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# Stanford CS224W: How Expressive are Graph Neural Networks?

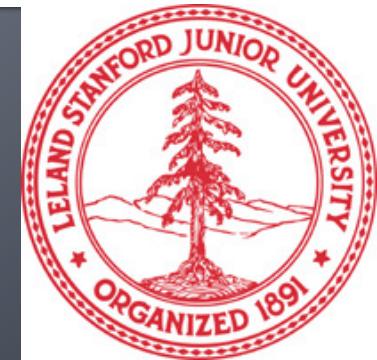
CS224W: Machine Learning with Graphs  
Joshua Robinson and Jure Leskovec, Stanford University  
<http://cs224w.stanford.edu>



# ANNOUNCEMENTS

- My email: [joshrob@cs.stanford.edu](mailto:joshrob@cs.stanford.edu)
- Please reach out with any questions, etc.!

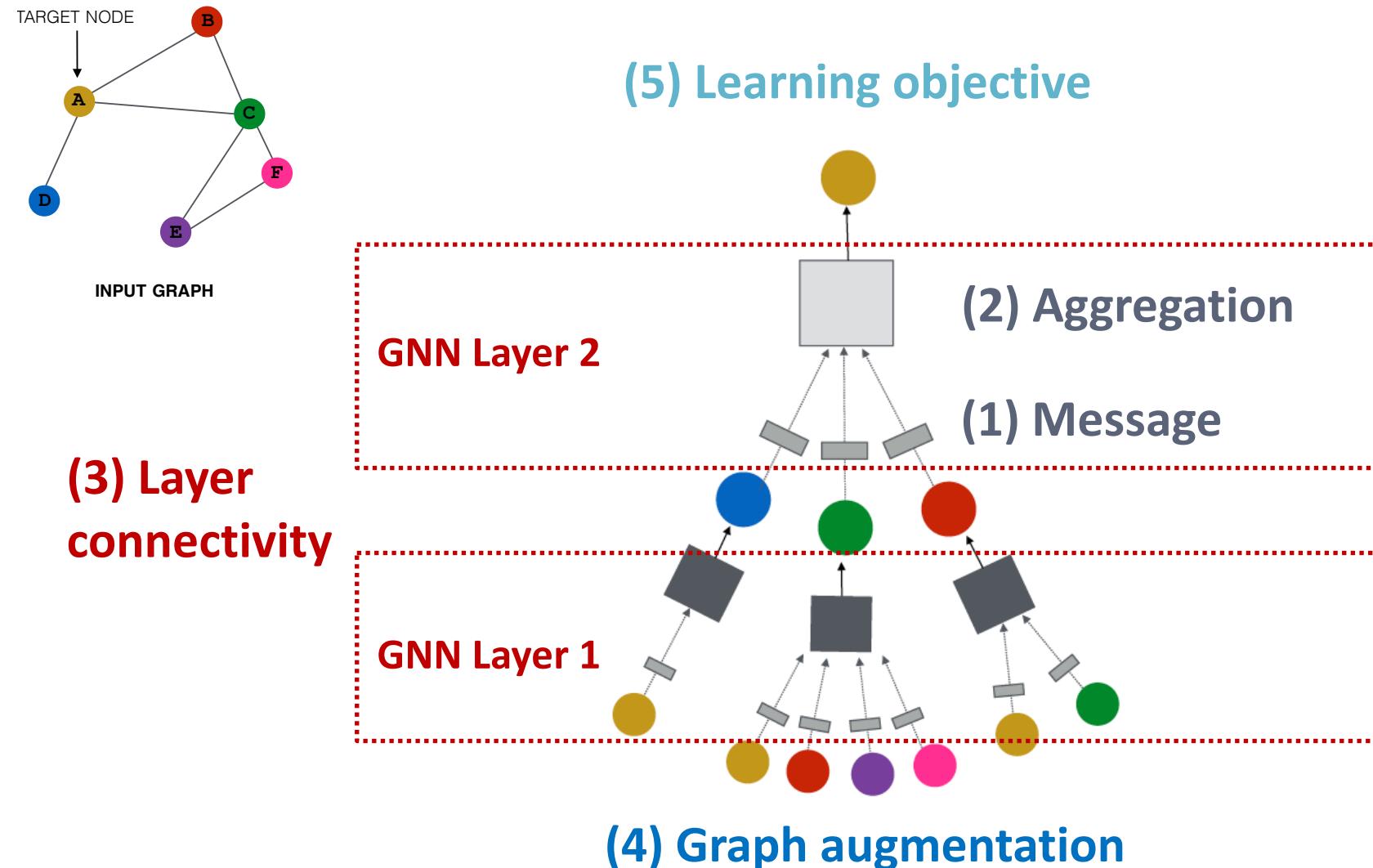
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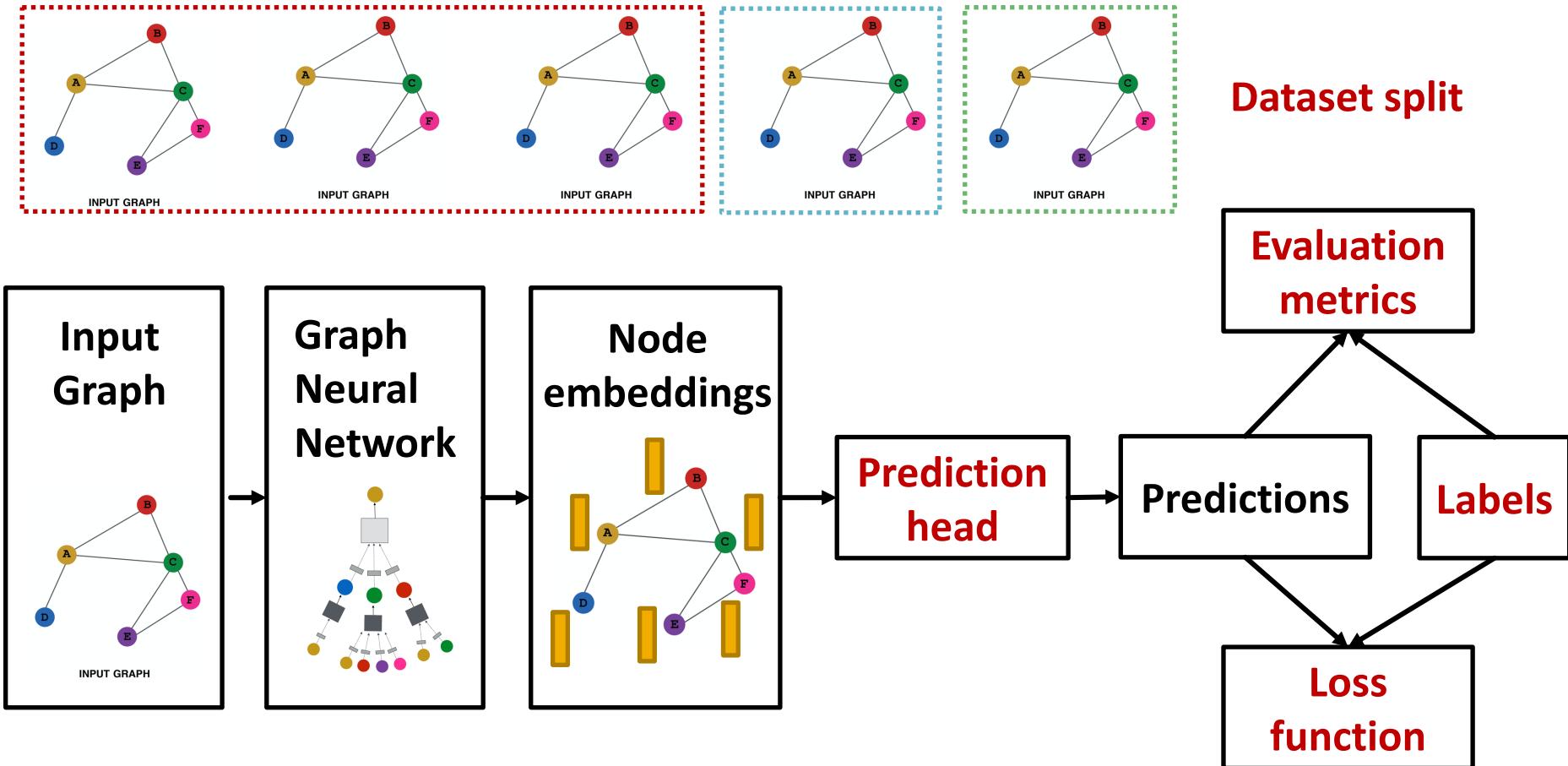
# Announcements

- **Homework 1** recitation session 1pm-3pm tomorrow
  - Details on Ed
- **Colab 2** will be released today by 9PM on our course website
  - Due on Thursday, October 26 (2 weeks from now)

# Recap: A General GNN Framework



# Recap: GNN Training Pipeline



## Implementation resources:

[PyG](#) provides core modules for this pipeline

[GraphGym](#) further implements the full pipeline to facilitate GNN design

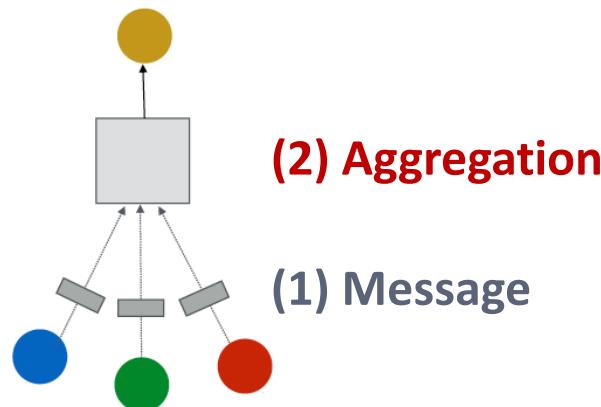
# Theory of GNNs

## How powerful are GNNs?

- Many GNN models have been proposed (e.g., GCN, GAT, GraphSAGE, design space).
- What is the expressive power (ability to distinguish different graph structures) of these GNN models?
- How to design a maximally expressive GNN model?

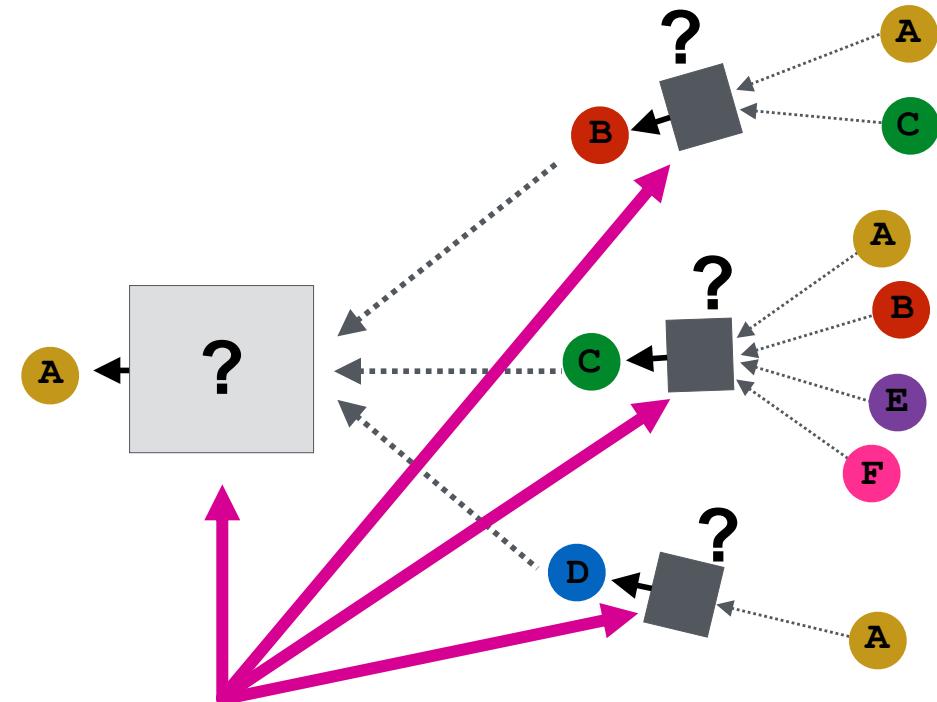
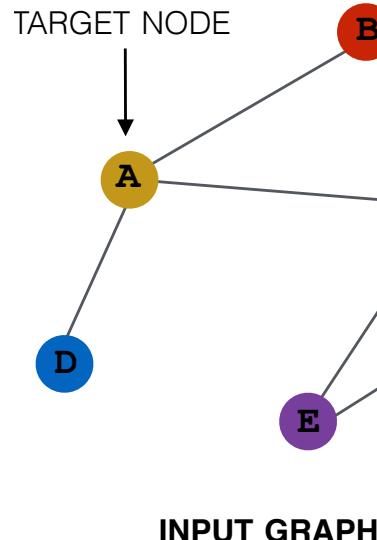
# Background: A Single GNN Layer

