Generalization = predicting power. Built a decision tree: how well will it do on future data? Lead us to PAC model. What is the "true error" or generalization error of a classifier? · Decision frees: fix T, probability distribution D on new examples.

(X, Y)

(X, Y)

(hallenge label $(x, y) \sim D$ True error/ Generalization error. X' | Y' | '= S training set.

! Learner is Given S.

Learner memorizes S, and hands it back.

On new example, H just outputs O. You can build a decision tree (size = |s|) that is consistent with all the points in S - training set

Question: How well does the tree generalize? What is the true error of this tree?

How can we estimate the true error of a classifier (in this case a decision tree)?

We a "hold-out" or a "validation set", call it "H".

S = training set.

1) use S to build a decision tree.

H = hold-out set.

2) Estimate tree 's true error via

its error on H.

Cross-validation: a way to reuse the data that you've held out into a hold-out set.

Another approach:

trade-off training error with "model complexity."

Define another potential function ϕ ϕ : frees \rightarrow IR. Given a training set S $\phi(T)$ = training error on S + χ . Size Shyperparameter, training set.

Good: minimize ϕ :

My training error

My Size of free

increase |S|

Another approach: MDL/Minimum Description Length

principle.

Some # of bits needed to encode S.

upper bound m.(n+1) label.

training features
examples

Build a tree T:

Let's say T is correct on 90% of S and incorrect on 10%.

We can encode S using # bits (T) and # bits to encode that 10% we got wrong.

This captures the notion of compression.