

# Dimensionality Reduction



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# Outline

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- ❑ Principal Component Analysis (PCA)
- ❑ Multidimensional Scaling (MDS)
- ❑ Isomap
- ❑ Kernel PCA
- ❑ Locally Linear Embedding (LLE)
- ❑ Laplacian Eigenmaps (LEM)
- ❑ Sammon Mapping
- ❑ Mutilayer Autoencoder
- ❑ Other Nonconvex methods

# Models

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## □ Linear methods

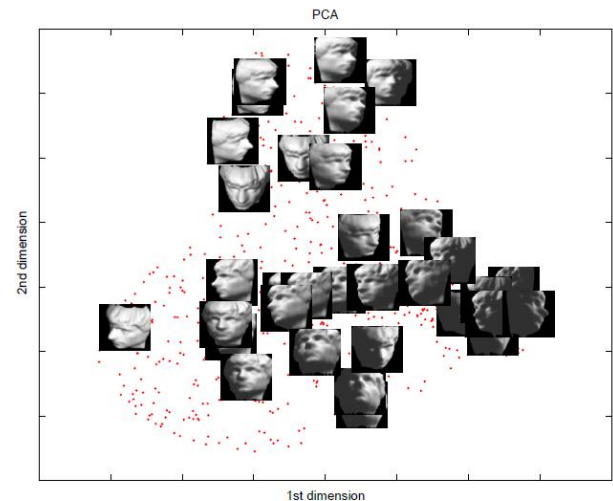
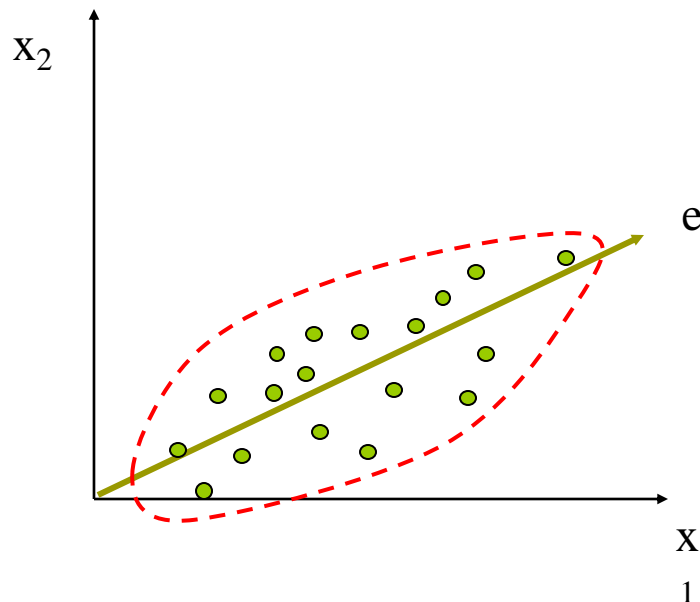
- Principal component analysis (PCA)
- Multidimensional scaling (MDS)
- Independent component analysis (ICA)

## □ Nonlinear methods

- Kernel PCA
- Locally linear embedding (LLE)
- Laplacian eigenmaps (LEM)

# Principal Component Analysis (PCA)

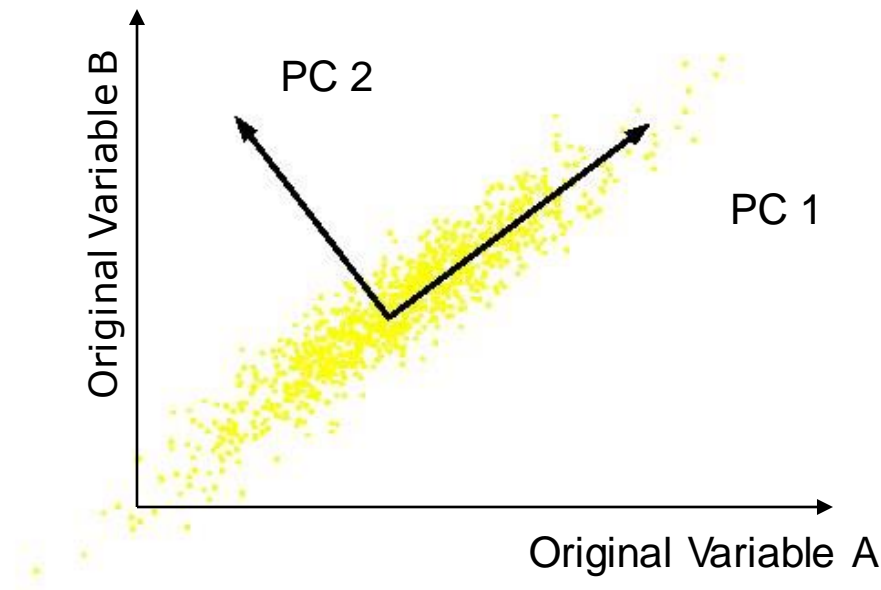
- History: Karl Pearson, 1901
- Find projections that capture the largest amounts of variation in data
- Find the eigenvectors of the covariance matrix, and these eigenvectors define the new space



