{(l)}}$ is a linear summation of node influence weighted by its degree in $\widehat{\mathbf{A}}$

$$\frac{\partial J}{\partial \mathbf{W}^{(l)}} = \sum_{i=1}^n d_{\widehat{\mathbf{A}}}(i) \mathbb{I}_i^{(\text{col})} = \sum_{j=1}^n d_{\widehat{\mathbf{A}}}(j) \mathbb{I}_j^{(\text{row})}$$

- $\mathbb{I}_i^{(\text{col})} = (\mathbb{E}_{j \sim \mathcal{N}(i)} [\mathbf{H}^{(l-1)}[j, :]])^T \frac{\partial J}{\partial \mathbf{E}^{(l)}[i, :]}$
- $\mathbb{I}_j^{(\text{row})} = (\mathbf{H}^{(l-1)}[j, :])^T \mathbb{E}_{i \sim \widehat{\mathcal{N}}(j)} \left[\frac{\partial J}{\partial \mathbf{E}^{(l)}[i, :]} \right]$
- $j \sim \widehat{\mathcal{N}}(i)$: Sampling node j from neighborhood of node i in $\widehat{\mathbf{A}}$
 - Sampling probability is proportional to $\widehat{\mathbf{A}}[i, j]$

$$d_{\widehat{\mathbf{A}}}(i) = \text{sum } \widehat{\mathbf{A}}^T$$


$$\mathbb{I}_i^{(\text{col})} = \mathbb{E} \left[\begin{array}{|c|c|} \hline & & \\ \hline & & \\ \hline & & \\ \hline \end{array} \right] \frac{\partial J}{\partial \mathbf{E}^{(l)}} \quad \left(\mathbf{H}^{(l-1)} \right)^T$$


Source of Unfairness: Row-wise Influence

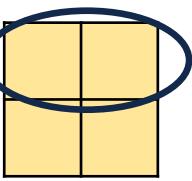
- $\frac{\partial J}{\partial \mathbf{W}^{(l)}}$ is a linear summation of node influence weighted by its degree in $\widehat{\mathbf{A}}$

$$\frac{\partial J}{\partial \mathbf{W}^{(l)}} = \sum_{i=1}^n d_{\widehat{\mathbf{A}}}(i) \mathbb{I}_i^{(\text{col})} = \sum_{j=1}^n d_{\widehat{\mathbf{A}}}(j) \mathbb{I}_j^{(\text{row})}$$

– $\mathbb{I}_i^{(\text{col})} = (\mathbb{E}_{j \sim \mathcal{N}(i)} [\mathbf{H}^{(l-1)}[j, :]])^T \frac{\partial J}{\partial \mathbf{E}^{(l)}[i, :]}$

– $\mathbb{I}_j^{(\text{row})} = (\mathbf{H}^{(l-1)}[j, :])^T \mathbb{E}_{i \sim \widehat{\mathcal{N}}(j)} \left[\frac{\partial J}{\partial \mathbf{E}^{(l)}[i, :]} \right]$

- $j \sim \widehat{\mathcal{N}}(i)$: Sampling node j from neighborhood of node i in $\widehat{\mathbf{A}}$
- Sampling probability is proportional to $\widehat{\mathbf{A}}[i, j]$

$$d_{\widehat{\mathbf{A}}}(j) = \text{sum } \widehat{\mathbf{A}}^T$$


$$\mathbb{I}_j^{(\text{row})} = \mathbb{E} \left[\begin{array}{c} \text{[4x4 matrix with green shaded 2x2 block in top-left]} \\ \frac{\partial J}{\partial \mathbf{E}^{(l)}} \end{array} \right]$$

