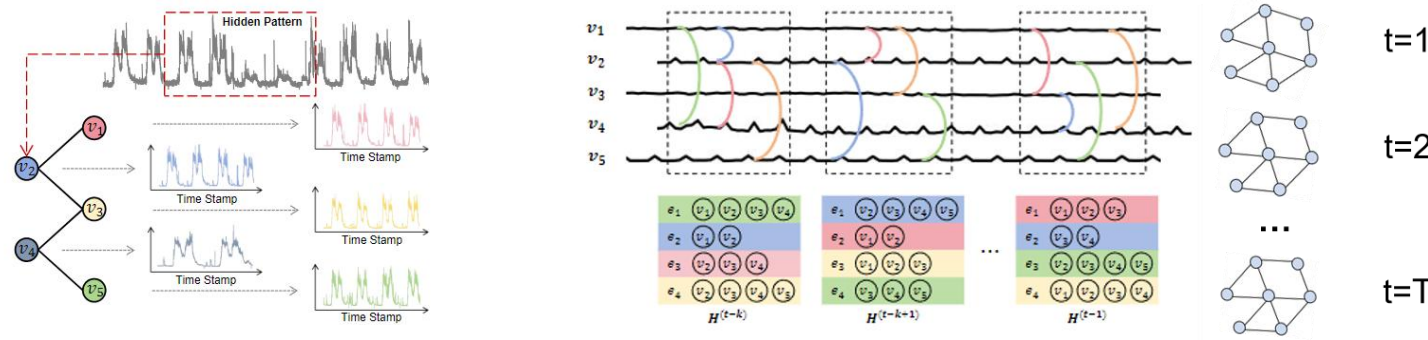


Background and Challenges



Classic LLMs fail to learn temporal and spatial feature information simultaneously

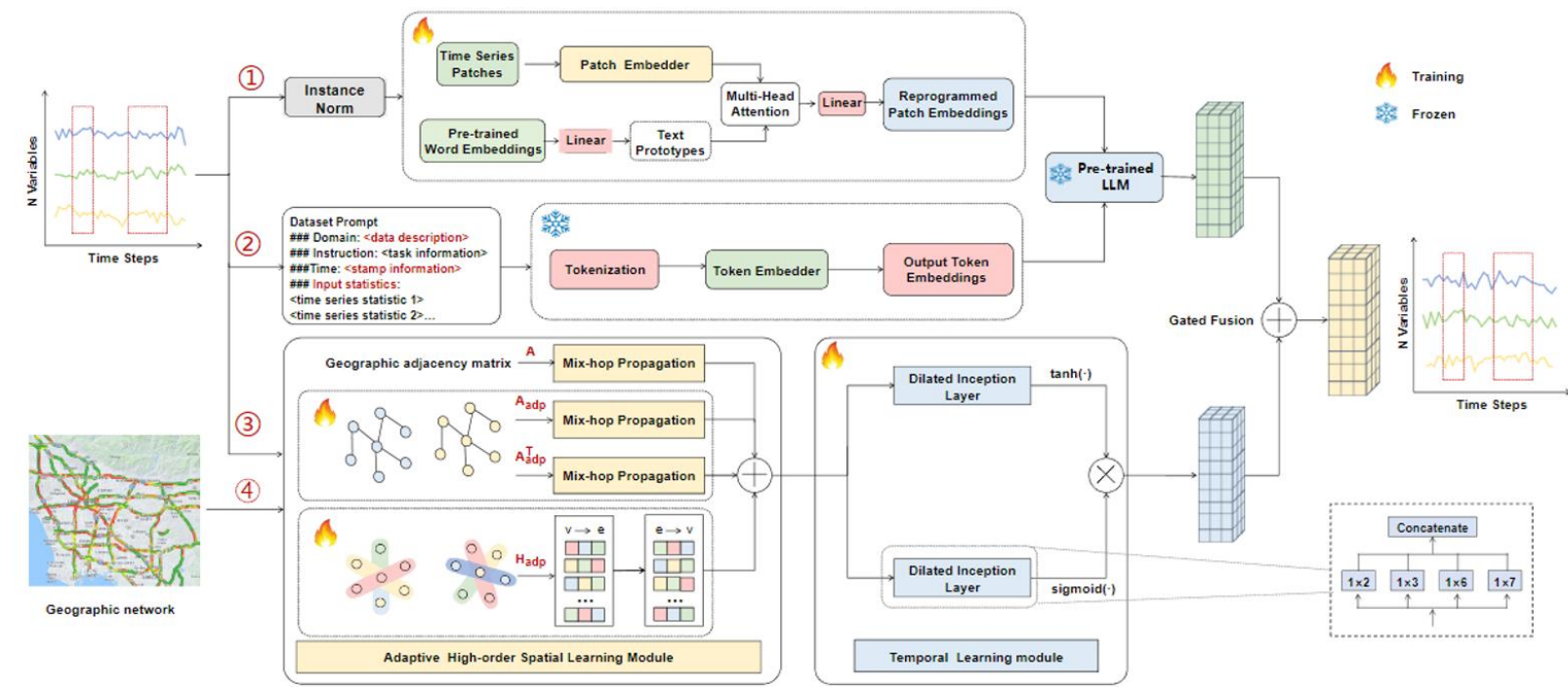
- Focus on temporal patterns, neglecting spatial dependencies.
- High computational cost for spatio structures modeling.

