

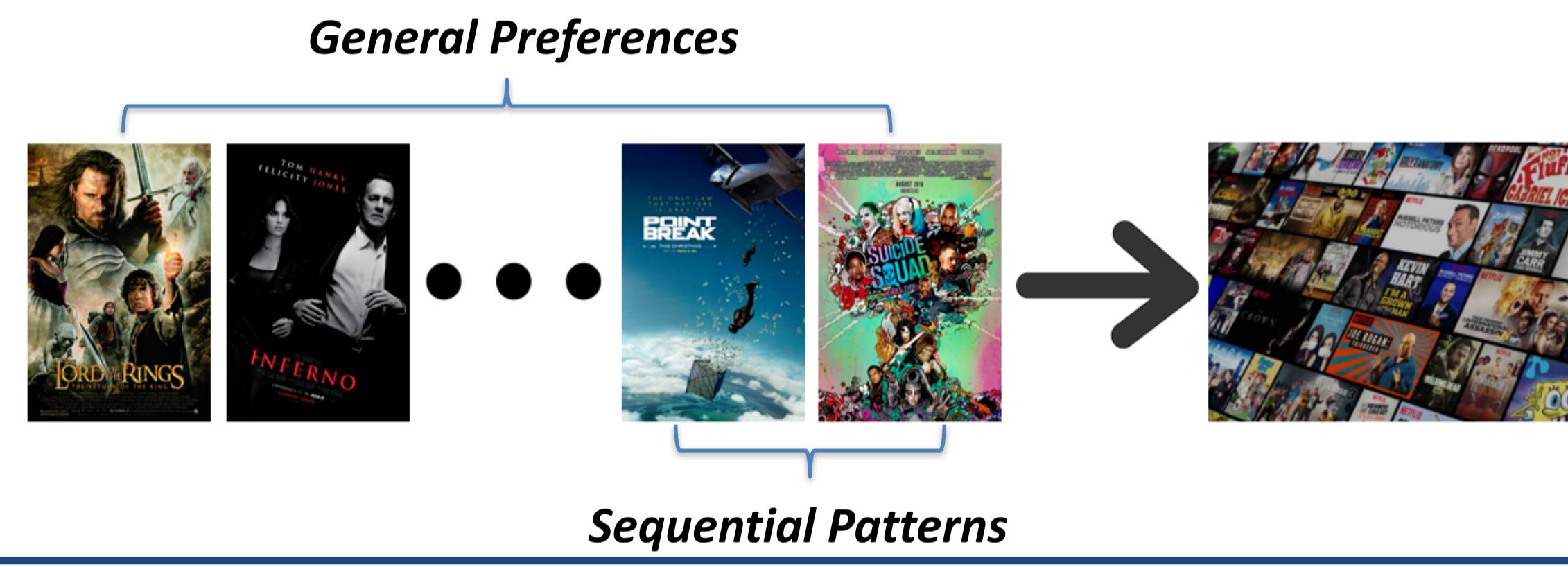
## Abstract

- We study **sequential recommendation** problem as the order of interaction implies that sequential patterns play an important role on user's next action.
- Under such setting, sequential patterns should be carefully modeled, in both **point-level** and **union-level**.
- We propose a **Convolutional Sequence Embedding Recommendation Model (Caser)** to model the above two types of sequential patterns.
- The experiments on public data sets demonstrated that Caser consistently outperforms state-of-the-art sequential recommendation methods