$$(\mathbf{H}^{(l-1)})^T$$

Source of Unfairness: Summary

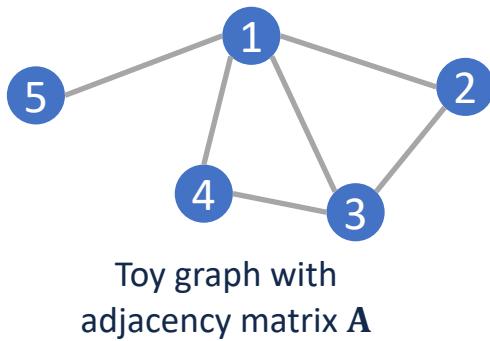
- Gradient of loss w.r.t. weight

$$\frac{\partial J}{\partial \mathbf{W}^{(l)}} = \sum_{i=1}^n d_{\hat{\mathbf{A}}}(i) \mathbb{I}_i^{(\text{col})} = \sum_{j=1}^n d_{\hat{\mathbf{A}}}(j) \mathbb{I}_j^{(\text{row})}$$

- Intuitions

- $\mathbb{I}_i^{(\text{col})}$ and $\mathbb{I}_j^{(\text{row})}$ → The directions for gradient descent
- $d_{\hat{\mathbf{A}}}(i)$ and $d_{\hat{\mathbf{A}}}(j)$ → The importance of the direction

- High degree → more focus on the corresponding direction
- Question: Why does the node degree vary in $\hat{\mathbf{A}}$?



Node degree in \mathbf{A}

- $d_{\mathbf{A}}(1) = 4$
- $d_{\mathbf{A}}(2) = 2$
- $d_{\mathbf{A}}(3) = 3$
- $d_{\mathbf{A}}(4) = 2$
- $d_{\mathbf{A}}(5) = 1$

Node degree in $\hat{\mathbf{A}}$

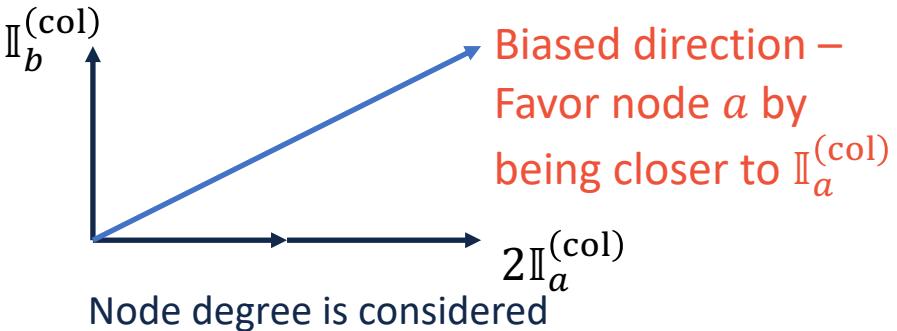
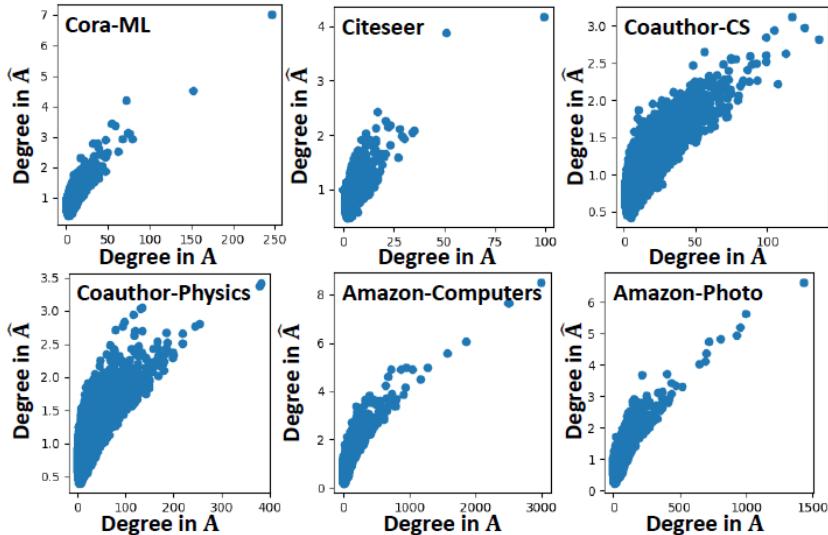
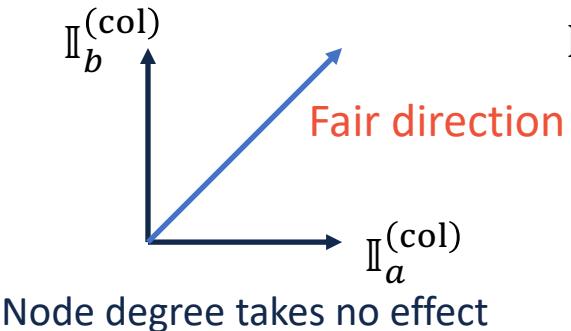
- $d_{\hat{\mathbf{A}}}(1) = 1.26$
- $d_{\hat{\mathbf{A}}}(2) = 0.88$
- $d_{\hat{\mathbf{A}}}(3) = 1.05$
- $d_{\hat{\mathbf{A}}}(4) = 0.88$
- $d_{\hat{\mathbf{A}}}(5) = 0.82$

