UCLA Algebra Seminar

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PRELIMINARY INFORMATION

This is a summary document for the UCLA Participating Algebra Seminar (i.e., MATH 290C, Participating Seminar: Current Literature in Algebra) in Winter 2023. The seminar is organized by Logan Hyslop, focusing on semisimple and reductive groups. Most of the information in this section are taken from the syllabus document.

Resources:

- Chapter 6 of *The Book of Involutions* ([boi])
- Milne's Notes on *Reductive Groups* ([rd])
- Milne's Book Algebraic Groups: the theory of group schemes of finite type over a field [(ag)], with a preliminary version available.

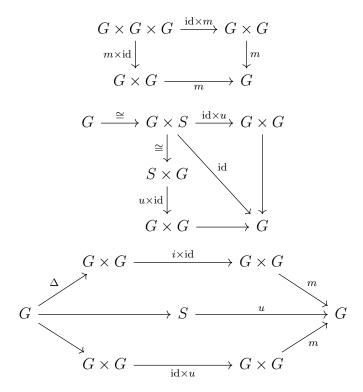
Seminar Lineup:

- 1. <u>Introduction</u>. Group schemes, subgroups, connected component of the identity, examples in group theory, c.f. section 20 of [boi].
- 2. Specific Kinds of Groups and Lie Algebras. Diagonalizable group schemes, groups of multiplicative type, Lie Algebra and smoothness, c.f. section 20 and 21 of [boi].
- 3. <u>Factor Groups.</u> Factor groups, representations, representations of diagonizable group schemes, c.f. section 22 of [boi].
- 4. Root Systems, Split Semisimple and Reductive Groups. Root systems, semisimple, reductive, split groups, c.f. section 25 of [boi], section 14-15 of [rd].

- 5. Root Systems, Split Semisimple and Reductive Groups. Split semisimple groups, root systems for split semisimple and split reductive groups, c.f. section 25 of [boi], section 18-19 of [rd].
- 6. Semisimple and Reductive Groups over Arbitrary Fields. Classification of semisimple groups over an arbitrary field, classification of reductive groups, c.f. section 24 and 26 of [rd].

1 Affine Group Scheme: Feb. 8, 2023

Definition 1.1 (Group Scheme). An S-scheme G together with the unit map $u: S \times G \to G$, the inverse map $i: G \times G \to G$, and the multiplication map $m: G \otimes_S G \to G$, is a (affine) group scheme over S if the following diagrams commutes:



Proposition 1.2. If T is a S-scheme, then

$$G(T) := \mathbf{Hom}(T, G)$$

is a group.

Remark 1.3. A group scheme homomorphism $\rho: G \to H$ over S is a morphism of schemes respecting the multiplication map. The group schemes and group scheme homomorphisms form a category, the category of group schemes over S.

Definition 1.4 (Hopf Algebra). Let F be a field and A be a commutative F-algebra. Take $G = \operatorname{Spec}(A)$ and $S = \operatorname{Spec}(F)$, then there are dual maps co-unit $u: A \to F$, co-inverse $i: A \to A$, and co-multiplication $c: A \to A \otimes_F A$. Suppose the dual diagrams of Definition 1.1 commutes, then A is a Hopf algebra over F. In particular, $Hom_{F-Alg}(A, -)$ are groups.

Example 1.5. Let $\mathbf{1} = \operatorname{Spec}(F)$. Note that F is trivially an F-Hopf algebra. In particular, $\mathbf{1}(T) = \{e\}$. We have $c: F[x] \to F[y, z]$ via $x \mapsto y + z$, $u: x \mapsto 0$, and $i: x \mapsto -x$ over $G_a = \operatorname{Spec}(F[x])$, where $G_a(A)$ is the additive group (A, +).

Let $G_m = \operatorname{Spec}(F[x, x^{-1}])$ with $c: x \mapsto x \otimes x$, we have $G_m(A)$ as the multiplicative group (A^{\times}, \cdot) . Now G_a and G_m correspond to \mathbb{A}^1 and $\mathbb{A}^1 \setminus \{0\}$, respectively.

