

Classics

Classes	Solutions
Projection and Mechanics	
$\min_{\alpha \in \mathbb{R}} \ x - \alpha u\ _2^2$	$\alpha = \frac{x^T u}{\ u\ _2^2} = \frac{u^T x}{\ u\ _2^2}$
$\min_{x \in \mathbb{R}} \ v - x \mathbf{1}\ _2^2$	$x = \frac{1}{n} \sum_{i=1}^n v_i = \text{average}$
$\min_{x \in \mathbb{R}^m} \ X - x \mathbf{1}^T\ _F$	$x = \frac{1}{n} X \mathbf{1} = \text{column average}$
$\min_{x \in \mathbb{R}} \ v - x \mathbf{1}\ _1$	$x = \text{median}$
$\min_{w \in \mathbb{R}^m} L(A^T w) + \lambda \ w\ _2^2, A \in \mathbb{R}^{m \times n}, \lambda \geq 0$	$\min_{v \in \mathbb{R}^n} L(A^T A v) + \lambda \ A v\ _2^2$
Least Squares and Variants	
Ordinary Least Squares $A \in \mathbb{R}^{m \times n}, x \in \mathbb{R}^n, y \in \mathbb{R}^m$	
$\min_x \ Ax - y\ _2$	$x_{opt} = A^{pi} y + N(A)$ $x^* = A^{pi} y \in R(A^T) = N(A)^\perp$ (least norm) If A full column rank, solution is unique: $x^* = (A^T A)^{-1} A^T y, R x^* = Q^T y$
$\arg \min_{\beta} \sum_{i=1}^n (y_i - \beta x_i)^2$	$\left(\sum_{i=1}^n x_i^2 \right) \beta^* = \sum_{i=1}^n x_i y_i$
Linearly Constrained Least Squares / Perturbations to Feasibility $C \in \mathbb{R}^{p \times n}, d \in \mathbb{R}^p$	
$\min_x \ Ax - y\ _2^2 \text{ s.t. } Cx = d$	$x = C^{pi} d + Nz$ where columns of N form a basis for $N(C)$
$\arg \min_x \ x\ _2^2 \text{ s.t. } Ax = y$	$x = A^{pi} y$ provided $y \in R(A)$, else no solution exists
$\min_{\delta y} \ \delta y\ _2^2 \text{ s.t. } y + \delta y \in R(A)$	$\delta y = y - A A^{pi} y = (\mathbb{I} - A A^{pi}) y$
Weighted Least Square	
$\min_x \sum_{i=1}^m w_i^2 a_i^T x - y ^2$	$\min_x \ W(Ax - y)\ _2^2$ where $W = \text{diag}(w_1, \dots, w_m)$
$\min_x \ Ax - y\ _2^2 + x^T W x, W \succ 0$	$\min_x \left\ \begin{bmatrix} A \\ W^{1/2} \end{bmatrix} x - \begin{bmatrix} y \\ 0 \end{bmatrix} \right\ _2^2$ $x^* = (A^T A + W)^{-1} A^T y$
Regularized Least Squares / Ridge Regression	
$\min_x \ Ax - y\ _2^2 + \lambda^2 \ x - c\ _2^2, \lambda > 0$	$\min_x \left\ \begin{bmatrix} A \\ \lambda \mathbb{I} \end{bmatrix} x - \begin{bmatrix} y \\ \lambda c \end{bmatrix} \right\ _2^2$ always full column rank due to $\lambda \mathbb{I}$ $x^* = (A^T A + \lambda^2 \mathbb{I})^{-1} (A^T y + \lambda^2 c)$
$\arg \min_x \ Ax - b\ _2^2 + \ \Gamma x\ _2^2$	$\arg \min_x \left\ \begin{bmatrix} A \\ \Gamma \end{bmatrix} x - \begin{bmatrix} b \\ 0 \end{bmatrix} \right\ _2^2$ Assuming Γ full rank: $x^* = (A^T A + \Gamma^T \Gamma)^{-1} A^T b$
Kernel Least Squares / Kernel Trick	
$\min_w \ A^T w - y\ _2^2 + \lambda \ w\ _2^2$	$\min_v \ A^T A v - y\ _2^2 + \lambda \ A v\ _2^2$ i.e. optimal w lies in $R(A)$ If $n \gg m$, dramatic reduction in problem size $\min_v \left\ \begin{bmatrix} A^T A \\ \sqrt{\lambda} A \end{bmatrix} v - \begin{bmatrix} y \\ 0 \end{bmatrix} \right\ _2^2$ $v = (K^2 + \lambda K)^{-1} K y, K = A^T A, w = A v$

