

TM 6.3

a)

EMD-G outputs maximally general consistent hypothesis

$$P(D|h) = \begin{cases} 1 & \text{if } h \text{ is consistent with } D \\ 0 & \text{otherwise} \end{cases}$$

 \therefore we choose $P(h)$ to be uniformly distributed

$$P(h) = \frac{1}{|H|} \text{ for all } h \in H$$

$$P(D) = \sum_{h \in H} P(D|h) \cdot P(h)$$

$$= \frac{1}{|H|} \sum_{h \in H} P(D|h)$$

$$= \frac{|V_{SH,D}|}{|H|}$$

hypotheses in $V_{SH,D}$ are consistent with D
 $\Rightarrow |V_{SH,D}|$ hypotheses equal to 1

$$P(h|D) = \frac{P(D|h) \cdot P(h)}{P(D)} = \begin{cases} \frac{1 \cdot \frac{1}{|H|}}{|V_{SH,D}|/|H|} = \frac{1}{|V_{SH,D}|} & \text{if } h \text{ is consistent with } D \\ 0 & \text{otherwise} \end{cases}$$

\therefore every consistent hypothesis is a MAP hypothesis
 since $G \subseteq V_{SH,D}$, all $g \in G$ is a MAP hypothesis

b)

EMD-G may not produce a MAP hypothesis if distribution of $P(h)$ is such that $P(g) < P(h)$ for all $g, h \in H$ such that $g >_g h$

If h is consistent with D ,

$$P(h|D) = \frac{P(D|h) \cdot P(h)}{P(h)} = \frac{1 \cdot P(h)}{|V_{SH,D}|/|H|} = \frac{P(h) \cdot |H|}{|V_{SH,D}|}$$

If h is not consistent with D ,

$$P(h|D) = 0$$

Hence $\forall g, h \in \mathcal{H}(D)$ $g >_D h \rightarrow P(g|D) < P(h|D)$

Maximally general consistent hypothesis will not be MAP if there exists
a less general hypothesis in $\mathcal{H}(D)$

c) Distribution of $P(h)$ does not matter for ML hypothesis,

$$\text{since } h_{ML} = \underset{h \in \mathcal{H}}{\text{argmax}} P(D|h)$$

$$= \text{any } h \text{ that is consistent with } D \quad (\because P(D|h) = 1)$$

Hence $P(D) - G$ which outputs a maximally consistent hypothesis is a ML hypothesis
regardless of distribution of $P(h)$

We can use the same distribution for $P(h)$ in b) which does not
guarantee a MAP hypothesis

TM6.1

$$P(\text{cancer}) = 0.008 \quad P(\neg \text{cancer}) = 0.992$$

$$P(+|\text{cancer}) = 0.98 \quad P(-|\text{cancer}) = 0.02$$

$$P(+|\neg \text{cancer}) = 0.03 \quad P(-|\neg \text{cancer}) = 0.97$$

$$\begin{aligned} P(\text{cancer} | ++) &= \frac{P(++ | \text{cancer}) \cdot P(\text{cancer})}{P(++)} \\ &\stackrel{\substack{\text{conditionally} \\ \text{independent} \\ \text{given } h}}{=} \frac{P(+|\text{cancer}) \cdot P(+|\text{cancer}) \cdot P(\text{cancer})}{P(+|\text{cancer})^2 \cdot P(\text{cancer}) + P(+|\neg \text{cancer})^2 \cdot P(\neg \text{cancer})} \\ &= \frac{0.98^2 \cdot 0.008}{(0.98^2 \cdot 0.008) + (0.03^2 \cdot 0.992)} \\ &= 0.896 = 0.9 \text{ (1dp)} \end{aligned}$$

$$h_{MAP} = \text{cancer}$$

vs
pg 6 where $h_{MAP} = \neg \text{cancer}$
given only 1 feature

$$P(\neg \text{cancer} | ++) = 1 - P(\text{cancer} | ++) = 0.104 = 0.1 \text{ (1dp)}$$

