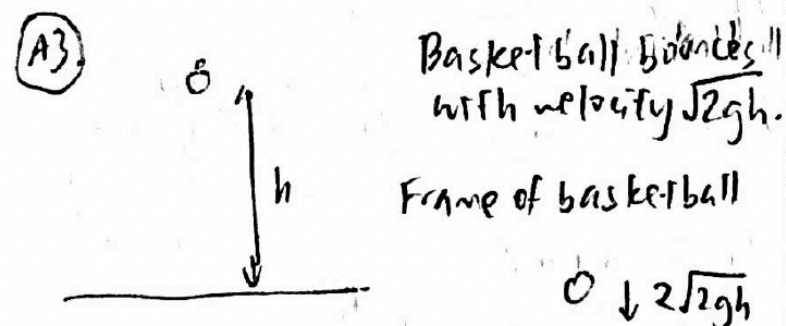


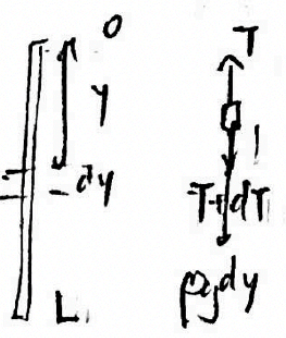
A1) $F(t) = ma_0 e^{-bt}$
 $\Rightarrow m\ddot{x} = ma_0 e^{-bt}$
 $\Rightarrow \ddot{x} = a_0 e^{-bt}$
 $\dot{x} = \int \ddot{x} dt = \frac{a_0}{-b} e^{-bt} + c$
 $\dot{x}(0) = 0 \Rightarrow c = \frac{a_0}{b}$
 $x = \int \dot{x} dt = \frac{a_0}{b^2} e^{-bt} + \frac{a_0}{b} t + c'$
 $x(0) = 0 \Rightarrow c' = -\frac{a_0}{b^2}$

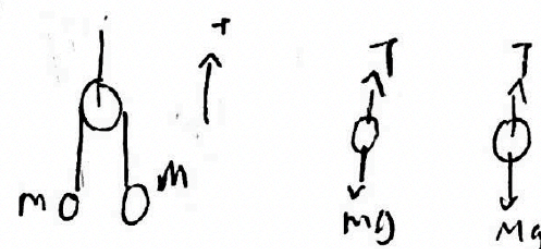
$$\therefore x(t) = \frac{a_0}{b^2} [e^{-bt} - 1 + bt]$$