# PCA

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- Definition: Given a set of data  $X \in R^{d \times N}$ , find the principal axes are those orthonormal axes onto which the variance retained under projection is maximal



# Formulation

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- Variance on the first dimension

- $\text{var}(\mathbf{U}_1) = \text{var}(\mathbf{w}^T \mathbf{X}) = \mathbf{w}^T \mathbf{S} \mathbf{w}$

- $\mathbf{S}$ : covariance matrix of  $\mathbf{X}$

- Objective: the variance retains the maximal

- Formulation

$$\begin{aligned} \max_{\mathbf{w}} \quad & \mathbf{w}^T \mathbf{S} \mathbf{w} \\ \text{s.t.} \quad & \mathbf{w}^T \mathbf{w} = 1 \end{aligned}$$

- Solving procedure

- Construct Lagrangian  $L(\mathbf{w}, \lambda_1) = \mathbf{w}^T \mathbf{S} \mathbf{w} - \lambda_1 (\mathbf{w}^T \mathbf{w} - 1)$

- Set the partial derivative on to zero

$$\frac{\partial L}{\partial \mathbf{w}} = 0 \Rightarrow \mathbf{S} \mathbf{w} = \lambda_1 \mathbf{w}$$

- As  $\mathbf{w} \neq \mathbf{0}$  then  $\mathbf{w}$  must be an eigenvector of  $\mathbf{S}$  with eigenvalue  $\lambda_1$

$$\mathbf{w}^T \mathbf{S} \mathbf{w} = \lambda_1 \mathbf{w}^T \mathbf{w} = \lambda_1$$

# How to choose $k$

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## Choosing $k$ (number of principal components)

Average squared projection error:  $\frac{1}{m} \sum_{i=1}^m \|x^{(i)} - x_{approx}^{(i)}\|^2$

Total variation in the data:  $\frac{1}{m} \sum_{i=1}^m \|x^{(i)}\|^2$

Typically, choose  $k$  to be smallest value so that

$$\begin{aligned} \rightarrow & \frac{\frac{1}{m} \sum_{i=1}^m \|x^{(i)} - x_{approx}^{(i)}\|^2}{\frac{1}{m} \sum_{i=1}^m \|x^{(i)}\|^2} \leq \underline{0.01} \quad \underline{(1\%)} \\ \rightarrow & \end{aligned}$$

→ “99% of variance is retained”

# Multidimensional Scaling (MDS)

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- History: T. Cox and M. Cox, 2001
- Attempts to preserve pairwise distances
- Different formulation of PCA, but yields similar result form

$$\min_Y \sum_{i=1}^N \sum_{j=1}^N (d_{ij}^{(X)} - d_{ij}^{(Y)})^2$$

where  $d_{ij}^{(X)} = \|x_i - x_j\|^2$  and  $d_{ij}^{(Y)} = \|y_i - y_j\|^2$ .

- Transformation

$$\min_Y \sum_{i=1}^N \sum_{j=1}^N (x_i^\top x_j - y_i^\top y_j)^2$$



# Isomap

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- ❑ History: J. Tenenbaum et al, Science 1998
- ❑ A nonlinear generalization of classical MDS
- ❑ Perform MDS, not in the original space, but in the **geodesic space**
- ❑ Procedure-similar to LLE
  1. Find neighbors of each data point
  2. Compute geodesic pairwise distances (e.g., shortest path ) between all points
  3. Embed the data via MDS

