

Aspect-Ratio Sensitive Network (ARS Net)

Jianxiong Cai

Anqi Pang

Lei Jin

Ruijian Li

Peijia Xu

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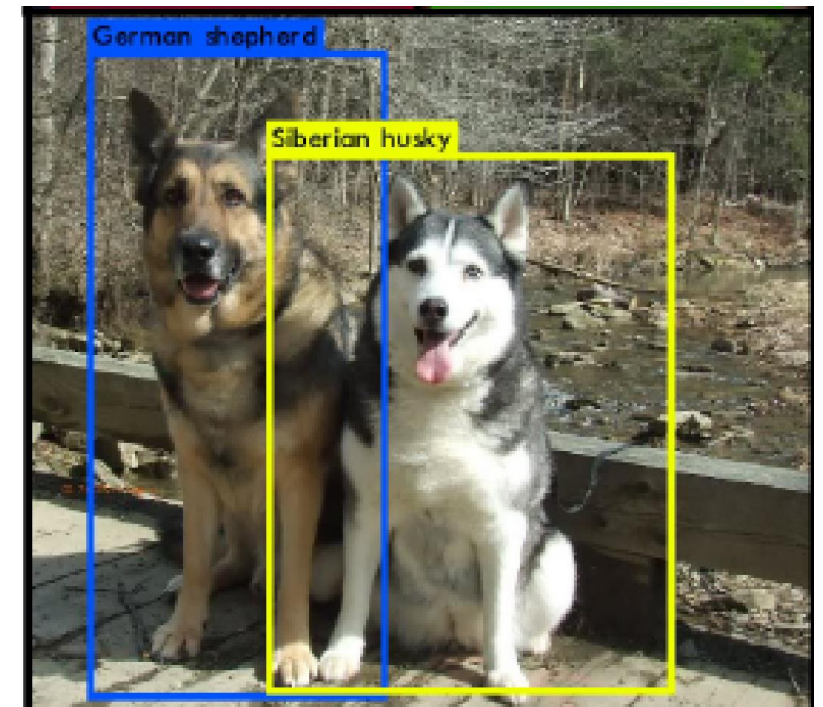
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 - Motivation
 - Related work
- Our approach
 - ARS net
 - NMS
- Performance Evaluation
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Object Detection

- Object Detection?
 - Identify bounding boxes
 - Classify the objects
- Two-stage Network (Faster RCNN)
 - Feature Extractor
 - RPN
 - Classifier + Regressor



An object detection result from YOLOv2

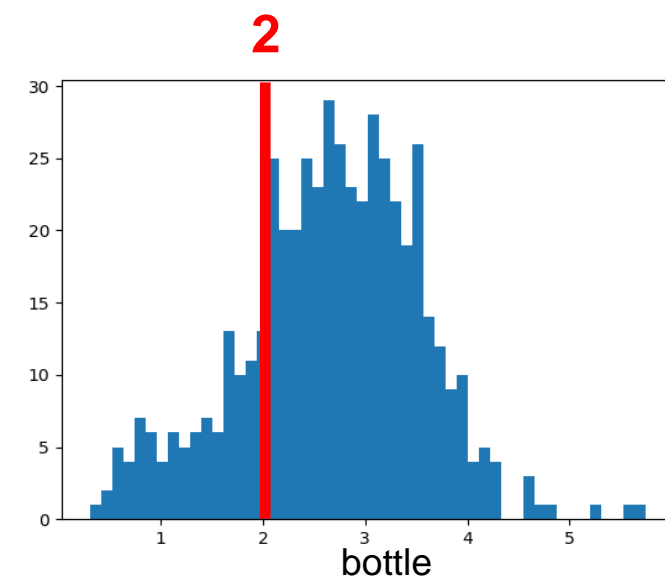
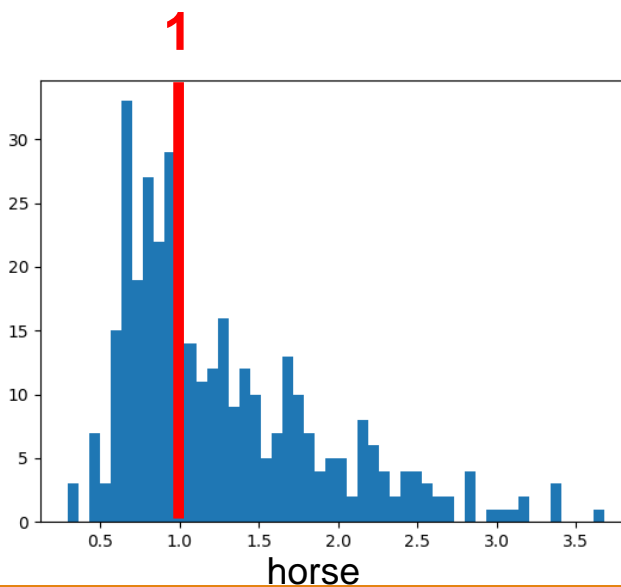
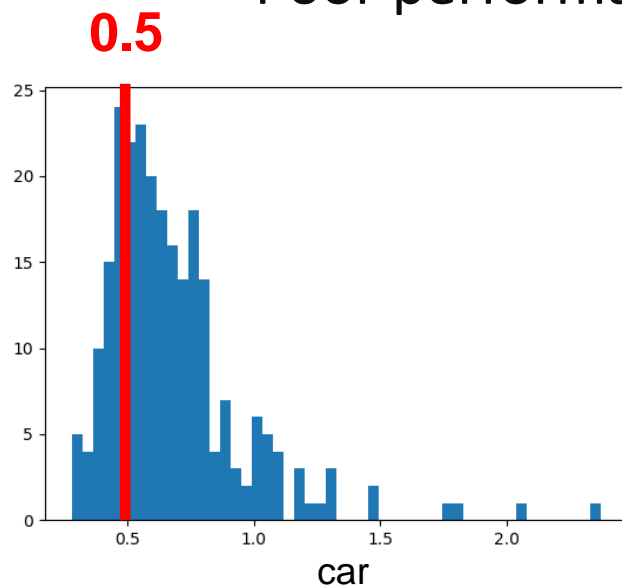
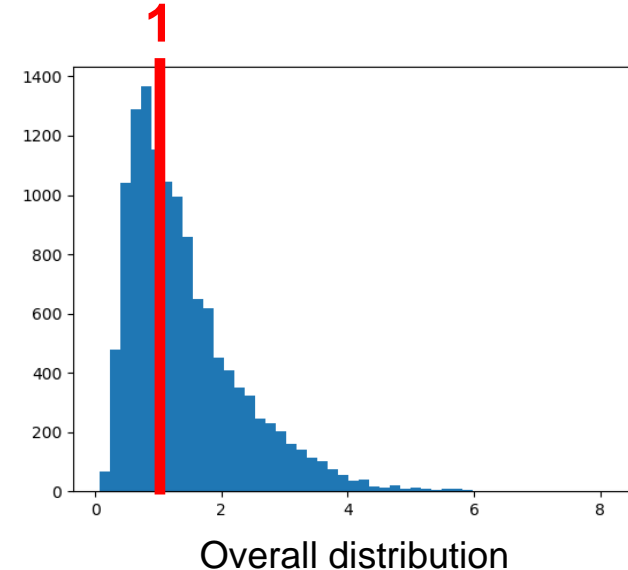
Motivation