Variational Characterization of Eigenvalues / Rayleigh Quotient / Maximum Gain	
$\max_{x: \ x\ _2 \leq 1} \ Ax\ _2 = \max_{x: \ x\ _2 = 1} \frac{\ Ax\ _2}{\ x\ _2}$	$\sqrt{\lambda_{\max}(A^T A)}$
Maximum / Minimum Variance Direction $A = A^T \in \mathbb{S}^n$	
$\max_{x \neq 0} \frac{x^T A x}{x^T x} = \max_{\ x\ _2 \leq 1} x^T A x$ $\arg \max_{\ x\ _2 \leq 1} x^T A x$	$\lambda_1(A)$ u_1
$\min_{x \neq 0} \frac{x^T A x}{x^T x} = \min_{\ x\ _2 \leq 1} x^T A x$ $\arg \min_{\ x\ _2 \leq 1} x^T A x$	$\lambda_n(A)$ u_n
$\max_{\mathcal{V}: \dim \mathcal{V} = k} \min_{x \in \mathcal{V}} \frac{x^T A x}{x^T x}$ $\min_{\mathcal{V}: \dim \mathcal{V} = k} \max_{x \in \mathcal{V}} \frac{x^T A x}{x^T x}$	$\lambda_k(A)$ $\lambda_{n-k+1}(A)$
$\min_{X': \text{rank}(X') \leq 1} \ X - X'\ _F = \min_{u,v} \ X - uv^T\ _F$ $\min_{u \in \mathbb{R}^m: \ u\ _2 = 1} \sum_{i=1}^n \min_{\alpha_i \in \mathbb{R}} \ x_i - \alpha_i u\ _2^2$ $\max_{u \in \mathbb{R}^m: u^T u = 1} u^T C u, \quad C = \frac{1}{n} X X^T$	Assuming X is centered. $\alpha_i = x_i^T u$ $X' = u [\alpha_1 \quad \dots \quad \alpha_n]$ $\lambda_{\max}(C)$
$\min_{U \in \mathbb{R}^{n \times n}, U \neq 0} \frac{\text{tr}(U A U^T)}{\lambda_{\max}(U B U^T)}, A, B \succ 0$	$\lambda_{\min}(B^{-\frac{1}{2}} A B^{-\frac{1}{2}})$
$\min_{\lambda: \lambda \mathbb{I} - C \succeq 0} \lambda \mathbb{I} - C$	$\lambda = \lambda_{\max}(C)$
$\min_{x, y: \ x\ _2, \ y\ _2 \leq 1} x^T A y$	$-\sigma_{\max}(A)$
$\max_{x, y: \ x\ _2, \ y\ _2 \leq 1} x^T A y$	$\sigma_{\max}(A)$
Singular Value Decomposition $A \in \mathbb{R}^{m \times n}$	
$\arg \max_{v: \ v\ _2 \leq 1} \ A v\ _2$	v_1 $u_1 = \frac{A v_1}{\sigma_1}$
$\ A\ _2 = \max_{v: \ v\ _2 \leq 1} \ A v\ _2$	$\sigma_1(A) = \ A v_1\ _2$
$\min_{\substack{V \subset \mathbb{R}^n \\ \dim V = k}} \sum_{i=1}^m \ a_i - \Pi_V(a_i)\ _2^2$	$V = \text{Span}\{v_1, \dots, v_k\}$ $\sigma_{k+1}^2 + \dots + \sigma_r^2$
$\min_{x, y} \ A - x y^T\ _F$	$\sqrt{\sigma_2^2 + \dots + \sigma_r^2}$
Rank k Approximation / Distance to Rank Deficiency	
$\arg \min_{\substack{A_k \in \mathbb{R}^{m \times n} \\ \text{rank}(A_k) = k}} \ A - A_k\ _F$ $\min_{\substack{A_k \in \mathbb{R}^{m \times n} \\ \text{rank}(A_k) = k}} \ A - A_k\ _F$	$A_k = \sum_{i=1}^k \sigma_i u_i v_i^T$ $\sqrt{\sigma_{k+1}^2 + \dots + \sigma_r^2}$
$\min_{V_k \subset \mathbb{R}^m, \dim V_k = k} \sum_{a_i: i \text{th row of } A} \ a_i - \Pi_{V_k}(a_i)\ _2^2$	$\sqrt{\sigma_{k+1}^2 + \dots + \sigma_r^2}$
$\min_{L, R} \ X^c - L R^T\ _F, L \in \mathbb{R}^{m \times k}, R \in \mathbb{R}^{k \times n}$ $\min_{L, R} \ X^c - L R^T\ _F, L \in \mathbb{R}^{m \times k}, R \in \mathbb{R}^{k \times n}, R^T \mathbb{1} = 0$	R consists of the top k right singular vectors of the SVD of X^c . $\mathbb{1} \in N(X^c) \subset N(R^T)$
Linear Programming (LP)	