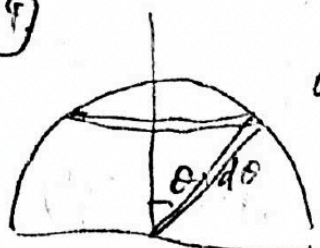


\Rightarrow Tennis ball bounces with $4\sqrt{2gh}$ in frame of basketball

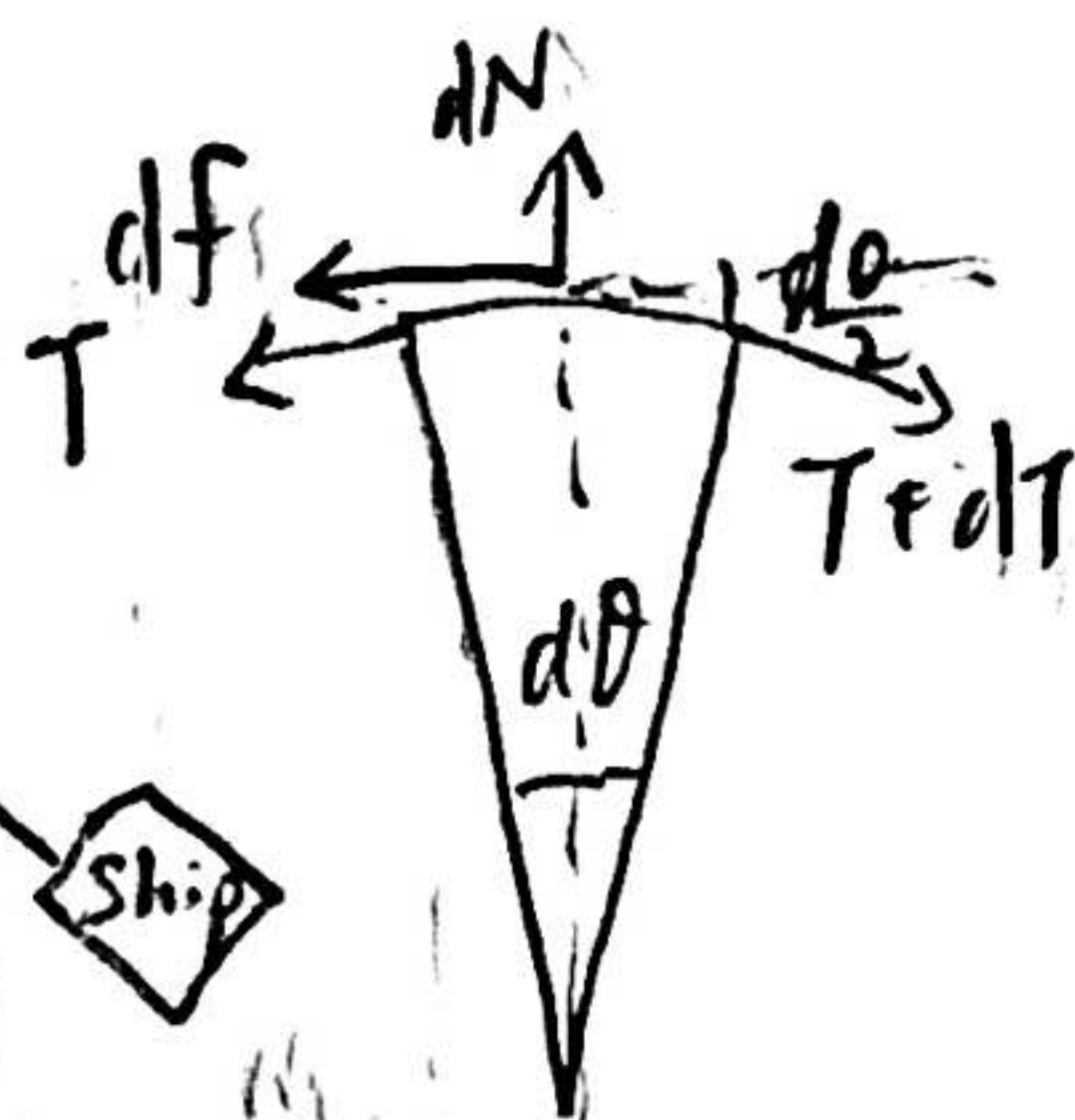
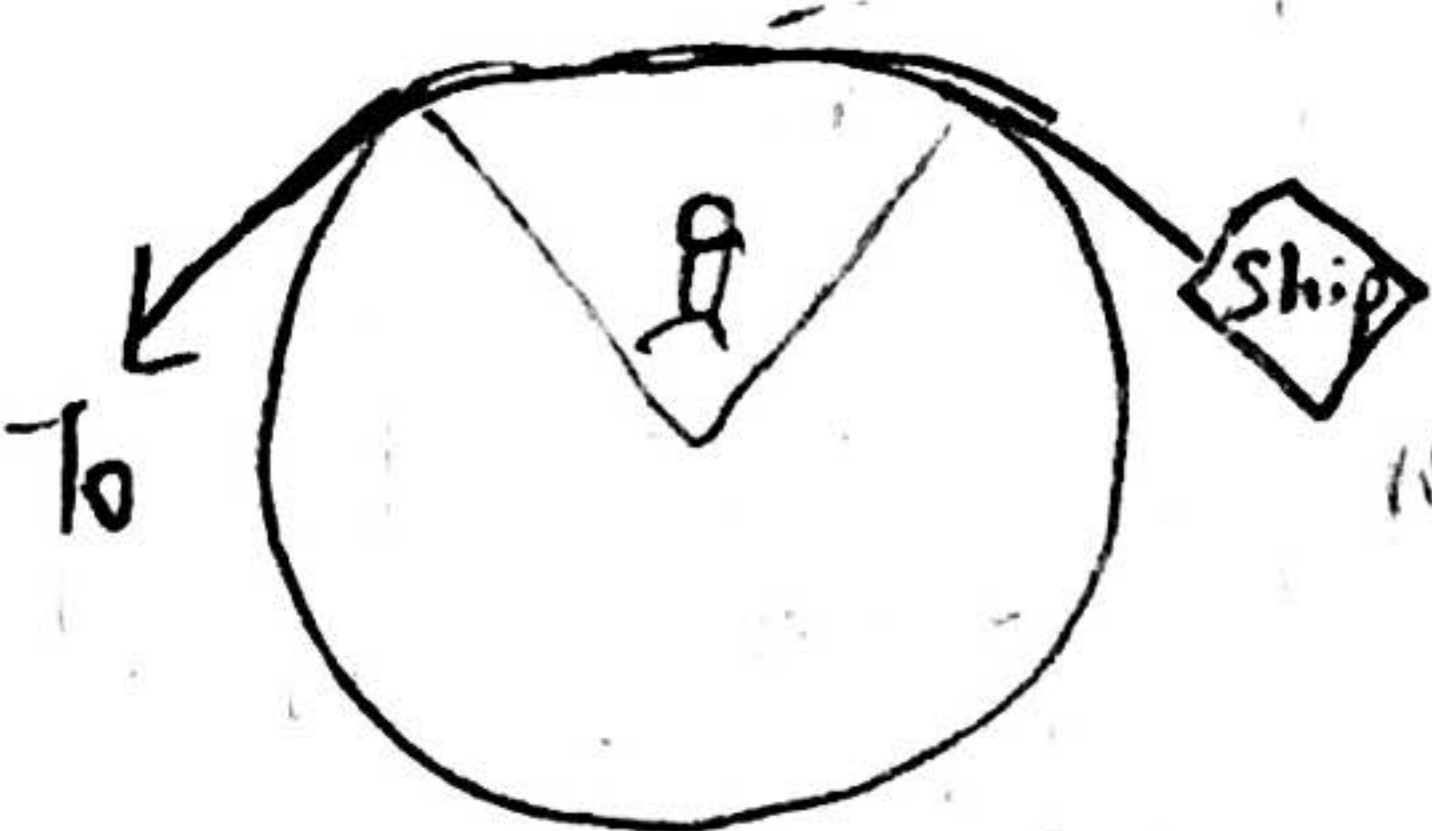
$$\Rightarrow \boxed{3\sqrt{2gh}}$$

A5)  $T + dT + p g dy = T$
 $\Rightarrow dT = -p g dy$
 $\Rightarrow T = -p g y + c$
 when $y = L$, $T = 0 \Rightarrow \boxed{T(h) = p g (h - L)}$

A2) 
 $ma_1 = T - mg$
 $Ma_2 = T - Mg$
 $a_1 = -a_2$ (conservation of string)
 $\Rightarrow \frac{T - mg}{m} = -\frac{T - Mg}{M}$
 $\Rightarrow T = \frac{2mM}{m+M} g$
 $a_1 = \frac{(m-M)g}{M+m}$ $a_2 = \frac{(M-m)g}{M+m}$
 $F = 2T = \boxed{\frac{4mM}{m+M} g}$

A4)  $dm = \sigma (R d\theta) 2\pi R \sin\theta$
 $\int y dm = \int (R \cos\theta) dm = \int R \cos\theta \sigma R 2\pi R \sin\theta d\theta$
 $= \pi \sigma R^3 \int_0^{\pi/2} 2 \sin\theta \cos\theta d\theta$
 $= \frac{M}{2} R \left[-\frac{\cos 2\theta}{2} \right]_0^{\pi/2} = \frac{MR}{2}$
 $Y_{cm} = \frac{\int y dm}{M} = \boxed{\frac{R}{2}}$

