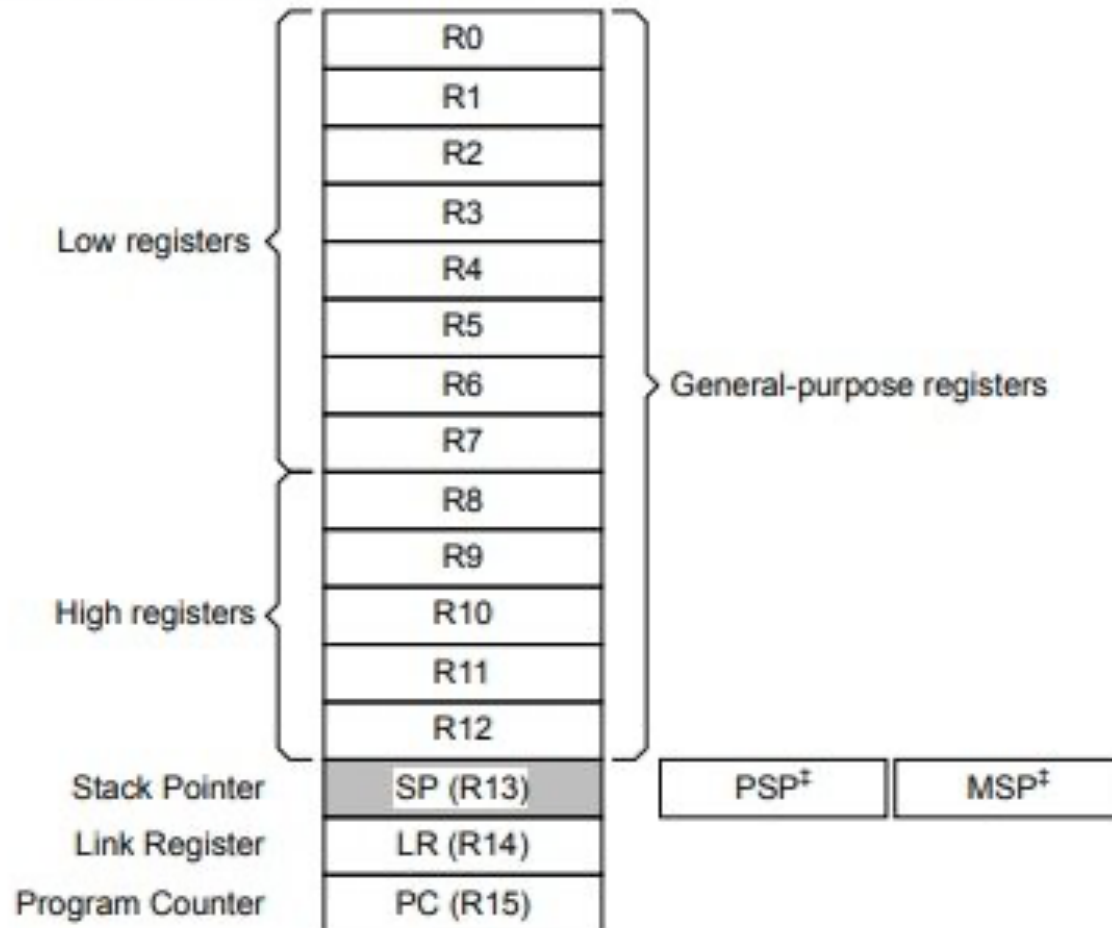


# LAB 2: Assembly Language and C Programming

Week 11

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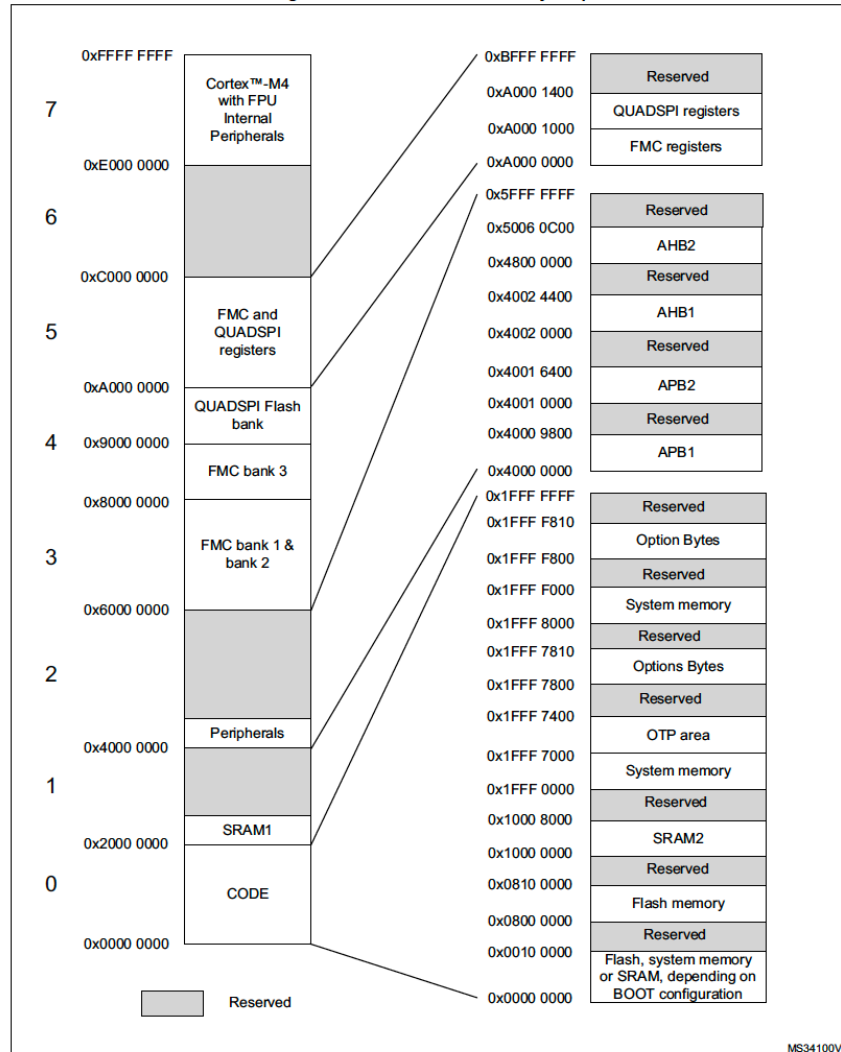
# LAB-1 Summary: Registers



- General Purpose Registers  
**(13 of them, R0-R12)**
- 3 Special Registers:
  - SP
  - LR
  - PC

# LAB-1 Summary: Memory

Figure 8. STM32L475xx memory map



- Memory space is segmented
- Each portion has designed to store certain information

# LAB-1 Summary: Why ASM?

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- ASM instructions are lower-level machine instruction.
- Not commonly used but mostly used for critical part of the program, e.g., core part of operating system were requiring  $<1\text{ms}$  running time.
- Program in ASM allow full control over microprocessor, the instruction are fully defined by programmer not the compiler.
- Higher level languages like C, Java, Python are being disassembled (translated) from C into ASM, the way of translating is decided by the compiler.
- Fast, full control of processor, low level machine language.

# LAB-2 Agenda

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- Assignment introduction:
  - Submission and Assessment
  - Background Concepts: K Nearest Neighbor
  - Objective: develop two ASM function **classification()**
  - Walkthrough the Assignment template
- Learning Focus:
  - Pass arguments between C and ASM functions
  - Declare Function in ASM (Optional)
  - Navigates between C and ASM functions - Link Register (LR, R14)
  - Why PUSH and POP? - Stack and Stack Pointer (SP Register, R13)

