Notations

- $Y \in \mathcal{Y}$: outcome variable
- $X = (X_1, X_2)$ two subsets of covariate varibles
 - \circ Study how much different model depend on X_1 to predict Y
- $ullet Z=(Y,X_1,X_2)\in \mathcal{Z}$
- data set $\mathbf{Z} = \left[\mathbf{y}^{n \times 1}, \mathbf{X}^{n \times p}\right]$
- ullet Z is iid
- Model Class $\mathcal{F} \subset \{f|f: \mathcal{X} \to \mathcal{Y}\}$
 - $\circ f(x)$ or $f(x_1, x_2)$ as a prediction model
- Loss function *L*
 - Squared Error Loss $L(f,z)=(y-f(x))^2$
- ullet Algorithm : $\mathcal{A}:\mathcal{Z}^n o\mathcal{F}$: $f=A(\mathbf{Z})$

Alogorithm Reliance (Existing Metic)

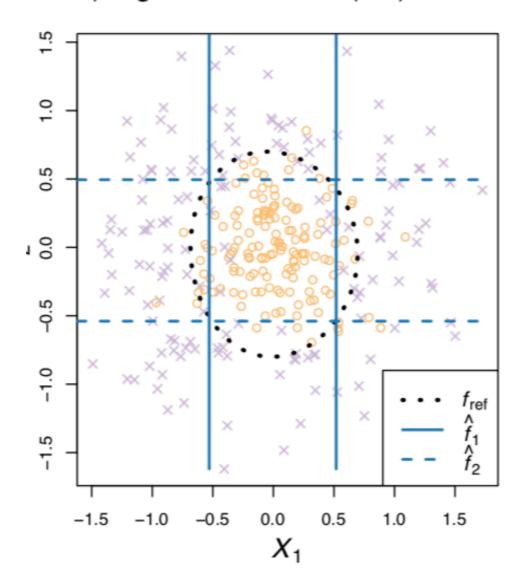
Algorithm (model-fitting algorithm) reliance (AR) on X_1 :

- run a model-fitting algorithm A twice,
 - o first on all of the data,
 - \circ and then again after removing X_1 from the dataset .
- ullet The losses for the two resulting models are then compared to determine the importance, or "necessity," of X_1

AR property

- This measure is a function of two prediction models rather than one,
 - it does not measure how much either individual model relies on X1.
- AR can result in seemingly incoherent behavior. Specifically, if several prediction models fit the data well, then removing a variable may not substantially change the prediction loss even if **the best prediction model relies heavily on that variable.**
 - can identify the strongest performing prediction model with no reliance on a given variable, but they generally do not bound how much any well-performing model may rely on that variable.

1) Algorithm reliance (AR)



MR: Model Reliance

How much a model, a model-fitting algorithm, or a model class, relies on a subset of covariates X_1 .

 $X = [X_1:(height), X_2:(age)]$, $x^a = (1.6,21), x^b = (1.8,22)$

- ullet 'Switched Loss' \colon be the loss of model f on $z^{(b)}$, if $x_1^{(b)}$ was first replaced with $x_1^{(a)}$:
 - Like anchors? fixed some feature and permutate

$$egin{aligned} h_f(z^a,z^b) &:= L(f,(y^b,x_1^{(a)},x_2^{(b)})) \ e_{switch}(f) &:= \mathbb{E} h_f(Z^{(a)},Z^{(b)}) \ \hat{e}_{switch}(f) &:= rac{1}{(n-1)(n)} \sum_{i=1}^n \sum_{j
eq i} h_f(\mathbf{Z}_{[i,:]},\mathbf{Z}_{[j,:]}) \ &= rac{1}{(n-1)(n)} \sum_{i=1}^n \sum_{j
eq i} L(f,(\mathbf{y}_{[i]},\mathbf{X}_{1[i,:]},\mathbf{X}_{2[j,:]})) \end{aligned}$$

