#### machine learning week3

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URL: https://www.coursera.org/learn/machine-learning/supplement/fDCQp/classification

# week 3 logistic regression

# classification and representation

- Introduction
  - task
    - facing discrete data, we usually need to make a classification.
    - begin with binary classification problem further multiclass
    - Hence, y∈{0,1}. 0 is also called the negative class, and 1 the positive class

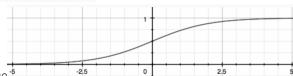
**Updated:** 

18/11/09 22:22

- method
  - linear regression doesn't work
  - use logistic regression
- hypothesis representation
  - Sigmoid function (Logistic function)

$$h_{ heta}(x) = g( heta^T x)$$

$$z = \theta^T x$$
$$g(z) = \frac{1}{1 + e^{-z}}$$



- image<sup>-5</sup>
- hθ(x) give us the probability that our output is 1. Just interpret it in Conditional probability.

$$h_{\theta}(x) = P(y = 1|x; \theta) = 1 - P(y = 0|x; \theta)$$
  
 $P(y = 0|x; \theta) + P(y = 1|x; \theta) = 1$ 

• when can we get  $h\theta(x)>0.5$ ? studying the hypothesis closer.

$$\theta^T x \ge 0 \Rightarrow y = 1$$
  
 $\theta^T x < 0 \Rightarrow y = 0$ 

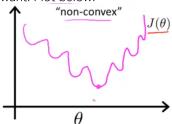
- we got this:
- and take the term: Decision Boundary
- Decision Boudary
  - the line that separates the area where y = 0 and where y = 1.
  - the property of  $h\theta(x)$ , once the theta decided, we got decision boundary. It doesn't come from data set.
  - Image! remember that decision boundary comes from  $\theta^T X$ , it can be linear or more complicated base on what polynomial function u chosen.

# Logistic Regression Model

- Cost Function
  - · review:
    - what cost function work. Cost function is to measure the accuracy of hypothesis. So if our hypothesis comes up with the output that close to the actual label, cost function should give value close to 0; while hypothesis gives wrong output, cost function should **penalize** it. That is give high value.
    - how to use cost function to get better theta: Gradient Descent. When we use GD, we want the cost function has global optimum and better not have local optimum so that it can converge to the theta we want.

convex:

non-convex: use the same cost function in linear regression we would get many local optimum. That's not we want. Plot below:



• we use:

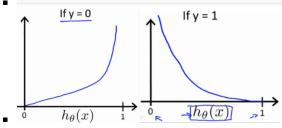
$$J(\theta) = \frac{1}{m} \sum_{i=1}^{m} \operatorname{Cost}(h_{\theta}(x^{(i)}), y^{(i)})$$

$$\operatorname{Cost}(h_{\theta}(x), y) = -\log(h_{\theta}(x)) \quad \text{if } y = 1$$

$$\operatorname{Cost}(h_{\theta}(x), y) = -\log(1 - h_{\theta}(x)) \quad \text{if } y = 0$$

how it work

$$\operatorname{Cost}(h_{\theta}(x), y) = 0 \text{ if } h_{\theta}(x) = y$$
 $\operatorname{Cost}(h_{\theta}(x), y) \to \infty \text{ if } y = 0 \text{ and } h_{\theta}(x) \to 1$ 
 $\operatorname{Cost}(h_{\theta}(x), y) \to \infty \text{ if } y = 1 \text{ and } h_{\theta}(x) \to 0$ 



o compress it:

$$h = g(X\theta)$$

$$J(\theta) = \frac{1}{m} \cdot \left(-y^T \log(h) - (1-y)^T \log(1-h)\right)$$

Gradient Descent

$$\theta := \theta - \frac{\alpha}{m} X^T (g(X\theta) - \vec{y})$$

- vectored version:
- further: how to make partial derivative?
  - link: <a href="https://math.stackexchange.com/questions/477207/derivative-of-cost-function-for-logistic-regression">https://math.stackexchange.com/questions/477207/derivative-of-cost-function-for-logistic-regression</a>

The reason is the following. We use the notation

$$\theta x^i := \theta_0 + \theta_1 x_1^i + \dots + \theta_p x_p^i.$$

Then

$$\log h_{ heta}(x^i) = \log rac{1}{1+e^{- heta x^i}} = -\log(1+e^{- heta x^i}),$$

$$\log(1-h_{\theta}(x^i)) = \log(1-\frac{1}{1+e^{-\theta x^i}}) = \log(e^{-\theta x^i}) - \log(1+e^{-\theta x^i}) = -\theta x^i - \log(1+e^{-\theta x^i}),$$

[ this used:  $1=rac{(1+e^{-\theta x^i})}{(1+e^{-\theta x^i})}$ , the 1's in numerator cancel, then we used:  $\log(x/y)=\log(x)-\log(y)$  ]

