Jiawei Huang

Email GitHub Homepage Google Scholar

EDUCATION

ETH Zurich Sept. 2022 – Now

Ph.D. Student in Computer Science

University of Illinois at Urbana-Champaign

Jan. 2021 - Aug. 2022

Ph.D. Student in Computer Science

Awarded by Master's Degree in Computer Science on Aug. 2022

(Ph.D. study was interrupted because of visa issue (P.P. 10043).)

Beihang University, Beijing, China

Sept. 2015 - July 2019

Undergraduate Student in Computer Science

Awarded by Bachelor's Degree in Computer Science on July 2019

INTERNSHIP EXPERIENCES

Reinforcement Learning | University of Illinois at Urbana-Champaign | Visiting Scholar | July 2019 – July 2020

- Doubly Robust Policy Gradient Method
- Offline Reinforcement Learning

Reinforcement Learning + Robotics | Tecent Robotics-X Lab | Research Intern | Aug. 2020 – Jan. 2021

Robot Motion Imitation with Reinforcement Learning and Imitation Learning

Reinforcement Learning | Microsoft Research Asia | Research Intern | Summer 2021

- > Deployment-Efficient Reinforcement Learning
- Reinforcement Learning with Tiered Structure

PUBLICATION

- 1. [Preprint] Robust Knowledge Transfer in Tiered Reinforcement Learning (arXiv)

 Jiawei Huang, Niao He
- 2. [NeurIPS 2022] Tiered Reinforcement Learning: Pessimism in the Face of Uncertainty and Constant Regret (arXiv)

Jiawei Huang, Li Zhao, Tao Qin, Wei Chen, Nan Jiang, Tie-Yan Liu

3. [ICML 2022 Long Oral] A Minimax Learning Approach to Off-Policy Evaluation in Confounded POMDP (arXiv)

Chengchun Shi, Masatoshi Uehara, Jiawei Huang, Nan Jian

4. [ICLR 2022 Spotlight] Towards Deployment-Efficient Reinforcement Learning: Lower Bound and Optimality (OpenReview)

Jiawei Huang, Jinglin Chen, Li Zhao, Tao Qin, Nan Jiang, Tie-Yan Liu

- 5. [AISTATS 2022] On the Convergence Rate of Density-Ratio Based Off-Policy Policy Gradient (arXiv) Jiawei Huang, Nan Jiang
- 6. [NeurIPS 2020] Minimax Confidence Interval for Off-Policy Evaluation and Policy Optimization (arXiv)
 Nan Jiang, Jiawei Huang

- 7. [ICML 2020] From Importance Sampling to Doubly Robust Policy Gradient (arXiv)

 Jiawei Huang, Nan Jiang
- 8. [ICML 2020] Minimax Weight and Q-Function Learning for Off-Policy Evaluation (arXiv) Masatoshi Uehara, <u>Jiawei Huang</u>, Nan Jiang
- 9. [ECCV 2020] WeightNet: Revisiting the Design Space of Weight Networks (arXiv) Ningning Ma, Xiangyu Zhang, Jiawei Huang, Jian Sun

PROGRAMMING SKILLS.

Python (TensorFlow, PyTorch), Java, C/C++.