

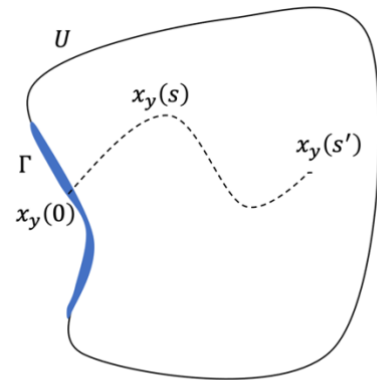
Method of Characteristics

General Form

- [Set Up] $U \subseteq \mathbb{R}^d$ open, $\partial U \in C^1$, $\Gamma \subseteq \partial U$, $F: U \times \mathbb{R} \times \mathbb{R}^d \rightarrow \mathbb{R}$, $u: U \rightarrow \mathbb{R}$
 - $x \in U \subseteq \mathbb{R}^d$, $u(x) \in \mathbb{R}$, $\nabla u = \begin{bmatrix} \partial_{x_1} u \\ \vdots \\ \partial_{x_d} u \end{bmatrix} \in \mathbb{R}^d$
 - $F(x, u(x), \nabla u(x)) = 0$ in U
 - $u = g$ on Γ
 - Idea: want to find $(\dot{x}(s), \dot{z}(s), \dot{p}(s)) = Q(x(s), z(s), p(s))$, so as to apply ODE
- [Procedure]
 - Write ODE for $x(s)$ and $z(s)$
 - $\forall y \in \Gamma$, find trajectory $x_y(s)$ and $z_y(s)$ such that:

Linear First-Order Scalar Equations

- $U \subseteq \mathbb{R}^d$, $a: U \rightarrow \mathbb{R}$, $b: U \rightarrow \mathbb{R}^d$, $\Gamma \subseteq \partial U$
 - $a(x)u + b(x) \cdot \nabla u - f(x) = 0$ in U
 - $u = g$ on Γ
- $x(s)$: path parametrized by s s.t. $x(0) \in \Gamma \subseteq \partial U$
- $z(s) = u(x(s))$: value function along the path $x(s)$
- $p(s) = (\nabla u)(x(s))$: gradient of value function evaluated at point $x(s)$
 - $p_j(s) = (\partial_{x_j} u)(x(s))$
 - $\dot{z} = (\nabla u)(x) \cdot \dot{x} = p \cdot \dot{x}$
- Choose $x(s)$ such that $\dot{x} = b(x)$
- Solve system of ODEs via x in terms of s first, then z in terms of s
 - Pick $y \in \Gamma$
 - $x_y(0) = y$, $z_y(0) = u(x_y(0)) = g(y)$
 - Invert $(s, y) \mapsto x_y(s) \in U$ to solve for $u(x) \forall x \in U$



$$z_y(s') = z_y(0) + \int_0^{s'} \left(\frac{d}{ds} z(s) \right) ds$$

Expanded	Compact
<ul style="list-style-type: none"> $\frac{d}{ds} x(s) = b(x(s))$ $\frac{d}{ds} z(s) = -a(x(s))z(s) + f(x(s))$ 	<ul style="list-style-type: none"> $\dot{x} = b(x)$ $\dot{z} = -a(x)z + f(x)$

- Examples:
 - [Transport / Advection] $\partial_t u + b(x) \cdot \nabla_x u = 0$

Quasilinear Equations

- Equations that are linear with respect to higher order derivatives.
 - $a(x, u)u + b(x, u) \cdot \nabla u = 0$ in U
 - $u = g$ on $\Gamma = \partial U$
- Choose $x(s)$ such that $\dot{x} = b(x, z)$

Expanded	Compact
<ul style="list-style-type: none"> $\frac{d}{ds} x(s) = b(x(s), z(s))$ $\frac{d}{ds} z(s) = -a(x(s), z(s))z(s)$ 	<ul style="list-style-type: none"> $\dot{x} = b(x, z)$ $\dot{z} = -a(x, z)z$

- Examples:
 - [Burger] $\partial_t u + u \partial_x u = 0$

Fully Nonlinear Scalar Equations

- $F(x, u(x), \nabla u(x)) = 0$ in U
- $u = g$ on Γ
- $\dot{p}_j(s) = \frac{d}{ds}(\partial_{x_j})(x(s)) = \sum_{k=1}^d (\partial_{x_j} \partial_{x_k} u)(x(s)) \dot{x}_k(s)$
- $0 = \partial_{x_j}(F(x, z, p)) = (\partial_{x_j} F)(x, z, p) + (\partial_z F)(x, z, p) p_j(s) + \sum_{k=1}^d (\partial_{p_k} F)(x, z, p) \partial_{x_j} \partial_{x_k} u(x(s))$
- Pick $x(s)$ s.t. $\dot{x}_k(s) = (\partial_{p_k} F)(x(s), z(s), p(s))$