Example 1.6. In general, let V be a F-vector space, then the symmetric algebra $S(V^*)$ of the dual space V^* satisfies

$$\mathbf{Hom}_{\mathbf{Alg}_F}(S(V^*), R) = \mathbf{Hom}_F(V^*, R) = V \otimes_F R,$$

and $S(V^*)$ represents $R \mapsto (R \otimes_F V, +)$, and so $\operatorname{Spec}(S(V^*))$ is a group scheme.

Example 1.7. Given an F-algebra A, $\operatorname{GL}_1(A)$ is described $\operatorname{GL}_1(A)(R) = (A \otimes R)^{\times}$, represented by $S(A^*) \left[\frac{1}{N}\right]$. In general, $\operatorname{GL}_n(F)$ is given by $F\left[X_{ij} \mid 1 \leq i, j \leq n\right] \left[\frac{1}{\det(X)}\right]$.

Remark 1.8. An (affine) group scheme G over F is a functor $G : \mathbf{Alg}_F \to \mathbf{Grp}$ isomorphic to $\mathbf{Hom}_{\mathbf{Alg}_F}(A, -)$ for some Hopf algebra A over F. By the Yoneda Lemma, the Hopf algebra A is uniquely determined by G (up to isomorphism), and is therefore denoted F[G]. In this sense, a group scheme homomorphism is a natural transformation of functors.

Remark 1.9 (Correspondence).

Group Schemes over $F \iff$ Commutative Hopf Algebras over F

$$G \mapsto F[G]$$

$$G^A \longleftrightarrow A$$

defines an equivalence of categories.

Definition 1.10 (Algebraic Group Scheme). An (affine) group scheme A is algebraic if its coordinate ring is a finitely-generated F-algebra.

Remark 1.11. If L/K is a field extension, then any L-algebra is a K-algebra, and so we say $A \otimes L$ is the restriction of A to L.

Definition 1.12 (Closed Subgroup, Normal). A closed subgroup H of a group scheme G is just a closed subscheme such that u, i, m restrict down to H. In particular, if G is affine, i.e., $G = \operatorname{Spec}(A)$, then $H = \operatorname{Spec}(A/J)$ where J is a Hopf ideal, i.e., $c(J) \subseteq J \otimes A + A \otimes J$.

We now denote $H \subseteq G$. We say $H \subseteq G$ is normal if $H(T) \subseteq G(T)$ is normal for all spectrums of F-algebras T.

Remark 1.13 (Trivial Subgroup). Every Hopf algebra has an augmented ideal $I = \ker(u : A \to F)$, which is a Hopf ideal. Therefore, $\mathbf{1} \to \operatorname{Spec}(A)$ always gives a trivial normal subgroup.

Remark 1.14 (Kernel). Let $\varphi: G \to H$ be a morphism of group schemes (over discrete groups). The kernel is constructed as the pullback:

$$\ker(\varphi) \longrightarrow G \\
\downarrow \qquad \qquad \downarrow \\
\mathbf{1} \longrightarrow H$$

Example 1.15. Consider $F[x, x^{-1}] \to F[x, x^{-1}]$ given by $x \mapsto x^k$, then by applying the spectrum functor, we obtain a morphism of group schemes $\exp(k): G_m \to G_m$. The kernel of this map is the unit group μ_k .

Now
$$\mathcal{O}(\mu_k) = F[x, x^{-1}] \otimes_{F[x^k, x^{-k}]} F = F[x]/(x^k - 1).$$

Recall if G is a Lie group, then $\pi_0(G)$ is a group and there is a surjection $G \to \pi_0(G)$ whose kernel is the connected component of identity (in the Zariski sense). There is a similar story for group schemes.

Definition 1.16 (étale). A finitely-generated F-algebra A is étale if $A \cong L_1 \times \cdots \times L_n$ where L_i/F is separable.

Example 1.17. $A \otimes_F F^{\text{sep}} \cong (F^{\text{sep}})^n$.