- We focus on message passing GNNs:
  - (1) Message: each node computes a message
$$\mathbf{m}_u^{(l)} = \text{MSG}^{(l)}\left(\mathbf{h}_u^{(l-1)}\right), u \in \{N(v) \cup v\}$$
  - (2) Aggregation: aggregate messages from neighbors
$$\mathbf{h}_v^{(l)} = \text{AGG}^{(l)}\left(\left\{\mathbf{m}_u^{(l)}, u \in N(v)\right\}, \mathbf{m}_v^{(l)}\right)$$



# Background: Many GNN Models

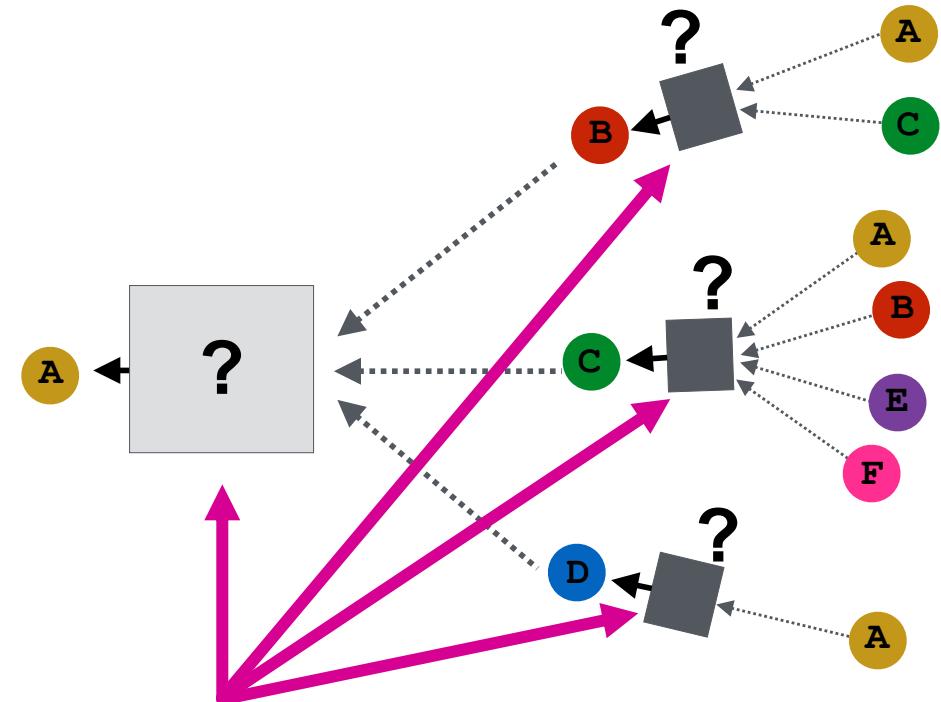
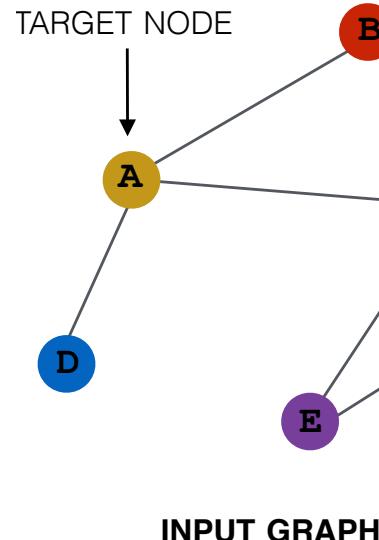
- Many GNN models have been proposed:
  - GCN, GraphSAGE, GAT, Design Space etc.



Different GNN models use different neural networks in the box

# GNN Model Example (1)

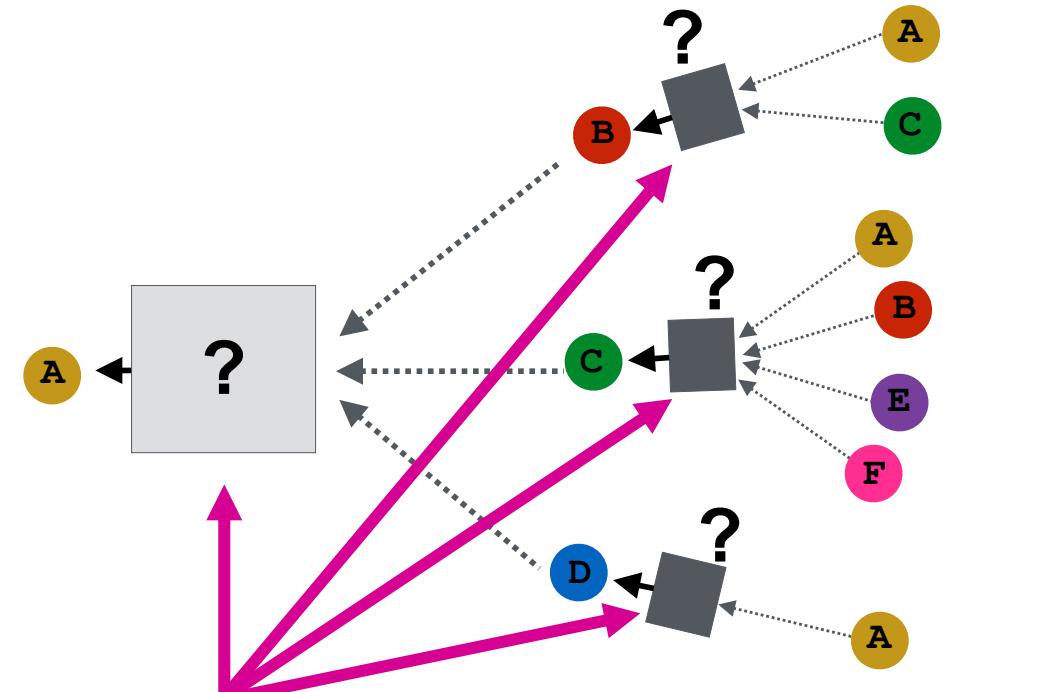
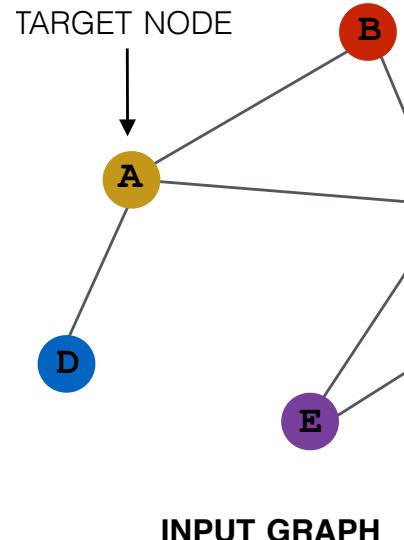
- GCN (mean-pool) [Kipf and Welling ICLR 2017]



Element-wise mean pooling +  
Linear + ReLU non-linearity

# GNN Model Example (2)

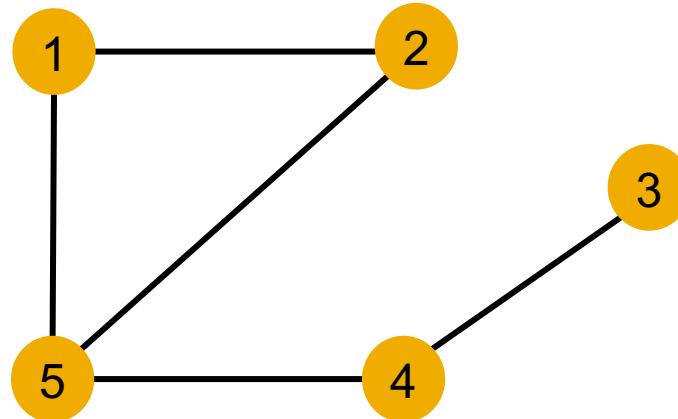
- GraphSAGE (max-pool) [Hamilton et al. NeurIPS 2017]



MLP + element-wise max-pooling

# Note: Node Colors

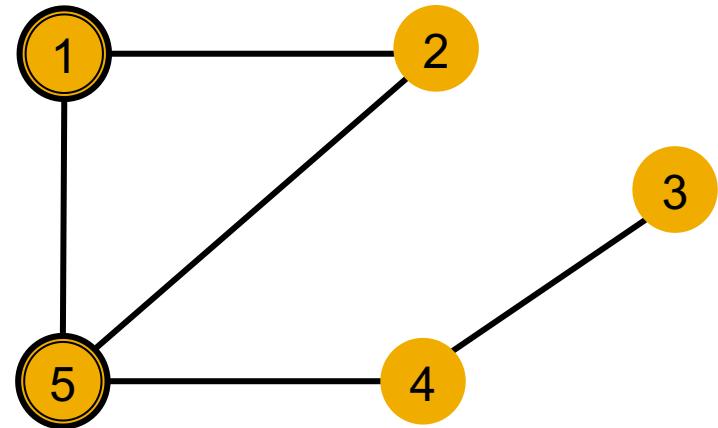
- We use node same/different **colors** to represent nodes with same/different features.
  - For example, the graph below assumes all the nodes share the same feature.



- **Key question:** How well can a GNN distinguish different graph structures?

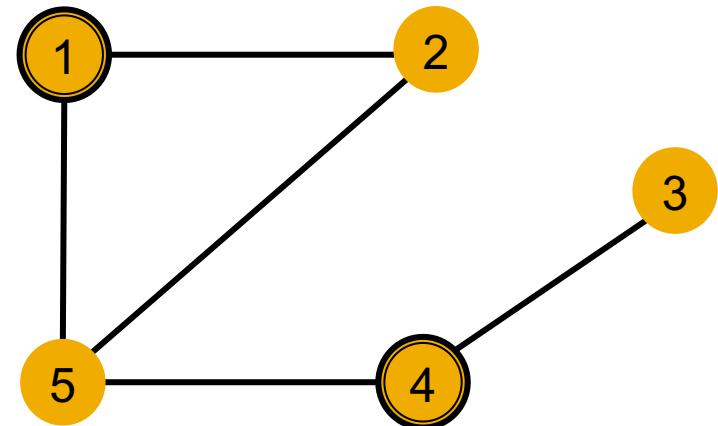
# Local Neighborhood Structures

- We specifically consider **local neighborhood structures** around each node in a graph.
  - **Example:** Nodes 1 and 5 have **different** neighborhood structures because they have different node degrees.



# Local Neighborhood Structures

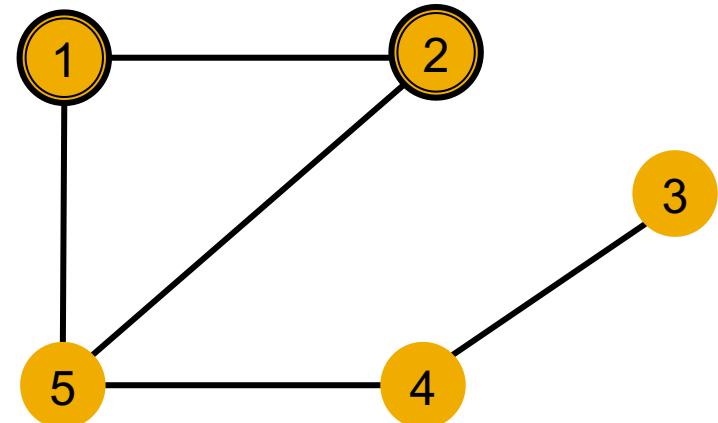
- We specifically consider **local neighborhood structures** around each node in a graph.
  - **Example:** Nodes 1 and 4 both have the same node degree of 2. However, they still have **different** neighborhood structures because **their neighbors have different node degrees.**



Node 1 has neighbors of degrees 2 and 3.  
Node 4 has neighbors of degrees 1 and 3.

# Local Neighborhood Structures

- We specifically consider **local neighborhood structures** around each node in a graph.
  - Example: Nodes 1 and 2 have the **same** neighborhood structure because **they are symmetric within the graph.**



Node 1 has neighbors of degrees 2 and 3.

Node 2 has neighbors of degrees 2 and 3.