- Object tends to have certain shape (Aspect Ratio)

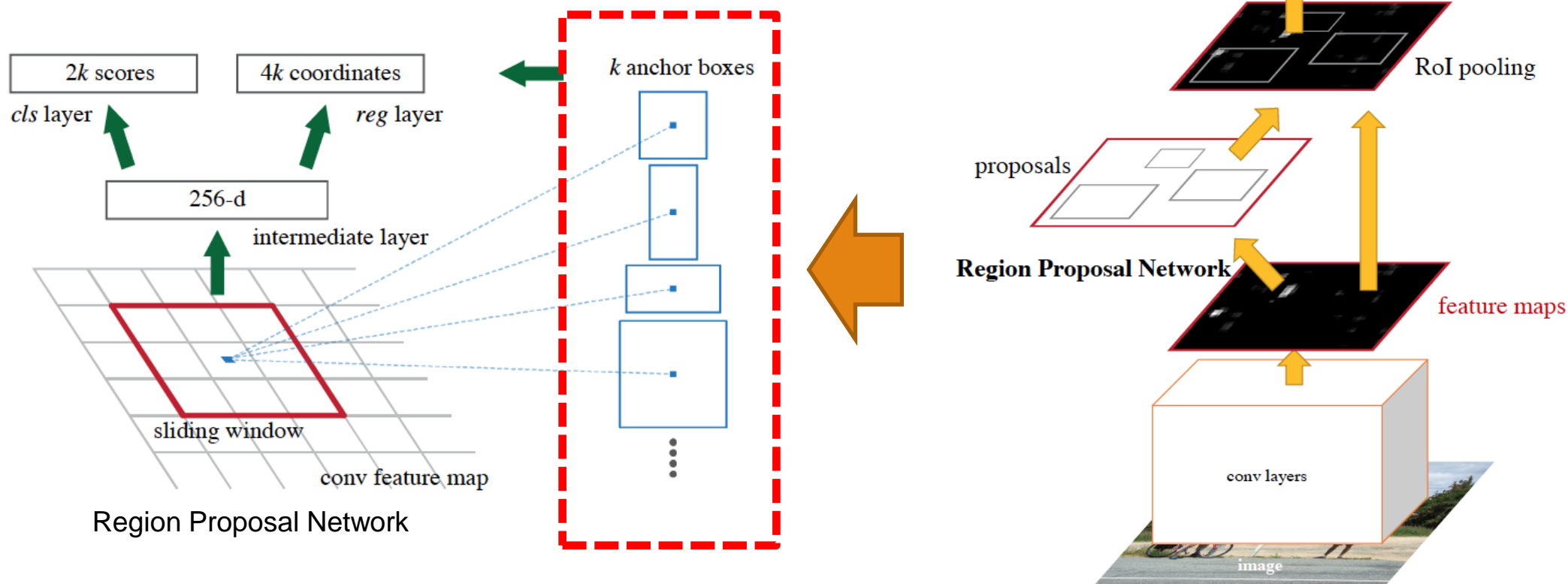


Motivation 1: Aspect Ratio

- VOC 2007 training set
 - Aspect ratio differ
 - Median ≈ 1
 - Poor performance



Motivation 2: RPN

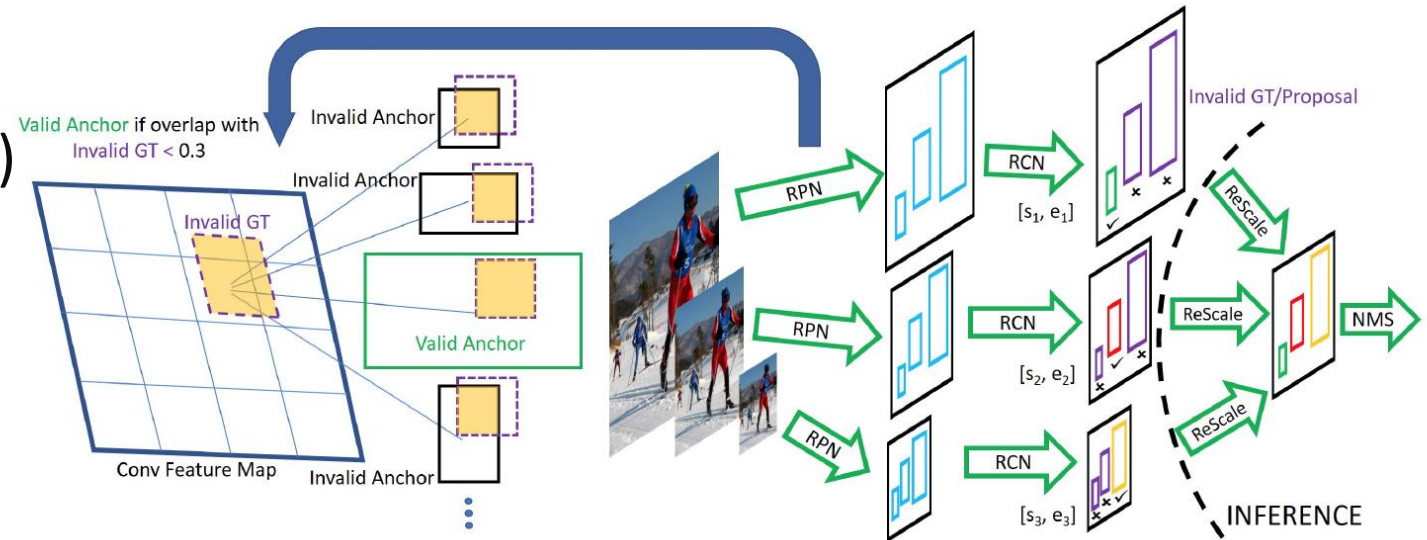


Goal

- RPN
 - Better ROI Proposal
 - Fewer ROI Proposal (less false negative)
- Aspect Ratio

