

Recent Advances in Charge Density Prediction

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Multiscale Modelling and Machine Learning Seminar

Outline

Charge density prediction and equivariant neural networks

E3NN

SCDP: Spherical Channel Density Prediction

ChargE3Net

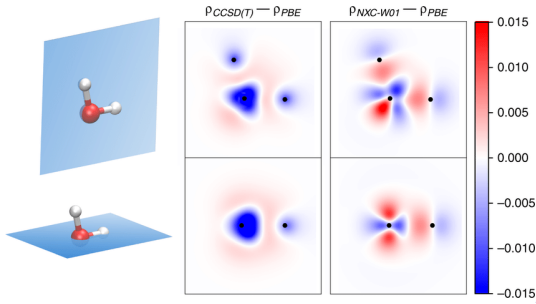
What is Charge Density?

- ▶ Charge density $\rho(\mathbf{r})$ represents the probability distribution of electrons in a system

$$\rho(\mathbf{r}) = N \int |\Psi(\mathbf{r}, \mathbf{r}_2, \dots, \mathbf{r}_N)|^2 d\mathbf{r}_2 \cdots d\mathbf{r}_N, \quad \rho(\mathbf{r}) = \sum_{i=1}^N |\phi_i(\mathbf{r})|^2,$$

for Hartree–Fock and density functional theory (DFT) where orbitals are defined.

- ▶ Key properties:
 - ▶ Non-negative: $\rho(\mathbf{r}) \geq 0$.
 - ▶ Normalized: $\int \rho(\mathbf{r}) d\mathbf{r} = N$ (number of electrons).



Why is Charge Density Important?

- ▶ Fundamental quantity of the DFT, required for most downstream calculations:
 - ▶ Band structure, phonon properties, etc.
 - ▶ High-throughput screening
 - ▶ Property optimization & Structure prediction
- ▶ Contains more information than the energy and force prediction. For a system with N atoms.
 - ▶ Total energy + Forces: dimension = $3N + 1$.
 - ▶ Charge density: dimension = n^3 (n is the plane-wave grid size) or the number of basis functions.
 - ▶ An analog: Text2Text v.s. Text2Image.

Challenges in Charge Density Prediction

Physical constraints:

- ▶ $E(3) = O(3) \oplus \mathbb{R}^3$ equivariance: given two systems $\{(\mathbf{r}_a, Z_a)\}$ and $\{(\mathbf{r}'_a, Z'_a)\}$ related by $\mathbf{r}'_a = \mathbf{R} \mathbf{r}_a + \mathbf{t}$, $Z'_a = Z_a$, the charge density should satisfy:

$$\rho(\mathbf{r}) = \rho'(\mathbf{R} \mathbf{r} + \mathbf{t}), \quad \mathbf{R} \in O(3), \mathbf{t} \in \mathbb{R}^3.$$

Much more difficult than the energy and force prediction, especially for the rotational equivariance. Equivariance on the level of operator.

- ▶ If $E = E(\{(\mathbf{r}_a, Z_a)\})$ is G-invariant, then the gradient of it $F = \nabla_{\mathbf{r}_a} E(\{(\mathbf{r}_a, Z_a)\})$ is G-equivariant.

Two network parametrization for equivariance

- (Basis-based) For molecular systems with basis functions, we require:

$$\rho(\mathbf{r}) = \sum_a \sum_{l=0}^{\infty} \sum_{m=-l}^l c_{alm} R_{al}(|\mathbf{r} - \mathbf{r}_a|) Y_{lm}(\widehat{\mathbf{r} - \mathbf{r}_a}), \quad r = |\mathbf{r}|, \quad \hat{\mathbf{r}} = \frac{\mathbf{r}}{r}.$$

The equivariance of the density can be expressed as the equivariance of the vector of coefficients c_{alm} .

$$\{(\mathbf{r}_a, Z_a)\} \rightarrow \{c_{alm}\}$$

- (Probe-based) For general systems, motivated by implicit neural representation, we require the following map to be invariant:

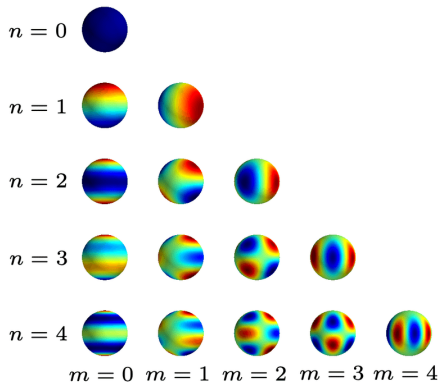
$$\{(\mathbf{r}_a, Z_a), \mathbf{r}'_1, \dots, \mathbf{r}'_n\} \rightarrow \{\rho(\mathbf{r}'_1), \rho(\mathbf{r}'_2), \dots, \rho(\mathbf{r}'_n)\}.$$

- (Mesh-based) Mesh representation of density can model the translational equivariance but not the rotational equivariance.

Representation of SO(3): spherical harmonics

- ▶ Spherical harmonics $Y_{lm}(\hat{\mathbf{r}})$ are eigenfunctions of angular momentum operators.
- ▶ $\{Y_{lm}\}_{m=-l}^l$ forms an irreducible representation of SO(3) of dimension $2l + 1$.

$$Y_{lm}(R\hat{\mathbf{r}}) = \sum_{m'=-l}^l D_{m'm}^l(R) Y_{lm'}(\hat{\mathbf{r}}) \implies (Rc)_{lm} = \sum_{m'=-l}^l D_{m'm}^l(R) c_{lm'}.$$



Add equivariance into graph neural networks (GNN)

- ▶ A GNN is defined on a graph $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ is permutation equivariant.
- ▶ A series of functions $f: \mathbb{R}^{|\mathcal{V}| \times F_i} \rightarrow \mathbb{R}^{|\mathcal{V}| \times F_{i+1}}$, locally aggregates all the features belonging to the neighborhood. For example, a GCN layer:

$$f(X) = \sigma(D^{-1/2} \tilde{A} D^{-1/2} X W), \quad A, D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{V}|}, X \in \mathbb{R}^{|\mathcal{V}| \times F_i}, W \in \mathbb{R}^{F_i \times F_{i+1}}, \tilde{A} = A + I,$$

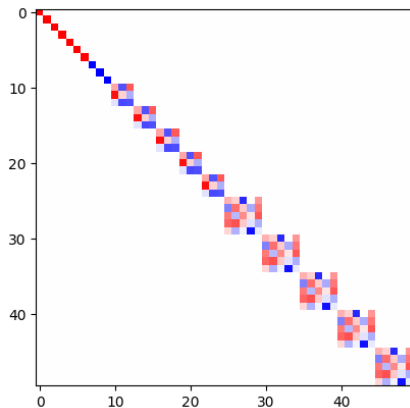
where W is the learnable weight matrix.

To enforce the equivariance $\text{NN}(gX) = g\text{NN}(X), g \in G$:

- ▶ The set of features X should have a $\text{SO}(3)$ -action: construct X via spherical harmonics.
- ▶ The function f should be equivariant for each layer: special attention on the architecture design.

Build an equivariant GNN: irreps as features

- ▶ For each graph node, the feature vector is the direct sum of all the irreps of dimension less than or equal to L .
- ▶ Invariant scalar corresponds to $l = 0$; vector corresponds to $l = 1$; below is the transformation matrix of a rotation on reps $10 \times 0_0 + 5 \times 0_1 + 5 \times 0_2$.



Fully Connected Tensor Product Operation

- ▶ Mathematical definition: $\text{reps} = \text{reps1} \otimes \text{reps2}$.

$$(U^{(l_1)} \otimes V^{(l_2)})_{cm}^{(l)} = \sum_{m_1=-l_1}^{l_1} \sum_{m_2=-l_2}^{l_2} C_{(l_1,m_1)(l_2,m_2)}^{(l,m)} U_{cm_1}^{(l_1)} V_{cm_2}^{(l_2)},$$

where $|l_1 - l_2| \leq l \leq |l_1 + l_2|$, $C_{(l_1,m_1)(l_2,m_2)}^{(l,m)}$ are Clebsch-Gordan coefficients