Unconstrained LP $A \in \mathbb{R}^{m \times n}, b \in \mathbb{R}^m, c \in \mathbb{R}^n$	
$\min_x c^T x \quad \text{s.t. } Ax \leq b$	$p^* = \begin{cases} 0, & c = 0 \\ -\infty, & c \neq 0 \end{cases}$
$\min_x c^T x + \lambda \ x\ _1 \quad \text{s.t. } Ax \leq b, \lambda > 0$	$\min_{x,u} c^T x + \lambda \sum_{i=1}^n u_i \quad \text{s.t. } Ax \leq b, u_i \geq x_i $
l_∞ Regression / Minimum Robust System $A \in \mathbb{R}^{m \times n}, b \in \mathbb{R}^m$	
$\min_x \ Ax - b\ _\infty$ $\min_x \max_{1 \leq i \leq m} a_i^T x - b_i $ $\min_{x,t} t \quad \text{s.t. } a_i^T x - b_i < t \quad \forall i$	$\min_{x,t} \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ t \end{bmatrix}$ subject to $\begin{bmatrix} A & -\mathbb{1} \\ -A & -\mathbb{1} \end{bmatrix} \begin{bmatrix} x \\ t \end{bmatrix} \leq \begin{bmatrix} b \\ -b \end{bmatrix}$
l_1 Regression $A \in \mathbb{R}^{m \times n}, b \in \mathbb{R}^m$	
$\min_x \ Ax - b\ _1 = \min_x \sum_{i=1}^m a_i^T x - b_i $ $\min_u \mathbb{1}^T u \quad \text{s.t. } a_i^T x - b_i < u_i \quad \forall i$	$\min_{x,u} \begin{bmatrix} 0 & \mathbb{1}^T \end{bmatrix} \begin{bmatrix} x \\ u \end{bmatrix}$ subject to $\begin{bmatrix} A & -\mathbb{I} \\ -A & -\mathbb{I} \end{bmatrix} \begin{bmatrix} x \\ u \end{bmatrix} \leq \begin{bmatrix} b \\ -b \end{bmatrix}$
Assignment Problem (M_{ij} = time for worker j to complete task i)	
$\min_{X \in \{0,1\}^{m \times n}} \text{tr}(X^T M) = \min_{X \in \{0,1\}^{m \times n}} \sum_{i,j} X_{ij} M_{ij}$ subject to $x\mathbb{1} = \mathbb{1}, x^T \mathbb{1} \leq \mathbb{1}$	$\min_{0 \leq X_{ij} \leq 1} \text{tr}(X^T M) = \min_{0 \leq X_{ij} \leq 1} \sum_{i,j} X_{ij} M_{ij}$ subject to $x\mathbb{1} = \mathbb{1}, x^T \mathbb{1} \leq \mathbb{1}$
Max Flow Problem	
$\max_{f,x} f$ subject to $Ax = [-f \quad 0 \quad \dots \quad 0 \quad f]^T$	<ul style="list-style-type: none"> Conservation of flow: $(Ax)_j = 0$ x_i: flow along link i $(Ax)_j$: net flow out of vertex j
Boolean Linear Program (Relaxation)	
$\min_x c^T x$ subject $Ax \leq b, x_i \in \{0,1\}$	$\min_x c^T x$ subject $Ax \leq b, x_i \in [0,1]$
Cardinality Minimization Trick (Relaxation)	
$\min_x \text{card}(x)$	<ul style="list-style-type: none"> Replace $\text{card}(x)$ with $\ x\ _1$ Replace $\ x\ _2$ with $\frac{\ x\ _1}{\sqrt{\text{card}(x)}}$ $\ x\ _1 \leq \ x\ _2 \sqrt{\text{card}(x)}$
Constraint Manipulation	
$u_i \geq x_i $	$u_i \geq -x_i, \quad u_i \geq x_i$
$\max_{i=1,\dots,m} a_i^T x - b_i \leq t$	$a_i^T x - b_i \leq t, \quad -a_i^T x + b_i \leq t$
Quadratic Programming (QP)	
Unconstrained QP	
$\min_x \frac{1}{2} x^T H x + c^T x \quad \text{s.t. } Ax \leq b, Cx = d$ $x \in \mathbb{R}^n, H \in \mathbb{S}$	<ul style="list-style-type: none"> $H \not\geq 0$ i.e. H has negative eigenvalues $p^* = -\infty$ $H \succ 0$ invertible $p^* = -\frac{1}{2} c^T H^{-1} c, \quad x^* = -H^{-1} c$ $H \succ 0$ not invertible, $c \in R(H)$ $p^* = -\frac{1}{2} c^T H^{pi} C, \quad x^* = -H^{pi} c + N(H)$ $H \succ 0$ not invertible, $c \notin R(H)$ $p^* = -\infty$
Least Squares	
$\min_x \ Ax - y\ _2^2$	$\min_x \frac{1}{2} x^T (2A^T A) x - 2y^T A x$

	$H = 2A^T A, c = -2A^T y$
QP with Equality Constraints	
$\min_x \frac{1}{2} x^T H x + c^T x \text{ s.t. } Ax = b$	$H' = N^T H N$ $c' = N^T c + N^T H^T x_0$
LASSO / l_1 Regularized Least Squares	
$\min_x \ Ax - y\ _2^2 + \lambda \ x\ _1$	$\min_{x,t} \ Ax - y\ _2^2 + \lambda \sum_{i=1}^n t_i \text{ s.t. } t \geq x, t \geq -x$
$\min_{x \in \mathbb{R}} \frac{1}{2} \ ax - y\ _2^2 + \lambda x $	$x^* = \begin{cases} 0, & a^T y \leq \lambda \\ \frac{a^T y}{\ a\ _2^2} - \frac{\lambda}{\ a\ _2^2} \text{sign}(a^T y), & a^T y > \lambda \end{cases}$
Cardinality Minimization Constraints (Relaxed)	
$\min_x \ Ax - y\ _2^2 \text{ s.t. } \text{card}(x) \leq k$	$\min_x \ Ax - y\ _2^2 \text{ s.t. } \ x\ _1 \leq k \ x\ _\infty$ $\min_x \ Ax - y\ _2^2 + \lambda \ x\ _1$
Piecewise Constant Function Fitting	
$D = \begin{bmatrix} -1 & 1 & 0 & 0 & \dots & 0 \\ 0 & -1 & 1 & 0 & \dots & 0 \\ 0 & 0 & -1 & 1 & \ddots & 0 \\ \vdots & \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & -1 & 1 \end{bmatrix}$ $\min_x \ x - y\ _2^2 \text{ s.t. } \text{card}(Dx) \leq k$	$\min_x \ x - y\ _2^2 + \lambda \ Dx\ _1$
Second-order Cone Programming (SOCP)	
$\min_x c^T x \text{ s.t. } \ A_i x + b_i\ _2 \leq c_i^T x + d_i, i = 1, \dots, m$	$A_i \in \mathbb{R}^{m_i \times n}, b_i \in \mathbb{R}^{m_i}, d_i \in \mathbb{R}, c \in \mathbb{R}^n, i = 1, \dots, m$
Reduction of QP	
$\min_x \frac{1}{2} x^T H x + c^T x \text{ s.t. } Ax \leq b$	$\min_{x,y} y + c^T x$ subject to $\frac{1}{2} x^T H x \leq y, Ax \leq b$
Quadratically Constrained QP (QCQP)	
$\min_x \frac{1}{2} x^T H x + c^T x \text{ s.t. } x^T Q_i x + a_i^T x \leq b_i$ $Q_i \in \mathbb{S}, Q_i \succeq 0 \text{ for } i = 1, \dots, m$	$\min_{x,u} u$ subject to $x^T Q_i x + a_i^T x \leq b_i, \frac{1}{2} x^T H x + c^T x \leq u$
Reciprocals	
$\min_x \sum_{i=1}^n h_i x_i + \frac{c_i}{x_i}$ subject to $0 \leq x$	$\min_{x>0} \sum_{i=1}^n h_i x_i + c_i y_i$ subject to $0 \leq x, \frac{1}{x_i} \leq y_i \Rightarrow 1 \leq x_i y_i$
Rational Powers	
$\min_w \ X^T w - y\ _2 + \lambda \sum_{i=1}^n w_i ^{\frac{3}{2}}$	$\min_{w,u,v,t} \ X^T w - y\ _2 + \lambda \sum_{i=1}^n t_i$ subject to $t \geq 0, u_i \geq w_i , v_i t_i \geq u_i^2, u_i \geq v_i^2$
Facility Locations	
$\min_x \sum_{i=1}^n \ A_i x - y_i\ _2$	$\min_{x,t} \sum_{i=1}^n t_i$ subject to $\ A_i x - y_i\ _2 \leq t_i \text{ for } i = 1, \dots, m$
$\min_x \max_i \ x - y_i\ _2$	$\min_{x,t} t$ subject to $\ A_i x - y_i\ _2 \leq t_i \text{ for } i = 1, \dots, m$