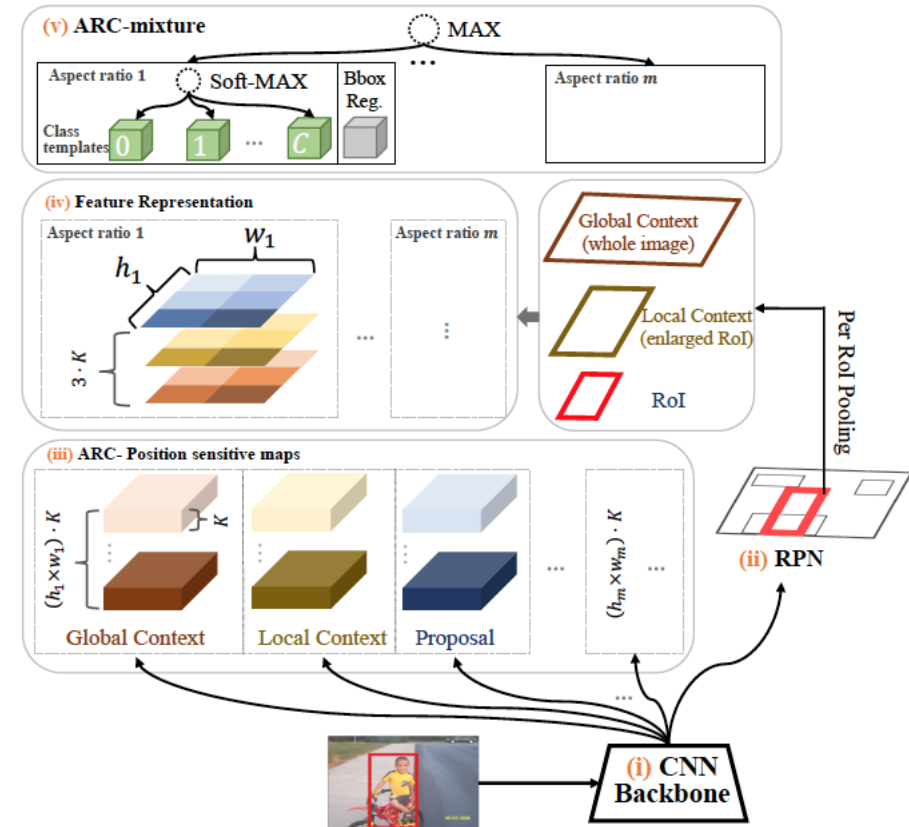
Related work

- SNIP
 - Feature pyramid
 - Multi RPN(based on multi-scale)



Related work

- ARC-R-CNN
(Aspect Ratio and Context Aware)
 - Filter RPN output
 - Multiple Aspect Ratio

