

$$E = \left\{ (x^i, w, y^j) \mid x^i, y^j \in LVar \right. \\ \left. w = \max \left\{ \begin{array}{l} \exists (\tau) : \text{Dep}(x^i, y^j, \tau, c) \end{array} \right\} \right\}$$

example: input x:

```

y=0;
i=0;
w=0;
z<q1;
if x=0 then
  (y < q2(z); i=x-1)
else
  (skip);
while i<neq x
  if i<neq x then w=0 else skip;
  i=i+1
  {w<q3(y,w); if i neq x-2 then w=0 else skip; i=i+1}
  
```

a trace τ_1, τ_2, τ_3
 $\tau_1: \tau_2, \tau_3$
 $\text{change } \tau_2 \Rightarrow \tau'_2 = \tau_2, \tau_3$

then another trace: $\tau_1 = w, \tau_2, \tau_3 = w, \tau_2$
 $\text{change } \tau_2 \Rightarrow \tau'_2 = w, v, \tau_3 = w, \tau_2$

+ trace s.t. $\# \text{trace} \geq \# \text{event} \geq \# \text{event where value of } w \text{ is changed}$.
 $\text{Dep}(\tau, \tau, w)$, # of occurrence time of $w \geq \# \text{of event where value of } w \text{ is changed}$.

then count: # trace τ s.t. $\text{Dep}(\tau, \tau, w)$.
 $| \text{Diff}(\tau_1, \tau_2, w) |$

\Rightarrow weight on edge (x^i, y^j, w) .
 $w = \max \{ | \text{Diff}(\tau_1, \tau_2, y^j) | \mid \# \tau_1, \tau_2, \text{s.t. } \text{Dep}(x^i, \tau_1, \tau_2, y^j) \}$

\Rightarrow 1. Dep on ω traces. redefine.

\Rightarrow ω Global Dep. ??

\Rightarrow add iteration id.

↳ possible unsound ??

then,

if cases H.t. observe the same
value, but in different iterations?
then intuitively no-dependency it is good.

\Rightarrow 2. $\text{Diff}(\tau_1, \tau_2, x^i)$

\Rightarrow $\#$
 $\text{Seq}(\tau_2, x^i) \triangleq \begin{cases} \tau_2 = \tau'_2 :: (x, i, y, z) \rightarrow \text{Seq}(\tau_1, \tau_2), y \\ \tau_2 = \tau'_2 :: (x, i, y, \alpha) \rightarrow \text{Seq}(\tau_1, \tau_2), \alpha \\ \tau_2 = \{ \} \rightarrow \{ \} \\ \text{o.w.} \rightarrow \text{Seq}(\tau_1, \tau_2) \end{cases}$

without loop iteration id.

for $\text{Seq}(\tau_2, x^i)$, where $\text{Dep}(y^j, x^i, \tau_1, \tau_2)$.

case of $\text{Seq}(\tau_2) \neq \text{Seq}(\tau_2)$:

①. $\text{len}_{\tau_1} \neq \text{len}_{\tau_2} \Rightarrow \text{Diff}(\text{Seq}(\tau_1), \text{Seq}(\tau_2), x^i) = \{ k \mid \text{Seq}(\tau_1)[k] \neq \text{Seq}(\tau_2)[k] \} \cup \{ \text{len}_{\tau_1}, \text{len}_{\tau_1} + 1, \dots, \text{len}_{\tau_2} \}$.

②. $\text{len}_{\tau_1} = \text{len}_{\tau_2} \Rightarrow \text{Diff}(\text{Seq}(\tau_1), \text{Seq}(\tau_2), x^i) = \{ k \mid \text{Seq}(\tau_1)[k] \neq \text{Seq}(\tau_2)[k] \}$

\Rightarrow potential issue: the different observed value is in different iterations.

case: if guard is affected by moving to different iteration, but it always executed the same time with same value.

then it doesn't matter which iteration it is in, then isn't dependence / adaptivity.