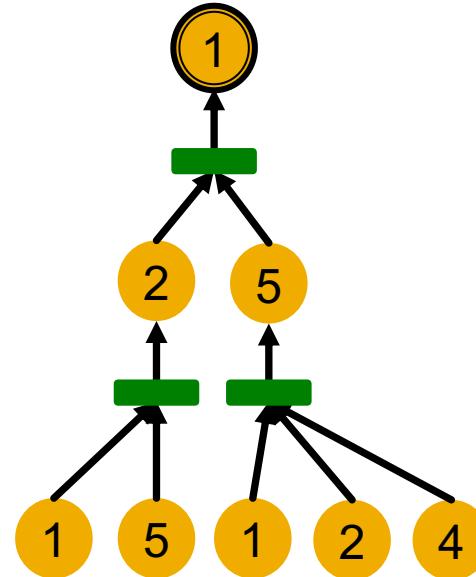
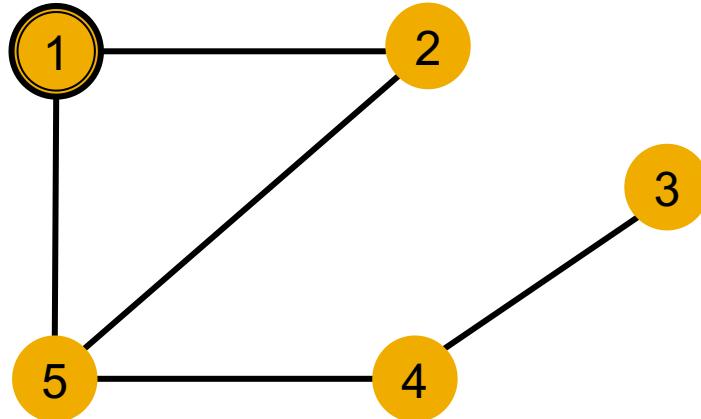
And even if we go a step deeper to 2<sup>nd</sup> hop neighbors, both nodes have the same degrees (Node 4 of degree 2)

# Local Neighborhood Structures

- **Key question:** Can GNN node embeddings distinguish different node's local neighborhood structures?
  - If so, when? If not, when will a GNN fail?
- **Next:** We need to understand how a GNN captures local neighborhood structures.
  - Key concept: Computational graph

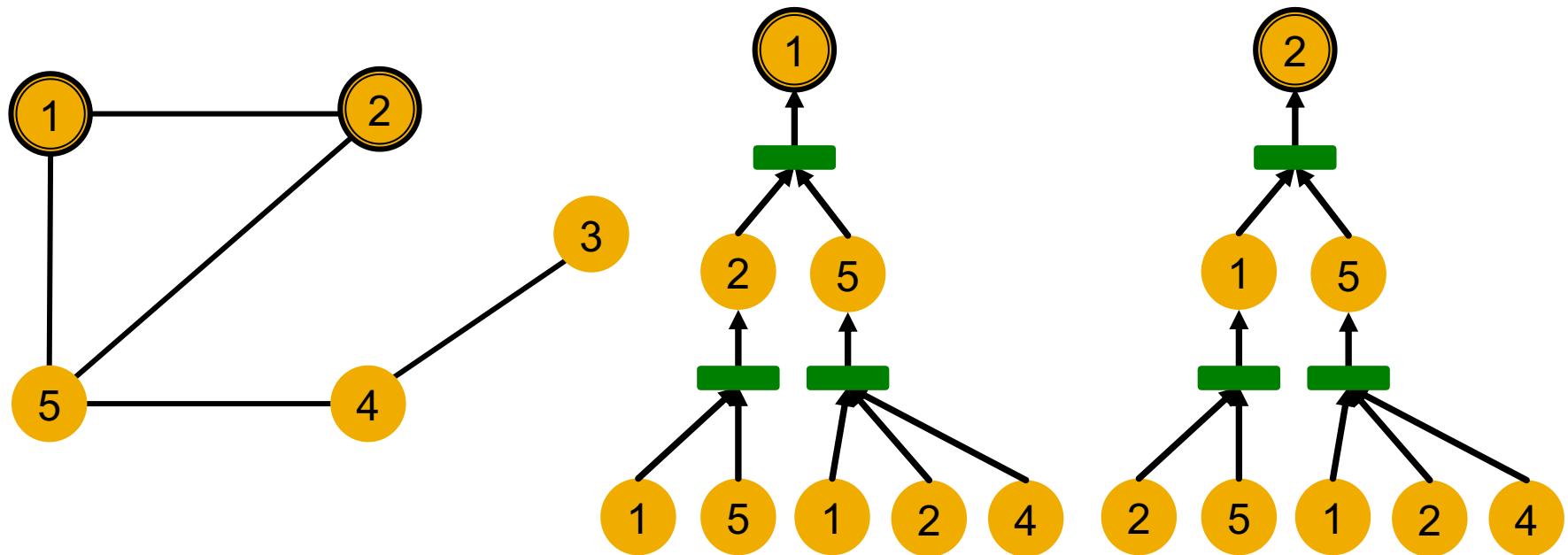
# Computational Graph (1)

- In each layer, a GNN aggregates neighboring node embeddings.
- A GNN generates node embeddings through a computational graph defined by the neighborhood.
  - Ex: Node 1's computational graph (2-layer GNN)



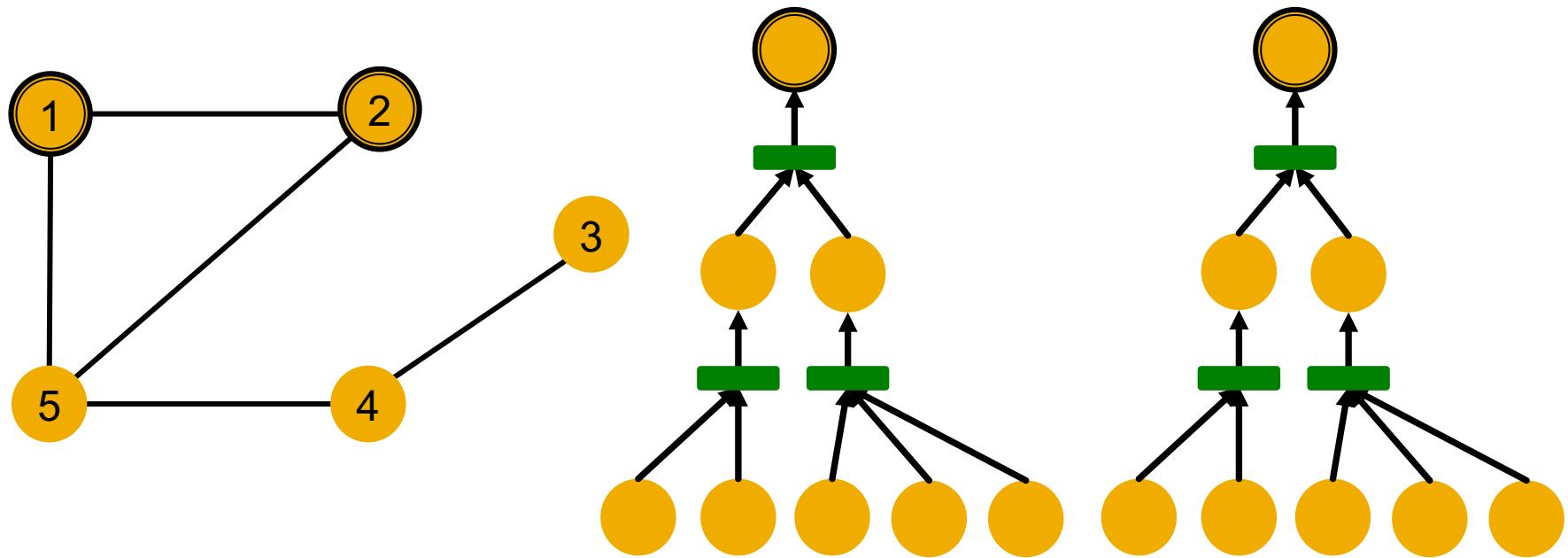
# Computational Graph (2)

- Ex: Nodes 1 and 2's computational graphs.



# Computational Graph (3)

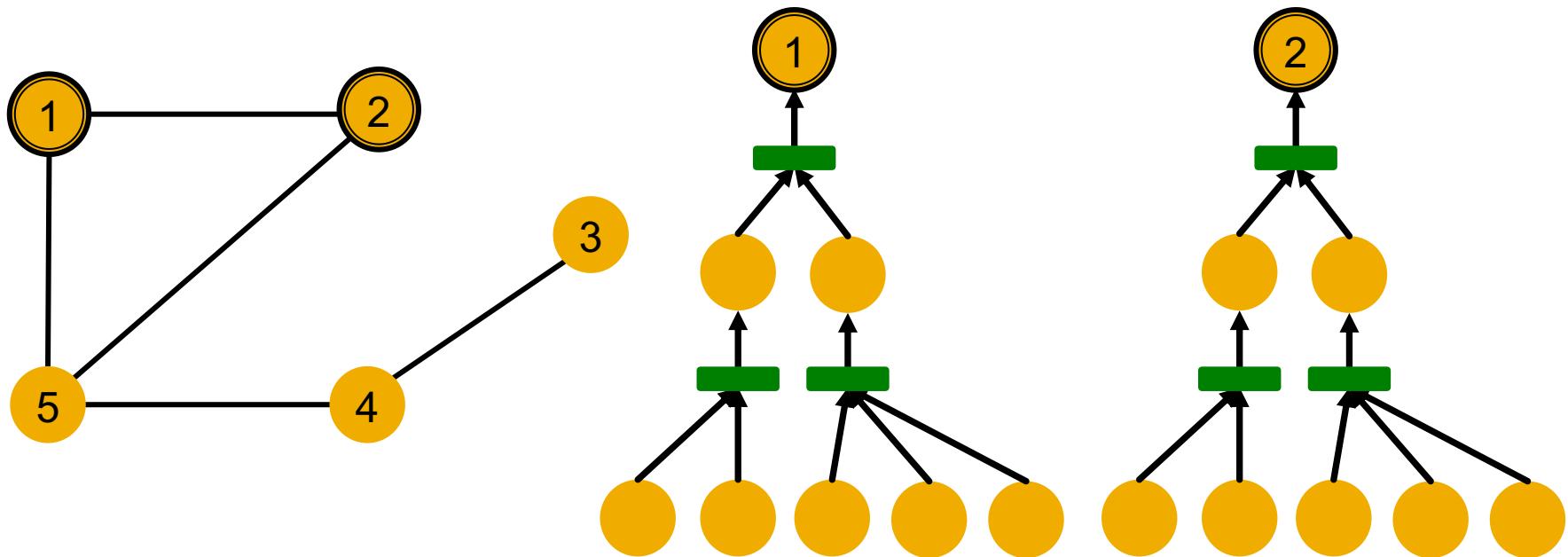
- Ex: Nodes 1 and 2's computational graphs.
- But GNN only sees node features (not IDs):



# Computational Graph (4)

- A GNN will generate the same embedding for nodes 1 and 2 because:
  - Computational graphs are the same.
  - Node features (colors) are identical.

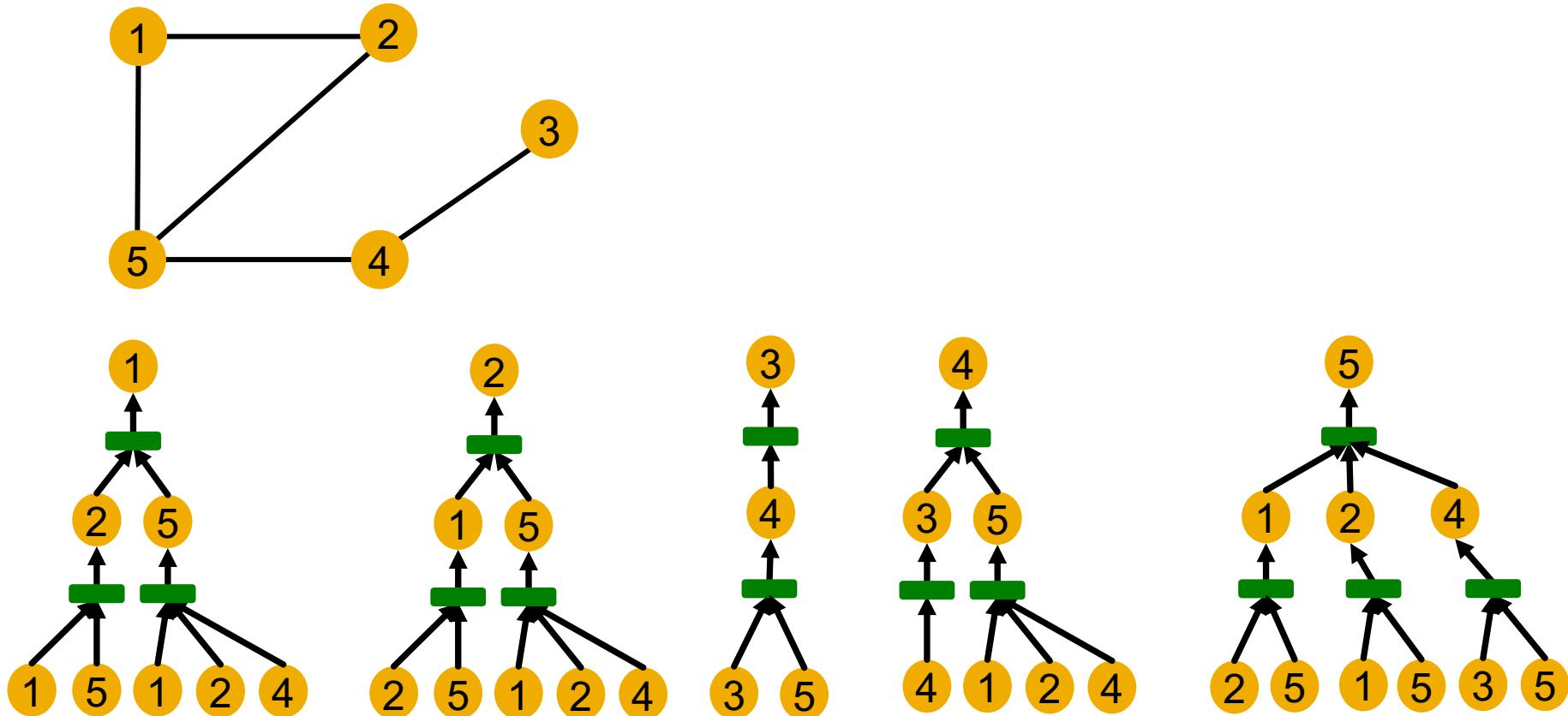
Note: GNN does not care about node ids, it just aggregates features vectors of different nodes.