TM6.4

x_d not fixed, but drawn from probability distribution defined over X

$$P(D|h) = \prod_{d \in D} P(x_d, t_d | h)$$

(conditional independence given h)

$$= \prod_{d \in D} P(t_d | h, x_d) \cdot P(x_d | h)$$

Trick 2 see notes

$$= \prod_{d \in D} P(t_d | h, x_d) \cdot P(x_d)$$

assume x_d independent of h

$$= \begin{cases} \prod_{d \in D} P(x_d) & \text{if } h \text{ consistent with } D \\ 0 & \text{otherwise} \end{cases}$$

$$P(t_d | h, x_d) = \begin{cases} h(x_d) & \text{if } t_d = 1 \\ 1 - h(x_d) & \text{if } t_d = 0 \end{cases}$$

$$= \begin{cases} 1 & \text{if } h \text{ consistent with } D \\ 0 & \text{otherwise} \end{cases}$$

if h consistent with D

$$P(h|D) = \frac{P(D|h) \cdot P(h)}{P(D)}$$

uniform prior

$$= \frac{\prod_{d \in D} P(x_d) \cdot \frac{1}{|H|}}{P(D)}$$

$$= \frac{1}{|V_{S_{H,D}}|}$$

$$P(D) = \sum_{h \in H} P(D|h) \cdot P(h)$$

$$= \frac{1}{|H|} \sum_{h \in V_{S_{H,D}}} \prod_{d \in D} P(x_d)$$

$$= \frac{|V_{S_{H,D}}|}{|H|} \cdot \prod_{d \in D} P(x_d)$$

If h inconsistent with D

$$P(h|D) = \frac{P(D|h) \cdot P(h)}{P(D)} = 0$$

$$P(h|D) = \begin{cases} \frac{1}{|V_{S_{H,D}}|} & \text{if } h \text{ is consistent with } D \\ 0 & \text{otherwise} \end{cases}$$

\Rightarrow same posterior belief even in more general condition

Suppose $p(D|h) = \begin{cases} 1 & \text{if } h \text{ is consistent with } D \\ 0 & \text{otherwise} \end{cases}$

and $\forall s, h \in \mathcal{H} \quad h \succ_g s \rightarrow p(s) > p(h)$

more specific hypothesis is more probable a priori

$$p(h|D) = \frac{p(D|h) \cdot p(h)}{p(D)}$$

$$= \begin{cases} \frac{p(h)}{p(D)} & \text{if } h \text{ is consistent with } D \\ 0 & \text{otherwise} \end{cases}$$

since s is maximally specific hypothesis

$$\frac{p(s)}{p(D)} \geq \frac{p(h)}{p(D)} \quad \forall h \in \mathcal{H}_{(D)} \quad \therefore \argmax_{h \in \mathcal{H}} p(h|D) = s = h_{MAP} = s$$

since s is also consistent with D , it is also a ML hypothesis

\therefore since $h_{MAP} = h_{ML}$, but $p(h) \neq p(h')$ for all $h, h' \in \mathcal{H}$

$T \rightarrow F$ is a false statement / implication

$$a) \quad P(\text{camer}) = 0.02 \quad P(\sim \text{camer}) = 0.98$$

$$P(+ | \text{camer}) = 0.999 \quad P(- | \text{camer}) = 0.001$$

$$P(+ | \sim \text{camer}) = 0.001 \quad P(- | \sim \text{camer}) = 0.999$$

$$\begin{aligned} P(\text{camer} | +) &= \frac{P(+ | \text{camer}) \cdot P(\text{camer})}{P(+)} \\ &= \frac{0.999 \cdot 0.02}{0.999 \cdot 0.02 + 0.001 \cdot 0.98} \\ &= 0.836 \end{aligned}$$

$$\begin{aligned} P(\sim \text{camer} | +) &= 1 - P(\text{camer} | +) \\ &= 0.164 \end{aligned}$$

$$\begin{aligned} b) \quad P(\sim \text{camer} | ++ &= \frac{P(++ | \sim \text{camer}) \cdot P(\sim \text{camer})}{P(++)} \\ &= \frac{P(+ | \sim \text{camer})^2 \cdot P(\sim \text{camer})}{P(+ | \sim \text{camer})^2 \cdot P(\sim \text{camer}) + P(+ | \text{camer})^2 \cdot P(\text{camer})} \\ &= \frac{0.001^2 \cdot 0.98}{0.001^2 \cdot 0.98 + 0.999^2 \cdot 0.02} \\ &= 0.000787 \end{aligned}$$

very likely is camer