NATIONAL UNIVERSITY OF SINGAPORE

SCHOOL OF COMPUTING

ASSESSMENT FOR Semester 2 AY2019/2020

CG2271 – Real-Time Operating Systems

Mar 2020 Time Allowed: 1 hour

INSTRUCTIONS TO STUDENTS:

- 1. This assessment paper contains **TWENTY-THREE (23)** questions and comprises **NINE (9)** printed pages, including this page.
- 2. Students are required to answer **ALL** the questions.
- 3. Shade your answers on the OCR Answer sheet using a 2B pencil. The OCR sheet is the only thing that will be collected back at the end of the test.
- 4. A Single A4 (Double-Sided) Reference Sheet is allowed.
- 5. You are allowed to use Stand-Alone Calculators. Handphone Calculators are NOT allowed.
- 6. When multiple options can be the answer, choose the most appropriate combination from the available options.

QUESTIONS

You are given the following code.

```
#define SW POS
#define MASK(x)
                                (1 << (x))
#define PORT ALPHA MASK
                                0xF0000u
#define PORT ALPHA SHIFT
                                16
#define PORT ALPHA WIDTH
#define PORT ALPHA(x)
                                (((x)<<PORT ALPHA SHIFT) & PORT ALPHA MASK)
                                0x700u
#define PORT_BETA_MASK
#define PORT BETA SHIFT
#define PORT_BETA_WIDTH
                                3
#define PORT BETA(x)
                                (((x)<<PORT BETA SHIFT) & PORT BETA MASK)
init()
{
    SIM->SCGC5 |= SIM SCGC5 PORTD MASK;
                                                   // LINE 1
    PORTD->PCR[SW POS] |= PORT ALPHA(0x0a | 0x01); // LINE 2
    PORTD->PCR[SW_POS] |= PORT_BETA(~0xFE);
                                                   // LINE 3
   PTD->PDDR &= ~MASK(SW POS);
                                                    // LINE 4
    NVIC SetPriority (PORTD IRQn, 1);
    NVIC ClearPendingIRQ(PORTD IRQn);
    NVIC EnableIRQ(PORTD IRQn);
```

You can refer to the Appendix for the full description of the registers. LINE 4 configures Port D Pin 6 as an input pin.

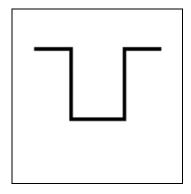
- 1. With reference to the code above, what is the objective of LINE 2?
 - a) Enable the Internal Pull-Up Resistor for Port D Pin 6.
 - b) Enable DMA Request Interrupt on Rising Edge of Port D Pin 6.
 - c) Enable Interrupt on Falling Edge of Port D Pin 6.
 - d) Enable Interrupt on Both Rising and Falling Edge of Port D Pin 6.
 - e) Enable Interrupt when the Pin has a Logic 1.

(d)

- 2. With reference to the code above, what is the objective of LINE 3?
 - S1. Enable Internal Pull-Up Resistor for Port D Pin 6.
 - S2. Enable the Slew Rate for Port D Pin 6.
 - S3. Enable GPIO Functionality for Port D Pin 6.
 - a) Only S1 and S2 are correct.
 - b) All three statements, S1, S2 and S3 are correct
 - c) Only S1 and S3 are correct
 - d) Only S3 is correct
 - e) All three statements are wrong

(d)

3. The following signal is generated by the Switch connected to Port D Pin 6 whenever it is pressed and released. When it is pressed, a negative transition is generated, and when it is released a positive transition is generated.



How many Interrupt Requests will be registered by the Microcontroller based on the current configuration?

- a) 1
- b) 2
- c) 3
- d) 4
- e) 5

(b)

4. It is known that Port D is mapped to IRQ 31. The priority is configured in IPR7 which is shown below.

Bits	31:30	29:24	23:22	21:16	15:14	13:8	7:6	5:0
IPR7	IRQ31	reserved	IRQ30	reserved	IRQ29	reserved	IRQ28	reserved

No other interrupts are configured in the system. What is the 32-bit value in the IPR register based on the given code?

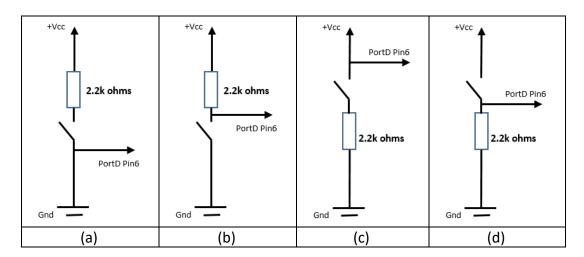
- a) 0x10000000
- b) 0x0000010
- c) 0x00000040
- d) 0x40000000
- e) 0x80000000

(d)

- 5. Which of the following lines correctly configures the IRQ Priority Level for Port D. Assume that IPR7 register can be directly accessed as shown below.
 - a) IPR7 |= (0x1 << 32);
 - b) IPR7 |= (0x1 << 31);
 - c) IPR7 |= (0x1 << 30);
 - d) IPR7 |= (0x1 << 6);
 - e) IPR7 |= (0x1 << 1);

(c)

6. The following figures are possible options for designing the Switch that is connected to Port D Pin 6. Which of the following designs will generate the signal based on the figure and the description in Question 3?