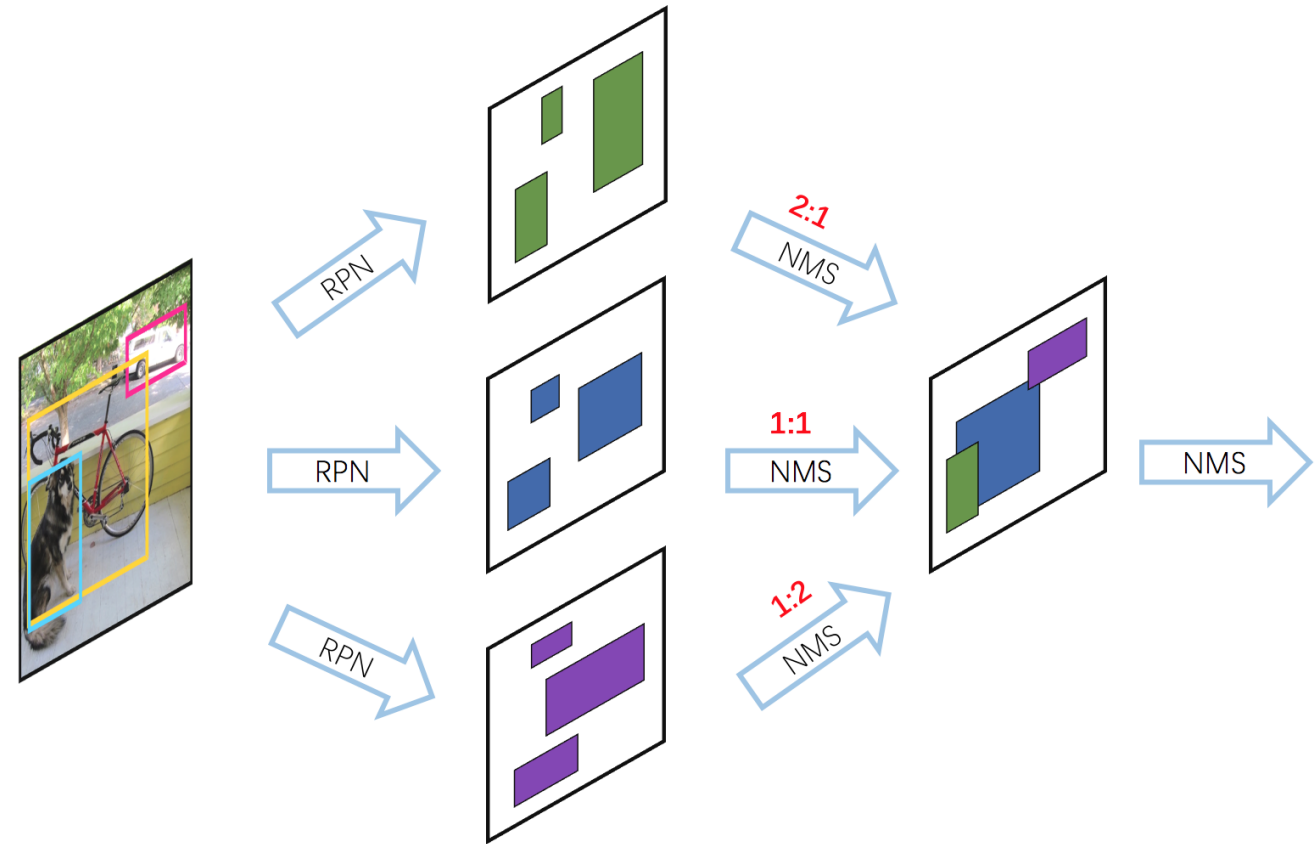


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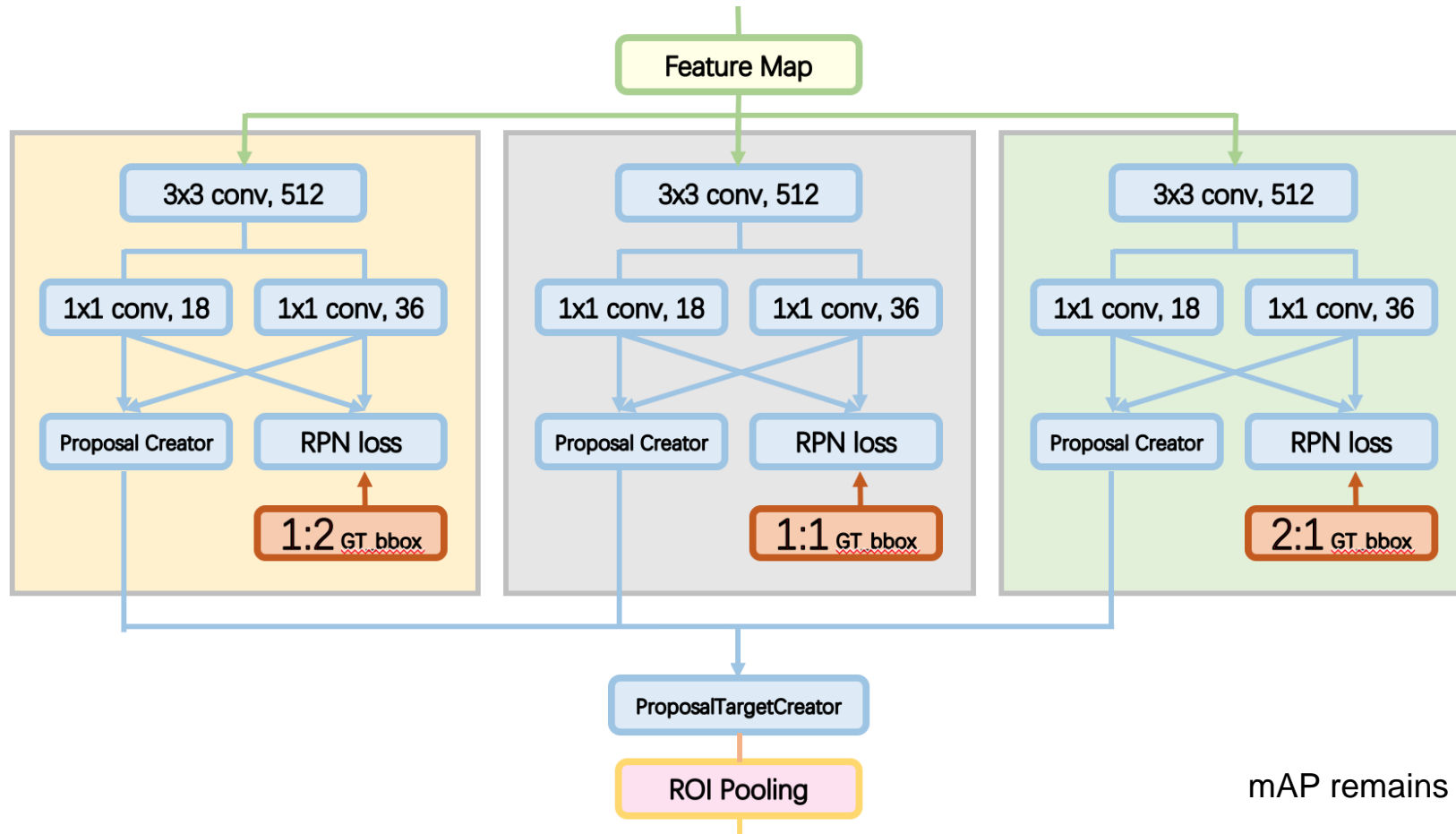
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Our Approach