• 'Original Loss' i.e, the standard loss

$$egin{aligned} e_{orig}(f) := \mathbb{E} h_f(Z^{(a)}, Z^{(a)}) \ \hat{e}_{orig}(f) := rac{1}{n} \sum_{i=1}^n L(f, \mathbf{Z}_{[i,:]}) = \hat{\mathbb{E}} L(f, Z) \end{aligned}$$

• Model Reliance: the ratio of switched loss and original loos

$$MR(f) =: rac{e_{switch}(f)}{e_{orig}(f)} \ \hat{M}R(f) =: rac{\hat{e}_{switch}(f)}{\hat{e}_{orig}(f)}$$

Model Reliance and Causal Effects

Causal Inferene Literature

Rename:
$$(Y, X_1, X_2) \Rightarrow (Y, T, C)$$
 $T: X_1$ represents a binary treatment indicator $\{0,1\}$
 $C: X_2$ a set of baseline covariates
 $f^*(t,c) = \mathbb{E}(Y|C=c,T=t)$

ullet Y_1,Y_0 : potential outcomes under treatment and control respectively

$$\circ \ \ Y = Y_0(1-T) + Y_1T.$$

$$\bullet \ \ \text{i.e., if } T=0, Y=Y_0, \text{if } T=1, Y=Y_1$$

- ullet Treatment Effect: Y_1-Y_0
- Average treatment effect : $\mathbb{E}[Y_1 Y_0]$
- Conditional average treatment effect :

$$\mathcal{TE}(c): \mathbb{E}[Y_1 - Y_0 | C = c] = \mathbb{E}[Y_1 | C = c, T = 1] - \mathbb{E}[Y_0 | C = c, T = 0] = f^*(t = 1, c) - f^*(t = 0, c)$$

• $P(T=1|C=c) \in (0,1)$

Relation between $\mathcal{TE}(c)$ and the model reliance $e_{orig}(f^*) - e_{switch}(f^*)$

suppose the loss function is $L(f,(y,t,c)):=(y-f(t,c))^2$

Relation

$$e_{orig}(f^*) - e_{switch}(f^*) = \operatorname{Var}(T) \sum_{t \in \{0,1\}} \mathbb{E}_{C|T=t} \mathcal{TE}(C)^2$$

Model reliance for linear models

For any prediction model f and squared error loss , and $f_{eta}(x)=X_1^Teta_1+X_2^Teta_2$ then,

$$e_{switch}(f) - e_{orig}(f) = 2Cov(Y, X_1)\beta_1 - 2\beta_2^T Cov(X_2, X_1)\beta_1$$

• Model reliance for linear models can be interpreted in terms of the **population covariances** and the model coefficients.

Model Class Reliance

$$\text{subset of good models: } \mathcal{R}(\epsilon, f^*, \mathcal{F}) := \{f \in \mathcal{F} : e_{orig}(f) \leq e_{orig}(f^*) + \epsilon\}$$

$$egin{aligned} MCR_+(\epsilon,f^*,\mathcal{F}) := \max_{f \in \mathcal{R}(\epsilon,f^*,\mathcal{F}):} MR(f) \ MCR_-(\epsilon,f^*,\mathcal{F}) := \min_{f \in \mathcal{R}(\epsilon,f^*,\mathcal{F}):} MR(f) \end{aligned}$$

- if MCR_+ is low, no well performing model exists that places high importance on X_1
- ullet if MCR_- is large, then every well performing model must rely substantially on X_1
- ullet In practice, we need to use f_{ref} to approximate the optimal f^*

Finite-sample bounds for model class reliance

Assumptions:

Bounded individual loss

$$f \in \mathcal{F}: L(f_{ref}, (y, x_1, x_2) \leq B_{ind}$$

Bounded relative loss)

$$|L(f,(y,x_1,x_2)-L(f_{ref},(y,x_1,x_2))| \leq B_{ref}$$

• Bounded average loss)

$$\mathbb{P}(0 \leq b_{avg} \leq \hat{e}_{orig}(f) \leq B_{avg}) = 1$$

Suppose $f_{+,\epsilon}=\in \arg\max_{\mathcal{R}(\epsilon)} MR(f)$ and $f_{-,\epsilon}=\in \arg\min_{\mathcal{R}(\epsilon)} MR(f)$ satisfy the above assumptions, then

$$egin{aligned} \mathbb{P}(MCR_{+}(\epsilon) > \widehat{MCR}_{+}(\epsilon_{1}) + \mathcal{Q}_{1}) & \leq \delta \ \mathbb{P}(MCR_{-}(\epsilon) < \widehat{MCR}_{-}(\epsilon_{1}) - \mathcal{Q}_{1}) & \leq \delta \ \epsilon_{1} := \epsilon + 2B_{ref}\sqrt{rac{\log(3\delta^{-1})}{2n}} \ \mathcal{Q}_{1} := rac{B_{avg}}{b_{avg}} - rac{B_{avg} - B_{ind}\sqrt{rac{\log(3\delta^{-1})}{n}}}{b_{avg}+B_{ind}\sqrt{rac{\log(3\delta^{-1})}{2n}}} \end{aligned}$$

r-margin-expection-cover : a function set \mathcal{G}_r : if for any $f \in \mathcal{F}$, and distribution D, there exists a $g \in \mathcal{G}_r$ such taht

$$\mathbb{E}_{Z\sim D}|L(f,Z)-L(g,Z)|\leq r$$
 $\mathcal{N}(\mathcal{F},r): ext{covering number: the size of smallest } \mathcal{G}_R$

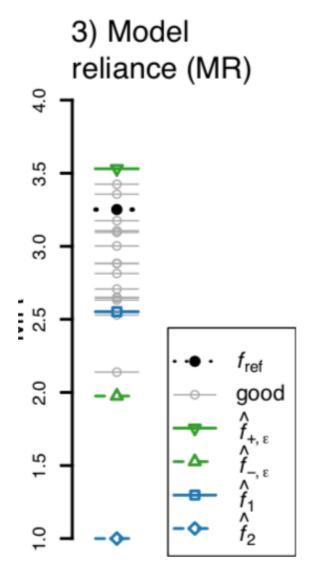
$$\mathbb{P}(MCR_+(\epsilon) < \widehat{MCR}_+(\epsilon_3) + \mathcal{Q}_3) \leq \delta \ \mathbb{P}(MCR_-(\epsilon) > \widehat{MCR}_-(\epsilon_3) - \mathcal{Q}_3) \leq \delta \ \epsilon_3 = \epsilon - 2B_{ref}\sqrt{rac{\log(4\delta^{-1}\mathcal{N}(\mathcal{F},r\sqrt{2}))}{n}} - 2r \ \mathcal{Q}_3 := rac{B_{avg}}{b_{avg}} - rac{B_{avg} - B_{ind}\sqrt{\log(8\delta^{-1}\mathcal{N}(\mathcal{F},r\sqrt{2})/n} - 2r\sqrt{2}}{b_{avg} + B_{ind}\sqrt{\log(8\delta^{-1}\mathcal{N}(\mathcal{F},r)/2n} - 2r}$$

