

Submodular Maximization

advances in distributed/streaming computing

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Overview

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 - Definitions
 - Properties
 - Constraints
 - Algorithms
- 2 Applications
- 3 Streaming Submodular Maximization
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Definitions of Submodularity

Definition (submodular concave)

A function $f : 2^V \rightarrow \mathbb{R}$ is **submodular** if for any $A, B \subseteq V$, we have that:

$$f(A) + f(B) \geq f(A \cup B) + f(A \cap B). \quad (1)$$

An alternate equivalent definition is more interpretable in many situations.

Definition (diminishing returns)

A function $f : 2^V \rightarrow \mathbb{R}$ is **submodular** if for any $A \subseteq B \subset V$, and $v \in V \setminus B$, we have that:

$$f(A + v) - f(A) \geq f(B + v) - f(B). \quad (2)$$

Modular Functions

Definition (Modularity)

A function $f : 2^V \rightarrow \mathbb{R}$ is **modular** if for any $A \subseteq B \subset V$, and $v \in V \setminus B$, we have that:

$$f(A + v) - f(A) = f(B + v) - f(B). \quad (3)$$

Notably, a modular function f can always be written as

$$f(S) = f(\emptyset) + \sum_{v \in S} (f(\{v\}) - f(\emptyset))$$

for any $S \subseteq V$. If we further assume $f(\emptyset) = 0$ (in this case, we call f **normalized** or **proper**), we have a simplified expression,

$$f(S) = \sum_{v \in S} f(\{v\}).$$

Monotonicity

Definition (Monotonicity)

A set function $f : 2^V \rightarrow \mathbb{R}$ is said to be non-decreasing if for any $A \subseteq B \subseteq V$, $f(A) \leq f(B)$. Non-increasing set functions are defined in the similar way.

When we say a submodular function is monotone, we mean it is non-decreasing.

Properties

Submodularity is closed under addition.

Property

Let $f_1, f_2 : 2^V \rightarrow \mathbb{R}$ be two submodular functions. Then

$$f : 2^V \rightarrow \mathbb{R} \text{ with } f(A) = \alpha f_1(A) + \beta f_2(A)$$

is submodular for any fixed $\alpha, \beta \in \mathbb{R}^+$.

Submodularity is preserved under restriction.

Property

Let $f : 2^V \rightarrow \mathbb{R}$ be a submodular function. Let $S \subseteq V$ be a fixed set. Then

$$f' : 2^V \rightarrow \mathbb{R} \text{ with } f'(A) = f(A \cap S)$$

is submodular.

Properties cont.

The following property can be useful when we show that the negative of the objective function of k-median problem is submodular.

Property

Consider V as a set of indices. Let $\mathbf{c} \in \mathbb{R}^V$ be a fixed vector, c_i its i th coordinate. Then

$$f : 2^V \rightarrow \mathbb{R} \text{ with } f(A) = \max_{j \in A} c_j$$

is submodular.

Constraints

Submodular Maximization Problem

A submodular maximization problem usually has the following form:

$$\arg \max_{I \in \mathcal{I}} f(I), \quad (4)$$

where f is a submodular function and $\mathcal{I} \subseteq 2^V$ is the collection of all feasible solutions. We call \mathcal{I} the **constraint** of the optimization problem.

Constraints

\mathcal{I} is important!

The structure of \mathcal{I} plays a crucial role in submodular optimization:

- Different constraints have different hardness results.
- Normally the difficulty increases when the constraint becomes more general.

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Popular constraints

Some popular constraints:

- Cardinality constraint
- Knapsack constraint
- Matroid constraint
- Matching
- p -System
- ...

Constraints cont.

First we define hereditary set systems.

Definition (Hereditary)

A constraint $\mathcal{I} \subseteq 2^V$ is said to be **hereditary** if

$$I \in \mathcal{I} \implies J \in \mathcal{I} \text{ for any } J \subseteq I.$$

A hereditary constraint is sometimes called an **independent system** and each $I \in \mathcal{I}$ is called an **independent set**.

All constraints we will discuss are hereditary.

Constraints cont.

Cardinality

Cardinality constraint: $\mathcal{I} = \{A \subseteq V \mid |A| \leq k\}$

Knapsack

Knapsack Constraint: each $i \in V$ is assigned a weight $w_i \geq 0$,
 $\mathcal{I} = \{S \subseteq V \mid \sum_{i \in S} w_i \leq W\}.$

Constraints cont.

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Matching

Matching: given a graph $G = (V, E)$, a *Matching* is a set $S \subseteq E$ such that no edges in S share common vertex.

Matroid

Matroid is the generalization of the independence concept in linear algebra; omit details here ...

p -System

p -system is very general, it includes many other constraints as special cases.

Definition of p -System

Let (V, \mathcal{I}) be a set system and \mathcal{I} hereditary. Let $\mathcal{B}(A)$ be the collection of all bases of A .

$$\mathcal{I} = \{A \subseteq V \mid \frac{\max_{S \in \mathcal{B}(A)} |S|}{\min_{S \in \mathcal{B}(A)} |S|} \leq p\}.$$

