

# Program Analysis via Graph Reachability

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# Backward Slice

```
int main() {  
    int sum = 0;  
    int i = 1;  
    while (i < 11) {  
        sum = sum + i;  
        i = i + 1;  
    }  
    printf("%d\n", sum) ;  
    printf("%d\n", i) ;  
}
```

**Backward slice** with respect to “printf(“%d\n”,i)”

# Backward Slice

```
int main() {  
    int sum = 0;  
    int i = 1;  
    while (i < 11) {  
        sum = sum + i;  
        i = i + 1;  
    }  
    printf ("%d\n", sum) ;  
    printf ("%d\n", i) ;  
}
```

**Backward slice** with respect to “printf(“%d\n”,i)”

# Slice Extraction

```
int main() {  
  
    int i = 1;  
    while (i < 11) {  
  
        i = i + 1;  
  
    }  
  
    printf("%d\n", i);  
}
```

**Backward slice** with respect to “printf(“%d\n”,i)”

# Forward Slice

```
int main() {  
    int sum = 0;  
    int i = 1;  
    while (i < 11) {  
        sum = sum + i;  
        i = i + 1;  
    }  
    printf ("%d\n", sum) ;  
    printf ("%d\n", i) ;  
}
```

**Forward slice** with respect to “sum = 0”

# Forward Slice

```
int main() {  
    int sum = 0;  
    int i = 1;  
    while (i < 11) {  
        sum = sum + i;  
        i = i + 1;  
    }  
    printf("%d\n", sum) ;  
    printf("%d\n", i) ;  
}
```

**Forward slice** with respect to “sum = 0”

# What Are Slices Useful For?

- Understanding Programs
  - What is affected by what?
- Restructuring Programs
  - Isolation of separate “computational threads”
- Program Specialization and Reuse
  - Slices = specialized programs
  - Only reuse needed slices
- Program Differencing
  - Compare slices to identify changes
- Testing
  - What new test cases would improve coverage?
  - What regression tests must be rerun after a change?

# Line-Character-Count Program

```
void line_char_count(FILE *f) {  
    int lines = 0;  
    int chars;  
    BOOL eof_flag = FALSE;  
    int n;  
    extern void scan_line(FILE *f, BOOL *bptr, int *iptr);  
    scan_line(f, &eof_flag, &n);  
    chars = n;  
    while(eof_flag == FALSE){  
        lines = lines + 1;  
        scan_line(f, &eof_flag, &n);  
        chars = chars + n;  
    }  
    printf("lines = %d\n", lines);  
    printf("chars = %d\n", chars);  
}
```



# Character-Count Program

```
void char_count(FILE *f) {  
    int lines = 0;  
    int chars;  
    BOOL eof_flag = FALSE;  
    int n;  
    extern void scan_line(FILE *f, BOOL *bptr, int *iptr);  
    scan_line(f, &eof_flag, &n);  
    chars = n;  
    while(eof_flag == FALSE){  
        lines = lines + 1;  
        scan_line(f, &eof_flag, &n);  
        chars = chars + n;  
    }  
    printf("lines = %d\n", lines);  
    printf("chars = %d\n", chars);  
}
```

# Line-Character-Count Program

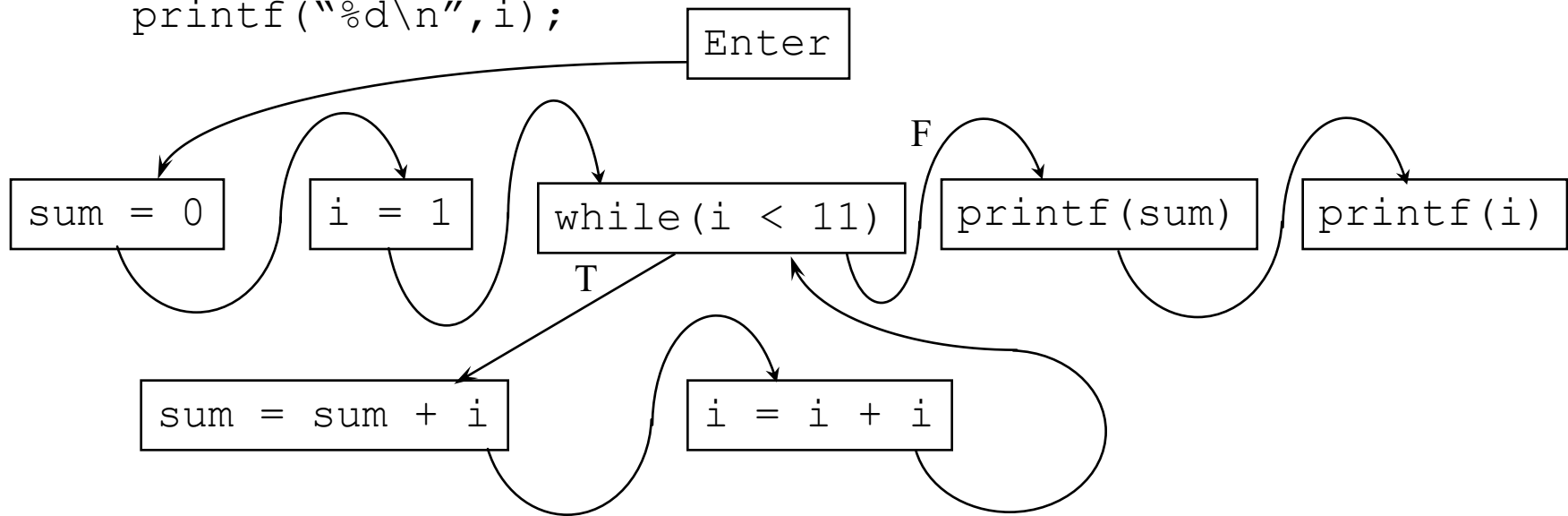
```
void line_char_count(FILE *f) {
    int lines = 0;
    int chars;
    BOOL eof_flag = FALSE;
    int n;
    extern void scan_line(FILE *f, BOOL *bptr, int *iptr);
    scan_line(f, &eof_flag, &n);
    chars = n;
    while(eof_flag == FALSE){
        lines = lines + 1;
        scan_line(f, &eof_flag, &n);
        chars = chars + n;
    }
    printf("lines = %d\n", lines);
    printf("chars = %d\n", chars);
}
```

# Line-Count Program

```
void line_count(FILE *f) {
    int lines = 0;
    int chars;
    BOOL eof_flag = FALSE;
    int n;
    extern void scan_line2(FILE *f, BOOL *bptr, int *iptr);
    scan_line2(f, &eof_flag, &n);
    chars = n;
    while(eof_flag == FALSE){
        lines = lines + 1;
        scan_line2(f, &eof_flag, &n);
        chars = chars + n;
    }
    printf("lines = %d\n", lines);
    printf("chars = %d\n", chars);
}
```

# Control Flow Graph

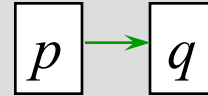
```
int main() {  
    int sum = 0;  
    int i = 1;  
    while (i < 11) {  
        sum = sum + i;  
        i = i + 1;  
    }  
    printf("%d\n", sum);  
    printf("%d\n", i);  
}
```



# Flow Dependence Graph

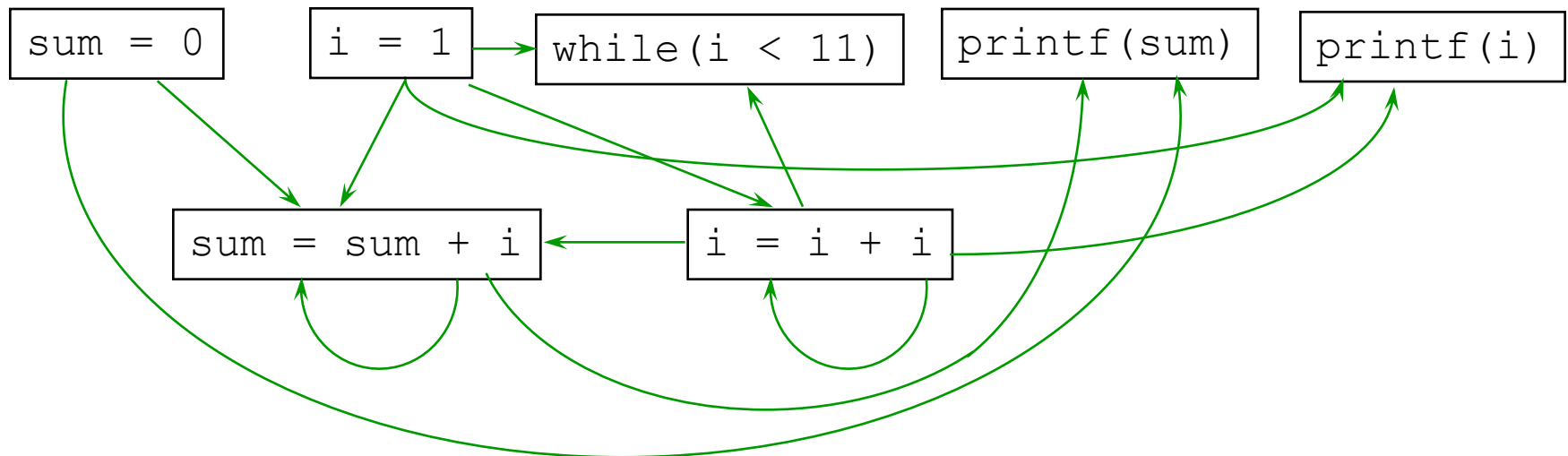
```
int main() {  
    int sum = 0;  
    int i = 1;  
    while (i < 11) {  
        sum = sum + i;  
        i = i + 1;  
    }  
    printf("%d\n", sum);  
    printf("%d\n", i);  
}
```

## Flow dependence



Value of variable assigned at  $p$  may be used at  $q$ .

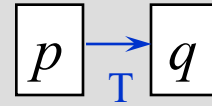
Enter



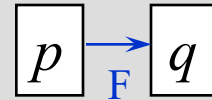
# Control Dependence Graph

```
int main() {  
    int sum = 0;  
    int i = 1;  
    while (i < 11) {  
        sum = sum + i;  
        i = i + 1;  
    }  
    printf("%d\n", sum);  
    printf("%d\n", i);  
}
```

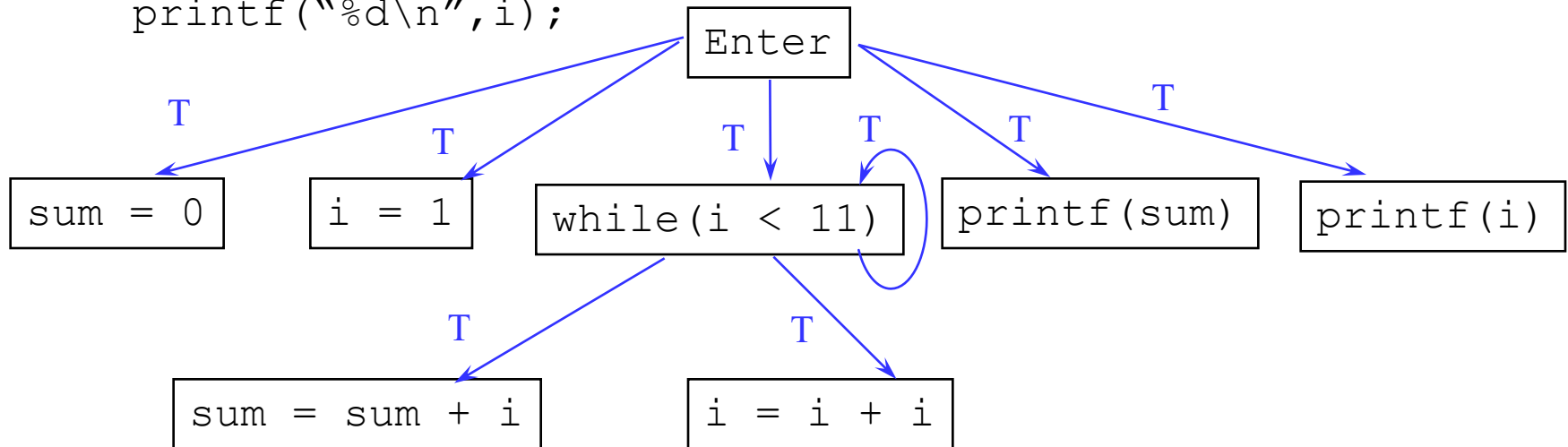
## Control dependence



$q$  is reached from  $p$  if condition  $p$  is true (T), not otherwise.



Similar for false (F).

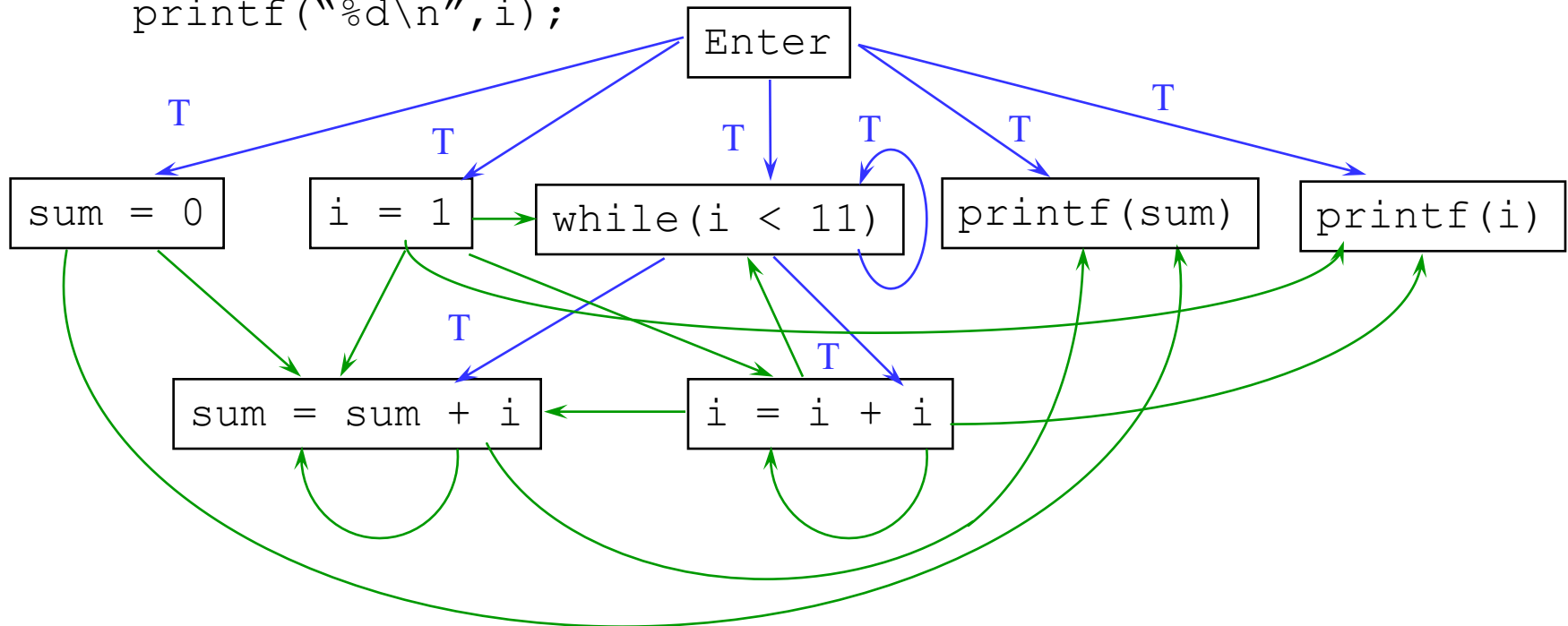


# Program Dependence Graph (PDG)

```
int main() {  
    int sum = 0;  
    int i = 1;  
    while (i < 11) {  
        sum = sum + i;  
        i = i + 1;  
    }  
    printf("%d\n", sum);  
    printf("%d\n", i);  
}
```

**Control dependence**

**Flow dependence**

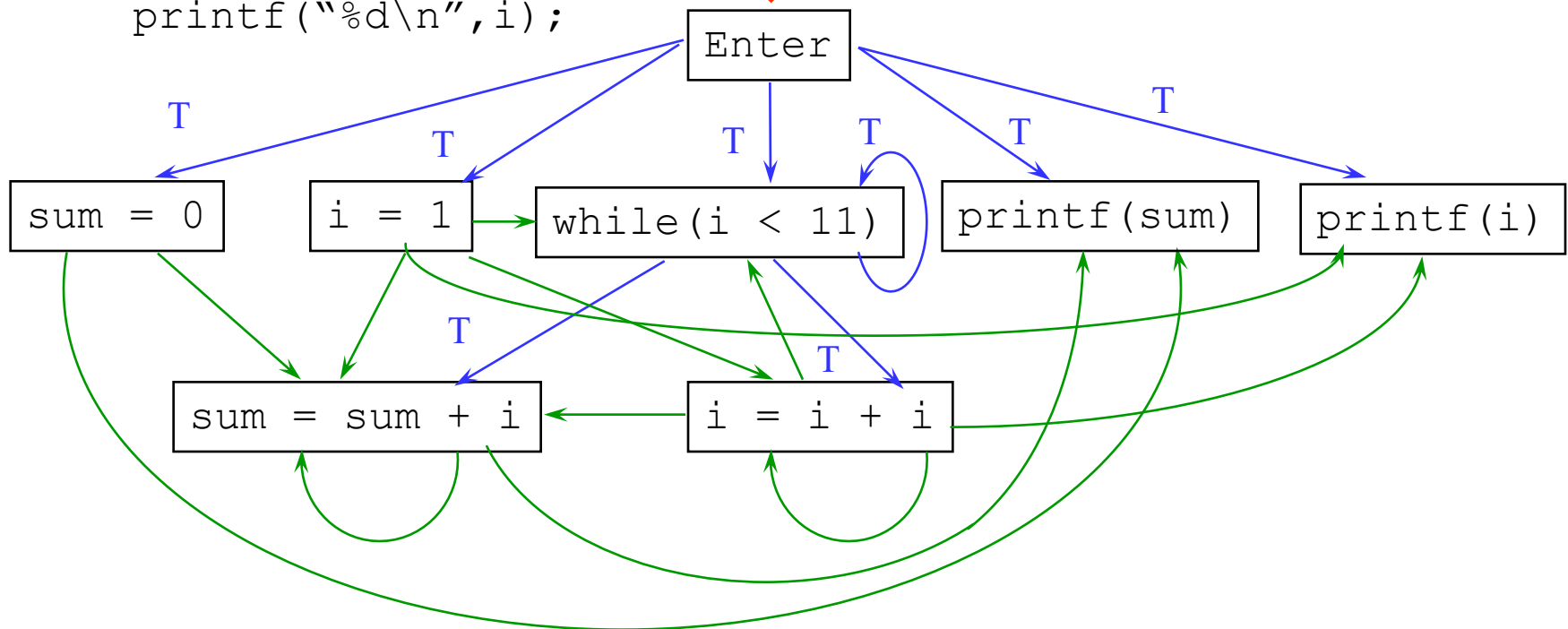


# Program Dependence Graph (PDG)

```
int main() {  
    int i = 1;  
    int sum = 0;  
    while (i < 11) {  
        sum = sum + i;  
        i = i + 1;  
    }  
    printf("%d\n", sum);  
    printf("%d\n", i);  
}
```

Opposite Order

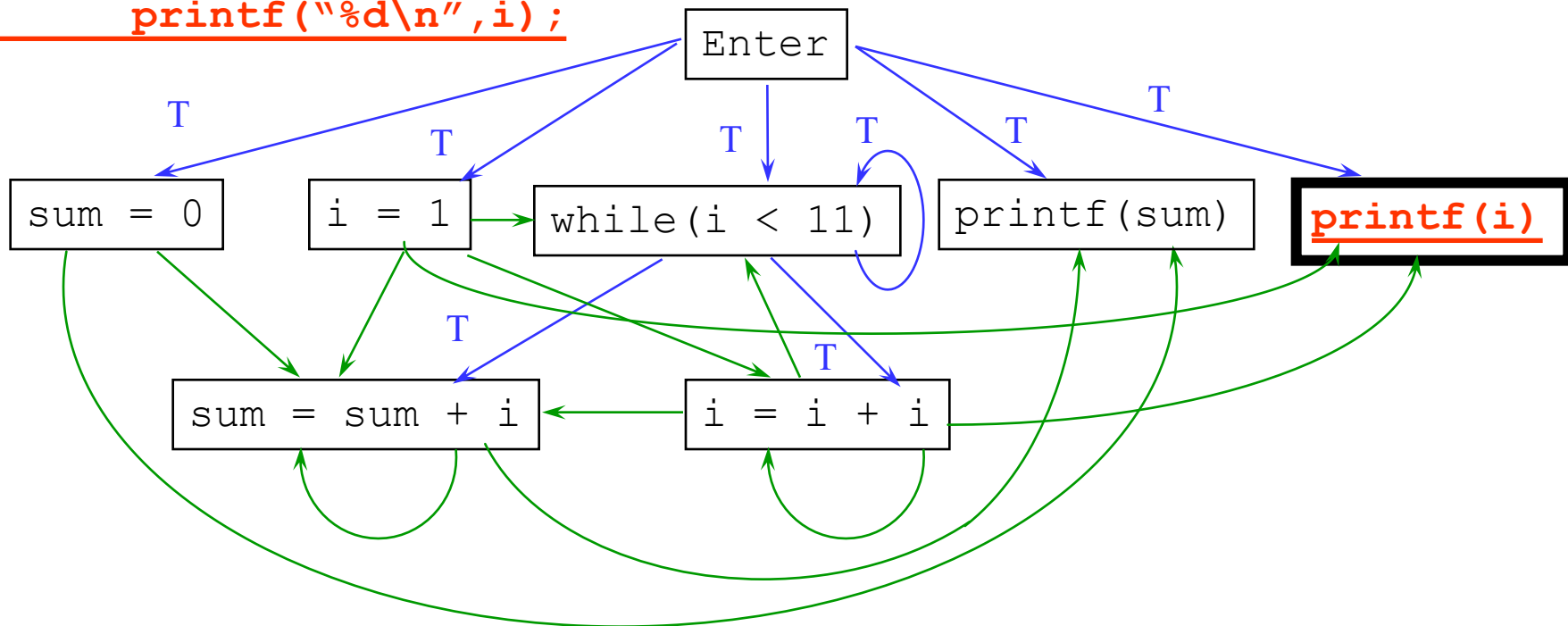
Same PDG





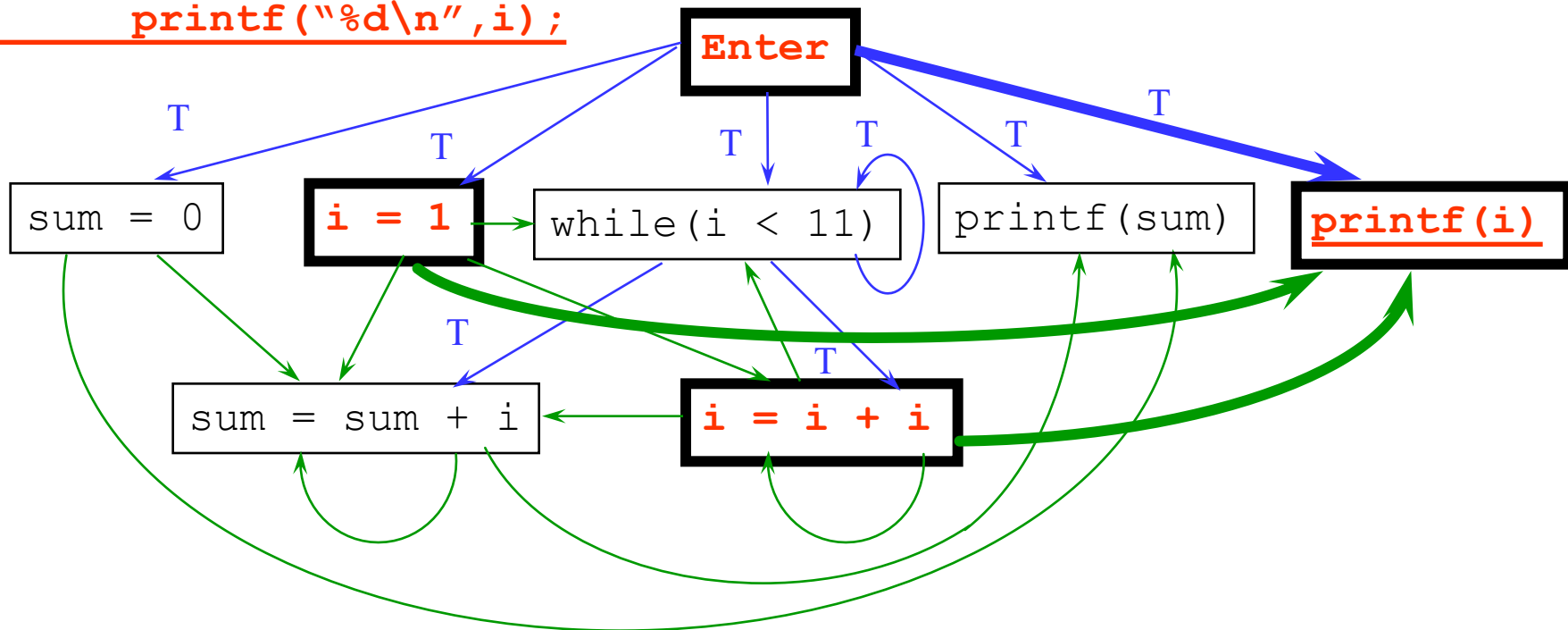
# Backward Slice

```
int main() {  
    int sum = 0;  
    int i = 1;  
    while (i < 11) {  
        sum = sum + i;  
        i = i + 1;  
    }  
    printf("%d\n", sum);  
    printf("%d\n", i);  
}
```