$\min_x \sum_{i=1}^m \ A_i x - b_i\ _2 + \lambda \ x\ _1 + \mu \ x\ _\infty$	$\min_{x,y,u,t} \sum_{i=1}^m y_i + \lambda \sum_{i=1}^n u_i + \mu t$ subject to $\ A_i x - b_i\ _2 \leq y_i, x_i \leq u_i, x_i \leq t$
Constraint Manipulation	
$Cx \leq r$	$A_i = 0, b_i = 0, c_i = -(\text{ith row of } C), d_i = r_i$
$x^T Q x + c^T x \leq t$ $Q \succcurlyeq 0$	$\left\ \begin{bmatrix} \sqrt{2} Q^{\frac{1}{2}} \\ -c^T \end{bmatrix} x + \begin{bmatrix} 0 \\ t - \frac{1}{2} \end{bmatrix} \right\ _2 \leq t - c^T x + \frac{1}{2}$
$\ R x\ _2^2 \leq r^T x$	$\left\ \begin{bmatrix} \sqrt{2} R \\ r^T \end{bmatrix} x - \begin{bmatrix} 0 \\ 1 \\ \frac{1}{2} \end{bmatrix} \right\ _2 \leq r^T x + \frac{1}{2}$
$\ x\ _2^2 \leq 2yz$	$\left\ \begin{bmatrix} x \\ \frac{1}{\sqrt{2}}(y-z) \end{bmatrix} \right\ _2 \leq \frac{1}{\sqrt{2}}(y+z)$
$1 \leq x_i y_i$	$\left\ \begin{bmatrix} 2 \\ y_i - x_i \end{bmatrix} \right\ _2 \leq x_i + y_i$
$\frac{3}{u^2} \leq t$	$vt \geq u^2, u \geq v^2$
$\ x - x_0\ _2 \leq \alpha$	$\ [\mathbb{I}][x] - x_0\ _2 \leq \alpha$
$\ x - y\ _2 \leq \alpha$	$\left\ \begin{bmatrix} \mathbb{I} & -\mathbb{I} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \right\ _2 \leq \alpha$
Robust Linear Programming (LP)	
$\min_x c^T x$	subject to $\forall a_i \in \mathcal{U}, a_i^T x \leq b_i$ for $i = 1, \dots, m$
Scenario Uncertainty Model (\mathcal{U} finite set)	
$\mathcal{U}_i = \{a_i^{(1)}, \dots, a_i^{(K)}\}$ $\forall a_i \in \mathcal{U}_i, a_i^T x \leq b_i$	$\min_x c^T x$ subject to $(a_i^{(j)})^T x \leq b_i$ for $i = 1, \dots, m$
Box Uncertainty Model (LP)	
$\mathcal{U} = \bigcup_{i=1}^m \mathcal{U}_i$ $\mathcal{U}_i = \{a : \ a - \hat{a}_i\ _\infty \leq \rho\}$	$\max_{a \in \mathcal{U}} a^T x \leq b$ $\max_{a \in \mathcal{U}} a^T x = \hat{a}^T x + \max_{\ y\ _\infty \leq \rho} y^T x = \hat{a}^T x + \rho \ x\ _1$ $\hat{a}^T x + \rho \ x\ _1 \leq b$ (LP constraint)
$\min_x c^T x$ subject to $\forall a_i \in \mathcal{U}_i, a_i^T x \leq b_i, i = 1, \dots, m$	$\min_x c^T x$ subject to $\hat{a}_i^T x + \rho \ x\ _1 \leq b_i, i = 1, \dots, m$
Ellipse Uncertainty Model (SOCP)	
$\mathcal{U} = \{a : (a - a_0)^T P^{-1} (a - a_0) \leq 1\}, P \succ 0$ $\mathcal{U} = \{a = \hat{a} + Ru : \ u\ _2 \leq 1\}$ where $P = RR^T, u = R^{-1}(a - a_0)$	$\max_{a \in \mathcal{U}} a^T x \leq b$ $\max_{a \in \mathcal{U}} a^T x = \hat{a}^T x + \max_{u: \ u\ _2 \leq 1} u^T R^T x$ $\leq \hat{a}^T x + \ R^T x\ _2$
$\min_x c^T x$ subject to $\forall a_i \in \mathcal{U}_i, a_i^T x \leq b_i, i = 1, \dots, m$	$\min_x c^T x$ subject to $\hat{a}_i^T x + \ R_i^T x\ _2 \leq b_i, i = 1, \dots, m$
Robust Optimization	
$\min_x f_0(x)$ subject to $f_i(x) \leq 0$ for $i = 1, \dots, m$	$\min_x \max_u F_0(x, u)$ subject to $F_i(x, u) \leq 0 \forall u \in \mathcal{U}$ for $i = 1, \dots, m$
Robust Least Squares (SOCP)	
$\min_x \max_{\ \Delta\ _2 \leq \rho} \ (\hat{A} + \Delta)x - y\ _2$	$\Delta = \frac{\rho(\hat{A}x - y)x^T}{\ \hat{A}x - y\ _2 \ x\ _2}$ (rank 1 matrix) $\min_x \ \hat{A}x - y\ _2 + \rho \ x\ _2$ (SOCP)