- Multiple RPNs
 - Aspect ratio differ
 - 3 anchor box each

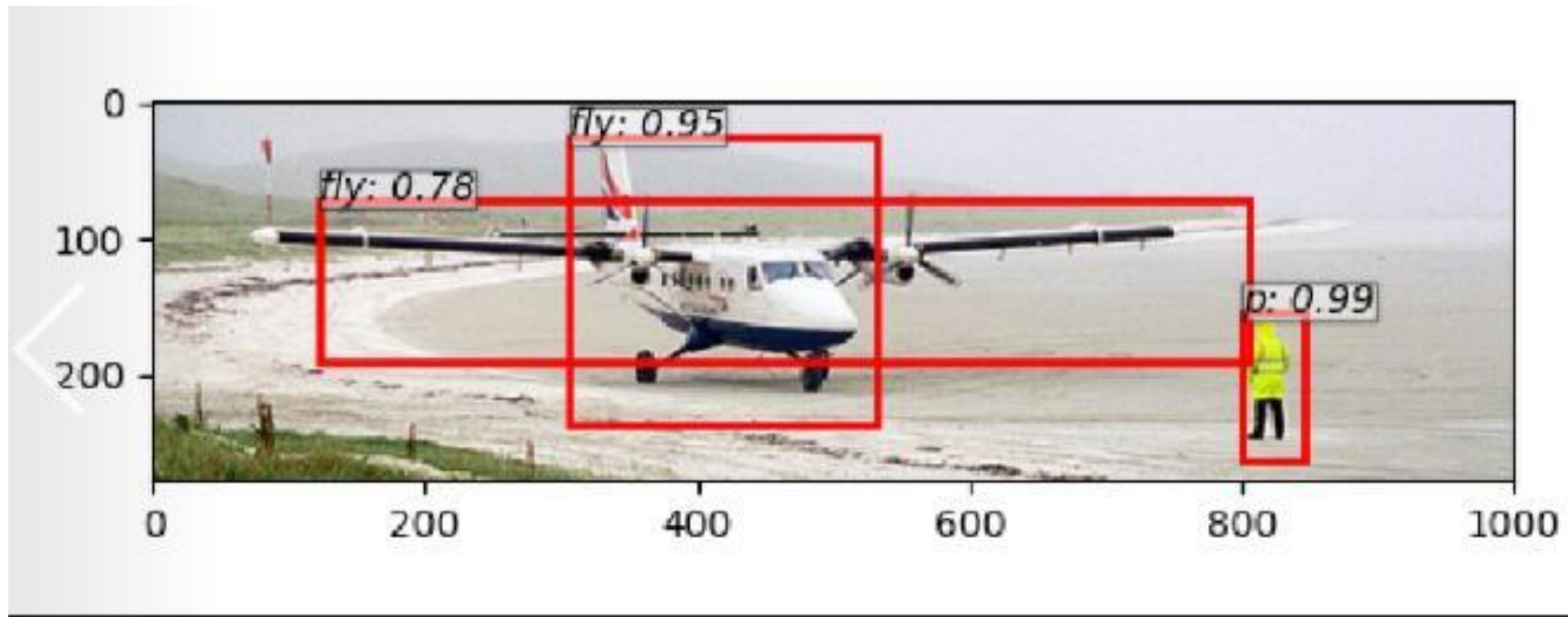


Multiple RPNs

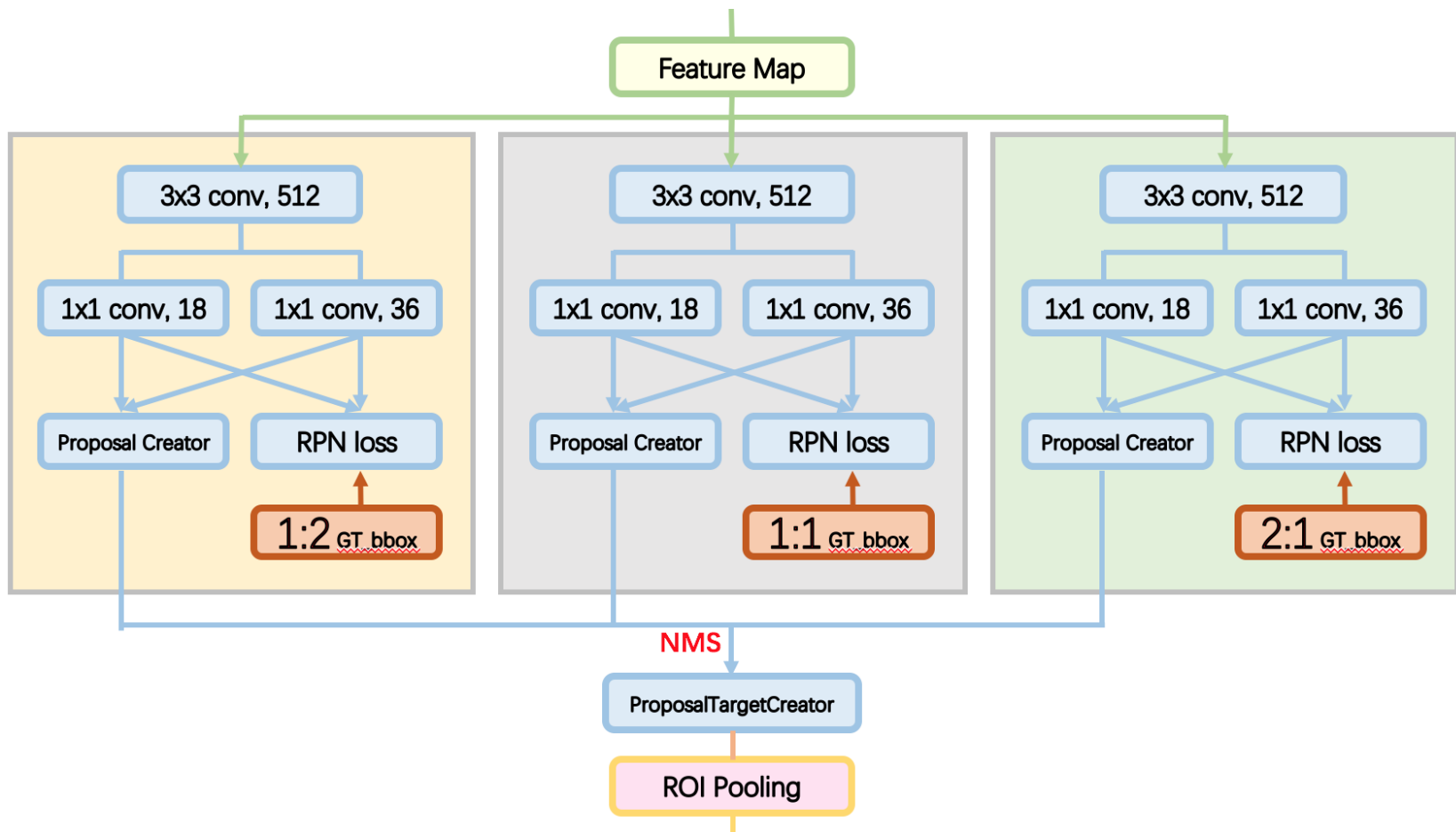


mAP remains unchanged

More False Positive



Multiple RPNs

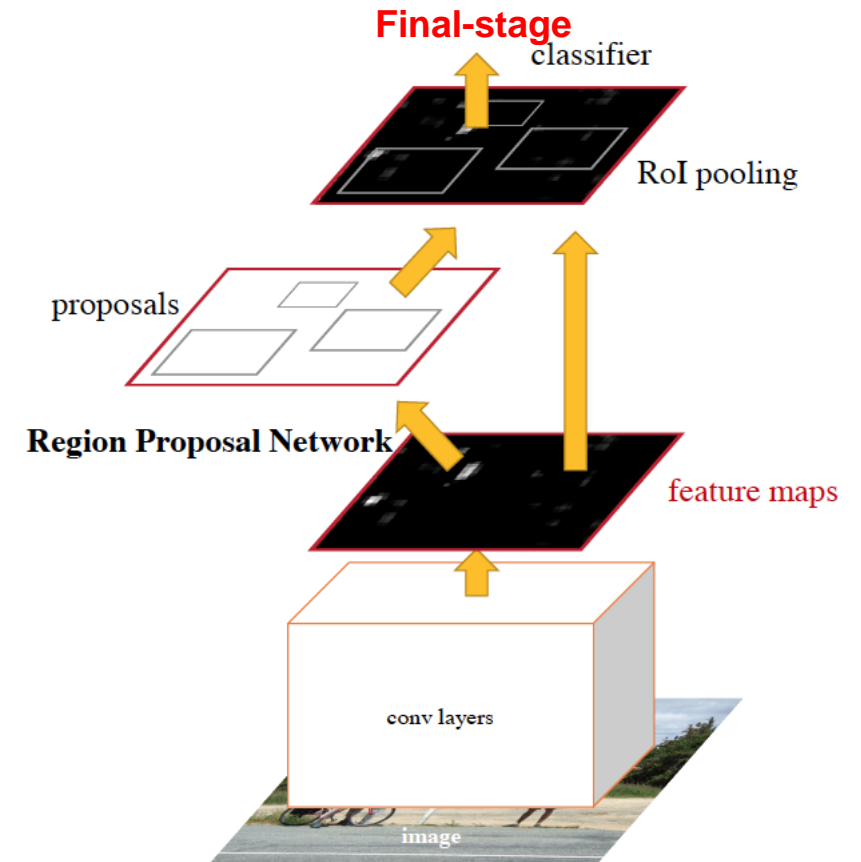
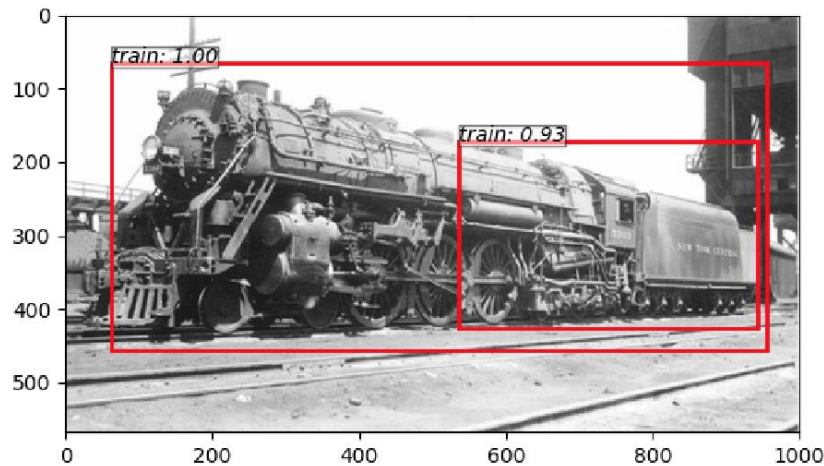