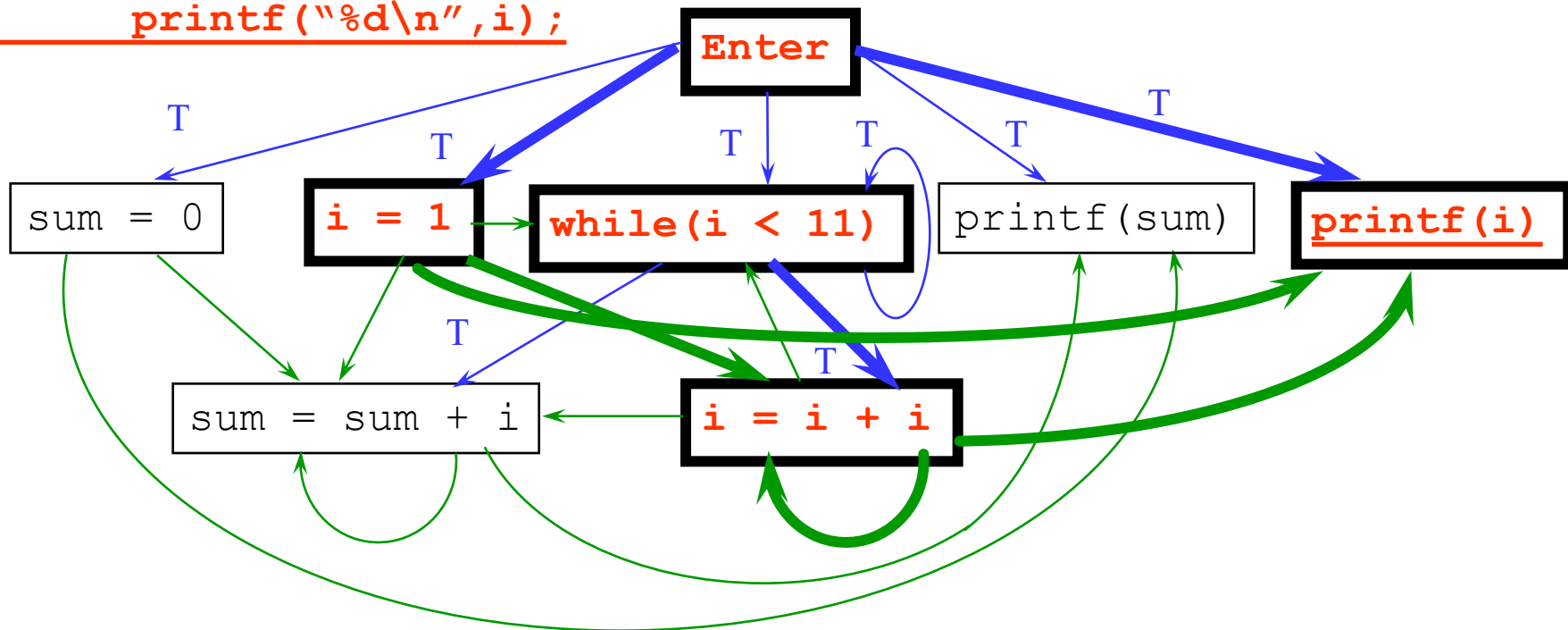
# Backward Slice (2)

```
int main() {  
    int sum = 0;  
    int i = 1;  
    while (i < 11) {  
        sum = sum + i;  
        i = i + 1;  
    }  
    printf("%d\n", sum);  
    printf("%d\n", i);  
}
```



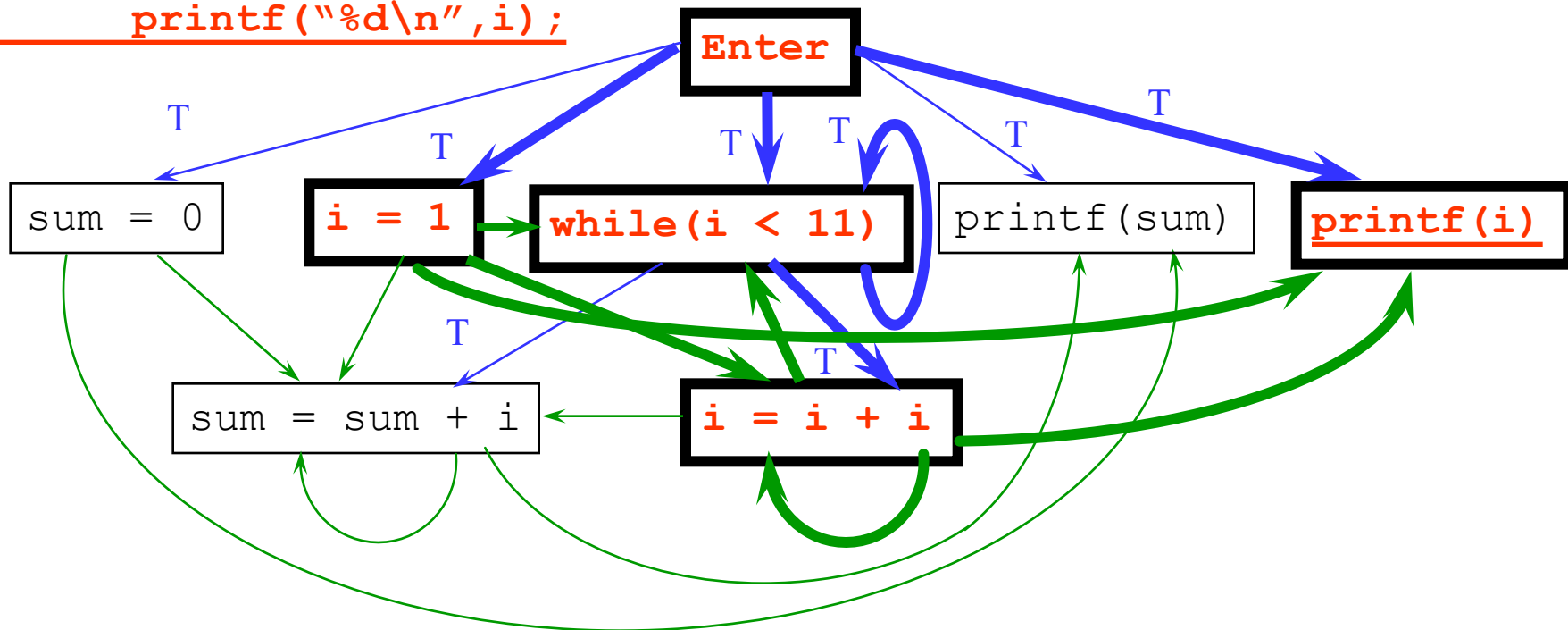
# Backward Slice (3)

```
int main() {  
    int sum = 0;  
    int i = 1;  
    while (i < 11) {  
        sum = sum + i;  
        i = i + 1;  
    }  
    printf("%d\n", sum);  
    printf("%d\n", i);  
}
```



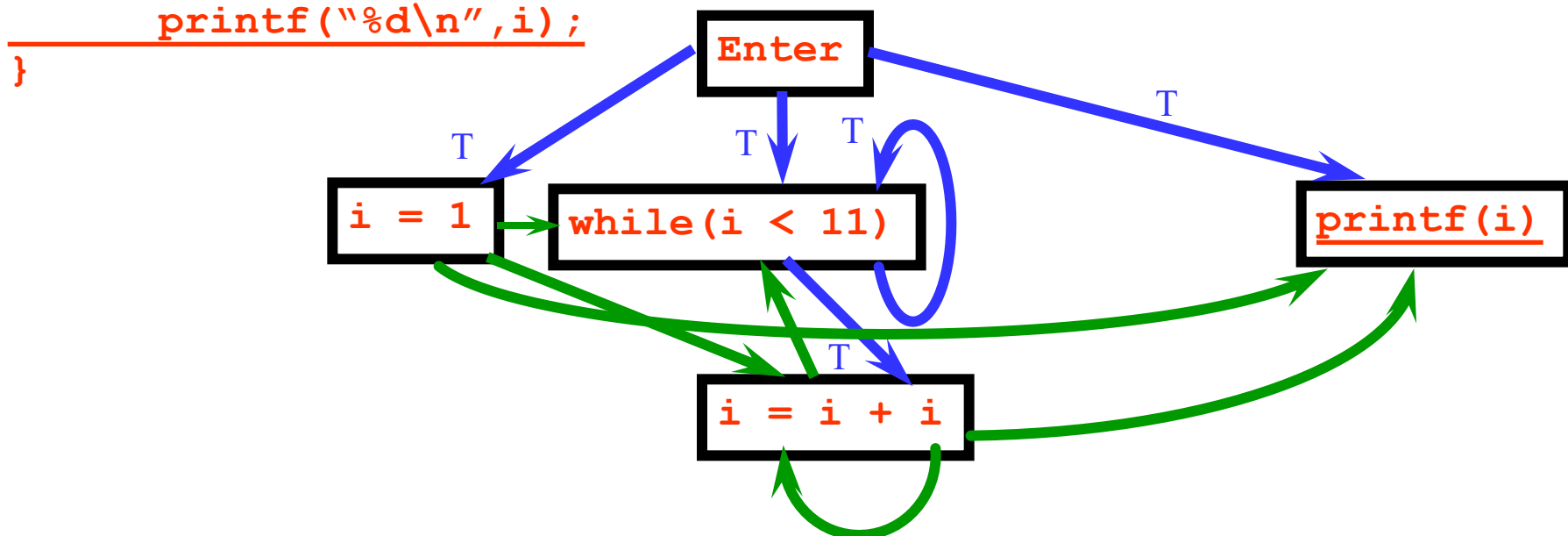
# Backward Slice (4)

```
int main() {  
    int sum = 0;  
    int i = 1;  
    while (i < 11) {  
        sum = sum + i;  
        i = i + 1;  
    }  
    printf("%d\n", sum);  
    printf("%d\n", i);  
}
```



# Slice Extraction

```
int main() {  
  
    int i = 1;  
    while (i < 11) {  
  
        i = i + 1;  
    }  
  
    printf("%d\n", i);  
}
```





```
InBuff = (unsigned char *)from_buf;
outBuff = (unsigned char *)to_buf;
do_decomp = action;

    if (do_decomp == 0) {
        compress();
#ifdef DEBUG
        if(verbose)                dump_tab();
#endif /* DEBUG */
    } else {
        /* Check the magic number */
        if (nomagic == 0) {
            if ((getbyte() != (magic_header[0] & 0xFF))
                || (getbyte() != (magic_header[1] & 0xFF))) {
                fprintf(stderr, "stdin: not in compressed format\n");
                exit(1);
            }
            maxbits = getbyte();    /* set -b from file */
            block_compress = maxbits & BLOCK_MASK;
            maxbits &= BIT_MASK;
            maxmaxcode = 1 << maxbits;
            fsize = 100000;        /* assume stdin large for USERMEM */
            if(maxbits > BITS) {
                fprintf(stderr,
                    "stdin: compressed with %d bits, can only handle %d bits\n",
                    maxbits, BITS);
                exit(1);
            }
        }
#ifdef DEBUG
    }
#endif
    }
    decompress();
#else
```

# *Inter*procedural Slice

```
int main() {  
    int sum = 0;  
    int i = 1;  
    while (i < 11) {  
        sum = add(sum,i) ;  
        i = add(i,1) ;  
    }  
    printf("%d\n",sum) ;  
    printf("%d\n",i) ;  
}
```

```
int add(int x, int y) {  
    return x + y;  
}
```

**Backward slice** with respect to “printf(“%d\n”,i)”

# *Inter*procedural Slice

```
int main() {  
    int sum = 0;  
    int i = 1;  
    while (i < 11) {  
        sum = add(sum,i) ;  
        i = add(i,1) ;  
    }  
    printf("%d\n",sum) ;  
    printf("%d\n",i) ;  
}
```

```
int add(int x, int y) {  
    return x + y;  
}
```

**Backward slice** with respect to “printf(“%d\n”,i)”



# *Inter*procedural Slice

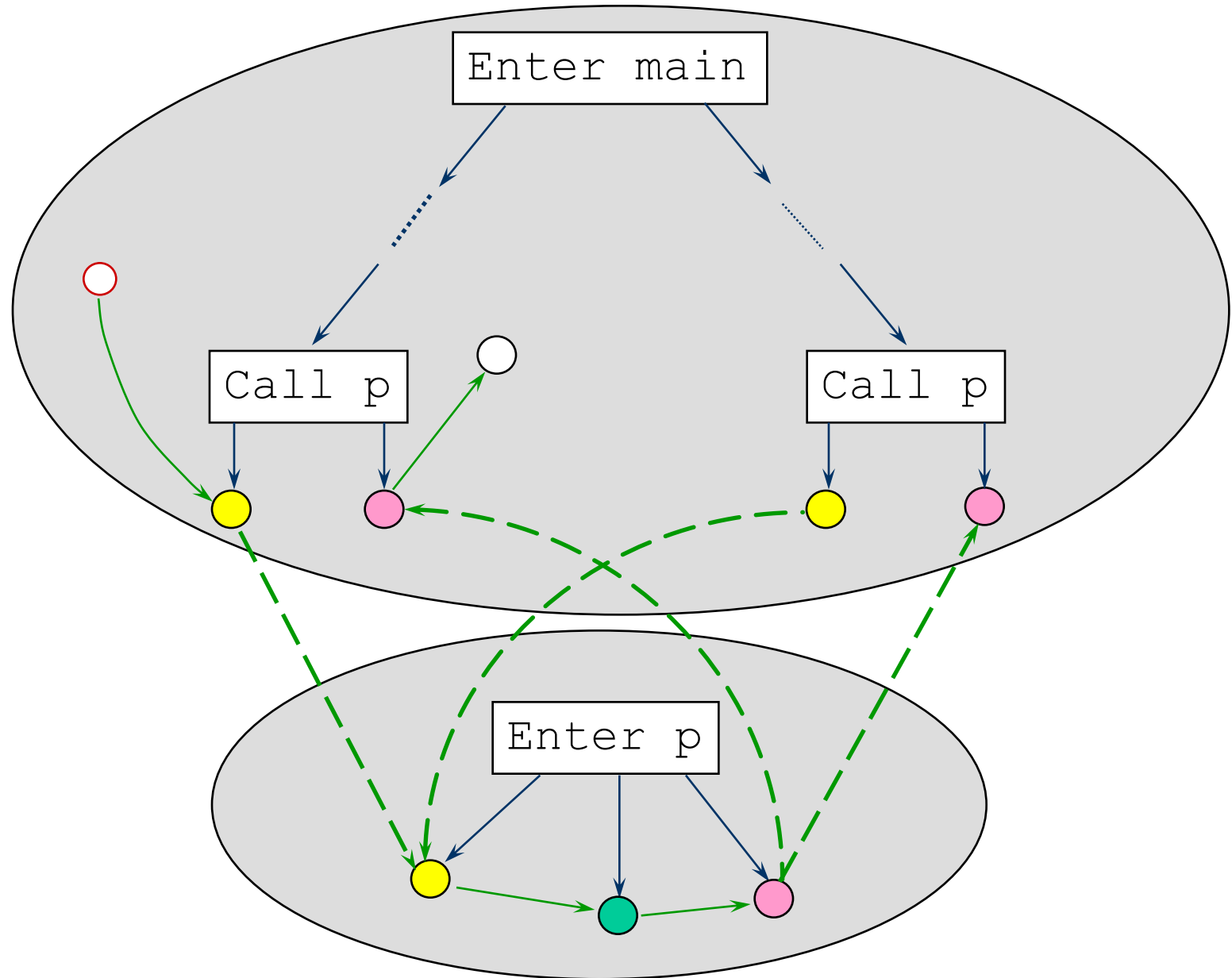
```
int main() {  
    int sum = 0;  
    int i = 1;  
    while (i < 11) {  
        sum = add(sum,i);  
        i = add(i,1);  
    }  
    printf("%d\n",sum);  
    printf("%d\n",i);  
}  
  
int add(int x, int y) {  
    return x + y;  
}
```

Superfluous components included by Weiser's slicing algorithm [TSE 84]  
Left out by algorithm of Horwitz, Reps, & Binkley [PLDI 88; TOPLAS 90]

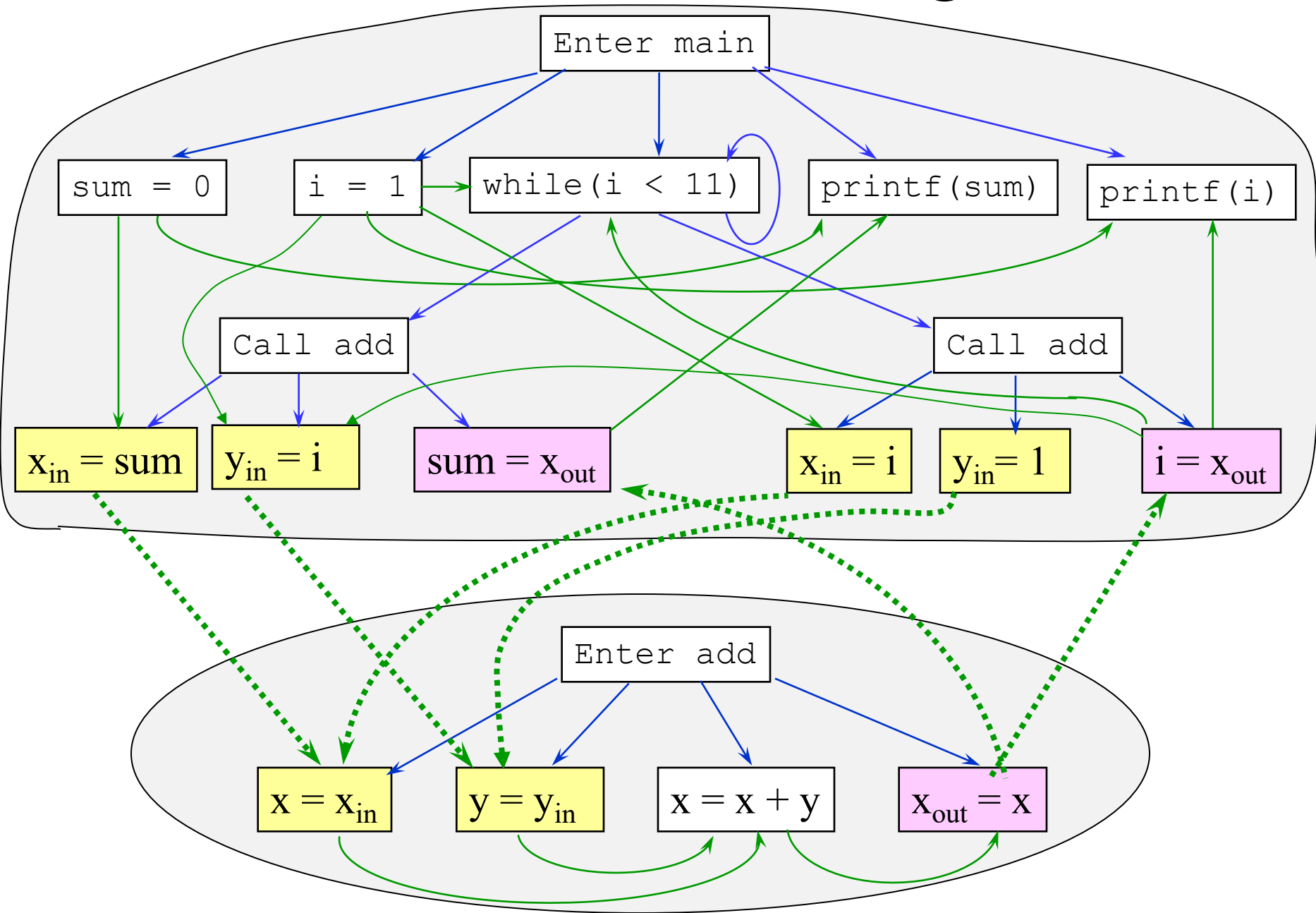
# How is an SDG Created?

