Reasoning about Probabilistic Programs

Oregon PL Summer School 2021

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Day 1: Introducing Probabilistic Programs

- Motivations and key questions
- Mathematical preliminaries

Day 2: First-Order Programs 1

- ► Probabilistic While language, monadic semantics
- ► Weakest pre-expectation calculus

Day 3: First-Order Programs 2

- Probabilistic While language, transformer semantics
- Probabilistic separation logic

Day 4: Higher-Order Programs

- ► Type system: probability monad
- ► Type system: probabilistic PCF

Please ask questions!

OPLSS Slack: #probabilistic

► I will check in periodically for offline questions

Zoom chat/raise hand

Thanks to Breandan Considine for moderating!

We don't have to get through everything

► We will have to skip over many topics, anyways

Requests are welcome!

► Tell me if you're curious about something not on the menu

Probabilistic Programs

Are Everywhere!



Executable code: Randomized Algorithms

Better performance in exchange for chance of failure

- ► Check if $n \times n$ matrices $A \cdot B = C$: $O(n^{2.37...})$ operations
- Freivalds' randomized algorithm: $O(n^2)$ operations

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Improve performance against "worst-case" inputs

- ▶ Quicksort: if input is worst-case, $O(n^2)$ comparisons
- ightharpoonup Randomized quicksort: $O(n \log n)$ comparisons on average

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Other benefits

- ► Randomized algorithms can be simpler to describe
- ► Sometimes: more efficient than deterministic algorithms



Executable code: Security and Privacy

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Cryptography

- Generate secrets the adversary doesn't know
- Example: draw encryption/decryption keys randomly

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Privacy

- ► Add random noise to blur private data
- Example: differential privacy



Executable code: Randomized Testing

Randomly generate inputs to a program

- ► Search a huge space of potential inputs
- Avoid human bias in selecting testcases

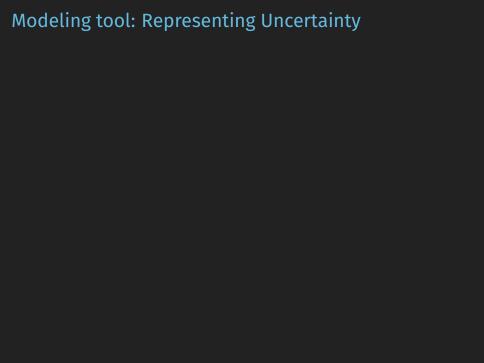
Executable code: Randomized Testing

Randomly generate inputs to a program

- Search a huge space of potential inputs
- Avoid human bias in selecting testcases

Very common strategy for testing programs

- Property-based testing (e.g., QuickCheck)
- ► Fuzz testing (e.g., AFL, OSS-Fuzz)



Modeling tool: Representing Uncertainty

Think of uncertain things as drawn from a distribution

- ► Example: whether a network link fails or not
- Example: tomorrow's temperature

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Different motivation from executable code

- ► Aim: model some real-world data generation process
- Less important: generating data from this distribution



Modeling tool: Fitting Empirical Data

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Foundation of machine learning

- ► Human designs a model of how data is generated, with unknown parameters
- Based on data collected from the world, infer parameters of the model

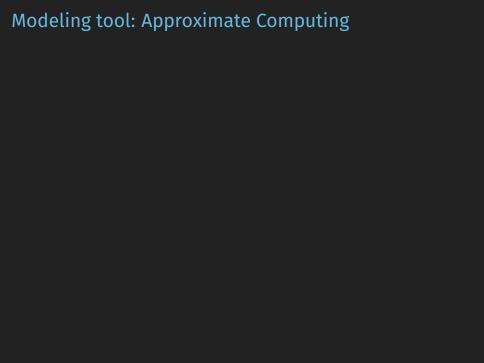
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Example: learning the bias of a coin

- ► Boolean data generated by coin flips
- ► Unknown parameter: bias of the coin
- Flip coin many times, try to infer the bias



Modeling tool: Approximate Computing

Computing on unreliable hardware

- ► Hardware operations may occasionally give wrong answer
- Motivation: lower power usage if we allow more errors

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Computing on unreliable hardware

- ► Hardware operations may occasionally give wrong answer
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Model failures as drawn from a distribution

- Run hardware many times, estimate failures rate
- Randomized program describes approximate computing

Main Questions

and Research Directions

What to know about probabilistic programs?