Different node degrees

Symmetric Normalization

- **Key idea:** Normalize the largest eigenvalue, but not degree
- **Observation:** High degree in $A \rightarrow$ high degree in \hat{A}
 - $\frac{\partial J}{\partial W^{(l)}}$ favors high-degree nodes in A due to such positive correlation
- **Consequence:** $\frac{\partial J}{\partial W^{(l)}}$ calculated using \hat{A} is biased
- **Example**

Node a : $d_{\hat{A}}(a) = 2$
 Node b : $d_{\hat{A}}(b) = 1$



Doubly Stochastic Matrix Computation



- **How to mitigate unfairness in $\frac{\partial J}{\partial \mathbf{w}^{(l)}}$?**
 - **Intuition:** Enforce row sum and column sum of $\hat{\mathbf{A}}$ to be 1
 - **Solution:** Doubly stochastic normalization on $\hat{\mathbf{A}}$
- **Method:** Sinkhorn-Knopp algorithm
 - **Key idea:** Iteratively normalize the row and column of a matrix
 - **Complexity:** Linear time and space complexity
 - **Convergence:** Always converge iff. the matrix has total support
- **Question:** Can we find the doubly stochastic form of $\hat{\mathbf{A}}$?



Existence of Doubly Stochastic Matrix

- Given
 - An undirected graph $\mathcal{G} = (\mathbf{A}, \mathbf{X})$
 - The degree matrix $\tilde{\mathbf{D}}$ of $\mathbf{A} + \mathbf{I}$
 - The renormalized graph Laplacian $\hat{\mathbf{A}} = \tilde{\mathbf{D}}^{-\frac{1}{2}}(\mathbf{A} + \mathbf{I})\tilde{\mathbf{D}}^{-\frac{1}{2}}$
- The Sinkhorn-Knopp algorithm **always** finds the unique doubly stochastic form $\hat{\mathbf{A}}_{DS}$ of $\hat{\mathbf{A}}$
 - (Check detailed proof in the paper)



Roadmap

- Motivation
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- Algorithms: RawlsGCN
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The Family of RawlsGCN

- Gradient computation

$$\left(\frac{\partial J}{\partial \mathbf{W}^{(l)}} \right)_{\text{fair}} = (\mathbf{H}^{(l-1)})^T \hat{\mathbf{A}}_{\text{DS}}^T \frac{\partial J}{\partial \mathbf{E}^{(l)}}$$