GNN won't be able to distinguish nodes 1 and 2

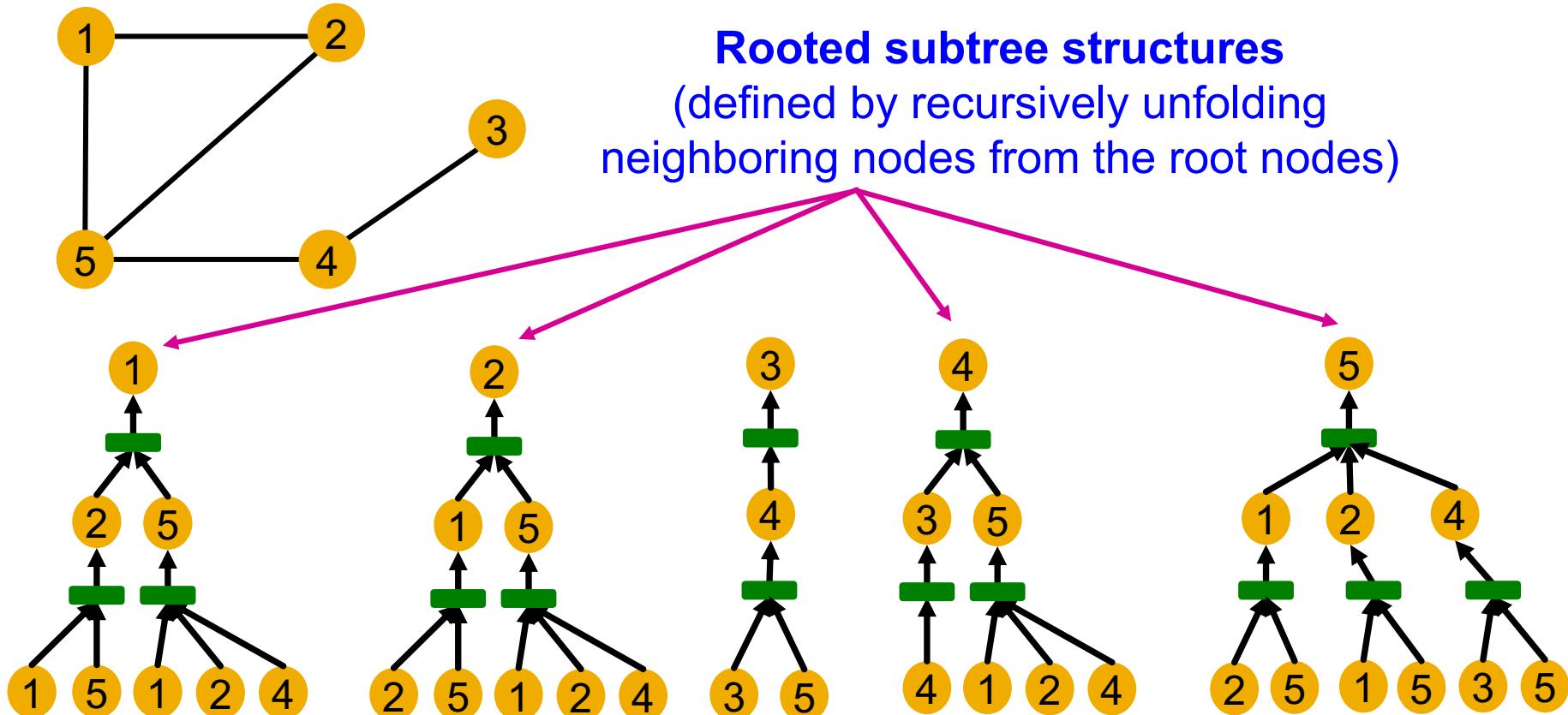
# Computational Graph

- In general, different local neighborhoods define different computational graphs



# Computational Graph

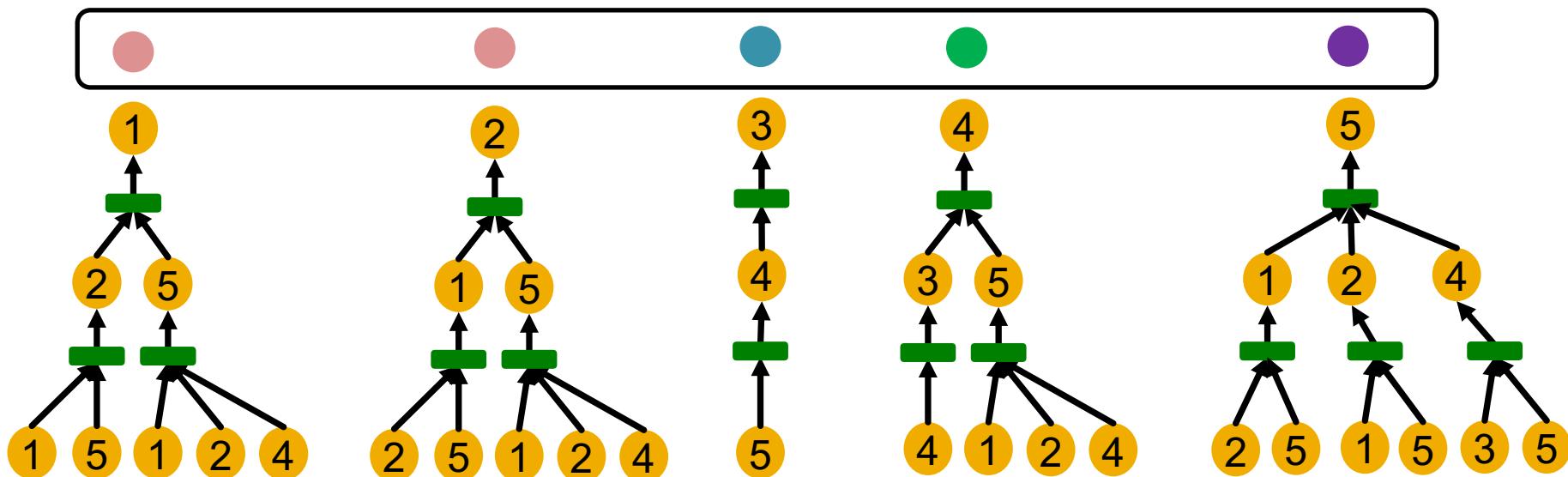
- Computational graphs are identical to **rooted subtree structures** around each node.



# Computational Graph

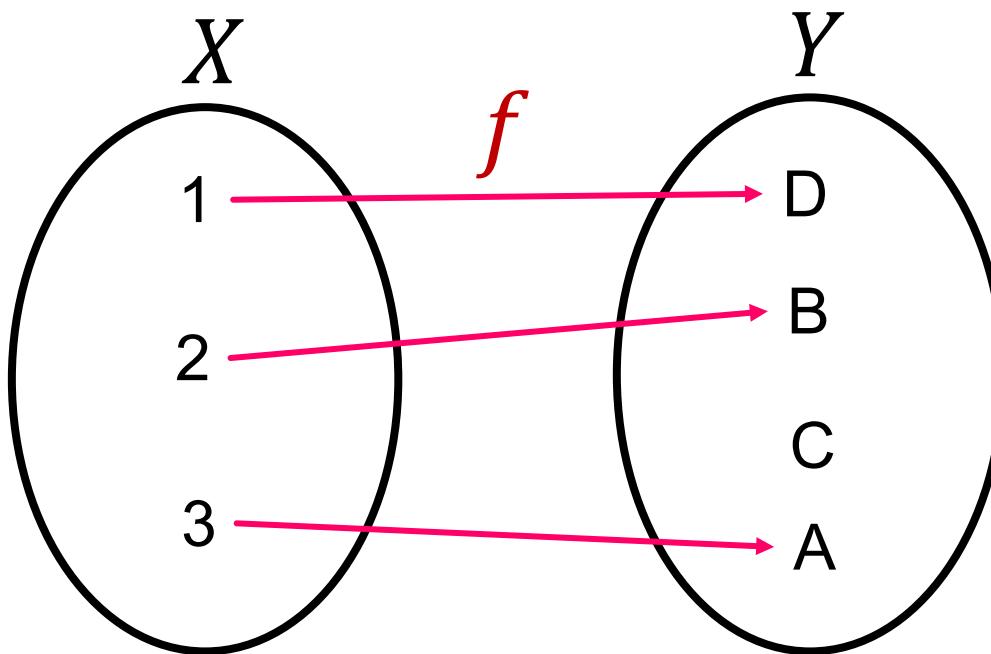
- GNN's node embeddings capture **rooted subtree structures**.
- Most expressive GNN maps different **rooted subtrees** into different node embeddings (represented by different colors).

Embedding



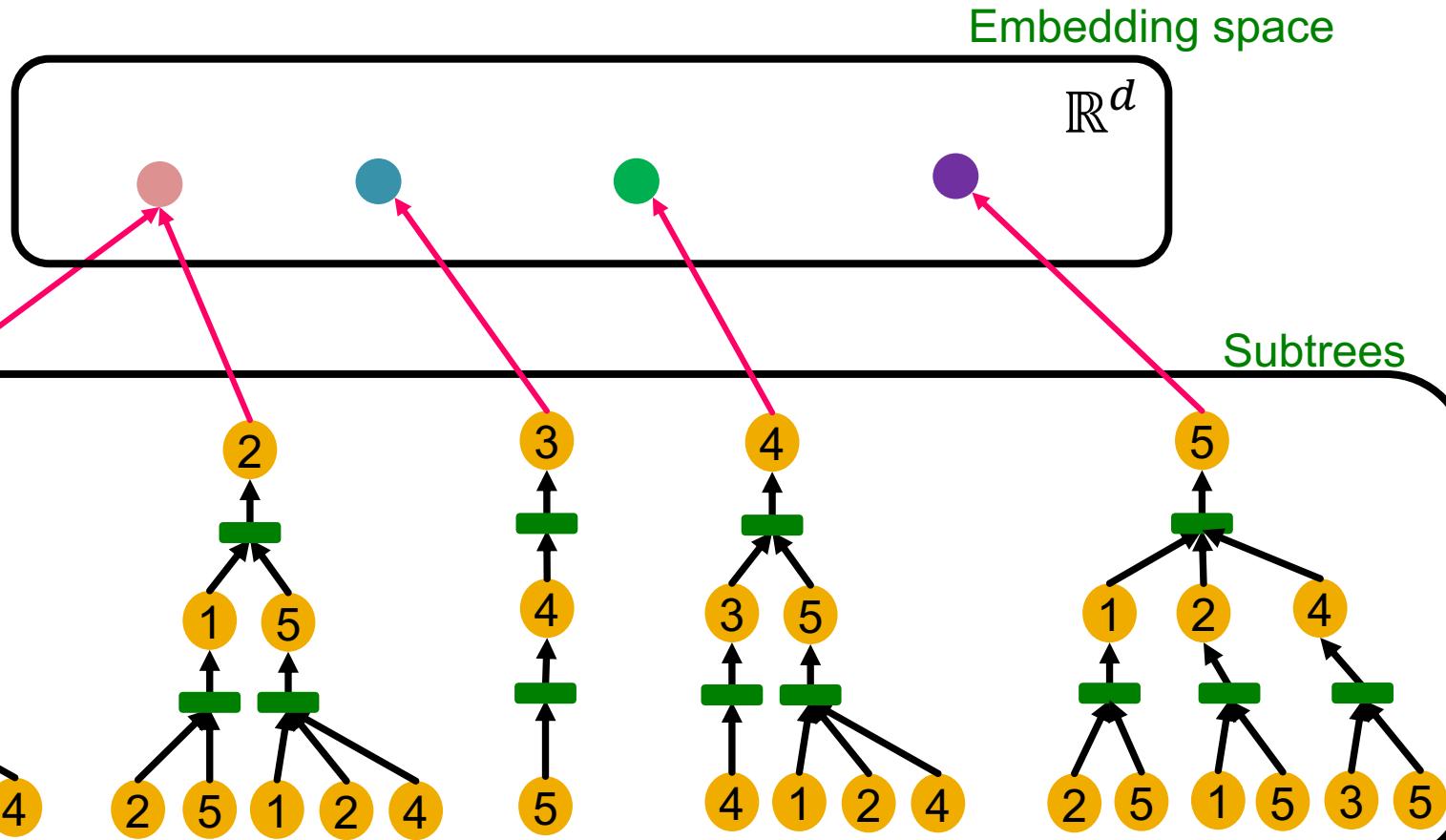
# Recall: Injective Function

- **Function**  $f: X \rightarrow Y$  is **injective** if it maps different elements into different outputs.
- **Intuition:**  $f$  retains all the information about input.



