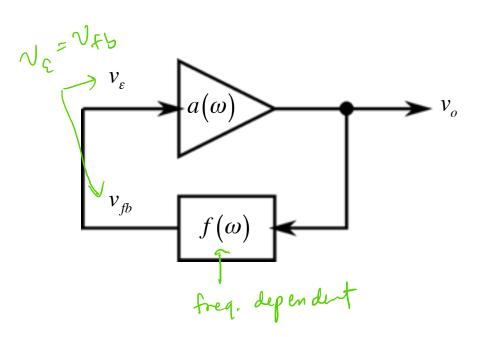


EEE 51: Second Semester 2017 - 2018 Lecture 23

Oscillators

(Positive Feedback)

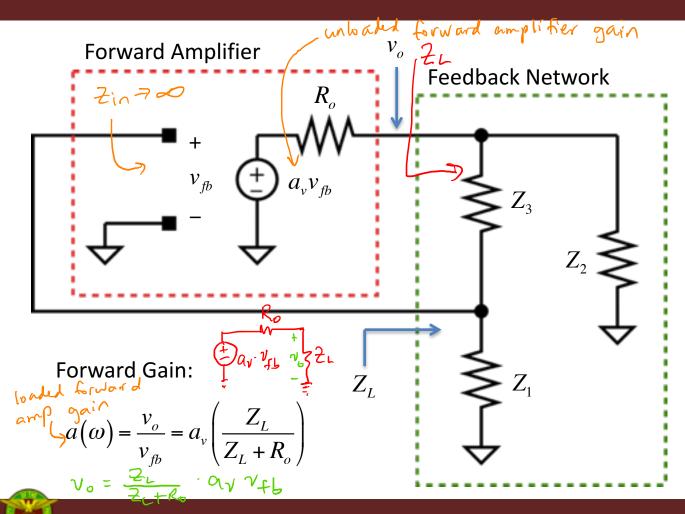


$$A_{CL}(s) = \frac{a(s)}{1 - T(s)}$$

$$a(\omega) = \frac{v_o}{v_\varepsilon} = \frac{v_o}{v_{fb}}$$

$$f(\omega) = \frac{v_{eb}}{v_o} \qquad \Rightarrow \quad a(\omega) = \frac{1}{f(\omega)}$$

Barkhausen Criteria:



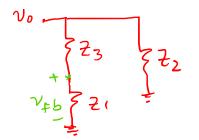
Barkhausen Criteria:

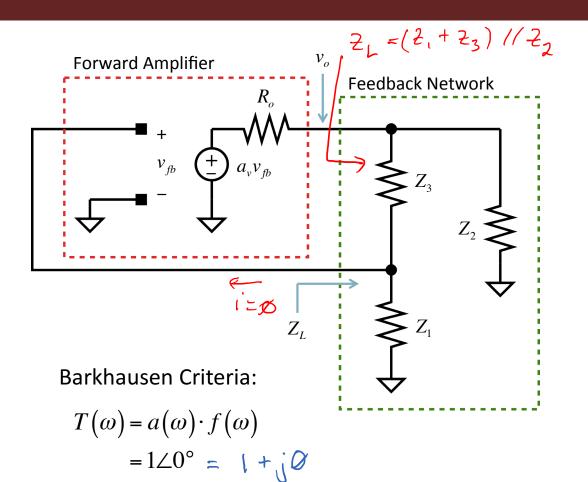
$$T(\omega) = a(\omega) \cdot f(\omega)$$
$$= 1 \angle 0^{\circ}$$

$$v_{pb} = \frac{2}{2} \cdot v_0$$

Feedback Factor:

$$f(\omega) = \frac{v_{fb}}{v_o} = \frac{Z_1}{Z_1 + Z_3}$$





$$a(\omega) = a_{v} \left(\frac{Z_{L}}{Z_{L} + R_{o}} \right)$$

$$f(\omega) = \frac{Z_1}{Z_1 + Z_3}$$

Loop Gain:

$$T(\omega) = a(\omega) \cdot f(\omega)$$

$$= a_{v} \frac{Z_{L}}{Z_{L} + R_{o}} \frac{Z_{1}}{Z_{1} + Z_{3}}$$

$$Z_{L} = Z_{2} \parallel (Z_{1} + Z_{3})$$

$$= \frac{Z_{2}(Z_{1} + Z_{3})}{Z_{1} + Z_{2} + Z_{3}}$$



Loop Gain:
$$T(\omega) = a(\omega) \cdot f(\omega)$$

$$= a_{v} \cdot \frac{Z_{L}}{Z_{L} + R_{o}} \cdot \frac{Z_{1}}{Z_{1} + Z_{3}}$$

$$= a_{v} \cdot \frac{\frac{Z_{2}(Z_{1} + Z_{3})}{Z_{1} + Z_{2} + Z_{3}}}{\frac{Z_{2}(Z_{1} + Z_{3})}{Z_{1} + Z_{2} + Z_{3}}} \cdot \frac{Z_{1}}{Z_{1} + Z_{3}} = a_{v} \cdot \frac{Z_{2}Z_{1}}{Z_{2}(Z_{1} + Z_{3}) + R_{o}(Z_{1} + Z_{2} + Z_{3})}$$

Barkhausen Criteria:

$$T(\omega) = a(\omega) \cdot f(\omega)$$

$$= a_{v} \cdot \frac{Z_{2}Z_{1}}{Z_{2}(Z_{1} + Z_{3}) + R_{o}(Z_{1} + Z_{2} + Z_{3})} = 1 \angle 0^{\circ}$$



Barkhausen Criteria:
$$T(\omega) = a(\omega) \cdot f(\omega)$$

$$= a_v \cdot \frac{Z_2 Z_1}{Z_2 (Z_1 + Z_3) + R_o (Z_1 + Z_2 + Z_3)} = 1 \angle 0^\circ$$

If we assume that Z_1 , Z_2 and Z_3 are purely reactive elements: $\begin{cases} Z_1 = jX_1 & Z_1 = \mathcal{R}_1 + \mathcal{I}_1 \\ Z_2 = jX_2 & Z_3 = \mathcal{R}_2 + \mathcal{I}_3 \\ Z_3 = jX_3 & Z_3 = \mathcal{R}_3 + \mathcal{I}_3 \end{cases}$

$$T(\omega) = a_{v} \cdot \frac{Z_{2}Z_{1}}{Z_{2}(Z_{1} + Z_{3}) + R_{o}(Z_{1} + Z_{2} + Z_{3})} = a_{v} \cdot \frac{jX_{2} \cdot jX_{1}}{jX_{2}(jX_{1} + jX_{3}) + R_{o}(jX_{1} + jX_{2} + jX_{3})}$$

$$= a_{v} \cdot \frac{-X_{2} \cdot X_{1}}{-X_{2}(X_{1} + X_{3}) + jR_{o}(X_{1} + X_{2} + X_{3})}$$

Loop Gain:
$$T(\omega) = a_v \cdot \frac{-X_2 \cdot X_1}{-X_2(X_1 + X_3) + jR_o(X_1 + X_2 + X_3)}$$

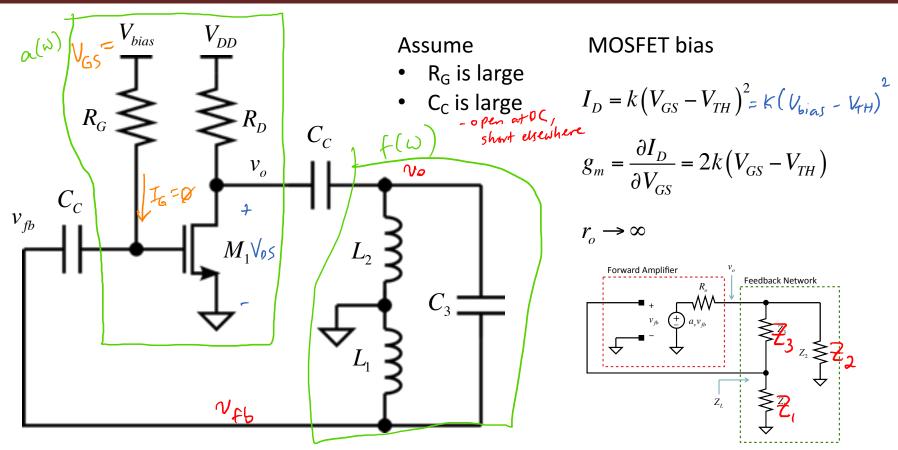
For oscillations to occur:
$$\operatorname{Im} \{T(\omega)\} = 0 \implies X_1 + X_2 + X_3 = 0$$

