

Reduce to walk

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general resource analysis

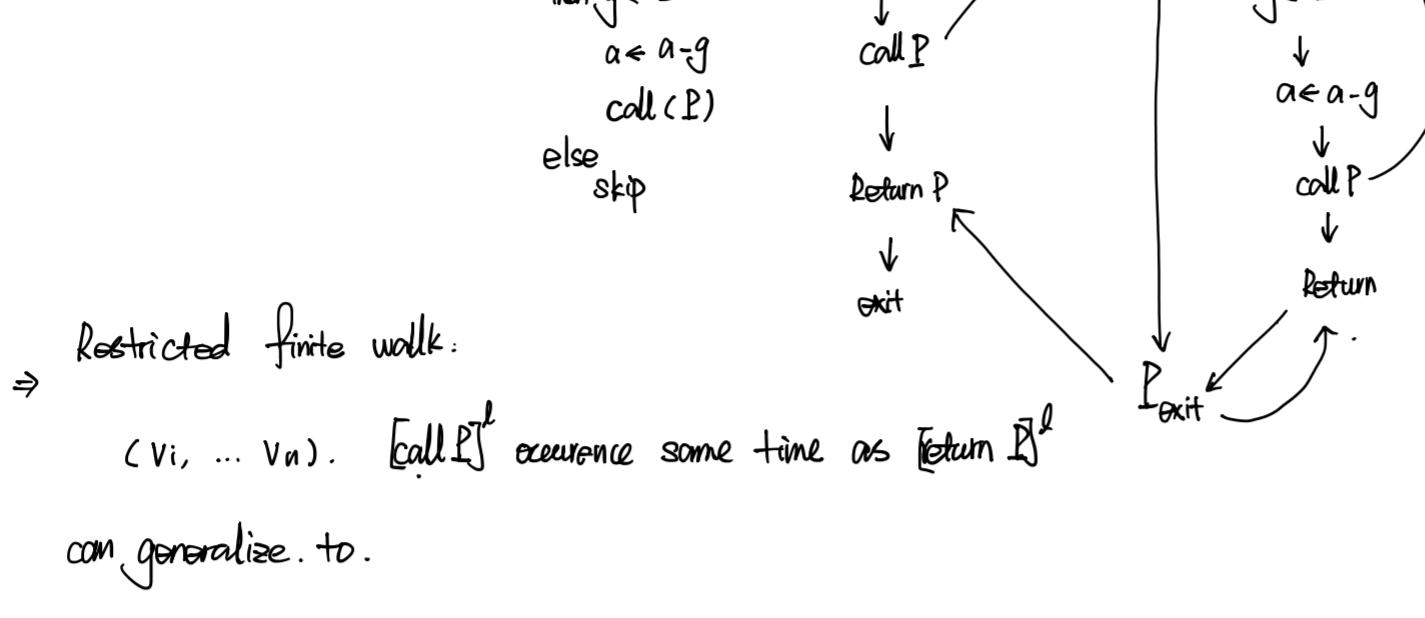
Better, More accurate, to reduce to finite walks

CFL - Reachability : labels of edges composing into a matched word

label matching can be reduced to restrict the occurrence times equality
→ higher efficient, & symbolic occurrence time.

for example:

①. interprocedure call by can be reduced to valid walk by



⇒ Restricted finite walk:

(vi, ... v_n). [call P] occurrence same time as [return P]

can generalize to.

②. Program slicing Problem:

Example Application ②:

program slicing Problem:

Backward / Forward slicing:

→ by define as a single-target L(slice)-problem:

where L defined as:

unbalanced-right := unbalanced-right matched

| unbalanced-right); 1 ≤ i ≤ call site. → ✓

| ↗

slice := unbalanced-right realizable.

→ by restricting inequality between occurrence times of vertices.

③. Data flow

standard Data reachability definition analysis is a special case of

valid walk.

by set the vertex kill x. weight 0

vertex gen x weight 1.

→ valid walk = feasible path.

①. I FDS: (Interprocedural, Finite, Distributive, Subset problems)

→ 1. Supergraph G^*

2. \mathcal{D} : domain of dataflow facts

associated.

Each program point $\rightarrow \text{node} \in \mathcal{D}$.

3. Assign of distributive dataflow functions: $\omega^D \rightarrow \omega^D$, to edges of G^* .

→ solve it as realizable-path reachability problem.

→ exploded supergraph: G^* . for each node in G^* :

$\Rightarrow G^*(n) = \{V_{G^*(n)}, E_{G^*(n)}\}$.

$d \in V_{G^*(n)}$: $d \in \mathcal{D}$: a dataflow fact.

$e = (d_1, d_2)$, $d_1 \in V_{G^*(n_1)}$

$d_2 \in V_{G^*(n_2)}$.

dataflow facts d_1 in node n_1 . if d_1 is true in n_1 .

↓

... d_2 in node n_2 . then $f(d_1) = d_2$ is true in n_2 .

↓ : the fact transformation function from n_1 to n_2 .

→ Formally : G^* :

$V = \bigcup_{n \in G^*} \text{node } n \in G^*, \exists \text{ a node } \langle n, \perp \rangle \text{ in } G^*$.

$\bigcup_{n \in G^*} \text{node } n \in G^*, d \in \mathcal{D}, \exists \text{ a node } \langle n, d \rangle \text{ in } G^*$.

$E_d = \text{edge } e = (\langle m, \perp \rangle, \langle n, d \rangle) \wedge d \in f(\perp)$.

$\bigcup \text{ edge } e = (\langle m, d_1 \rangle, \langle n, d_2 \rangle) \wedge d_1, d_2 \in \mathcal{D}, d_1 \in f(d_2) \wedge d_2 \notin f(\perp)$

$\bigcup \text{ edge } e = (\langle m, \perp \rangle, \langle n, \perp \rangle)$.

Example :

data flow facts : $\perp \vee x, y$: x is the possible uninitialized variable.

$\langle 1, x \rangle$: the node for start point in program where data flow fact x is true.

fact transformation function $f: \lambda S. \perp \vee x, y$

$\perp \vee f(\perp) = \perp \vee x, y \Rightarrow \text{edges: } (\perp, x), (\perp, y), (x, \perp), (y, \perp)$

→ composition of edges. ⇒ pasting nodes.