NMS again after RPN?

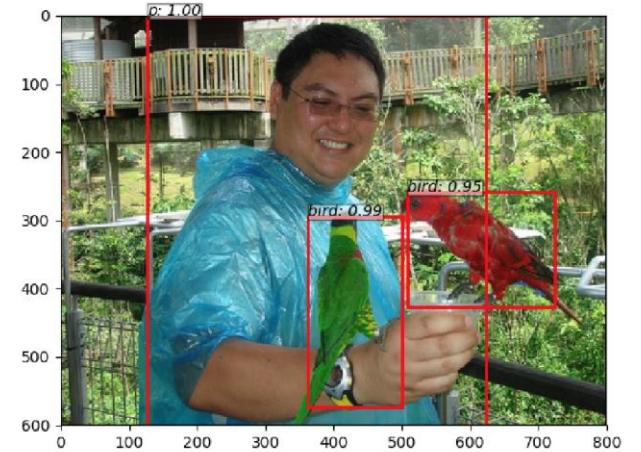
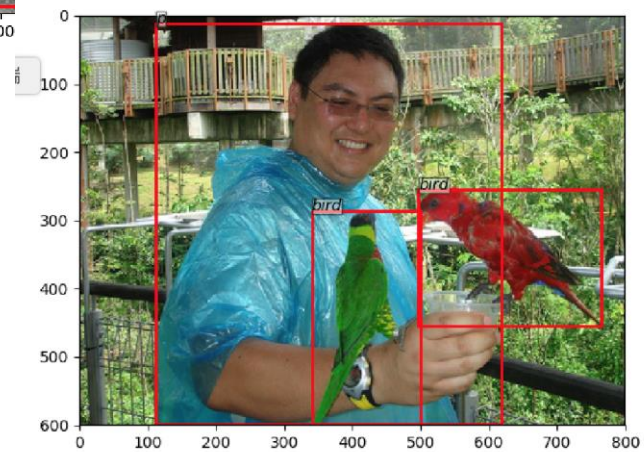
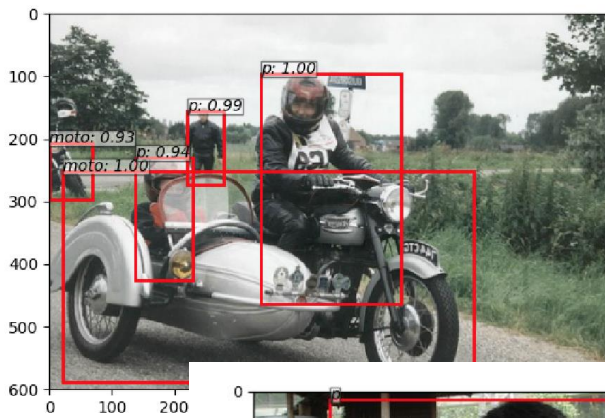
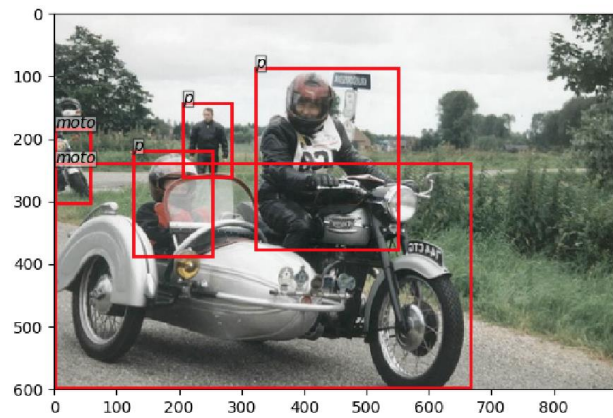
- Keep the proposal number same (900->300)
- That's doesn't work (at this stage)
 - mAP decreased by 1% (RPNs are isolated)

