

General Purpose I/O

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Overview



How do we make a program light up LEDs in response to a switch?

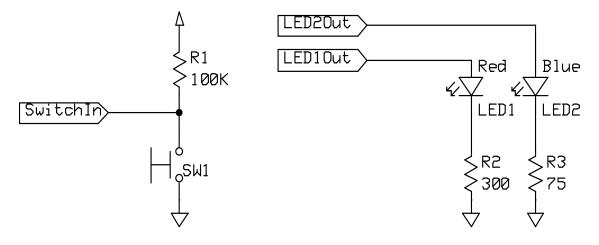
GPIO

- Basic Concepts
- Port Circuitry
- Control Registers
- Accessing Hardware Registers in C
- Clocking and Muxing
- Circuit Interfacing
 - Inputs
 - Outputs
- Additional Port Configuration



Basic Concepts





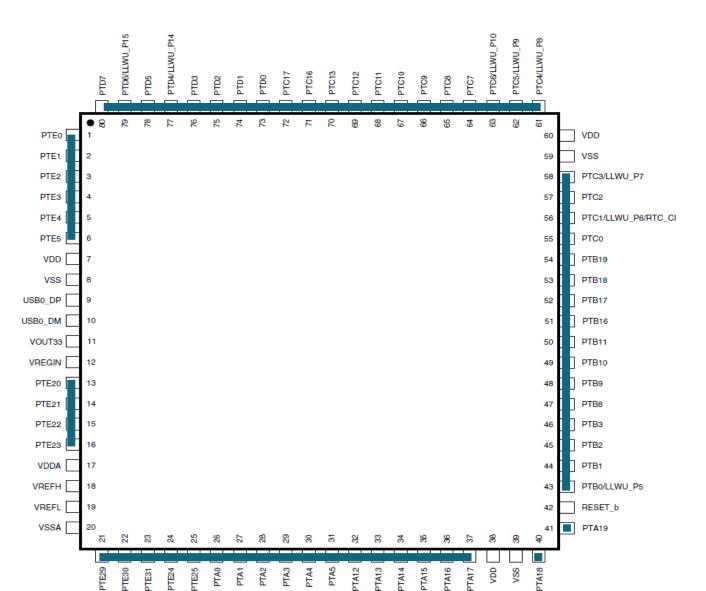


- Goal: light either LED1 or LED2 based on switch SW1 position
- GPIO = General-purpose input and output (digital)
 - Input: program can determine if input signal is a 1 or a 0
 - Output: program can set output to I or 0
- Can use this to interface with external devices
 - Input: switch
 - Output: LEDs



KL25Z GPIO Ports

- Port A (PTA) through Port E (PTE)
- Not all port bits are available
- Quantity depends on package pin count



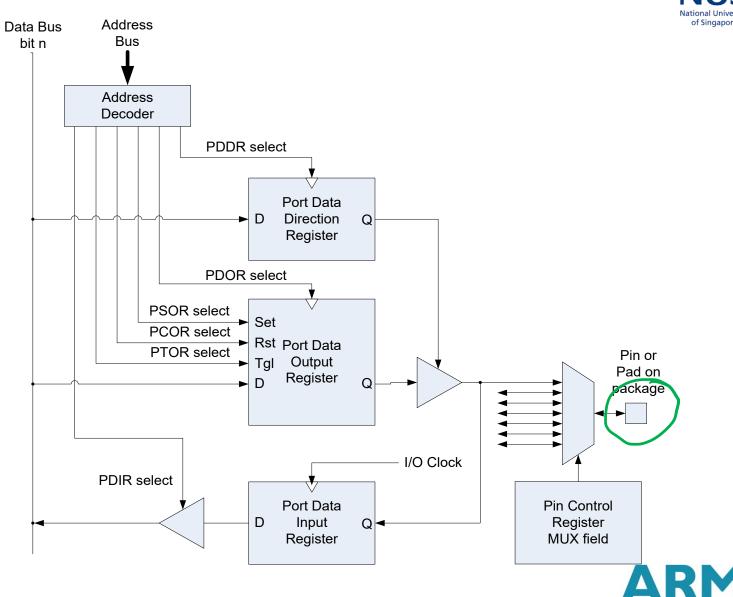




GPIO Port Bit Circuitry in MCU

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- Control
 - Direction
 - MUX
- Data
 - Output (different ways to access it)
 - Input