- ▶ **Equivariant convolution combines features of different angular momenta:**

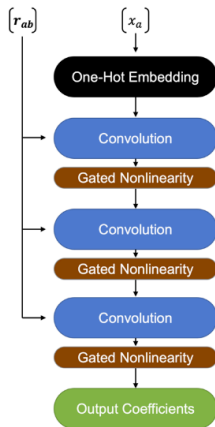
$$\text{Conv}(\mathbf{r}_a, V_{alm}^c) = \sum_{m_1, m_2} C_{(l_1, m_1)(l_2, m_2)}^{(l, m)} \sum_{b \in \partial a} V_{bl_1 m_1}^c R(r_{ab}) Y_{l_2 m_2}(\hat{\mathbf{r}}_{ab}),$$

$$R(r_{ab}) = W_n \sigma(\cdots \sigma(W_2 \sigma(W_1 B(r_{ij}))))), \quad B(r_{ab}) = \frac{2}{r_c} \frac{\sin\left(\frac{n\pi}{r_c} r_{ij}\right)}{r_{ij}} f(r_{ij}, r_c).$$

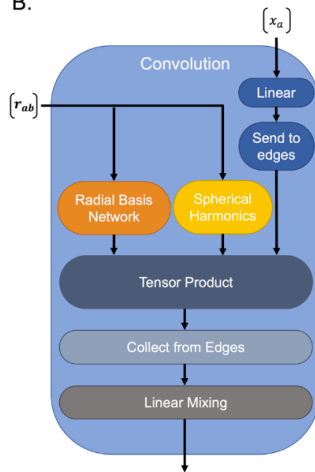
- ▶ Equivariance follows from the definition of the tensor product of the reps and the second reps depends both on the parameters and \mathbf{r} .

Equivariant graph convolution

A.



B.



Other equivariant operations

- ▶ Gated nonlinearity:

$$\sigma_{\text{Gated}}(X) = \sigma(X_{l=0}) \oplus (\sigma(X_{l=0}) \cdot X_{l \neq 0}).$$

- ▶ Self-interaction (similar to 1×1 convolution)

$$X_{c_1 l}^{\text{out}} = \sum_{c_2} W_{c_1 c_2} X_{j l}^{\text{in}}, \quad c_1 \in [F_{\text{out}}], c_2 \in [F_{\text{in}}], l \in [(L+1)^2].$$

- ▶ Point-wise spherical non-linearity.
- ▶ Selfmix layers (similar to self-attention), tensor product with itself.
- ▶ Pairemix layers.

Literature

- ▶ Thomas, Nathaniel, et al. "Tensor field networks: Rotation-and translation-equivariant neural networks for 3d point clouds." arXiv preprint arXiv:1802.08219 (2018).
- ▶ Batzner, Simon, et al. "E (3)-equivariant graph neural networks for data-efficient and accurate interatomic potentials." Nature communications 13.1 (2022): 2453.
- ▶ Passaro, Saro, and C. Lawrence Zitnick. "Reducing SO (3) convolutions to SO (2) for efficient equivariant GNNs." International conference on machine learning. PMLR, 2023.

Dataset

- ▶ QM9: 134k small organic molecules, on average 18 atoms and 666K grid points for charge density voxels¹.
- ▶ MP: 123K crystal structures with charge density².

⁴Ramakrishnan, Raghunathan, et al. "Quantum chemistry structures and properties of 134 kilo molecules." Scientific data 1.1 (2014): 1-7.

⁵Shen, Jimmy-Xuan, et al. "A representation-independent electronic charge density database for crystalline materials." Scientific data 9.1 (2022): 661.

E3NN: Density fitting

- ▶ A consistent basis for all the charge density, not the case for DFT.
- ▶ **Density fitting**: fit the density to a predefined basis set, def2-universal-JFIT³.

$$\rho(\mathbf{r}) = \sum_b C_b \phi_b^{\text{basis}}(\mathbf{r}),$$

The objective function is to minimize: $\mathcal{L} = \frac{1}{N} \sum_i \left(C_b - \widehat{C}_b \right)^2$.

- ▶ 3 hidden layers.
- ▶ Input reps = 2x0e (2 channels l=0) with hydrogen ([1, 0]) and oxygen ([0, 1]).
- ▶ Hidden reps = 125x0o + 125x0e + 40x1o + 40x1e + 25x2o + 25x2e + 15x3o + 15x3e.
- ▶ Output reps = 7x0e + 4x1e + 2x2e + 1x3e.