- Each PDG has nodes for
  - entry point
  - procedure parameters and function result
- Each call site has nodes for
  - call
  - arguments and function result
- Appropriate edges
  - entry node to parameters
  - call node to arguments
  - call node to entry node
  - arguments to parameters

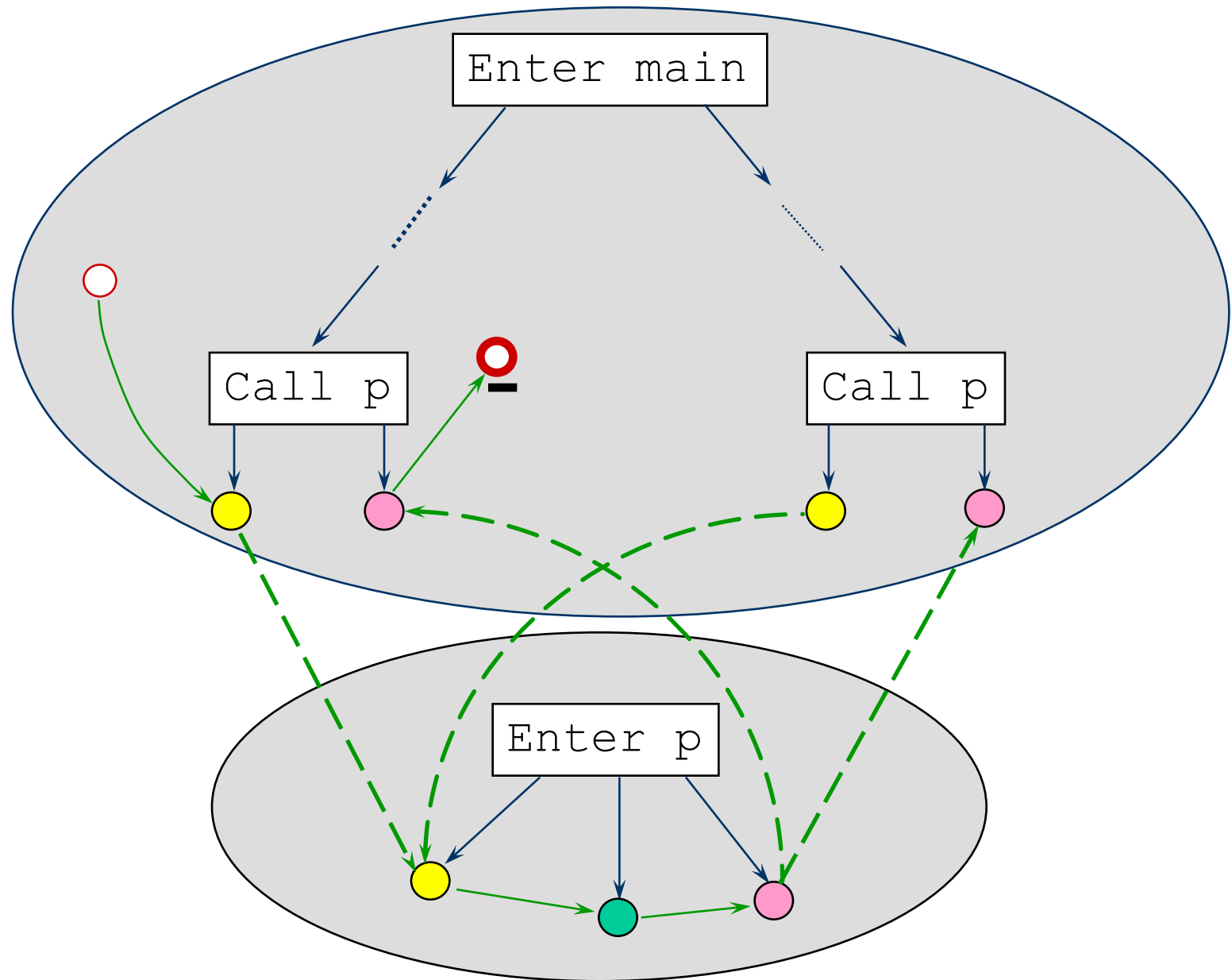
# System Dependence Graph (SDG)



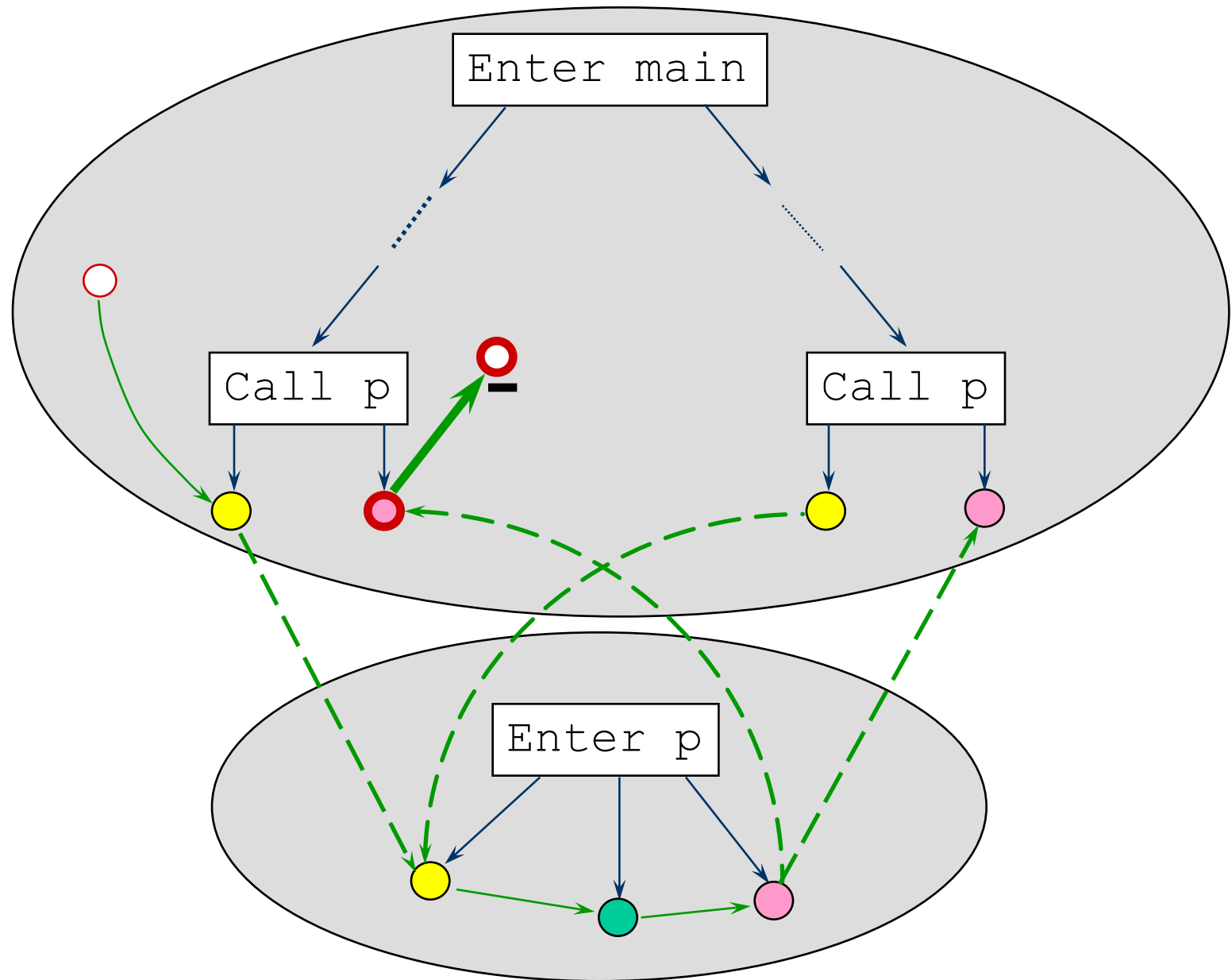
# SDG for the Sum Program



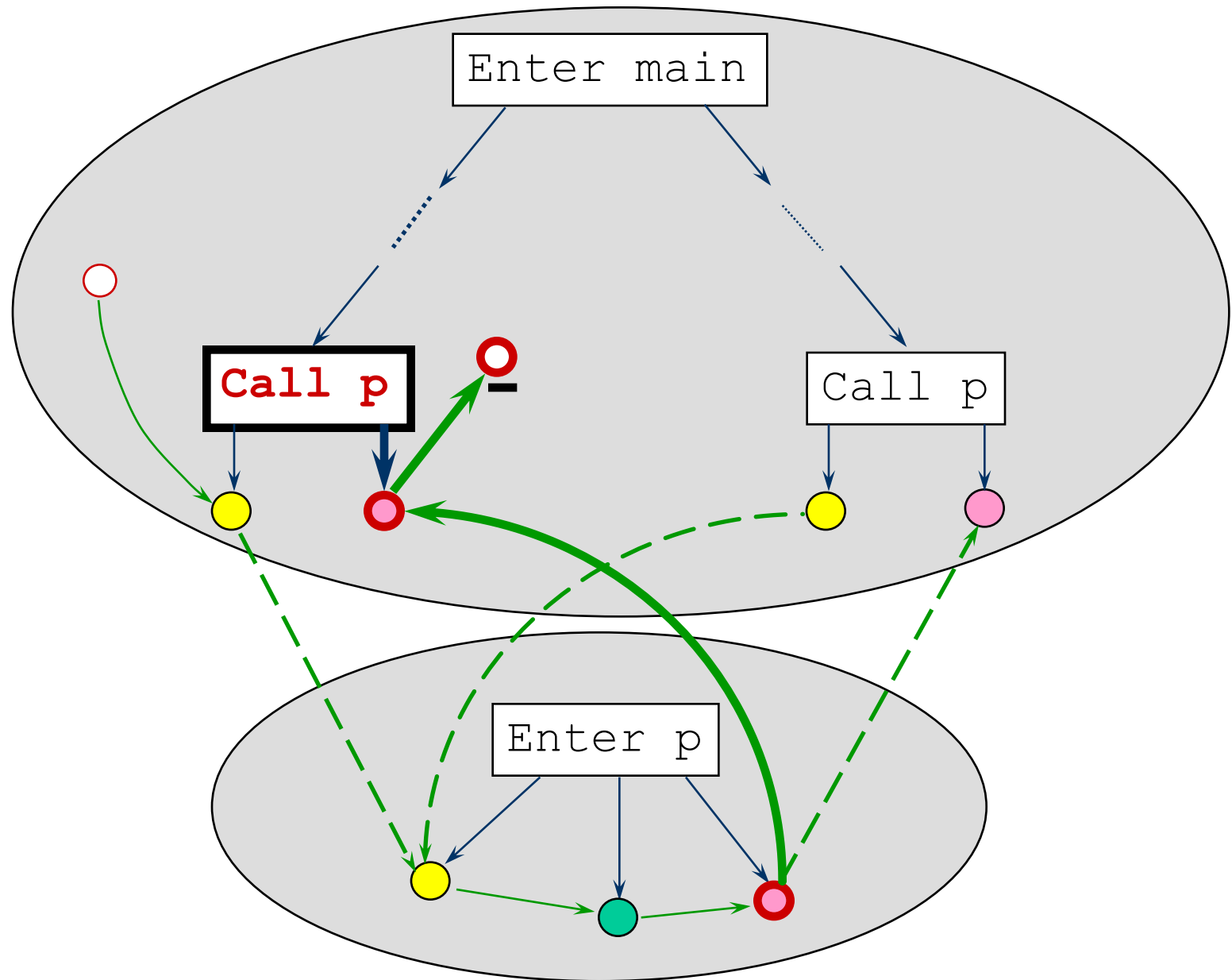
# *Inter*procedural Backward Slice



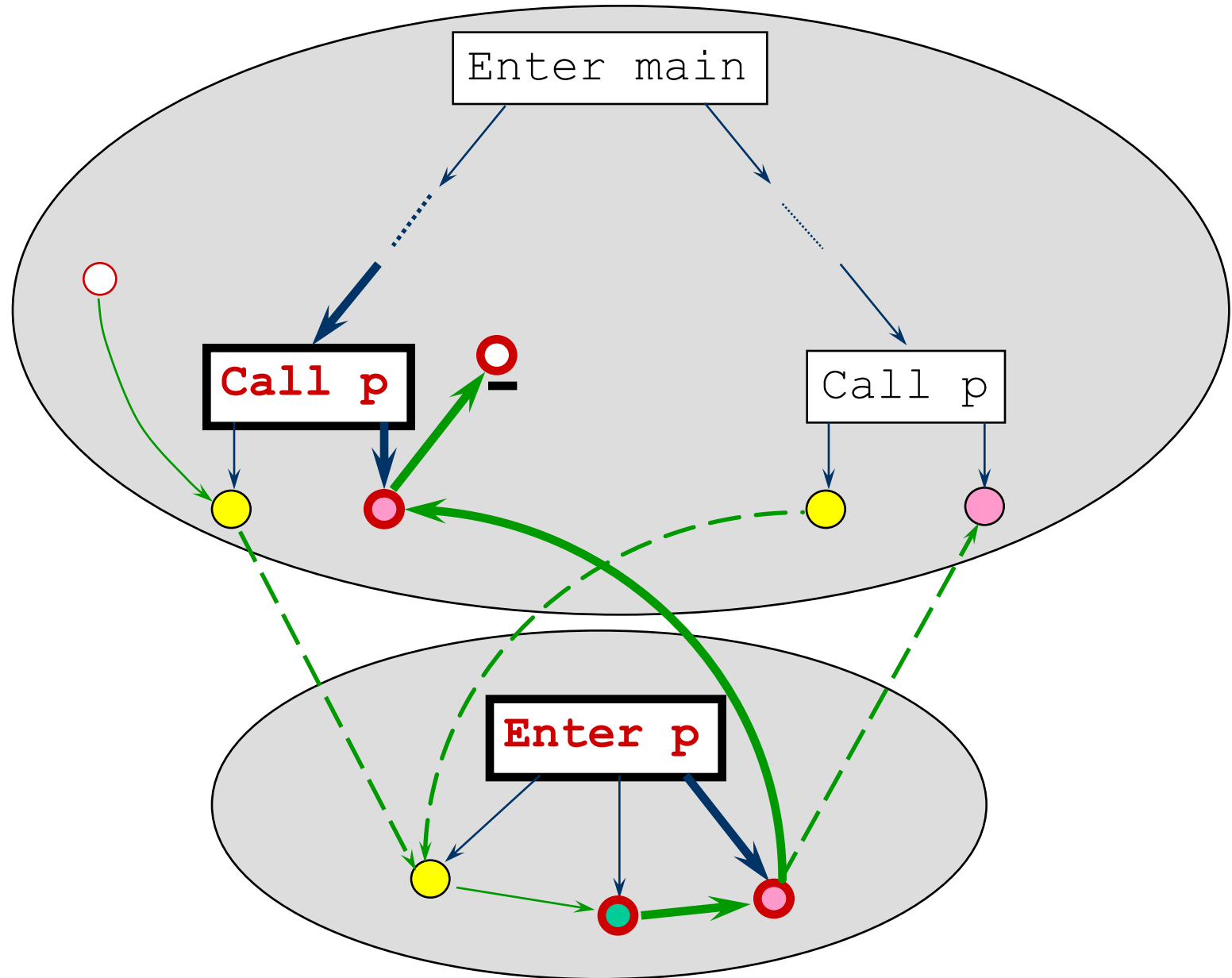
# *Inter*procedural Backward Slice (2)



# *Inter*procedural Backward Slice (3)

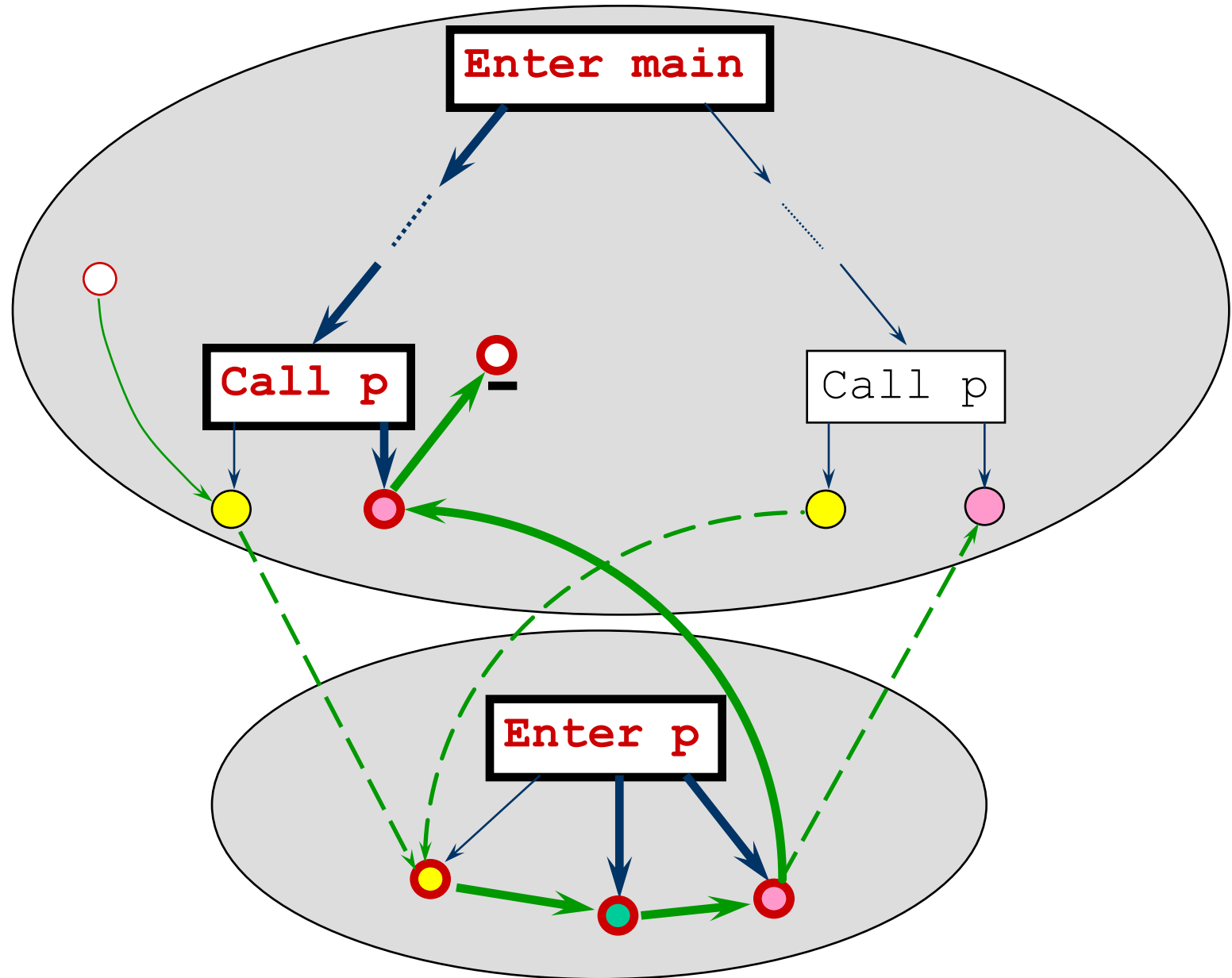


# *Inter*procedural Backward Slice (4)

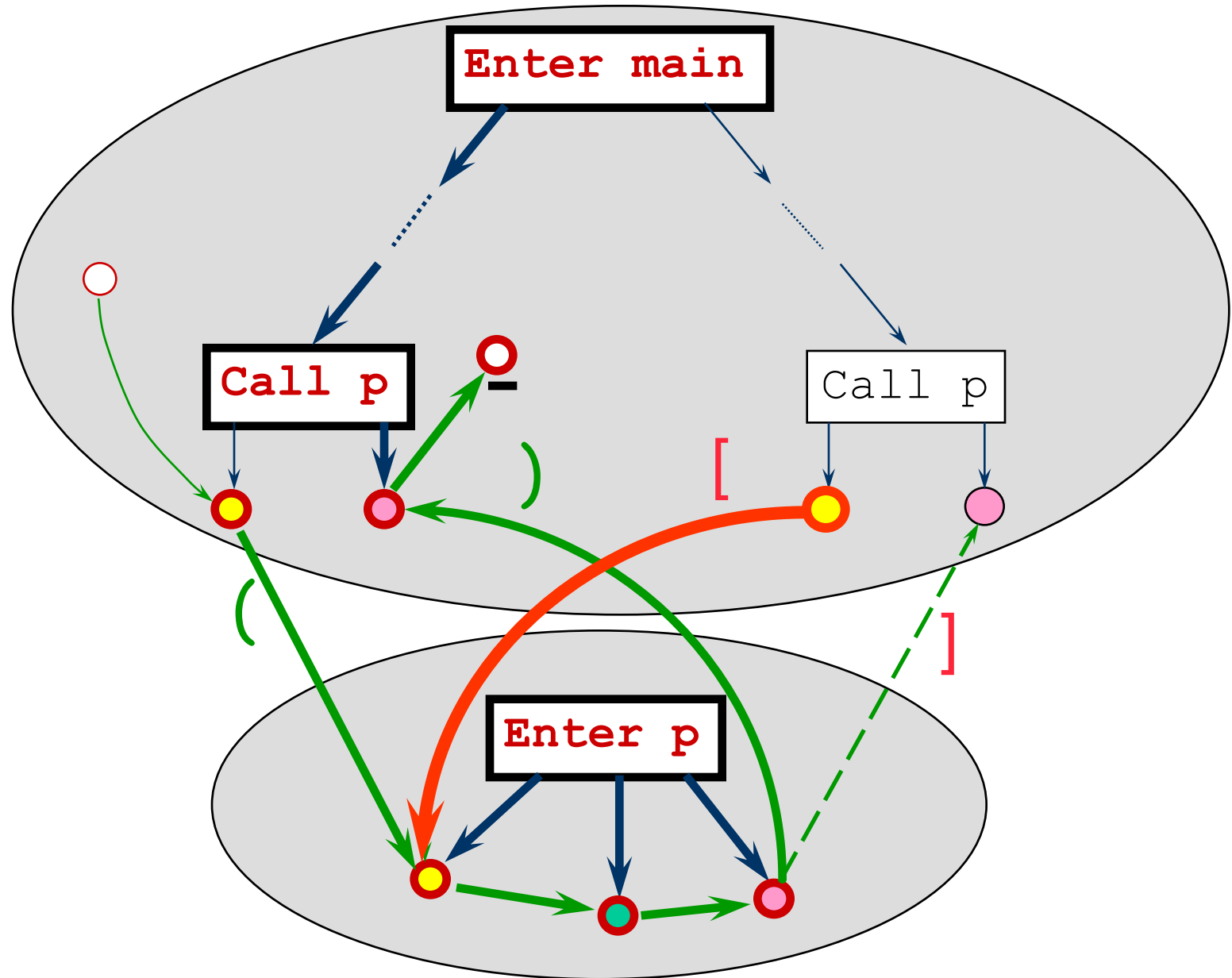




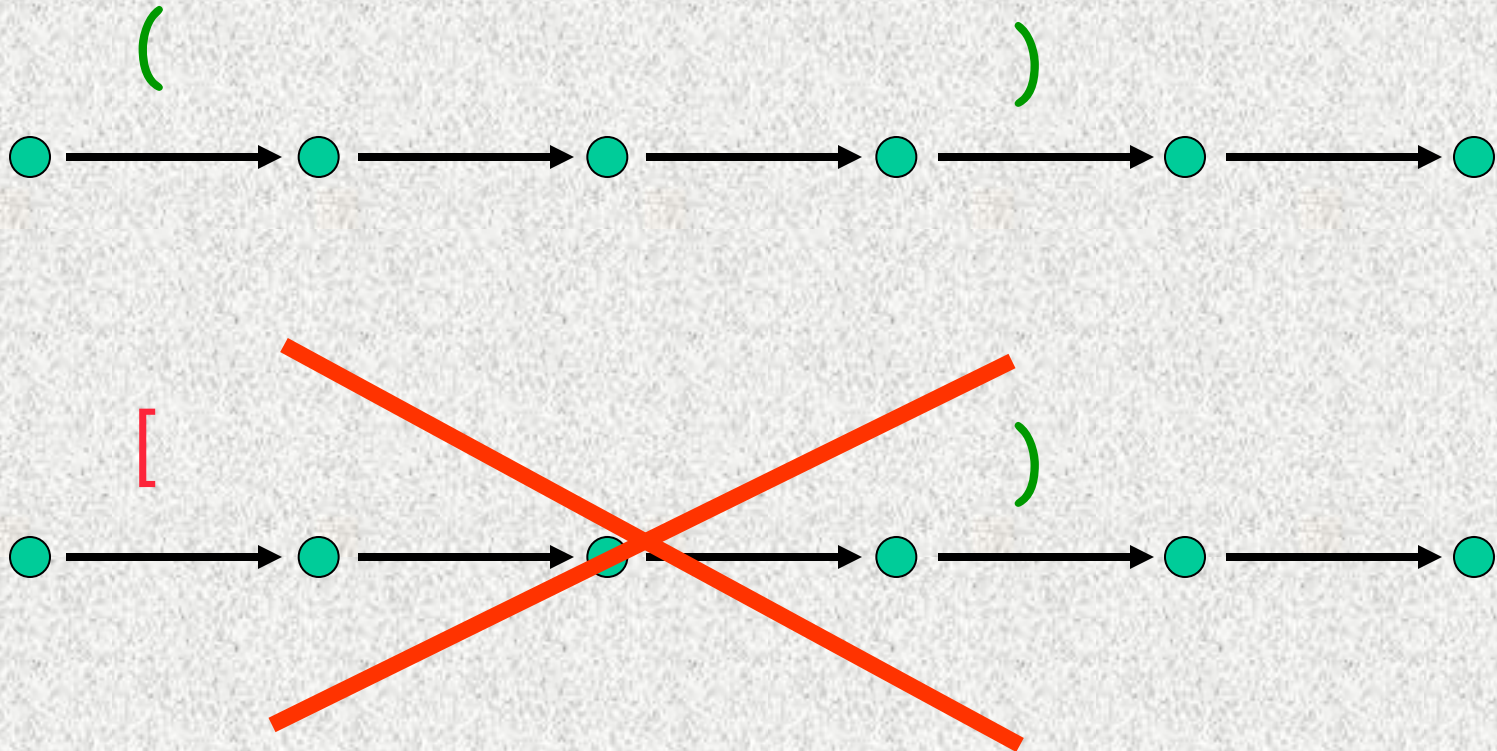
# *Inter*procedural Backward Slice (5)