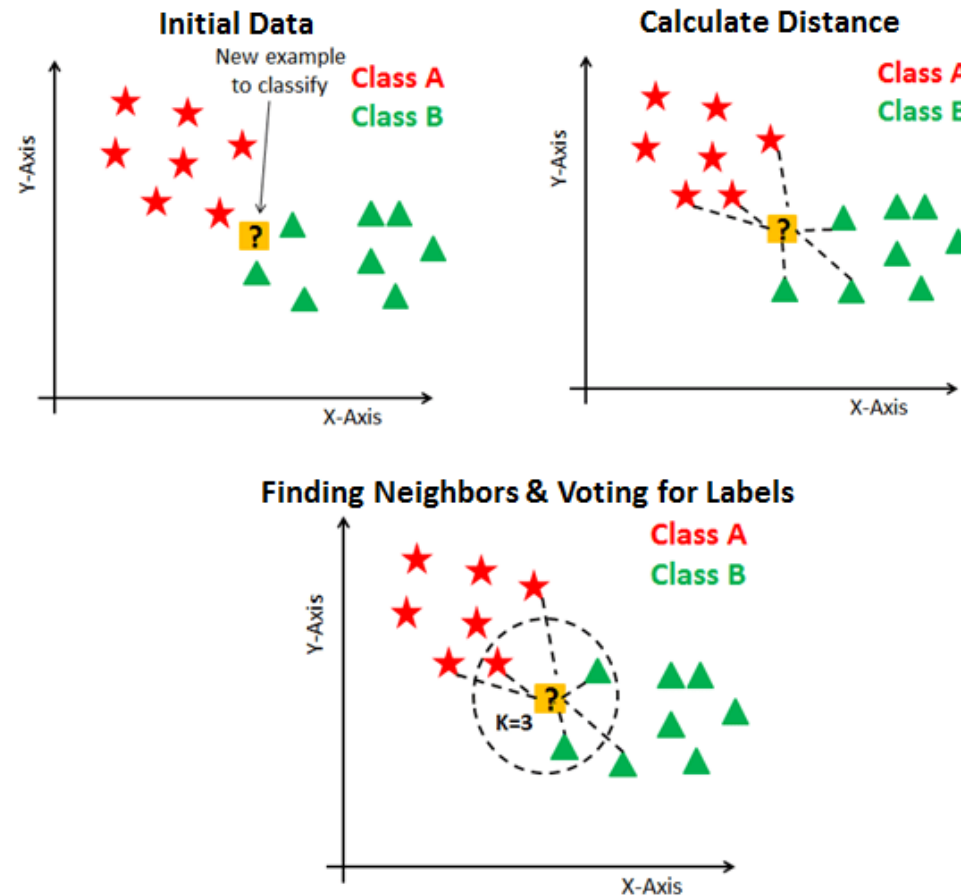
# Submission and Assessment

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- Submission: The report and archived workspace have to be uploaded to LumiNUS **on Week 13 Tuesday/Wednesday by 11:59 PM**. Login to the **zoom session at least 5 mins** before your slot.
- Assessment: **on Week 13 Wednesday/Thursday during lab session.**
- During the Assessment:
  - GA will modify your program slightly
  - GA will ask both students questions related to the code/logic/structure
  - You need to be familiar with all aspects of the assignment
- Other Requirements:
  - Peer Review submit by **11:59 PM 14-Nov (Week 13 Sunday)** [LumiNUS > CG2028 > Survey > Peer Review]
  - Project (ZIP file only)
  - Report (PDF file only)
  - **Prepare your achieve** and **follow the naming** templates in Wiki.NUS

# K-Nearest Neighbour (k-NN)

- K-nearest neighbour (k-NN) is one of the popular non-parametric classification methods. It is used for classification and regression.



# Flow of the Program

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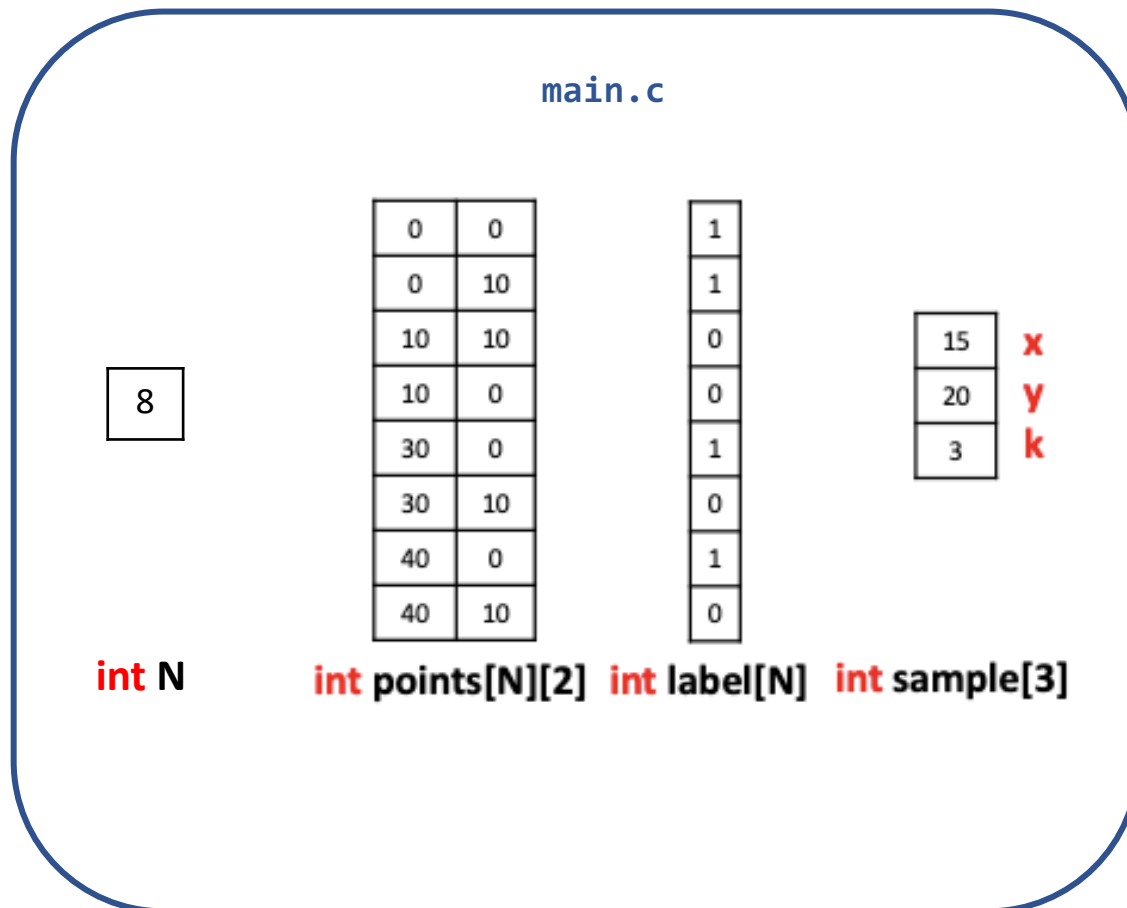
Three source files:

- `main.c`:
  - define necessary parameters (not required to edit)
  - calls the assembly function
  - prints out the result on the console pane
- `classification.s`:
  - write the ASM instructions that implement the **`classification()`** function to classify the data point with 1 nearest neighbour.



# K-Nearest Neighbour (k-NN)

- `classification.s`:
  - classify the data point with k nearest neighbour.
  - Remind you again: int sample in your skeleton code is `sample[2] = {15,20}`, since we are doing 1-NN, and int class is an integer.



Function  
call



Function  
return



`int class`

## `classification.s`

1. Calculate the **distances** to each points

$$d^2 = (x_2 - x_1)^2 + (y_2 - y_1)^2$$

2. Compare the distances to find nearest
3. Determine the class of sample, based on the class of the nearest neighbours.
3. Return the **int class**

# Assignment: Passing Arguments from C to ASM (R0- R3)

```
1 #include "stdio.h"
2 #define k 1
3
4
5 // CG2028 Assignment, Sem 1, AY 2021/22
6
7
8 extern int classification(int N, int* points, int* label, int* sample); // asm implementation
9 int classification_c(int N, int* points, int* label, int* sample); // reference C implementation
10
11 int main(void)
12 {
13     //variables
14     int N = 8;
15     // think of the values below as numbers of the form x.y
16     // (decimal fixed point with 1 fractional decimal digits precision)
17     // which are scaled up to allow them to be used integers
18
19     int points[16] = {35, 0, 0, 15, 10, 10, 10, 0, 30, 0, 30, 10, 40, 0, 40, 10};
20     int label[8] = {1, 1, 0, 0, 1, 0, 1, 0};
21     int sample[2] = {15, 20};
22
23     // Call assembly language function to perform classification
24     printf( "asm: class = %d \n", classification(N, points, label, sample) );
25     printf( "C : class = %d \n", classification_c(N, points, label, sample) );
26
27     while (1); //halt
28 }
29
```

Function  
Declaration

Function  
Call

- Function Declaration:
  - **extern void func(int\* arg1, int\* arg2)**
  - Why the \*?
- When ASM functions being called, we are passing:
  - **(int)** N → R0
  - **(int\*)** points → R1
  - **(int\*)** label → R2
  - **(int\*)** sample → R3
  - What are we passing in exactly?

# Assignment: Constant and Variables in Memory

- Question: Knowing the starting address of array points `[][]`, how to find the memory address of the A-th data point, say  $A \leq N$  ?

