

Adaptivity analysis

AExpr.	a	$::=$	$n \mid x \mid a_1 + a_2 \mid a_1 - a_2 \mid a_1 * a_2$
BExpr	b	$::=$	$v \mid a_1 < a_2 \mid a_1 = a_2 \mid \neg b \mid b_1 \wedge b_2 \mid b_1 \vee b_2$
Command	c	$::=$	$Skip \mid c_1; c_2 \mid \text{if } b \text{ then } c_1 \text{ else } c_2 \mid \text{while}(b) \ c$ $\mid x \leftarrow a \mid x \leftarrow^l \delta^l(a)$
Label	l	\in	\mathbb{Z}
Trace	T	$::=$	$\{[(x_1, l_1), \dots, (x_i, l_i)], \dots, [(y_1, l_1), \dots, (y_i, l_i)]\}$
Environment	θ	$::=$	$x_1 \mapsto (n_1, T_1), \dots, x_n \mapsto (v_n, T_n)$
Node	N	$::=$	$Empty \mid D_1(x, T) \mid D_2(x, T) \mid IFT(T_b, N)$ $\mid IFF(T_b, N) \mid W(T_b, N) \mid N_1; N_2$
Trace	T	\in	$Set < List < Var \times Label > >$

$$\boxed{\theta, a \rightarrow^T n}$$

$$\frac{\theta(x) = (n, T)}{\theta, x \rightarrow^T n} \text{ var} \quad \frac{}{\theta, n \rightarrow () n} \text{ const} \quad \frac{\theta, a_1 \rightarrow^{T_1} n_1 \quad \theta, a_2 \rightarrow^{T_2} n_2}{\theta, a_1 + a_2 \rightarrow^{T_1 \cup T_2} n_1 + n_2} \text{ sum}$$

$$\boxed{\theta, b \rightarrow^T v}$$

$$\frac{\theta, a_1 \rightarrow^{T_1} n_1 \quad \theta, a_2 \rightarrow^{T_2} n_2}{\theta, a_1 + a_2 \rightarrow^{T_1 \cup T_2} n_1 < n_2} \text{ les} \quad \frac{\theta, b_1 \rightarrow^{T_1} v_1 \quad \theta, b_2 \rightarrow^{T_2} v_2}{\theta, b_1 \wedge b_2 \rightarrow^{T_1 \cup T_2} v_1 \wedge v_2} \text{ land}$$

$$\boxed{\theta, c \rightarrow^N \theta'}$$

$$\frac{}{\theta, \text{Skip} \rightarrow \theta} \text{ skip} \quad \frac{\theta, c_1 \rightarrow^{N_1} \theta_1 \quad \theta_1, c_2 \rightarrow^{N_2} \theta_2}{\theta, c_1; c_2 \rightarrow^{N_1; N_2} \theta_2} \text{ Seq}$$

$$\frac{\theta, a \rightarrow^T n}{\theta, x \leftarrow a \rightarrow^{D_1(x, T)} \theta[x \rightarrow (n, T)]} \text{ Assign}$$

$$\frac{\theta, a \rightarrow^T n \quad \delta(n) = n_1}{\theta, x \leftarrow^l \delta^l(a) \rightarrow^{D_2(x, T + (x, l))} \theta[x \rightarrow (n_1, T + (x, l))]} \text{ FAssign}$$

$$\frac{\theta, b \rightarrow^{T_b} \text{false} \quad \theta, c_2 \rightarrow^{N_2} \theta_2}{\theta, \text{if } b \text{ then } c_1 \text{ else } c_2 \rightarrow^{IFF(T_b, N_2)} \theta_2} \text{ IFF}$$

$$\frac{\theta, b \rightarrow^{T_b} \text{true} \quad \theta, c_1 \rightarrow^{N_1} \theta_1}{\theta, \text{if } b \text{ then } c_1 \text{ else } c_2 \rightarrow^{IFT(T_b, N_1)} \theta_1} \text{ IFT}$$

$$\frac{\theta, b \rightarrow^{T_b} \text{false}}{\theta, \text{while}(b) \rightarrow^{WF(T_b)} \theta} \text{ WHILEF}$$

$$\frac{\theta, b \rightarrow^{T_b} \text{true} \quad \theta, c \rightarrow^{N_1} \theta_1 \quad \theta_1, \text{while}(b) \rightarrow^{N_2} \theta_2}{\theta, \text{while}(b) \rightarrow^{WT(T_b, N_1, N_2)} \theta_2} \text{ WHILET}$$

$$\begin{aligned} \{\} + (x, l) &\triangleq \{(x, l)\} \\ \{[(x_1, l_1), \dots, (x_i, l_i)], \dots, [(y_1, l'_1), \dots, (y_i, l'_i)]\} + (x, l) &\triangleq \\ \{[(x_1, l_1), \dots, (x_i, l_i), (x, l)], \dots, [(y_1, l'_1), \dots, (y_i, l'_i), (x, l)]\} &\end{aligned}$$

Figure 1: Big-step semantics