Four general categories

- **▶** Semantics
- **▶** Verification
- **▶** Automation
- ► Implementation

Semantics: what do programs mean mathematically?

Specify what programs are supposed to do

- ► Programs may generate complicated distributions
- ► Desired behavior of programs may not be obvious

Common tools

- Denotational semantics: define program behavior using mathematical concepts from probability theory (distributions, measures, ...)
- ► Operational semantics: define how programs step

Verification: how to prove programs correct?

Design ways to prove probabilistic program properties

- ► Target properties can be highly mathematical, subtle
- Goal: reusable techniques to prove these properties

Common tools

- ► Low-level: interactive theorem provers (e.g., Coq, Agda)
- ► Higher-level: type systems, Hoare logic, and custom logics

Automation: how to analyze programs automatically?

Prove correctness without human help

- ► Benefit: don't need any human expertise to run
- ► Drawback: less expressive than manual techniques

Common tools

- Probabilistic model checking (e.g., PRISM, Storm)
- ► Abstract interpretation

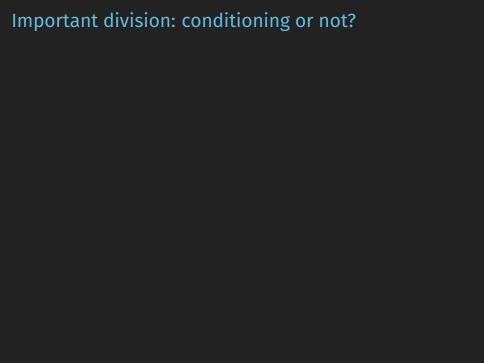
Implementation: how to run programs efficiently?

Executing a probabilistic program is not always easy

- ► Especially: in languages supporting conditioning
- ► Algorithmic insights to execute probabilistic programs

Common tools: sampling algorithms

- Markov Chain Monte Carlo (MCMC)
- Sequential Monte Carlo (SMC)



Important division: conditioning or not?

No conditioning in language

- ► Semantics is more straightforward
- Easier to implement; closer to executable code
- Verification and automation are more tractable

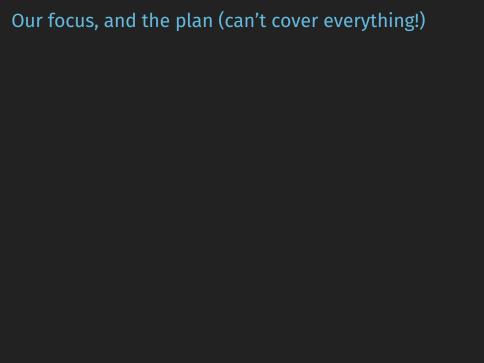
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Yes conditioning in language

- Semantics is more complicated
- Difficult to implement efficiently, but useful for modeling
- Verification and automation are very difficult



Our focus, and the plan (can't cover everything!)

Primary focus: verification

► Main course goal: reasoning about probabilistic programs

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Secondary focus: semantics

► Introduce a few semantics for probabilistic languages

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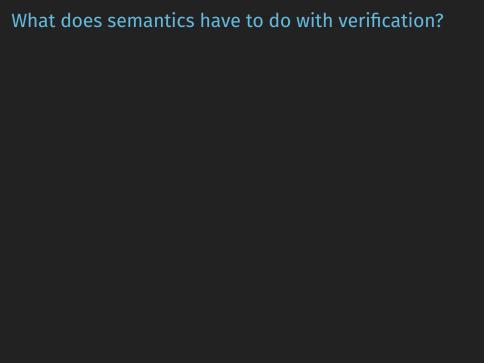
► Main course goal: reasoning about probabilistic programs

Secondary focus: semantics

Introduce a few semantics for probabilistic languages

Programs without conditioning

Simpler, and covers many practical applications



What does semantics have to do with verification?