Proposition 1.18. If A is a finitely-generated F-algebra, then A has a unique maximal étale subgroup $\pi_0(A)$.

If $B \subseteq A$ is étale, then $\dim_F(B)$ is bounded by the number of essential idempotents, and the compositum of two étale subalgebras is again étale. Therefore, there is a maximal étale subalgebra.

Further, if A is a Hopf algebra, then $\pi_0(A)$ is also a Hopf algebra, then the identity of an affine group scheme is the kernel of the map

$$G \to \operatorname{Spec}(\pi_0 \mathcal{O}(G)) =: \pi_0(G).$$

Proposition 1.19. If G is a finite group and $A := \mathbf{Hom}(G, F) \cong F[e_g \mid g \in G]$, then A has a Hopf algebra structure given by $A \ni e_g \mapsto \sum_{hk=g} e_h \otimes e_k$. Furthermore, $\mathrm{Spec}(A(T)) \cong G$ for Zariski connected T.

2 Groups and Lie Algebras: Feb. 15, 2023

In this section, we construct all concepts upon a based field F.

2.1 Diagonalizable Groups

Definition 2.1 (Diagonalizable Group Schemes). Let H be an Abelian group, then the functor $R \to \mathbf{Hom}(H, R^{\times})$ is representable by H_{diag} , for $R \in \mathbf{Alg}_F$. That is, we have $H_{\text{diag}}(R) = \mathbf{Hom}(H, R^{\times})$. In particular, H_{diag} is the group scheme representing the group algebra $F \langle H \rangle$ over F to be the group algebra of H, given by $c(h) = h \otimes h$, $i(h) = h^{-1}$, and u(h) = 1. Therefore, this gives a Hopf algebra structure on the group algebra. Group schemes of the form H_{diag} are called diagonalizable.

Remark 2.2. Note that the elements in $F\langle H\rangle$ are given of the form $h\otimes h$ for $h\in H$. Therefore, we have a natural isomorphism from $(H_{\text{diag}})^*$ and H.

Example 2.3. $\mathbb{Z}_{\text{diag}} = G_m$ and $(\mathbb{Z}/n\mathbb{Z})_{\text{diag}} = \mu_n$.

Definition 2.4 (Multiplicative Type). We say a group scheme G is of multiplicative type if $G_{\text{sep}} := G_{F_{\text{sep}}}$ is diagonalizable.

Remark 2.5. In particular, diagonalizable group schemes are of multiplicative type.

Let $\Gamma = \operatorname{Gal}(F^{\operatorname{sep}}/F)$ and H be an Abelian group equipped with a continuous Γ -action, then $R \to \operatorname{Hom}_{\Gamma}(H, (R \otimes_F F^{\operatorname{sep}})^{\times})$ is represented by H_{mult} . In cash, $H_{\operatorname{mult}}(R) = \operatorname{Hom}_{\Gamma}(H, (R \otimes_F F_{\operatorname{sep}})^{\times})$.

Proposition 2.6. There is an equivalence of categories between

- \bullet group schemes of multiplicative type over F, and
- Abelian groups with a continuous Γ-action,

defined by two contravariant functors, with $G \mapsto (G_{\text{sep}})^* = \mathbf{Hom}_{\mathbf{GrpSch}}(G_{\text{sep}}, G_m)$ for group scheme G, and with $H \mapsto H_{\text{mult}}$ for Abelian group H.

Remark 2.7. In particular, diagonalizable group schemes correspond to Abelian groups with trivial Γ -action.

2.2 Lie Algebra

Let G be an algebraic group scheme.

Definition 2.8 (Lie Algebra). The Lie algebra of G, denoted Lie(G) is the tangent space of G at the identity.

Proposition 2.9. Lie(G) = $(I/I^2)^*$ where I is the augmentation ideal of A, the Hopf Algebra of G, i.e., $G = \operatorname{Spec}(A)$.

Proof. A_I is the local ring at the identity, so $\text{Lie}(A) = (IA_I/I^2A_I)^* = (I/I^2)^*$.