$$X_1 + X_3 = -X_2$$

Thus:
$$T(\omega_0) = a_v \cdot \frac{+X_2 \cdot X_1}{+X_2(X_1 + X_3)} = a_v \cdot \frac{X_1}{(X_1 + X_3)} = -a_v \cdot \frac{X_1}{X_2} = 1 \angle 0^\circ$$

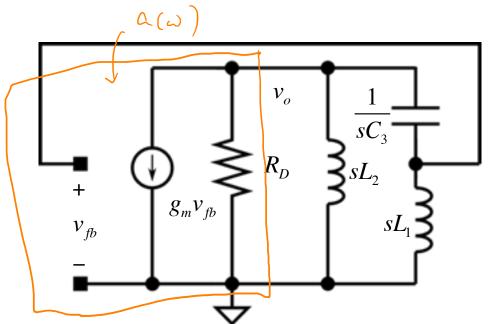
Case 1: $a_v > 0 \rightarrow X_1$ and X_2 must have different signs

Case 2: $a_v < 0 \rightarrow X_1$ and X_2 must have the same sign



Named after Ralph Vinton Lyon Hartley (November 30, 1888 – May 1, 1970)

Small-signal model:



$$X_1 = \omega L_1$$

$$X_2 = \omega L_2$$

$$X_1 = \omega L_1 \qquad X_2 = \omega L_2 \qquad X_3 = -\frac{1}{\omega C_3}$$

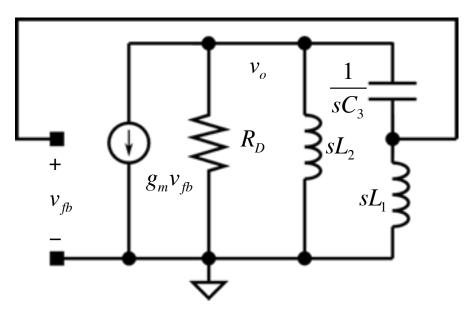
Forward unloaded amplifier:

$$a_v = -g_m R_D$$

$$R_o = R_D = R_0 //r_b$$
 if r_o is finite.

Note: X₁ and X₂ must have the same sign Since ar 40

Small-signal model:



$$a_{v} = -g_{m}R_{D} \qquad X_{2} = \omega L_{2}$$

$$R_{o} = R_{D} \qquad X_{1} = \omega L_{1}$$

$$X_{3} = -\frac{1}{\omega C_{3}}$$

Recall:

$$T(\omega) = a_{v} \cdot \frac{-X_{2} \cdot X_{1}}{-X_{2}(X_{1} + X_{3}) + jR_{o}(X_{1} + X_{2} + X_{3})}$$

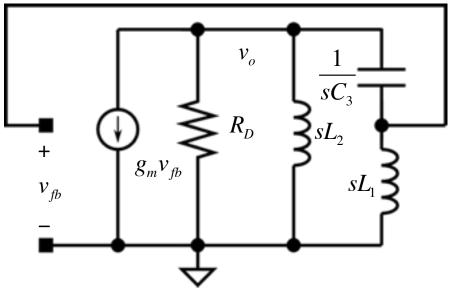
To oscillate:

$$\underbrace{X_1 + X_2 + X_3 = 0}_{\text{WL}_1 + \text{WL}_2 - \text{U}} \Rightarrow \omega_0 (L_1 + L_2) = \frac{1}{\omega_0 C_3}$$