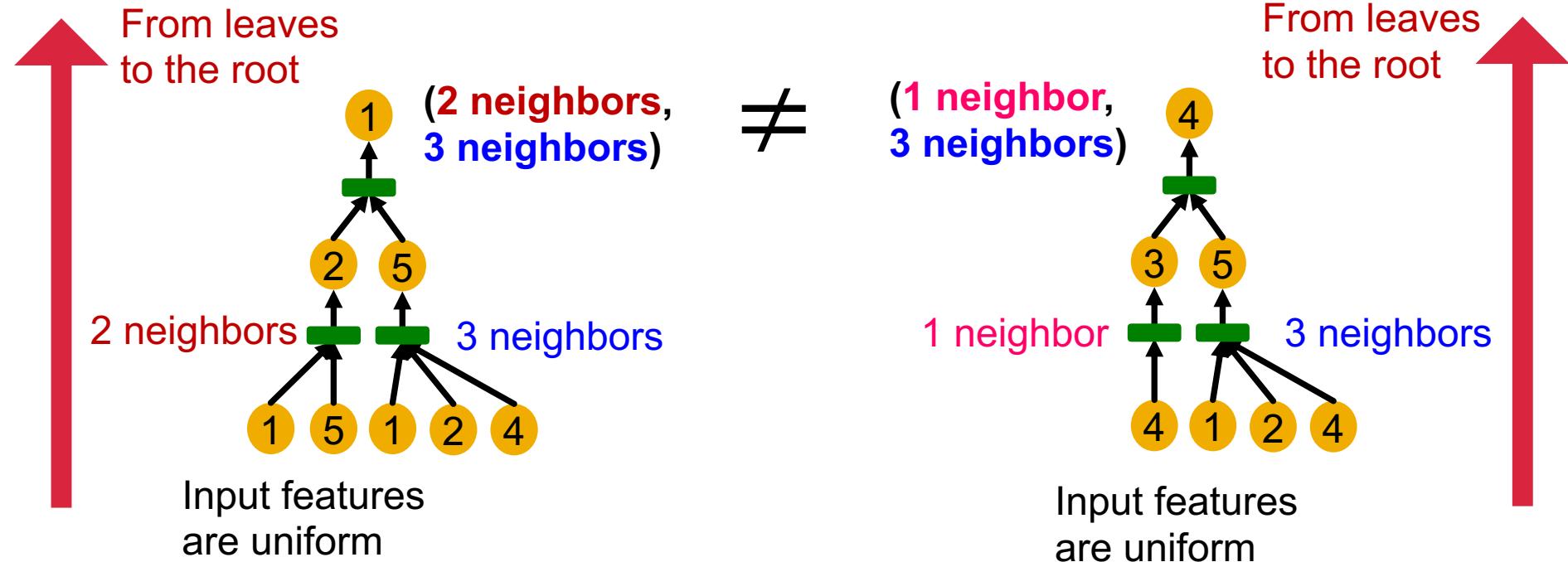
# How Expressive is a GNN?

- Most expressive GNN should map subtrees to the node embeddings **injectively**.



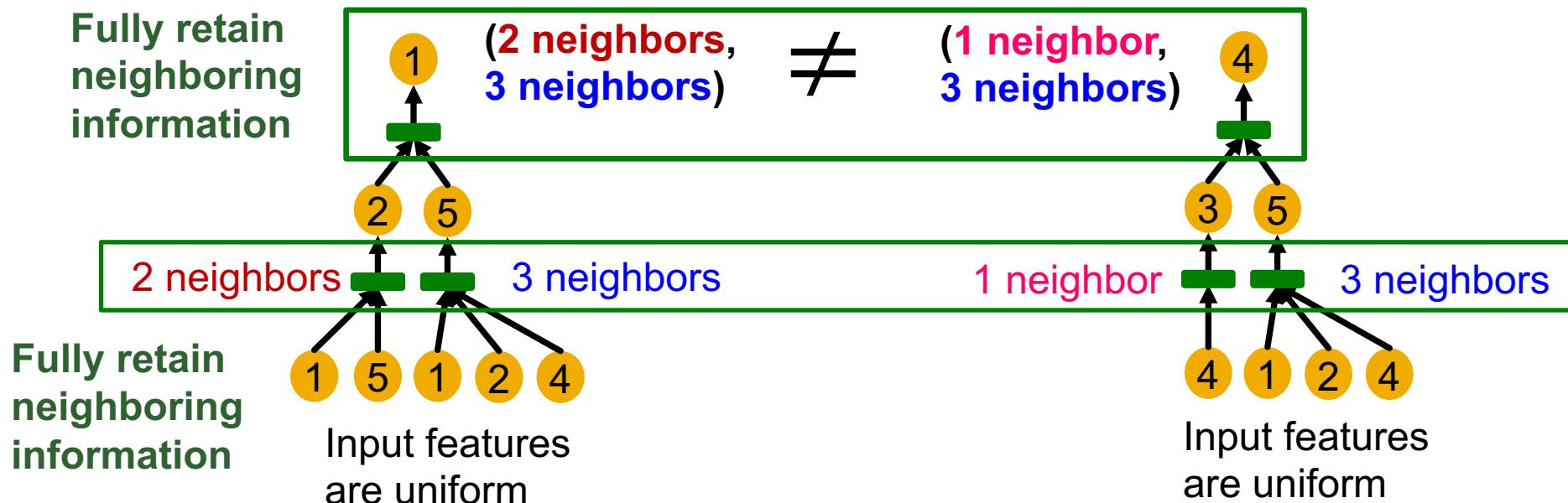
# How Expressive is a GNN?

- **Key observation:** Subtrees of the same depth can be recursively characterized from the leaf nodes to the root nodes.



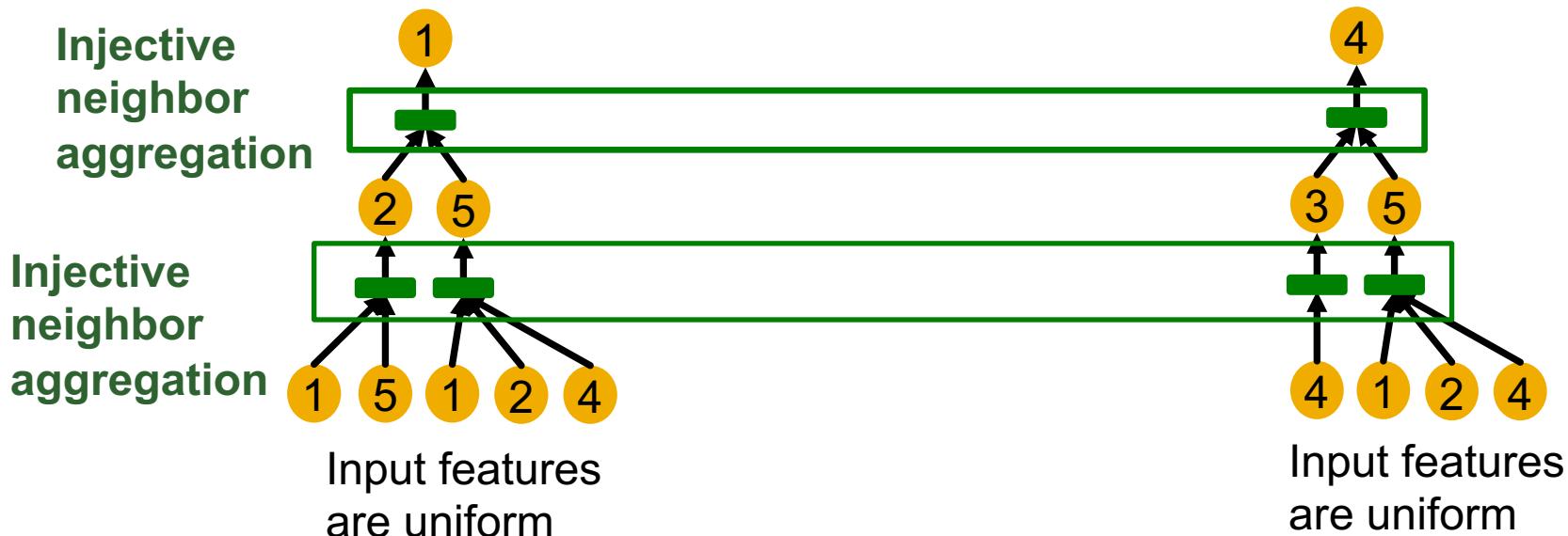
# How Expressive is a GNN?

- If each step of GNN's aggregation **can fully retain the neighboring information**, the generated node embeddings can distinguish different rooted subtrees.



# How Expressive is a GNN?

- In other words, most expressive GNN would use an **injective neighbor aggregation** function at each step.
  - Maps different neighbors to different embeddings.

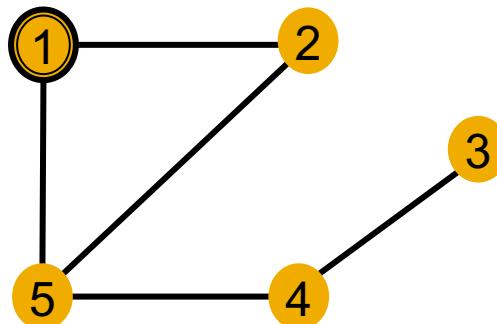


# How Expressive is a GNN?

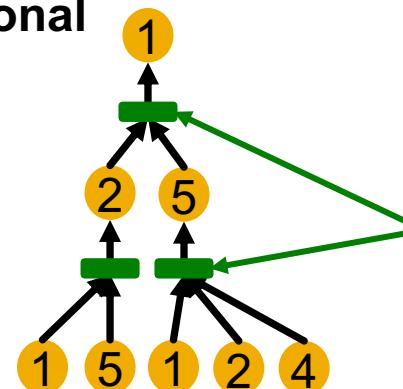
## ■ Summary so far

- To generate a node embedding, GNNs use a computational graph corresponding to a **subtree rooted around each node**.

Input graph



Computational graph  
= Rooted subtree



Using injective neighbor aggregation → distinguish different subtrees

- GNN can fully distinguish different subtree structures if **every step of its neighbor aggregation is injective**.

# **Stanford CS224W:** **Designing the Most Powerful** **Graph Neural Network**

CS224W: Machine Learning with Graphs

Jure Leskovec, Stanford University

<http://cs224w.stanford.edu>

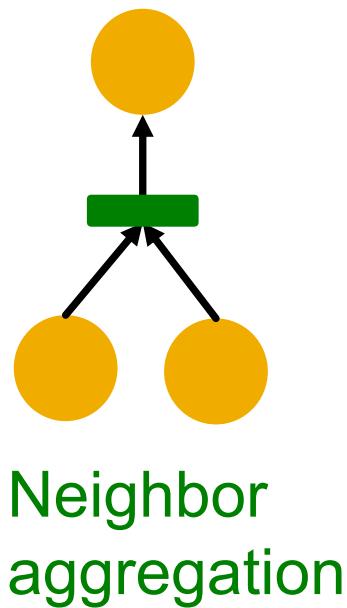


# Expressive Power of GNNs

- **Key observation:** Expressive power of GNNs can be characterized by that of neighbor aggregation functions they use.
  - A more expressive aggregation function leads to a more expressive GNN.
  - Injective aggregation function leads to the most expressive GNN.
- **Next:**
  - Theoretically analyze expressive power of aggregation functions.