Expanded	Compact
<ul style="list-style-type: none"> $\dot{x}_k(s) = (\partial_{p_k} F)(x(s), z(s), p(s))$ $\dot{p}_j(s) = -(\partial_{x_j} F)(x(s), z(s), p(s)) - p_j(s)(\partial_z F)(x(s), z(s), p(s))$ $\dot{z}(s) = \sum_{j=1}^d p_j (\partial_{p_j} F)(x(s), z(s), p(s))$ 	<ul style="list-style-type: none"> $\dot{x} = (\nabla_p F)(x, z, p)$ $\dot{z} = p \cdot (\nabla_p F)(x, z, p)$ $\dot{p} = -(\nabla_x F)(x, z, p) - p(\partial_z F)(x, z, p)$

- Pick $y \in \partial U$, then set $x_y(0) = y, z_y(0) = g(y)$
- $p_y(0)$ is the solution to:
 - $F(x_y(0), z_y(0), p_y(0)) = 0$
 - $\forall v$ tangent to Γ at $y, v \cdot p_y(0) = v \cdot \nabla g$

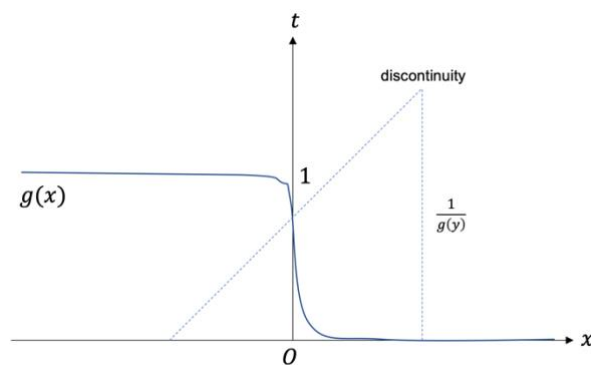
Scalar Conservation Law

- Let $u: t, x \rightarrow \mathbb{R}, f: t, x \rightarrow \mathbb{R}$
 - u : density, f : flux
 - [1D Conservation Law] $\partial_t u + \partial_x f = 0$
- [1D Scalar Conservation Law] $f: \mathbb{R} \rightarrow \mathbb{R}$, quasilinear PDE
 - $\partial_t u + f'(u) \partial_x u = 0$ in U
 - $u = g$ on Γ
- All characteristics are straight lines.
 - $x_y(s) = \begin{bmatrix} 1 \\ f'(g(y)) \end{bmatrix} s + \begin{bmatrix} 0 \\ y \end{bmatrix}$
 - $z_y(s) = g(y)$
 - $u(t, x) = g(y)$ for some y such that $x = t f'(g(y)) + y$

Singularity Formation

- [Bounded Integral Solution] A bounded and locally integrable function is a function $u: (0, \infty)_t \times \mathbb{R} \rightarrow \mathbb{R}$ is an integral solution if $\int_0^\infty \int_{\mathbb{R}_x} (u \partial_t \phi + f(u) \partial_x \phi) dx dt + \int_{\mathbb{R}_x} g(x) \phi(0, x) dx = 0 \forall \phi \in C_0^\infty(\mathbb{R}_t \times \mathbb{R}_x)$
 - If $u \in C^1([0, \infty) \times \mathbb{R})$ is bounded, then u is a classical solution and hence is a bounded integral solution.
- [Lemma] Let $f \in C^2(\mathbb{R})$ and $g \in C^1(\mathbb{R})$. Assume that $\exists x_0 \in \mathbb{R}$ s.t. $f''(g(x_0))g'(x_0) < 0$, then $\sup_{x \in \mathbb{R}} |\partial_x u(t, \cdot)| \rightarrow +\infty$ as $t \rightarrow T^-$ where $T = \frac{1}{f''(g(x_0))g'(x_0)}$
- [Shock Curve] The shock curve is a curve $\{(t, x) | x = \sigma(t)\}$ where the solution u is not continuous i.e. there is a jump discontinuity.
- [Rankine-Hugoniot] For a shock solution $u(t, x)$, the speed of the shockwave $\sigma'(t)$ is given by $\sigma'(t) = \frac{f(u_+(t)) - f(u_-(t))}{u_+(t) - u_-(t)}$
 - $u_+(t) = \lim_{x \rightarrow \sigma(t)^+} u(t, x)$

- $u_-(t) = \lim_{x \rightarrow \sigma(t)^-} u(t, x)$
- Characteristic lines crash into the shock curve from left and right
- Example: Burger's equation
 - $\partial_t u + u \partial_x u = 0$ in $U = (0, \infty)_t \times \mathbb{R}_x$
 - $f(u) = \frac{1}{2}u^2, f'(u) = u$
 - $u = g$ on $\Gamma = \{t = 0\} \times \mathbb{R}_x$
 - $x_y(s) = \begin{bmatrix} 1 \\ g(y) \end{bmatrix} s + \begin{bmatrix} 0 \\ y \end{bmatrix}$
 - $z_y(s) = g(y)$



Line of Attack**General Form**

- Method of characteristics
 - Any PDE of the form $F(x, u, \nabla u) = 0$
- Separation of Variables
 - Try a solution of the form $u(t, x) = T(t)X(x)$
 - Beware: this might not comprise all solutions
- Fourier Transform
 - Keep t , transform x
- See if variant of Heat / Wave / Laplacian
- Inverse of a distribution