## Sequential Recommendation

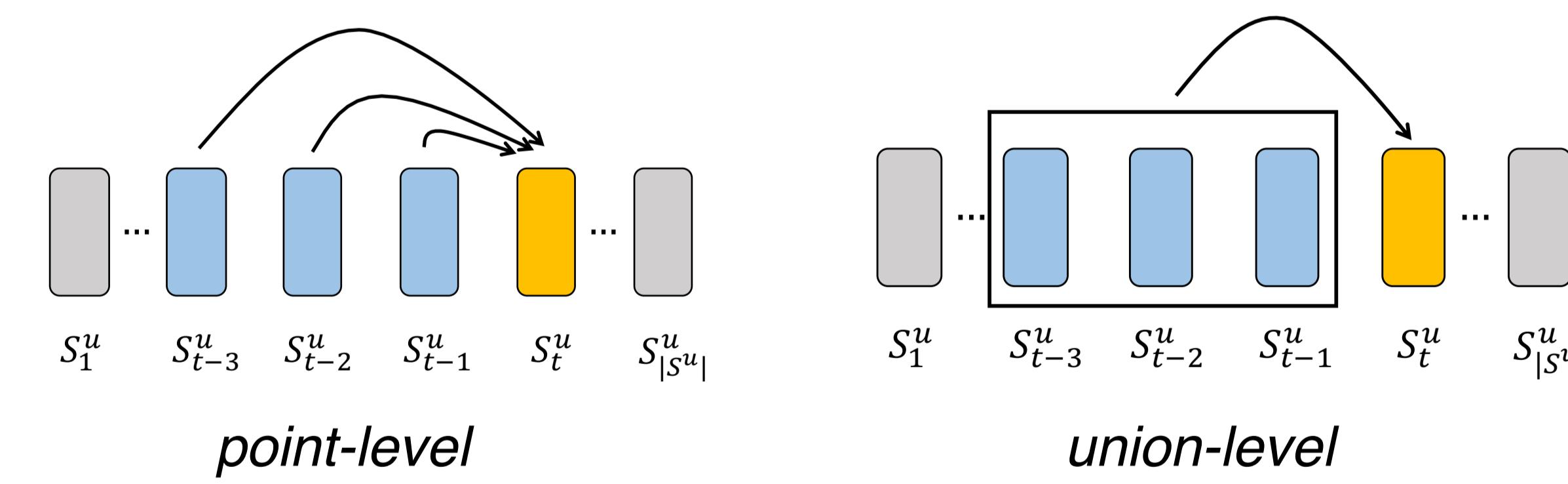
Given a user's sequences  $S_u$ , recommend a list of items that maximize her/his future needs, by considering both **general preferences** and **sequential patterns**.

- General Preferences:** represent user's **long term** and **static** behaviors and are unlikely to change in a short period of time.
- Sequential Patterns:** represent user's **short term** and **dynamic** behaviors and come from a close proximity of time.



## Related Works and Motivations

- Existing works model sequential pattern in **point-level**, fail to model sequential pattern in **union-level**.
- point-level:** each of the previous actions influences the target action **individually**, instead of collectively
- union-level:** several previous actions **jointly** influence the target action.

