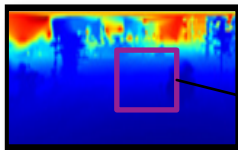
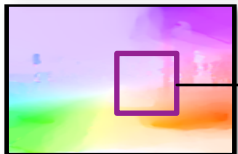


LIDAR



L

Optical
flow



(U, V)

Video



(R, G, B)



RGBLUV
channels