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# Advanced Optimization

- require: Advanced Mathematics. Know how to make partial derivative.
- $\circ$  "Conjugate gradient", "BFGS", and "L-BFGS" are more sophisticated, faster ways to optimize  $\theta$
- how: use the library.

```
% write a single function that returns both of these
function [jVal, gradient] = costFunction(theta)
  jVal = [...code to compute J(theta)...];
  gradient = [...code to compute derivative of J(theta)...];
end
% give to the function "fminunc()" our cost function
% for more details, refer to official document.
```

#### Multi-class Classification: One vs All

- Supposed we have N class. Then train a logistic regression classifier  $h\theta(X)$  for each class to predict the probability that y = i. That's say now we have N classifier. Each classifier can predict whether the sample is class(j) or not.
- To make a prediction on a new x, pick the class that **maximizes**  $h\dot{\theta}(X)$

# Regularization

### over-fitting/under-fitting

- hypothesis fit training set perfectly but fail to predict / map poorly to the trend of data set.
- o solution:

#### Reduce features

- 1. manually select features to remain
- 2. use a model selection algorithm
- Regularization

## modify cost function

add regularization parameter λ. It's a penalty for theta. It determines how much the costs of our theta parameters are inflated.

$$min_{\theta} \frac{1}{2m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})^2 + \lambda \sum_{j=1}^{n} \theta_j^2$$

- Proper lambda can make hypothesis smoother so that avoid over-fitting. But
  - too large: penalize too strong that make theta close to 0. Finally we may get a flat line ( assumed that θ0 not been regularized ).
  - too small: help little to fix over-fitting.
- for linear regression:
  - new GD here:

$$\begin{aligned} & \text{Repeat } \{ \\ & \theta_0 := \theta_0 - \alpha \,\, \frac{1}{m} \,\, \sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)}) x_0^{(i)} \\ & \theta_j := \theta_j - \alpha \left[ \left( \frac{1}{m} \,\, \sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)}) x_j^{(i)} \right) + \frac{\lambda}{m} \, \theta_j \right] \\ & \} \end{aligned} \qquad \qquad j \in \{1, 2...n\}$$

• separate out  $\theta_0$  from the rest of the parameters because we do not want to penalize  $\theta_0$ 

$$\theta_j := \theta_j (1 - \alpha \frac{\lambda}{m}) - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) x_j^{(i)}$$

- and merge θ:
- new normal equation:

$$heta = \left( X^T X + \lambda \cdot L 
ight)^{-1} X^T y$$
 where  $L = \left[ egin{array}{ccc} 1 & & & & \ & 1 & & & \ & & \ddots & & \ & & & 1 \end{array} 
ight]$ 

- benefit: add the term  $\lambda \cdot L$ , then  $X^TX + \lambda \cdot L$  becomes always **invertible**.
  - when  $X_{m*n}$ , has m<n, the  $X^TX$  would be non-invertible.
  - because:
    - a invertible matrix is full rank.
    - $\blacksquare$  R(X<sub>m\*n</sub>)<=min(m,n)=m
    - X<sup>T</sup>X is n\*n matrix, which full rank should equal to n.
      - Suppose matrix A is of size vxw. Then rank(A)<=min(v,w).
      - Also suppose matrices A and B with rank(A)=a and rank(B)=b. Then rank(A\*B)=min(a,b).

Remember X is a mxn - matrix, now with m<n.

Multiplying out X'\*X is of dimension nxn, but rank $(X'*X) \le m \le n$ .

Invertibility of a matrix requires full rank, which is by now not given. A square matrix that has full rank is also called **regular**, which is maybe why the name **regularization** arises.

- further explanation:
- also work for logistic regression:
  - new cost function: (just add  $\theta_i^2$  at the end)

$$J( heta) = -rac{1}{m} \sum_{i=1}^m ig[ y^{(i)} \; \log ig( h_ heta(x^{(i)}) ig) + ig( 1 - y^{(i)} ig) \; \log ig( 1 - h_ heta(x^{(i)}) ig) ig] + rac{\lambda}{2m} \sum_{j=1}^n heta_j^2$$

by solving partial derivative : new GD

# Gradient descent Repeat $\{$ $\theta_0 := \theta_0 - \alpha \frac{1}{m} \sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)}) x_0^{(i)}$ $\theta_j := \theta_j - \alpha \left[ \frac{1}{m} \sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)}) x_j^{(i)} + \frac{\lambda}{m} \Theta_j \right]$

$$\theta_{j} := \theta_{j} - \alpha \underbrace{\left[\frac{1}{m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)}) x_{j}^{(i)} + \frac{\lambda}{m} \Theta_{j}\right]}_{\{j = \mathbf{X}, 1, 2, 3, \dots, n\}}$$

$$\frac{\lambda}{\lambda \Theta_{j}} \underbrace{\mathcal{I}(\Theta)}_{\{j = \mathbf{X}, 1, 2, 3, \dots, n\}} h_{\Theta}(\mathbf{x})^{2} \underbrace{\mathbf{I}_{\mathbf{x}} \mathbf{e}^{-\mathbf{e}^{-\mathbf{x}}}}_{\{j = \mathbf{x}, 1, 2, 3, \dots, n\}}$$

• remember to separate  $\theta 0$  out.