(A6)



$$x) df + T \cos\left(\frac{d\theta}{2}\right) = (T + dT) \cos\left(\frac{d\theta}{2}\right)$$

$$y) dN = T \sin\left(\frac{d\theta}{2}\right) + (T + dT) \sin\left(\frac{d\theta}{2}\right)$$

$$df = \mu dN \text{ (if } df < \mu dN, \text{ then not maximum)}$$

$$x) \Rightarrow df = dT$$

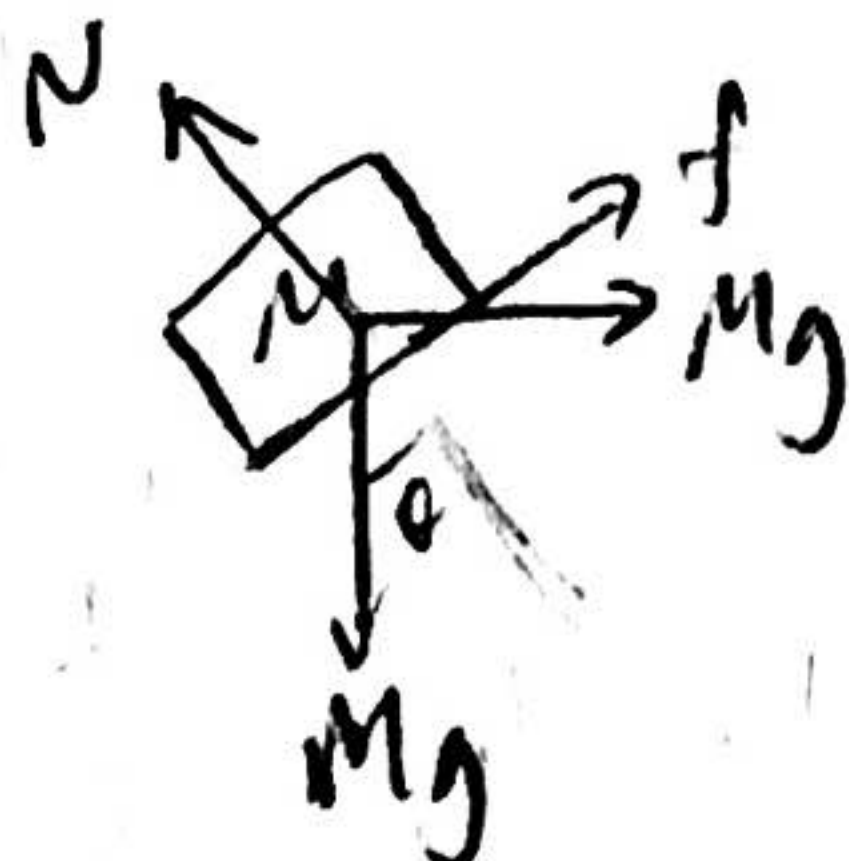
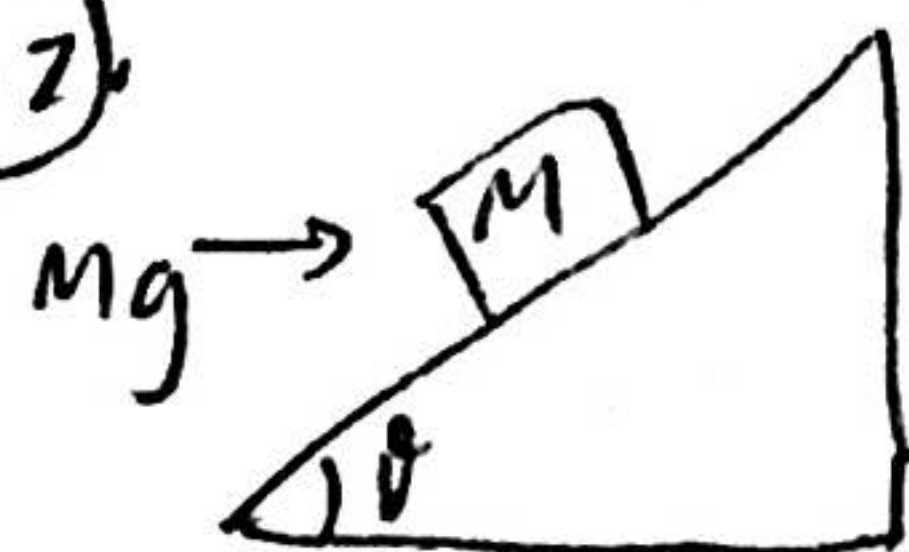
$$y) \Rightarrow dN = \frac{T}{2} d\theta + \frac{T + dT}{2} d\theta = T d\theta$$

$$\Rightarrow dT = \mu T d\theta \Rightarrow \int_{T_0}^T \frac{dT}{T} = \int_0^\theta \mu d\theta$$

$$\Rightarrow [\ln T]_{T_0}^T = [\mu \theta]_0^\theta$$

$$\Rightarrow T = T_0 e^{\mu \theta}$$

(B2)



$$N = Mg \cos \theta + Mg \sin \theta$$

$$f = Mg \sin \theta - Mg \cos \theta$$

$$|f| \leq \mu N$$

$$\text{For } \theta > 1 \Rightarrow \sin \theta - \cos \theta \leq \mu (\cos \theta + \sin \theta)$$

$$\Rightarrow \tan \theta \leq \frac{1+\mu}{1-\mu}$$

$$\text{For } \theta < 1 \Rightarrow -\sin \theta + \cos \theta \leq \mu (\sin \theta + \cos \theta)$$

$$\Rightarrow \tan \theta \geq \frac{1-\mu}{1+\mu}$$

$$\therefore \frac{1-\mu}{1+\mu} \leq \tan \theta \leq \frac{1+\mu}{1-\mu}$$

(B1)