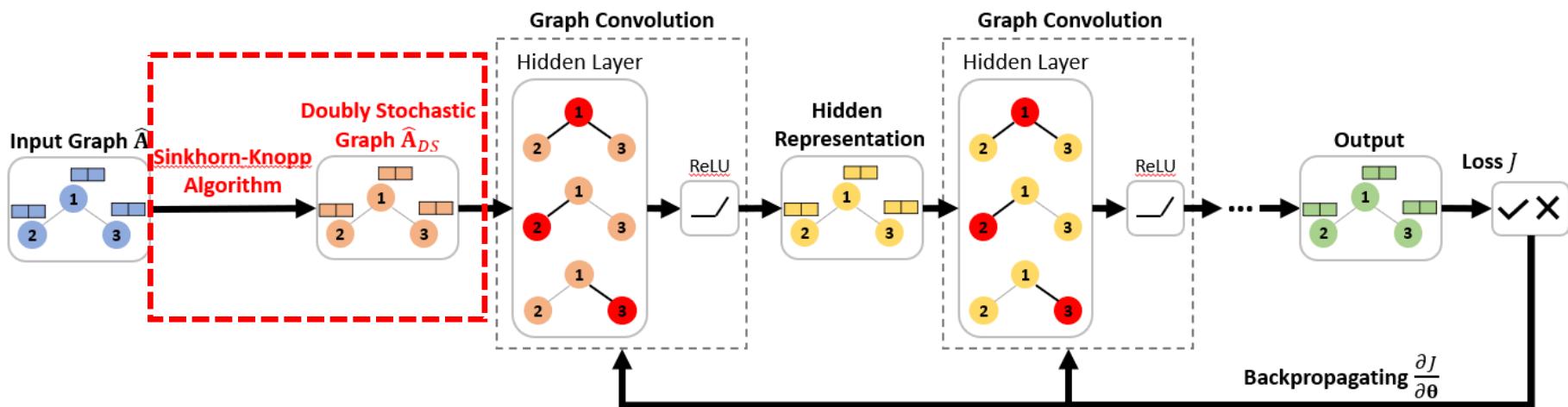
– Key term: $\hat{\mathbf{A}}_{\text{DS}}$ – Doubly-stochastic normalization of $\hat{\mathbf{A}}$

- Proposed methods

- **RawlsGCN-Graph:** During **data pre-processing**, compute $\hat{\mathbf{A}}_{\text{DS}}$ and treat it as the input of GCN
- **RawlsGCN-Grad:** During **optimization (in-processing)**, treat $\hat{\mathbf{A}}_{\text{DS}}$ as a normalizer to equalize the importance of node influence

RawlsGCN-Graph: Pre-processing

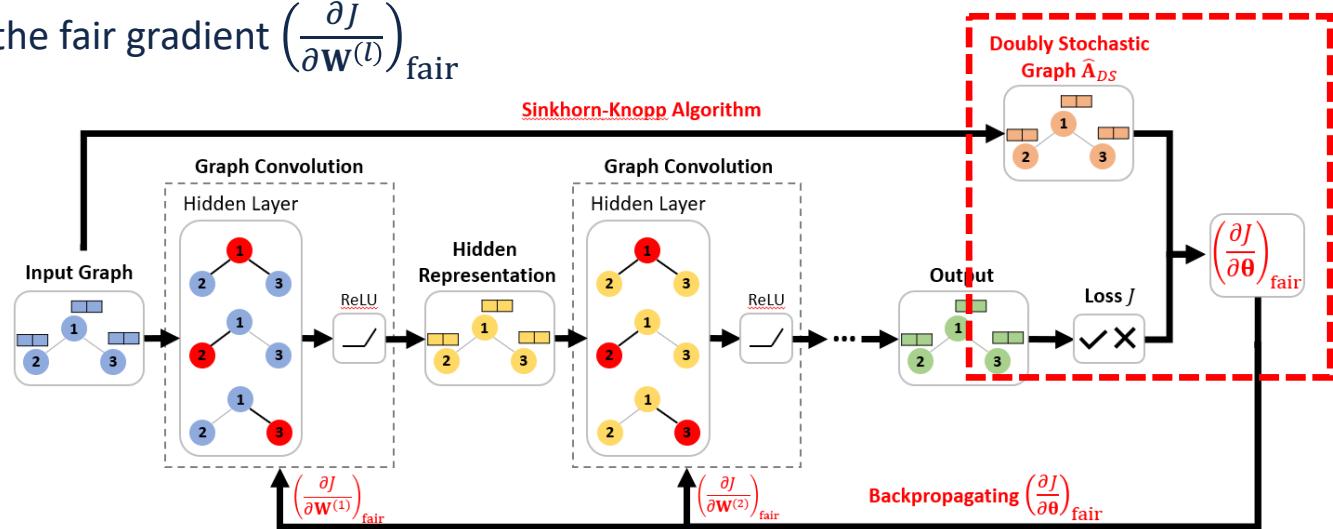
- **Intuition:** Normalize the input renormalized graph Laplacian into a doubly stochastic matrix
- **Key steps**
 1. Precompute the renormalized graph Laplacian $\hat{\mathbf{A}}$
 2. Precompute $\hat{\mathbf{A}}_{DS}$ by applying the Sinkhorn-Knopp algorithm
 3. Input $\hat{\mathbf{A}}_{DS}$ and \mathbf{X} (node features) to GCN for training