Thus,

$$\omega_0 = \frac{1}{\sqrt{\left(L_1 + L_2\right)C_3}}$$

Frequency of oscillation:
$$\omega_0 = \frac{1}{\sqrt{(L_1 + L_2)C_3}}$$



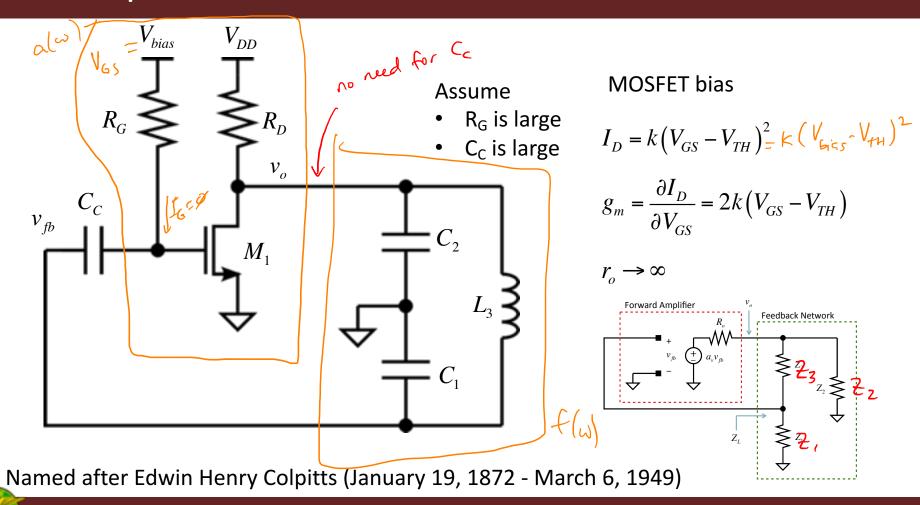
$$a_v = -g_m R_D \qquad X_2 = \omega L_2$$

$$R_o = R_D \qquad X_1 = \omega L_1 \qquad X_3 = -\frac{1}{\omega C_3}$$

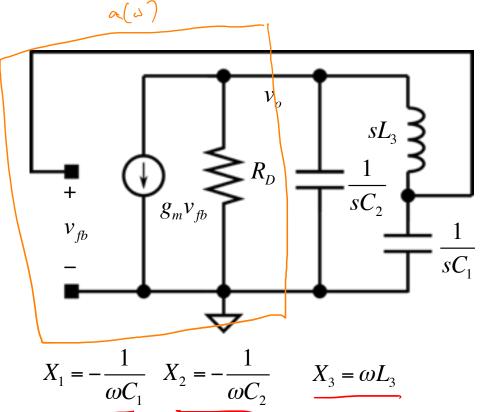
Loop Gain:
$$T(\omega_0) = \boxed{-a_v \cdot \frac{X_1}{X_2} = 1 \angle 0^\circ}$$
$$= g_m R_D \frac{L_1}{L_2} = 1 \angle 0^\circ$$

For
$$L_1 = L_2$$
: $g_m R_D = 1$

if $g_m R_0 = 10$
 $L_2 = 10.L_1$



Small-signal model:



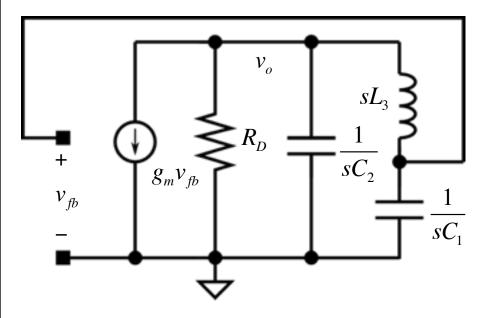
Forward unloaded amplifier:

$$a_v = -g_m R_D$$

$$R_o = R_D$$

Note: X_1 and X_2 must have the same sign $S_1 \cap L_2 \cap S_2 \subset S_2 \cap S_3 \cap L_4 \cap S_4 \cap$