$$m \dot{v} = -mg - m \alpha v$$

$$\dot{v} = -g - \alpha v$$

$$\Rightarrow \int_{v_0}^0 \frac{1}{g + \alpha v} dv = \int_0^t -dt$$

$$\Rightarrow \left[\frac{1}{\alpha} \ln |g + \alpha v| \right]_{v_0}^0 = [-t]_0^t$$

$$\Rightarrow t = \frac{1}{\alpha} \ln \left(\frac{g + \alpha v_0}{g} \right)$$

$$m v \frac{dv}{dx} = -mg - m \alpha v$$

$$\Rightarrow \int_{v_0}^0 \frac{v}{g + \alpha v} dv = \int_0^H -dx$$

$$\Rightarrow \left[\frac{1}{\alpha} v - \frac{g}{\alpha^2} \ln |g + \alpha v| \right]_{v_0}^0 = -H$$

$$\Rightarrow H = \frac{g}{\alpha^2} \ln \left(\frac{g + \alpha v_0}{g} \right) - \frac{1}{\alpha} v_0$$

OR

$$\frac{1}{\alpha} \ln \frac{g + \alpha v}{g + \alpha v_0} = -t$$

$$\Rightarrow g + \alpha v = (g + \alpha v_0) e^{-\alpha t}$$

$$\Rightarrow v = \frac{1}{\alpha} \left[(g + \alpha v_0) e^{-\alpha t} - g \right]$$

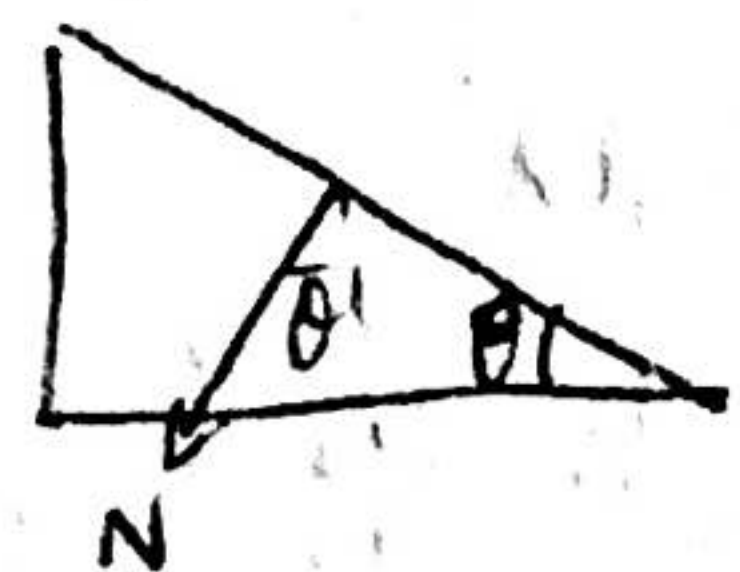
$$h = -\frac{1}{\alpha^2} (g + \alpha v_0) e^{-\alpha t} + \frac{1}{\alpha^2} (g + \alpha v_0) - \frac{g}{\alpha^2} t$$

Sub in t.

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7P



y) $mg - N \cos \theta = m a_y$
 x) $N \sin \theta = m a_x$
 x) $N \sin \theta = M A_x$

4 equations, 4 unknowns
 $\{a_x, a_y, A_x, N\}$

$\Delta y = \tan \theta \Delta x \Rightarrow a_y = \tan \theta (A_x + a_x)$

$M A_x = m a_x$

$a_y = g - a_x \frac{\cos \theta}{\sin \theta} = \tan \theta (A_x + a_x)$

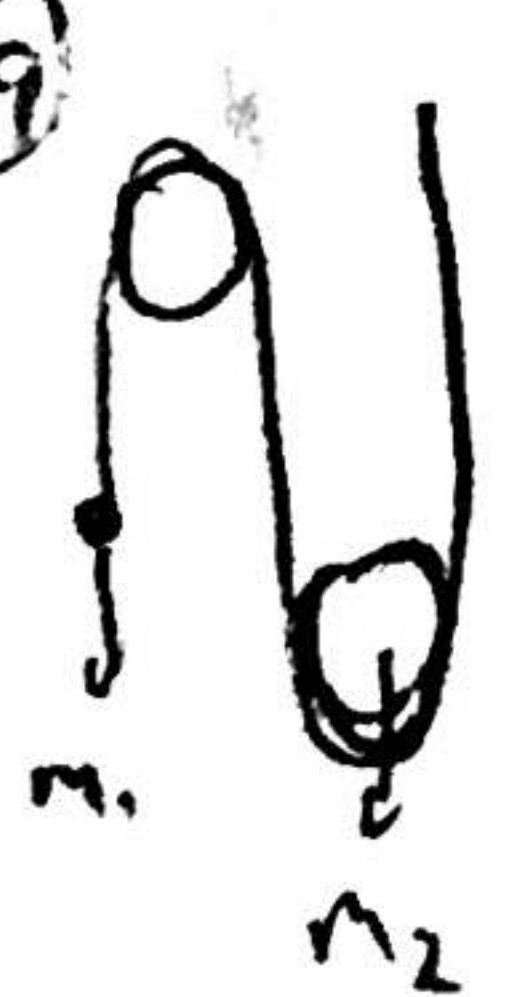
$\tan \theta A_x = g - \frac{a_x}{\tan \theta} - a_x \tan \theta$

$(\tan \theta + \frac{1}{\tan \theta} \frac{M}{m} + \tan \theta \frac{M}{m}) A_x = g$

$\Rightarrow A_x = g \frac{m \tan \theta}{m \tan^2 \theta + M + M \tan^2 \theta}$