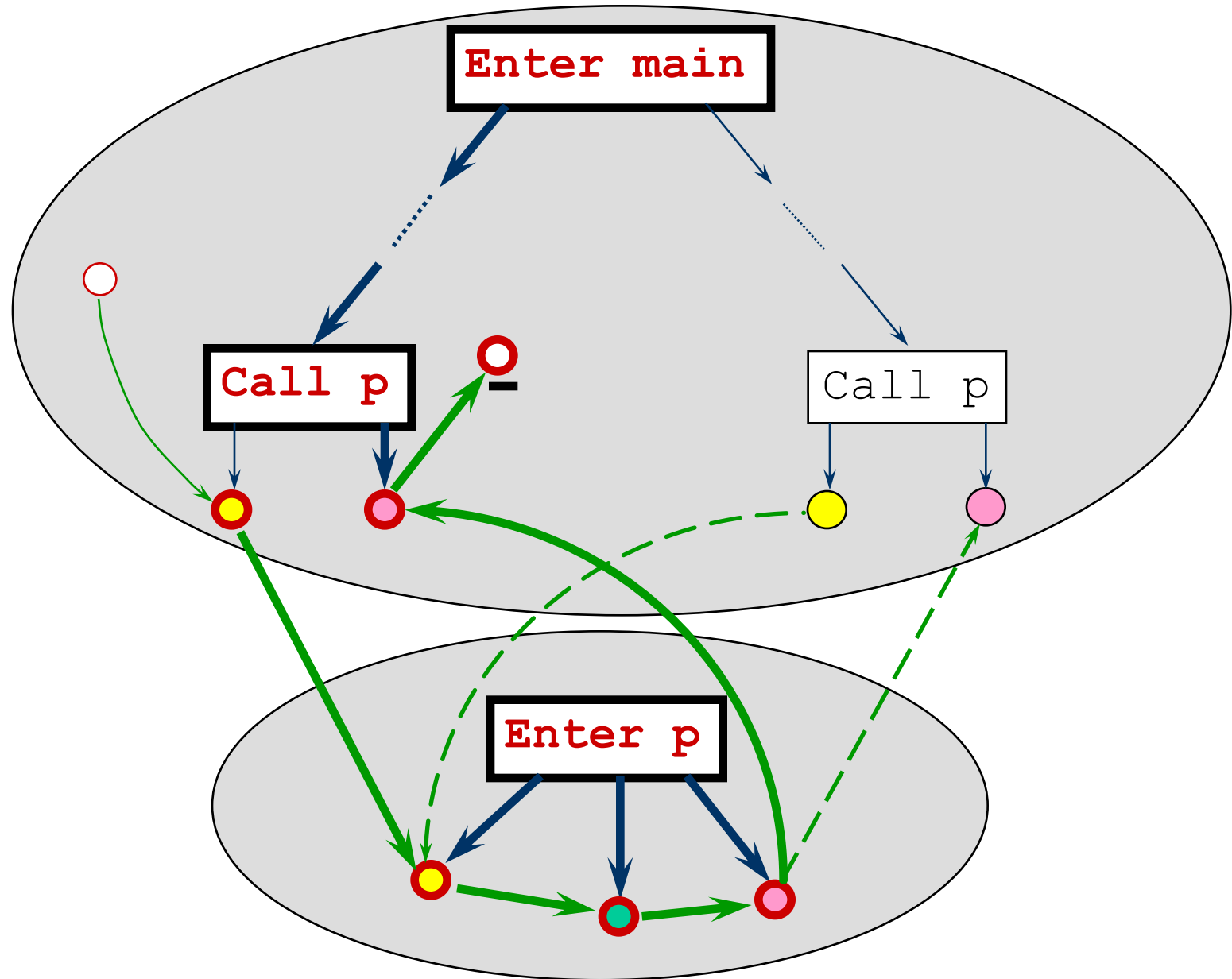
# *Inter*procedural Backward Slice (6)



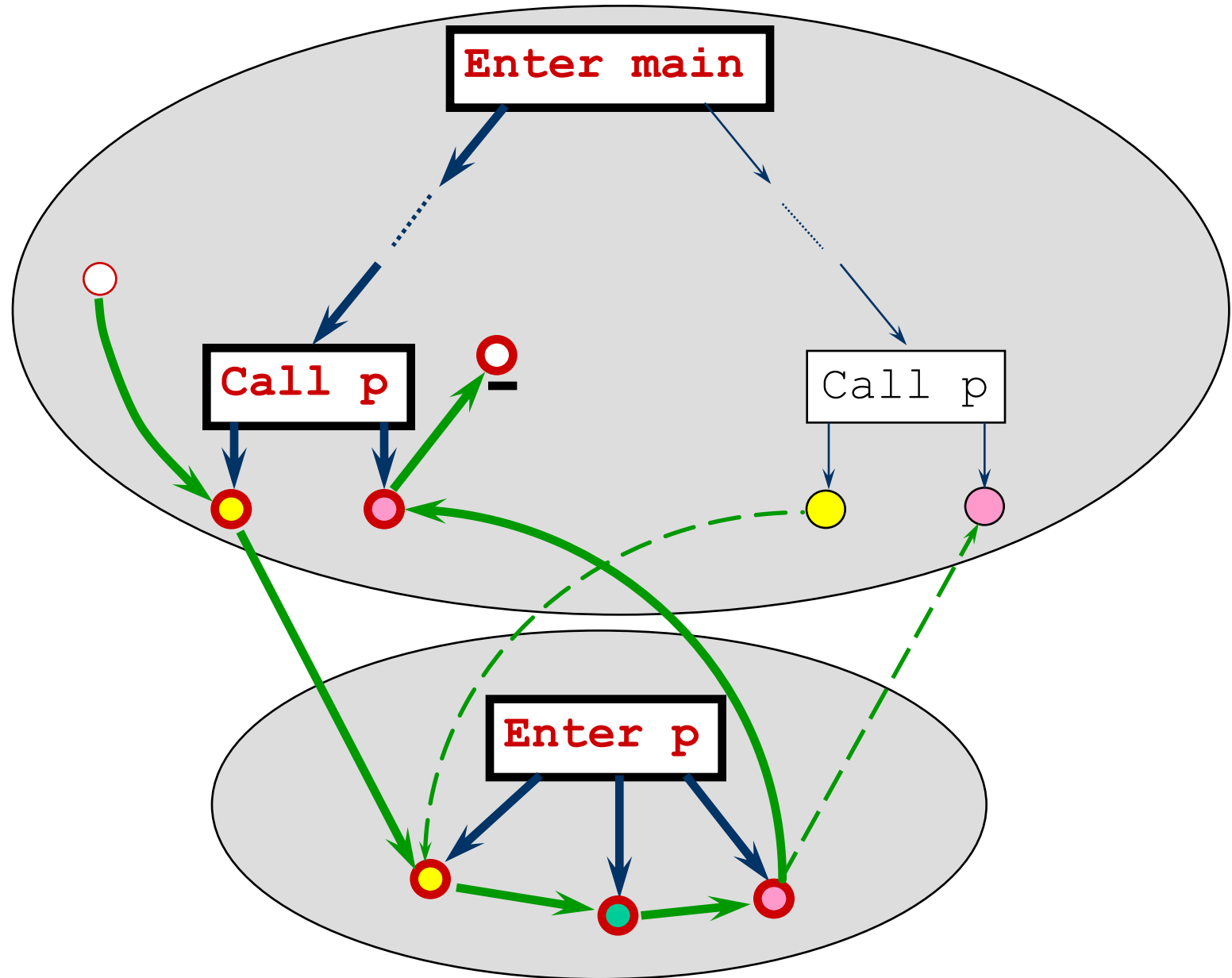
# Matched-Parenthesis Path



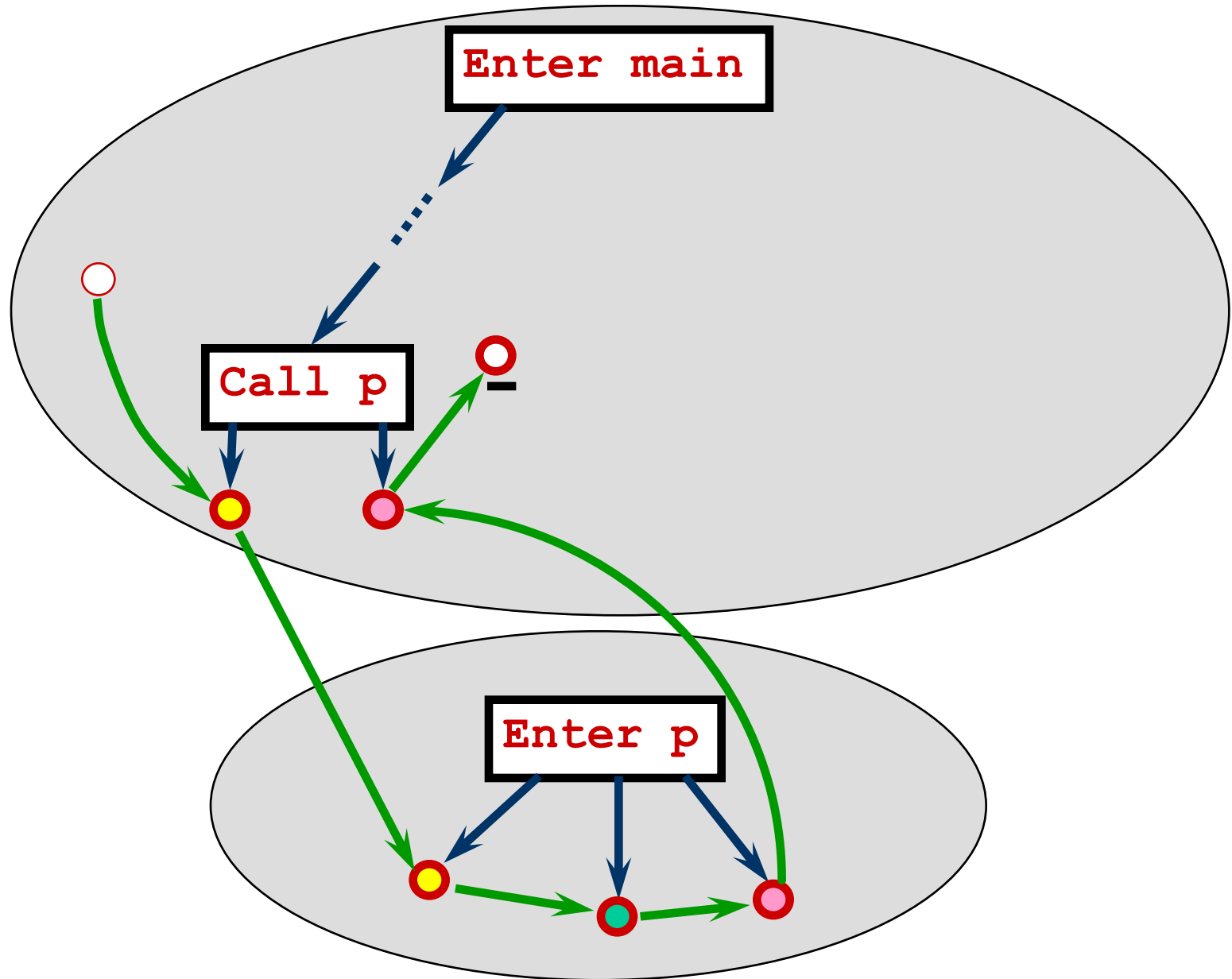
## *Inter*procedural Backward Slice (6)



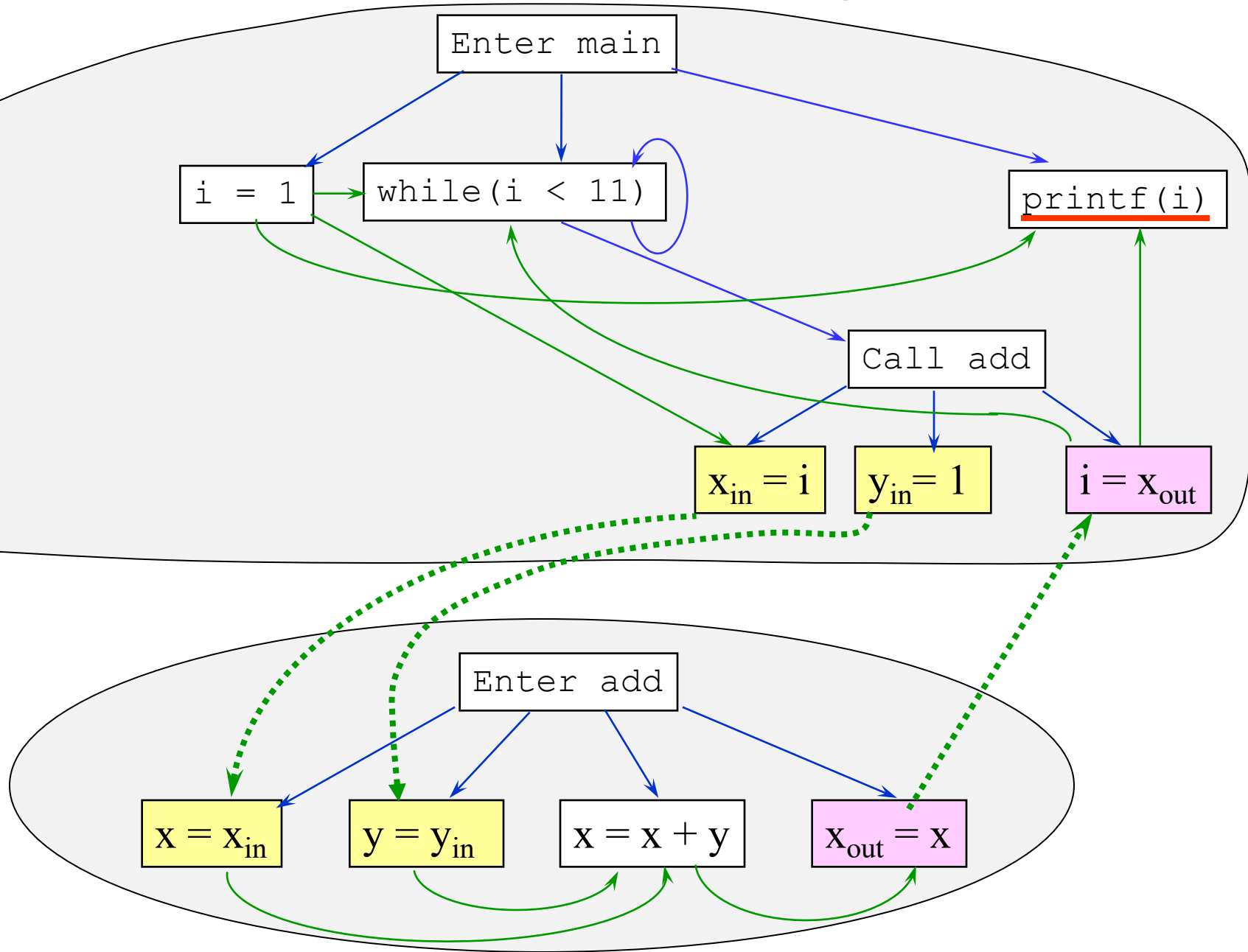
# *Inter*procedural Backward Slice (7)



# Slice Extraction



# Slice of the Sum Program



# CFL-Reachability

[Yannakakis 90]

- $G$ : Graph ( $N$  nodes,  $E$  edges)
- $L$ : A context-free language
- $L$ -path from  $s$  to  $t$  iff  $s \xrightarrow{\alpha}^* t, \alpha \in L$
- Running time:  $O(N^3)$



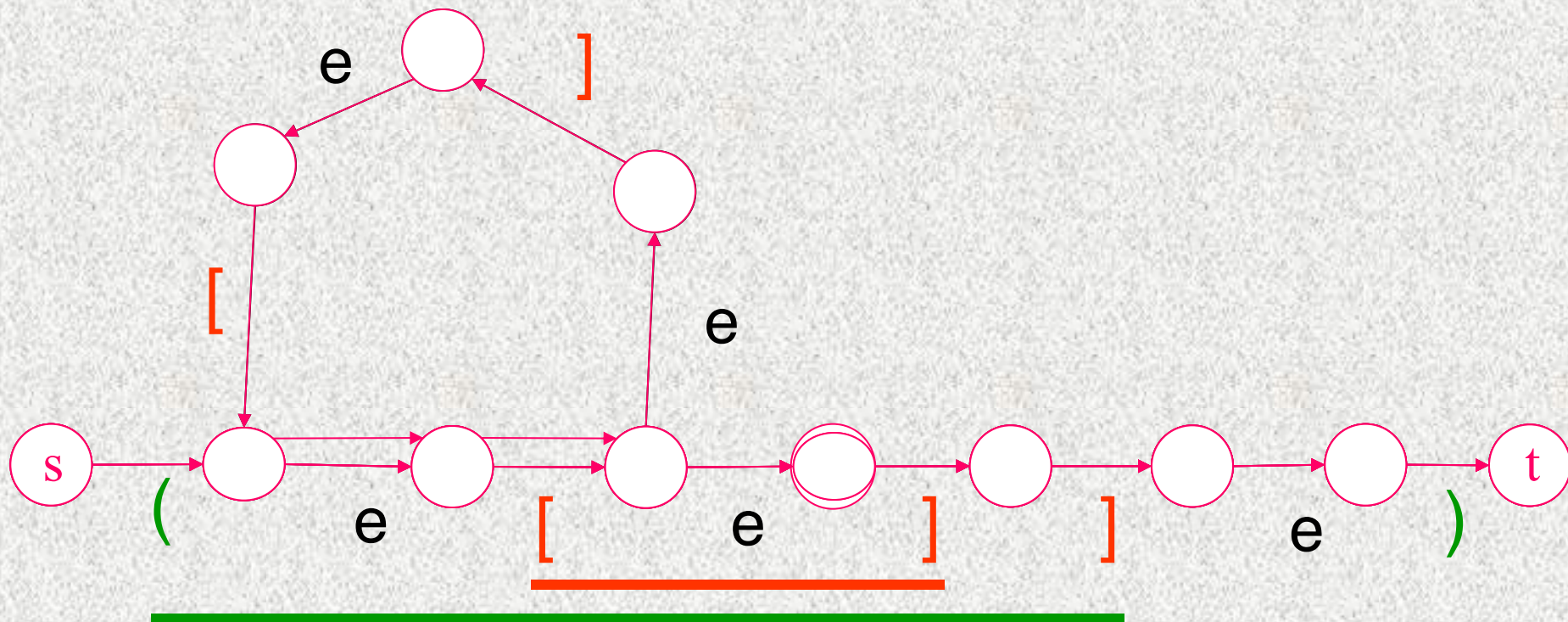
# Interprocedural Slicing via CFL-Reachability

- Graph: System dependence graph
- $L$ :  $L(\textit{matched})$  [roughly]
- Node  $m$  is in the slice w.r.t.  $n$  iff there is an  $L(\textit{matched})$ -path from  $m$  to  $n$



$matched \rightarrow \varepsilon$

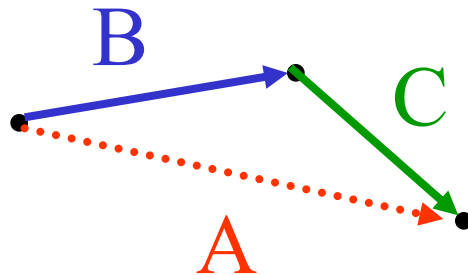
| e  
| [ *matched* ]  
| ( *matched* )  
| *matched matched*