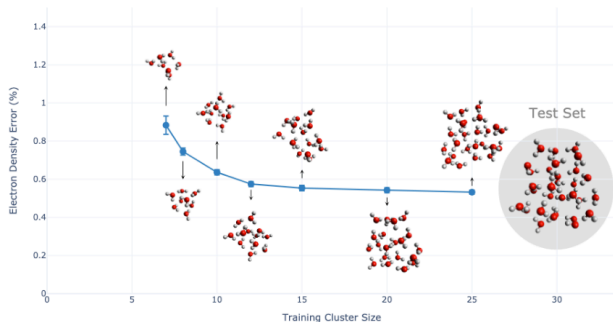
⁶Rackers, Joshua A., et al. "Cracking the quantum scaling limit with machine learned electron densities." arXiv preprint arXiv:2201.03726 (2022).

The effect of cluster size on density prediction

This is one of the first lines of work:

- ▶ Does not train on large dataset for density prediction.
- ▶ Training on specific systems to push the frontier of quantum chemistry calculations.

The y-axis is the relative L^1 -error.



SCDP Architecture Overview

- ▶ Basis-based approach with following ingredients:
 - ▶ Virtual nodes for non-local electronic structures
 - ▶ Even-tempered Gaussian basis sets
 - ▶ High-capacity equivariant spherical channel network (eSCN).
- ▶ Charge density representation with trainable scale parameters:

$$\rho(\mathbf{r}) = \sum_a \sum_l^{N_a} \sum_{m=-l}^l c_{alm} \Phi_{\alpha,l,m,\mathbf{r}_a}(\mathbf{r}, s_{al})$$

$$\Phi_{\alpha,l,m,\mathbf{r}_i}(\mathbf{r}, s) = z_{\alpha,l,s} \exp(-s \cdot \alpha |\mathbf{r} - \mathbf{r}_a|^2) |\mathbf{r} - \mathbf{r}_a|^l Y_{lm}(\widehat{\mathbf{r} - \mathbf{r}_a})$$

- ▶ Model prediction, scaling factors $s_{al} \in (0.5, 2.0)$:

$$\{c_{alm}, s_{al}\} = F(\{(\mathbf{r}_a, Z_a)\}).$$

Virtual Nodes and Basis Sets

- ▶ Virtual nodes:
 - ▶ Placed at bond midpoints.
 - ▶ Use oxygen basis functions
 - ▶ SE(3)-equivariant placement
- ▶ Even-tempered Gaussian basis for better accuracy:

$$\alpha_k = \alpha \cdot \beta^k \text{ for } k = 0, 1, 2, \dots, N_l$$

- ▶ Reducing SO(3) convolution to SO(2): $O(L^6) \rightarrow O(L^3)$.
- ▶ The basis set is not orthonormal, the coefficients depend on the cutoff radius.
- ▶ Two-stage training for stability caused by the scale factors on the exponent:
 - ▶ pre-train the model with fixed basis set exponents
 - ▶ fine-tune the prediction model with a small learning rate with the learning for scaling factors enabled.

Model Architecture

- ▶ Backbone: eSCN (equivariant spherical channel network)
 - ▶ $\{x_a\} = \text{eSCN}(\{(\mathbf{r}_a, Z_a)\})$
 - ▶ Complexity: $O(L^3)$ vs $O(L^6)$ for tensor products
 - ▶ Features: Multi-channel spherical harmonics
 - ▶ Example: $128 \times 0e + 128 \times 1o + 128 \times 2e + 128 \times 3o$
- ▶ Prediction layers:

$$\{c_{alm}, h_i\} = \text{FullyConnectedTensorProduct}(x_i, x_l)$$

$$s_{al} = \frac{C_1}{1 + \exp(-\text{Linear}(h_i) + \ln C_2)} + C_3 \in [C_1, C_3].$$

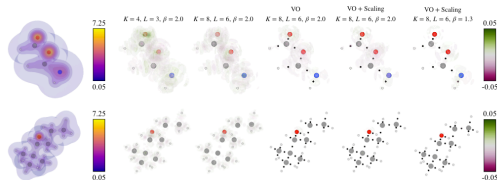
- ▶ Training objective:

$$\mathcal{L} = \mathbb{E}_{\mathbf{r} \in \text{Data}}[|\rho(\mathbf{r}) - \hat{\rho}(\mathbf{r})|]$$