RawlsGCN-Grad: In-processing

- **Intuition:** Equalize the importance of node influence in gradient computation
- **Key steps**

1. Precompute the renormalized graph Laplacian $\widehat{\mathbf{A}}$
2. Input $\widehat{\mathbf{A}}$ and \mathbf{X} (node features) to GCN
3. Compute $\widehat{\mathbf{A}}_{DS}$ by applying the Sinkhorn-Knopp algorithm
4. Repeat until maximum number of training epochs
 - Compute the fair gradient $\left(\frac{\partial J}{\partial \mathbf{W}^{(l)}}\right)_{\text{fair}} = (\mathbf{H}^{(l-1)})^T \widehat{\mathbf{A}}_{DS}^T \frac{\partial J}{\partial \mathbf{E}^{(l)}}$ using $\widehat{\mathbf{A}}_{DS}$
 - Update $\mathbf{W}^{(l)}$ by the fair gradient $\left(\frac{\partial J}{\partial \mathbf{W}^{(l)}}\right)_{\text{fair}}$





Roadmap

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Experiments: Settings

- Task: Semi-supervised node classification
- Datasets

Name	Nodes	Edges	Features	Classes	Median Deg.
Cora-ML	2,995	16,316	2,879	7	3
Citeseer	3,327	9,104	3,703	6	2
Coauthor-CS	18,333	163,788	6,805	15	6
Coauthor-Physics	34,493	495,924	8,415	5	10
Amazon-Computers	13,752	491,722	767	10	22
Amazon-Photo	7,650	238,162	745	8	22

- Baseline methods
 - Vanilla model: GCN
 - Fairness-aware models: DEMO-Net, DSGCN, Tail-GNN, Adversarial Fair GCN, REDRESS
- Metrics
 - Utility: Classification Accuracy
 - Bias: Variance of average loss values

Experiments: Node Classification

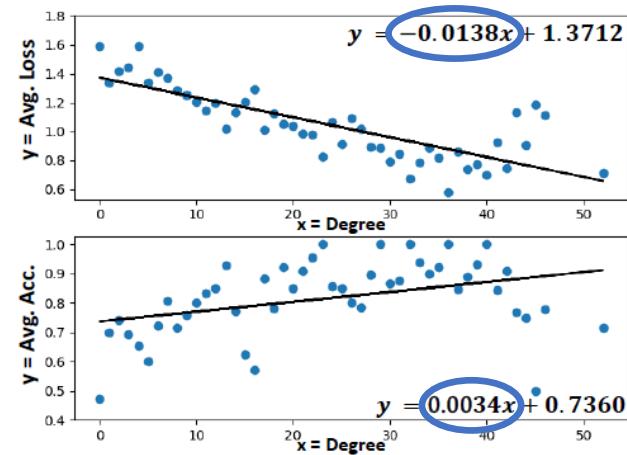
Method	Coauthor-Physics		Amazon-Computers		Amazon-Photo	
	Acc.	Bias	Acc.	Bias	Acc.	Bias
GCN	93.96 ± 0.367	0.023 ± 0.001	64.84 ± 0.641	0.353 ± 0.026	79.58 ± 1.507	0.646 ± 0.038
DEMO-Net	77.50 ± 0.566	0.084 ± 0.010	26.48 ± 3.455	0.456 ± 0.021	39.92 ± 1.242	0.243 ± 0.013
DSGCN	79.08 ± 1.533	0.262 ± 0.075	27.68 ± 1.663	1.407 ± 0.685	26.76 ± 3.387	0.921 ± 0.805
Tail-GNN	OOM	OOM	76.24 ± 1.491	1.547 ± 0.670	86.00 ± 2.715	0.471 ± 0.264
AdvFair	87.44 ± 1.132	0.892 ± 0.502	53.50 ± 5.362	4.395 ± 1.102	75.80 ± 3.563	51.24 ± 39.94
REDRESS	94.48 ± 0.172	0.019 ± 0.001	80.36 ± 0.206	0.455 ± 0.032	89.00 ± 0.369	0.186 ± 0.030
RawlsGCN-Graph (Ours)	94.06 ± 0.196	0.016 ± 0.000	80.16 ± 0.859	0.121 ± 0.010	88.58 ± 1.116	0.071 ± 0.006
RawlsGCN-Grad (Ours)	94.18 ± 0.306	0.021 ± 0.002	74.18 ± 2.530	0.195 ± 0.029	83.70 ± 0.672	0.186 ± 0.068