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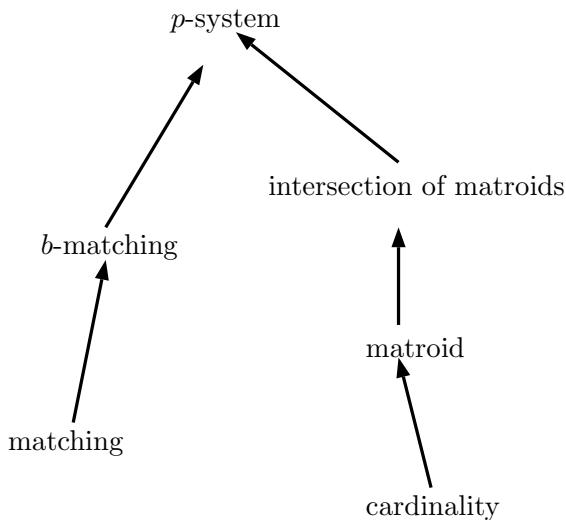
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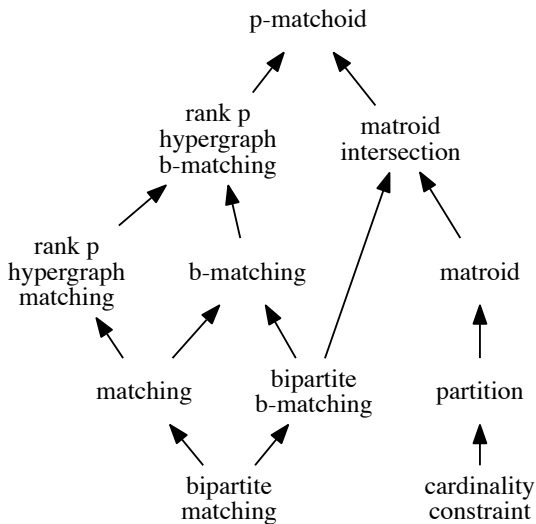
examples of p -system

- matroid is 1-system
- matching is 2-system
- intersection of p matroid is p -system
- ...

Hierarchy of constraints



Hierarchy of constraints (extended)



Notations

Some notations

- $\Delta_f(e|S) = f(S + e) - f(S)$ (or simply $\Delta(e|S)$ when f is clear from context)
- **α -approximation**: the returned solution S always satisfies $f(S) \geq \alpha \cdot \arg \max_{I \in \mathcal{I}} f(I)$
- When the algorithm is randomized, we normally say it guarantees **α -approximation in expectation** if

$$\mathbf{E}[f(S)] \geq \alpha \cdot \arg \max_{I \in \mathcal{I}} f(I).$$

The standard greedy algorithm

Algorithm 1: GREEDY algorithm for submodular maximization

Input: V the ground set, f the submodular function, \mathcal{I} the constraint

Output: a set $S \subseteq V$

```
1  $S \leftarrow \emptyset$ 
2 while  $\exists e \in V \setminus S$  s.t.  $S \cup \{e\} \in \mathcal{I}$  do
3    $e \leftarrow \arg \max_{e \in V \setminus S, S \cup \{e\} \in \mathcal{I}} \Delta_f(e|S)$ 
4    $S \leftarrow S \cup \{e\}$ 
5 return  $S$ 
```

Theorems of Algorithm 1

Theorem ([5], for cardinality constraint)

For a non-negative *monotone submodular* function $f : 2^V \rightarrow \mathbb{R}$, let \mathcal{I} be the *cardinality constraint*, Algorithm 1 returns a $(1 - 1/e)$ -approximation to $\arg \max_{I \in \mathcal{I}} f(S)$.

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Theorem ([5, 1], for p -system)

For a non-negative *monotone submodular* function f , given a p -system (V, \mathcal{I}) , Algorithm 1 returns a $\frac{1}{p+1}$ -approximation.

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Theorem ([2], modular maximization s.t. p -system)

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Speedup - GREEDYLAZY

GreedyLazy

- Minoux [3] proposed LAZY-GREEDY as a fast implementation for Algorithm 1.

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- In each step, only update the top element in the heap and push it back, if this element remains in the top, include it into solution.

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- GREEDYLAZY keeps an upper bound $\rho(e)$ on the marginal gain sorted in a heap.
- In each step, only update the top element in the heap and push it back, if this element remains in the top, include it into solution.
- Again gives $(1 - e^{-1})$ -approximation.

Speedup - STOCGREEDY[4]

StocGreedy

- In each round, instead of considering all $V \setminus S$ to get

$$e \leftarrow \arg \max_{e \in V \setminus S, S \cup \{e\} \in \mathcal{I}} \Delta_f(e|S),$$

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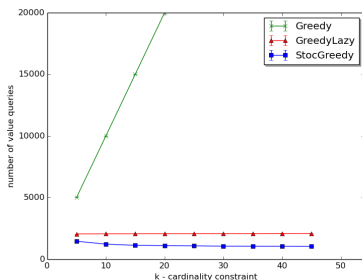
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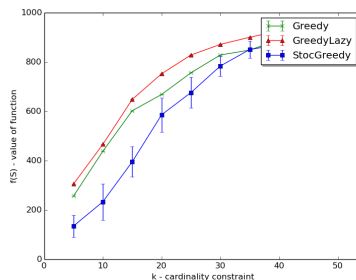
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- consider only $\frac{|V|}{k} \log \frac{1}{\epsilon}$ random samples from $V \setminus S$.
- $(1 - e^{-1} - \epsilon)$ -approximation in expectation.

Comparison



(a) Efficiency



(b) Quality

Figure : Experiment on SYNTHETIC dataset

Multiple Columns

Heading

- ① Statement
- ② Explanation
- ③ Example

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consectetur adipiscing elit.
Integer lectus nisl, ultricies in
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Sed volutpat ante purus, quis
accumsan dolor.

Table

Treatments	Response 1	Response 2
Treatment 1	0.0003262	0.562
Treatment 2	0.0015681	0.910
Treatment 3	0.0009271	0.296

Table : Table caption

Theorem

Theorem (Mass–energy equivalence)

$$E = mc^2$$

Figure

Uncomment the code on this slide to include your own image from the same directory as the template .TeX file.

Citation

An example of the `\cite` command to cite within the presentation:

This statement requires citation [Smith, 2012].

References



John Smith (2012)

Title of the publication

Journal Name 12(3), 45 – 678.

The End



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