

# Mandelbrot CUDA Optimizations

By Benjamin Tiffany, Richard Qin, Jiawei Zheng

## Serial/OpenMP

- 512x512, maxIter=1000
- Pixels near the center tend to take longer to render > dynamic scheduling
- Collapse nested loop into 1 loop
- gfx functions can have race conditions

```
double start = omp_get_wtime();
// Display the fractal image
compute_image(xmin,xmax,ymin,ymadouble stop = omp_get_wtime();
```

```
CUDA (GeForce RTX 2060)

Blocks: 512 Threads per Block: 512 Size:512x512 Depth: 1000 Time: 0.008425
```

#### **CUDA Optimizations**

- Approach 1 (Baseline): 1 block, 1 thread per block (N=1, M=1).
  - Simulate serial version of CUDA mandelbrot
- Approach 2 (Extreme): 1 block, 512x512 threads per block.
  - Each thread is assigned one pixel to render.
- Approach 3 (Extreme): 512x512 blocks, 1 thread per block.
  - Each block is assigned one pixel to render.

```
Blocks: 1 Threads per Block: 1 Size:512x512 Depth: 1000 Time: 7.793414
|Blocks: 1 Threads per Block: 1024 Size:512x512 Depth: 1000 Time: 0.338495
|Blocks: 262144 Threads per Block: 1 Size:512x512 Depth: 1000 Time: 0.187520
```

## **CUDA Optimizations**

- Warp Size: 32
  - When threads%32!=0, have to create a new warp for leftover threads.
- Approach 4: vary number of threads per block in multiples of 32, keeping blocks fixed.
- Approach 5: vary pixels per thread with larger resolutions

### **CUDA Optimizations**

- https://docs.nvidia.com/cuda/cuda-c-programming-guide/index.html#deviceside-kernel-launch
- Approach 6: Shared Memory
  - kernel\_name<<< Dg, Db, Ns, S >>>([kernel arguments]);
  - "Ns is of type size\_t and specifies the number of bytes of shared memory that is dynamically allocated per thread block".
- Approach 7: Multiple Kernels
  - Separate line "mandel\_kernel<<<n, m>>>(dev\_counts, xmin, ymin, step, max\_iter, dim, colors);" into n kernel calls and n separate streams.
- Approach 8: math\_functions.h, device\_functions.h
  - CUDA math functions
  - More speed for slightly lower accuracy.