ROBUST STABLE MATCHING PROBLEM MASTER THESIS (PDM) - SPRING 2024

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Table of Contents

Introduction

Robustness of stable matchings

Polytope and lattice structure

Prototype

We consider a real-life stable matching problem.

Input:

- ► a set of students *S*,
- ▶ a set of (semester) projects *P*,
- preference lists of each student and project over the opposite set;

Output:

▶ a stable matching between *S* and *P*.

Settings

Throughout the talk, we will use the following settings unless otherwise specified:

- ▶ Complete bipartite graph $G = (S \cup P, E)$,
- Two-sided strict preferences,
- ► |S| = |P| = n.

Stable matching

Definition (Blocking edge)

An edge $sp \in E$ is a **blocking edge (unstable pair)** of matching M, if

- ▶ $sp \notin M$,
- ightharpoonup s prefers p to M(s),
- \triangleright p prefers s to M(p),

where M(s) is the partner of s in M, similar for M(p).

Stable matching

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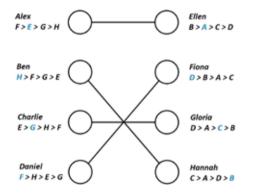
- sp ∉ M,
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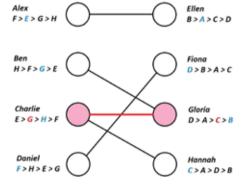
where M(s) is the partner of s in M, similar for M(p).

Definition (Stable matching)

A matching M is **stable** if it has no blocking edge.

Example





Applications of stable matching

- Marriage;
- College admission;
- Online dating;
- Firm / worker matchings;
- Jobs / server matchings;
- Patient / hospital matchings;

Results

- 1. The stable matching problem can be solved in linear time, using **Gale-Shapley** algorithm (1962), which is a deferred acceptance algorithm.
- 2. Depending on who propose, the output of Gale-Shapley algorithm can be either student-optimal M_0 , or project-optimal M_z .
- 3. The number of all stable matchings of an instance can be exponentially large.
- 4. The set of stable matchings can be equipped with polytope structure and lattice structure (explained later).

Research on stable matchings

Different iutput:

- Preference with ties,
- One-sided preferences.

Different onput (other than stability):

- Popular matching,
- Pareto-optimal matching,
- Internally stable matching,
- ► Robust stable matching.

Table of Contents

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Question: What does "robustness" mean for stable matching problems?

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When an unforeseen event occurs, we want our stable matching solution remains stable under minimum number of modifications.

Question: What are the "unforeseen events"?

1. Elements in the preference list are swapped, e.g.,

Alex:
$$F > E > G > H$$
 \longrightarrow $F > G > E > H$,

- 2. Certain edges are not allowed to appear in the solution,
- 3. Certain agents quit (have not been studied before).

Problems

We shall focus on the last kind, i.e., some projects become unavailable (removed from the instance).

Problems

Problem (FINDING (a, b)-ROBUST STABLE MATCHING)

Input:

- ightharpoonup matching instance \mathcal{I} with n students, n+a projects, and complete preferences,
- ightharpoonup $a,b\in\mathbb{N}$.

Output:

ightharpoonup stable matching M, such that when any a matched projects are removed from \mathcal{I} , we can repair by breaking at most b extra edges, to get again a stable matching.

Problems

Problem (CHECKING (a, b)-ROBUST STABLE MATCHING)

Input:

- ightharpoonup matching instance $\mathcal I$ with n students, n+a projects, and complete preferences,
- ightharpoonup $a,b\in\mathbb{N}$.
- ightharpoonup stable matching M of \mathcal{I} .

Output:

Decision of whether M is (a, b)-robust, i.e., when any a matched projects are removed from \mathcal{I} , we can repair M by breaking at most b extra edges to get again a stable matching.

Upper bound of extra changes?

Question: How many extra edges need to be changed for repairing, that is, how large can b be? Let's consider the following example, for a = 1.

The formulation of our problem, is motivated by the (a, b)-supermatch problem, studied in [Genc et al., 2017].