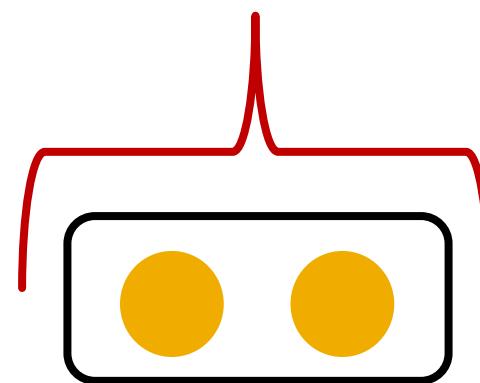
# Neighbor Aggregation

- **Observation:** Neighbor aggregation can be abstracted as **a function over a multi-set** (a set with repeating elements).



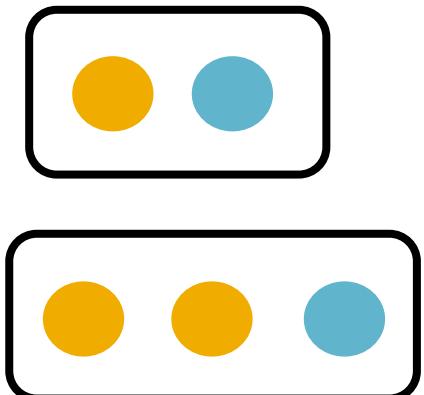
Equivalent

A double-headed grey arrow indicating equivalence between the graph representation on the left and the multi-set representation on the right.



Multi-set function

Examples of multi-set



Same color indicates the same features.

# Neighbor Aggregation

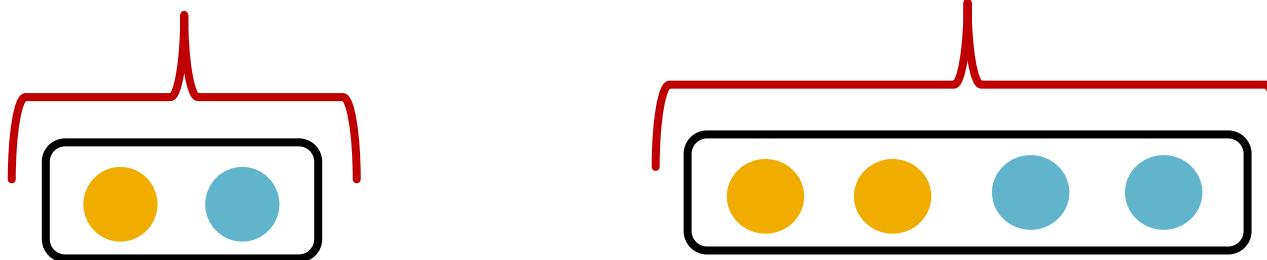
- **Next:** We analyze aggregation functions of two popular GNN models
  - **GCN** (mean-pool) [Kipf & Welling, ICLR 2017]
    - Uses **element-wise** mean pooling over neighboring node features
$$\text{Mean}(\{x_u\}_{u \in N(v)})$$
  - **GraphSAGE** (max-pool) [Hamilton et al. NeurIPS 2017]
    - Uses **element-wise** max pooling over neighboring node features
$$\text{Max}(\{x_u\}_{u \in N(v)})$$

# Neighbor Aggregation: Case Study

## ■ GCN (mean-pool) [Kipf & Welling ICLR 2017]

- Take **element-wise mean**, followed by linear function and ReLU activation, i.e.,  $\max(0, x)$ .
- **Theorem** [Xu et al. ICLR 2019]
  - GCN's aggregation function **cannot distinguish different multi-sets with the same color proportion**.

### Failure case



## ■ Why?

# Neighbor Aggregation

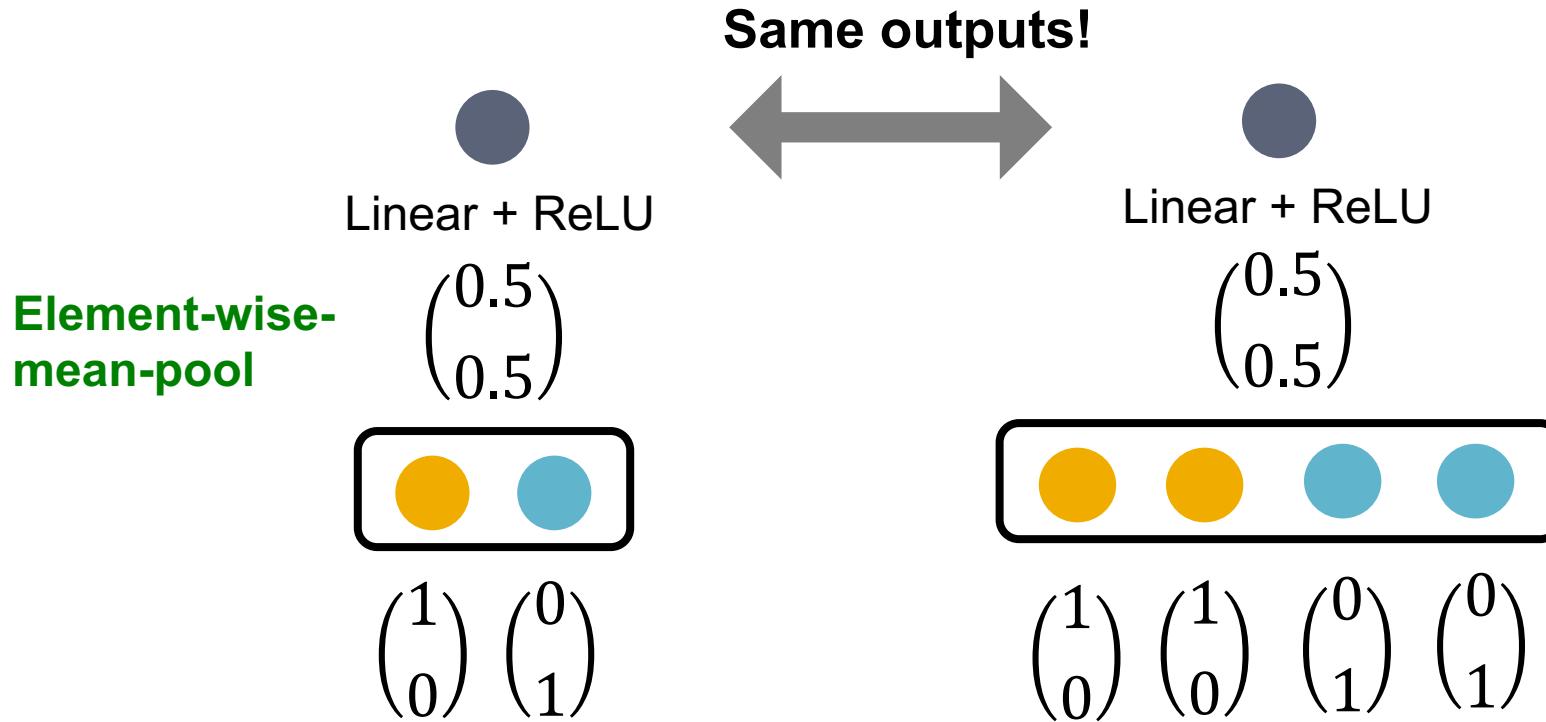
- For simplicity, we assume node features (colors) are represented by **one-hot encoding**.
  - Example: If there are two distinct colors:

$$\text{Yellow Circle} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \text{Blue Circle} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

- This assumption is sufficient to illustrate how GCN fails.

# Neighbor Aggregation: Case Study

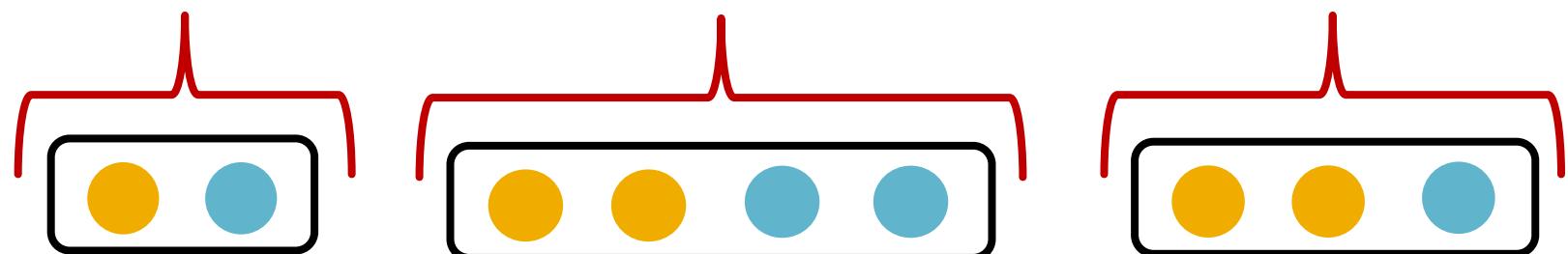
- **GCN (mean-pool)** [Kipf & Welling ICLR 2017]
  - Failure case illustration



# Neighbor Aggregation: Case Study

- **GraphSAGE (max-pool)** [Hamilton et al. NeurIPS 2017]
  - Apply an MLP, then take **element-wise max**.
  - **Theorem** [Xu et al. ICLR 2019]
    - GraphSAGE's aggregation function cannot distinguish different multi-sets with the same set of distinct colors.

## Failure case



- **Why?**

# Neighbor Aggregation: Case Study

- **GraphSAGE (max-pool)** [Hamilton et al. NeurIPS 2017]
  - Failure case illustration

The same outputs!

Element-wise-  
max-pool

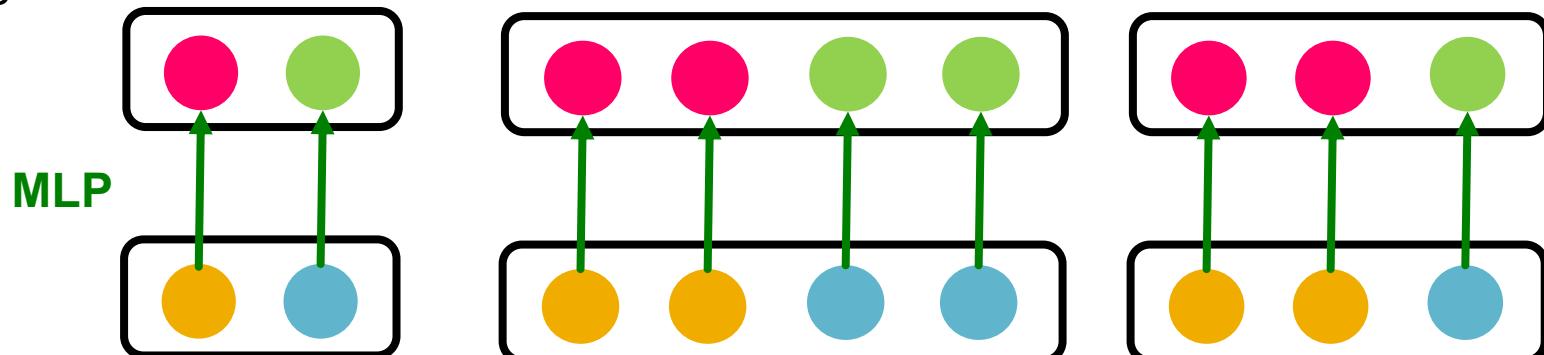
$$\begin{pmatrix} 1 \\ 1 \end{pmatrix} \longleftrightarrow \begin{pmatrix} 1 \\ 1 \end{pmatrix} \longleftrightarrow \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

For simplicity,  
assume the one-  
hot encoding  
after **MLP**.

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$



# Summary So Far

- We analyzed the **expressive power of GNNs.**
- **Main takeaways:**
  - Expressive power of GNNs can be characterized by that of the neighbor aggregation function.
  - Neighbor aggregation is a function over multi-sets (sets with repeating elements)
  - GCN and GraphSAGE's aggregation functions fail to distinguish some basic multi-sets; hence **not injective**.
  - Therefore, GCN and GraphSAGE are **not** maximally powerful GNNs.

# Designing Most Expressive GNNs

- Our goal: Design maximally powerful GNNs in the class of message-passing GNNs.
- This can be achieved by designing injective neighbor aggregation function over multisets.
- Here, we design a neural network that can model injective multiset function.