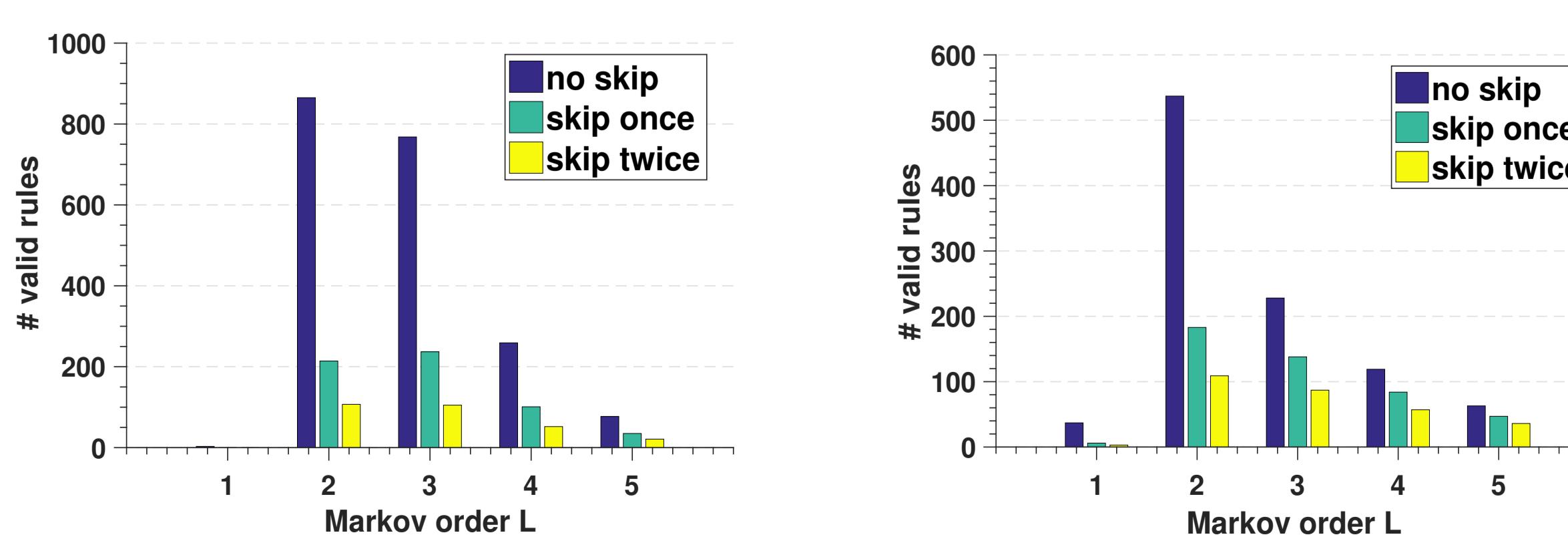


- Find the existence of union-level sequential pattern.

When we mine sequential association