Definition 2.10 (Derivator). If A is an F-algebra and M is an A-module, then a derivator D from A to M is a F-linear map $A \to M$ satisfying D(fg) = fD(g) + gD(f).

Proposition 2.11. There are natural isomorphisms between

- 1. Lie group G,
- 2. $\operatorname{der}(A, F)$, where F is an A-algebra using $u: A \to F$ with D(fg) = u(f)D(g) + u(g)D(f),
- 3. The left-invariant derivations, given by $\{D \in \text{Der}(A, A) \mid c \circ D = (\text{id} \otimes D) \circ c\},\$
- 4. $\ker(G(F[\varepsilon]) \to G(F))$ where $F[\varepsilon]$ is the dual numbers over F given by $\varepsilon^2 = 0$. This is a kernel of groups induced by $F[\varepsilon] \to F$. In particular, the kernel carries a natural F-vector space structure: the addition operation is the multiplication on $G(F[\varepsilon])$, and the scalar multiplication operation is defined by the following action: for $a \in F$ and g in the kernel, $a \cdot g = G(l_a)g$, where $l_a : F[\varepsilon] \to F[\varepsilon]$ is the multiplication map defined by $\varepsilon \mapsto a\varepsilon$.

Proposition 2.12. Lie(G) has finite dimension over F.

Proof. Note that A is Noetherian, so I is finite-dimensional, so I/I^2 is finite-dimensional over A/I = F, so $(I/I^2)^*$ is finite-dimensional over F.

Remark 2.13. The Lie group has the following properties.

- 1. $\operatorname{Lie}(G_1 \times G_2) = \operatorname{Lie}(G_1) \times \operatorname{Lie}(G_2)$.
- 2. $\operatorname{Lie}(G^0) = \operatorname{Lie}(G)$.
- 3. Given a field extension L/F, $Lie(G_L) = Lie(G) \otimes_F L$.

Remark 2.14. In particular, the Lie bracket is induced via the structure on vector space and the bracket on deriviators given by $[D_1, D_2] = D_1D_2 - D_2D_1$.

Example 2.15. 1. For the general linear group $GL_n(R)$, the associated Lie algebra is $\mathfrak{gl}_n = M_n(F)$.

- 2. For the standard linear group $SL_n(R)$, the associated Lie algebra is $\mathfrak{sl}_n = \{M \in M_n(F) \mid tr(M) = 0\}$.
- 3. For the orthogonal group $O_n(R)$, the associated Lie algebra is $\mathfrak{O}_n = \{M \in M_n(F) \mid M + M^T = 0\}$.

In particular, for even n=2m, we have the special linear group $\mathfrak{sp}_n(R)=\{A\in M_n(R)\mid A^T\Omega A=\Omega\}$ for $\Omega=\begin{bmatrix}0&I_n\\-I_n&0\end{bmatrix}$, then the associated Lie algebra is given by $\mathfrak{sp}_n=\{M\in M_n(F)\mid \Omega M+M^T\Omega=0\}.$

2.3 Dimension and Smoothness

Definition 2.16 (Dimension). If G is a connected group, then the reduced structure $F[G]_{red}$ is a domain. In particular, the dimension $\dim(G)$ of G is the transcendence degree of F over the field of fractions of $F[G]_{red}$. If G is not connected, we define $\dim(G) = \dim(G^0)$.

Example 2.17. • $\dim(V) = \dim_F(V)$.

- $\dim(\operatorname{GL}_n(R)) = n^2$.
- $\dim(\operatorname{SL}_n(R)) = n^2 1$.
- $\dim(G_m) = \dim(G_a) = 1.$
- $\dim(\mu_n) = 0$.

Remark 2.18. The dimensions satisfy many important properties.

- 1. $\dim(G) = \dim(F[G])$, given by the Krull dimension.
- 2. G is finite if and only if $\dim(G) = 0$.
- 3. Given a field extension L/F, $\dim(G_L) = \dim(G)$.
- 4. $\dim(G_1 \times G_2) = \dim(G_1) + \dim(G_2)$.