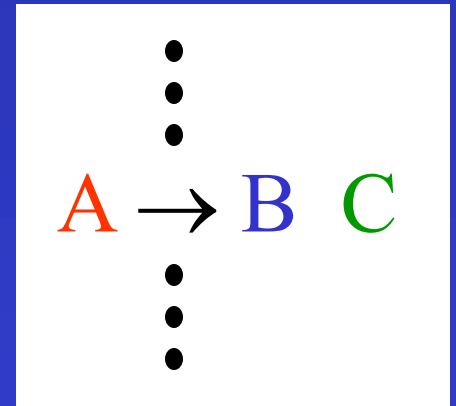
Ordinary CFG Graph Reliability

# CFL-Reachability via Dynamic Programming

Graph



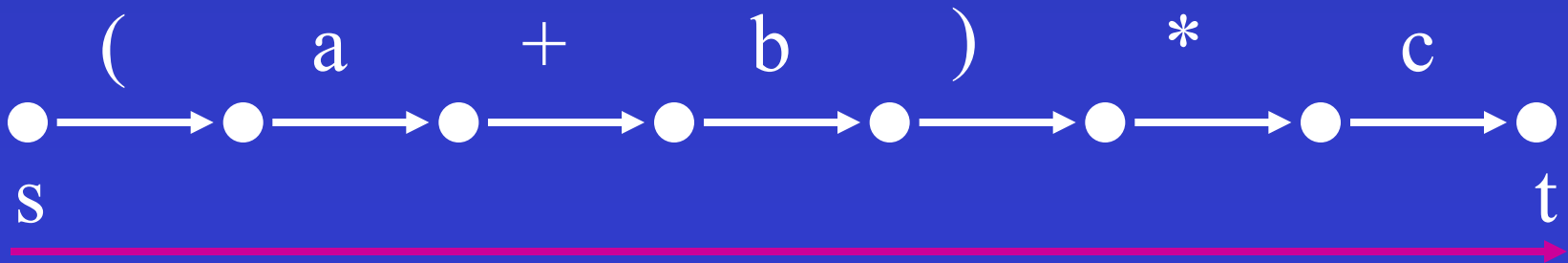
Grammar



# Degenerate Case: CFL-Recognition

$\text{exp} \rightarrow \text{id} \mid \text{exp} + \text{exp} \mid \text{exp} * \text{exp} \mid ( \text{exp} )$

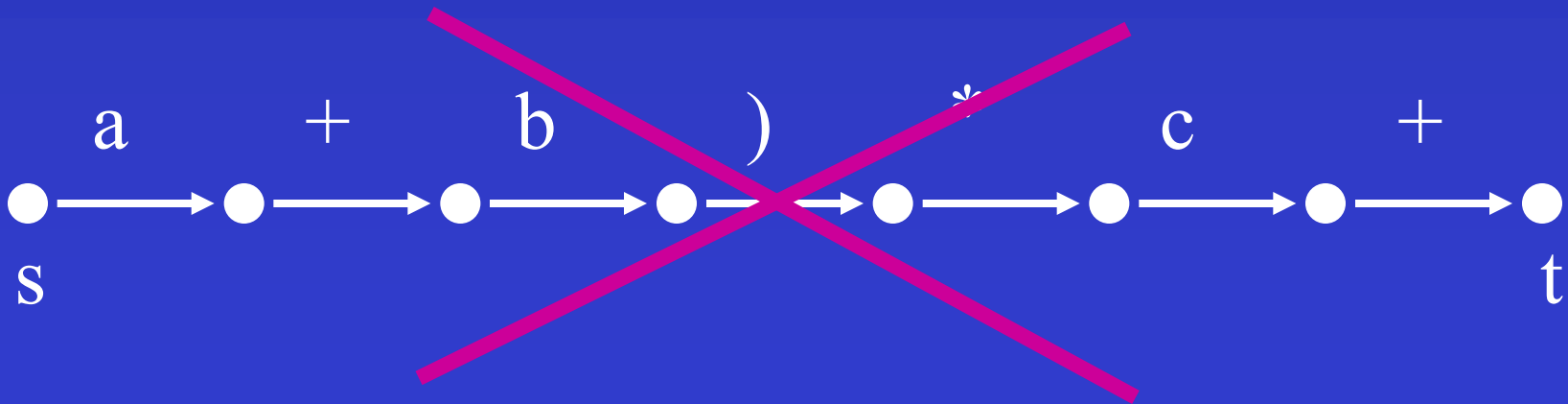
“(a + b) \* c”  $\in L(\text{exp})$  ?



# Degenerate Case: CFL-Recognition

$\text{exp} \rightarrow \text{id} \mid \text{exp} + \text{exp} \mid \text{exp} * \text{exp} \mid ( \text{exp} )$

“a + b) \* c +”  $\in L(\text{exp})$  ?



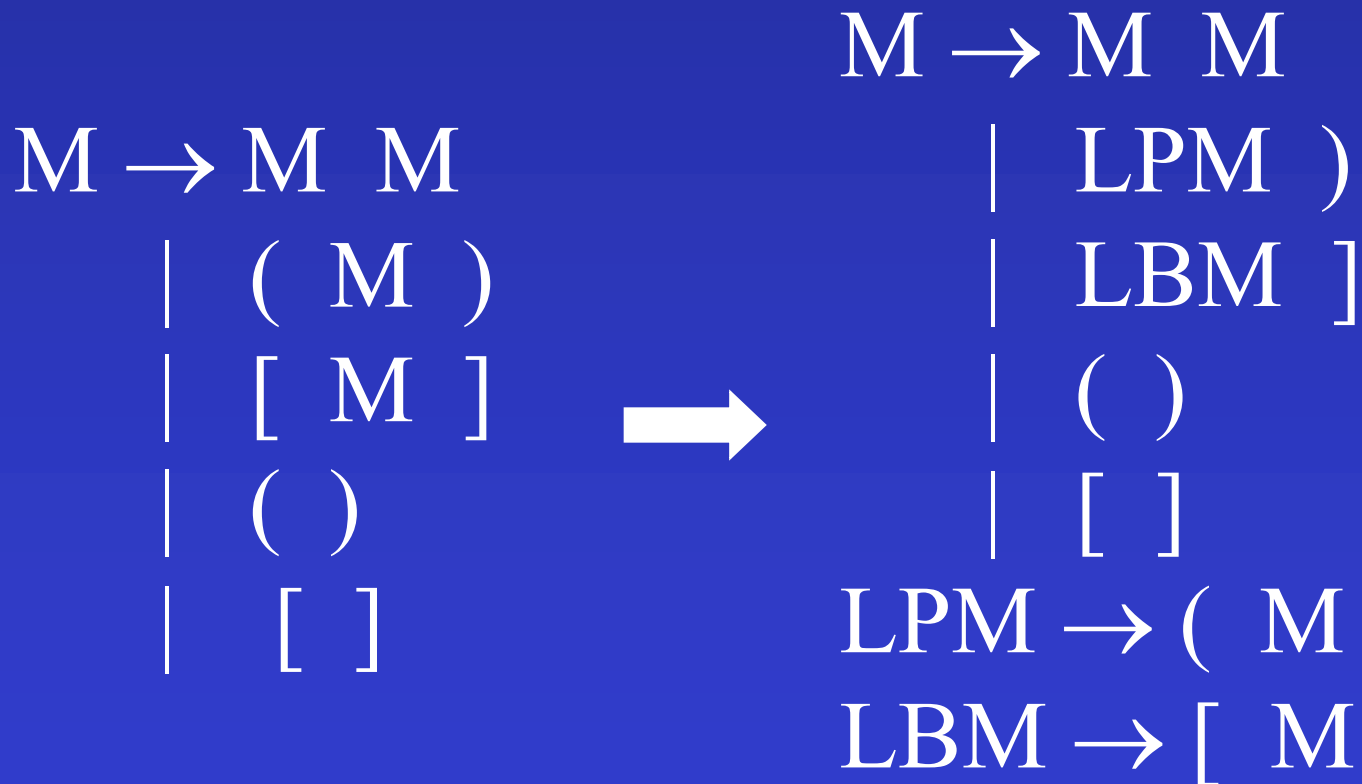
# CYK: Context-Free Recognition

$$\begin{array}{l} M \rightarrow M \ M \\ | \ ( \ M \ ) \\ | \ [ \ M \ ] \\ | \ ( \ ) \\ | \ [ \ ] \end{array}$$

$\boxed{?} = “([ ])[ ]”$

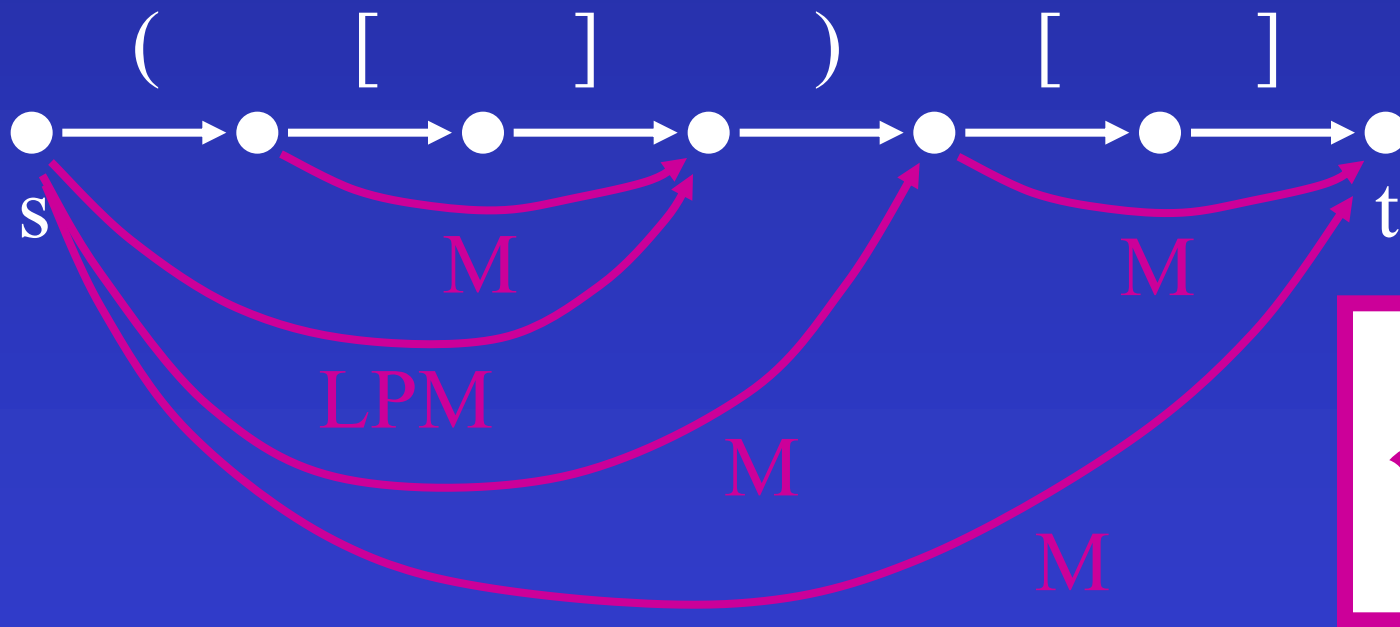
Is  $\boxed{?} \in L(M)$ ?

# CYK: Context-Free Recognition



# CYK

Is “([ ] ) [ ]”  $\in L(M)$ ?

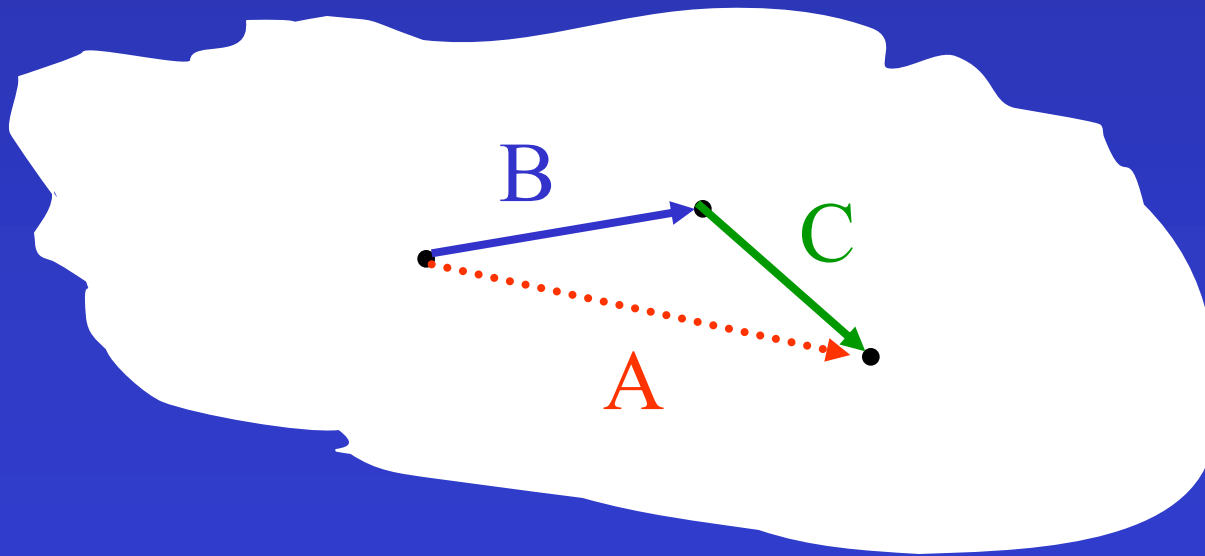


$M \rightarrow M \ M \mid LPM \ ) \mid LBM \ ] \mid ( \ ) \mid [ \ ]$   
 $LPM \rightarrow ( \ M \qquad LBM \rightarrow [ \ M$

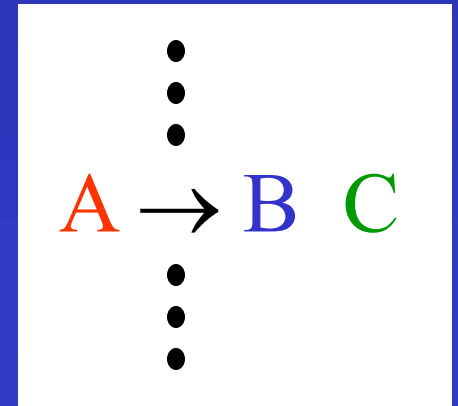


# CFL-Reachability via Dynamic Programming

Graph



Grammar

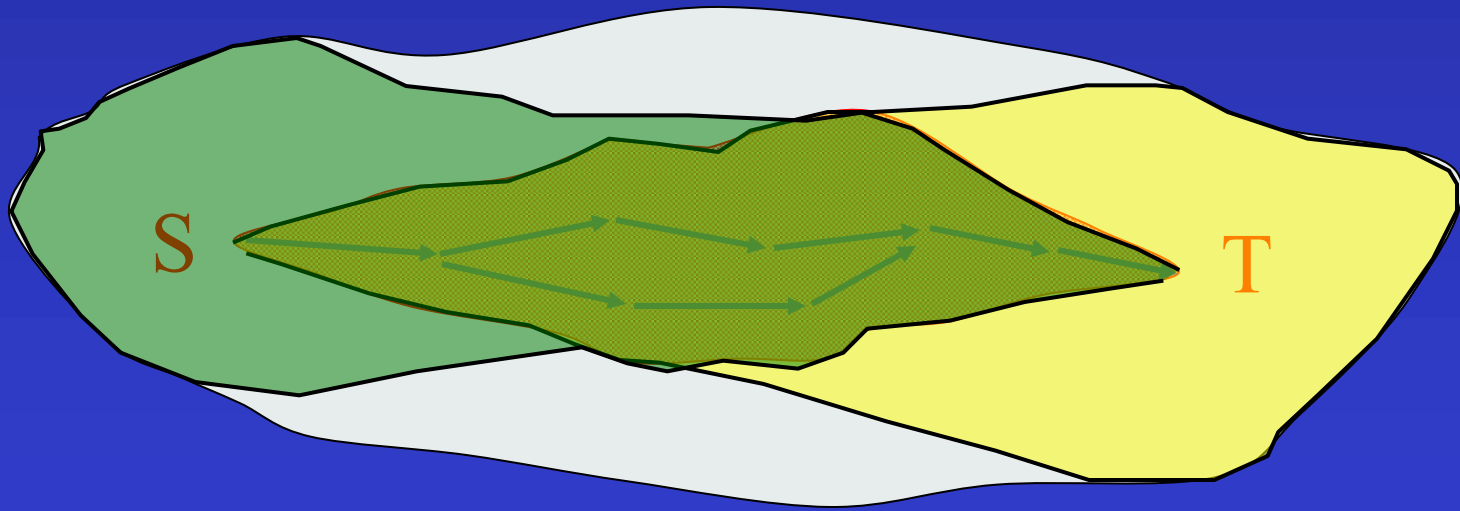


# Dynamic Transitive Closure ?!

- Aiken et al.
  - Set-constraint solvers
  - Points-to analysis
- Henglein et al.
  - type inference
- But a CFL captures a **non-transitive** reachability relation [Valiant 75]

# Program Chopping

Given source  $S$  and target  $T$ , what program points transmit effects from  $S$  to  $T$ ?



Intersect forward slice from  $S$  with backward slice from  $T$ , right?

# Non-Transitivity and Slicing

```
int main() {  
    int sum = 0;  
    int i = 1;  
    while (i < 11) {  
        sum = add(sum,i);  
        i = add(i,1);  
    }  
    printf("%d\n",sum);  
    printf("%d\n",i);  
}  
  
int add(int x, int y) {  
    return x + y;  
}
```

**Forward slice** with respect to “sum = 0”

# Non-Transitivity and Slicing

```
int main() {  
    int sum = 0;  
    int i = 1;  
    while (i < 11) {  
        sum = add(sum,i);  
        i = add(i,1);  
    }  
    printf("%d\n",sum);  
    printf("%d\n",i);  
}  
  
int add(int x, int y) {  
    return x + y;  
}
```

**Forward slice** with respect to “sum = 0”

# Non-Transitivity and Slicing

```
int main() {  
    int sum = 0;  
    int i = 1;  
    while (i < 11) {  
        sum = add(sum,i) ;  
        i = add(i,1) ;  
    }  
    printf("%d\n",sum) ;  
    printf("%d\n",i) ;  
}
```

```
int add(int x, int y) {  
    return x + y;  
}
```

**Backward slice** with respect to “printf(“%d\n”,i)”

# Non-Transitivity and Slicing

```
int main() {  
    int sum = 0;  
    int i = 1;  
    while (i < 11) {  
        sum = add(sum,i) ;  
        i = add(i,1) ;  
    }  
    printf("%d\n",sum) ;  
    printf("%d\n",i) ;  
}  
  
int add(int x, int y) {  
    return x + y;  
}
```

**Backward slice** with respect to “printf(“%d\n”,i)”

# Non-Transitivity and Slicing

```
int main() {  
    int sum = 0;  
    int i = 1;  
    while (i < 11) {  
        sum = add(sum,i);  
        i = add(i,1);  
    }  
    printf("%d\n",sum);  
    printf("%d\n",i);  
}
```

```
int add(int x, int y) {  
    return x + y;  
}
```

**Forward slice** with respect to “sum = 0”



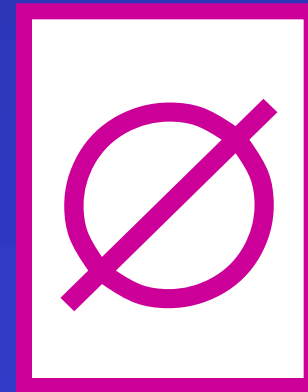
**Backward slice** with respect to “printf(“%d\n”,i)”



# Non-Transitivity and Slicing

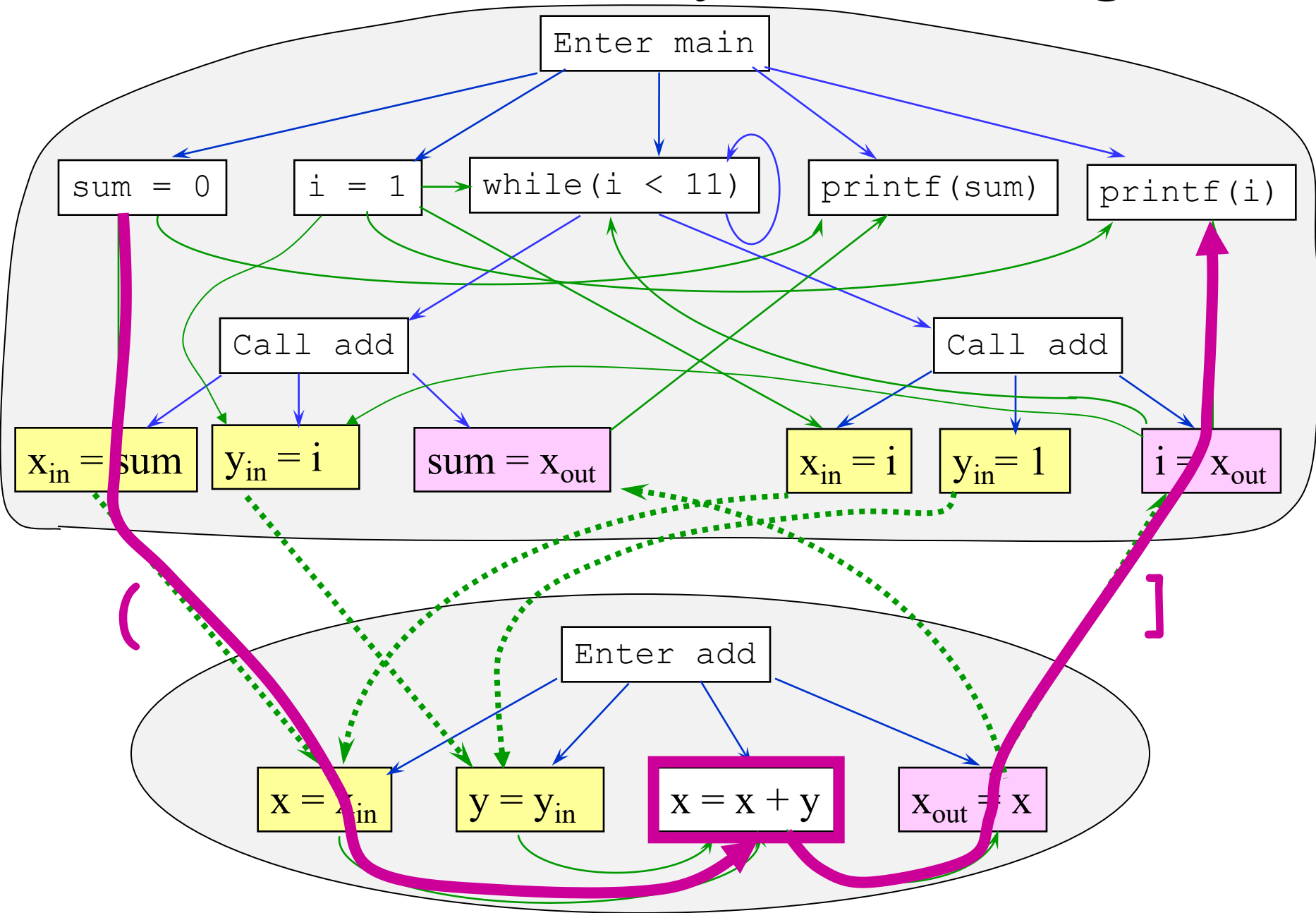
```
int main() {  
    int sum = 0;  
    int i = 1;  
    while (i < 11) {  
        sum = add(sum,i);  
        i = add(i,1);  
    }  
    printf("%d\n",sum);  
    printf("%d\n",i);  
}
```

```
int add(int x, int y) {  
    return x + y;  
}
```



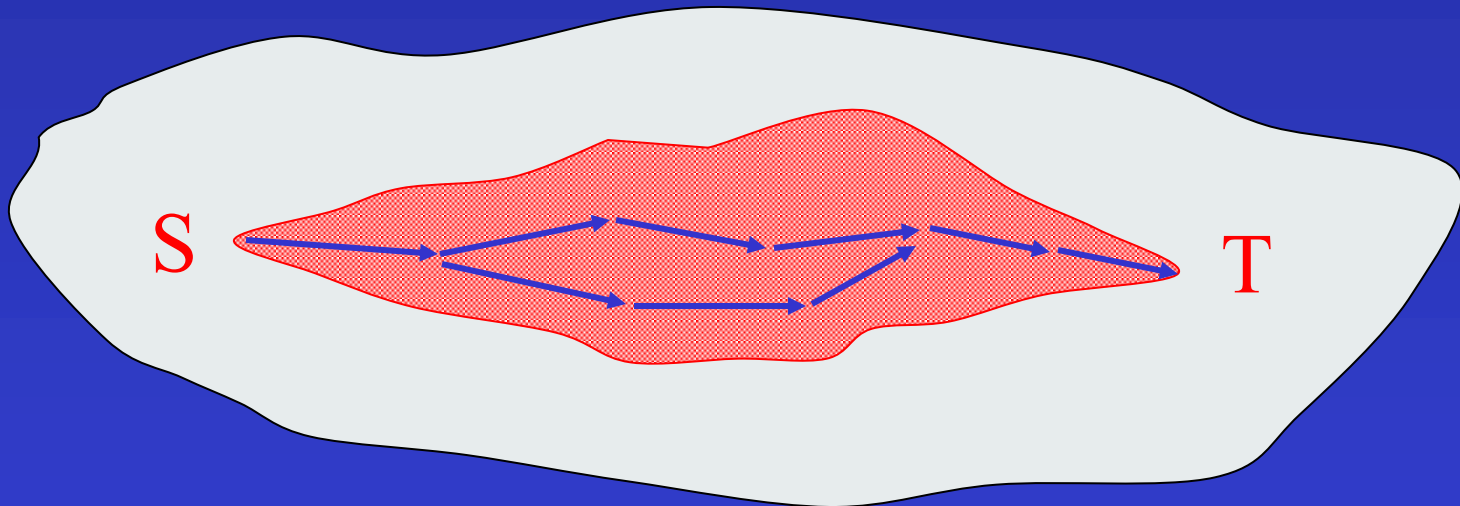
**Chop** with respect to “sum = 0” and “printf(“%d\n”,i)”

# Non-Transitivity and Slicing



# Program Chopping

Given source  $S$  and target  $T$ , what program points transmit effects from  $S$  to  $T$ ?