rules of the form

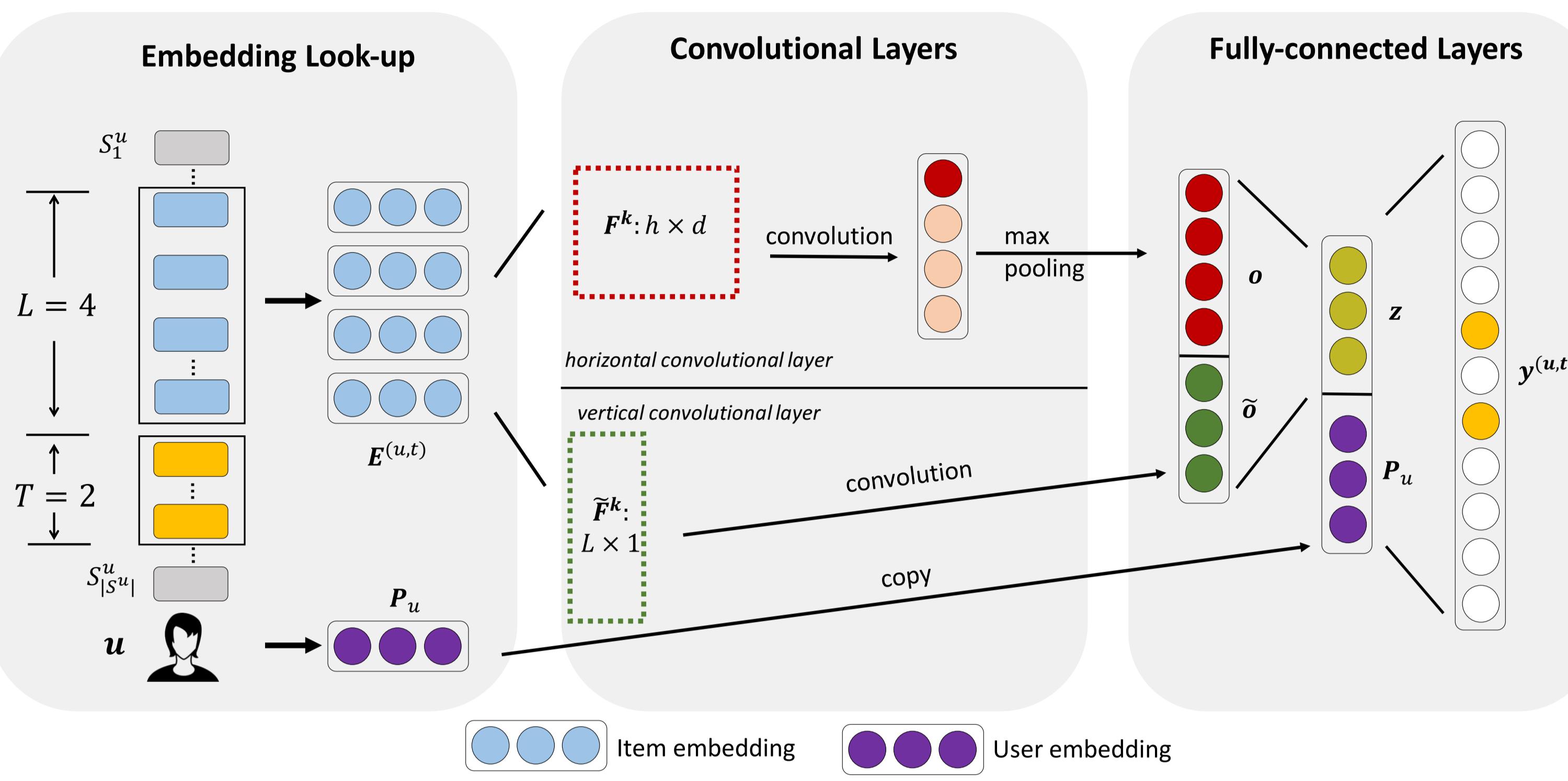
$$(S_{t-L}^u, \dots, S_{t-2}^u, S_{t-1}^u) \rightarrow S_t^u.$$