- Observations

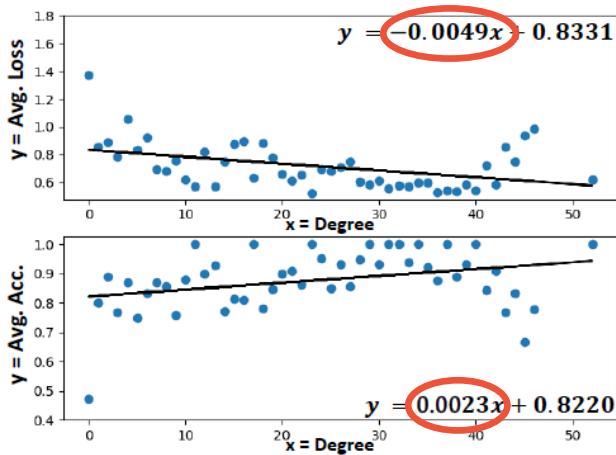
- RawlsGCN achieves the smallest bias
- Classification accuracy can be improved
 - mitigating the bias → higher accuracy for low-degree nodes

\downarrow
 Higher overall accuracy

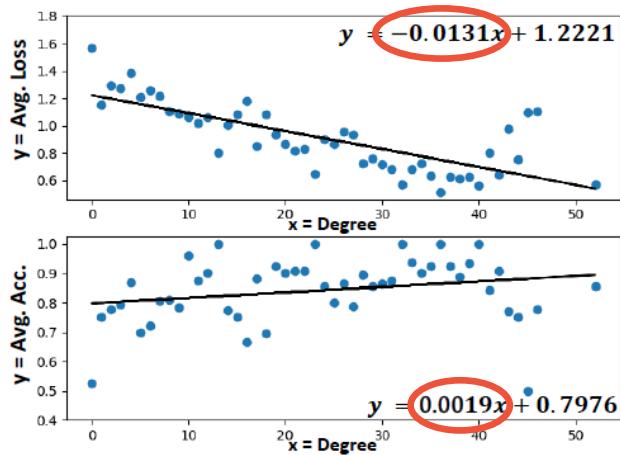
Experiments: Node Classification



(a) GCN



(b) RawlsGCN-Graph



(c) RawlsGCN-Grad

- **Observation:** RawlsGCN achieves more balanced loss and classification accuracy
 - Flatter slope of the regression line for RawlsGCN (in orange) than GCN (in blue)

Experiments: Efficiency

Method	# Param.	Memory	Training Time
GCN (100 epochs)	48,264	1,461	13.335
GCN (200 epochs)	48,264	1,461	28.727
DEMO-Net	11,999,880	1,661	9158.5
DSGCN	181,096	2,431	2714.8
Tail-GNN	2,845,567	2,081	94.058
AdvFair	89,280	1,519	148.11
REDRESS	48,264	1,481	291.69
RawlsGCN-Graph (Ours)	48,264	1,461	11.783
RawlsGCN-Grad (Ours)	48,264	1,461	12.924