“Precise interprocedural chopping”  
[Reps & Rosay FSE 95]

# CF-Recognition vs. CFL-Reachability

- CF-Recognition
  - Chain graphs
  - General grammar: sub-cubic time [Valiant75]
  - LL(1), LR(1): linear time
- CFL-Reachability
  - General graphs:  $O(N^3)$
  - LL(1):  $O(N^3)$
  - LR(1):  $O(N^3)$
  - Certain kinds of graphs:  $O(N+E)$
  - Regular languages:  $O(N+E)$

Gen/kill IDFA

GMOD IDFA

# Regular-Language Reachability

[Yannakakis 90]

- $G$ : Graph ( $N$  nodes,  $E$  edges)
- $L$ : A regular language
- $L$ -path from  $s$  to  $t$  iff  $s \xrightarrow{\alpha}^* t, \alpha \in L$
- Running time:  $O(N+E)$  — vs.  $O(N^3)$
- Ordinary reachability (= transitive closure)
  - Label each edge with  $e$
  - $L$  is  $e^*$

# Themes

- Harnessing CFL-reachability
- Relationship to other analysis paradigms
- Exhaustive alg.  $\Rightarrow$  Demand alg.
- Understanding complexity
  - Linear . . . cubic . . . undecidable
- Beyond CFL-reachability

# Relationship to Other Analysis Paradigms

- Dataflow analysis
  - reachability versus equation solving
- Deduction
- Set constraints

# Dataflow Analysis

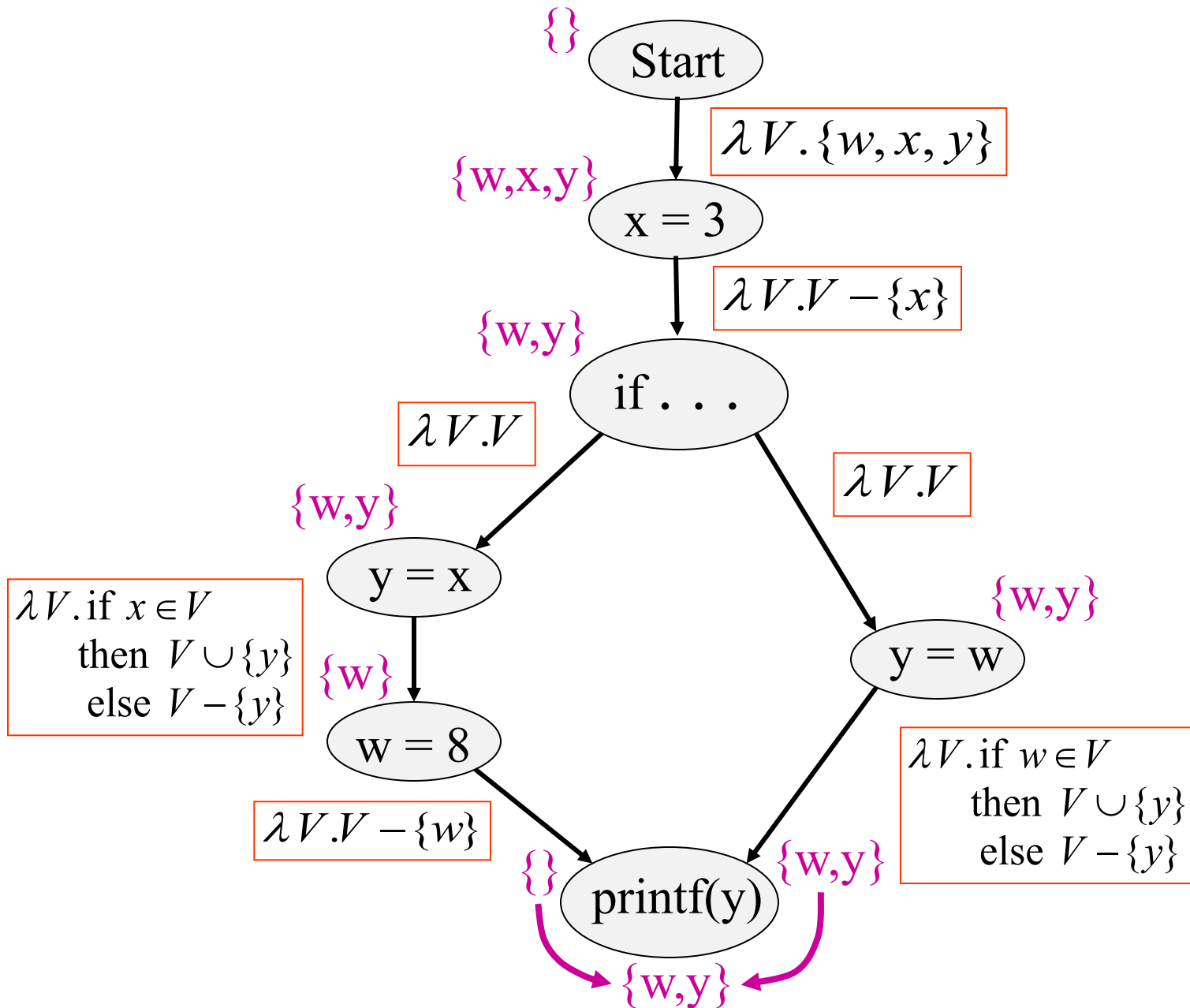
- Goal: For each point in the program, determine a superset of the “facts” that could possibly hold during execution
- Examples
  - Constant propagation
  - Reaching definitions
  - Live variables
  - Possibly uninitialized variables



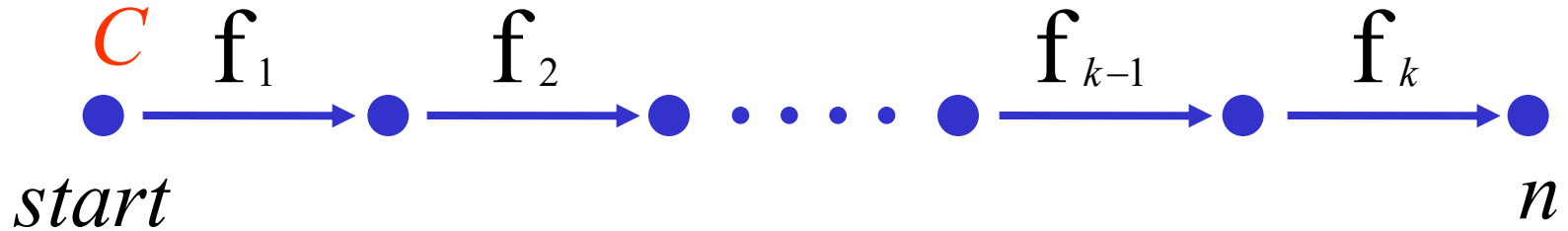
# Useful For . . .

- Optimizing compilers
- Parallelizing compilers
- Tools that detect possible logical errors
- Tools that show the effects of a proposed modification

# Possibly Uninitialized Variables

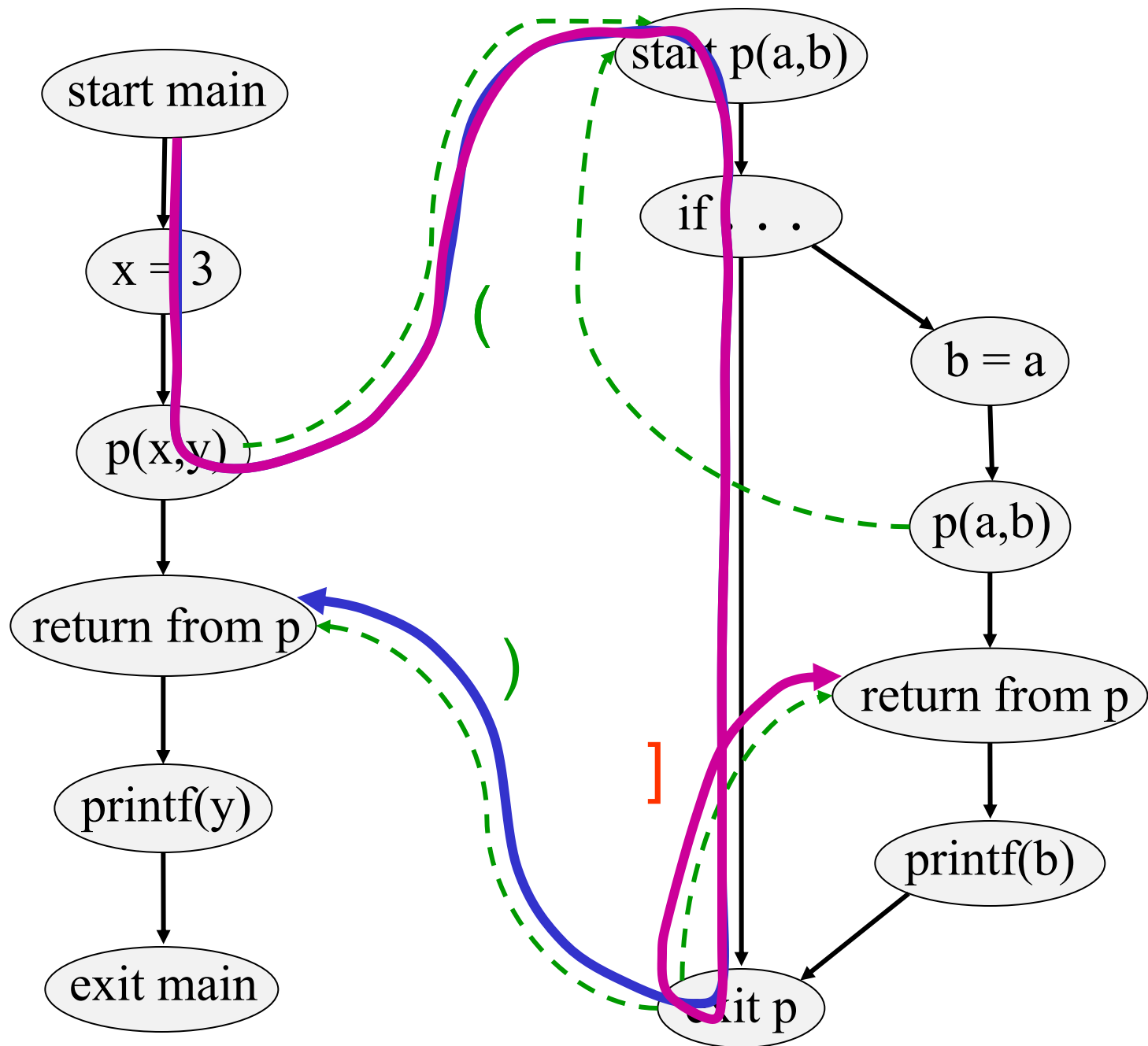


# Precise *Intra*procedural Analysis

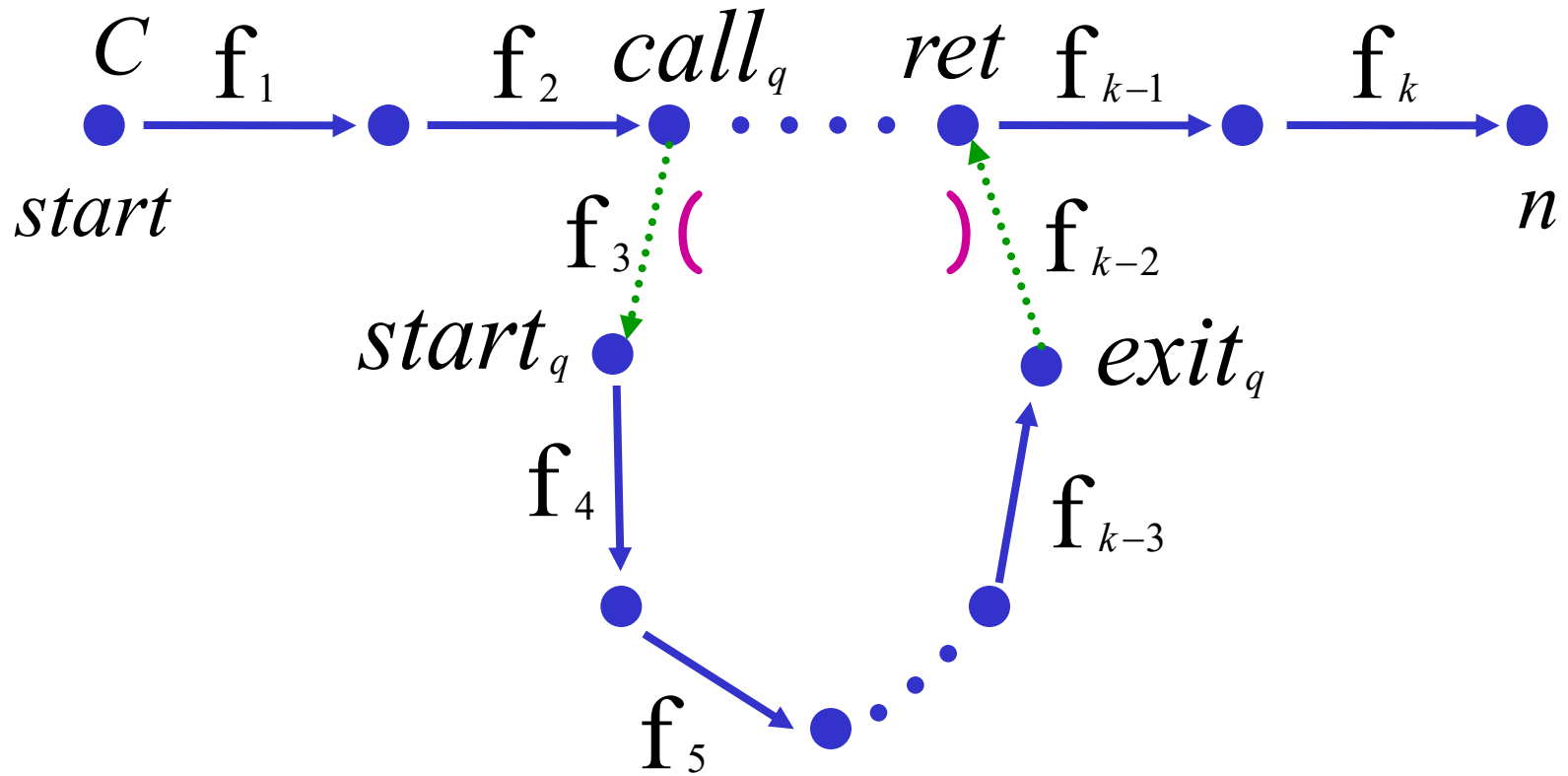


$$\text{pf}_p = f_k \circ f_{k-1} \cdots \circ f_2 \circ f_1$$

$$\text{MOP}[n] = \bigcup_{p \in \text{PathsTo}[n]} \text{pf}_p(C)$$



# Precise *Inter*procedural Analysis



$$MOMP[n] = \bigcup_{p \in \text{MatchedPathsTo}[n]} pf_p(C)$$

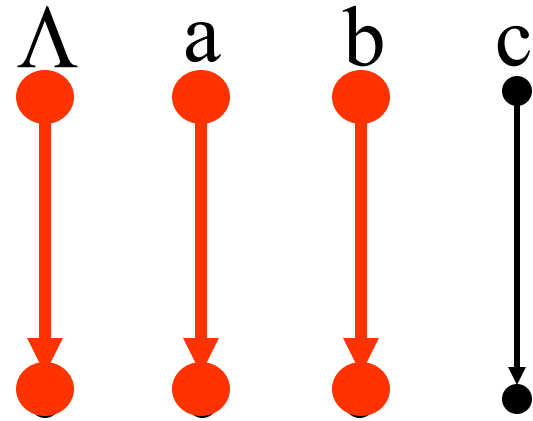
[Sharir & Pnueli 81]

# Representing Dataflow Functions

Identity Function

$$f = \lambda V.V$$

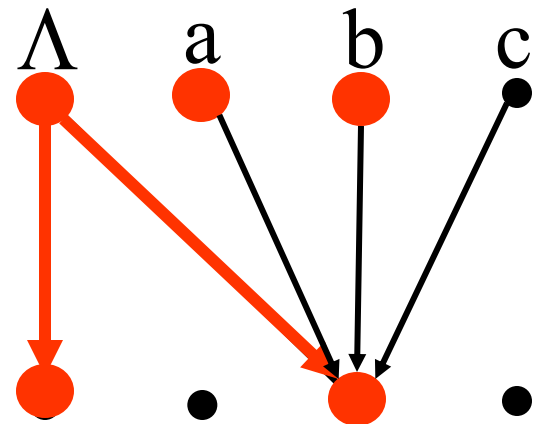
$$f(\{a, b\}) = \{a, b\}$$



Constant Function

$$f = \lambda V.\{b\}$$

$$f(\{a, b\}) = \{b\}$$

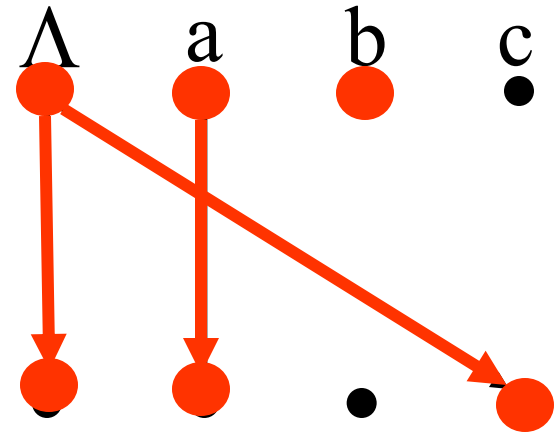


# Representing Dataflow Functions

“Gen/Kill” Function

$$f = \lambda V. (V - \{b\}) \cup \{c\}$$

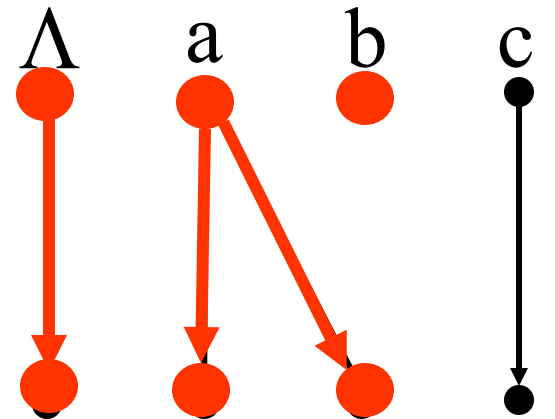
$$f(\{a, b\}) = \{a, c\}$$

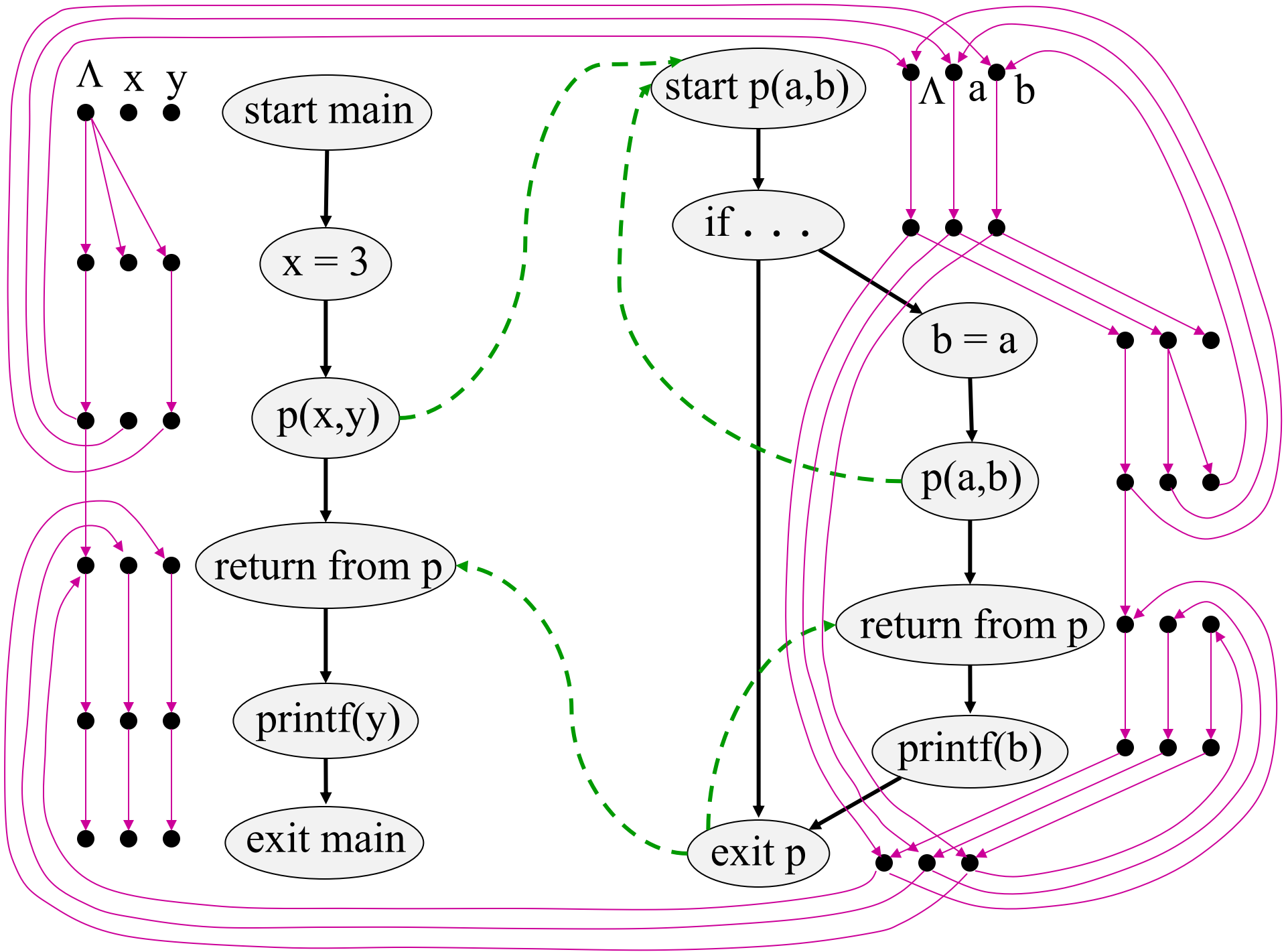


Non-“Gen/Kill” Function

$$f = \lambda V. \text{if } a \in V \\ \text{then } V \cup \{b\} \\ \text{else } V - \{b\}$$