# Injective Multi-Set Function

**Theorem** [Xu et al. ICLR 2019]

Any injective multi-set function can be expressed as:

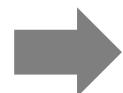
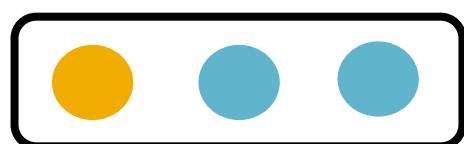
$$\text{Some non-linear function} \xrightarrow{\quad} \Phi \left( \sum_{x \in S} f(x) \right)$$

Some non-linear function

Sum over multi-set

Some non-linear function

$S$  : multi-set



$$\Phi \left( f(\text{yellow circle}) + f(\text{blue circle}) + f(\text{blue circle}) \right)$$

# Injective Multi-Set Function

**Proof Intuition:** [Xu et al. ICLR 2019]

$f$  produces one-hot encodings of colors. Summation of the one-hot encodings retains all the information about the input multi-set.

$$\Phi \left( \sum_{x \in S} f(x) \right)$$

Example:  $\Phi \left[ f([\text{Yellow}]) + f([\text{Blue}]) + f([\text{Blue}]) \right]$

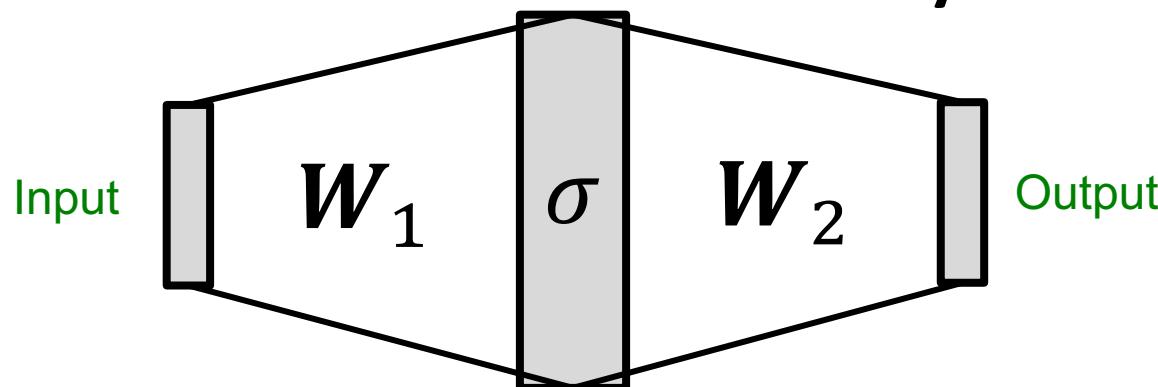
One-hot  $\begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$

# Universal Approximation Theorem

- How to model  $\Phi$  and  $f$  in  $\Phi(\sum_{x \in S} f(x))$  ?
- We use a Multi-Layer Perceptron (MLP).
- **Theorem: Universal Approximation Theorem**

[Hornik et al., 1989]

- 1-hidden-layer MLP with sufficiently-large hidden dimensionality and appropriate non-linearity  $\sigma(\cdot)$  (including ReLU and sigmoid) can **approximate any continuous function to an arbitrary accuracy**.



# Injective Multi-Set Function

- We have arrived at a **neural network** that can model any injective multiset function.

$$\text{MLP}_\Phi \left( \sum_{x \in S} \text{MLP}_f(x) \right)$$

- In practice, MLP hidden dimensionality of 100 to 500 is sufficient.

# Most Expressive GNN

- **Graph Isomorphism Network (GIN)** [Xu et al. ICLR 2019]

- Apply an MLP, element-wise sum, followed by another MLP.

$$\text{MLP}_\Phi \left( \sum_{x \in S} \text{MLP}_f(x) \right)$$

- **Theorem** [Xu et al. ICLR 2019]
  - GIN's neighbor aggregation function is injective.
- **No failure cases!**
- **GIN is THE most expressive GNN in the class of message-passing GNNs we have introduced!**

# Full Model of GIN

- So far: We have described the neighbor aggregation part of GIN.
- We now describe the full model of GIN by relating it to **WL graph kernel** (traditional way of obtaining graph-level features).
  - We will see how GIN is a “neural network” version of the WL graph kernel.

# Relation to WL Graph Kernel

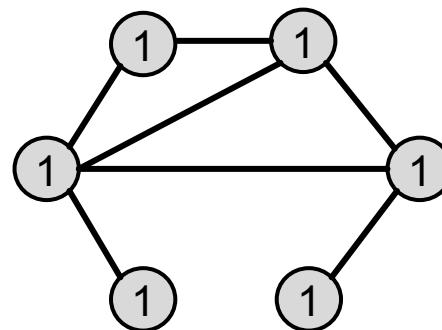
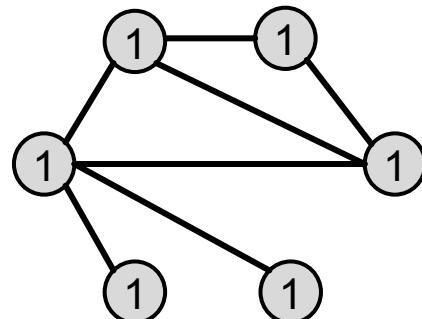
**Recall: Color refinement algorithm in WL kernel.**

- **Given:** A graph  $G$  with a set of nodes  $V$ .
    - Assign an initial color  $c^{(0)}(\nu)$  to each node  $\nu$ .
    - Iteratively refine node colors by
- $$c^{(k+1)}(\nu) = \text{HASH} \left( c^{(k)}(\nu), \{c^{(k)}(u)\}_{u \in N(\nu)} \right),$$
- where HASH maps different inputs to different colors.
- After  $K$  steps of color refinement,  $c^{(K)}(\nu)$  summarizes the structure of  $K$ -hop neighborhood

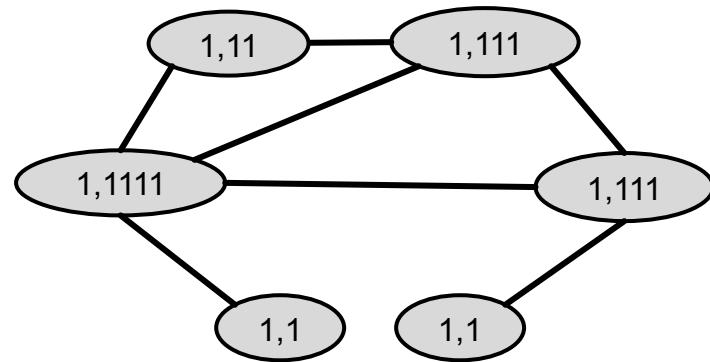
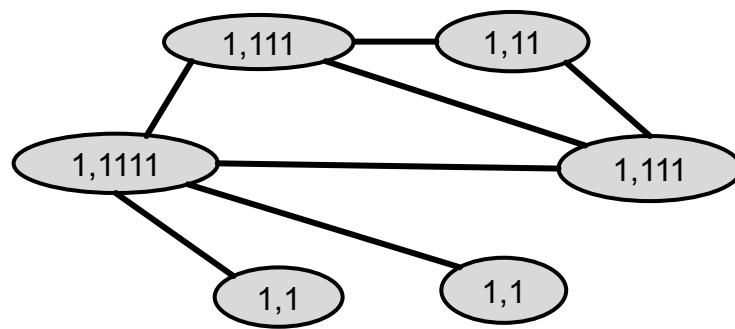
# Color Refinement (1)

Example of color refinement given two graphs

- Assign initial colors



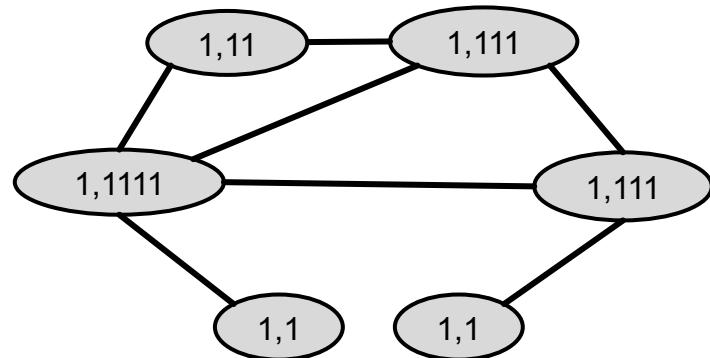
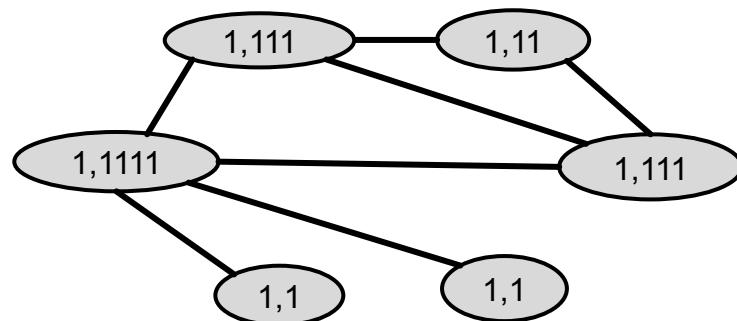
- Aggregate neighboring colors



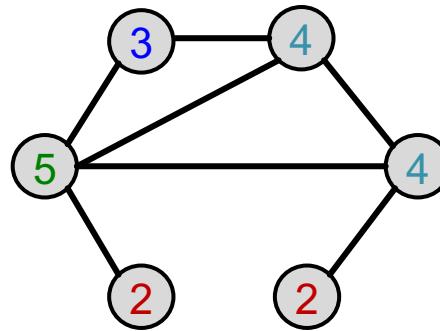
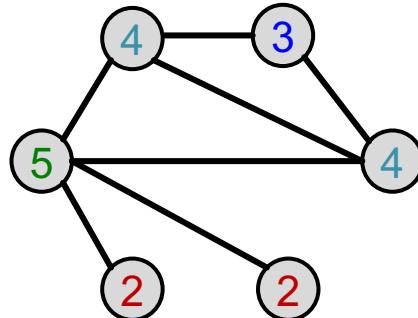
# Color Refinement (2)

## Example of color refinement given two graphs

- Aggregated colors:



- Injectively HASH the aggregated colors



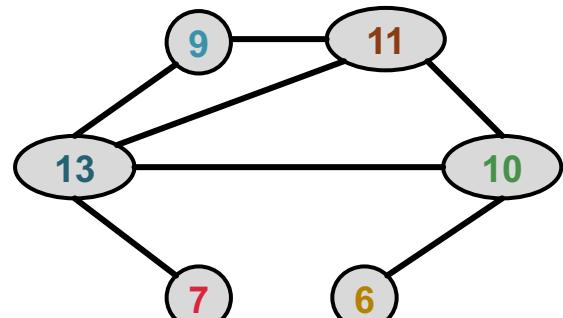
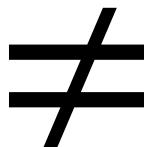
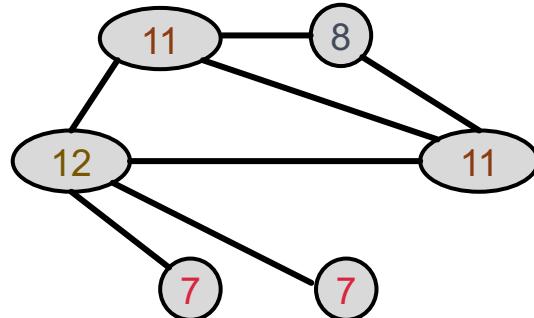
HASH table: **Injective!**

1,1	-->	2
1,11	-->	3
1,111	-->	4
1,1111	-->	5

# Color Refinement (3)

## Example of color refinement given two graphs

- Process continues until a stable coloring is reached
- Two graphs are considered **isomorphic** if they have the same set of colors.



# The Complete GIN Model

- GIN uses a **neural network** to model the injective HASH function.

$$c^{(k+1)}(v) = \text{HASH} \left( c^{(k)}(v), \{c^{(k)}(u)\}_{u \in N(v)} \right)$$

- Specifically, we will model the injective function over the tuple:

$$(c^{(k)}(v), \{c^{(k)}(u)\}_{u \in N(v)})$$

Root node  
features

Neighboring  
node colors

# The Complete GIN Model

**Theorem** (Xu et al. ICLR 2019)

Any injective function over the tuple

Root node  
feature

$(c^{(k)}(v), \{c^{(k)}(u)\}_{u \in N(v)})$

Neighboring  
node features

can be modeled as

$$\text{MLP}_\Phi \left( (1 + \epsilon) \cdot \text{MLP}_f(c^{(k)}(v)) + \sum_{u \in N(v)} \text{MLP}_f(c^{(k)}(u)) \right)$$

where  $\epsilon$  is a learnable scalar.

# The Complete GIN Model

- If input feature  $c^{(0)}(v)$  is represented as one-hot, **direct summation is injective.**

Example:  $\Phi \left[ \begin{array}{c} \text{Yellow circle} \\ + \\ \text{Blue circle} \\ + \\ \text{Blue circle} \end{array} \right]$

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

- We only need  $\Phi$  to ensure the injectivity.

$$\text{GINConv} \left( c^{(k)}(v), \{c^{(k)}(u)\}_{u \in N(v)} \right) = \text{MLP}_\Phi \left( (1 + \epsilon) \cdot c^{(k)}(v) + \sum_{u \in N(v)} c^{(k)}(u) \right)$$

Root node features  
Neighboring node features

This MLP can provide “one-hot” input feature for the next layer.