0	0
0	1
1	1
1	0
3	0
3	1
4	0
4	1

**int** points[N][2]

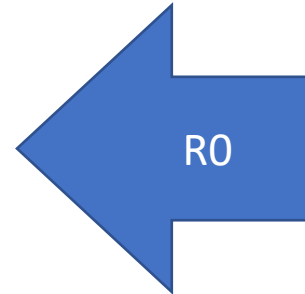
Word address*	Content	
points[][] → 0x20007FA0	0x00000000	points[0][0]
0x20007FA4	0x00000000	points[0][1]
0x20007FA8	0x00000000	points[1][0]
0x20007FAC	0x0000000A	points[1][1]
0x20007FB0	0x0000000A	points[2][0]
0x20007FB4	0x0000000A	points[2][1]
0x20007FB8	:	:
0x20007FBC	:	:

- Let's do a quick demo to exam the values in memories and registers.

# Assignment 1: Passing Arguments from ASM to C (R0)

main.c

```
1 #include "stdio.h"
2 #define k 1
3
4
5 // CG2028 Assignment, Sem 1, AY 2021/22
6
7
8 extern int classification(int N, int* points, int* label, int* sample); // asm implementation
9 int classification_c(int N, int* points, int* label, int* sample); // reference C implementation
10
```



- Are we returning any values here?
- If we want to return, how?
- If not allowed to use R0, can you think of several ways to save the result in the memory?

asm.s

```
24 classification:
25 @ PUSH / save (only those) re
26     PUSH {R1-R4,R14}
27 @ parameter registers need no
28
29 @ write asm function body her
30
31 @ branch to SUBROUTINE for il
32     BL SUBROUTINE
33 @ prepare value to return (cl
34 @ the #5 here is an arbitrary
35     MOVW R0, #5
36 @ POP / restore original regi
37     POP {R1-R4,R14}
38 @ return to C program
39     BX LR
40
41 @ you could write your code w
42 SUBROUTINE:
43
44     BX LR
```

# Assignment: Declare Subroutine (Function) in ASM (Optional)

```
24 classification:
25 @ PUSH / save (only those) registers which are modified by your function
26     PUSH {R1-R4,R14}
27 @ parameter registers need not be saved.
28
29 @ write asm function body here
30
31 @ branch to SUBROUTINE for illustration only
32     BL SUBROUTINE
33 @ prepare value to return (class) to C program in R0
34 @ the #5 here is an arbitrary result
35     MOVW R0, #5
36 @ POP / restore original register values. DO NOT save or restore R0. Why?
37     POP {R1-R4,R14}
38 @ return to C program
39     BX LR
40
41 @ you could write your code without SUBROUTINE
42 SUBROUTINE:
43
44     BX LR
```

Function Call

Function Declaration

- Line 32: Branch to SUBROUTINE
- Execute SUBROUTINE
- Line 44: Branch back to main function in **ASM**
- Execute the rest in main of ASM
- Line 39: Branch back to **main.c**
- **Question1: Why PUSH & POP R14?**
- **Question2: Why not R0?**

# Navigates between C and ASM: LR - Link Register (R14)

	Word Address	Instruction Memory
asm_fun.s	e.g. 0x0000 0070	ADD ...
	0x0000 0074	SUB ...
	...	...
	0x0000 0100	<b>BX LR</b>
main.c	...	
	<i>A block of memory location</i>	int i,j;
	e.g. 0x0000 2000 to 0x0000 2008	int points [N][2];
	0x0000 2009 to 0x0000 2014	int class[N][2];
	...	...
	...	asm_fun(int* points, int* class);
	...	...
	...	for (i=0; i<M; i++)
	...	...

**BX** → Branch Indirect (Register)

Format: **BX{cond} Rm**

Performs: branch to location indicated by Rm

$PC \leftarrow Rm$

PC: program counter always points to the next line that should be execute

**BX LR: LR serves as a marking to navigate back**

**Let's take a look at our code.**

Why a range?

- Many registers are involved to create the “link” between C and ASM, losing the link will cause problems when navigate back from ASM to C.
- ASM function should not affect C program after its execution so that main.c could continue. **HOW?**

# Why PUSH and POP?

- Discussed earlier: PUSH and POP helped us preserve the “marking” we made to navigate back to C.

