

Supplementary details on experiments of effective reproduction number estimation with trend filtering

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1 Supplementary details on experimental settings of RtEstim for Section 3.1

We run 10-fold cross validation (CV) to choose the best tuning parameter from the candidate set of size 50, i.e., $\lambda = \{\lambda_1, \dots, \lambda_{50}\}$. Specifically, we divide all samples (except the first and last entries) into ten folds evenly and randomly, and build models on each sample set by leaving a fold out across all hyperparameters. We select the tuning parameter that gives the lowest averaged *deviance* between the estimated incidence and the observed samples averaged over all folds.

2 Experimental comparisons between EpiEstim with monthly sliding windows and other methods for Section 3.1

Fig 10 displays the KL divergence values for negative Binomial incidence. Comparing across \mathcal{R}_t estimates by EpiLPS, RtEstim and EpiEstim with *monthly* sliding windows, KL divergence computation excludes the first month of \mathcal{R}_t estimates for all approaches, since EpiEstim estimates with the monthly sliding windows are not available until the second month. The y -axis is displayed on a logarithmic scale for a better visualization, since a few values are much larger than others.

The relative performance of EpiEstim with monthly sliding windows, in general, is not as good as its weekly sliding window based on the relative positions of its boxes and the counterparts of the other methods, except for the Scenario 2 with negative Binomial incidence. It can be explained by EpiEstim with longer sliding windows assume similarity of neighbouring \mathcal{R}_t across longer periods, and thus, is smoother and less accurate compared to the one with shorter sliding windows.

3 Supplementary results of experiments for Fig 3 in Section 3.2

The full KL divergence values for Poisson incidence without excluding the outliers are shown in Fig 11. The y -axis is displayed on a logarithmic scale for the same reason in Fig 10.

Comparing among \mathcal{R}_t estimations by EpiLPS, RtEstim and EpiEstim with *weekly* sliding windows, KL divergence computation excludes the first week of \mathcal{R}_t estimates for all approaches. The outliers are mainly EpiLPS and EpiEstim \mathcal{R}_t estimations in Scenario 2, which is generally an easy problem except for the