Control Registers



Absolute address (hex)	Register name	Width (in bits)
400F_F000	Port Data Output Register (GPIOA_PDOR)	32
400F_F004	Port Set Output Register (GPIOA_PSOR)	32
400F_F008	Port Clear Output Register (GPIOA_PCOR)	32
400F_F00C	Port Toggle Output Register (GPIOA_PTOR)	32
400F_F010	Port Data Input Register (GPIOA_PDIR)	32
400F_F014	Port Data Direction Register (GPIOA_PDDR)	32

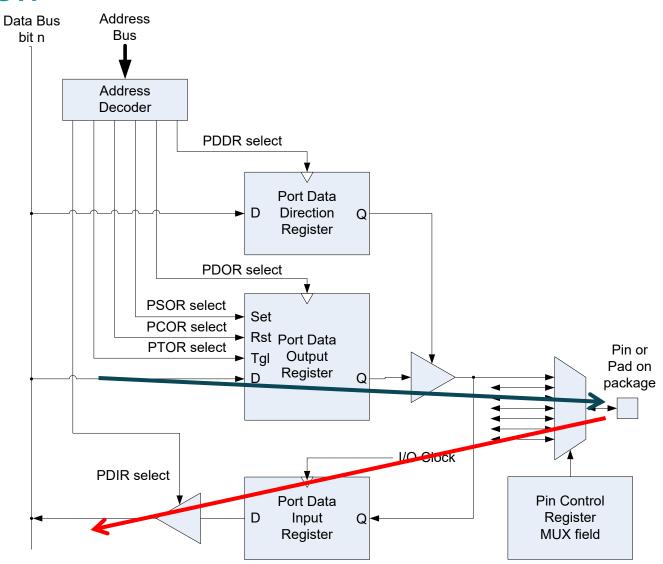
- One set of control registers per port
- Each bit in a control register corresponds to a port bit



PDDR: Port Data Direction

National University

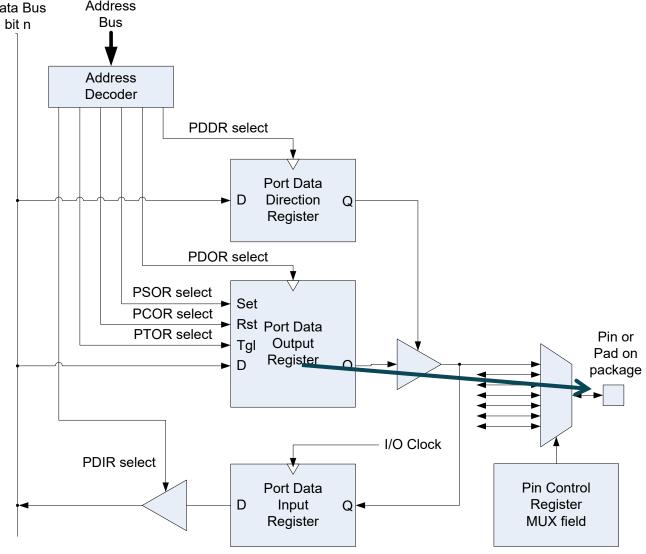
- Each bit can be configured differently
- Input: 0
- Output: I
- Reset clears port bit direction to 0





Writing Output Port Data

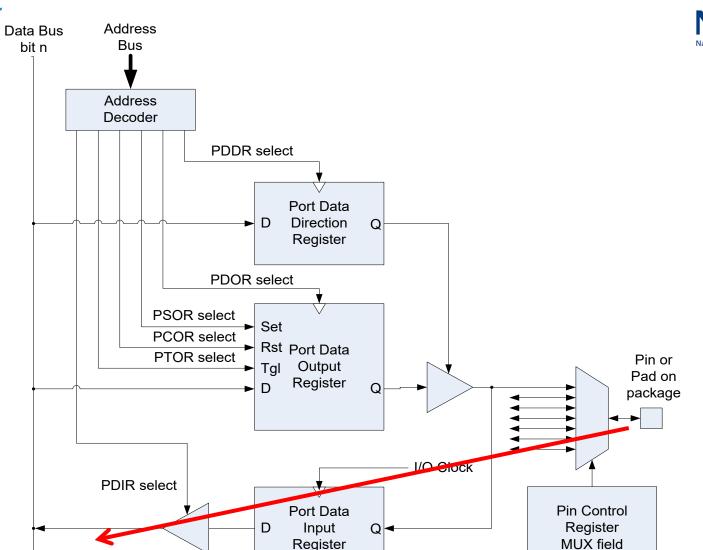
- Address Data Bus Bus bit n Direct: write value to PDOR
- Toggle: write I to PTOR
- Clear (to 0):Write I to PCOR
- Set (to I): write I to PSOR