\Rightarrow for case ② where they have some len, it doesn't loss adaptivity if I observe the same value in the same location of $\text{Seq}(\tau_1)$ and $\text{Seq}(\tau_2)$

but where they actually comes from different loop iteration.

i.e. it is sound that only consider the diff of same location.

\Rightarrow for case ①. $\text{len}_{\tau_1} \neq \text{len}_{\tau_2}$.

in the ω seqs from $[0, \min(l_1, l_2)]$, it is still sound by just observe the different value in same location,

for the same reason as case ②.

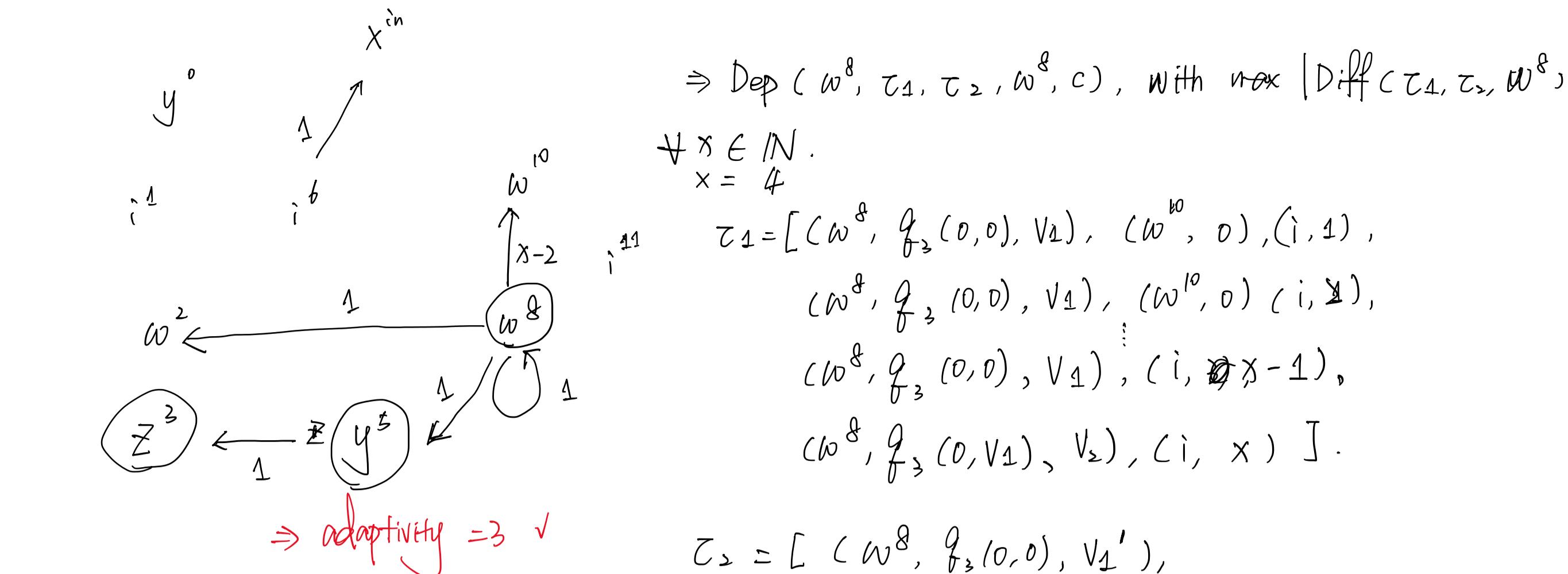
in the longer seq from $[\min(l_1, l_2), \max(l_1, l_2)]$.

case: $i=0$
 while $i < x$ do:
 $i=i+1$
 $y=g(x)$.
 \Rightarrow when $x=100$.
 still safe.
 $(y, 1, v_1), (y, 1, v_2), (y, 1, v_3), (y, 1, v_4), \dots$
 $(y, 1, v_1'), (y, 1, v_2'), (y, 1, v_3'), (y, 1, v_4') \dots$

$\Rightarrow Gy^*(i_0, x)$.

if in order to get different length, only way is by changing value affect guards.
 $(x, n, 1), (y, 1, v_1), \dots$
 \Rightarrow all the value are the same. then

$(x, 2n, 100), (y, 1, v_1), \dots$ adaptivity is actually 1.