Classical spatio-temporal models fail to learning latent or high-order spatial coupling interactions

- Static graphs hard to model dynamic spatial changes.
- Only pairwise spatial relations are typically considered.

Method

Spatio-Temporal Modeling Prediction with LLMs



Framework of SHT-SepNet

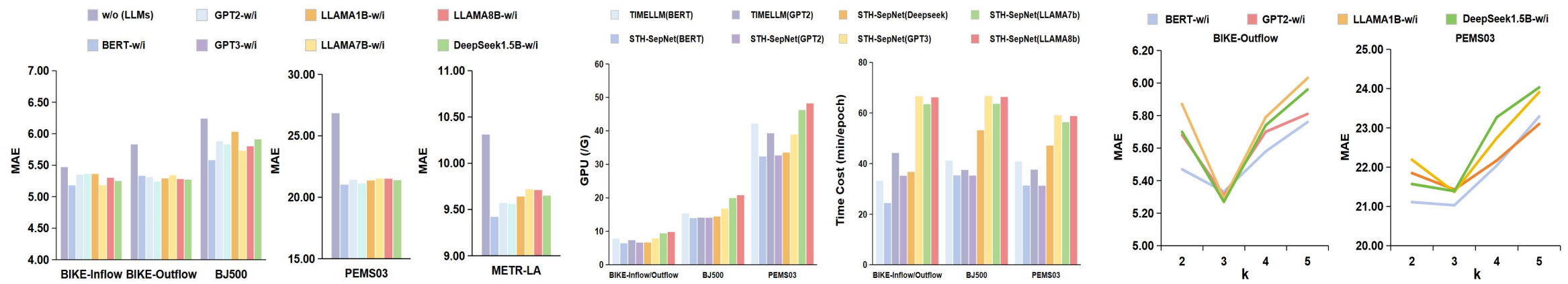
Contributions

- Lightweight spatio-temporal separation framework (STH-SepNet) fuses textual cues with high-order spatial dependencies.
- Adaptive hypergraph structure for spatial modeling that dynamically captures intricate dependencies via effective order modeling.
- State-of-the-art performance and single-GPU efficiency by experiments, confirming the framework's readiness for real-world deployment.