$$f(\{a, b\}) = \{a, b\}$$



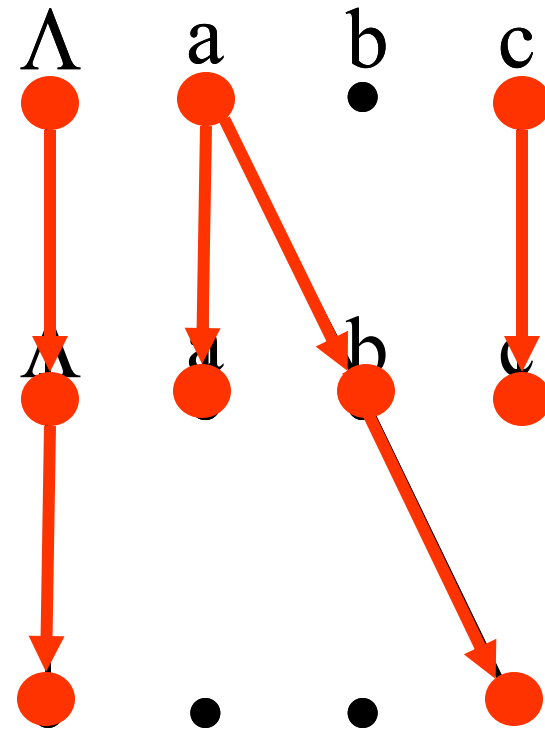




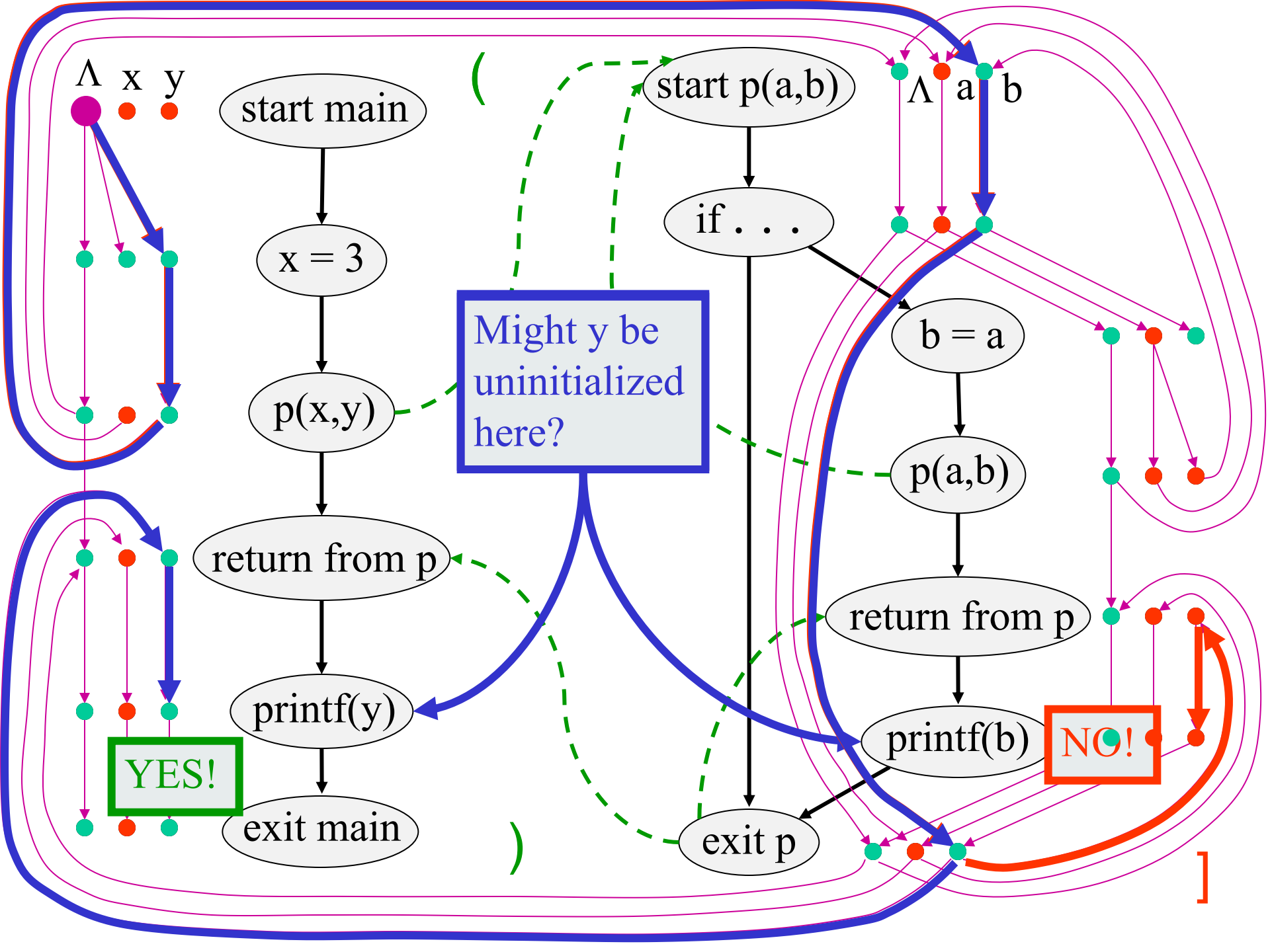
# Composing Dataflow Functions

$f_1 = \lambda V. \text{if } a \in V$   
     then  $V \cup \{b\}$   
     else  $V - \{b\}$

$f_2 = \lambda V. \text{if } b \in V$   
     then  $\{c\}$   
     else  $\phi$



$$f_2 \circ f_1(\{a, c\}) = \boxed{\{c\}}$$

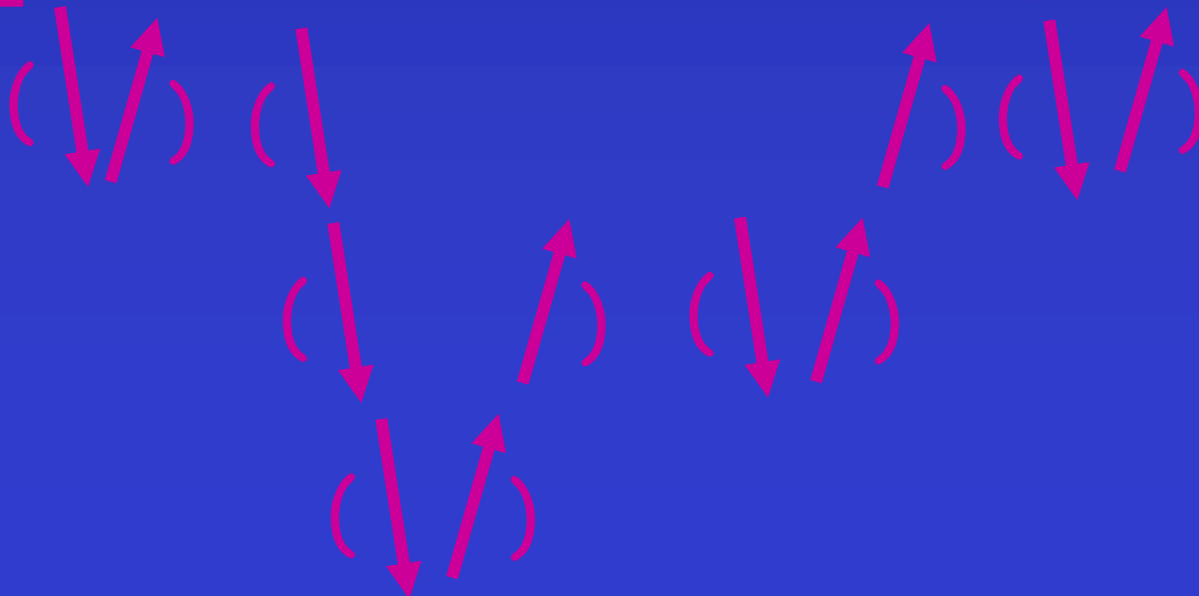


*matched*  $\square$  *matched matched*

$(\text{matched})_i$   $1 \leq i \leq \text{CallSites}$

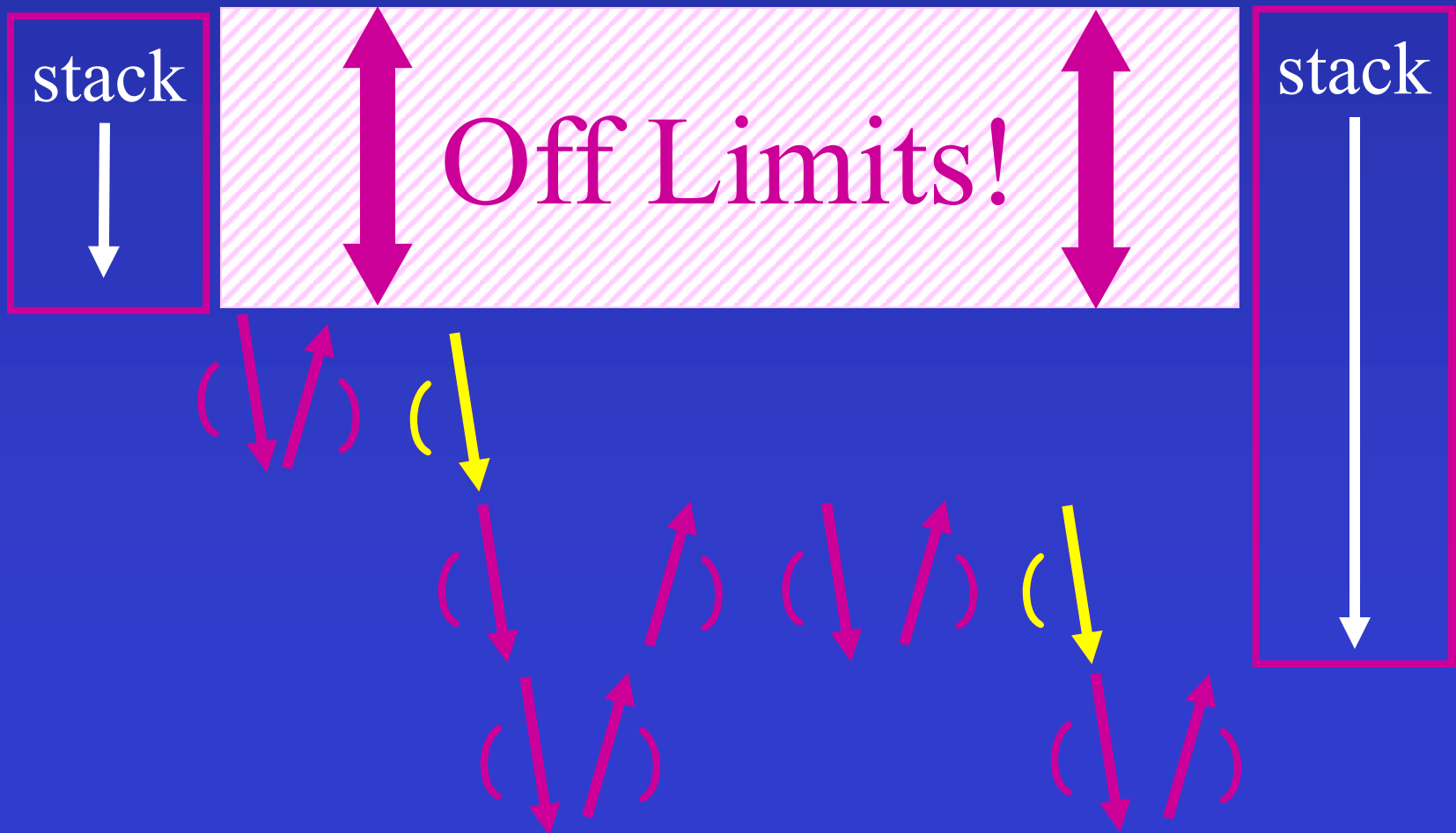
edge

$\square$



*unbalLeft*  $\square$  *matched unbalLeft*

|  $(_i \text{ unbalLeft} \quad 1 \square i \square \text{CallSites}$   
 |  $\square$




# Interprocedural Dataflow Analysis via CFL-Reachability

- Graph: Exploded control-flow graph
- $L$ :  $L(unbalLeft)$
- Fact  $d$  holds at  $n$  iff there is an  $L(unbalLeft)$ -path from  $\langle start_{main}, \Lambda \rangle$  to  $\langle n, d \rangle$

# Asymptotic Running Time

[Reps, Horwitz, & Sagiv 95]

- CFL-reachability
  - Exploded control-flow graph:  $ND$  nodes
  - Running time:  $O(N^3D^3)$
- Exploded control-flow graph  Special structure

Running time:  $O(ED^3)$

Typically:  $E \mid N$ , hence  $O(ED^3) \mid O(ND^3)$

“Gen/kill” problems:  $O(ED)$

# Why Bother?

“We’re only interested in million-line programs”

- Know thy enemy!
  - “Any” algorithm must do these operations
  - Avoid pitfalls (e.g., claiming  $O(N^2)$  algorithm)
- The essence of “context sensitivity”
- Special cases
  - “Gen/kill” problems:  $O(ED)$
- Compression techniques
  - Basic blocks
  - SSA form, sparse evaluation graphs
- Demand algorithms

# Relationship to Other Analysis Paradigms

- Dataflow analysis
  - reachability versus equation solving
- Deduction
- Set constraints



# The Need for Pointer Analysis

```
int main() {  
    int sum = 0;  
    int i = 1;  
    int *p = &sum;  
    int *q = &i;  
    int (*f)(int,int) = add;  
    while (*q < 11) {  
        *p = (*f)(*p,*q);  
        *q = (*f)(*q,1);  
    }  
    printf("%d\n", *p);  
    printf("%d\n", *q);  
}
```

```
int add(int x, int y)  
{  
    return x + y;  
}
```

# The Need for Pointer Analysis

```
int main() {  
    int sum = 0;  
    int i = 1;  
    int *p = &sum;  
    int *q = &i;  
    int (*f)(int,int) = add;  
    while (*q < 11) {  
        *p = (*f)(*p, *q);  
        *q = (*f)(*q, 1);  
    }  
    printf("%d\n", *p);  
    printf("%d\n", *q);  
}
```

```
int add(int x, int y)  
{  
    return x + y;  
}
```

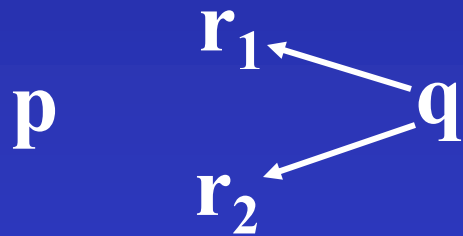
# The Need for Pointer Analysis

```
int main() {  
    int sum = 0;  
    int i = 1;  
    int *p = &sum;  
    int *q = &i;  
    int (*f)(int,int) = add;  
    while (i < 11) {  
        sum = add(sum,i);  
        i = add(i,1);  
    }  
    printf("%d\n", sum);  
    printf("%d\n", i);  
}
```

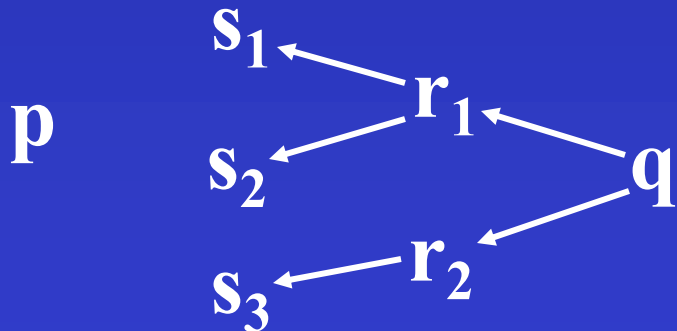
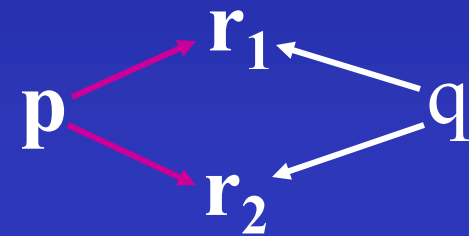
```
int add(int x, int y)  
{  
    return x + y;  
}
```

# Flow-Sensitive Points-To Analysis

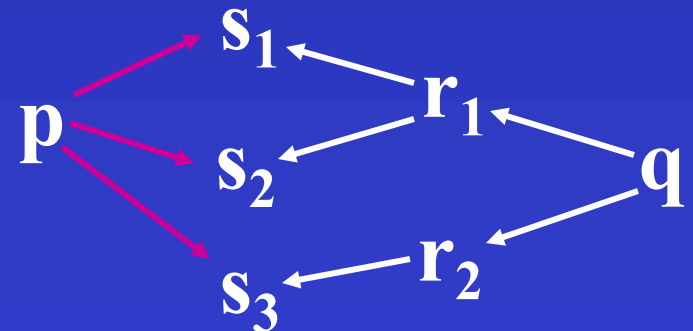
**p      q      p = &q;      p  $\longrightarrow$  q**



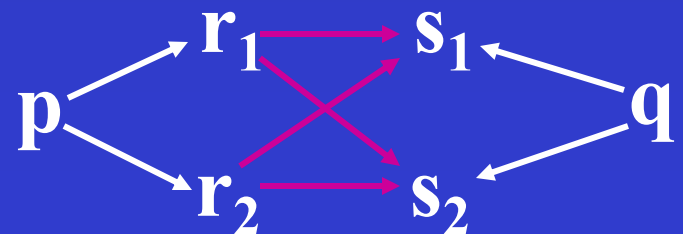
**p = q;**



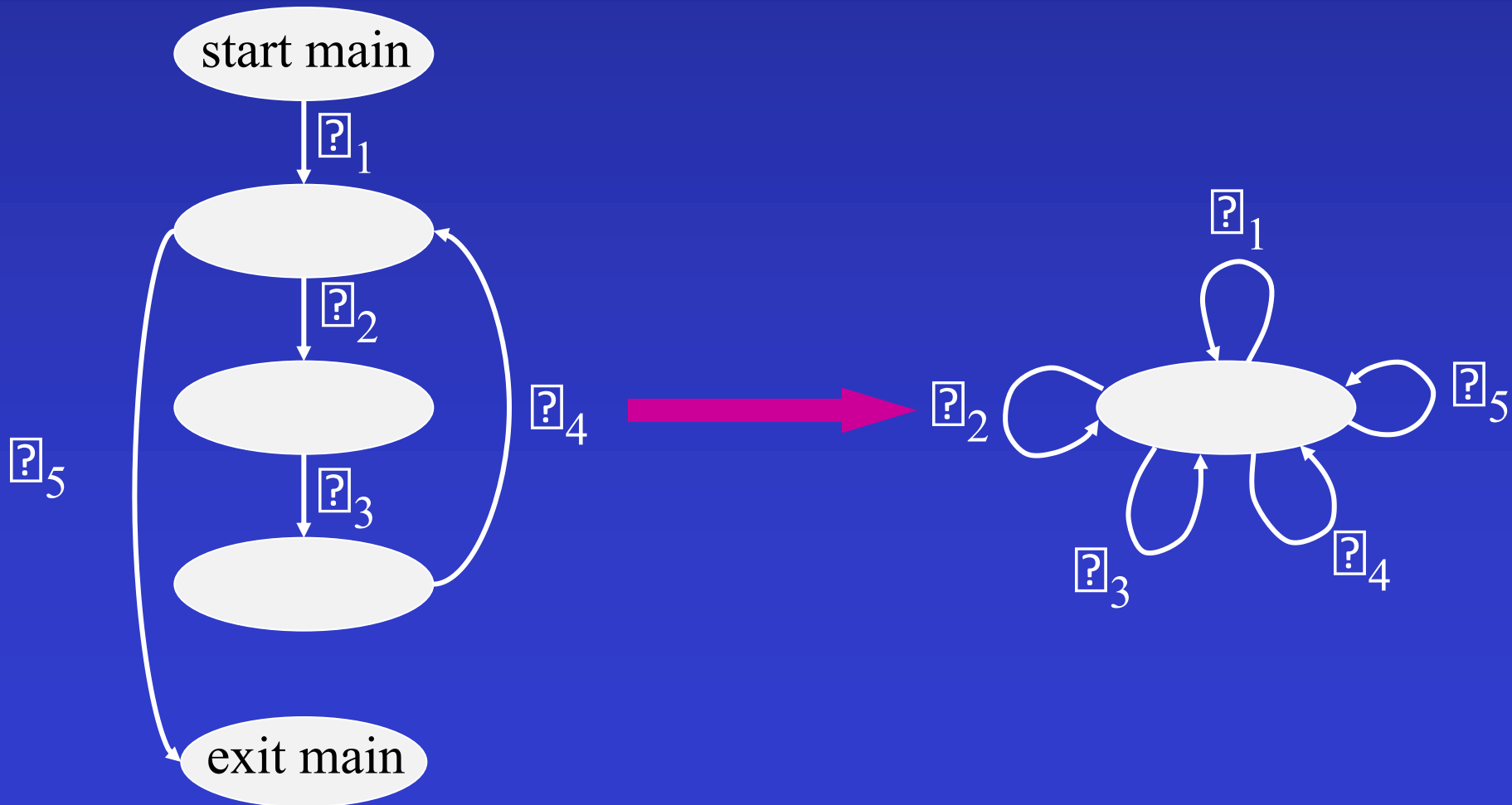
**p = \*q;**



**\*p = q;**



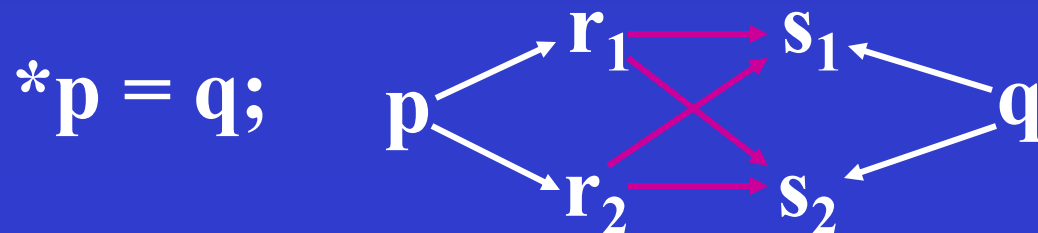
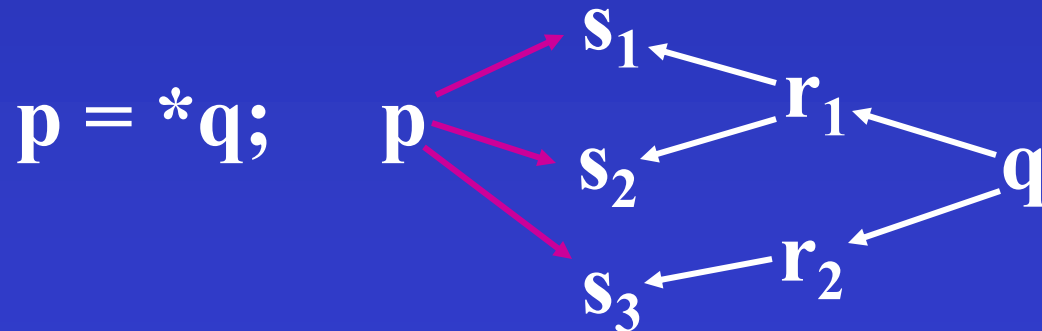
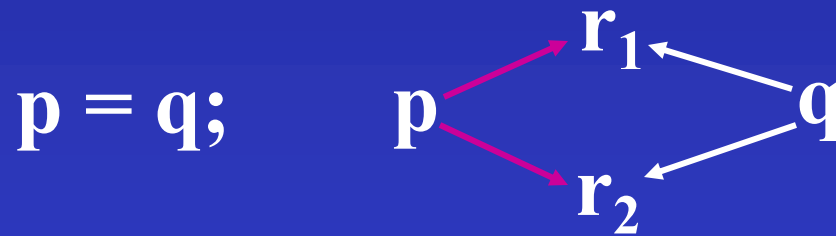
# Flow-Sensitive $\rightarrow$ Flow-Insensitive