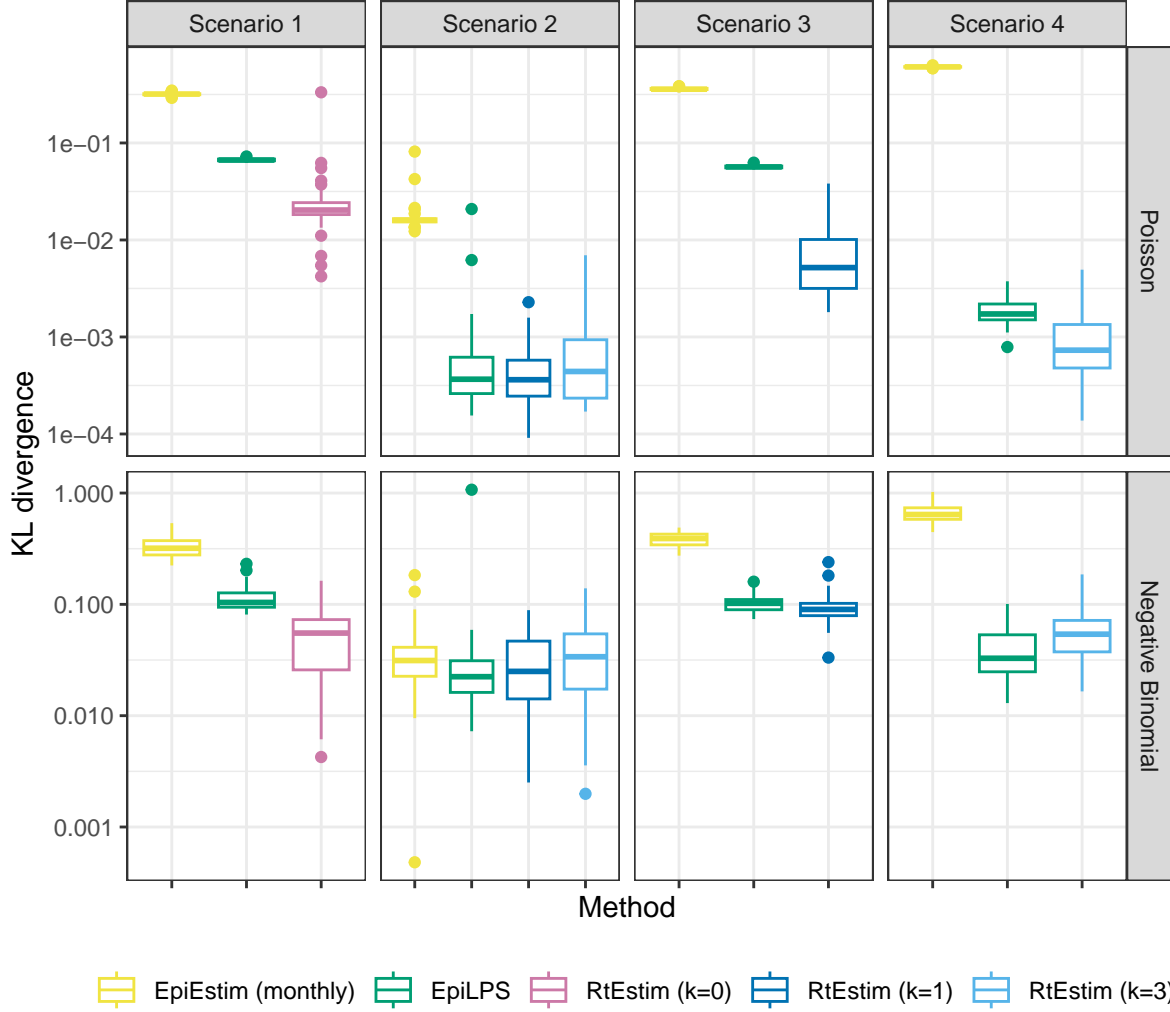


Fig 10. KL divergence for EpiEstim with monthly sliding windows and other methods. Y-axis is on a logarithmic scale.

change point at where the two segments are discontinuous. Since EpiEstim produces a continuous \mathcal{R}_t curve, the change point can be difficult to recover and make estimation less accurate.

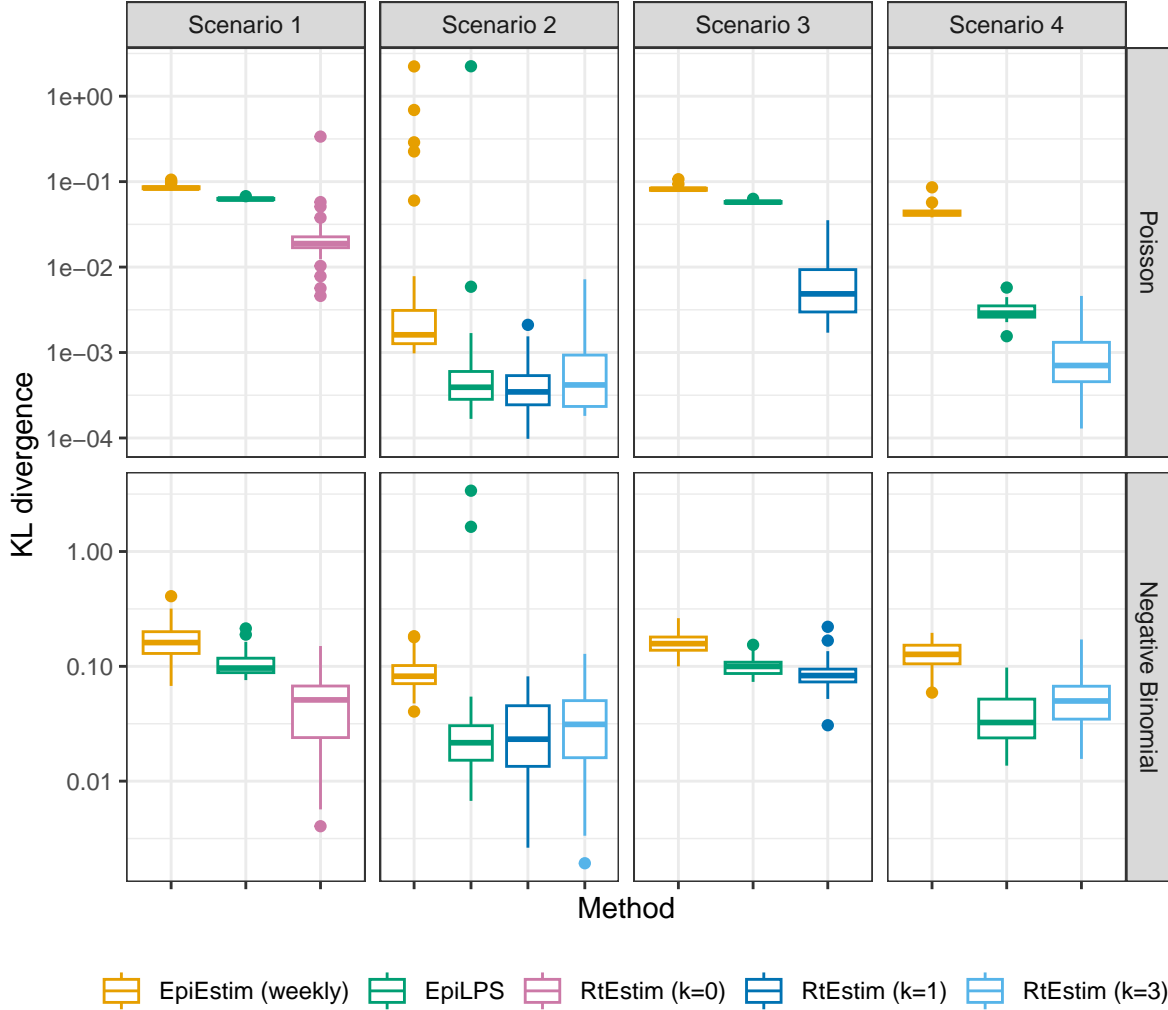


Fig 11. KL divergence for methods with weekly sliding windows. Y-axis is on a logarithmic scale.

