

Motivating Example

Friday, June 24, 2022 12:36 PM

$$E = \left\{ \begin{array}{l} x^i, w, y^j \mid x^i, y^j \in LV(c) \\ w = \max \{ g(\tau) \mid \text{Dep}(x^i, y^j, \tau, c) \} \end{array} \right\}$$

example: input x :

```

y=0;
i=0;
w=0;
z< q1;
if x=0;
  {y < q2(z); i=x-1}
else
  (skip);
while i<neq x
  {w < q3(y); if i neq x-2 then w=0 else skip; i=i+1}
  
```

a trace τ_1, τ_2, τ_3 :
 $\tau_1 = w=2, \tau_2 = w=2, \tau_3 = w=2$
change $w \neq w$ $\Rightarrow \tau_1' = \tau_2, \tau_3'$

then another trace: $\epsilon_1 = w=2, \epsilon_2 = w=2, \epsilon_3 = w=2$
change $w \neq w$ $\Rightarrow \epsilon_1' = w=2, \epsilon_2 = w=2, \epsilon_3' = w=2, \tau_3'$

+ trace. s.t. $\text{Dep}(w, \tau, w)$, # of occurrence time of $w \geq$ # of start where value of w is changed.

then. count: + trace τ s.t. $\text{Dep}(w, \tau, w)$.
 $| \text{Diff}(\tau_1, \tau_2, w^*) |$

\Rightarrow weight on edge (x^i, y^j, w) :
 $w = \max \{ | \text{Diff}(\tau_1, \tau_2, y^j) | + \tau_1, \tau_2, \text{s.t. } \text{Dep}(x^i, \tau_1, \tau_2, y^j) \}$

\Rightarrow 1 Dep on 2 traces. define.

\Rightarrow 2. Control Dep. ??

\Rightarrow add iteration id.

possible unsound ??

inorder to know the value changed in the 2 traces are in the same iteration.

then,

if cases + t. deserve the same
value, but in different iterations?
then intuitively no-dependency. it's good.

\Rightarrow 3. $\text{Diff}(\tau_1, \tau_2, x^i)$

\Rightarrow ~~case~~
 $\text{seq}(\tau_1) x^i \triangleq \begin{cases} \tau_1 = \tau_1' :: (x, i, v, \alpha) \rightarrow \text{seq}(\tau_1') :: v \\ \tau_1 = \tau_1' :: (x, i, v, \alpha) \rightarrow \text{seq}(\tau_1') :: v \\ \tau_1 = \tau_1' :: (x, i, v, \alpha) \rightarrow \text{seq}(\tau_1') :: v \\ \text{o.w.} \rightarrow \text{seq}(\tau_1') \end{cases}$

without loop iteration id.

for $\text{seq}(\tau_1) x^i$, where $\text{Dep}(y^j, x^i, \tau_1, \tau_2)$.

case of $\text{seq}(\tau_1) \neq \text{seq}(\tau_2)$:

①. $\text{len}_1 \neq \text{len}_2 \Rightarrow \text{Diff}(\text{seq}(\tau_1), \text{seq}(\tau_2), x^i) = \{ k \mid \text{seq}(\tau_1)[k] \neq \text{seq}(\tau_2)[k] \vee k \in \text{len}_1, \text{len}_2+1, \dots, \text{len}_2 \}$.

②. $\text{len}_1 = \text{len}_2 \Rightarrow \text{Diff}(\text{seq}(\tau_1), \text{seq}(\tau_2), x^i) = \{ k \mid \text{seq}(\tau_1)[k] \neq \text{seq}(\tau_2)[k] \}$

\Rightarrow potential issue: the different observed value is in different iterations.

case: if y is affected by moving to different iteration, but it always executed the same time with same value.

then it doesn't matter which iteration it is in, thus isn't dependence / adaptivity.

\Rightarrow for case ②, where they have same len, it doesn't loss adaptivity if I observe the same value in the same location of $\text{seq}(\tau_1)$ and $\text{seq}(\tau_2)$
 b/c where they actually comes from different loop iteration.

i.e. it's sound that only count the diff of some iteration.