Performance Analysis

- NMAE: 0.178% on QM9 test set
- 31.7x faster than ChargE3Net
- Flexible accuracy-efficiency trade-off

	NMAE [%] ↓	NMAE, Split 2 [%] ↓	Mol. per min. [min^{-1}] ↑
i-DeepDFT [7]	0.357 ± 0.001	-	-
e-DeepDFT [7]	0.284 ± 0.001	-	-
ChargE3Net [15]	0.196 ± 0.001	0.203 ± 0.003	3.95
InfGCN [12]	0.869 ± 0.002	0.93	72.00
InfGCN, GTO only [12]	-	3.72	-
GPWNO [22]	-	0.73	-
SCDP models (Ours)			
eSCN, $K = 4, L = 3, \beta = 2.0$	0.504 ± 0.001	0.514 ± 0.003	675.47
eSCN, $K = 8, L = 6, \beta = 2.0$	0.434 ± 0.006	0.452 ± 0.017	567.19
eSCN, $K = 8, L = 6, \beta = 1.5$	0.381 ± 0.001	0.391 ± 0.002	442.25
eSCN + VO, $K = 8, L = 6, \beta = 2.0$	0.237 ± 0.001	0.250 ± 0.002	231.21
eSCN + VO, $K = 8, L = 6, \beta = 1.5$	0.206 ± 0.001	0.220 ± 0.002	177.14
eSCN + VO, $K = 8, L = 6, \beta = 1.3$	0.196 ± 0.001	0.209 ± 0.002	136.92
SCDP models fine-tuned with scaling factors (Ours)			
eSCN, $K = 4, L = 3, \beta = 2.0$	0.432 ± 0.001	0.438 ± 0.003	644.00
eSCN, $K = 8, L = 6, \beta = 2.0$	0.369 ± 0.007	0.386 ± 0.018	544.56
eSCN, $K = 8, L = 6, \beta = 1.5$	0.346 ± 0.001	0.354 ± 0.002	419.57
eSCN + VO, $K = 8, L = 6, \beta = 2.0$	0.207 ± 0.001	0.220 ± 0.002	221.19
eSCN + VO, $K = 8, L = 6, \beta = 1.5$	0.187 ± 0.001	0.200 ± 0.002	164.94
eSCN + VO, $K = 8, L = 6, \beta = 1.3$	0.178 ± 0.001	0.191 ± 0.002	125.29



ChargE3Net Architecture Overview

- ▶ Based on the E3NN backbone.
- ▶ Construct two k-d trees to partition the atoms and probes.
- ▶ Two types of convolutions:
 - ▶ $\text{Conv}_{\text{atom}}$: Bidirectional between atoms

$$\text{Conv}_{\text{atom}}^n(\mathbf{r}_i, X_i^n) = W_1^n \left(\sum_{j \in \partial(i)} W_2^n X_j^n \otimes R(r_{ij}) Y(\mathbf{r}_{ij}) \right) + W_3^n X_i^n.$$

- ▶ $\text{Conv}_{\text{probe}}$: From atoms to probes, only contains neighboring atoms, no probe-probe interactions.
- ▶ Training objective:

$$\mathcal{L} = \frac{\sum_{\mathbf{r} \in G} |\rho(\mathbf{r}) - \hat{\rho}(\mathbf{r})|}{\sum_{\mathbf{r} \in G} |\rho(\mathbf{r})|}$$

Model performance

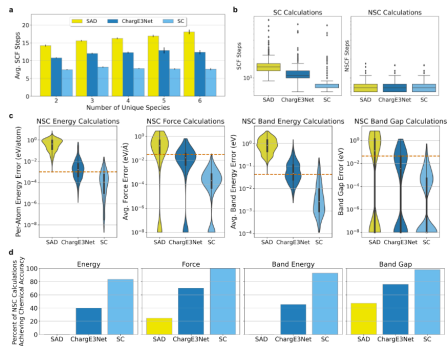
- ▶ Vertices:
 - ▶ Atoms: One-hot encoding of atomic number; reps = $N \times 0$.
 - ▶ Probe points: Initialized as zero scalar; reps = 1×0 .
- ▶ Edges:
 - ▶ Atom-atom: Unidirectional, cutoff 4Å
 - ▶ Atom-probe: Directed from atoms to probes
- ▶ Periodic boundary conditions supported