Small-signal model:



$$a_{v} = -g_{m}R_{D} \qquad X_{1} = -\frac{1}{\omega C_{1}} \qquad X_{2} = -\frac{1}{\omega C_{2}}$$

$$R_{o} = R_{D} \qquad X_{3} = \omega L_{3}$$

Recall:

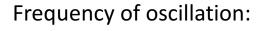
$$T(\omega) = a_{v} \cdot \frac{-X_{2} \cdot X_{1}}{-X_{2}(X_{1} + X_{3}) + jR_{o}(X_{1} + X_{2} + X_{3})}$$

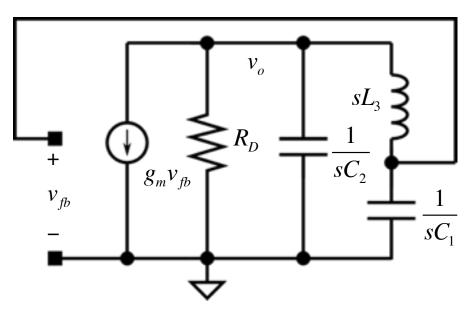
To oscillate:

$$\underbrace{X_1 + X_2 + X_3 = 0}_{} \implies \omega_0 L_3 = \frac{1}{\omega_0} \left(\frac{1}{C_1} + \frac{1}{C_2} \right)$$

Thus,
$$\omega_0 = \frac{1}{\sqrt{L_3 \cdot \frac{1}{C_1} + \frac{1}{C_2}}}$$

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$$a_{v} = -g_{m}R_{D} \qquad X_{1} = -\frac{1}{\omega C_{1}} \qquad X_{2} = -\frac{1}{\omega C_{2}}$$

$$R_{o} = R_{D} \qquad X_{3} = \omega L_{3}$$

$$\omega_0 = \frac{1}{\sqrt{L_3 \cdot \frac{C_1 C_2}{C_1 + C_2}}}$$

Loop Gain:

$$T(\omega_0) = -a_v \cdot \frac{X_1}{X_2} = 1 \angle 0^\circ$$

$$= g_m R_D \frac{C_2}{C_1} = 1 \angle 0^\circ$$

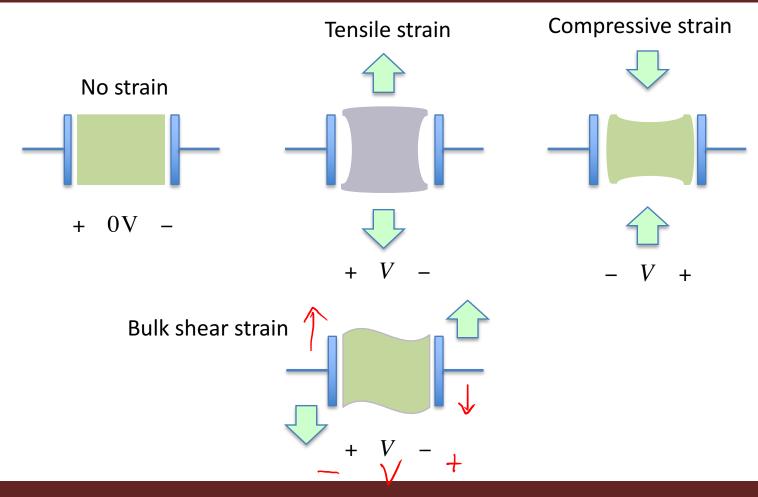
For
$$C_1 = C_2$$
: $g_m R_D = 1$

if $g_m R_D = 10$; $\frac{C_2}{C_1} = \frac{1}{10}$ or $C_1 = 10 \cdot C_2$

Crystal Oscillators

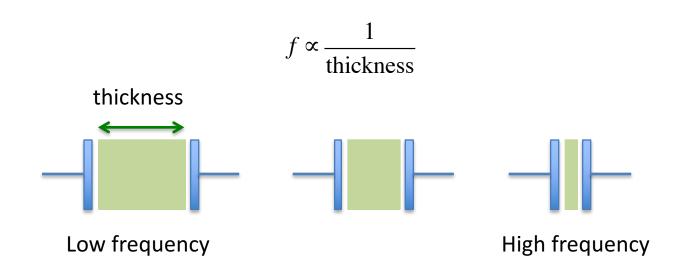
- Crystals are materials that exhibits the piezoelectric effect
 - When stress is applied, voltage is generated between opposite faces of the crystal
 - When a voltage is applied, the crystal deforms at the frequency of the applied voltage
- Mechanical to electrical energy conversion
- Provides stable frequency of oscillation
 - Resonant frequency dependent on physical crystal size
 - 1 ppm/°C or 0.0001%/°C
 - Compare with LC oscillator: ~1% drift

Crystal Strain



Natural Crystal Frequency

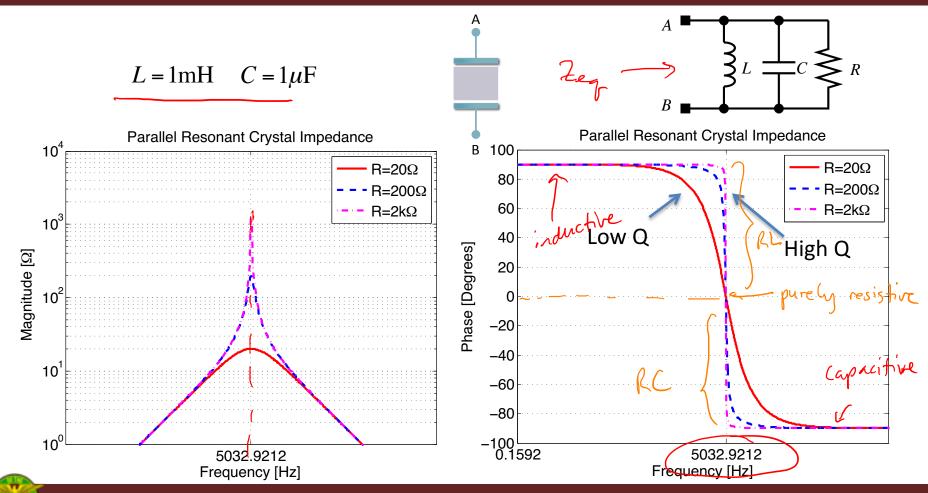
Proportional to crystal thickness



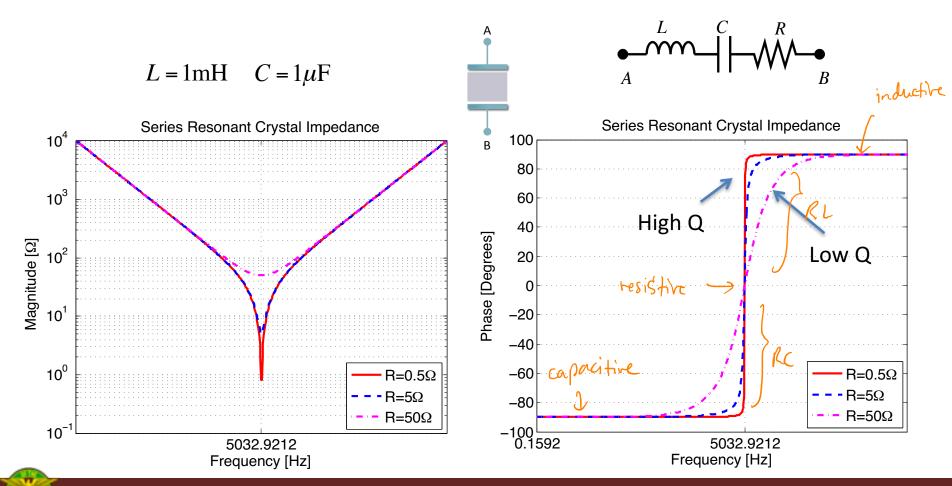
Typical natural frequencies below 20-30 MHz