4 Time comparisons of methods for Section 3.2

Fig 12 shows the time comparisons across all methods. EpiEstim with both weekly and monthly sliding windows are very fast and converge in less than 0.1 seconds. Piecewise constant RtEstim (with $k=0$) estimates can be generated within 0.1 seconds as well. EpiLPS is slightly slower, but still very fast and within 1 second for all experiments. Piecewise linear and cubic RtEstim (with $k=1$ and $k=3$ respectively) are slower, but mostly within 10 seconds.

It is remarkable that our RtEstim computes 50 lambda values with 10-fold CV for each experiment, which results in 550 times of modelling per experiment (including modelling for all folds). The running times are no more than 10 seconds for most of the experiments, which means the running time for each time of modelling is very fast, and on average can be less than 0.02 seconds. The other two methods only run once for a fixed set of hyperparameters for each experiment.

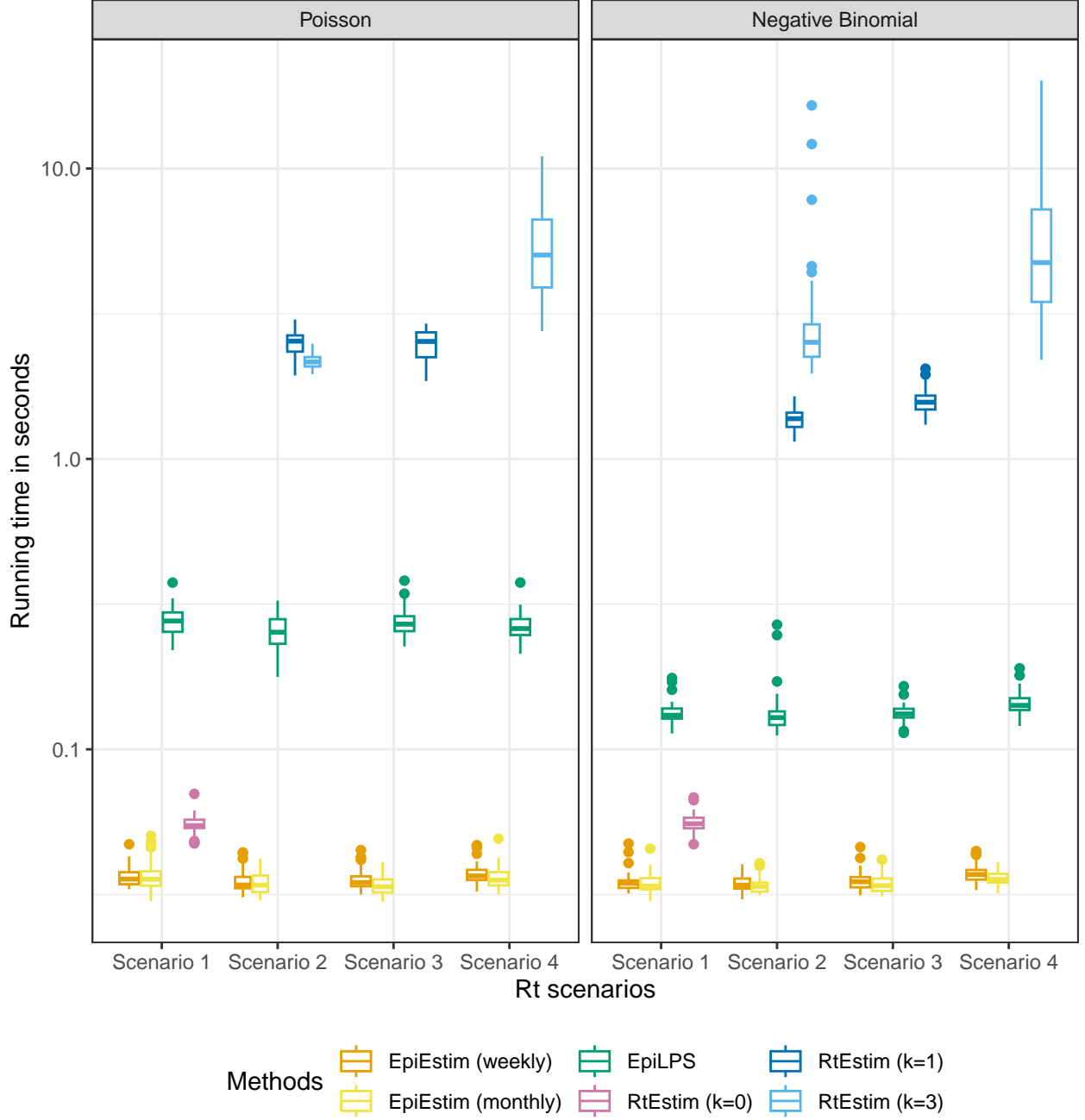


Fig 12. Time comparisons of methods (excluding one outlier of RtEstim (k=1) in Scenario 2 with negative Binomial incidence). Y-axis is on a logarithmic scale.