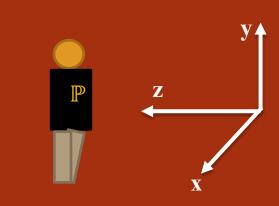


A Graph-based Algorithm to Video Stitching

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MOTIVATION

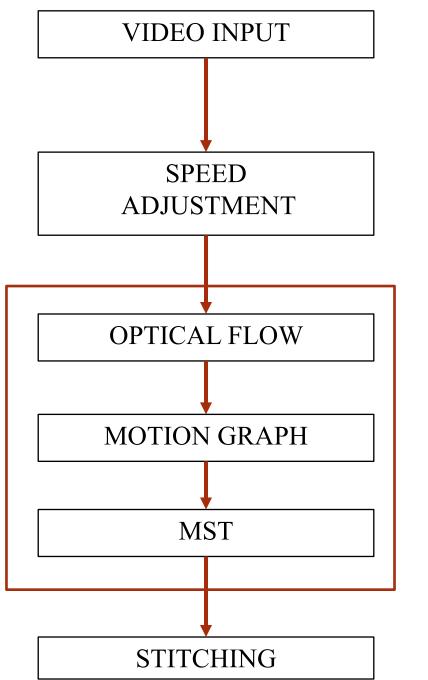
- Portable device panorama allows people to capture their favorite scenes and moments on a single canvas.
- Taking a collection of pictures for panorama is both harder to manage and more error-prone. Video input is more convenient and robust to client-side risks, such as photos too distinct to perform panorama.
- The majority of current video stitching models either 1) relies heavily on hardware and camera position, or 2) overlook the advantage of structrual similarity between adjacent frames.

RELATED WORK

Brown and Lowe[1] developed a multiple-image stitching algorithm that uses bundle adjustment to avoid cumulative distortion and blur, unlike a baseline model that iteratively joins adjacent images that does not guarantee structrual similarity. Conceptually speaking, the bundle adjustor picks the next best match of existing bundle, calibrate its perspective, and stitch it into the bundle.

However, with video inputs, we can develop a more efficient bundle adjustor (compared to the proposed non-linear least square minimization) by tracking camera movement. In particular, we observe that frames with similar camera position should inherintly be each other's best match. Therefore, we set out to reconstruct the camera movement in a graph-based algorithm.

ALGORITHM OVERVIEW



Speed Adjustment

Users may not rotate their camera at a uniform speed, therefore the first challenge is to selecting frames that accommodate varying camera moving speed. We propose an algorithm such that the probability of selecting one frame is proportional to the camera moving speed at that frame.

Graph-based stitching

The algorithm uses optical flow to calculate estimated camera movement between each adjacent selected frame. An undirected graph is constructed to reflect such camera movement, in which the edge weight reflects the Euclidean distance of x- and yaxis camera movement between two frames. Minimum Spanning Tree (MST) algorithm thus produces a stitching order that conceptually reflect the bundle adjustment method[1].

SPEED ADJUSTMENT

The speed adjustment algorithm treats the selection of each frame as a **Bernoulli Trial** with

$$P(X_i = 1) = c T_i,$$

And set

$$E[\Sigma X_i] = N$$

Where $X_i = 1$ means select frame, T_i is the estimated camera moving speed at that frame, and *N* is the number of frames we want to extract.

Solving for *c* gives the speed-adjusted selection. Running the algorithm on a speedvariant video produces a reasonable panorama, while uniform frame extraction fails to stitch many frames.

Results on Same Video Input



Graph Panorama without Speed Adjustment (Failed to stitch frames to the right.)



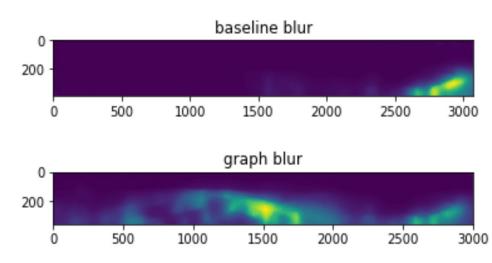
Graph Panorama with Speed Adjustment

EVALUATION

SAMPLE RESULT



Graph-based Result



graph blur score: 13.02%

METRICS

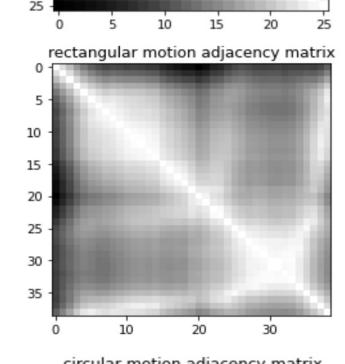
We adopt blurriness as an estimation of the effect of graph-based algorithm because, as Brown and Lowe suggested, efficient bundle adjustment should remove blurriness and distortion.

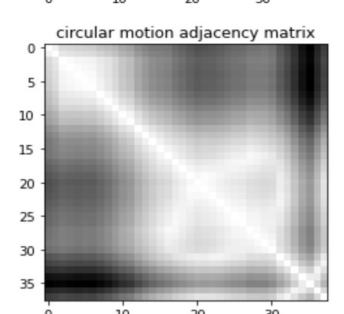
DISCUSSIONS

- Testified that video stitching could leverage the sequential content similarity between frames to produce better results and potentially more efficient algorithms
- Graph-based algorithms can implement the concept of bundle adjustment with lower complexity.
- Exist alternatives to optical flow that could be explored. Improvement could be made to calculate more accurate and apprehensive camera movements
- Exist alternatives to MST calculation. One immediate possibility is maxflow/min-cut algorithm that partition the graph into most structrually similar regions.

GRAPH-BASED STITCHING

line motion adjacency matrix 10 15 rectangular motion adjacency matrix





Optical Flow

- Optical Flow produces a 2D vector that describe keypoiny movement between two images
- Assuming still scene, keypoint movement suggests camera motion

Motion Graph

• We calculate x-axis displacement by

$$\mathbb{D}_{x}(m,n) = \sum_{i=m}^{n-1} \Delta x_{i,i+1}$$

and same for y-axis, assuming m > n WLOG

- Graph node is each frame, and edge is the Euclidean distance using previous equation
- The graph is tested with three typical camera movements:
- 1) Horizonta: camera does not move up or down
- 2) Rectangular: move right, move up, move left
- 3) Circular: camera rotates around z-axis
- As shown in the left, the adjacency matrix reflect information about the actual camera movement.

Minimum Spanning Tree

As each edge reflect the estimation of camera distance from two node frames, the MST algorithm finds a sequence to stitch all selected frames so that frames are stitched with most similar "best matches"

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