Reading Input Port Data

- Read from PDIR
- Corresponding bit holds value which was read



Register



```
Pseudocode for Program
// Make PTA1 and PTA2 outputs
set bits 1 and 2 of GPIOA_PDDR
// Make PTA5 input
clear bit 5 of GPIOA_PDDR
// Initialize the output data values: LED 1 off, LED 2 on
clear bit 1, set bit 2 of GPIOA_PDOR
```

// read switch, light LED accordingly

```
if bit 5 of GPIOA_PDIR is 1 {
      // switch is not pressed, then light LED 2
      set bit 2 of GPIOA_PDOR
      clear bit 1 of GPIO_PDOR
} else {
      // switch is pressed, so light LED 1
      set bit 1 of GPIOA_PDOR
      clear bit 2 of GPIO_PDOR
}
```





do forever {

CMSIS - Accessing Hardware Registers in C



Header file MKL25Z4.h defines C data structure types to represent hardware registers ...
 MCU with CMSIS-Core hardware abstraction layer



Accessing Hardware Registers in C (2)



Header file MKL25Z4.h declares pointers to the registers

```
/* GPIO - Peripheral instance base addresses */
/** Peripheral PTA base address */
#define PTA_BASE (0x400FF000u)
/** Peripheral PTA base pointer */
#define PTA ((GPIO_Type *)PTA_BASE)
PTA->PDOR = ...
```



Coding Style and Bit Access



- Easy to make mistakes dealing with literal binary and hexadecimal values
- Make the literal value from shifted bit positions

```
n = (1UL << 19) \mid (1UL << 13);
```

Define names for bit positions

```
#define GREEN_LED_POS (19)
#define YELLOW_LED_POS (13)
n = (1UL << GREEN_LED_POS) | (1UL << YELLOW_LED_POS);</pre>
```

Create macro to do shifting to create mask

```
#define MASK(x) (1UL << (x))
n = MASK(GREEN_LED_POS) | MASK(YELLOW_LED_POS);</pre>
```



Using Masks



Overwrite existing value in n with mask

```
n = MASK(foo);
```

Set in n all the bits which are one in mask, leaving others unchanged

```
n |= MASK(foo);
```

Complement the bit value of the mask

```
~MASK(foo);
```

Clear in n all the bits which are zero in mask, leaving others unchanged
 n &= MASK(foo);



C Code



```
#define LED1_POS (1)
#define LED2_POS (2)
#define SW1_POS (5)
#define MASK(x) (1UL \ll (x))
PTA->PDDR |= MASK(LED1_POS) | MASK (LED2_POS); // set LED bits to outputs
PTA->PDDR &= ~MASK(SW1_POS); // clear Switch bit to input
PTA->PDOR = MASK(LED2_POS); // turn on LED1, turn off LED2
while (1) {
     if (PTA->PDIR & MASK(SW1_POS)) {
       // switch is not pressed, then light LED 2
       PTA->PDOR = MASK(LED2_POS);
     } else {
       // switch is pressed, so light LED 1
       PTA->PDOR = MASK(LED1_POS);
```



Clocking Logic



Bit	Port
13	PORTE
12	PORTD
Ш	PORTC
10	PORTB
9	PORTA

- Need to enable clock to GPIO module
- By default, GPIO modules are disabled to save power
- Writing to an unclocked module triggers a hardware fault!
- Control register SIM_SCGC5 gates clocks to GPIO ports
- Enable clock to Port A
 SIM->SCGC5 |= (1UL << 9);</pre>
- Header file MKL25Z4.h has definitions



```
#define SIM_SCGC5_PORTA_MASK 0x200u
```