Recall that we say a commutative local ring R we have $\dim_{R/\mathfrak{m}}(\mathfrak{m}/\mathfrak{m}^2) \geq \dim(R)$. In particular, we say R is regular if the equality holds.

Definition 2.19 (Smooth). We say a group G is smooth if $\dim(\text{Lie}(G)) = \dim(G)$. Equivalently, $F[G]_L$ is reduced for any field extension L/F.

Proposition 2.20. If F is a perfect field, then G is smooth if and only if F[G] is reduced.

Remark 2.21. Suppose F has characteristic 0, every algebraic group is smooth.

Example 2.22. Suppose F has characteristic p > 0, then $\mu_p = \text{Spec}(k[x]/x^p - 1) = k[x]/(x - 1)^p$, which is not smooth.

3 Factor Schemes and Representations: Fed. 22, 2023

3.1 Criteria of Injectivity and Surjectivity

Recall that a homomorphism of group schemes $f: F \to G$ is a natural transformation. We now try and describe what it means for this morphism to be injective or surjective.

Definition 3.1 (Injective). f is injective if $\ker(f) = 1$, or equivalently, all the maps $F(R) \to G(R)$ are injective.

Proposition 3.2 (Injectivity Criterion). Let $f: G \to H$ be a homomorphism, then the following are equivalent:

- 1. f is injective,
- 2. f is a closed embedding, i.e., $f^*: F[h] \to F[G]$ is surjective,
- 3. $f_{\text{alg}}: G(F_{\text{alg}}) \to H(F_{\text{alg}})$ is injective, and $df: \text{Lie}(G) \to \text{Lie}(H)$ is injective.

Remark 3.3 (Facts about Hopf Algebras). Suppose $A \subseteq B$ are Hopf algebras over F, then B is faithfully flat over A:

- $A \to B$ is flat, and $\operatorname{Spec}(B) \to \operatorname{Spec}(A)$ is surjective.
- M, N are A-modules, $M \to N$ is an injective map if and only if $M \otimes_A B \to N \otimes_A B$ is.

Let us see how we may apply this fact. Look at the maps $B \rightrightarrows B \otimes_A B$ defined by $b \mapsto b \otimes 1$ and $b \mapsto 1 \otimes b$, respectively, then the elements of B having the same images under $B \rightrightarrows B \otimes_A B$ are precisely the elements of A.

Proof. We only prove $(1) \Rightarrow (2)$ here.

By restricting the codomain, we can make sure f^* is injective. The elements of $G(F[G] \otimes_{F[H]} F[G])$ corresponding to $F[G] \rightrightarrows F[G] \otimes_{F[H]} F[G]$ have the same image in $H(F[G] \otimes_{F[H]} F[G])$, and therefore they have to be the same. Thus, for $F[G] \rightrightarrows F[G] \otimes_{F[H]} F[G]$, both maps have the same image, thus F[G] = F[H] as a consequence of the remark above.

Example 3.4. • $\mu_n \to G_m$.

• $G_m \to \mathrm{GL}_n$.

Definition 3.5 (Surjective). $f: G \to H$ is surjective if $f^*: F[H] \to F[G]$ is injective.

Proposition 3.6 (Surjectivity Criterion). For $f: G \to H$ a homomorphism of algebraic group schemes, and suppose H is smooth, then f is surjective if and only if $f_{\text{alg}}: G(F_{\text{alg}}) \to H(F_{\text{alg}})$ is surjective.

Example 3.7. The *n*the power map $G_m \to G_m$.

3.2 Construction of Quotients

The quotient structure behaves weirdly over group schemes. Consider the exact sequence of group schemes

$$1 \longrightarrow \mu_n \longrightarrow G_m \stackrel{\cdot^n}{\longrightarrow} G_m \longrightarrow 1$$

but on points we only have

$$1 \longrightarrow \mu_n(R) \longrightarrow G_m(R) \stackrel{\cdot^n}{\longrightarrow} G_m(R)$$

and we note that $(G/N)(R) \not\cong G(R)/N(R)$ in general.

