

CS591S1 Homework 2: More on Differential Privacy

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1 Problem 1

1. (Sensitivity)

Given data set \mathbf{x} , for arbitrary $y \in \{1, \dots, R\}$ and adjacent dataset \mathbf{x}' by insertion or deletion of one data point x_k , we have following cases for insertion (deletion will be symmetric):

- $y = x_k$:

$$q(y; \mathbf{x}') = -\left| \sum_{i=0}^n \text{sign}(y - x_i) + \text{sign}(y - x_k) \right| = -\left| \sum_{i=0}^n \text{sign}(y - x_i) + 0 \right| = -\left| \sum_{i=0}^n \text{sign}(y - x_i) \right| = q(y; \mathbf{x})$$

- $y < x_k$

$$\begin{aligned} q(y; \mathbf{x}') &= -\left| \sum_{i=0}^n \text{sign}(y - x_i) + \text{sign}(y - x_k) \right| \\ &= -\left| \sum_{i=0}^n \text{sign}(y - x_i) - 1 \right| \quad (\star) \end{aligned}$$

By triangle inequality, we have:

$$\begin{aligned} (\star) &\leq -\left| \sum_{i=0}^n \text{sign}(y - x_i) \right| + 1 = q(y; \mathbf{x}) + 1 \\ (\star) &\geq -\left| \sum_{i=0}^n \text{sign}(y - x_i) \right| - 1 = q(y; \mathbf{x}) - 1 \end{aligned}$$

Then we can get:

$$-1 \leq q(y; \mathbf{x}') - q(y; \mathbf{x}) \leq 1$$

- $y > x_k$

$$\begin{aligned} q(y; \mathbf{x}') &= -\left| \sum_{i=0}^n \text{sign}(y - x_i) + \text{sign}(y - x_k) \right| \\ &= -\left| \sum_{i=0}^n \text{sign}(y - x_i) + 1 \right| \quad (\star) \end{aligned}$$

By triangle inequality, we have:

$$\begin{aligned} (\star) &\leq -\left| \sum_{i=0}^n \text{sign}(y - x_i) \right| + 1 = q(y; \mathbf{x}) + 1 \\ (\star) &\geq -\left| \sum_{i=0}^n \text{sign}(y - x_i) \right| - 1 = q(y; \mathbf{x}) - 1 \end{aligned}$$

Then we can get:

$$-1 \leq q(y; \mathbf{x}') - q(y; \mathbf{x}) \leq 1$$

The Deletion is symmetric where we can get: $-1 \leq q(y; \mathbf{x}) - q(y; \mathbf{x}') \leq 1$ in the same way. Then, we can conclude from all cases, the $|q(y; \mathbf{x}) - q(y; \mathbf{x}')| \leq 1$, i.e., the sensitivity be at most 1.

2. *Proof.* By the definition of $rank_{\mathbf{x}}(y)$, we have:

$$|rank_{\mathbf{x}}(y) - \frac{n}{2}| = -q(y; \mathbf{x}).$$

Then, we know:

$$\begin{aligned} Pr_{y \sim A_{\epsilon}(\mathbf{x})}[|rank_{\mathbf{x}}(y) - \frac{n}{2}| > c \cdot \frac{\ln(R) + \ln(1/\beta)}{\epsilon}] &\equiv Pr_{y \sim A_{\epsilon}(\mathbf{x})}[-q(y; \mathbf{x}) > c \cdot \frac{\ln(R) + \ln(1/\beta)}{\epsilon}] \\ &= Pr_{y \sim A_{\epsilon}(\mathbf{x})}[q(y; \mathbf{x}) \leq -c \cdot \frac{\ln(R) + \ln(1/\beta)}{\epsilon}] \end{aligned}$$

By definition of exponential mechanism, we have:

$$\begin{aligned} Pr_{y \sim A_{\epsilon}(\mathbf{x})}[q(y; \mathbf{x}) \leq -c \cdot \frac{\ln(R) + \ln(1/\beta)}{\epsilon}] &= \sum_{y | q(y; \mathbf{x}) < -c \cdot \frac{\ln(R) + \ln(1/\beta)}{\epsilon}} \frac{\exp(q(y; \mathbf{x})\epsilon/2S)}{\sum_y \exp(q(y; \mathbf{x})\epsilon/2S)} \\ &\leq R \frac{\exp(-c \cdot \frac{\ln(R) + \ln(1/\beta)}{\epsilon} \frac{\epsilon}{2S})}{\sum_y \exp(q(y; \mathbf{x})\epsilon/2S)} \\ &= R \frac{\exp(\frac{c}{2}(\ln(\frac{1}{R}) + \ln(\beta)))}{\sum_y \exp(q(y; \mathbf{x})\epsilon/2S)} \quad (\star) \end{aligned}$$