Problem (FINDING (a, b)-SUPERMATCH)

Input:

- \triangleright matching instance \mathcal{I} with n students, n projects, and complete preferences,
- \triangleright $a, b \in \mathbb{N}$.

Output:

▶ stable matching M, such that when any a matched edges are not allowed, we can repair by breaking at most b extra edges, to get again a stable matching.

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▶ stable matching M, such that when any a matched edges are not allowed, we can repair by breaking at most b extra edges, to get again a stable matching.

Results: This problem is proved to be NP-hard. Moreover, even the special case of finding (1,1)-supermatch is NP-hard.

Problem (CHECKING (a, b)-SUPERMATCH)

Input:

- lacktriangleright matching instance ${\mathcal I}$ with n students, n+a projects, and complete preferences,
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- ▶ stable matching M of I.

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- ightharpoonup matching instance \mathcal{I} with n students, n+a projects, and complete preferences,
- ightharpoonup $a,b\in\mathbb{N}$.
- ightharpoonup stable matching M of \mathcal{I} .

Output:

Decision whether M is a (a, b)-supermatch, i.e., when any a matched edges are not allowed, we can repair M by breaking at most b extra edges to get again a stable matching.

Results: The special case of this problem, which is CHECKING (1, b)-SUPERMATCH, can be solved in polynomial-time, whose complexity is independent of b.

Problems to attack

	Supermathch	ROBUST STABLE MATCHING			
Definition	Edges not allowed	Projects deleted			
Instance changed?	No	Yes			
Algorithmic results	Checking $(1, b)$: poly-time	?1			
Complexity results	Finding $(1,1)$: NP-hard	?2			

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Lists of questions:

- 1. Try to show that checking (1, b)-robustness can be solved in poly-time,
- 2. Try to prove that finding (1, b)-robust stable matching is not FPT, Try to prove that finding (1, 1)-robust stable matching is NP-hard.

Problems to attack

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Lists of questions:

- 1. Try to show that checking (1, b)-robustness can be solved in poly-time,
- 2. Try to prove that finding (1, b)-robust stable matching is not FPT, Try to prove that finding (1, 1)-robust stable matching is NP-hard.

Remark. Deleting projects is NOT the same as not allowing all the edges the projects incident to.

Table of Contents

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Matching polytope

Definition (Incidence vector)

The **incidence vector** of a matching M is a vector $x(M) \in \{0,1\}^{|S| \times |P|}$ (for simplicity, we just write x), such that

$$x_{s,p} = \begin{cases} 1, & \text{if } M(s) = p \\ 0, & \text{otherwise} \end{cases}$$

We often identify each matching M with its incidence vector x.

Matching polytope

Theorem

A vector $x \in \mathbb{R}^{|S| \times |P|}$ is a matching if and only if it is an integer solution of the following system of linear inequalities:

$$\sum_{s,p} x_{s,p} \le 1, \quad \text{for each } s \in S, \tag{1}$$

$$\sum_{s \in S} x_{s,p} \le 1, \quad \text{for each } p \in P, \tag{2}$$

$$x_{s,p} \ge 0$$
, for each $s \in S, p \in P$. (3)

Matching polytope

Definition (Fractional matching)

A **fractional matching** is a (not necessarily integer) vector in $\mathbb{R}^{|S|\times|P|}$ which satisfies the matching constraints (1), (2), and (3).

These inequalities define a matching polytope.

Theorem (Birkhoff)

Each fractional matching is a convex combination of matchings.

Equivalently,

- 1. Matching polytope is integral.
- 2. The extreme points of matching polytope are exactly the matchings.

Stable matching polytope

Theorem

A vector $x \in \mathbb{R}^{|S| \times |P|}$ is a stable matching if and only if it is an integer solution of the following system of linear inequalities:

$$\sum_{p \in P} x_{s,p} \le 1, \quad \text{for each } s \in S, \tag{1}$$

$$\sum_{s \in S} x_{s,p} \le 1, \quad \text{for each } p \in P, \tag{2}$$

$$x_{s,p} \ge 0$$
, for each $s \in S, p \in P$, (3)

$$\sum_{p'>_{s}p} x_{s,p'} + \sum_{s'>_{p}s} x_{s',p} + x_{s,p} \ge 1, \quad \text{for each } s \in S, p \in P. \tag{4}$$

We call the last inequality the **stability constraint**.