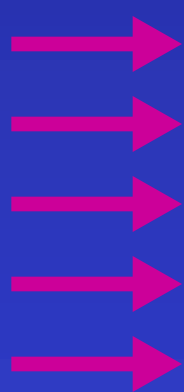
# Flow-**Insensitive** Points-To Analysis

[Andersen 94, Shapiro & Horwitz 97]

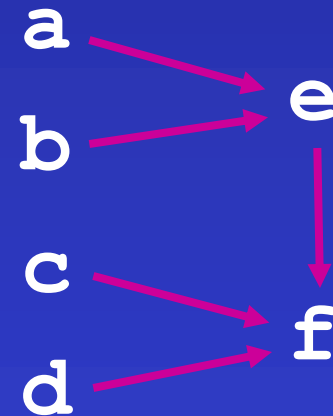
$p = \&q;$      $p \longrightarrow q$



# Flow-Insensitive Points-To Analysis

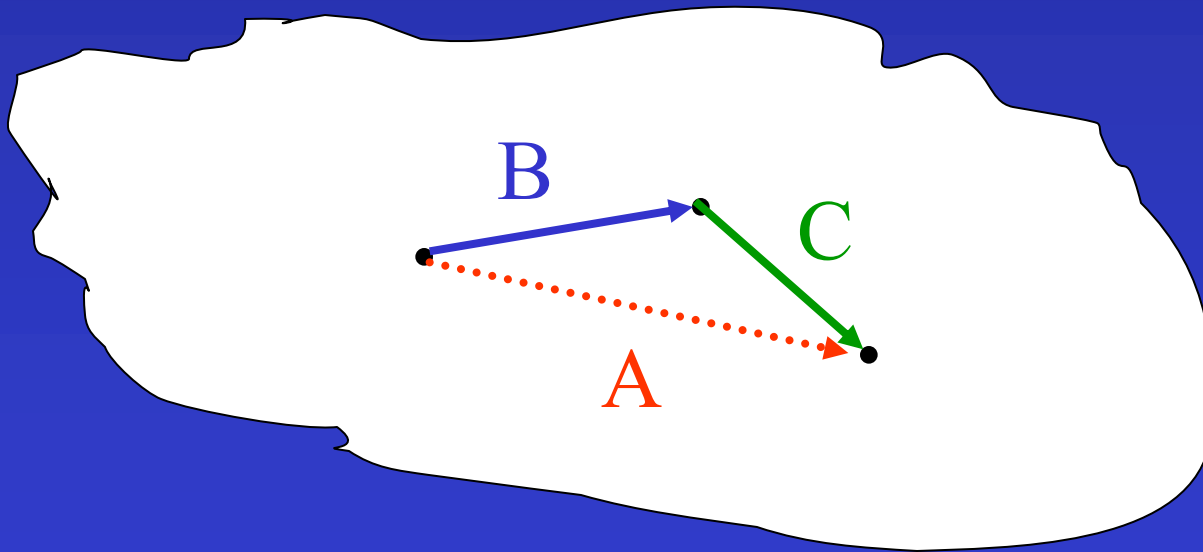


```
a = &e;  
b = a;  
c = &f;  
*b = c;  
d = *a;
```

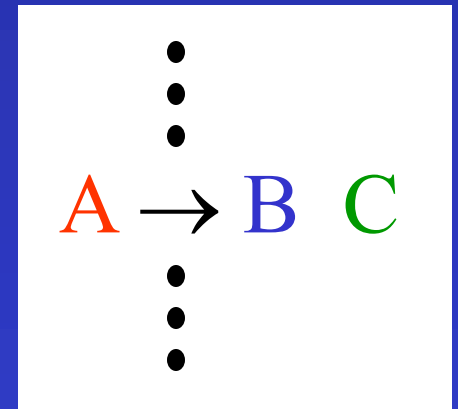


# CFL-Reachability via Dynamic Programming

Graph



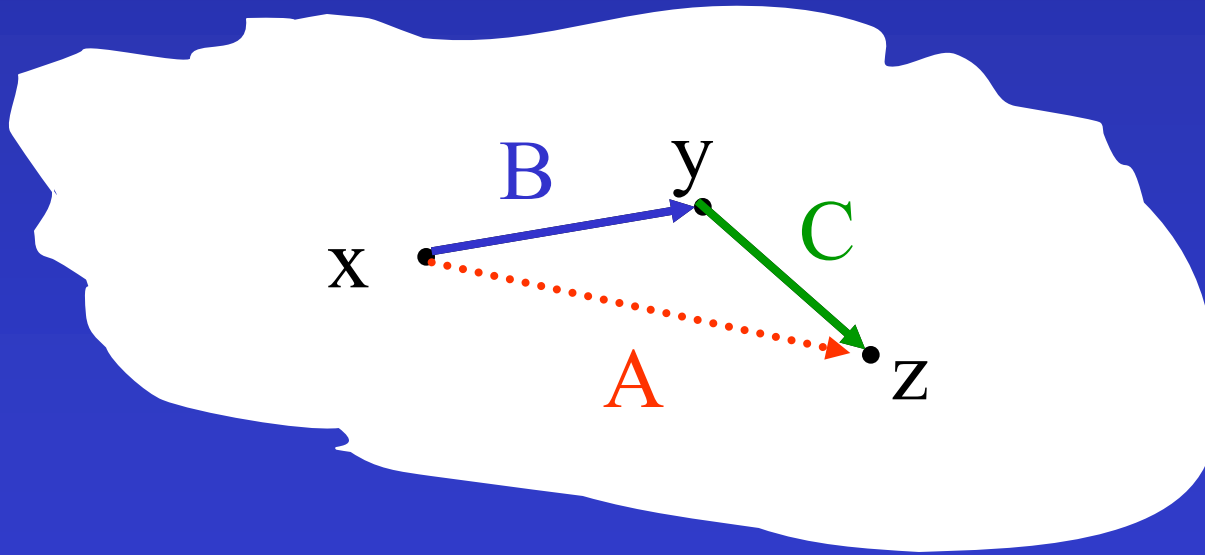
Grammar



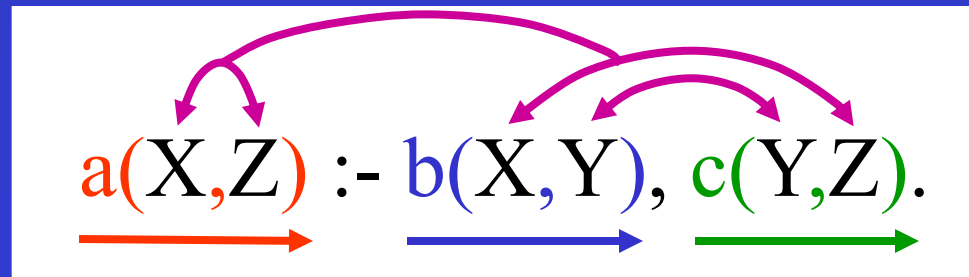
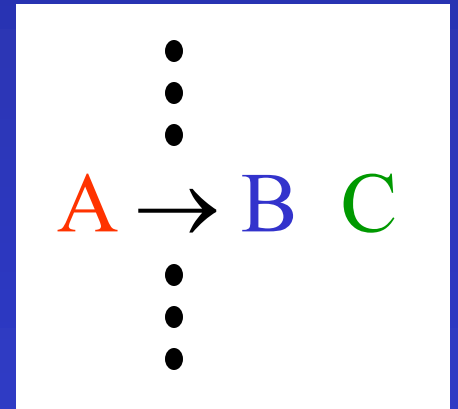


# CFL-Reachability = Chain Programs

Graph



Grammar



# Base Facts for Points-To Analysis

$p = \&q;$        $\text{assignAddr}(p,q).$

$p = q;$        $\text{assign}(p,q).$

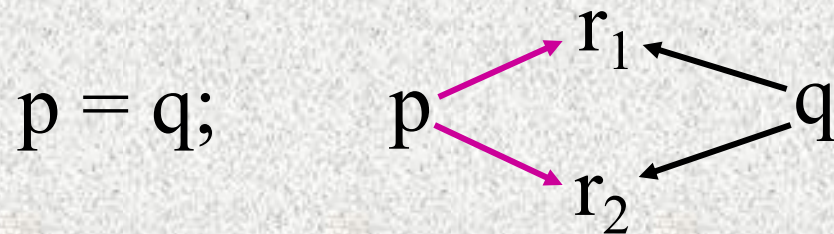
$p = *q;$        $\text{assignStar}(p,q).$

$*p = q;$        $\text{starAssign}(p,q).$

# Rules for Points-To Analysis (I)

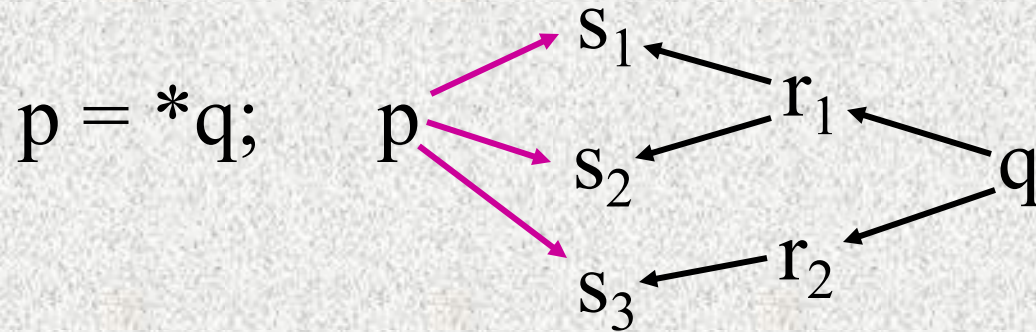
$p = \&q; \quad p \longrightarrow q$

$\text{pointsTo}(P,Q) \text{ :- assignAddr}(P,Q).$

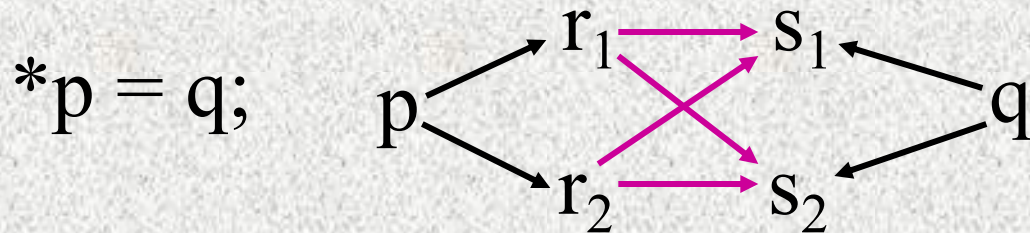


$\text{pointsTo}(P,R) \text{ :- assign}(P,Q), \text{pointsTo}(Q,R).$

# Rules for Points-To Analysis (II)

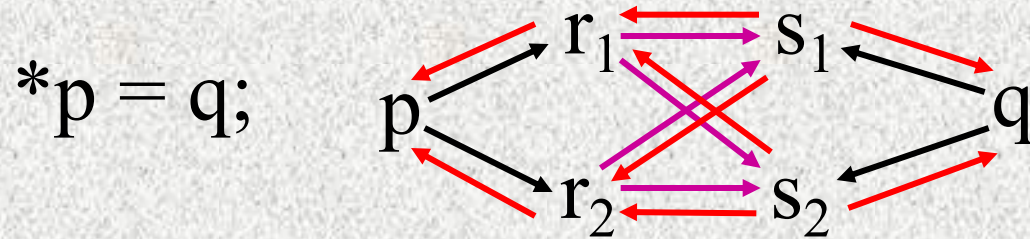


**pointsTo(P,S)** :- assignStar(P,Q),pointsTo(Q,R),pointsTo(R,S).



**pointsTo(R,S)** :- starAssign(P,Q),pointsTo(P,R),pointsTo(Q,S).

# Creating a Chain Program



~~pointsTo(R,S) :- starAssign(P,Q),pointsTo(P,R),pointsTo(Q,S).~~

pointsTo(R,S) :- pointsTo(P,R),starAssign(P,Q),pointsTo(Q,S).

pointsTo(R,S) :- pointsTo(R,P),starAssign(P,Q),pointsTo(Q,S).

~~pointsTo(R,P) :- pointsTo(P,R).~~

# Base Facts for Points-To Analysis

$p = \&q;$       assignAddr(p,q).  
assignAddr(q,p).

$p = q;$       assign(p,q).  
assign(q,p).

$p = *q;$       assignStar(p,q).  
assignStar(q,p).

$*p = q;$       starAssign(p,q).  
starAssign(q,p).



# Creating a Chain Program

pointsTo(P,Q) :- assignAddr(P,Q).

pointsTo(Q,P) :- assignAddr(Q,P).

pointsTo(P,R) :- assign(P,Q), pointsTo(Q,R).

pointsTo(R,P) :- pointsTo(R,Q), assign(Q,P).

pointsTo(P,S) :- assignStar(P,Q), pointsTo(Q,R), pointsTo(R,S).

pointsTo(S,P) :- pointsTo(S,R), pointsTo(R,Q), assignStar(Q,P).

pointsTo(R,S) :- pointsTo(R,P), starAssign(P,Q), pointsTo(Q,S)

pointsTo(S,R) :- pointsTo(S,Q), starAssign(Q,P), pointsTo(P,R).

. . . and now to CFL-Reachability

pointsTo  $\rightarrow$  assignAddr

pointsTo  $\rightarrow$  assignAddr

pointsTo  $\rightarrow$  assign pointsTo

pointsTo  $\rightarrow$  pointsTo assign

pointsTo  $\rightarrow$  assignStar pointsTo pointsTo

pointsTo  $\rightarrow$  pointsTo pointsTo assignStar

pointsTo  $\rightarrow$  pointsTo starAssign pointsTo

pointsTo  $\rightarrow$  pointsTo starAssign pointsTo



# Themes

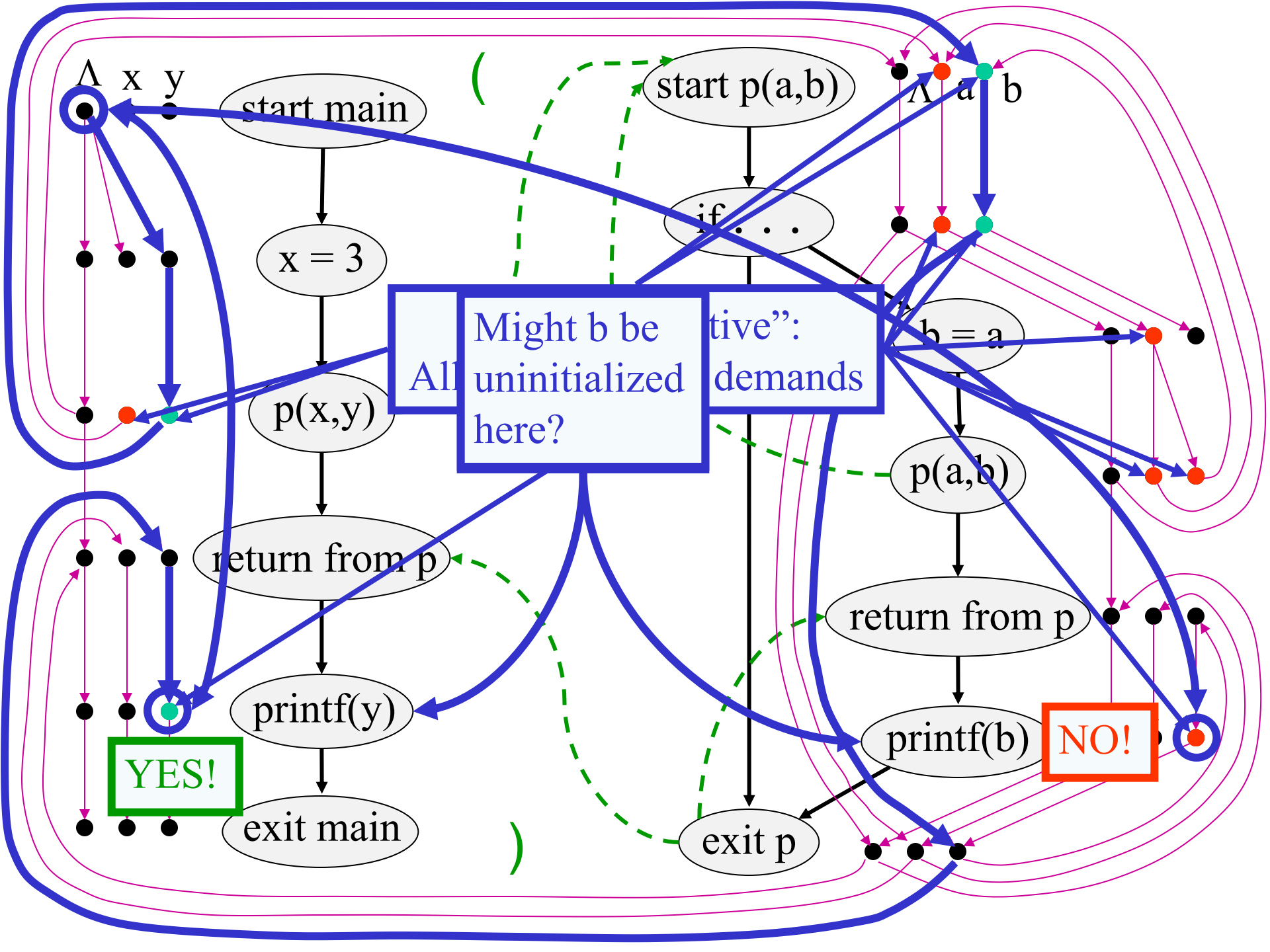
- Harnessing CFL-reachability
- Relationship to other analysis paradigms
- Exhaustive alg.  $\Rightarrow$  Demand alg.
- Understanding complexity
  - Linear . . . cubic . . . undecidable
- Beyond CFL-reachability

# Exhaustive Versus Demand Analysis

- Exhaustive analysis: **All** facts at **all** points
- Optimization: Concentrate on inner loops
- Program-understanding tools: Only some facts are of interest

# Exhaustive Versus Demand Analysis

- Demand analysis:
  - Does a **given** fact hold at a **given** point?
  - **Which** facts hold at a **given** point?
  - At **which** points does a **given** fact hold?
- Demand analysis via CFL-reachability
  - single-source/single-target CFL-reachability
  - single-source/multi-target CFL-reachability
  - multi-source/single-target CFL-reachability



# Experimental Results

[Horwitz , Reps, & Sagiv 1995]

- 53 C programs (200-6,700 lines)
- For a single fact of interest:
  - demand **always better** than exhaustive
- All “appropriate” demands beats exhaustive when percentage of “yes” answers is high
  - Live variables
  - Truly live variables
  - Constant predicates
  - . . .

# Demand Analysis and LP Queries (I)

- Flow-insensitive points-to analysis
  - Does variable  $p$  point to  $q$ ?
    - Issue query:  $?- \text{pointsTo}(p, q)$ .
    - Solve single-source/single-target  $L(\text{pointsTo})$ -reachability problem
  - What does variable  $p$  point to?
    - Issue query:  $?- \text{pointsTo}(p, Q)$ .
    - Solve single-source  $L(\text{pointsTo})$ -reachability problem
  - What variables point to  $q$ ?
    - Issue query:  $?- \text{pointsTo}(P, q)$ .
    - Solve single-target  $L(\text{pointsTo})$ -reachability problem

# Demand Analysis and LP Queries (II)

- Flow-sensitive analysis
  - Does a given fact  $f$  hold at a given point  $p$ ?  
?- dfFact( $p$ ,  $f$ ).
  - Which facts hold at a given point  $p$ ?  
?- dfFact( $p$ ,  $F$ ).
  - At which points does a given fact  $f$  hold?  
?- dfFact( $P$ ,  $f$ ).
- E.g., flow-sensitive points-to analysis
  - ?- dfFact( $p$ , pointsTo( $x$ ,  $Y$ )).
  - ?- dfFact( $P$ , pointsTo( $x$ ,  $y$ )).
  - etc.