#define SIM_SCGC5_PORTA_SHIFT

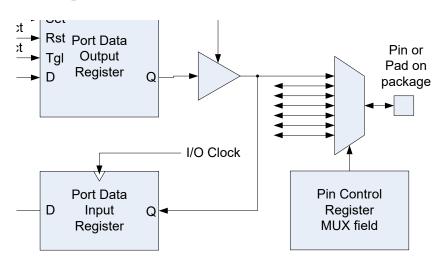
#define SIM_SCGC5_PORTA_WIDTH

#define SIM_SCGC5_PORTA(x) (((uint32_t)(((uint32_t)(x))<<SIM_SCGC5_PORTA_SHIFT))&SIM_SCGC5_PORTA_MASK)



Connecting a GPIO Signal to a Pin



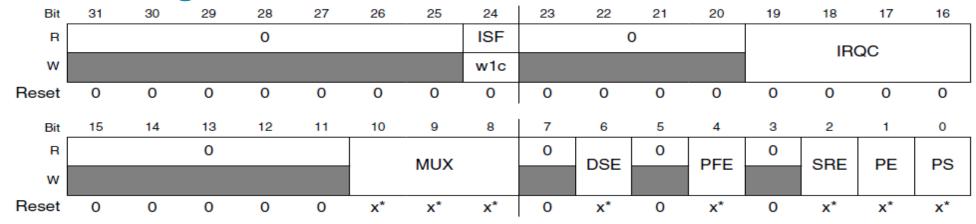


- Multiplexer used to increase configurability what should pin be connected with internally?
- Each configurable pin has a Pin Control Register



Pin Control Register





80 LQFP	64 LQFP	48 QFN	32 QFN	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7
64	52	40	28	PTC7	CMP0_IN1	CMP0_IN1	PTC7	SPI0_MISO			SPI0_MOSI		
65	53	_	_	PTC8	CMP0_IN2	CMP0_IN2	PTC8	I2C0_SCL	TPM0_CH4				_

MUX field of PCR defines connections

MUX (bits 10-8)	Configuration
000	Pin disabled (analog)
001	Alternative I – GPIO
010	Alternative 2
011	Alternative 3
100	Alternative 4
101	Alternative 5
110	Alternative 6
111	Alternative 7



CMSIS C Support for PCR



 MKL25Z4.h defines PORT_Type structure with a PCR field (array of 32 integers) /** PORT - Register Layout Typedef */ typedef struct { ___IO uint32_t PCR[32]; /** Pin Control Register n, array offset: 0x0, array step: 0x4 */ __O uint32_t GPCLR; /** Global Pin Control Low Register, offset: 0x80 __O uint32_t GPCHR; /** Global Pin Control High Register, offset: 0x84 */ uint8_t RESERVED_0[24]; __IO uint32_t ISFR; /** Interrupt Status Flag Register, offset: 0xA0 } PORT_Type;



CMSIS C Support for PCR



```
    Header file defines pointers to PORT Type registers

  PORT - Peripheral instance base addresses */
/** Peripheral PORTA base address */
#define PORTA_BASE (0x40049000u)
/** Peripheral PORTA base pointer */
#define PORTA ((PORT_Type *)PORTA_BASE)
Also defines macros and constants
#define PORT_PCR_MUX_MASK 0x700u
#define PORT_PCR_MUX_SHIFT
#define PORT_PCR_MUX(x)
(((uint32_t)(((uint32_t)(x))<<PORT_PCR_MUX_SHIFT)) &PORT_PCR_MUX_MASK)
```



Resulting C Code for Clock Control and Mux



```
// Enable Clock to Port A
SIM->SCGC5 |= SIM_SCGC5_PORTA_MASK;
// Make 3 pins GPIO
PORTA->PCR[LED1_POS] &= ~PORT_PCR_MUX_MASK;
PORTA->PCR[LED1_POS] |= PORT_PCR_MUX(1);
PORTA->PCR[LED2_POS] &= ~PORT_PCR_MUX_MASK;
PORTA->PCR[LED2_POS] |= PORT_PCR_MUX(1);
PORTA->PCR[SW1_POS] &= ~PORT_PCR_MUX_MASK;
PORTA \rightarrow PCR[SW1\_POS] \mid = PORT\_PCR\_MUX(1);
```