Stable matching polytope

Definition (Stable fractional matching)

A **stable fractional matching** is a (not necessarily integer) vector which satisfies the matching constraints (1), (2), (3), and (4).

These inequalities define a **stable matching polytope**, denoted as $P(\mathcal{M})$.

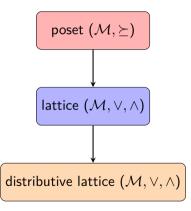
Theorem (Vande Vate, 1989)

Each stable fractional matching is a convex combination of stable matchings. Equivalently,

- 1. Stable matching polytope is integral.
- 2. The extreme points of stable matching polytope are exactly the stable matchings.

Stable matching lattice

Let \mathcal{M} be the set of stable matchings.



Poset

Definition

For any two (stable) matching M and M', $M \succeq M'$ if and only if all students weakly prefer M to M'. We say that M dominates M'.

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Example. Students: 1, 2, 3, 4; Projects: A, B, C, D.

The following are their preference lists.

		{B}			A	4	3	2	1
2	B	$\{A\}$	D	C	В	3	4	1	2
3	{C }	D	A	В	C	2	1	4	3
4	{ D }	C	В	A	D	1	2	3	4

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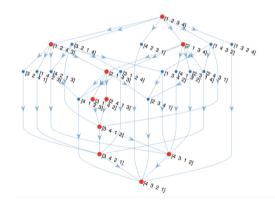
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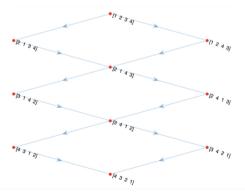
$$M_{\text{red}} \succeq M_{\{\}}, M_{\square} \succeq M_{\text{blue}}$$

Examples





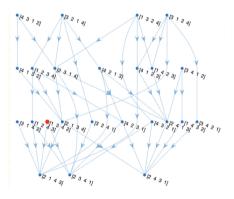




Examples

1	C	A C A D	D	В
2	В	C	Α	D
3	В	Α	C	D
4	В	D	C	A

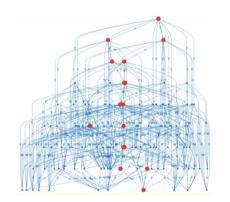
A B C D	1	3	2	4
В	4	2	3	1
C	2	3	1	4
D	4	3	1	2



Examples

1	Α	B A D C B	E	D	C
2	В	Α	D	E	C
3	C	D	Α	В	\mathbf{E}
4	D	C	В	Α	\mathbf{E}
5	Ε	В	C	D	Α

Α	5 3 2 5 4	4	3	2	1
В	3	4	5	1	2
C	2	1	5	4	3
D	5	1	2	3	4
E	4	3	2	1	5





Two operators

Definition

For two stable matchings M, M', define

$$M \vee M' = M^{\uparrow}$$

where M^{\uparrow} is the set of student-project pairs, in which each student is matched to their better (more preferred) partner between M and M'.

Two operators

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$$M \vee M' = M^{\uparrow}$$

where M^{\uparrow} is the set of student-project pairs, in which each student is matched to their better (more preferred) partner between M and M'.

For two stable matchings M, M', define

$$M \wedge M' = M^{\downarrow}$$

where M^{\downarrow} is the set of student-project pairs, in which each student is matched to their worse (less preferred) partner between M and M'.

Example.

