

Prep: bring ID, water, glasses, jacket, pen and a handwritten version of this set of notes

**You got this!**

Union Find Disjoint Set (UFDS)		Set Cover	
<p>rank(<math>x</math>): height of subtree below node <math>x</math> (excl)</p> <ul style="list-style-type: none"> <li><math>\forall x</math> rank(<math>x</math>) <math>\leq</math> rank(<math>\pi(x)</math>) with equality if and only if <math>x = \pi(x)</math> (<math>\pi(x)</math> = parent of <math>x</math>)</li> <li>Any root node of rank(<math>k</math>) has <math>\geq 2^k</math> nodes in its subtree (excl)</li> <li>For <math>n</math> nodes, at most <math>\frac{n}{2^k}</math> nodes of rank <math>k</math></li> <li>[Corollary] All nodes have rank <math>\leq \log n</math>. Hence, <i>find</i> and <i>union</i> takes <math>O(\log n)</math></li> </ul> <p>Path compression: a sequence of <math>n</math> <i>make_sets</i> and <math>m</math> <i>union / find</i> takes <math>O(n + m \cdot \alpha(m, n))</math></p> <p>Proof for <math>O((m + n) \log^* n)</math> (<math>\log^*(2 \uparrow i) = i</math>):</p> <ul style="list-style-type: none"> <li>Group nodes by rank; consider intervals <math>[0], [1], (1, 2), \dots, (2 \uparrow i, 2 \uparrow (i + 1)], \dots</math></li> <li>Largest nonempty interval <math>i = \log^* n - 1</math></li> <li># of nodes in <math>(2 \uparrow i, 2 \uparrow (i + 1)] \leq \frac{n}{2 \uparrow i}</math></li> </ul>		<p>Given <math>U = \{1, \dots, n\}</math>, subsets <math>S_1, \dots, S_m \subset U</math> s.t. <math>\bigcup_{i=1}^m S_i = U</math>, find collection of minimal cardinality <math>J = \{S_i\}</math> s.t. <math>\bigcup_{i \in J} S_i = U</math>.</p> <p><u>Greedy algorithm</u>: Repeatedly pick <math>S_i</math> that covers the maximum # of uncovered elements</p> <p><u>Theorem</u>: If optimal solution uses <math>k</math> sets, Greedy uses at most <math>k \ln n</math> sets. Greedy is the best efficient approximation for Set Cover.</p> <p><u>Key idea</u>: Let <math>n_t</math> be number of elements not covered after <math>t</math> iterations of Greedy. Suffices to show <math>n_{k \ln n} &lt; 1</math>. Claim: <math>n_{t+1} \leq n_t \left(1 - \frac{1}{k}\right)</math></p>	
Linear Programming		Max Flow	
<p><u>Definitions</u>:</p> <ul style="list-style-type: none"> <li>Vertex: <math>x</math> s.t. <math>x</math> is <b>feasible</b> and <math>n</math> of inequalities are tight (<math>n</math> is dimension of the problem i.e. <math>x \in \mathbb{R}^n</math>) <ul style="list-style-type: none"> <li>For every subset of <math>n</math> constraints, solve for point of intersection; check feasibility</li> </ul> </li> <li>Unbounded: objective value <math>p^* = \infty</math> <ul style="list-style-type: none"> <li>Primal unbounded <math>\Rightarrow</math> Dual infeasible and has no vertices</li> <li>Can check for boundedness by using linear combinations of constraints</li> </ul> </li> <li>Feasible: solution <math>p^* &lt; \infty</math> <ul style="list-style-type: none"> <li>Primal feasible <math>\Rightarrow</math> Dual feasible and lower-bounded</li> <li>Dual feasible <math>\Rightarrow</math> Primal upper-bounded</li> </ul> </li> </ul> <p><u>Facts</u>:</p> <ul style="list-style-type: none"> <li>Feasible region of LP is always convex</li> <li><math>\forall</math> LP, <math>\exists x</math> a solution that is a vertex <ul style="list-style-type: none"> <li>Find all vertices, get optimal value</li> </ul> </li> </ul>		<p><u>Algorithm</u>:</p> <ul style="list-style-type: none"> <li>Start with zero flow</li> <li>Repeat: choose viable path from <math>s</math> to <math>t</math>; increase flow along the edges as much as possible; change weights of residue graph</li> </ul> <p><math>G^f = (V, E^f)</math> is the residual graph of <math>G = (V, E)</math></p> $f(x) = \begin{cases} c_{uv} - f_{uv}, & (u, v) \in E, f_{uv} < c_{uv} \\ f_{uv}, & (u, v) \in E, f_{uv} > 0 \end{cases}$ <p><u>Definitions</u>:</p> <ul style="list-style-type: none"> <li><math>s - t</math> cut: <math>(L, R)</math> s.t. <math>L \cup R = V, s \in L, t \in R</math></li> <li>Capacity of <math>(L, R)</math>: <math>\sum_{u \rightarrow v: u \in L, v \in R} c_{u \rightarrow v}</math></li> </ul> <p><u>Theorems and Facts</u>:</p> <ul style="list-style-type: none"> <li>Max-Flow Min-Cut: Size of maximum flow in a network = capacity of smallest <math>s - t</math> cut</li> <li>For any flow <math>f</math> and any cut <math>(L, R)</math>, <math>f \leq \text{capacity}(L, R)</math></li> <li>If all capacities <math>\in \mathbb{Z}</math>, maximum flow is integral</li> <li>No flow of value <math>k</math> from <math>s</math> to <math>t \Rightarrow</math> min cut has capacity <math>&lt; k</math> with <math>s \in S, t \in T</math></li> <li>Flow of value <math>k</math> from <math>s</math> to <math>t \Rightarrow</math> min cut has capacity <math>\geq k</math></li> </ul> <p><u>Techniques</u>:</p> <ul style="list-style-type: none"> <li>Phantom source, sink, nodes and edges</li> </ul>	
Duality			
Primal LP	Dual LP		
$\max_x c^T x$ <p>subject to <math>Ax \leq b</math> and <math>x \geq 0</math></p>	$\min_y b^T y$ <p>subject to <math>A^T y \geq c,</math> <math>y \geq 0</math></p>		