Let us have GL_2 acting on $k^2 = ke_1 \oplus ke_2$. Consider the subgroup scheme B of upper-triangulars, then B is the stabilizer of ke_1 , and GL_2 acts transitively on the one-dimensional subspaces of k^2 . Therefore, the coset space is P^1 , which is not affine.

3.3 Representations

A representation of a group scheme G is $\rho: G \to \mathrm{GL}(V)$ for V a finite-dimensional vector space over F.

On points: R is a F-algebra, then G(R) acts on $V \otimes_F R$ by R-linear automorphsims, for $g \in G(R)$, $v \in V \otimes_F R$, $g \cdot v = \rho_R(g)(v)$.

On the Hopf side, note that for A = F[G] we have $\bar{\rho}: V \to V \otimes_F A$ such that $\bar{\rho}(v) = \mathrm{id}_A \cdot v$.

Example 3.8. For dim(V) = 1, $GL(V) = G_m$ (characters of $G: G \to G_m$).

There i san adjoint representation from having G(R) acts on $\text{Lie}(G) \otimes_F R$ (with G = GL(v) conjugation).

Theorem 3.9. If $G \to H$ has kernel N and is surjective, then any group scheme map $f': G \to H'$ which vanishes on N factors uniquely through f.

If N is a normal subgroup scheme of G, then there is a surjection $G \to H$ with kernel N. Here every structure is affine.

4 ROOT SYSTEMS, SPLIT SEMISIMPLE AND REDUCTIVE GROUPS:

4.1 ROOT SYSTEMS AND SEMISIMPLE LIE ALGEBRA

All concepts in this subsection are over \mathbb{C} . Recall that \mathbf{SL}_n is the kernel of the determinant map, and $d(\det)$ is the trace. Therefore, we have SL_n is the kernel of the trace, therefore as a subset of \mathfrak{gl}_n . We mainly discuss two examples, \mathfrak{sl}_2 and \mathfrak{sl}_3 .

In \mathfrak{sl}_2 , there is a basis given by

$$e = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, f = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, h = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

and in particular this is a h-eigenbasis, with

$$[h, e] = 2e, [h, f] = -2f, [h, h] = 0.$$

Let V be a finite-dimensional irreducible representation of \mathfrak{sl}_2 , so $V = \bigoplus_{\alpha \in \mathbb{C}} V_{\alpha}$ where $V_{\alpha} = \{v \in V : hv = \alpha v\}$. In this sense,

$$e: V_{\alpha} \to V_{\alpha+2}$$

$$f: V_{\alpha} \to V_{\alpha-2}$$

We also need to make use of several facts:

- \bullet All h-eigenvalues of V are integers, and
- if we let n be the maximal h-eigenvalue with $v \in V_n \setminus \{0\}$, then $\{v, f(v), \dots, f^n(v)\}$ is a basis for V. In particular, there is

$$0 \stackrel{e}{\longleftrightarrow} V_{-n} \stackrel{e}{\longleftrightarrow} \cdots \stackrel{e}{\longleftrightarrow} V_{n-2} \stackrel{e}{\longleftrightarrow} V_n \stackrel{e}{\longleftrightarrow} 0$$

and therefore V_n is the highest weight.

Theorem 4.1. Finite-dimensional irreducible representations of \mathfrak{sl}_2 are totally and uniquely determined by the largest h-eigenvalue.

Remark 4.2. Note that \mathfrak{sl}_2 is semisimple.