- Observation:** RawlsGCN has the best efficiency compared with other baseline methods
 - Same number of parameters and memory usage (in MB)
 - Much shorter training time (in seconds)

Experiments: Ablation Study

Method	Normalization	Acc.	Bias
RawLSGCN-Graph	Row	87.98 ± 0.791	0.076 ± 0.006
	Column	88.32 ± 2.315	0.138 ± 0.112
	Symmetric	89.12 ± 0.945	0.071 ± 0.005
	Doubly Stochastic	88.58 ± 1.116	0.071 ± 0.006
RawLSGCN-Grad	Row	82.86 ± 1.139	0.852 ± 0.557
	Column	84.96 ± 1.235	0.221 ± 0.064
	Symmetric	82.92 ± 1.121	0.744 ± 0.153
	Doubly Stochastic	83.70 ± 0.672	0.186 ± 0.068

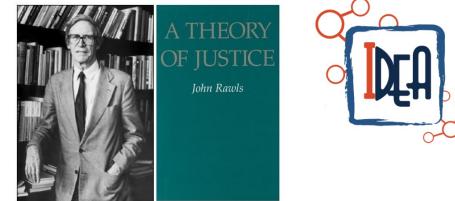
- **Observation:** Doubly stochastic normalization is the best normalization technique to balance accuracy and fairness



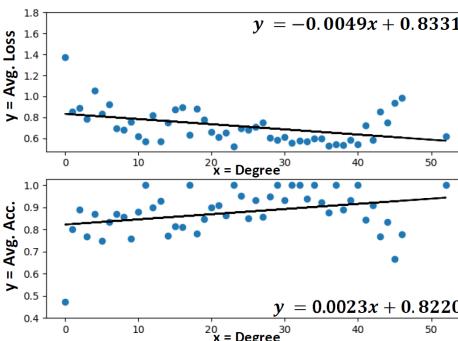
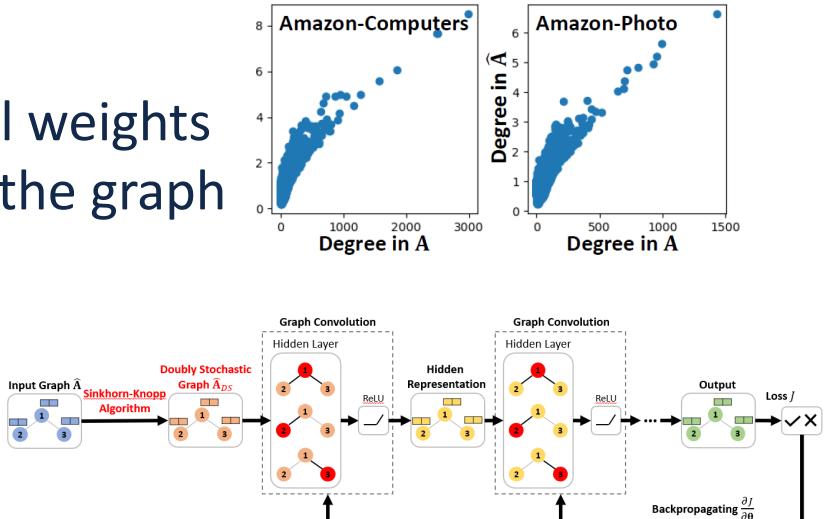
Roadmap

- Motivation
- Theory: Source of Unfairness
- Algorithms: RawlsGCN
- Experiments
- Conclusion

Conclusion



- **Problem:** Enforce the Rawlsian difference principle on GCN
- **Source of unfairness**
 - Analysis on the gradient w.r.t. model weights
 - Doubly stochastic normalization on the graph
- **Solution:** RawlsGCN
 - Pre-processing by RawlsGCN-Graph
 - In-processing by RawlsGCN-Grad
- **Results**
 - Effectiveness in bias mitigation while maintaining accuracy
 - Significant improvement in efficiency
- More details in the paper
 - Proofs and analysis
 - Detailed experiments



Title: RawlsGCN: Towards Rawlsian Difference Principle on Graph Convolutional Network

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