$\min_x c^T x$ <p>subject to <math>Ax \geq b</math> and <math>x \geq 0</math></p>	$\max_y b^T y$ <p>subject to <math>A^T y \leq c</math>, <math>y \geq 0</math></p>
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**Duality Theorems:**

- [Weak] Objective value of any feasible solution to primal  $\leq$  objective value of any feasible solution to dual i.e.  $p^* \leq d^*$ 
  - Solutions of dual upper bounds primal
  - Solutions of primal lower bounds dual
- [Strong] If  $p^* < \infty$ , then  $p^* = d^*$ .
  - If LP has bounded optimum  $p^*$ , so does its dual, and  $p^* = d^*$

Interpretation of  $y$ : Lagrange multiplier for constraints; i.e. weights the importance placed on each constraint.

Primal	Dual
$\max_x c_1 x_1 + \dots + c_n x_n$ <p><math>a_{i1}x_1 + \dots + a_{in}x_n \leq b_i</math> for <math>i \in I</math>  <math>a_{i1}x_1 + \dots + a_{in}x_n = b_i</math> for <math>i \in E</math>  <math>x_j \geq 0</math> for <math>j \in N</math></p>	$\max_y b_1 y_1 + \dots + b_m y_m$ <p><math>a_{1j}y_1 + \dots + a_{mj}y_m \geq c_j</math> for <math>j \in N</math>  <math>a_{1j}y_1 + \dots + a_{mj}y_m = c_j</math> for <math>j \notin N</math>  <math>y_i \geq 0</math> for <math>i \in I</math></p>

**Zero Sum Games**

For game matrix  $G = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ , expected payoff =  $\sum_{i,j} G_{ij} \mathbb{P}[R = i, C = j]$  ( $R$  plays  $i$ ,  $C$  plays  $j$ )

**Theorems and Facts:**

- Once a player's strategy is fixed, there is a optimal pure strategy for the other player.
- [Von Neumann] For  $A \in \mathbb{R}^{m \times n}$ 

$$\max_{x \in X} \min_{y \in Y} x^T A y = \min_{y \in Y} \max_{x \in X} x^T A y$$

$$\max_x \min_y \sum_{i,j} G_{ij} x_i y_j = \min_y \max_x \sum_{i,j} G_{ij} x_i y_j$$