# The Complete GIN Model

- **GIN's node embedding updates**
- **Given:** A graph  $G$  with a set of nodes  $V$ .
  - Assign an **initial vector**  $c^{(0)}(\nu)$  to each node  $\nu$ .
  - Iteratively update node vectors by

$$c^{(k+1)}(\nu) = \text{GINConv} \left( \left\{ c^{(k)}(\nu), \left\{ c^{(k)}(u) \right\}_{u \in N(\nu)} \right\} \right),$$

Differentiable color HASH function

where **GINConv** maps different inputs to different embeddings.

- After  $K$  steps of GIN iterations,  $c^{(K)}(\nu)$  summarizes the structure of  $K$ -hop neighborhood.

# GIN and WL Graph Kernel

- GIN can be understood as differentiable neural version of the WL graph Kernel:

	Update target	Update function
WL Graph Kernel	Node colors (one-hot)	HASH
GIN	Node embeddings (low-dim vectors)	GINConv

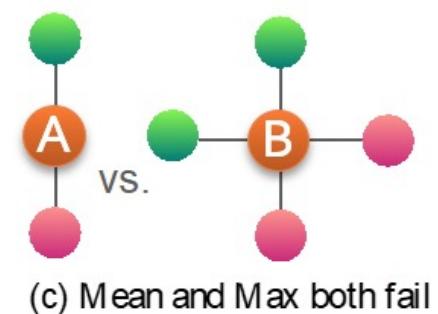
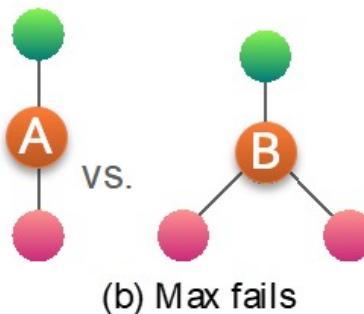
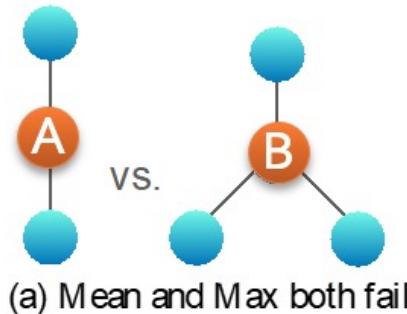
- Advantages of GIN over the WL graph kernel are:
  - Node embeddings are **low-dimensional**; hence, they can capture the fine-grained similarity of different nodes.
  - Parameters of the update function can be **learned for the downstream tasks**.

# Expressive Power of GIN

- Because of the relation between GIN and the WL graph kernel, their expressive power is exactly the same.
  - If two graphs can be distinguished by GIN, they can be also distinguished by the WL kernel, and vice versa.
- How powerful is this?
  - WL kernel has been both theoretically and empirically shown to distinguish most of the real-world graphs [Cai et al. 1992].
  - Hence, GIN is also powerful enough to distinguish most of the real graphs!

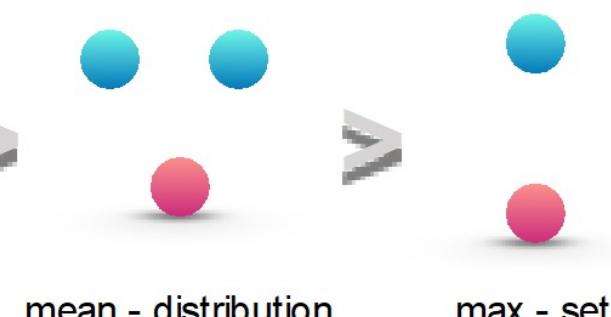
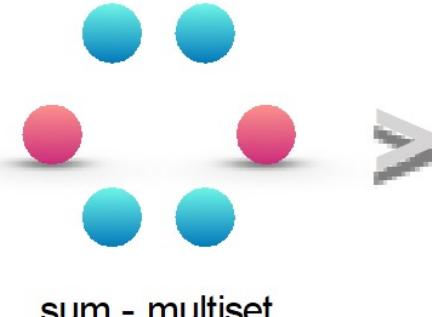
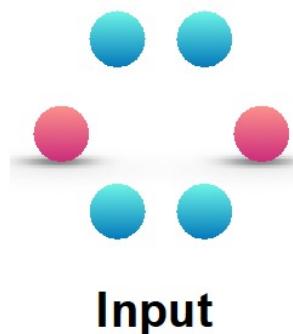
# Discussion: The Power of Pooling

Failure cases for mean and max pooling:



Colors represent feature values

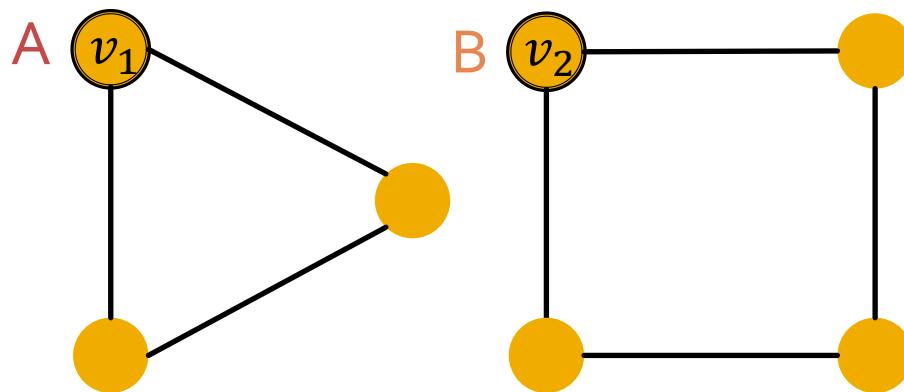
Ranking by discriminative power:



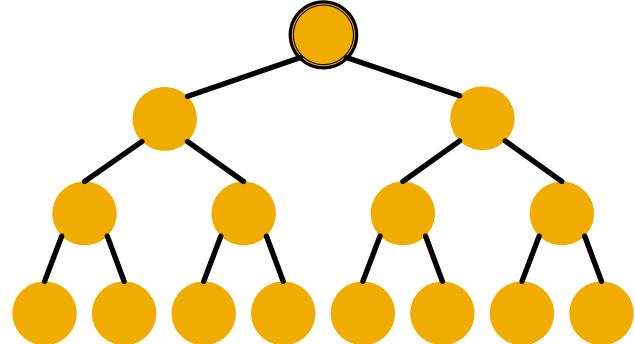
# Improving GNNs' Power

## ■ Can the expressive power of GNNs be improved?

- There are basic graph structures that existing GNN framework cannot distinguish, such as difference in cycles.



Computational graphs  
for nodes  $v_1$  and  $v_2$ :



- GNNs' expressive power **can be improved** to resolve the above problem. [You et al. AAAI 2021, Li et al. NeurIPS 2020]
  - Stay tuned for **Lectures 13 and 14: Advanced Topics in GNNs, Graph Transformers**

# Summary of the Lecture

- We design a neural network that can model an **injective multi-set function**.
- We use the neural network for neighbor aggregation function and arrive at **GIN---the most expressive GNN model**.
- The key is to use **element-wise sum pooling**, instead of mean-/max-pooling.
- GIN is closely related to the WL graph kernel.
- Both GIN and WL graph kernel can distinguish most of the real graphs!

# Stanford CS224W: When Things Don't Go As Planned

CS224W: Machine Learning with Graphs

Jure Leskovec, Stanford University

<http://cs224w.stanford.edu>



# General Tips

- **Data preprocessing is important:**
  - Node attributes can vary a lot! Use **normalization**
    - E.g. probability ranges  $(0,1)$ , but some inputs could have much larger range, say  $(-1000, 1000)$
- **Optimizer:** ADAM is relatively robust to learning rate
- **Activation function**
  - ReLU activation function often works well
  - Other good alternatives: [LeakyReLU](#), [PReLU](#)
  - No activation function at your output layer
  - Include bias term in every layer
- **Embedding dimensions:**
  - 32, 64 and 128 are often good starting points

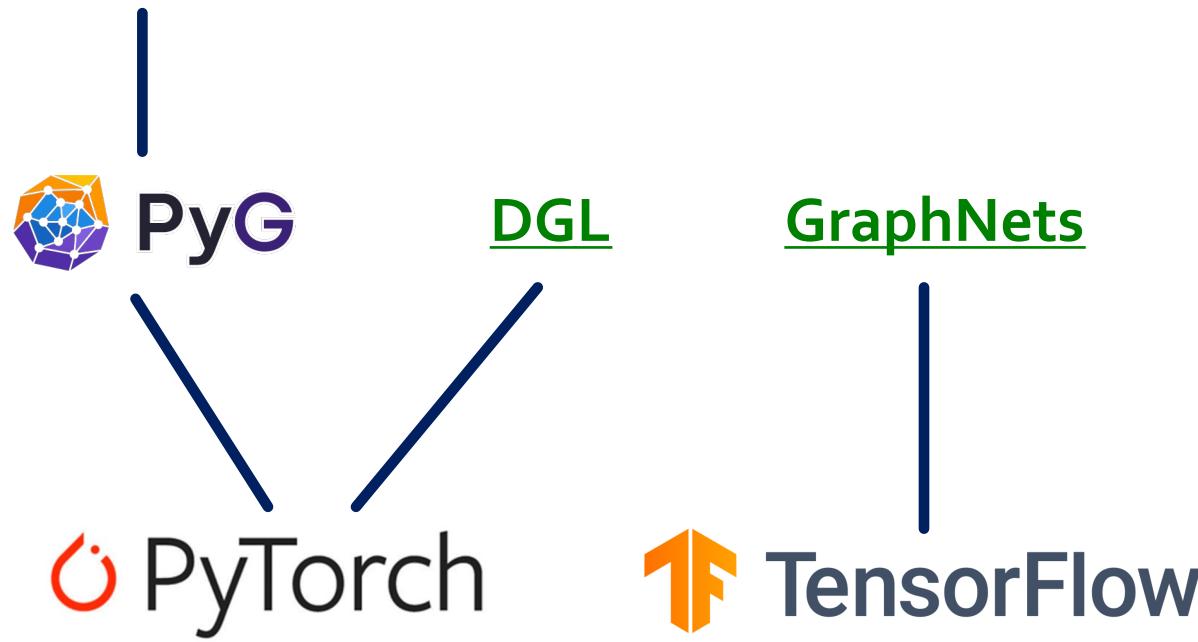
# Debugging Deep Networks

- **Debug issues:** Loss/accuracy not converging during training
  - Check pipeline (e.g. in PyTorch we need zero\_grad)
  - Adjust hyperparameters such as learning rate
  - Pay attention to weight parameter initialization
  - Scrutinize loss function!
- **Important for model development:**
  - **Overfit on (part of) training data:**
    - With a small training dataset, loss should be essentially close to 0, with an expressive neural network
  - **Monitor the training & validation loss curve**

# Resources on Graph Neural Networks

## GraphGym:

Easy and flexible end-to-end GNN pipeline  
based on PyTorch Geometric (PyG)



**GNN frameworks:**  
Implements a variety  
of GNN architectures

Auto-differentiation frameworks

# Resources on Graph Neural Networks

## Tutorials and overviews:

- Relational inductive biases and graph networks (Battaglia et al., 2018)
- Representation learning on graphs: Methods and applications (Hamilton et al., 2017)

## Attention-based neighborhood aggregation:

- Graph attention networks (Hoshen, 2017; Velickovic et al., 2018; Liu et al., 2018)

## Embedding entire graphs:

- Graph neural nets with edge embeddings (Battaglia et al., 2016; Gilmer et. al., 2017)
- Embedding entire graphs (Duvenaud et al., 2015; Dai et al., 2016; Li et al., 2018) and graph pooling (Ying et al., 2018, Zhang et al., 2018)
- Graph generation and relational inference (You et al., 2018; Kipf et al., 2018)
- How powerful are graph neural networks(Xu et al., 2017)

## Embedding nodes:

- Varying neighborhood: Jumping knowledge networks (Xu et al., 2018), GeniePath (Liu et al., 2018)
- Position-aware GNN (You et al. 2019)

## Spectral approaches to graph neural networks:

- Spectral graph CNN & ChebNet (Bruna et al., 2015; Defferrard et al., 2016)
- Geometric deep learning (Bronstein et al., 2017; Monti et al., 2017)

## Other GNN techniques:

- Pre-training Graph Neural Networks (Hu et al., 2019)
- GNNExplainer: Generating Explanations for Graph Neural Networks (Ying et al., 2019)