Vocabulary	
Regression	Measure of relation between one variable and another.
Regularized	Already have a target in mind; want a solution close to the target.
Sparsity	As few nonzero elements as possible; see LASSO.
Robust	A solution that accounts for the uncertainty; ambiguity or error exists in data
Weighted	Just introduce weights; usually no change in problem type
Underdetermined	$m \leq n$, full row rank, AA^T invertible, $N(A^T) = \{0\}$, rows of A linearly independent
Overdetermined	$n \leq m$, full column rank, $A^T A$ invertible, $N(A) = \{0\}$, columns of A linearly independent

Identification	
Least Squares	Slogan: <i>squared l_2 norm + linear inequality constraints</i>
LP	l_1 norm/regression, l_∞ norm/regression, box uncertainty, resource management, max flow
QP	Energy, variance, error (squared), index tracking), l_1 regularized least squares (sparsity, piecewise fitting)
SOCP	Ellipsoid uncertainty, inverses, rational power, distance (no square), route planning, sum of norms, general robust optimization

Theory

QR Decomposition $A = QR$	Pseudo-inverse A^{pi} and Square Roots \sqrt{A}												
<ul style="list-style-type: none"> Standard QR (for full column rank A) $A = QR$ $A \in \mathbb{R}^{m \times n}$ full column rank $Q \in \mathbb{R}^{m \times n}$ columns orthogonal (i.e. $Q^T Q = \mathbb{I}_n$) and forms an orthogonal basis in $R(A)$ $R \in \mathbb{R}^{n \times n}$ upper triangular, square, invertible. <table border="1"> <tr> <td>$A = QR$</td><td>$R(A) = R(Q)$</td></tr> <tr> <td>$QQ^T y = \Pi_{R(A)}(y)$</td><td>$A^{pi} = R^{-1}Q^T$</td></tr> </table> <ul style="list-style-type: none"> Full QR (for full column rank A) $A = QR = [Q_1 \ Q_2] \begin{bmatrix} R_1 \\ 0 \end{bmatrix}$ $A \in \mathbb{R}^{m \times n}$ full column rank $Q \in \mathbb{R}^{m \times m}$ orthogonal matrix; Q_1 forms orthonormal basis for $R(A)$, Q_2 forms orthonormal basis for $R(A)^\perp = N(A^T)$ $R \in \mathbb{R}^{m \times n}$ with $R_1 = \mathbb{R}^{n \times n}$ upper-triangular and invertible. <p>In $\ Ax - b\ _2$, $\ Q_2^T b\ _2$ corresponds to distance between b and orthogonal projection to $R(A)$.</p> <ul style="list-style-type: none"> Not full column rank A $AP = QR = Q[R_1 \ R_2]$ $R = [R_1 \ R_2]P^T$ $Q \in \mathbb{R}^{m \times r}$ is has orthogonal columns ($Q^T Q = \mathbb{I}_r$) $R_1 \in \mathbb{R}^{r \times r}$ is upper-triangular, square, invertible $R_2 \in \mathbb{R}^{r \times (n-r)}$ $P \in \mathbb{R}^{n \times n}$ permutation matrix Full QR Decomposition $AP = QR = [Q_1 \ Q_2] \begin{bmatrix} R_1 & R_2 \\ 0 & 0 \end{bmatrix}$ $Q \in \mathbb{R}^{m \times m}$ orthogonal, square $Q^T Q = QQ^T = \mathbb{I}_m$ $R_1 \in \mathbb{R}^{r \times r}$ upper triangular and invertible $P \in \mathbb{R}^{n \times n}$ permutation matrix. 	