We now think of the embeddings $\mathfrak{sl}_2 \hookrightarrow \mathfrak{sl}_3$, and in particular there are three types of them:

(i)

$$\begin{pmatrix} . & . \\ . & . \\ . & . \\ e \mapsto e_{12} \\ f \mapsto f_{21} \\ h \mapsto h_{12} \end{pmatrix}$$

(ii)

$$\begin{pmatrix} \cdot & \cdot \\ \cdot & \cdot \\ \cdot & \cdot \end{pmatrix}$$

$$e \mapsto e_{13}$$

$$f \mapsto f_{31}$$

$$h \mapsto h_{13}$$

(iii)

$$\begin{pmatrix} \cdot & \cdot & \cdot \\ & \cdot & \cdot \\ & \cdot & \cdot \end{pmatrix}$$

$$e \mapsto e_{23}$$

$$f \mapsto f_{32}$$

$$h \mapsto h_{23}$$

Definition 4.3. Let $\mathfrak{g} = \mathfrak{sl}_3$ and $\mathfrak{h} = \{x \in \mathfrak{g} \mid x \text{ diagonal}\} \subseteq \mathfrak{g}$ the maximal Abelian subalgebra.

A few other crucial facts include:

- The adjoint matrix of $(h_{ij})_{i,j}$ is diagonalizable,
- v is an eigenvector of h, and

• consider the map

$$\mathfrak{h} o \mathbb{C}$$

 $h \mapsto \text{eigenvalue of } h \text{ on } V$

then $\mathfrak{h}^* = \mathbb{C} \langle L_1, L_2, L_3 \rangle / (L_1 + L_2 + L_3 = 0)$ where $L_i(x) = x_{ii}$. Then

$$\begin{cases} \operatorname{adj}(h)(e_{ij}) = (L_i - L_j)(h)e_{ij} \\ \operatorname{adj}(h)(f_{ji}) = (L_j - L_i)(h)f_{ji} \end{cases}$$

for i < j and all $h \in \mathfrak{h}$.

Proposition 4.4. $\mathfrak{g} = \mathfrak{h} \oplus \bigoplus_{\alpha \in R} g_{\alpha}$ where R is the set $\{L_i - L_j \mid 1 \leq i \neq j \leq 3\}$ (as roots of \mathfrak{g} with respect to \mathfrak{h}), and $\mathfrak{g}_{\alpha} = \{v \in \mathfrak{g} \mid hv = \alpha(h)v \ \forall h \in \mathfrak{h}\}$. For instance, $g_{L_1 - L_2} = \operatorname{span}(e_{12})$.

Definition 4.5 (Killing Form). The Killing form is defined by

$$k: \mathfrak{g} \otimes \mathfrak{g} \to \mathbb{C}$$

 $x \otimes y \mapsto \operatorname{tr}(\operatorname{adj}(x)\operatorname{adj}(y))$

A few facts to know include:

- k is non-degerneate, then $\mathfrak{g} \xrightarrow{\sim} \mathfrak{g}^k$.
- For $h \in \mathfrak{h}$, $k(h,h) = \sum_{\alpha \in R} \alpha(h)^2$ where $\alpha(h_\alpha) = 2$. This is the inner product on \mathfrak{h} .

Definition 4.6. $E = \mathbb{R} \langle R \rangle$ is the inner product space on the Killing form.

Given a root α , let S_{α} be (orthonormal) reflection in E about span $(\alpha)^{\perp}$.

Definition 4.7 (Weil Group). We define $W(\mathfrak{g}) = \langle S_{\alpha} \mid \alpha \in R \rangle$ to be the Weil group.

Example 4.8. For $\mathfrak{g} = \mathfrak{sl}_3$, then $W(\mathfrak{g}) \cong S_3$.

Theorem 4.9. Now let E be a finite-dimensional real vector space, K is an inner product space, and $R \subseteq E$ be a finite subset, such that

- (i) for all $\alpha \in R$, $n\alpha \in R$ if and only if $n = \pm 1$,
- (ii) S_{α} preserves R,
- (iii) $\alpha, \beta \in R$, then $K(\alpha, \beta)/K(\alpha, \alpha) \in \frac{1}{2}\mathbb{Z}$,
- (iv) $E = \operatorname{span}(R)$,

then (E, K, R) is a root system.

4.2 Reductive Groups and Root Datum

Let k be a field in this subsection.

Definition 4.10. An algebraic group is called unipotent if all of its non-zero representations admit a non-zero fixed point.