\Rightarrow for case ③: $\text{len}_1 \neq \text{len}_2$.

in the 2 seqs from $[0, \min(l_1, l_2)]$, it is still sound by just observe the different value in some location.

for the same reason as case ①.

in the longer seq from $[\min(l_1, l_2), \max(l_1, l_2)]$.

case: $i=0$
 while $i < x$:
 $i = i+1$
 $y = f(a)$.

\Rightarrow when $x=100$
 still safe.
 $(y, 1, v_1), (y, 2, v_2), (y, 1, v_3), (y, 2, 0, \dots)$
 $(y, 1, v_4), (y, 1, v_5), (y, 4, v_6), (y, 3, 0, \dots)$

$\Rightarrow Gy^*(inf, s)$.

if in order to get different length, only way is by changing value affect y .
 c.s. in Σ : $(y, 1, v_1), (y, 2, v_2)$ \Rightarrow all the value are the same. then

$(x, inf, 100), (y, 1, v_1), (y, 2, v_2) \dots$ adaptivity is actually 1.

guard variable
 $\frac{\text{is used in evaluating } y}{\text{or } y \text{ itself is used through a chain}} \rightsquigarrow$
 \Rightarrow if they are different, then either

case: $i=0$
 while $i < x$:
 $w = f(a)$
 $\text{if } i > 3, w=0, \text{skip}$
 $\{i=i+1\}$

$x = 1, 2, (w, 0), (w, 1, 0)$
 $x = 100, (w, 1, 0), (w, 1, 1, 0), (w, 1, 1, 1, 0) \dots$

$\{i=i+1\}$

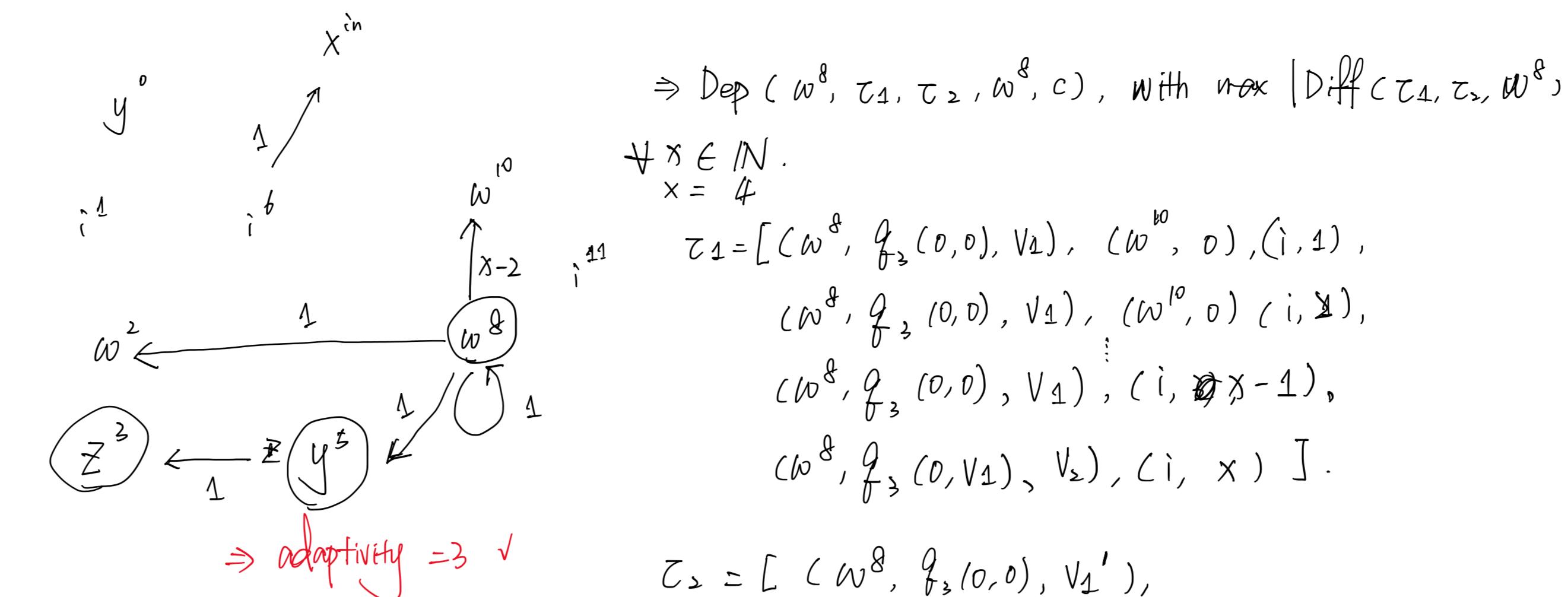
two approaches:
① prove there must exist value dependency from x to y or from other variable to y .