$A = QR$	$R(A) = R(Q)$	$QQ^T y = \Pi_{R(A)}(y)$	$A^{pi} = R^{-1}Q^T$	<p>Moore-Penrose Pseudo-inverse $A^{pi} \in \mathbb{R}^{n \times m}$</p> <table border="1"> <tr> <td>$AA^{pi}A = A$</td><td>$\Pi_{N(A)^\perp} = A^{pi}A$</td></tr> <tr> <td>$A^{pi}AA^{pi} = A^{pi}$</td><td>$\Pi_{N(A)} = I - A^{pi}A$</td></tr> <tr> <td>$(AA^{pi})^{pi} = AA^{pi}$</td><td>$\Pi_{R(A)} = AA^{pi}$</td></tr> <tr> <td>$(A^{pi}A)^{pi} = A^{pi}A$</td><td>$\Pi_{R(A)^\perp} = I - AA^{pi}$</td></tr> </table> <p>Such a matrix always exists and is unique</p> <ul style="list-style-type: none"> A full column rank $A^{pi} = (A^T A)^{-1} A^T$ A full row rank $A^{pi} = A^T (AA^T)^{-1}$ A invertible $A^{pi} = A^{-1}$ A general $A^{pi} = V \Sigma^{pi} U^T = V_r \tilde{\Sigma}^{-1} U_r^T$ $\Sigma^{pi} = \begin{bmatrix} \sigma_1^{-1} & & \\ & \ddots & \\ & & \sigma_r^{-1} \end{bmatrix}$ <ul style="list-style-type: none"> A positive definite $\Rightarrow \sqrt{A}$ also positive definite 	$AA^{pi}A = A$	$\Pi_{N(A)^\perp} = A^{pi}A$	$A^{pi}AA^{pi} = A^{pi}$	$\Pi_{N(A)} = I - A^{pi}A$	$(AA^{pi})^{pi} = AA^{pi}$	$\Pi_{R(A)} = AA^{pi}$	$(A^{pi}A)^{pi} = A^{pi}A$	$\Pi_{R(A)^\perp} = I - AA^{pi}$
$A = QR$	$R(A) = R(Q)$												
$QQ^T y = \Pi_{R(A)}(y)$	$A^{pi} = R^{-1}Q^T$												
$AA^{pi}A = A$	$\Pi_{N(A)^\perp} = A^{pi}A$												
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$(A^{pi}A)^{pi} = A^{pi}A$	$\Pi_{R(A)^\perp} = I - AA^{pi}$												
Singular Value Decomposition $A \in \mathbb{R}^{m \times n}$	Dual Norms and Matrix Norms												
$A = \sum_{i=1}^r \sigma_i u_i v_i^T = U \Sigma V^T = U_r \tilde{\Sigma} V_r^T, \Sigma := \begin{bmatrix} \tilde{\Sigma} & 0 \\ 0 & 0 \end{bmatrix}$ $r \leq \min(n, m) \quad \tilde{\Sigma} = \text{diag}(\sigma_1, \dots, \sigma_r), \quad \sigma_1 \geq \dots \geq \sigma_r > 0$ <ul style="list-style-type: none"> $Av_i = \sigma_i u_i; A^T u_i = \sigma_i v_i; u_i^T A = \sigma_i v_i^T$ r is the rank of $A, A^T, A^T A$ and AA^T $\sigma_1^2, \dots, \sigma_r^2$ are eigenvalues of AA^T and $A^T A$ u_1, \dots, u_r are the eigenvectors for AA^T v_1, \dots, v_r are the eigenvectors for $A^T A$ $\{u_1, \dots, u_r\}$: an orthonormal basis of $R(A)$ 	<p>Dual norm $\ \cdot\ ^*: \mathbb{R}^n \rightarrow \mathbb{R}$:</p> $\ y\ ^* := \max_{x: \ x\ \leq 1} y^T x \equiv \max_{x: \ x\ \leq 1} y^T x $ <p>Operator norm:</p> $\ f\ _{op} := \max_{x: \ x\ \leq 1} f(x), \quad f \in \mathcal{X}^*$ <p>Condition number $\kappa(A) = \frac{\sigma_1}{\sigma_n} = \frac{\sigma_{\max}}{\sigma_{\min}}$</p> <p>If A is square, $\kappa(A) = \ A\ _{LSV} \ A^{-1}\ _{LSV}$ If A is unitary, $\kappa(A) = 1$</p> <p>Induced p-norms (measure of stretch):</p> $\ A\ _p := \max_{x: \ x\ _p \leq 1} \ Ax\ _p = \max_{x: \ x\ _p \neq 0} \frac{\ Ax\ _p}{\ x\ _p}$ <ul style="list-style-type: none"> $\ A\ _1 = \max_{1 \leq i \leq n} \ a_i\ _1$ (max l_1 norm of columns) $\ A\ _2 = \sqrt{\lambda_{\max}(A^T A)}$ $\ A\ _\infty = \max_{1 \leq i \leq m} \ a_i^T\ _1$ (max l_1 norm of rows) $\ A\ _F = \sqrt{\text{tr}(A^T A)} = \sqrt{\sum_{i=1}^n \lambda_i(A^T A)}$ <p>Matrix norms are sub-multiplicative:</p> $\ AB\ _p \leq \ A\ _p \ B\ _p$												
Empirical Covariance Matrix													
	$\Sigma = \mathbb{E}[(X - \mathbb{E}[X])(X - \mathbb{E}[X])^T] = \frac{1}{n} \sum_{i=1}^n (x_i - \hat{x})(x_i - \hat{x})^T$ $\Sigma = \frac{1}{n} X^C (X^C)^T = \frac{1}{n} \sum_{i=1}^n x_i x_i^T$												