Definition 4.11. Let G be a smooth, connected algebraic group over k. $R_n(G)$ is the maximal smooth connected unipotent normal group, usually called the unipotent radical.

We say that G is reductive if $R_n(G_{\bar{k}})$ is trivial.

Example 4.12. G_a is unipotent. GL_n , SL_n , PGL_n are reductive.

Let G be a reductive group, and let $T \subseteq G$ be the maximal torus.

Definition 4.13. • The lattice is defined by $X^{\cdot}(T) = \mathbf{Hom}(T, G_n)$.

- Define the set of roots $R \subseteq X^{\cdot}(T)$ as the non-zero characters arising from the roots of adj(A) on \mathfrak{g} .
- The colattice is defined by $X_{\cdot}(T) = \mathbf{Hom}(G_m, T)$.
- The coroots $R^v \subseteq X_{\cdot}(T)$ are the cocharacters arising from the following proposition.

Proposition 4.14. For $\alpha \in R$, there exists maps

$$\mathbf{SL}_2 \mapsto G$$

$$\mathfrak{sl}_2 \mapsto \mathfrak{g}$$

$$e \mapsto \mathfrak{g}_\alpha \setminus \{0\}$$

restrict this to $T \cong G_m \subseteq \operatorname{SL}_2$ then gives

$$G_m \longrightarrow T$$

$$\downarrow \qquad \qquad \downarrow$$

$$\operatorname{SL}_2 \longrightarrow G$$

Now there is a table of root datum:

	SL_2	SL_3
torus T	$\begin{pmatrix} \alpha \\ \alpha^{-1} \end{pmatrix}$	$\begin{pmatrix} \alpha \\ 1 \end{pmatrix}$
$X^{\cdot}(T)$	$ \begin{array}{c} \mathbb{Z} \xrightarrow{\sim} \mathbf{Hom}(T, G_m) \\ n \mapsto \left(\begin{pmatrix} \alpha \\ \alpha^{-1} \end{pmatrix} \mapsto \alpha^n \right) \end{array} $	$\mathbb{Z} \xrightarrow{\sim} \mathbf{Hom}(T, G_m)$ $n \mapsto \begin{pmatrix} \alpha \\ 1 \end{pmatrix} \mapsto \alpha^n$
R	$\begin{pmatrix} \alpha \\ \alpha^{-1} \end{pmatrix}$ with $\alpha \mapsto \alpha^2$, $\alpha^{-1} \mapsto \alpha^{-2}$, represented by $\{\pm 2\}$	$\begin{pmatrix} \alpha \\ 1 \end{pmatrix}$ with $\alpha \mapsto \alpha^2$, $1 \mapsto \alpha^{-1}$, represented by $\{\pm 1\}$
X.(T)	\mathbb{Z}	\mathbb{Z}
R^v	$\begin{pmatrix} \alpha \\ \alpha^{-1} \end{pmatrix}$ with $\alpha \mapsto \begin{pmatrix} \alpha \\ \alpha^{-1} \end{pmatrix}$, $\alpha^{-1} \mapsto \begin{pmatrix} \alpha^{-1} \\ \alpha \end{pmatrix}$ represented by $\{\pm 1\}$	with $\alpha \mapsto \begin{pmatrix} \alpha \\ \alpha^{-1} \end{pmatrix}$ $\alpha^{-1} \mapsto \begin{pmatrix} \alpha^2 \\ 1 \end{pmatrix} \sim \begin{pmatrix} \alpha \\ \alpha^{-1} \end{pmatrix},$ $\alpha^{-1} \mapsto \begin{pmatrix} \alpha^{-2} \\ 1 \end{pmatrix}$ represented by $\{\pm 2\}$

Example 4.15. • $Lie(T) = A = \mathfrak{h}$,

• $\operatorname{Lie}(G_m) = G_a$.

Remark 4.16. There is a correspondence between reductive groups over $k = \bar{k}$ and the roots datum above, given by the map $G \mapsto G^L$, where $(-)^L$ is the Langlands dual.