With confidence=50% and support=5, most of the resulting rules have the length larger than 1 ( $L > 1$ ), indicating the existence of union-level influences.



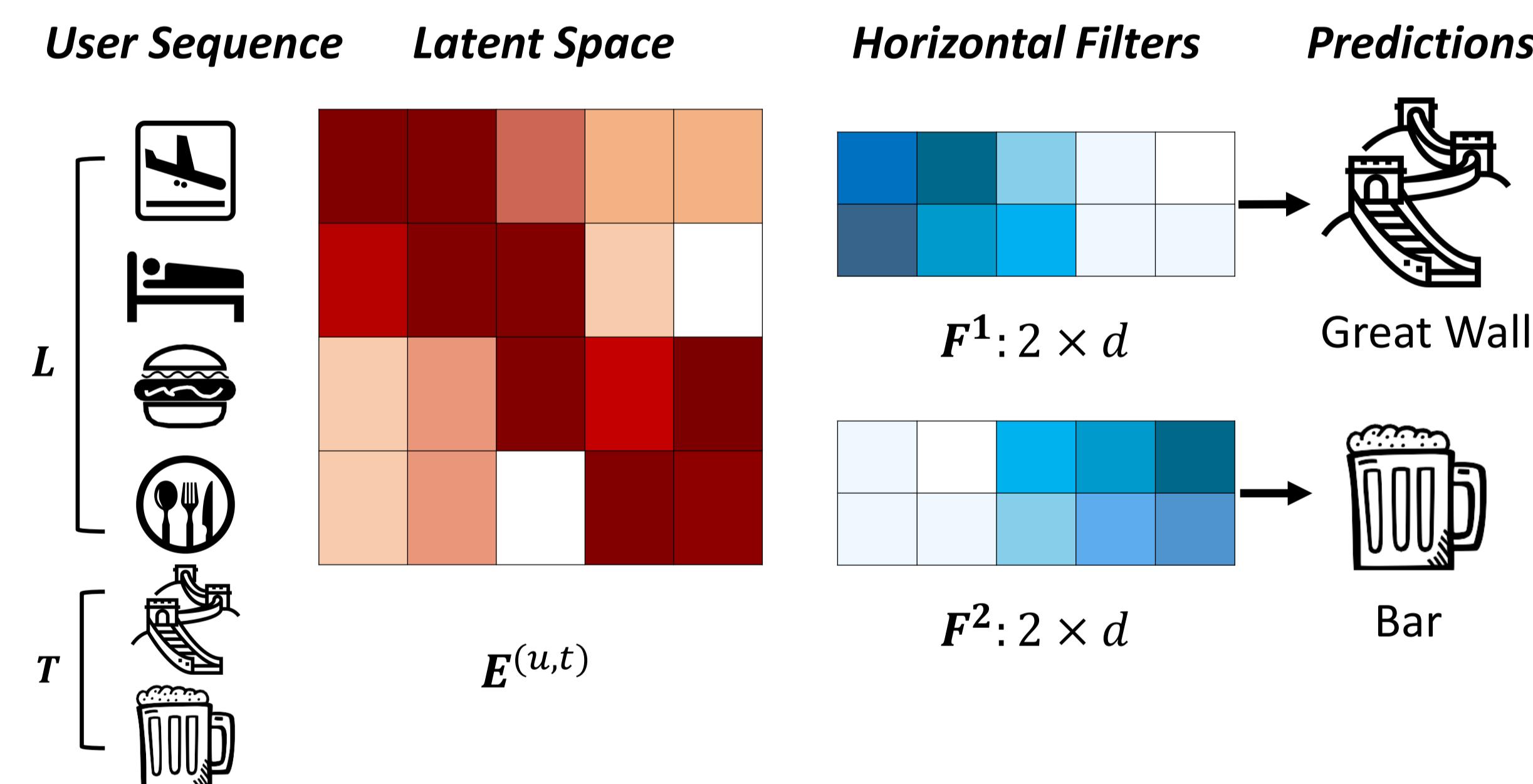
## The network architecture of Caser

- Convolutional Neural Network (CNN)** is used to capture both **point-level** and **union-level** sequential patterns.
- By incorporating **Latent Factor Model (LFM)**, Caser is also able to capture user's **general preferences**.



## Capture Union-level Sequential Pattern with Horizontal Convolutional Filters

- Borrow the idea of using CNN in text classification, we use convolutional filters to search for sequential patterns.
- Sliding horizontally (from top to bottom), the horizontal convolutional filters are used with **different height** (multiple union sizes) but **same width** (same to the latent dimension).
- Max pooling** operation on the result for extracting the **most significant** feature from a particular filter.



The first horizontal filter picks up the union-level sequential pattern "(Airport, Hotel) → Great Wall" by having larger values in the latent dimensions where Airport and Hotel have larger values.

## Capture Point-level Sequential Pattern with Vertical Convolutional Filters

- Sliding vertically (from left to right), the vertical convolutional filters have **same height** (i.e.,  $L$ ) and **same width** (i.e., 1).
- Vertical convolutional filters are learned to **aggregate** the latent embeddings of previous items.
- In other words, they are performing **weighted sum** over previous items' latent representations, thus capture point-level sequential pattern.

## Network Training

- Extract every  $L$  item as input, and the next  $T$  items as targets.
- Sigmoid Negative Log-Loss** with random negative sampling is used as optimization criterion.

Codes and Data are available at: <http://www.sfu.ca/~jiaxit/>

## Experimental Setup

- Datasets:** 4 datasets with large **Sequential Intensity** is used MovieLens, Gowalla, Foursquare and Tmall.

$$\text{Sequential Intensity (SI)} = \frac{\#\text{rules}}{\#\text{users}}$$

Datasets	Sequential Intensity	#users	#items	avg. actions per user
MovieLens	0.3265	6.0k	3.4k	165.50
Gowalla	0.0748	13.1k	14.0k	40.74
Foursquare	0.0378	10.1k	23.4k	30.16
Tmall	0.0104	23.8k	12.2k	13.93