Semantics is the foundation of verification

- ► Semantics: definition of program behavior
- Verification: prove program behavior satisfies property

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- ► Verification: prove program behavior satisfies property

Semantics can make properties easier or harder to verify

- Probabilistic programs: several natural semantics
- ► Choice of semantics strong(y affects verification

What Are the Challenges?

Verifying Proba	ıbilistic P	rograms



It computes a super-set of the possible run-time errors. ASTRÉE is designed for efficiency on large software: hundreds of thousands of lines of code are analyzed in a matter of hours, while producing very few false alarms. For example, some fly-by-wire avionics reactive control codes (70000 and 380000 lines respectively, the latter of a much more complex design) are analyzed in 1h and 10 h 30' respectively on current single-CPU PCs, with no false alarm [129].

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Key lessons for designing static analyses tools deployed to find bugs in hundreds of millions of lines of code.

BY DINO DISTEFANO, MANUEL FÄHNDRICH, FRANCESCO LOGOZZO, AND PETER W. O'HEARN

Scaling Static Analyses at Facebook

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Scaling Static Analyses at Facebook How Coverity built a bug-finding tool, and a business, around the unlimited supply of bugs in software systems.

BY AL BESSEY, KEN BLOCK, BEN CHELF, ANDY CHOU, BRYAN FULTON, SETH HALLEM, CHARLES HENRI-GROS, ASYA KAMSKY, SCOTT MCPEAK, AND DAWSON ENGLER

A Few Billion Lines of Code Later

Randomized programs: small code, specialized proofs

Small code

- ► Usually: on the order of (0s of lines) of code
- ► 100-line algorithm: unthinkable (and un-analyzable)

Specialized proofs

- Often: apply combination of known and novel techniques
- Proofs (and techniques) can be research contributions

Simple programs, but complex program states

Programs manipulate distributions over program states

- ► Each state has a numeric probability
- Probabilities of different states may be totally unrelated

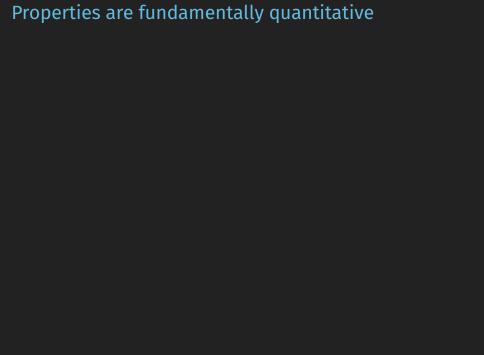
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Example: program with 10 Boolean variables

- Non-probabilistic programs: $2^{10} = 1024$ possible states
- ► Probabilistic programs: each state also has a probability
- ▶ 1024 possible states versus uncountably many states



Properties are fundamentally quantitative

Key probabilistic properties often involve...

- Probabilities of events (e.g., returning wrong result)
- Average value of randomized quantities (e.g., running time)

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Can't just "ignore" probabilities

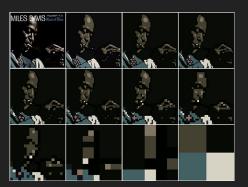
- Treat probabilities as zero or non-zero (non-determinism)
- Simplifies verification, but can't prove most properties

Needed: good abstractions for probabilistic programs

Discard unneeded aspects of a program's state/behavior

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Discard unneeded aspects of a program's state/behavior



What do we want from these abstractions?

Desired features

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Desired features

- 1. Retain enough info to show target probabilistic properties
- 2. Be easy to establish (or at least not too difficult)
- 3. Behave well under program composition



Distributions and sub-distributions

Distribution over A assigns a probability to each $a \in A$

Let A be a countable set. A (discrete) distribution over A, $\mu \in \mathsf{Distr}(A)$, is a function $\mu : A \to [0,1]$ such that:

$$\sum_{a \in A} \mu(a) = 1.$$

For modeling non-termination: sub-distributions

A (discrete) subdistribution over A, $\mu \in {\rm SDistr}(A)$, is a function $\mu:A \to [0,1]$ such that:

$$\sum_{a \in A} \mu(a) \le 1.$$

"Missing" mass is probability of non-termination.