Since the only one optimal output candidate is the median value where $q(y, \mathbf{x}) = 0$, so we have:

$$(\star) \leq \frac{\exp(\frac{c}{2}(\ln(\frac{1}{R}) + \ln(\beta)))}{\exp(0)}$$

In order to have this probability be at most β , we take the equality and get:

$$\begin{aligned} \frac{\exp(\frac{c}{2}(\ln(\frac{1}{R}) + \ln(\beta)))}{\exp(0)} &= \beta \\ R^{1-\frac{c}{2}} &= \beta^{1-\frac{c}{2}} \end{aligned}$$

Since we have $R \geq 1$ and $\beta \in (0, 1)$, there exists $c = 2$ which can make the equation holds. \square

2 Problem 2

Proof. The proof are developed by two cases where the insertion and deletion whether or not make changes on empty bins:

case changes on nonempty bins

Taking arbitrary data set \mathbf{x} and one possible output S , there are two cases of insertion to create the adjacent data set \mathbf{x}' :

subcase insertion

Inserting one data that makes an empty bin ($k \in \mathcal{X}$) be nonempty, we have the

$$\begin{aligned} \frac{Pr[A(\mathbf{x}')=S]}{Pr[A(\mathbf{x})=S]} &= \frac{Pr[A(\mathbf{x})=S \wedge \tilde{c}_k' < \tau]}{Pr[A(\mathbf{x})=S]} \\ &= \frac{Pr[A(\mathbf{x})=S] \cdot Pr[\tilde{c}_k' < \tau]}{Pr[A(\mathbf{x})=S]} \\ &= Pr[1 + Lap(\frac{1}{\epsilon}) < \tau] \\ &\leq (1 - \frac{\delta}{2}) \end{aligned}$$

subcase deletion.

Deleting one data point that makes the existing nonempty bins ($k \in \mathcal{X}$) be empty bins, we have the probability as:

$$\begin{aligned}
\frac{Pr[A(\mathbf{x}')=S]}{Pr[A(\mathbf{x})=S]} &= \frac{Pr[A(\mathbf{x}')=S]}{Pr[A(\mathbf{x}')=S \wedge \tilde{c}_k < \tau]} \\
&= \frac{Pr[A(\mathbf{x}')=S]}{Pr[A(\mathbf{x}')=S] \cdot Pr[\tilde{c}_k < \tau]} \\
&= \frac{1}{Pr[1 + Lap(\frac{1}{\epsilon}) < \tau]} \\
&\geq \frac{1}{1 - \frac{\delta}{2}}
\end{aligned}$$

case no change on nonempty bins

Taking arbitrary data set \mathbf{x} and a possible output S , There are two cases of creating the adjacent data set \mathbf{x}' :

subcase insertion

insert one data which makes an empty bin ($k \in \mathcal{X}$) be nonempty, we have the

$$\begin{aligned}
\frac{Pr[A(\mathbf{x}')=S]}{Pr[A(\mathbf{x})=S]} &= \frac{Pr[A(\mathbf{x} \setminus k)=S \setminus k \wedge \tilde{c}'_k = \tilde{c}_k]}{Pr[A(\mathbf{x})=S]} \\
&= \frac{Pr[A(\mathbf{x} \setminus k)=S \setminus k] \cdot Pr[\tilde{c}'_k = \tilde{c}_k]}{Pr[A(\mathbf{x})=S]} \\
&= \frac{Pr[c'_k + Lap(\frac{1}{\epsilon}) = \tilde{c}_k]}{Pr[c_k + Lap(\frac{1}{\epsilon}) = \tilde{c}_k]} \\
&\leq e^\epsilon
\end{aligned}$$

subcase deletion

insert one data point in the existing nonempty bins ($k \in \mathcal{X}$). We have the probability as:

$$\begin{aligned}
\frac{Pr[A(\mathbf{x}')=S]}{Pr[A(\mathbf{x})=S]} &= \frac{Pr[A(\mathbf{x} \setminus k)=S \setminus k \wedge \tilde{c}'_k = \tilde{c}_k]}{Pr[A(\mathbf{x})=S]} \\
&= \frac{Pr[A(\mathbf{x} \setminus k)=S \setminus k] \cdot Pr[\tilde{c}'_k = \tilde{c}_k]}{Pr[A(\mathbf{x})=S]} \\
&= \frac{Pr[c'_k + Lap(\frac{1}{\epsilon}) = \tilde{c}_k]}{Pr[c_k + Lap(\frac{1}{\epsilon}) = \tilde{c}_k]} \\
&\geq e^{-\epsilon}
\end{aligned}$$

By summarization, the probability of failure would be δ above cases. So we have the algorithm be (ϵ, δ) -DP. \square