- Baselines (non-sequential):** POP, BPR,
- Baselines (sequential):** FPMC, Fossil and GRU4Rec

## Evaluation Metrics:

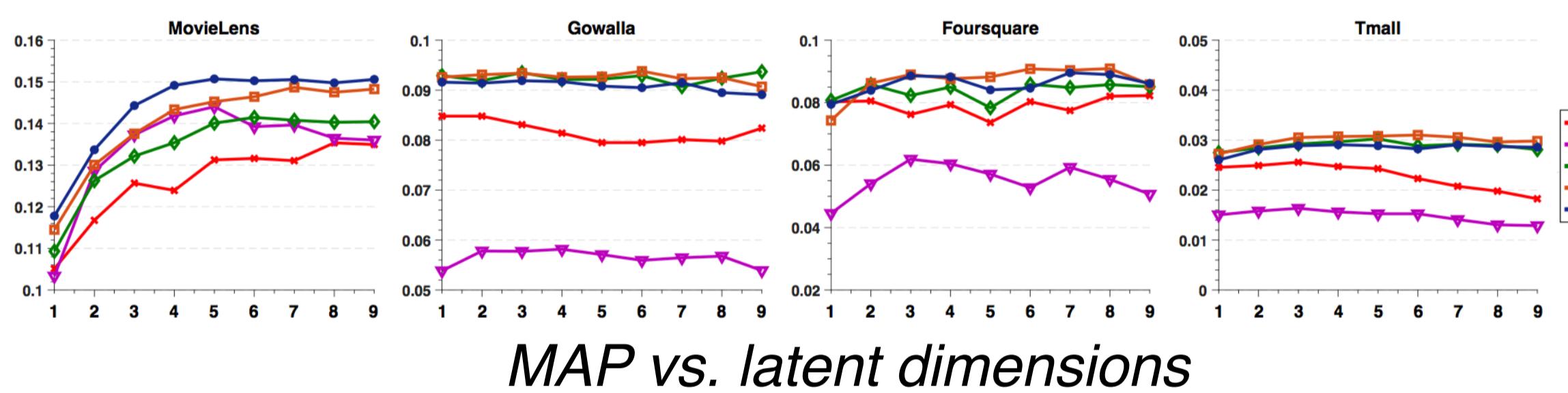
- Precision@n ( $n \in \{1, 5, 10\}$ )
- Recall@n ( $n \in \{1, 5, 10\}$ )
- Mean Average Precision (MAP)

## Experimental Results

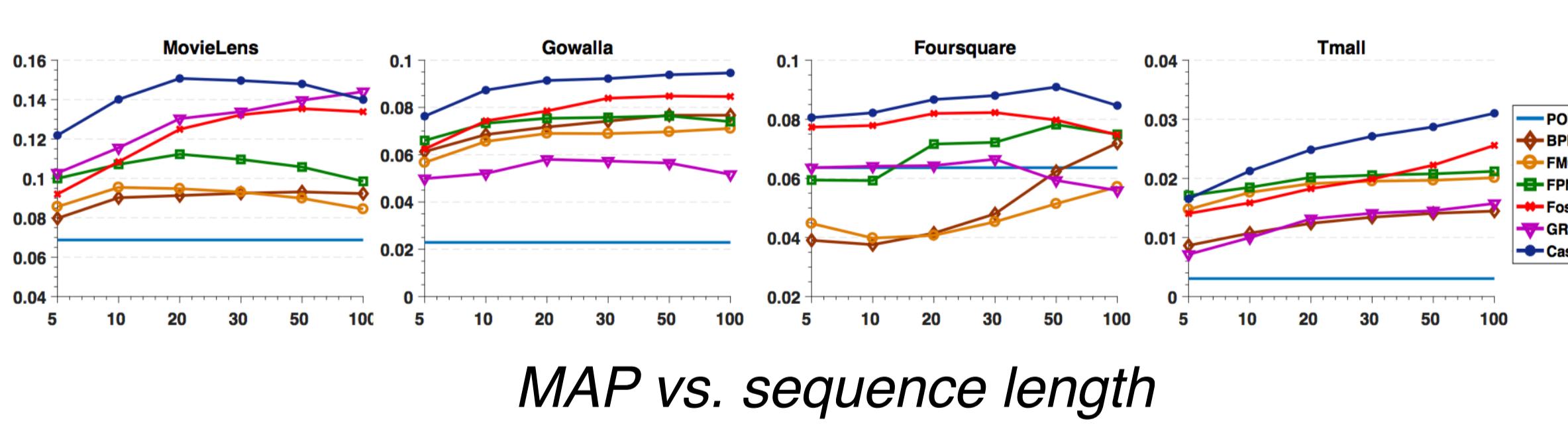
### Overall performance:

Dataset	Metric	POP	BPR	FPMC	FPMC	Fossil	GRU4Rec	Caser	Improv.
MovieLens	Prec@1	0.1280	0.1478	0.1748	0.2022	0.2306	<b>0.2515</b>	0.2502	-0.5%
	Prec@5	0.1282	0.1288	0.1505	0.1659	0.2000	0.2146	<b>0.2175</b>	1.4%
	Prec@10	0.1011	0.1193	0.1317	0.1460	0.1800	0.1916	<b>0.1991</b>	4.0%
	Recall@1	0.0059	0.0070	0.0104	0.0118	0.0144	<b>0.0153</b>	0.0148	-3.3%
	Recall@5	0.0213	0.0312	0.0432	0.0468	0.0602	0.0629	<b>0.0632</b>	0.5%
	Recall@10	0.0375	0.0560	0.0722	0.0777	0.1061	0.1093	<b>0.1121</b>	2.6%
Gowalla	MAP	0.0687	0.0913	0.0949	0.1053	0.1354	0.1440	<b>0.1507</b>	4.7%
	Prec@1	0.0517	0.1640	0.1532	0.1555	0.1736	0.1850	<b>0.1961</b>	13.0%
	Prec@5	0.0362	0.0983	0.0876	0.0936	0.1045	0.1071	<b>0.1129</b>	8.0%
	Prec@10	0.0281	0.0726	0.0657	0.0698	0.0782	0.0871	<b>0.0833</b>	6.5%
	Recall@1	0.0064	0.0250	0.0234	0.0256	0.0277	0.0155	<b>0.0310</b>	11.9%
	Recall@5	0.0257	0.0743	0.0648	0.0722	0.0793	0.0529	<b>0.0845</b>	6.6%
Foursquare	Recall@10	0.0402	0.1077	0.0950	0.1059	0.1166	0.0826	<b>0.1223</b>	4.9%
	MAP	0.0229	0.0767	0.0711	0.0764	0.0848	0.0850	<b>0.0928</b>	9.4%
	Prec@1	0.1090	0.1233	0.0875	0.1081	0.1191	0.1018	<b>0.1351</b>	13.4%
	Prec@5	0.0477	0.0543	0.0445	0.0553	0.0580	0.0475	<b>0.0619</b>	6.7%
	Prec@10	0.0304	0.0348	0.0309	0.0385	0.0399	0.0331	<b>0.0425</b>	6.5%
	Recall@1	0.0376	0.0445	0.0308	0.0440	0.0497	0.0369	<b>0.0565</b>	13.7%
Tmall	Recall@5	0.0800	0.0888	0.0689	0.0948	0.0707	0.0700	<b>0.1035</b>	7.9%
	Recall@10	0.0954	0.1061	0.0911	0.1200	0.1187	0.1011	<b>0.1291</b>	7.6%
	MAP	0.0636	0.0719	0.0571	0.0782	0.0823	0.0643	<b>0.0909</b>	10.4%

- Caser outperform other baselines with fewer parameters:



- Caser best utilizes the extra information provided by increasing number of items in the sequence:



## Case Studies

- Visualize the influences of Caser's prediction when masking out certain items within a sequence.

