

# HOR/STOA masterclass

19/7/16

1. HW 6 discussion
2. PW 7 discussion
3. Preview: SSA algorithm
4. HW 7 introduction/worktime

HW 7 discussion summary:

Sensitivity of results to parameters  
can be tested by:

- Rule N: significance of eigenvalues (HWS)
- robustness of eigenvectors to random noise (HW6)

• ~~stat~~ changing: time interval, spatial domain, observational error, ...  
→ effect on interpreted EOFs, PCs, ...  
✓

for 21/7:

HW 7

PW 8

# 

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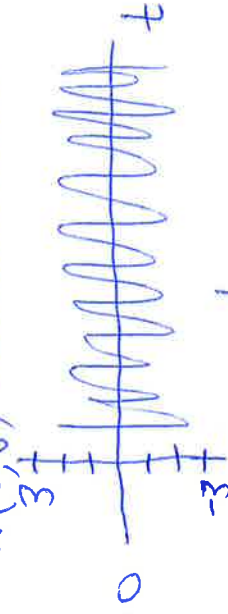
- Based on Broomhead + King (1986); Strangatz (1988); Ghil et al (2002)

Background: Given a time series of data  $T(t)$  and an embedding

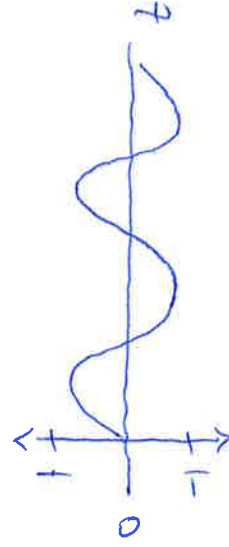
dimension  $M$ , phase spaces can be illustrated as a scatter plot

of  $T(t+1)$  vs  $T(t)$ :

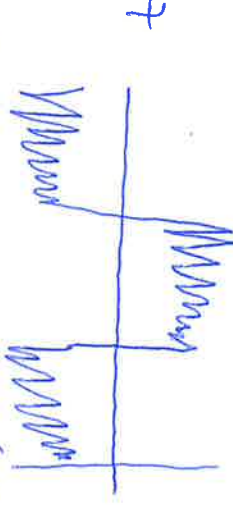
$N(0, \sigma)$ : Gaussian data



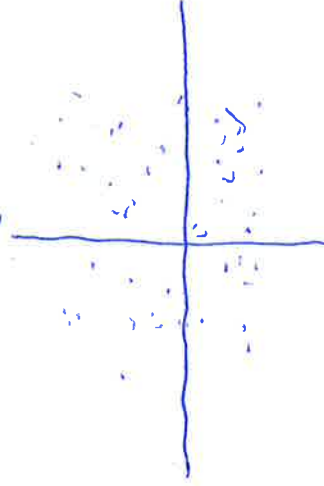
$\sin(\omega t)$



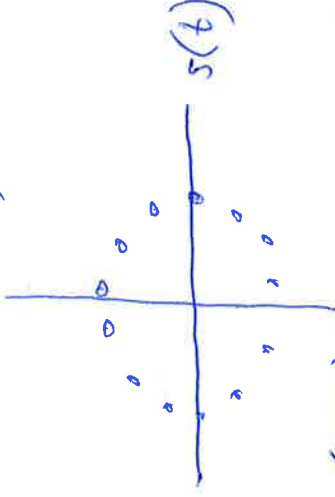
$x(t)$  Lorenz attractor (Lorenz, 1983)



$N(t+1)$

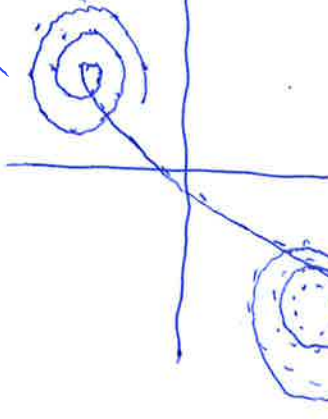


$s(t+1)$



$\downarrow$

$x(t+1)$



$x(t)$

Singular spectrum analysis (SSA) finds the patterns in the autocovariance of the time series over a given bandwidth. (embedding dimension):

- non parametric (except for  $M$ )
- data adaptive (trends, oscillations, random variations)

# HDR/masterclass SSA algorithm

1. for a time series  $x(t) = [x_1, x_2, x_3, \dots, x_n]$  with  $\bar{x} = 0$ :

2. We form a trajectory matrix for a chosen embedding dimension  $m$ :

$$X = \begin{matrix} & x_1 & x_2 & x_3 & \dots & x_{n+1-m} \\ \begin{matrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_m \end{matrix} & \begin{bmatrix} x_1 & x_2 & x_3 & \dots & x_{n+1-m} \\ x_2 & x_3 & x_4 & \dots & x_n \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ x_m & \dots & \dots & \dots & x_n \end{bmatrix} \end{matrix}$$

3. Form the autocovariance matrix  $R$ :

$$R = \frac{XX^T}{n-m+1}$$

(subtract mean of each row of  $X$  to give each autocovariance)

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HW7 problem 1:

1.  $x = [0, -1, 0, 1, 0]$ ,  $n=5$

2.  $m=2$ :

$$X = \begin{bmatrix} 0 & -1 & 0 & 1 \\ -1 & 0 & 1 & 0 \end{bmatrix}$$

$$R = \begin{bmatrix} 0 & -1 & 0 & 1 \\ -1 & 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & -1 \\ -1 & 0 \\ 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$= \frac{1}{4} \begin{bmatrix} 0 \cdot 0 + (-1) \cdot (-1) + 0 \cdot 0 + 1 \cdot 1 & 0 \cdot (-1) + (-1) \cdot 0 + 0 \cdot 1 + 1 \cdot 0 \\ -1 \cdot 0 + 0 \cdot (-1) + 1 \cdot 0 + 0 \cdot 1 & -1 \cdot (-1) + 0 \cdot 0 + 1 \cdot 1 + 0 \cdot 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$



Problem 1 HW7

4. The eigenvector problem is:  $EA = RA$

- characteristic equation  $f(\lambda) = 0$
- eigenvalue determination.
- eigenvector determination:
- principal components:

$$A = E^T X$$

$$\begin{vmatrix} \frac{1}{2} - \lambda & 0 \\ 0 & \frac{1}{2} - \lambda \end{vmatrix} = 0$$

$$\left(\frac{1}{2} - \lambda\right)\left(\frac{1}{2} - \lambda\right) = 0$$

$$\lambda = \frac{1}{2}, \frac{1}{2}$$

$$\text{for } RE = \lambda E$$

$$\begin{bmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{2} \end{bmatrix} \begin{bmatrix} e_{11} & e_{12} \\ e_{21} & e_{22} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{2} \end{bmatrix} \begin{bmatrix} e_{11} & e_{12} \\ e_{21} & e_{22} \end{bmatrix}$$

$$\rightarrow E = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$A = E^T X = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & -1 & 0 & 1 \\ -1 & 0 & 1 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 \cdot 0 + 0 \cdot -1 & 1 \cdot -1 + 0 \cdot 1 & 0 \cdot 0 + 1 \cdot 1 & 0 \cdot 1 + 1 \cdot 0 \\ -1 \cdot 1 + 0 \cdot 0 & -1 \cdot -1 + 0 \cdot 1 & 0 \cdot -1 + 1 \cdot 0 & 0 \cdot 0 + 1 \cdot 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & -1 & 1 & 0 \\ -1 & 1 & 0 & 1 \end{bmatrix}$$

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# HW7/STVA masterclass SSA algorithm

5. Reconstructed components are formed by convolution of principal components with eigenvectors:  $q = a * e$

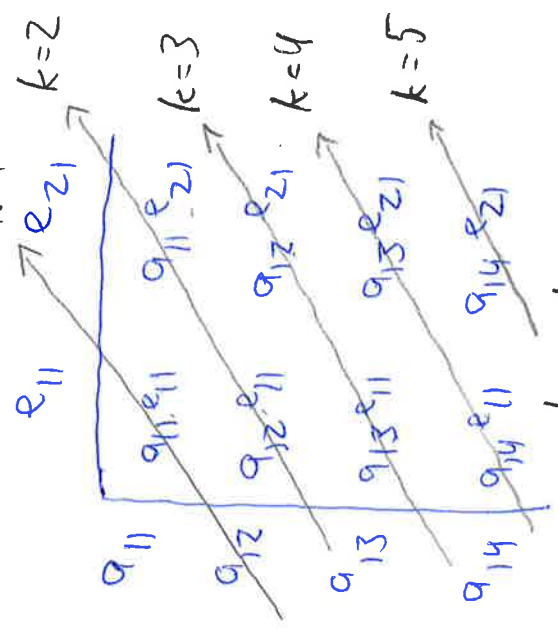
The convolution can be written as the sum of the inverse diagonals of a matrix formed as the products of

$a$  and  $e$ :

for example:  $a = \begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} \end{bmatrix}$   
 $e = \begin{bmatrix} e_{11} & e_{21} \end{bmatrix}$

HW7 problem 1:

$q_1 =$



$q_1 =$

$$\begin{bmatrix} 0.1 & 0.0 & 0.0 & 0.0 \\ -1.1 & -1.0 & 0.0 & 0.0 \\ 0.1 & 0.0 & 0.0 & 0.0 \\ 1.1 & 1.0 & 0.0 & 0.0 \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ k_3 \\ k_4 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 0 \\ 0 \end{bmatrix}^T$$

$q_2 =$

# HDR/STDA masterclass

SSA algorithm

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The RC's are scaled (Ghah et al 2002):

for column in  $Q: 1, 2, 3, \dots, t, \dots, n$ :

$$1 \leq t \leq m-1: \quad q_t/t$$

$$m \leq t \leq n-m+1: \quad q_t/m$$

$$n-m+2 \leq t \leq n: \quad q_t/(n-t+1).$$

$$Q = \begin{bmatrix} 0 & -1 & 0 & 1 & 0 \\ 0 & -1 & 0 & 1 & 0 \end{bmatrix}$$

scalings for  $m=2$ :

$$k=1 \quad q = q/1$$

$$k=2, 3, 4 \quad q = q/2$$

$$k=5 \quad q = q/1.$$

scaled  $Q$ :

$$\begin{bmatrix} 0/1 & -1/2 & 0/2 & 1/2 & 0/1 \\ 0/1 & -1/2 & 0/2 & 1/2 & 0/1 \end{bmatrix}$$

$$x = \begin{bmatrix} 0 & -1 & 0 & 1 & 0 \end{bmatrix},$$

6. Reconstitution of  $x$ :

$$x = \sum_{i=1}^m q_i$$