$A_x = \frac{m g \sin \theta \cos \theta}{M + m \sin^2 \theta}$

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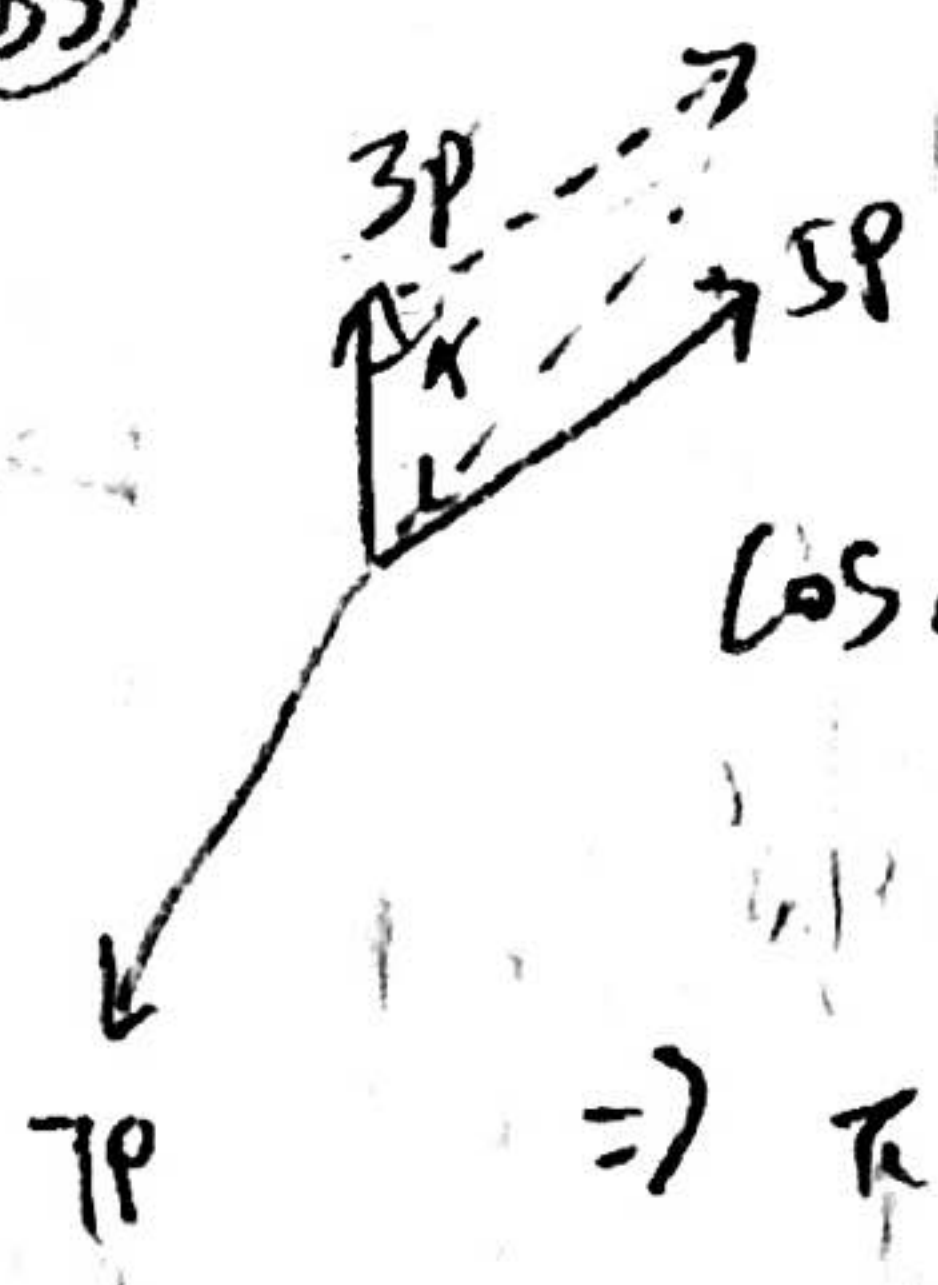
$T - m_1 = m_1 a_1$

$2T - m_2 = m_2 a_2$

Conservation of string $\Rightarrow a_1 = -2 a_2$

$a_1 = g \frac{2m_2 - 4m_1}{4m_1 + m_2}$; $a_2 = g \frac{2m_1 - m_2}{4m_1 + m_2}$; $T = \frac{3m_1 m_2 g}{4m_1 + m_2}$

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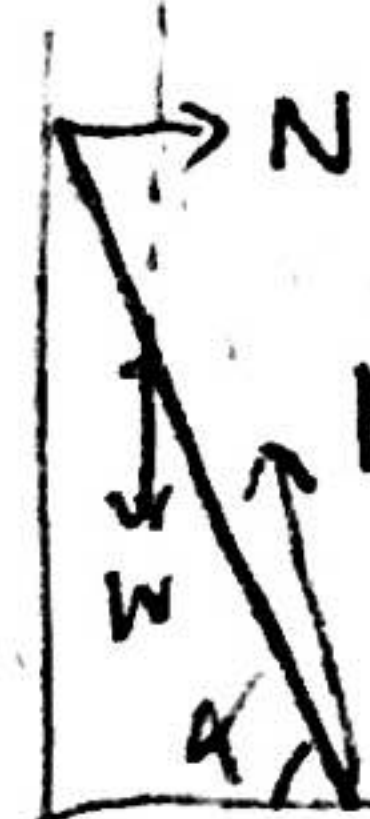