Examples of distributions

Fair coin: Flip

- ▶ Distribution over $\mathbb{B} = \{tt, ff\}$
- $\blacktriangleright \mu(tt) = \mu(ff) \triangleq 1/2$

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Dice roll: Roll

- ▶ Distribution over $\mathbb{N} = \{0, 1, 2, \dots\}$
- $\blacktriangleright \ \mu(1) = \dots = \mu(6) \triangleq 1/6$
- ▶ Otherwise: $\mu(n) \triangleq 0$

Notation for distributions

Probability of a set

Let $E\subseteq A$ be an event, and let $\mu\in {\sf Distr}(A)$ be a distribution. Then the probability of E in μ is:

$$\mu(E) \triangleq \sum_{x \in E} \mu(x).$$

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Expected value

Let $\mu \in \mathsf{Distr}(A)$ be a distribution, and $f: A \to \mathbb{R}^+$ be a non-negative function. Then the expected value of f in μ is:

$$\mathbb{E}_{x \sim \mu}[f(x)] \triangleq \sum_{x \in A} f(a) \cdot \mu(a).$$

Operations on distributions: unit

The simplest possible distribution

Dirac distribution: Probability 1 of producing a particular element, and probability 0 of producing anything else.

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Distribution unit

Let $a \in A$. Then $unit(a) \in \mathsf{Distr}(A)$ is defined to be:

$$unit(a)(x) = \begin{cases} 1 & : x = a \\ 0 & : \text{ otherwise} \end{cases}$$

Why "unit"? The unit ("return") of the distribution monad.

Operations on distributions: map

Translate each distribution output to something else Whenever sample x, sample f(x) instead. Transformation map f is deterministic: function $A \to B$.

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Distribution map

Let $f:A\to B$. Then $map(f): {\sf Distr}(A)\to {\sf Distr}(B)$ takes $\mu\in {\sf Distr}(A)$ to:

$$map(f)(\mu)(b) \triangleq \sum_{a \in A: f(a) = b} \mu(a)$$

Probability of $b \in B$ is sum probability of $a \in A$ mapping to b.

Example: distribution map

Swap results of a biased coin flip

- ▶ Let $neg: \mathbb{B} \to \mathbb{B}$ map $tt \mapsto ff$, and $ff \mapsto tt$.
- ► Then $\mu = map(neg)(\mathbf{Flip}(1/4))$ swaps the results of a biased coin flip.
- ▶ By definition of map: $\mu(tt) = 3/4, \mu(ff) = 1/4$.

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Try this at home!

What is the distribution obtained by adding 1 to the result of a dice roll Roll? Compute the probabilities using map.

Operations on distributions: bind

Sequence two sampling instructions together

Draw a sample x, then draw a sample from a distribution f(x) depending on x. Transformation map f is randomized: function $A \to \mathsf{Distr}(B)$.

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Distribution bind

Let $\mu \in \mathsf{Distr}(A)$ and $f: A \to \mathsf{Distr}(B)$. Then $bind(\mu, f) \in \mathsf{Distr}(B)$ is defined to be:

$$bind(\mu, f)(b) \triangleq \sum_{a \in A} \mu(a) \cdot f(a)(b)$$

Unpacking the formula for bind

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Probability of sampling b is ...

1. Sample $a \in A$ from μ : probability $\mu(a)$

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Probability of sampling b is ...

- 1. Sample $a \in A$ from μ : probability $\mu(a)$
- **2.** Sample b from f(a): probability f(a)(b)

Unpacking the formula for bind

$$bind(\mu, f)(b) \triangleq \sum_{a \in A} \mu(a) \cdot f(a)(b)$$

Probability of sampling b is ...

- 1. Sample $a \in A$ from μ : probability $\mu(a)$
- **2.** Sample b from f(a): probability f(a)(b)
- 3. Sum over all possible "intermediate samples" $a \in A$

Example: distribution bind

Summing two dice rolls

- ▶ For $n \in \mathbb{N}$, let $f(n) \in \mathsf{Distr}(\mathbb{N})$ be the distribution of adding n to the result of a fair dice roll Roll.
- ► Then: $\mu = bind(\mathbf{Roll}, f)$ is the distribution of the sum of two fair dice rolls.
- ► Can check from definition of bind:

$$\mu(2) = (1/6) \cdot (1/6) = 1/36$$

Example: distribution bind

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Try this at home!