**Linear Programs**

Game #1: Row announces her strategy  $p$

$$\max_{p_1, p_2: p_1 + p_2 = 1, p_1, p_2 \geq 0} \min_{q \text{ mixed}} p^T A q = \max_p \min_{q \text{ pure}} p^T A q$$

Game #2: Column announces her strategy  $q$

$$\min_{q_1, q_2: q_1 + q_2 = 1, q_1, q_2 \geq 0} \max_{p \text{ mixed}} p^T A q = \min_q \max_{p \text{ pure}} p^T A q$$

Note: In  $\min_c \max_r P(r, c)$ , row goes second  $\Rightarrow$  has more information.

- Bipartite matching: have phantom nodes  $s, t$ , find max flow from  $s$  to  $t$ .  $\exists$  matching  $\Leftrightarrow$  can send  $n$  units of flow
- Hall's Marriage Lemma

**LP Algorithms (Simplex, Ellipsoid, Interior Point)**

**SIMPLEX( $v$ )**: # returns optimal vertex  
 while  $obj(v') > obj(v)$  and  $v'$  neighbor of  $v$ :  
 return **SIMPLEX( $v'$ )**  
 return  $v$

- Two vertices  $\in \mathbb{R}^n$  are neighbors if they share  $n - 1$  inequalities in common
- Number of neighbors of  $v$  in LP with  $n$  variables and  $m$  constraints  $\leq (m - n) \cdot n$
- $O\left(\binom{m+n}{n} mn\right)$  (worst case exponential time)
- Problems with Simplex and Solutions
  - Starting vertex (find by transforming LP)
  - Degeneracy (introduce perturbation)
  - Unboundedness (opt increases to  $\infty$ ; halt and complain)

Ellipsoid algorithm and Interior Point method are polynomial time algorithms

**Multiplicative Weights Update**

Problem:  $n$  experts  $E_1, \dots, E_n$ . On  $t$ th day, expert  $E_i$  incurs a loss  $l_i^{(t)} \in \{0, 1\}$ . Pick  $E_j$  and incurs loss  $l_j^{(t)}$ . Want to minimize regret after  $T$  days = Total loss – Total loss of best expert in hindsight

At  $t$ th day, for distribution  $x^{(t)} = (x_1^{(t)}, \dots, x_n^{(t)})$

- Loss of algorithm on day  $t = \sum_{i=1}^n x_i^{(t)} \cdot l_i^{(t)}$
- Total loss over  $T$  days =  $\sum_{t=1}^T \sum_{i=1}^n x_i^{(t)} \cdot l_i^{(t)}$
- $R_T = \sum_{t=1}^T \sum_{i=1}^n x_i^{(t)} \cdot l_i^{(t)} - \min_{1 \leq i \leq n} \sum_{t=1}^T l_i^{(t)}$
- Exists an algorithm s.t.  $\lim_{T \rightarrow \infty} R = \lim_{T \rightarrow \infty} \frac{R_T}{T} = 0$

**Key Idea:**

- Fix  $\epsilon$ ;  $\forall i, w_i^{(0)} = 1$
- For each expert, assign weight  $w_i^{(t)}$  (weight of expert  $i$  on day  $t$ )
- On day  $t$ ,  $\mathbb{P}[\text{pick } i] = x_i^{(t)} = \frac{w_i^{(t)}}{\sum_{i=1}^n w_i^{(t)}}$
- At end of day  $t$ , update weights via:  $w_i^{(t+1)} = w_i^{(t)} (1 - \epsilon)^{l_i^{(t)}}$

**Results:**

Last Resort	
<ul style="list-style-type: none"> <li>• Think DP (including change of states), Greedy, Graphs, DnC; on the fly trick</li> <li>• Check LPs; don't be tricked by the direction of inequalities</li> <li>• Is the question asking about dual or primal problem?</li> <li>• Huffman coding: inequality of leaf nodes does not matter</li> </ul>	<ul style="list-style-type: none"> <li>• After <math>T</math> days, regret <math>R_T \leq \epsilon T + \frac{\ln n}{\epsilon}</math></li> <li>• Average regret <math>R \in O\left(\sqrt{\frac{\ln n}{T}}\right)</math></li> </ul> <p><u>Variants and Corollaries:</u></p> <ul style="list-style-type: none"> <li>• Online algorithm</li> <li>• Constant # of variables per expert (decreasing <math>n</math> lowers memory)</li> <li>• # of timesteps affect runtime of algorithm</li> <li>• <math>\epsilon</math> affects calculations of weights</li> </ul> <p>If losses <math>\in [a, b]</math>, <math>R_T \leq (b - a) \left( \epsilon T + \frac{\ln n}{\epsilon} \right)</math></p>