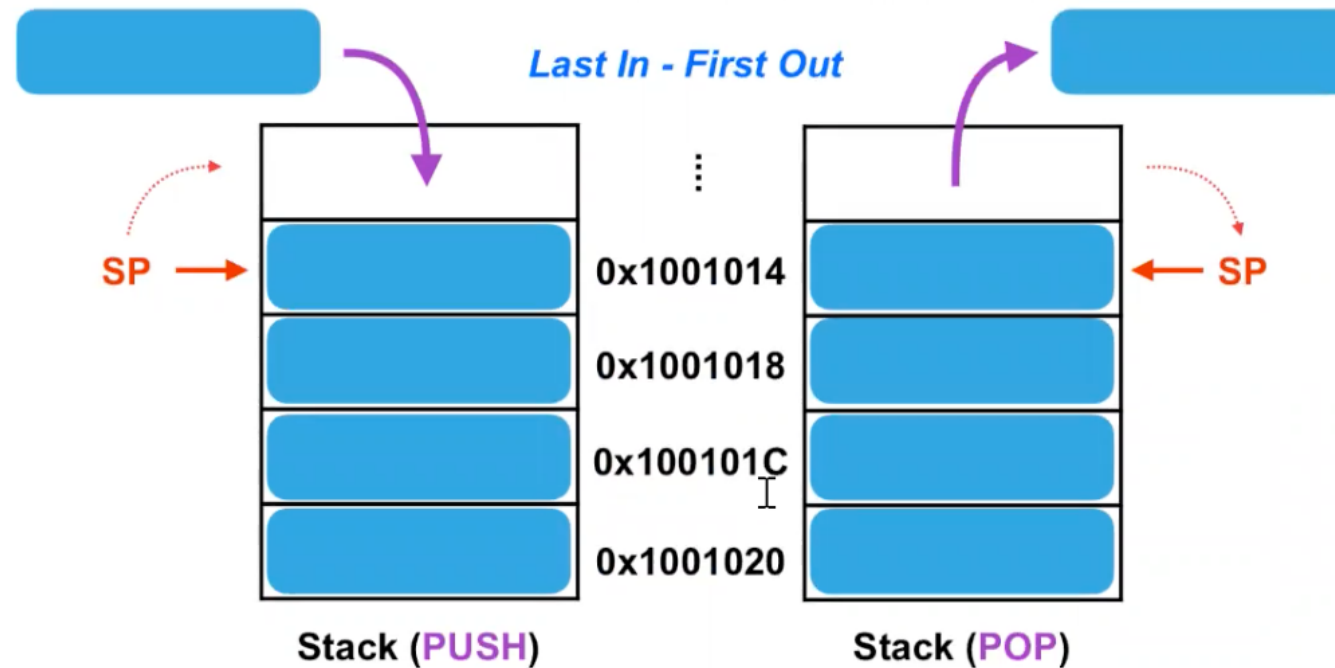
```
24 classification:
25 @ PUSH / save (only those) r
26     PUSH {R1-R4,R14}
27 @ parameter registers need r
28
29 @ write asm function body he
30
31 @ branch to SUBROUTINE for i
32     BL SUBROUTINE
33 @ prepare value to return (c
34 @ the #5 here is an arbitrar
35     MOVW R0, #5
36 @ POP / restore original reg
37     POP {R1-R4,R14}
38 @ return to C program
39     BX LR
40
41 @ you could write your code
42 SUBROUTINE:
43
44     BX LR
```

(int*) N	→ R0
(int*) points	→ R1
(int*) label	→ R2
(int*) sample	→ R3

- We are to use R0-R3 in asm\_fun.s as well, do we need to PUSH and POP them as well? **YES! But not R0!**
- WHY? IDE translates C language into Assembly then implement on the board → Essentially, main.c is relying on registers to do processing.
- We must preserve the status and revert back when we return to C.
- If you used more registers, what should you do?

# How PUSH/POP works: Stack & Stack Pointer (R13)

- A very commonly used data structure
- A part of the memory is dedicated as a “Stack”
- Stack Pointer (SP) always pointing to the top of the stack





# Good practices to follow

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- Use and re-use registers in a systematic way to reduce the usage of processor.
- Give meaningful comments helps you and your teammate understand each other (also remind yourself if you happen to have fish memory)
- Maintain a register dictionary or table for each `asm_fun.s` at different time.

```
15 @Register map
16 @R0 - N, returns class
17 @R1 - points
18 @R2 - label
19 @R3 - sample
20 @R4 - <use(s)>
21 @R5 - <use(s)>
22 @....
```

- Make use of flowchart to design before attempt to code, include it in your report to better explain your logic.

# Exercise to Warm up

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- Compile the project and execute the program, **exam your registers and memory** to locate all the predefined parameters.
- Comment the **PUSH {R14}** and **POP {R14}** lines in **classification()**, recompile and execute the program again. Observe the difference.