# Kernel PCA

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- History: S. Mika et al, NIPS, 1999
- Data may lie on or near a nonlinear manifold, not a linear subspace
- Find principal components that are nonlinearly to the input space via nonlinear mapping

$$\Phi : x \rightarrow \mathcal{H} \quad x \mapsto \Phi(x)$$

- Objective  $\min_{U_k} \sum_{i=1}^N \|\Phi(\mathbf{x}_i) - U_k U_k^T \Phi(\mathbf{x}_i)\|^2$

- Solution found by SVD:  $\Phi(X) = U \Sigma V^T$   
 $U$  contains the eigenvectors of  $\Phi(X) \Phi(X)^T$

# Locally Linear Embedding (LLE)

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- History: S. Roweis and L. Saul, Science, 2000
- Procedure
  1. Identify the neighbors of each data point
  2. Compute weights that best linearly reconstruct the point from its neighbors

$$\min_{\mathbf{w}} \sum_{i=1}^N \left\| \mathbf{x}_i - \sum_{j=1}^k w_{ij} \mathbf{x}_{N_i(j)} \right\|^2$$

3. Find the low-dimensional embedding vector which is best reconstructed by the weights determined in Step 2

$$\min_Y \sum_{i=1}^N \left\| \mathbf{y}_i - \sum_{j=1}^k w_{ij} \mathbf{y}_{N_i(j)} \right\|^2$$

# Laplacian Eigenmaps (LEM)

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- History: M. Belkin and P. Niyogi, 2003
- Similar to locally linear embedding
- Different in weights setting and objective function

- Weights 
$$W_{ij} = \begin{cases} 1 & i, j \text{ are connected} \\ \exp\left(\frac{-\|x_i - x_j\|^2}{s}\right) & \text{otherwise} \end{cases}$$

- Objective

$$\min_Y \sum_{i=1}^N \sum_{j=1}^N (y_i - y_j) W_{ij}$$

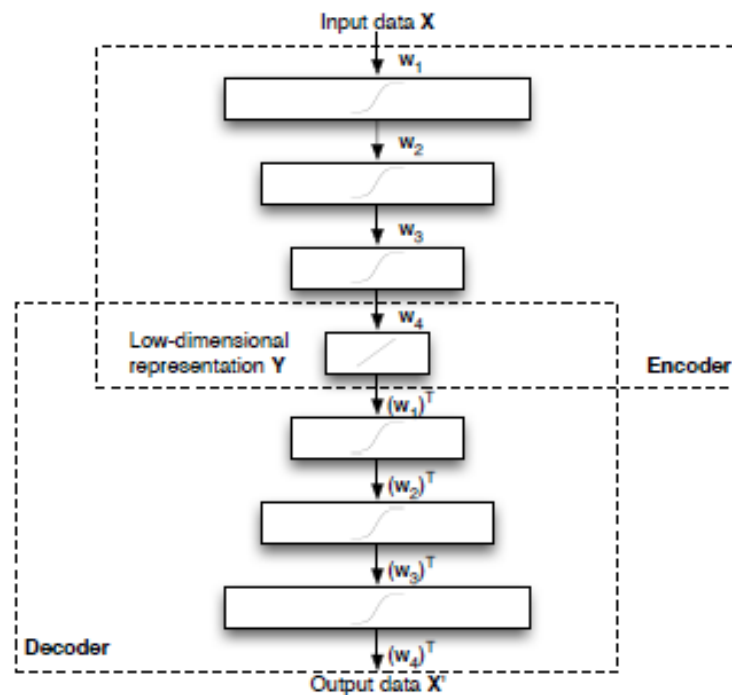
# Sammon's Mapping

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- A variation on MDS
- Preserve the distances between nearby points than between those which are far a part
- formulation

$$\phi(\mathbf{Y}) = \frac{1}{\sum_{ij} d_{ij}} \sum_{i \neq j} \frac{(d_{ij} - \|\mathbf{y}_i - \mathbf{y}_j\|)^2}{d_{ij}}$$

# Multilayer Autoencoders



# Summary

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- nonlinear techniques for dimensionality reduction are, despite their large variance, often not capable of outperforming traditional linear techniques such as PCA
- new nonlinear techniques for dimensionality reduction required
  - (i) do not suffer from the presence of trivial optimal solutions
  - (ii) may be based on non-convex objective functions
  - (iii) do not rely on neighbourhood graphs to model the local structure of the data manifold