# Appendix of Pseudo-codes and DP Recurrences

(for quick referencing)

All Pairs Shortest Path $O(n^3)$	Shortest Path in DAG $O(n + m)$
<p><math>d[i, j, k]</math> denotes length of shortest <math>i \rightarrow j</math> path where intermediate vertices are in <math>\{1, \dots, k\}</math></p> <ul style="list-style-type: none"> <li><math>d[i, j, 0] = w(i, j)</math></li> <li><math>d[i, j, k] = \min(d[i, j, k-1], d[i, k, k-1] + d[k, j, k-1])</math></li> </ul> <p>APSP(<math>G</math>):</p> <pre> for <math>(i, j) \in E</math>: <math>d[i, j, 0] \leftarrow w(i, j)</math> for <math>(i, j) \notin E</math>: <math>d[i, j, 0] \leftarrow \infty</math> for <math>k = 1, \dots, n</math>:   for <math>i = 1, \dots, n</math>:     for <math>j = 1, \dots, n</math>:       <math>d[i, j, k] \leftarrow \min(d[i, j, k-1], d[i, k, k-1] + d[k, j, k-1])</math> return <math>d</math> </pre>	<p><math>dp[i]</math> denotes length of shortest <math>s \rightarrow i</math> path</p> $dp[v] = \min_{u:(u,v) \in E} \{dp[u] + w(u, v)\}$ <p>SP_DAG(<math>G, s</math>):</p> <pre> <math>\forall u</math> <math>dp[u] \leftarrow \infty</math> <math>dp[s] \leftarrow 0</math> for <math>v \in G</math> in linearized order:   <math>dp[v] \leftarrow \min_{u:(u,v) \in E} \{dp[u] + w(u, v)\}</math> return <math>dp[t]</math> </pre>
Shortest Path Problem $O(k( V  +  E ))$	Travelling Salesman Problem $O(2^n \cdot n^2)$
<p>Given directed <math>G = (V, E)</math>, edge weights can be positive or negative, <math>s, t \in V</math>, integer <math>k</math>, output length of shortest path using at most <math>k</math> edges</p> $dp(v, i) = \min \left( \min_{u:(u,v) \in E} \{dp(u, i-1) + w(u, v)\}, dp(v, i-1) \right)$ <p>SHORTEST_K_PATH(<math>G, s, t, k</math>):</p> <pre> <math>dist[v, 0] \leftarrow \infty</math> <math>dist[s, 0] \leftarrow 0</math> for <math>i = 1, \dots, K</math>:   for <math>v \in V</math>:     <math>dist[v, i] \leftarrow \min \left( \min_{u:(u,v) \in E} \{dist(u, i-1) + w(u, v)\}, dist(v, i-1) \right)</math> return <math>dist[t, k]</math> </pre> <p>Remark: For shortest path, return <math>dist[t, n-1]</math></p>	<p>Problem: find shortest tour starting at 1 (i.e. visits every node exactly once and ends at 1)</p> <p>For <math>S</math> s.t. <math>i \in S</math>, denote <math>T[S, i]</math> as the length of shortest path that starts at 1, visits every node in subset <math>S</math>, ends at <math>i</math></p> $T[s, i] = \min_{j \in S \setminus \{i\}} \{T[S \setminus \{i\}, j] + d_{ij}\}$ <p>TSP(<math>G</math>):</p> <pre> <math>T[\{1\}, 1] \leftarrow 0</math> for <math>s = 2, \dots, n</math>:   for <math>S</math> s.t. <math> S  = s, 1 \in S</math>:     for <math>i \in S</math>:       <math>T[S, i] \leftarrow \min_{j \in S, j \neq i} \{T[S \setminus \{i\}, j] + d_{ij}\}</math> </pre>
Maximum Independent Set (Trees) $O( V  +  E )$	Horn SAT
<p>Find <math>S</math> s.t. for <math>u, v \in S, (u, v) \notin E</math></p> <p><math>I(v)</math> = size of largest independent set in <math>T_v</math> (the subtree rooted <math>v</math>)</p> $I(v) = \max \left\{ 1 + \sum_{w \in \text{grandchild}} I(w), \sum_{u \in \text{child}} I(u) \right\}$	<p>HORN_SAT(<math>X</math>):</p> <pre> <math>\forall i, x_i \leftarrow \text{False}</math> while <math>\exists</math> unsatisfied <math>(x_i \wedge \dots \wedge x_j) \Rightarrow x_k</math>:   <math>x_k \leftarrow \text{True}</math> if every <math>(\bar{x}_i \vee \dots \vee \bar{x}_j)</math> satisfied:   return <math>(x_1, \dots, x_n)</math> else return "not satisfiable" </pre>