- ▶ Define *f* in terms of distribution map.
- ▶ What if you try to define μ with map instead of bind?

Operations on distributions: conditioning

Restrict a distribution to a smaller subset Given a distribution over A, assume that the result is in $E \subseteq A$. Then what probabilities should we assign elements in A?

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Distribution conditioning

Let $\mu \in \mathsf{Distr}(A)$, and $E \subseteq A$. Then μ conditioned on E is the distribution in $\mathsf{Distr}(A)$ defined by:

$$(\mu \mid E)(a) \triangleq \begin{cases} \mu(a)/\mu(E) & : a \in E \\ 0 & : a \notin E \end{cases}$$

Idea: probability of a "assuming that" the result must be in E. Only makes sense if $\mu(E)$ is not zero!

Example: conditioning

Rolling a dice until even number

Suppose we repeatedly roll a dice until it produces an even number. What distribution over even numbers will we get?

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Model as a conditional distribution

- ▶ Let $E = \{2, 4, 6\}$
- ► Resulting distribution is $\mu = (\mathbf{Roll} \mid E)$
- From definition of conditioning: $\mu(2) = \mu(4) = \mu(6) = 1/3$

Try this at home!

Suppose we keep rolling two dice until the sum of the dice is 6 or larger. What is the distribution of the final sum?

Operations on distributions: convex combination

Blending/mixing two distributions

Say we have distributions μ_1, μ_2 over the same set. Blending the distributions: with probability p, draw something from μ_1 . Else, draw something from μ_2 .

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Say we have distributions μ_1, μ_2 over the same set. Blending the distributions: with probability p, draw something from μ_1 . Else, draw something from μ_2 .

Convex combination

Let $\mu_1, \mu_2 \in \mathsf{Distr}(A)$, and let $p \in [0,1]$. Then the convex combination of μ_1 and μ_2 is defined by:

$$\mu_1 \oplus_p \mu_2(a) \triangleq p \cdot \mu_1(a) + (1-p) \cdot \mu_2(a).$$

Example: convex combination

Blend two biased coin flips

- ► Let $\mu_1 = \mathbf{Flip}(1/4), \mu_2 = \mathbf{Flip}(3/4)$
- ▶ From definition of mixing, $\mu_1 \oplus_{1/2} \mu_2$ is a fair coin Flip

Example: convex combination

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Try this at home!

- ▶ Show that $\mathbf{Flip}(r) \oplus_p \mathbf{Flip}(s) = \mathbf{Flip}(p \cdot r + (1-p) \cdot s)$.
- Show this relation between mixing and conditioning:

$$\mu = (\mu \mid E) \oplus_{\mu(E)} (\mu \mid \overline{E})$$

Operations on distributions: independent product

Distribution of two "fresh" samples

Common operation in probabilistic programming languages: draw a sample, and then draw another, "fresh" sample.

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Common operation in probabilistic programming languages: draw a sample, and then draw another, "fresh" sample.

Independent product

Let $\mu_1 \in \mathsf{Distr}(A_1)$ and $\mu_2 \in \mathsf{Distr}(A_2)$. Then the independent product is the distribution in $\mathsf{Distr}(A_1 \times A_2)$ defined by:

$$(\mu_1 \otimes \mu_2)(a_1, a_2) \triangleq \mu_1(a_1) \cdot \mu_2(a_2).$$

Example: independent product

Distribution of two fair coin flips

- \blacktriangleright Let $\mu_1 = \mu_2 = \mathbf{Flip}$
- lacktriangle Then distribution of pair of fair coin flips is $\mu=\mu_1\otimes\mu_2$
- lacktriangle By definition, can show $\mu(b_1,b_2)=(1/2)\cdot(1/2)=1/4$.