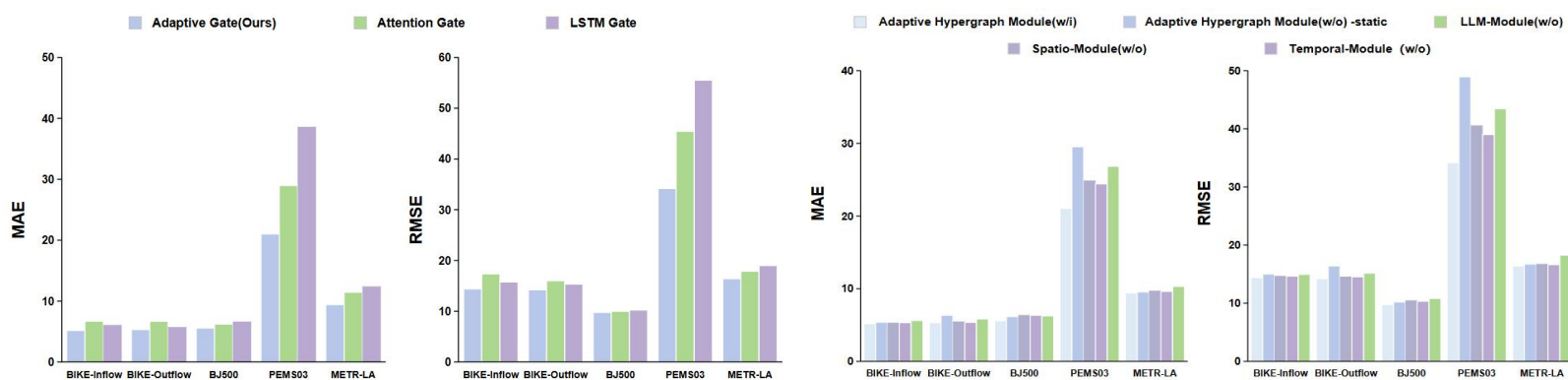
Results and Conclusion

Model	BIKE-Inflow		BIKE-Outflow		PEMS03		BJ500		METR-LA	
	MAE	RMSE	MAE	RMSE	MAE	RMSE	MAE	RMSE	MAE	RMSE
Autoformer (NIPS, 2021)[30]	7.01	17.52	7.19	17.75	44.87	70.84	10.79	16.06	12.47	20.04
Informer (AAAI, 2021)[34]	8.25	20.37	9.21	21.50	33.72	52.15	7.58	11.96	14.50	20.35
FEDformer (PMLR, 2022)[29]	6.28	16.30	6.56	16.67	35.00	50.84	10.77	15.99	12.35	18.79
DLinear (AAAI, 2023)[23]	5.71	15.49	5.82	15.36	45.30	66.81	8.55	13.49	10.90	17.31
TimesNet (ICLR, 2023)[35]	5.54	15.41	5.56	15.18	37.54	62.99	8.67	13.96	10.22	18.29
PatchTST (ICLR, 2023)[36]	5.53	15.39	5.63	15.23	48.42	78.24	8.79	14.28	10.13	18.27
iTransformer (ICLR, 2024)[26]	6.05	16.39	6.15	16.69	43.63	70.61	9.01	14.32	10.15	18.36
TIMELLM (ICLR, 2024)[37]	6.81	16.72	6.93	16.30	32.62	49.77	7.25	11.58	12.36	18.53
AdaMSHyper (NIPS, 2024)[38]	6.72	16.91	7.04	17.14	33.49	50.37	7.41	11.60	12.51	18.60
AGCRN (NIPS, 2020)[39]	6.64	16.14	6.77	16.36	33.14	54.88	6.32	12.81	11.39	23.15
ASTGCN (AAAI, 2019)[40]	6.66	15.87	6.26	14.48	30.65	53.96	6.34	11.34	10.54	22.76
MSTGCN (TNSRE, 2021)[41]	5.91	14.11	6.04	14.24	29.57	47.97	5.62	11.15	10.17	20.24
MTGNN (KDD, 2020)[1]	6.16	14.80	5.93	13.93	29.04	50.32	5.86	10.91	9.98	21.23
STGCN (KDD, 2021)[42]	6.77	15.93	6.82	15.50	33.39	54.16	6.44	12.14	11.48	22.85
STSGCN (AAAI, 2020)[14]	6.73	15.89	6.58	15.36	34.23	58.07	6.40	12.03	11.07	22.79
STGCN (IJCAI, 2018)[43]	7.08	15.72	7.36	16.11	36.02	53.44	6.73	12.62	12.38	22.55
GMAN (AAAI, 2020)[44]	6.73	15.60	6.94	15.84	33.96	53.02	6.41	12.40	11.69	22.37
STAEformer (CIKM, 2024)[27]	5.97	14.57	6.17	14.70	29.62	48.03	5.79	10.42	9.91	21.17
STD-MAE (IJCAI, 2024)[45]	6.13	14.87	6.21	14.37	30.40	48.38	5.92	11.49	10.52	23.11
STH-SepNet (Ours)	5.18	14.40	5.33	14.23	21.03	34.17	5.58	9.77	9.42	16.41

- STH-SepNet decreases errors by 28.8 % on drifting data and running 23.8 % better than LLM baselines
- Adaptive hypergraphs dynamically reweight to capture sudden spatial drift, outperform massive models with a lightweight backbone, and consistently excel across architectures via higher-order interactions.



- Lightweight LLMs (BERT, GPT2) achieve competitive performance while maintain stability and efficiency
- STH-SepNet (BERT) outperforms TIMELLM and larger STH-SepNet in GPU usage, training speed



- Adaptive gate fusion achieves superior MAE/RMSE
- Adaptive hypergraph module shows obvious improvements

Dataset		2	3	4	5
BIKE-Outflow	BERT	13.36	14.23	14.89	15.37
	GPT2	14.48	14.24	15.29	15.58
	LLAMA1B	14.80	14.20	15.54	16.19
	DeepSeek1.5B	14.55	14.19	15.46	16.05
PEMS03	BERT	34.52	34.17	35.81	37.84
	GPT2	35.78	35.01	36.22	37.74
	LLAMA1B	35.87	34.92	37.16	39.07
	DeepSeek1.5B	35.47	34.96	38.03	39.27

- Excessive parameter scaling is not essential for effective temporal modeling
- Effective order ($k=3$), STH-SepNet model achieves smallest MSE