$\cos \alpha = \frac{|3P|^2 + |5P|^2 - |7P|^2}{2|3P||5P|}$

$= -\frac{1}{2} \Rightarrow \alpha = \frac{2\pi}{3}$

$\Rightarrow \pi - \alpha = \boxed{\frac{\pi}{3}}$

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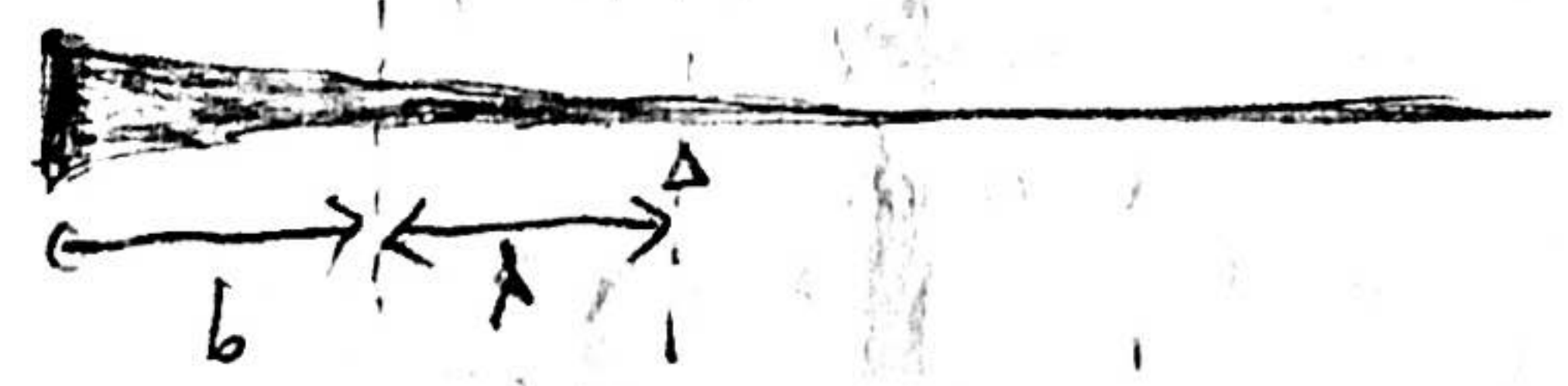


y) $F \sin \beta = W$

$\tan \beta = \frac{g \sin \alpha}{\frac{2}{3} g \cos \alpha} = \frac{3}{2} \tan \alpha$

x) $|N| = |F \cos \beta| = \left| \frac{F \sin \beta}{\tan \beta} \right| = \boxed{\frac{2W}{3 \tan \alpha}}$

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$\int_b^{b+l} p(x)(b+l-x) dx = \int_{b+l}^\infty p(x)(x-b-l) dx$

$\Rightarrow \int_b^\infty p(x)(b+l+x) dx = 0 \quad \forall b$

let $F = \int_b^\infty p(x)(b+l-x) dx$

Then $\frac{dF}{db} = 0 \quad \forall b$

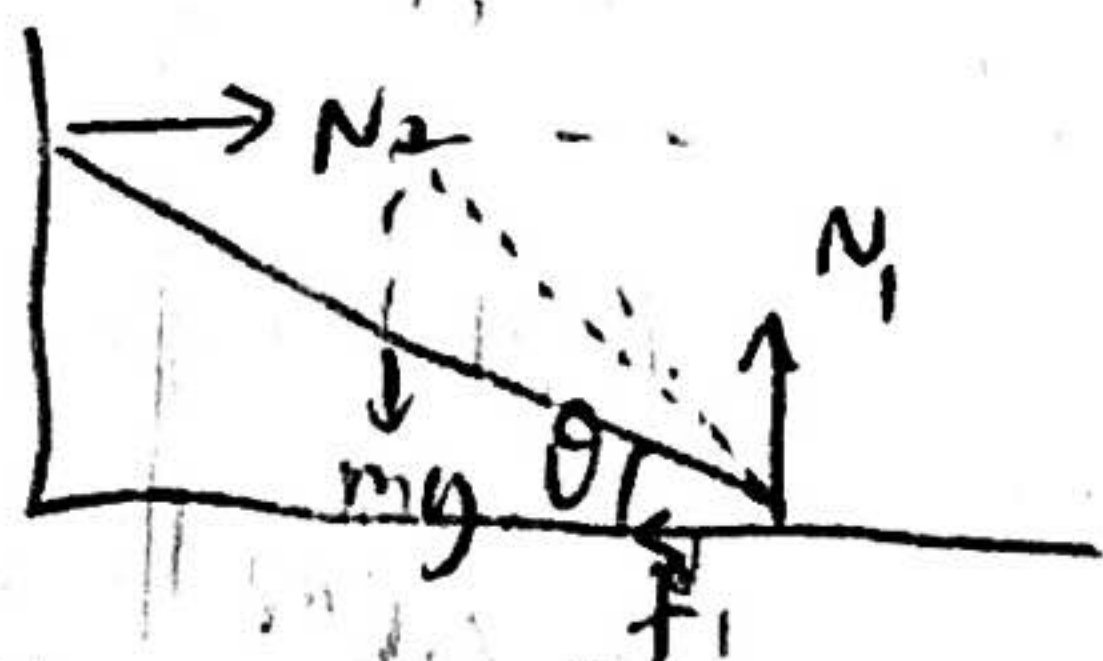
$dF = \left(\int_{b+db}^\infty p(x)(b+db+l-x) dx - \int_b^\infty p(x)(b+l-x) dx \right)$

$= \int_b^\infty p(x) db dx - \int_b^{b+db} p(x)(b+db+l-x) dx$

$= db \int_b^\infty p(x) dx - p(b)l db$

$p(b)l = \int_b^\infty p(x) dx \Rightarrow p(x) = A e^{-\frac{x}{l}}$

(B4)