② define $|\text{Diff}|$ as $\{ \text{seq}(\tau_{\text{max}})[\text{min} : \text{max}] \}$. \rightsquigarrow sound set of unique values.

possible case: $(1, 0, 1, 0, 1, 0)$ I actually have no intuition does this adaptive or not.

\Rightarrow if it is, then $|\text{Diff}|$ defined as $\{ k \mid \text{seq}[k-1] \neq \text{seq}[k] \}$ can capture.

but "intuitive adaptivity" is unclear.



\Rightarrow adaptivity = 3

\Rightarrow Diff Graph:

$\forall i \in \{x^i \mid x^i \in LV(c)\}$

$\text{EGF} \{ (x^i, y^j, w) \mid w = \max \{ | \text{Diff}(\tau_1, \tau_2, y^j) | \mid \# \tau_1, \tau_2, \text{s.t. } \text{Dep}(x^i, \tau_1, \tau_2, y^j) \} \}$

$\text{Diff}(\tau_1, \tau_2, x^i) \triangleq \{ k \mid (k=0, \dots, l_{\min} \wedge \text{Seq}(\tau_1) x^i[k] \neq \text{Seq}(\tau_2) x^i[k]) \wedge$

$\wedge (\text{Seq}(\tau_{\max}, x^i)[k-1] \neq \text{Seq}(\tau_{\max}, x^i)[k] \wedge k=l_{\min}, \dots, l_{\max}) \wedge$

$\wedge l_{\min} = \min(|\text{Seq}(\tau_1, x^i)|, |\text{Seq}(\tau_2, x^i)|)$

$l_{\max} = \max(\dots)$

$\tau_{\max} = \text{longer Sequence. } \tau$

$\Rightarrow \text{Seq}(\tau, x^i) \triangleq \begin{cases} \text{seq}(\tau', x^i) :: v & \tau = \tau' :: (i, v, \alpha) \\ \text{seq}(\tau', x^i) :: v & \tau = \tau' :: (i, v, \alpha) \\ \square & \tau = \square \\ \text{seq}(\tau_1') & \text{o.w.} \end{cases}$

$\text{Dep}(x^i, \tau_1, \tau_2, y^j, c) \triangleq$

$\exists \tau_1', \tau_2', \tau_0'$

$\epsilon_1 = (x, i, v_-, -, -), \epsilon_2 = (y, j, -, -, -)$

$\epsilon_1 \neq \text{start } \epsilon_1'$

$\langle C, \tau_0 \rangle \rightarrow \langle C_1, \tau_1' :: \epsilon_1 \rangle \rightarrow \langle \text{skip}, \tau_0' :: \epsilon_1 + \tau_1 \rangle$

$\wedge \langle C_1, \tau_0' :: \epsilon_1' \rangle \rightarrow \langle \text{skip}, \tau_1' :: \epsilon_1 + \tau_1 \rangle$

$\text{Diff}(\tau_1, \tau_2, y^j) \neq \emptyset$.

example:

\Rightarrow

$$\max \{ | \text{Diff}(\tau_1, \tau_2, w^8) | \mid \text{Dep}(w^8, \tau_1, \tau_2, w^8, c) \} = 1.$$

$\Rightarrow | \text{Diff}(\tau_1, \tau_2, w^8) | = 1.$

$\Rightarrow | \text{Diff}(\tau_1, \tau_2, w^8) | = 1.$