- $\{u_{r+1}, \dots, u_m\}$: an orthonormal basis of $N(A^T)$
- $\{v_1, \dots, v_r\}$: an orthonormal basis of $R(A^T)$
- $\{v_{r+1}, \dots, v_n\}$: an orthonormal basis of $N(A)$

Full column rank, $r = n$, so $A = U \begin{bmatrix} \Sigma \\ 0 \end{bmatrix} V^T$

Full row rank matrices, $r = m$, $A = U[\Sigma \ 0]V^T$

$Px = q$ unique solution if Σ full column rank

- Symmetric, positive semi-definite
- Total variance: $\text{tr}(\Sigma) = \frac{1}{n} \|X^C\|_F^2$
- k th order explained variance = $\frac{\sigma_1^2 + \dots + \sigma_k^2}{\sigma_1^2 + \dots + \sigma_n^2}$
- Mean along vector u
 $\hat{z} = u^T \hat{x}$
- Variance along vector u
 $\sigma^2(u) = \frac{1}{m} \sum_{k=1}^m (u^T (x_k - \hat{x}))^2 = u^T \Sigma u$
- u_1 (the first eigenvector of $X^C (X^C)^T$) maximizes the variance.

Principle Component Analysis

Algorithm

- Center data matrix $X \rightarrow X^C$
- Project onto a well-chosen direction $u_1 \in \mathbb{R}^n$ with $\|u\|_2 = 1$ that minimizes the component of data not explained by u_1
$$u_1 = \arg \min_{u_1: \|u_1\|_2 \leq 1} \sum_{i=1}^m \|(u_1^T \hat{x}_i)u_1 - \hat{x}_i\|_2^2$$

$$= \arg \max_{u_1: \|u_1\|_2 \leq 1} u_1^T \left(\frac{1}{m} X^C (X^C)^T \right) u_1 = v_{\max}(\Sigma)$$
- Subtract the component of X^C explained by u_1 and repeat the algorithm.
- u_1 is the direction of maximum variance, also called the principle component vector

Mechanics $X \in \mathbb{R}^{m \times n}$

- Column average: $\hat{x} = \frac{1}{n} X \mathbf{1}$
- Centering matrix: $P = I - \frac{1}{n} \mathbf{1} \mathbf{1}^T$
 $XP = X^C = X - \hat{x} \mathbf{1}^T$
 $P \mathbf{1} = 0$
- For a centered matrix X^C : $X^C \mathbf{1} = 0$
$$\frac{1}{2} \sum_{1 \leq i, j \leq n} \|x_i - x_j\|_2^2 = n \text{tr}(XPX^T)$$

Polyhedral

Definition: A function is polyhedral if its epigraph is polyhedral i.e. if and only if $\exists C \in \mathbb{R}^{m \times (n+1)}, d \in \mathbb{R}^m$ s.t.

$$\begin{aligned} \text{epi } f &= \{(x, t) \in \mathbb{R}^{n+1}: t \geq f(x)\} \\ &= \{(x, t) \in \mathbb{R}^{n+1}: C \begin{bmatrix} x \\ t \end{bmatrix} \leq d\} \end{aligned}$$

[Max affine functions] Functions expressible as the max of a finite number of affine functions is polyhedral $f(x) = \max_{1 \leq i \leq m} a_i^T x + b_i$

Consequence: l_∞ norm is polyhedral.

Functions expressible as the sum of functions that are max affine functions are polyhedral.

Consequence: l_1 norm is polyhedral.

The projection of polyhedral is polyhedral.

Properties of Norms and Traces

Norms

- $|x^T y| \leq \|x\|_p \|y\|_q, \frac{1}{p} + \frac{1}{q} = 1$
- $\frac{1}{\sqrt{n}} \|x\|_2 \leq \|x\|_\infty \leq \|x\|_2 \leq \|x\|_1 \leq \sqrt{n} \|x\|_2 \leq n \|x\|_\infty$
- For $x \neq 0$, $\text{card}(x) \geq \frac{\|x\|_1^2}{\|x\|_2^2}$
- $\|A\|_F^2 = \text{tr}(A^T A) = \sum_{i=1}^r \sigma_i^2$
- $\|A + B\|_F^2 = \|A\|_F^2 + \|B\|_F^2 + 2 \text{tr}(A^T B)$

Traces

- $\text{tr}(A)^2 \leq \text{rank}(A) \|A\|_F^2$
- $\text{tr}(AB) \leq \|A\|_F \|B\|_F$
- $\text{tr}(u^T u) = \|u\|_F^2 = \|u\|_2^2$
- $\text{tr}(AB) = \text{tr}(BA)$
- $\text{tr}(ba^T) = a^T b$
- $\text{tr}(ABCD) = \text{tr}(BCDA) = \text{tr}(CDAB) = \text{tr}(DABC)$
- $\|AB\|_p \leq \|A\|_p \|B\|_p$
- $\|A\|_p := \max_{x: \|x\|_p \leq 1} \|Ax\|_p = \max_{x: \|x\| \neq 0} \frac{\|Ax\|_p}{\|x\|_p}$
- $\|x\|_2^2 = \|Ux\|_2^2$ for U orthogonal
- $x^T Q x = \text{tr}(x^T Q x) = \text{tr}(x x^T Q)$

Problem Solving Techniques

- Take derivatives!
- Fix a few variables, minimize w.r.t. the rest.
- Reduce to classic problems/formulations
- Group terms and simplify
- Geometry argument / Decomposition

Final Checks

- Sign constraints? $x \geq 0$
- Standard form
- Check symmetric property for positive semi-definite