At boundary condition, f is not sufficient to make the three forces collinear

$$y) N_1 = mg$$

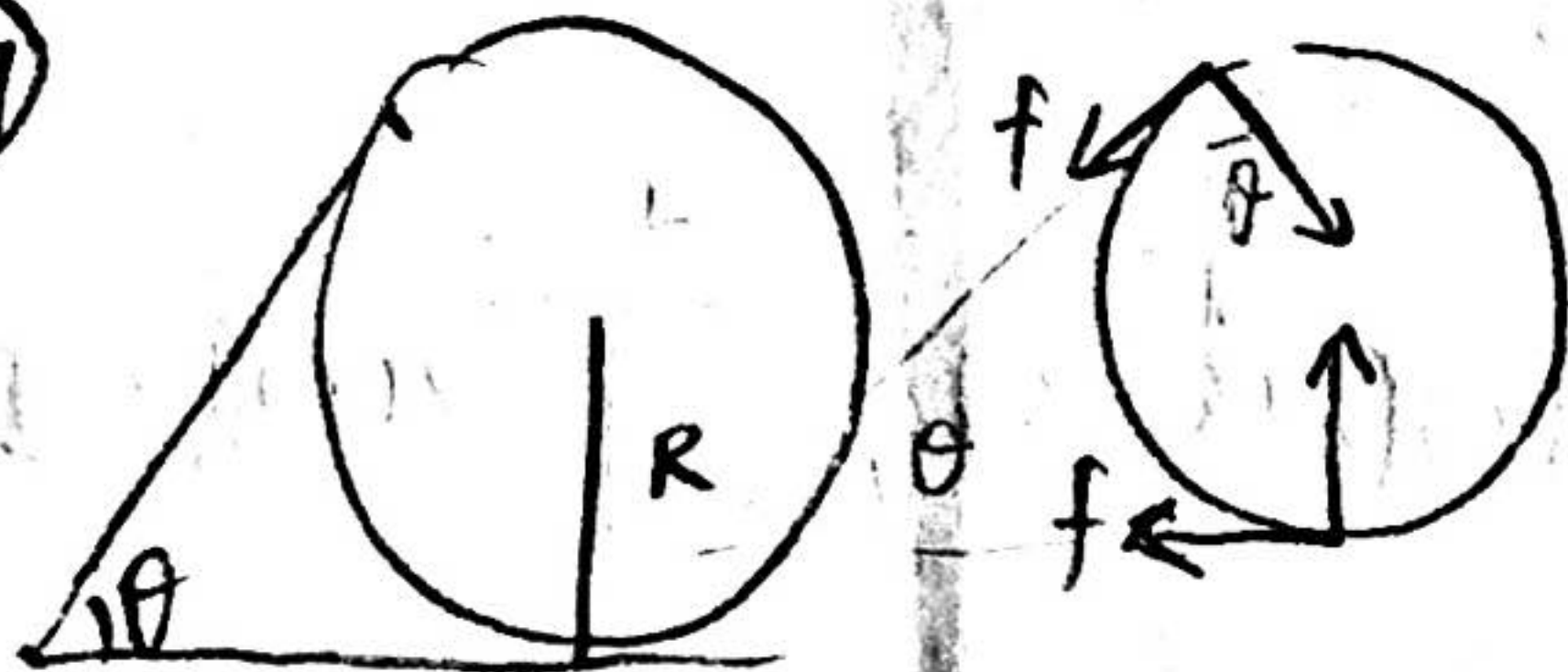
$$x) N_2 = f \leq \mu N_1 = \mu mg$$

$$\frac{N_1}{f} = 2 \tan \theta$$

$$\Rightarrow \tan \theta = \frac{N_1}{2f} = \frac{mg}{2f} \geq \frac{1}{2\mu}$$

$$\Rightarrow \theta_{\min} = \tan^{-1}\left(\frac{1}{2\mu}\right)$$

(B7)



Stick) $mg \cos \theta \left(\frac{R}{2}\right) = NR$
 $\Rightarrow N = \frac{1}{2} \rho g R \cos \theta$

Ball) $f(1 + \cos \theta) = N \sin \theta$

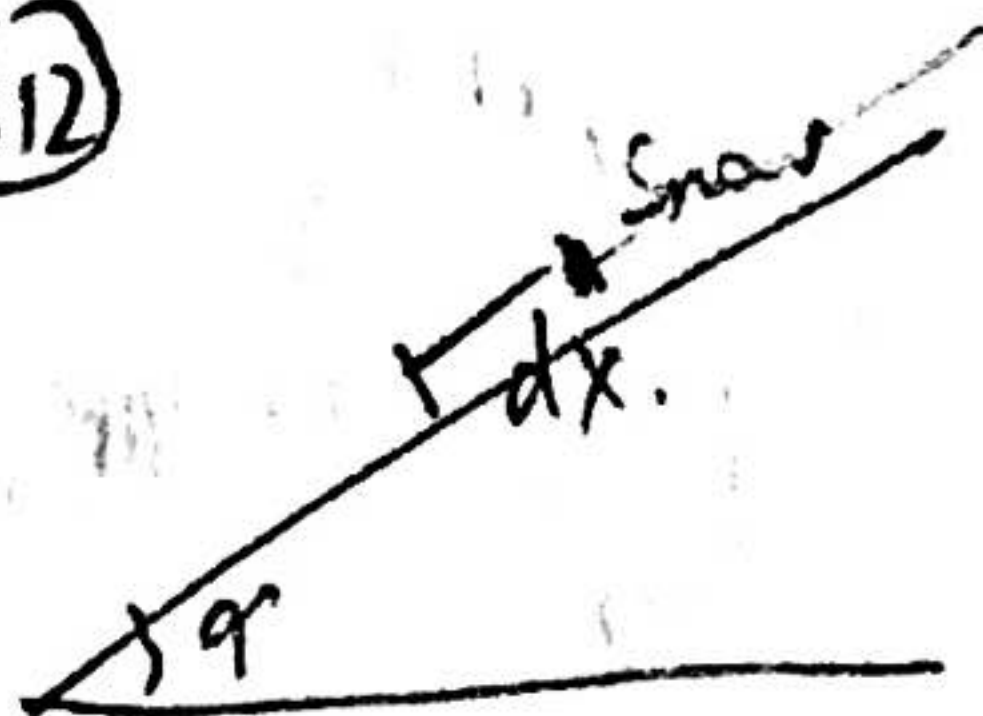
$$\Rightarrow f = \frac{1}{2} \rho g R \frac{\sin \theta \cos \theta}{1 + \cos \theta}$$