Dataset	invDeepDFT	equiDeepDFT	OrbNet-Equi	ChargE3Net
NMC	0.089 ± 0.001	0.061 ± 0.001	-	0.060 ± 0.001
QM9	0.357 ± 0.001	0.284 ± 0.001	0.206 ± 0.001	0.196 ± 0.001
MP	0.859 ± 0.011	0.799 ± 0.010	-	0.523 ± 0.010

All values are presented as an average ϵ_{mae} (%) and \pm one standard error. Bold values represent the best ϵ_{mae} (%) scores. ϵ_{mae} reported for MP include both magnetic and non-magnetic materials.

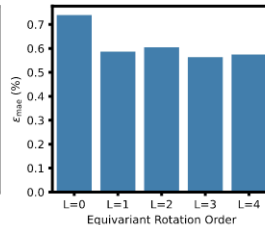
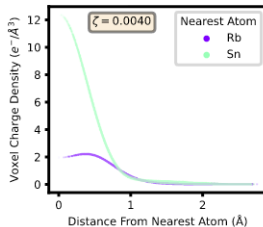
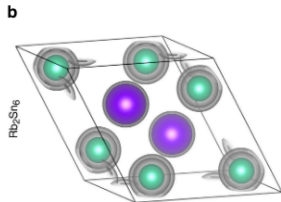
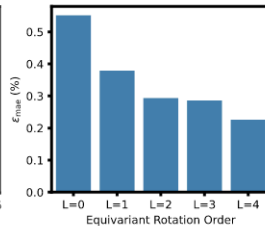
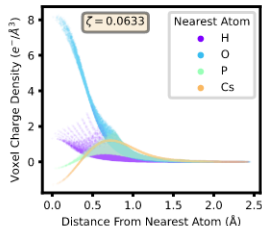
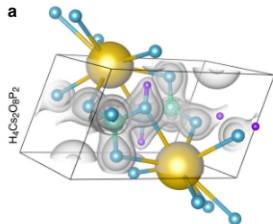
Performance

- ▶ Accelerate DFT calculations: MP materials: 26.7% reduction; GNoME materials: 28.6% reduction.
- ▶ Non-self-consistent property prediction:
 - ▶ 40% of materials: energy errors < 1 meV/atom
 - ▶ 70% of materials: forces < 0.03 eV/Å
 - ▶ 76% of materials: band gaps within chemical accuracy
- ▶ Linear scaling $O(N)$ with system size.



Effect of higher-order features

- ▶ The total dimension of features is N .
- ▶ With highest order L , The dimension of each order is $N/(L + 1)$.
- ▶ The channel of order l is $N/(L + 1)/(2l + 1)$.



Angular Variance Analysis

- ▶ Performance improvement:
 - ▶ 44.6% median improvement for materials with non-metals/metalloids
 - ▶ 23.0% median improvement for materials with only metals
- ▶ Metric ζ for angular variance:

$$\zeta(G) = 1 - \frac{\sum_{\vec{g}_k \in G} |\nabla \rho(\vec{g}_k) \cdot \hat{r}_{ki}|}{\sum_{\vec{g}_k \in G} \|\nabla \rho(\vec{g}_k)\|}$$

- ▶ High angular variance materials, e.g. $\text{Cs}(\text{H}_2\text{PO}_4)$
 - ▶ Strong covalent bonding
 - ▶ Significant L=4 improvement
- ▶ Low angular variance materials, e.g. Rb_2Sn_6 :
 - ▶ Primarily ionic interactions
 - ▶ Similar L=0 and L=4 performance

Discussions

- ▶ Incorporate more symmetries: space-group symmetry, point-group symmetry of crystal.
- ▶ Comparison with approaches of canonical transformations. This type of method is restricted to be probe-based.
- ▶ Different approaches to equivariance in robot community: equivariant vision.
- ▶ **Sobolev training for downstream tasks where the gradient information of the density is required.**
- ▶ Does it worth to pursue the equivariance for the model? Seems not necessary as the AlphaFold evolves.