Final-stage Suppression

- Overlapping bbox



Some Results



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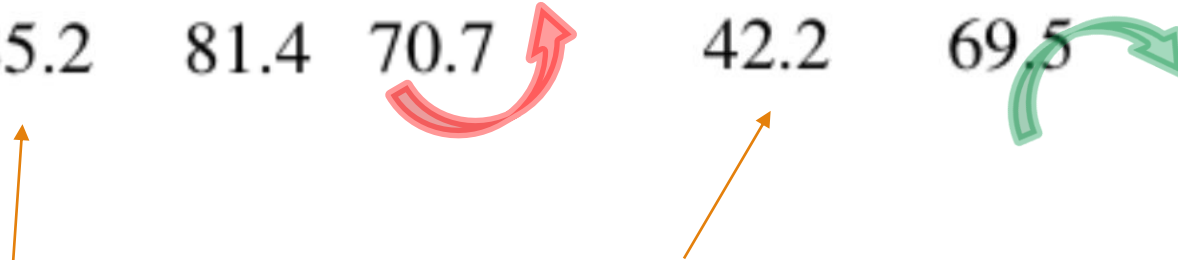
Final-stage Suppression

ARSNNet, no suppression, 900 proposals	71.7
ARSNNet, with suppression, 900 proposals	73.3

Ours vs Original Fast-RCNN

More precious on certain region

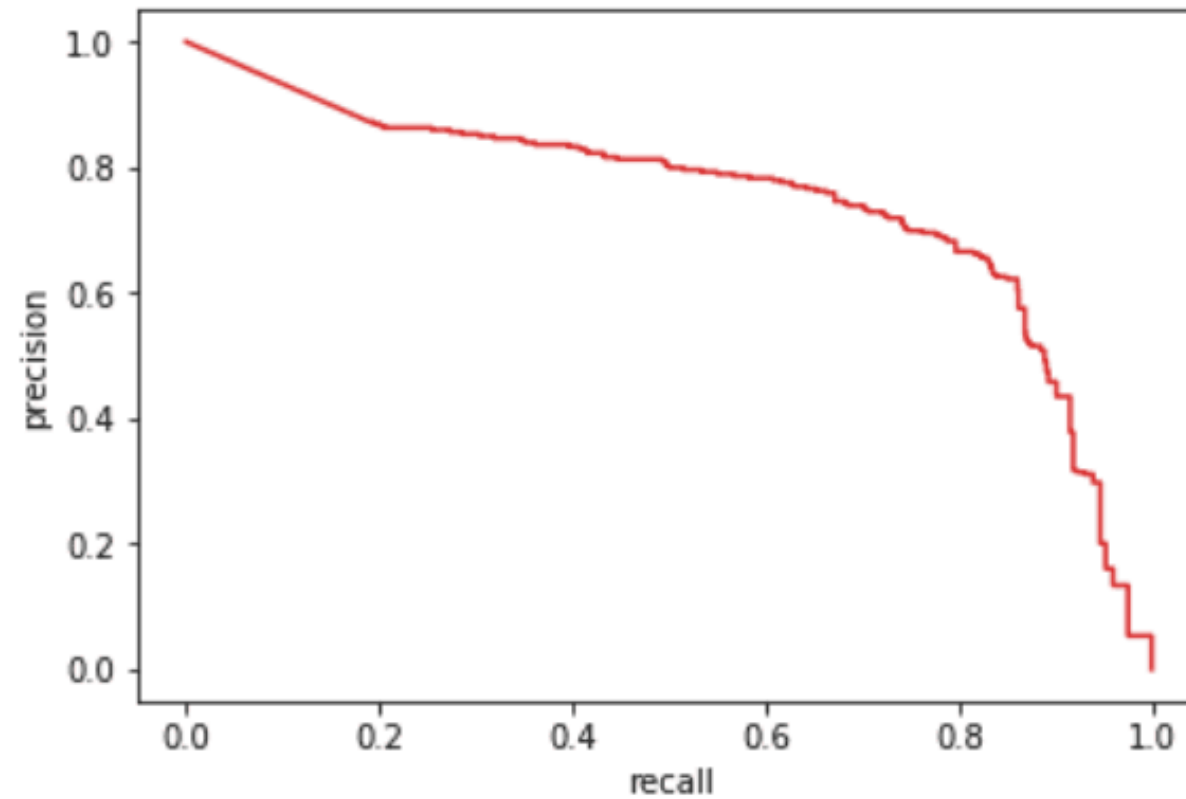
method	proposals	mAP	bottle	bus	cow	sofa	plant	sheep
Faster RCNN	300	71.8	52.3	80.7	76.8	65.9	44.7	72.5
Our approach	300	73.0	56.1	83.4	82.9	70.0	40.7	69.7
Our approach	900	73.3	58.0	85.2	81.4	70.7	42.2	69.5



The diagram illustrates the performance gains of 'Our approach' over 'Faster RCNN'. An orange arrow points from the 'Faster RCNN' row to the first 'Our approach' row (300 proposals), highlighting improvements in mAP (71.8 to 73.0) and specific class APs (bottle: 52.3 to 56.1, bus: 80.7 to 83.4, cow: 76.8 to 82.9, sofa: 65.9 to 70.0, plant: 44.7 to 40.7, sheep: 72.5 to 69.7). A red curved arrow points from the 'Faster RCNN' row to the second 'Our approach' row (900 proposals), indicating further gains in mAP (71.8 to 73.3) and class APs (bottle: 52.3 to 58.0, bus: 80.7 to 85.2, cow: 76.8 to 81.4, sofa: 65.9 to 70.7, plant: 44.7 to 42.2, sheep: 72.5 to 69.5). A green curved arrow points from the first 'Our approach' row to the second 'Our approach' row, showing the benefit of increasing proposals from 300 to 900.