$$R = R \tan\left(\frac{\theta}{2}\right)$$

$$\Rightarrow f = \frac{1}{2} \rho g \frac{R}{\tan\left(\frac{\theta}{2}\right)} \frac{\sin \theta \cos \theta}{1 + \cos \theta}$$

$$\boxed{f = \frac{1}{2} \rho g R \cos \theta}$$

(B12)



$$dm = \sigma dx \quad m = \sigma x$$

$$\sigma x g \sin \alpha = \frac{dp}{dt} = m \frac{dv}{dt} + v \frac{dm}{dt}$$

$$= \sigma x \frac{dv}{dt} + \sigma v^2$$

$$x \frac{dv}{dt} + v^2 = x g \sin \alpha$$

$$\Rightarrow x v \frac{dv}{dx} + v^2 = x g \sin \alpha$$

$$\Rightarrow x^2 v \frac{dv}{dx} + x v^2 = x^2 g \sin \alpha$$

$$\Rightarrow \frac{d}{dx}(x^2 v^2) = 2 x^2 g \sin \alpha$$

$$\Rightarrow x^2 v^2 = \int 2 x^2 g \sin \alpha dx$$

$$= \frac{2}{3} x^3 g \sin \alpha + c$$

$$v^2 = \frac{2}{3} x g \sin \alpha + c$$

$$a = v \frac{dv}{dx} = \frac{1}{2} \frac{d}{dx}(v^2) = \boxed{\frac{1}{3} g \sin \alpha}$$

(B11) $M \rightarrow V_i$

In an infinitesimal time dt

$$k dt = \boxed{\quad}$$

$$dm = -k dt$$

$$\text{com) } (m + dm)(v + dv) + dm(v - v_r) = mv$$

$$v_r dm + m dv = 0$$

$$\Rightarrow \int_{m_i}^{m_f} \frac{1}{m} dm = \int_{v_i}^{v_f} -\frac{1}{v_r} dv$$

$$\Rightarrow \ln\left(\frac{M_f}{M_i}\right) = \frac{v_i - v_f}{v_r}$$

$$\Rightarrow \boxed{V = V_i + v_r \ln\left(\frac{M_i}{M_f}\right)}$$

(B13)

Suppose that if a system is stationary, then top mass acceleration of kg , k some constant.

$$kg = 2k(1-k)g$$

$$\Rightarrow 2(1-k)g = 1$$

$$2k(1-k)g \Rightarrow k = \frac{1}{2}$$

$$\therefore \boxed{\frac{1}{2}g}$$

(B8)

$$V_{i+1} = 2V_i + \sqrt{2gh}$$

$$\therefore V_n = (2^n - 1)\sqrt{2gh}$$

\therefore Height which ball n rises to is

$$2 + (2^n - 1)^2 h$$

$$2 + (2^n - 1)^2 h > 1000 \Rightarrow \boxed{n \geq 6}$$

(B14)

Suppose for N blocks, the max distance reached is $\frac{R}{2}(1 + \frac{1}{2} + \dots + \frac{1}{N})$.

For $N+1$ blocks

$$\text{dist} = k + \frac{R}{2}(1 + \frac{1}{2} + \dots + \frac{1}{N})$$

$$CM = kNm + (k - \frac{R}{2})m \leq 0$$

$$\Rightarrow k \leq \frac{1}{N+1} \frac{R}{2}$$

$$\Rightarrow \text{Total is } \frac{R}{2}(1 + \frac{1}{2} + \dots + \frac{1}{N} + \frac{1}{N+1})$$

The reason why this greedy induction works will be covered in lesson.

(B15)

$$U + V = V' - U'$$

$$MU - mv = MU' + mv'$$

$$v' = V' + U + V$$

$$\Rightarrow (M+m)V' = MU - mv - mU - mv$$

$$\Rightarrow U' = \frac{M-m}{M+m}U + \frac{2m}{M+m}V$$

$$V' = \frac{2M}{M+m}U + \frac{M-m}{M+m}V$$

$$\begin{pmatrix} U' \\ V' \end{pmatrix} = \frac{1}{M+m} \begin{pmatrix} M-m & -2m \\ 2M & M-m \end{pmatrix} \begin{pmatrix} U \\ V \end{pmatrix}$$

Eigenvectors

$$A_1 = \begin{pmatrix} 1 \\ -i\sqrt{\frac{M}{m}} \end{pmatrix} \quad A_2 = \begin{pmatrix} 1 \\ i\sqrt{\frac{M}{m}} \end{pmatrix}$$

Eigenvalues

$$\lambda_1 = \frac{(M-m) + 2i\sqrt{Mm}}{M+m} \quad \lambda_2 = \frac{(M-m) - 2i\sqrt{Mm}}{M+m}$$

where $\theta = \tan^{-1} \left(\frac{2\sqrt{Mm}}{M-m} \right) \approx 2\sqrt{\frac{m}{M}}$

Initial condition: $\begin{pmatrix} U \\ V \end{pmatrix} = \begin{pmatrix} V_0 \\ 0 \end{pmatrix}$

$$\Rightarrow \begin{pmatrix} U_n \\ V_n \end{pmatrix} = \frac{V_0}{2} (\lambda_1^n A_1 + \lambda_2^n A_2)$$

$$= \frac{V_0}{2} \left(e^{in\theta} \begin{pmatrix} 1 \\ -i\sqrt{\frac{M}{m}} \end{pmatrix} + e^{-in\theta} \begin{pmatrix} 1 \\ i\sqrt{\frac{M}{m}} \end{pmatrix} \right)$$

$$= V_0 \begin{pmatrix} \cos n\theta \\ \sqrt{\frac{m}{M}} \sin n\theta \end{pmatrix}$$

Closest when $\cos n\theta = 0$

$$\Rightarrow n\theta = \frac{\pi}{2} \Rightarrow n = \frac{\pi}{2(2\sqrt{\frac{m}{M}})} \approx \boxed{\frac{\pi}{4} \sqrt{\frac{M}{m}}}$$