Inputs and Outputs, Ones and Zeros, Voltages and Currents

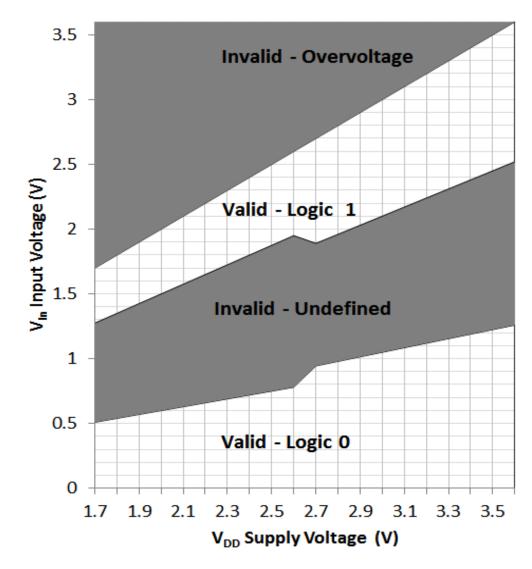
INTERFACING



Inputs: What's a One? A Zero?

- Input signal's value is determined by voltage
- Input threshold voltages depend on supply voltage V_{DD}
- Exceeding V_{DD} or GND may damage chip







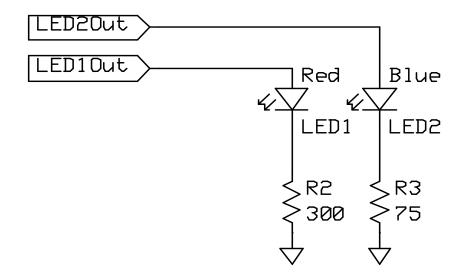
Output Example: Driving LEDs

- Need to limit current to a value which is safe for both LED and MCU port driver
- Use current-limiting resistor

$$R = (V_{DD} - V_{LED})/I_{LED}$$

- Set $I_{LED} = 4 \text{ mA}$
- V_{LED} depends on type of LED (mainly color)
 - Red: ~I.8V
 - Blue: ~2.7 V
- Solve for R given VDD = ~3.0 V
 - Red: 300 Ω
 - Blue: 75 Ω





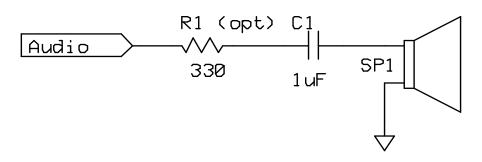


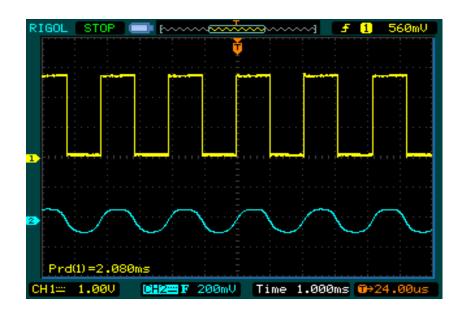
Output Example: Driving a Speaker

- Create a square wave with a GPIO output
- Use capacitor to block DC value
- Use resistor to reduce volume if needed
- Write to port toggle output register (PTOR) to simplify code

```
void Beep(void) {
   unsigned int period=20000;
   while (1) {
      PTC->PTOR = MASK(SPKR_POS);
      Delay(period/2);
   }
}
```



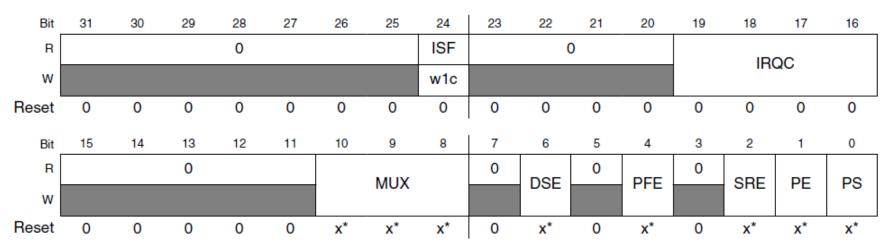






Additional Configuration in PCR





Pull-up and pull-down resistors

- Used to ensure input signal voltage is pulled to correct value when high-impedance
- PE: Pull Enable. I enables the pull resistor
- PS: Pull Select. I pulls up, 0 pulls down.

High current drive strength

- DSE: Set to I to drive more current (e.g. I8 mA vs. 5 mA @ > 2.7 V, or 6 mA vs. I.5 mA @ <2.7 V)
- Available on some pins MCU dependent



Lab 2

Let's get prepared for Lab 2!