Example: independent product

Distribution of two fair coin flips

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- ▶ By definition, can show $\mu(b_1, b_2) = (1/2) \cdot (1/2) = 1/4$.

Try this at home!

- ▶ Show that $unit(a_1) \otimes unit(a_2) = unit((a_1, a_2))$.
- Can you formulate and prove an interesting property relating independent product and distribution bind?

Our First Probabilistic Language

Probabilistic WHILE (PWHILE)





The language, in a nutshell

- ► Core imperative WHILE-language
- ► Assignment, sequencing, if-then-else, while-loops
- ▶ Main extension: a command for random sampling $x \triangleq d$, where d is a built-in distribution

The language, in a nutshell

- ► Core imperative WHILE-language
- Assignment, sequencing, if-then-else, while-loops
- ▶ Main extension: a command for random sampling $x \notin d$, where d is a built-in distribution

Can you guess what this program does?

```
\begin{array}{l} x \not \in \mathbf{Roll}; \\ y \not \in \mathbf{Roll}; \\ z \leftarrow x + y \end{array}
```

Control flow can be probabilistic

- ► Branches can depend on random samples
- Challenge for verification: can't do a simple case analysis
- ► In some sense, an execution takes both branches

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```
\begin{array}{c} choice \, \stackrel{\$}{\sim} \, \mathbf{Flip}; \\ \text{if } choice \, \text{then} \\ res \, \stackrel{\$}{\sim} \, \mathbf{Flip}(1/4) \\ \text{else} \\ res \, \stackrel{\$}{\sim} \, \mathbf{Flip}(3/4) \end{array}
```

Loops can also be probabilistic

- ► Number of iterations can be randomized
- ► Termination can be probabilistic

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Can you guess what this program does?

```
\begin{split} t \leftarrow 0; stop \leftarrow f\!\!f; \\ \text{while } \neg stop \text{ do} \\ t \leftarrow t+1; \\ stop & \stackrel{\$}{\leftarrow} \mathbf{Flip}(1/4) \end{split}
```

More formally: PWHILE expressions

Grammar of boolean and numeric expressions

$$\begin{array}{l} \mathcal{E}\ni e\coloneqq x\in\mathcal{X} & \text{(variables)}\\ \mid b\in\mathbb{B}\mid\mathcal{E}>\mathcal{E}\mid\mathcal{E}=\mathcal{E} & \text{(booleans)}\\ \mid n\in\mathbb{N}\mid\mathcal{E}+\mathcal{E}\mid\mathcal{E}\cdot\mathcal{E} & \text{(numbers)} \end{array}$$

Basic expression language

- Expression language can be extended if needed
- Assume: programs only use well-typed expressions

More formally: PWHILE d-expressions

Grammar of d-expressions

```
\mathcal{DE}
ightarrow d:=\mathbf{Flip} (fair coin flip) |\mathbf{Flip}(p)| (p-biased coin flip, p\in[0,1]) |\mathbf{Roll}| (fair dice roll)
```

"Built-in" or "primitive" distributions

- Distributions can be extended if needed
- "Mathematically standard" distributions
- Distributions that can be sampled from in hardware

More formally: PWHILE commands

Grammar of commands

```
\begin{array}{lll} \mathcal{C}\ni c\coloneqq \mathsf{skip} & \mathsf{(do\ nothing)} \\ & \mid \mathcal{X}\leftarrow\mathcal{E} & \mathsf{(assignment)} \\ & \mid \mathcal{X}\stackrel{\$}{\sim}\mathcal{D}\mathcal{E} & \mathsf{(sampling)} \\ & \mid \mathcal{C}\;;\mathcal{C} & \mathsf{(sequencing)} \\ & \mid \mathsf{if}\;\mathcal{E}\;\mathsf{then}\;\mathcal{C}\;\mathsf{else}\;\mathcal{C} & \mathsf{(if-then-else)} \\ & \mid \mathsf{while}\;\mathcal{E}\;\mathsf{do}\;\mathcal{C} & \mathsf{(while-loop)} \end{array}
```

Imperative language with sampling

- ► Bare-bones imperative language
- ► Many possible extensions: procedures, pointers, etc.