\Rightarrow Dep Graph:

$\forall x^i \mid x^i \in LVar(C)$

$$E(C) = \left\{ (x^i, y^j, w^k) \mid w = \max \{ | \text{Diff}(\tau_1, \tau_2, y^j) | \mid \# \tau_1, \tau_2, \text{s.t. } \text{Dep}(x^i, \tau_1, \tau_2, y^j) \} \right\}$$

$\text{Diff}(\tau_1, \tau_2, x^i) \triangleq \{ k \mid (k=0, \dots, l_{\max} - 1) \wedge \text{Seq}(\tau_1, x^i)[k] \neq \text{Seq}(\tau_2, x^i)[k] \}$

$\wedge (\text{Seq}(\tau_{\max}, x^i)[k+1] \neq \text{Seq}(\tau_{\max}, x^i)[k] \wedge k = l_{\min}, \dots, l_{\max})$

$\wedge l_{\min} = \min(|\text{Seq}(\tau_1, x^i)|, |\text{Seq}(\tau_2, x^i)|)$

$l_{\max} = \max(\dots)$

$\tau_{\max} = \text{longer Sequence. } \tau$

$\Rightarrow \text{Seq}_f(\tau, x^i) \triangleq \begin{cases} \text{seq}(\tau, x^i) \wedge \tau = \tau :: (x, i, y, \alpha) \\ \text{seq}(\tau, x^i) \wedge \tau = \tau' :: (x, i, y, \alpha) \\ \{ \} \wedge \tau = \{ \} \\ \text{seq}(\tau) \wedge \text{o.w.} \end{cases}$

$\text{Dep}(x^i, \tau_1, \tau_2, y^j, C) \triangleq$

$\exists \tau_1', \tau_2, \tau'$

$\tau_1 = (x, i, y, \alpha), \tau_2 = (y, j, \beta, \gamma)$

$\tau_1' \neq \text{empty } \tau_1'$

$\langle C, \tau_1 \rangle \rightarrow \langle C_1, \tau_1' \rangle :: \tau_1' \rightarrow \langle \text{skip}, \tau_1' :: \tau_1 + \tau_2 \rangle$

$\wedge \langle C_1, \tau_1' :: \tau_1' \rangle \rightarrow \langle \text{skip}, \tau_1' :: \tau_1 + \tau_2 \rangle$

$\text{Diff}(\tau_1, \tau_2, y^j) \neq \emptyset$.

\Rightarrow example:

if they are different, then either y itself is used (through a chain) or y is used in evaluating y .

case: $i=0$
 while $i < x$:
 $i=i+1$
 $w=g(x)$.
 \Rightarrow when $x=100$.
 still safe.
 $(w, 1, 0), (w, 1, 0), \dots$

case: $i=0$
 while $i < x$:
 $w=g(x)$.
 \Rightarrow when $x=100$.
 still safe.
 $(w, 1, 0), (w, 1, 0), \dots$

two approaches:
 ↗ unknown to prove, because change x could change length
 ↗ and value in the same time.

③ prove there must exist value dependency from x to y or from other variable to y .

④ define $|\text{Diff}|$ as $\{ \text{seq}(\tau_{\max})[m : m] \}$. ↗ sound set of unique values.

possible case: $(1, 0, 1, 0, 1, 0)$ I actually have no intuition does this adaptive or not.

⇒ if it is, then $|\text{Diff}|$ defined as $\{ k \mid \text{seq}[k : k] \neq \text{Seq}[k : k] \}$ can capture.

but "intuitive adaptivity" is unclear.

Hence:
 $\max \{ | \text{Diff}(\tau_1, \tau_2, w^k) | \mid \# \tau_1, \tau_2, \text{s.t. } \text{Dep}(w^k, \tau_1, \tau_2, C) \} = 1$.

$\Rightarrow | \text{Diff}(\tau_1, \tau_2, w^k) | = 1$.