Illustrations

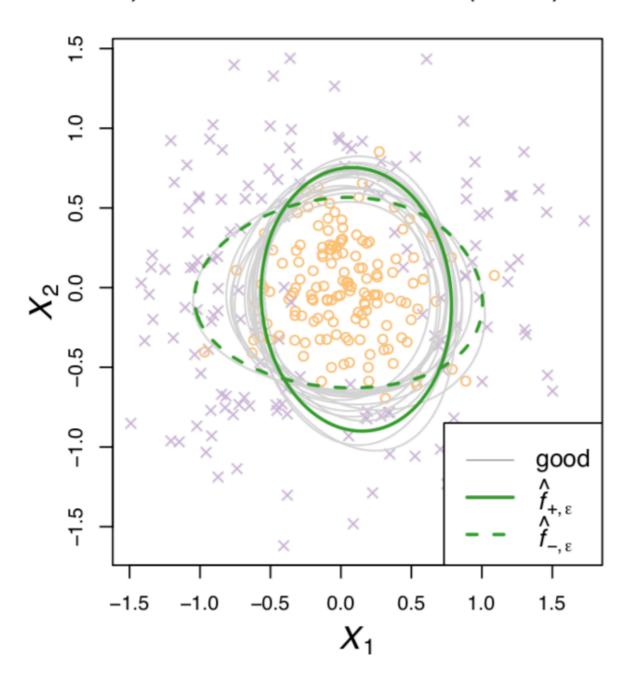
- $ullet \ X=(X_1,X_2)\in \mathbb{R}^2 ext{ and } Y\in \{-1,1\}$
- ullet $\mathbb{E}[X_1|Y=-1]=\mathbb{E}[X_2|Y=-1]=0$, $\mathbb{V}(X_1|Y=-1)=\mathbb{V}(X_2|Y=-1)=1/9$
- ullet For Y=1, X are drawn as Y=-1, but additional $(\cos(U,\sin(U))$ are added
- \mathcal{F} : 3-degree polynomial classifers

$$f_{ heta}(x_1,x_2) = heta_1 + heta_2 x_1 \ldots heta_4 x_1^2 + heta_5 x_2^2 + heta_6 x_1 x_2 \ldots heta_{10} x_1 x_2^2$$

MR



2) Model class reliance (MCR)



• v:vector

 $\circ \ \mathbf{v}_{[j]}$: the jth element of \mathbf{v}

 $\circ \ \mathbf{v}_{[-j]}$: all elements except the jth

• A: matrix

 \circ \mathbf{A}^T : TRANSPOSE

 $e_{switch}(f)$: expected loss in a pair of observations in which the treatment has been switched?.

$$\begin{split} e_{orig}(f) &= \mathbb{E}(L(f,y,T,C)) = p(t=1) \int \int L(f,y,t=1,c) g(y,c|t=1) d_y d_c + p(t=0) \int \int L(f,y,t=0,c) g(y,c|t=0) d_y d_c \\ &= e_{switch}(f) = p(t=1) \int \int L(f,y,t=0,c) g(y,c|t=1) d_y d_c + \\ &= p(t=0) \int \int L(f,y,t=1,c) g(y,c|t=0) d_y d_c \\ &= e_{switch}(f^*) - e_{orig}(f^*) = p(t=1) \int \int [(y-\mathbb{E}[y|0,c])^2 - (y-\mathbb{E}[y|1,c])^2] g(y,c|t=1) d_y d_c \\ &+ (1-p(t=1)) \int \int [(y-\mathbb{E}[y|1,c])^2 - (y-\mathbb{E}[y|0,c])^2] g(y,c|t=0) d_y d_c \end{split}$$

 $\text{subset of good models: } \mathcal{R}(\epsilon, f^*, \mathcal{F}) := \{f \in \mathcal{F} : e_{orig}(f) \leq e_{orig}(f^*) + \epsilon\}$

$$\mathcal{TE}(C): \mathbb{E}[Y_1 - Y_0 | C = c] = \mathbb{E}[Y_1 | C = c, T = 1] - \mathbb{E}[Y_0 | C = c, T = 0] = f^*(T = 1, C) - f^*(T = 0, C)$$

$$\sum_{t \in \{0,1\}} \mathbb{E}_{C|T = t} \mathcal{TE}(C)^2 = \int \int (\mathbb{E}[y|1, c] - \mathbb{E}[y|0, c])^2 g(y, c|1) d_y d_c + \int \int (\mathbb{E}[y|1, c] - \mathbb{E}[y|0, c])^2 g(y, c|0) d_y d_c$$

$$\operatorname{Var}(T) = \mathbb{E}[(T - p(t = 1))^2] = p(t = 1)(1 - p(t = 1))$$