1	\boldsymbol{A}	{B}	C	D	A	4	3	2	1
2	B	$\{A\}$	D	C	В	3	4	1	2
3	{C }	D	A	В	C	2	1	4	3
4	{ D }	C	В	A	D	1	2	3	4

Example.

$$M_{\text{red}} = M_{\{\}} \lor M_{\square}$$

 $\{1B, 2A, 3D, 4C\} = M_{\{\}} \land M_{\square}$

Join and meet

Proposition

- 1. M^{\uparrow} , M^{\downarrow} are stable matchings.
- 2. M^{\uparrow} is the **join** of M and M', i.e.,
 - $ightharpoonup M^{\uparrow} \succ M$ and $M^{\uparrow} \succ M'$.
 - for any M" such that M" \succ M and M" \succ M', M" \succ M[†]
- 3. M^{\downarrow} is the **meet** of M and M', i.e.,
 - $ightharpoonup M \succ M^{\downarrow}$ and $M' \succ M^{\downarrow}$.
 - for any M" such that $M \succ M$ " and $M' \succ M$ ". $M^{\downarrow} \succ M$ ".

Lattice

A poset where each pair of elements has a join and a meet is a lattice. Hence,

Corollary

The stable matching poset (S,\succeq) , equipped with \vee and \wedge , becomes a lattice (S,\vee,\wedge) .

Distributive lattice

Proposition

The stable matching lattice (S, \vee, \wedge) is **distributive**, i.e.,

$$(M \vee M') \wedge M'' = (M \wedge M'') \vee (M' \wedge M'')$$

$$(M \wedge M') \vee M'' = (M \vee M'') \wedge (M' \vee M'')$$

Representation theorem

(Finite) distributive lattice has a nice property.

Theorem (Birkhoff's representation theorem, 1937)

For any finite distributive lattice $(\mathcal{L}, \vee, \wedge)$, there exists

- ▶ a poset (P, \succeq^*) called the **representation poset** of \mathcal{L} ,
- \blacktriangleright a bijection between $\mathcal L$ and the upper closed subsets of $(\mathcal P,\succeq^*)$.

Representation theorem

Definition

A subset $Q \subseteq \mathcal{P}$ is an **upper closed subset** of (\mathcal{P},\succeq^*) , if

$$q \in Q, \ q' \succeq^* q \implies q' \in Q.$$

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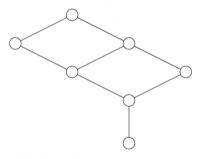
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Remark. Usually $|\mathcal{P}| \ll |\mathcal{L}|$.

Example



(a) Hasse Diagram of the Lattice



(b) Representation Poset

Representation of stable matching lattice

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Now, apply the Birkhoff's representation theorem to the stable matching lattice:

Representation of stable matching lattice

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Now, apply the Birkhoff's representation theorem to the stable matching lattice:

The representation poset of stable matching lattice is called **rotation poset**, denoted as (\mathcal{R},\succeq^*) , whose element is called **rotation**, denoted as ρ .

Rotation poset

- ▶ A rotation $\rho \in \mathcal{R}$ can transform a stable matching M to another stable matching M/ρ , called **elimination of** ρ **from** M. Rotation can help us traverse in the lattice of stable matchings.
- $ightharpoonup |\mathcal{R}| = O(n^2).$

Rotation poset

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- $\blacktriangleright |\mathcal{R}| = O(n^2).$

What is a rotation exactly?

Relation between polytope and lattice

Definition (Order polytope)

For a poset (\mathcal{P},\succeq) , define its associated **order polytope**

$$O(\mathcal{P}) := \{x \in [0,1]^{|\mathcal{P}|} : x_i \ge x_j \text{ if } i \succeq j\}.$$

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Theorem

Let $(\mathcal{M}, \vee, \wedge)$ be a stable matching lattice and let \mathcal{R} be its rotation poset (from Birkhoff's representation), then the stable matching polytope $P(\mathcal{M})$ is **affinely equivalent** to the order polytope $O(\mathcal{R})$, i.e.,

$$P(\mathcal{M}) = A \cdot O(\mathcal{R}) + x(M_0),$$

where $A \in \mathbb{R}^{|E| \times |\mathcal{R}|}$ and $x(M_0)$ is the incidence vector of the student-optimal stable matching M_0 .

For each stable matching instance,

SM lattice

rotation poset, whose order polytope $\quad \stackrel{\text{affine}}{\longleftrightarrow}$

SM polytope