(b)

- 7. The Cortex M0+ has a Periodic Interrupt Timer (PIT) module. Which of the following statements is TRUE?
 - S1. The Timer Start Value can be changed anytime.
 - S2. We can configure Interrupts to be triggered whenever the Timer counts down to 0.

- S3. We can configure Interrupts to be triggered whenever the Timer counts up to a specific value.
- a) All three statements S1, S2 and S3 are TRUE.
- b) Only statements S1 and S2 are TRUE
- c) Only statements S1 and S3 are TRUE
- d) Only statements S2 and S3 are TRUE
- e) Only S2 is TRUE

(b)

- 8. The earlier program is updated with the code to allow the PIT module to generate Interrupts. The following sequence takes place.
 - The main() code is running and the Push Button is pressed.
 - Immediately after that, the PIT module generates an Interrupt.

Here are possible scenarios on what will happen next.

- S1. The moment the PIT generates an Interrupt, the code will immediately jump to the IRQ Handler for the PIT module.
- S2. The Push Button IRQ Handler will complete first and then we will execute the PIT IRQ Handler.
- S3. The PIT module's Interrupt request can be programmed so that it is ignored and the interrupt is never serviced.

Which of the above statements is TRUE?

- a) Only S1 is TRUE
- b) Only S2 is TRUE
- c) Only S1 and S2 can be TRUE
- d) Only S2 and S3 can be TRUE
- e) All statements S1, S2 and S3 can be TRUE

(e)

- 9. Which of the following statements is TRUE for a volatile global variable?
 - S1. Whenever the data is accessed in the code, it will use the last fetched data that is stored in the internal registers of the processor.

- S2. Whenever the data is accessed in the code, a new copy of the data is always fetched from memory.
- S3. It can be accessed by a task and an interrupt.
- a) Only S1 is TRUE
- b) Only S1 and S3 are TRUE
- c) Only S2 and S3 are TRUE
- d) S1, S2 and S3 are all TRUE
- e) S1, S2 and S3 are all FALSE

(c)

- 10. The UART2 module in the Cortex M0+ is configured to operate in Interrupt mode for both Transmit and Receive Data. Which of the following statements is TRUE?
 - S1. There are TWO separate IRQ Handlers for the Transmit and Receive Interrupts.
 - S2. There is only ONE IRQ Handler for both the Transmit and Receive Interrupts.
 - S3. There are TWO separate Interrupt Flags for Transmit and Receive Interrupts.
 - a) Only S1 and S2 are correct.
 - b) Only S2 and S3 are correct.
 - c) Only S1 and S3 are correct.
 - d) S1, S2 and S3 are all correct.
 - e) S1, S2 and S3 are all wrong.

(b)

The following questions are to be answered in the context of a RTX-RTOS based system with default settings.

- 11. A task (T1) that is **RUNNING** gets switched to the **READY** state. Which of the following could be the cause?
 - a) Another task acquired a resource that was being held by T1.
 - b) T1 attempted to acquire a resource and was successful.
 - c) T1 attempted to acquire a resource that is currently unavailable.
 - d) T1 chose to call osDelay(1) in its code to voluntarily give up the CPU.
 - e) None of the above statements are valid.

(e)

- 12. A task (T1) that is **RUNNING** gets switched to a **BLOCKED** state. Which of the following statements is TRUE?
 - a) T1 has been preempted by a higher priority task.
 - b) T1 attempted to acquire a resource but was unable to get it.
 - c) T1 was allocated a resource that it was waiting for.
 - d) T1 was preempted by another task with the same priority as T1.
 - e) Option (b) and (d) are both TRUE.

(b)

- 13. A task is currently in the **RUNNING** state with all the required resources. The scheduler will still perform a context switch after some time to ensure that other equal-priority tasks have a chance to execute.
 - a) True
 - b) False

(a)

14. A system has FOUR tasks labelled T1, T2, T3 and T4, in order of priority (T1 being the highest). It is observed that only T1 is in the **RUNNING** state most of the time. Tasks T2 and T3 only got a chance to go to the **RUNNING** once. Task t4 gets to go to the **RUNNING** state occasionally.

Examine the following statements:

- S1. This can only happen if Task t1 is always in the RUNNING state preventing the lower priority tasks from running.
- S2. Tasks t2 and t3 and always stuck in the READY state from the start of the program.
- S3. Task t1 is holding onto a resource that is required by Task t2 and t3.
- S4. Task t4 is holding onto a resource that is required by Task t2 and t3.

Which of the above statements can be TRUE?

- a) Only S1 and S2
- b) Only S2
- c) Only S3
- d) Only S3 and S4
- e) None of the statements can be true

(d)

15. The following code snippet shows the creation of TWO threads in the main() function.

Examine the following statements.

- S1. The InitGPIO() function is necessary to ensure that the GPIO pins used by the RTOS scheduler are correctly initialized.
- S2. The scheduler will randomly decide which of the TWO threads will run first.
- S3. The moment we complete the osKernelInitialize() function, we have switched over to the RTOS multi-threaded environment.

Which of the above statements is TRUE?

- a) Only S2 is TRUE
- b) Only S1 and S2 are TRUE
- c) Only S1 and S3 are TRUE
- d) Only S2 and S3 are TRUE
- e) All of the statements, S1, S2 and S3 are FALSE.

(e)

THE END