method	proposals	data	mAP	areo	bike	bird	boat	bottle	bus	car	cat	chair	cow	table	dog	horse	mbike	person	plant	sheep	sofa	train	tv
Faster RCNN(Github)	300	VOC07	71.8	73.5	81.5	68.5	53.7	52.3	80.7	85.3	84.3	52.5	76.8	71.5	81.3	84.9	75.1	79.6	44.7	72.5	65.9	79.8	72.3
Our approach	300	VOC07	73.0	75.2	81.3	70.9	55.4	56.1	83.4	83.3	87.4	53.6	82.9	71.5	83.7	87.6	74.6	77.3	40.7	69.7	70.0	81.8	73.9
Our approach	900	VOC07	73.3	75.0	80.6	71.7	56.5	58.0	85.2	83.6	87.9	53.1	81.4	71.9	83.6	87.5	74.2	77.3	42.2	69.5	70.7	82.3	73.4

Performance



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Discussion

- Hard negative
 - No obvious improvement on VOC 2007



- Unbalanced size of proposal from each RPN net
- Change ratio (shape) of anchor

Conclusion (Contribution)

- Multiple RPN based on shape (aspect ratio) is simple and useful especially for some aspect-ratio sensitive objects.
- More Proposal -> More false positive -> Suppress at the final-stage
- Future Work: Train and Evaluation on coco

Reference

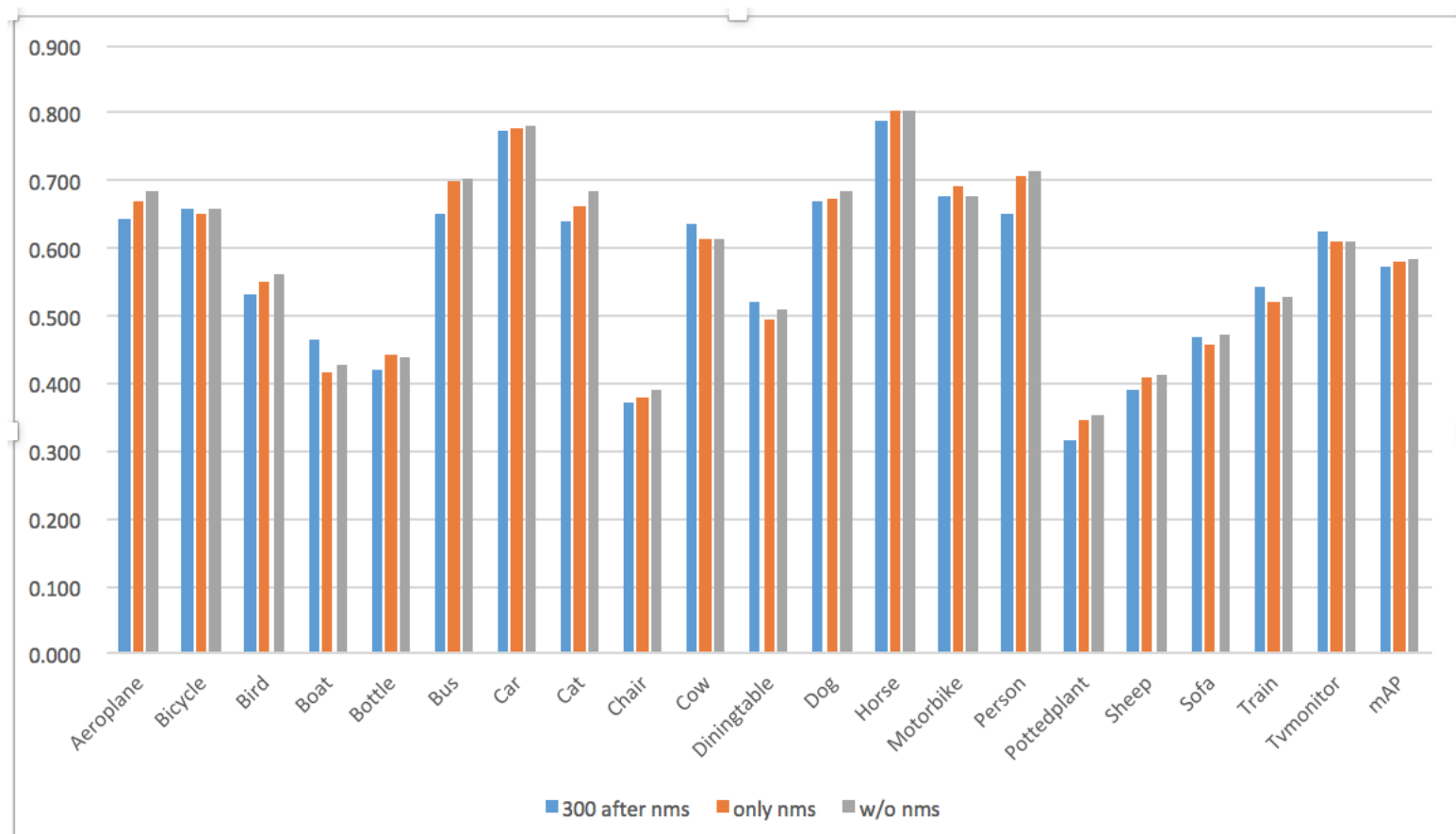
Works mentioned in the presentation only

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- [2] Redmon, Joseph, and Ali Farhadi. "YOLO9000: Better, Faster, Stronger." *Computer Vision and Pattern Recognition (CVPR), 2017 IEEE Conference on*. IEEE, 2017.
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- [5] Singh, Bharat, and Larry S. Davis. "An Analysis of Scale Invariance in Object Detection-SNIP." , 2017.
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- [7] K. Simonyan and A. Zisserman. Very deep convolutional networks for large-scale image recognition. Technical report, 2014.

Q&A

Appendix

Result of NMS immediately after RPNs



Appendix: Performance

method	proposals	data	mAP
Faster RCNN	300	VOC07	71.8
Our approach	300	VOC07	73.0
Our approach	900	VOC07	73.3

Appendix: number of proposal

method	proposals	data	mAP
Faster RCNN	300	VOC07	71.8
ARSNNet, no suppression	900	VOC07	71.7

Appendix: Related Ideas

- Rotated bounding box
 - Less background
 - Ground truth?
 - Split RPN by rotation