Longest Increasing Subsequence $O( a ^2)$	Edit Distance $O( s  t )$
<p>Denote <math>L[j]</math> as the length of the longest LIS in <math>a_1, \dots, a_j</math> that ends in <math>a_j</math></p> $L[x] = 1 + \max_{i < x} \{L[i] : a_i < a_x\}$ <p>LIS(<math>a</math>):</p> <pre> for <math>x = 1, \dots, n</math>:   if <math>\exists i &lt; x</math> s.t. <math>a_i &lt; a_x</math>:     <math>L[x] \leftarrow 1 + \max_{i &lt; x} \{L[i] : a_i &lt; a_x\}</math>   else: <math>L[x] \leftarrow 1</math> return <math>\max_{x \in \{1, \dots, n\}} L[x]</math> </pre>	<p>Edits allowed: insert one character, delete one character, substitute one character</p> $E[i, j] = \text{edit distance of } s[1, \dots, i], t[1, \dots, j]$ $E[i, j] = \min \{1 + E(i-1, j), 1 + E(i, j-1), E(i-1, j-1) + \text{diff}(i, j)\}$ $\text{diff}(i, j) = \begin{cases} 0, & s[i] = t[j] \\ 1, & \text{otherwise} \end{cases}$ <p>EDIT_DISTANCE(<math>s, t</math>):</p> <pre> for <math>i = 0, \dots, m</math>: <math>E[i, 0] \leftarrow i</math> for <math>j = 0, \dots, n</math>: <math>E[0, j] \leftarrow j</math> for <math>i = 1, \dots, m</math>:   for <math>j = 1, \dots, n</math>:     <math>E[i, j] = \min \{E[i-1, j] + 1, E[i, j-1] + 1, E[i-1, j-1] + \text{diff}(i, j)\}</math> return <math>E[m, n]</math> </pre>
Knapsack with Replacement $O(nW)$	Knapsack without Replacement $O(nW)$
<p><math>K(C)</math> denote the maximum value that can be achieved with total weight <math>\leq C</math></p> $K(C) = \max_{i: w_i \leq C} \{v_i + K(C - w_i)\}$ <p>KNAPSACK(<math>W</math>):</p> <pre> <math>K(0) \leftarrow 0</math> for <math>C = 1, \dots, W</math>:   <math>K(C) \leftarrow \max_{i: w_i \leq C} \{v_i + K(C - w_i)\}</math> return <math>K(W)</math> </pre>	<p><math>K(C, j)</math> is the max value achievable with total weight <math>C</math> using items <math>1, \dots, j</math></p> $K(C, j) = \max \{v_j + K(C - w_j, j-1), K(C, j-1)\}$ <p>KNAPSACK(<math>W</math>):</p> <pre> <math>\forall j</math> <math>K(0, j) \leftarrow 0</math> <math>\forall i</math> <math>K(i, 0) \leftarrow 0</math> for <math>j = 1, \dots, n</math>:   for <math>C = 1, \dots, W</math>:     if <math>w_j &gt; C</math>: <math>K(C, j) \leftarrow K(C, j-1)</math>     else: <math>K(C, j) \leftarrow \max \{v_j + K(C - w_j, j-1), K(C, j-1)\}</math> return <math>K(W, n)</math> </pre>