Appendix I: Mathematical Toolbox

Linear algebra, multivariable calculus tricks and techniques

Linear Algebra	Multivariable Calculus
<div> $\begin{array}{ c c } \hline (\text{rank}(A))^\perp = \text{null}(A^T) & (\text{null}(A))^\perp = \text{rank}(A^T) \\ \hline (\text{rank}(A^T))^\perp = \text{null}(A) & (\text{null}(A^T))^\perp = \text{rank}(A) \\ \hline \end{array}$ $S \subset T \Rightarrow T^\perp \subset S^\perp$ </div> <p>Projection</p> <ul style="list-style-type: none"> Let $\{u_1, \dots, u_n\}$ be an orthonormal basis for V. Then $P = \sum u_i u_i^T$ is the matrix of orthogonal projection. If A is a matrix with its column as any basis of V, then $P = A(A^T A)^{-1} A^T$ is the matrix of orthogonal projection. <p>Decompositions</p> <ul style="list-style-type: none"> [Spectral] Any symmetric matrix has exactly n real (not necessarily distinct) eigenvalues; and eigenvectors can be chosen to be orthonormal. $A = U \Lambda U^T = \sum_i \lambda_i u_i u_i^T$ [Cholesky] If A is symmetric positive definite, then $A = LL^T$ where L is lower triangular with real and positive diagonal entries (i.e. L invertible) A symmetric positive definite \Rightarrow every eigenvalue is positive (similar for semi) A positive definite, then $B^T A B$ also positive definite (similar for semi) A positive definite, then exists unique positive definite \sqrt{A}. (similar for semi) $\sqrt{A} = U \sqrt{\Lambda} U^T$ [Inertia Theorem] A symmetric matrix is congruent to a diagonal matrix with 0, 1, -1 under $A = B \Lambda B^T$. [Sylvester's Rule of Inertia] Negative index of inertia q = the number of sign changes of the leading minors $\Delta_0 = 1, \dots, \Delta_n = \det A$ [Schur Complement] Let S be a symmetric matrix partitioned into blocks $S = \begin{bmatrix} A & B \\ B^T & C \end{bmatrix}$ with C positive definite. TFAE: <ul style="list-style-type: none"> S is positive semi-definite. $A - B C^{-1} B^T$ (Schur's complement of C) is positive semi-definite 	<p>Determinants</p> $\det(I + uv^T) = 1 + u^T v$ $\det(I_2 + A) = 1 + \det A + \text{tr}(A)$ $\det(I + \epsilon A) \approx 1 + \det(A) + \epsilon \text{tr}(A) + \frac{1}{2} \epsilon^2 \text{tr}(A)^2 - \frac{1}{2} \epsilon \text{tr}(A^2)$ <p>Approximations</p> $f(x) \approx f(x_0) + \nabla f(x_0)^T (x - x_0)$ $f(x) \approx q(x) = f(x_0) + \nabla f(x_0)^T (x - x_0) + \frac{1}{2} (x - x_0)^T \nabla^2 f(x_0) (x - x_0)$ <p>Derivatives</p> $\nabla(a^T x + b) = a \quad \nabla(x^T x) = 2x$ $\nabla_x \ X - P\ _F^2 = 2(X - P)$ $\nabla^2 \left(\frac{1}{2} x^T A x \right) = \frac{1}{2} (A + A^T)$ $g(x) = f(Ax + b) \Rightarrow \nabla g(x) = A^T \nabla f(Ax + b)$ $q(x) = \frac{1}{2} \begin{bmatrix} x & 1 \end{bmatrix} \begin{bmatrix} A & b \\ b^T & c \end{bmatrix} \begin{bmatrix} x \\ 1 \end{bmatrix} = \frac{1}{2} x^T A x + b^T x + c$ $\nabla q = Ax + b$ $\nabla^2 q = A$ $\nabla_x \text{tr}(X H X^T) = X H^T + X H$ $\nabla_x \text{tr}(A X) = A^T$ $H_q = \begin{bmatrix} \frac{\partial^2 q}{\partial x_1^2} & \frac{\partial^2 q}{\partial x_1 \partial x_2} \\ \frac{\partial^2 q}{\partial x_2 \partial x_1} & \frac{\partial^2 q}{\partial x_2^2} \end{bmatrix}$ <p>Inequalities</p> <ul style="list-style-type: none"> <u>Cauchy Schwarz / Holder's</u> $p^{-1} + q^{-1} = 1$: $x^T y \leq \ x\ _p \ y\ _q \Rightarrow \max_{y: \ y\ _p \leq 1} y^T x = \ x\ _q$ <p>Equality when $y_i = \frac{\text{sign}(x_i) x_i ^{p-1}}{\ x\ _q}$</p> <ul style="list-style-type: none"> <u>Power Mean Inequality</u> $p \geq q \Rightarrow n^{-\frac{1}{p}} \ x\ _p \geq n^{-\frac{1}{q}} \ x\ _q$ <u>Smoothing</u> <u>Sherman-Morrison-Woodbury</u> $A \in \mathbb{R}^{n \times n}, u, v \in \mathbb{R}^n$ s.t. $A, A + uv^T$ non-singular $(A + uv^T)^{-1} = A^{-1} - \frac{A^{-1} u v^T A^{-1}}{1 + v^T A^{-1} u}$ <u>Minkowski's Inequality</u> $1 \leq p < \infty$ $\ f + g\ _p \leq \ f\ _p + \ g\ _p$

Appendix II: Diagrams