For 100 MHz, thickness ~ 17μm thick

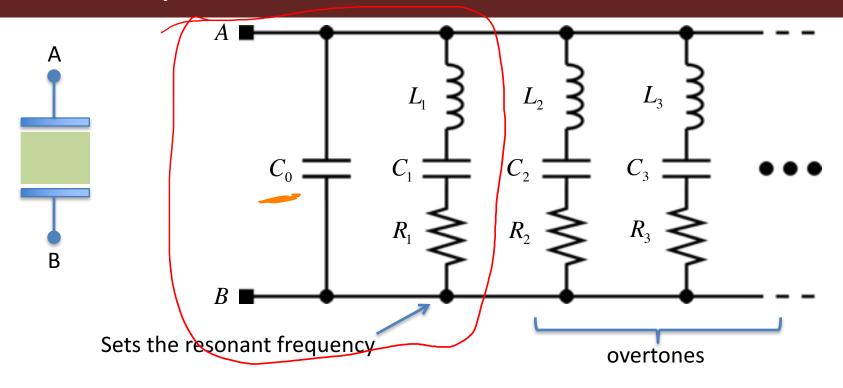
The Parallel Resonant Mode



The Series Resonant Mode



Electrical Equivalent Circuit



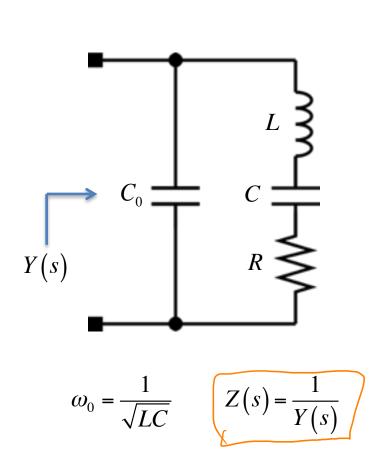
 C_0 = parallel capacitances due to contacts and wires

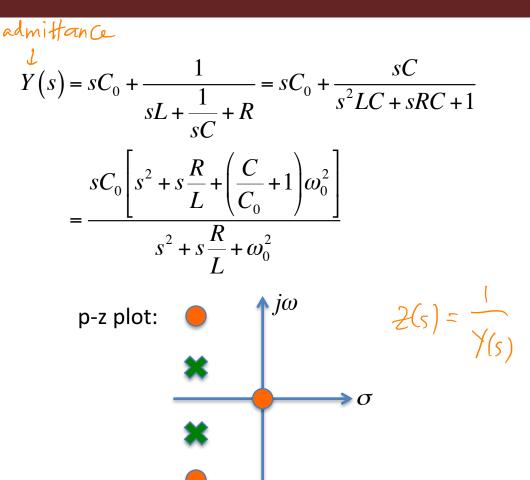
 $L_i, C_i =$ mechanical energy storage (mass & spring effects)

 $R_i =$ electrical losses due to mechanical effects (e.g. friction)

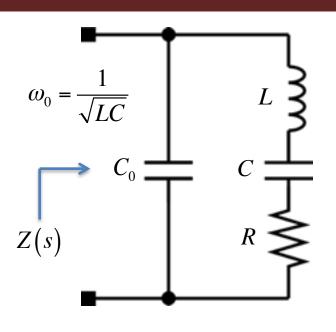


Crystal Equivalent Circuit

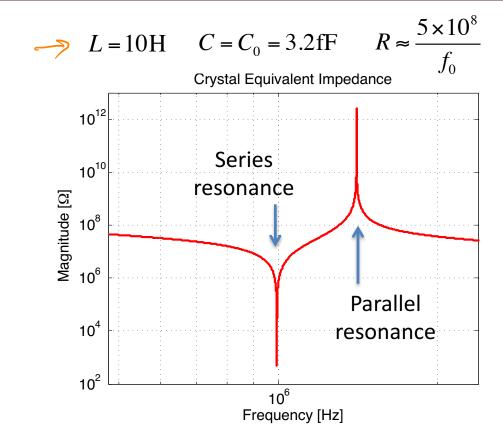




Crystal Equivalent Circuit



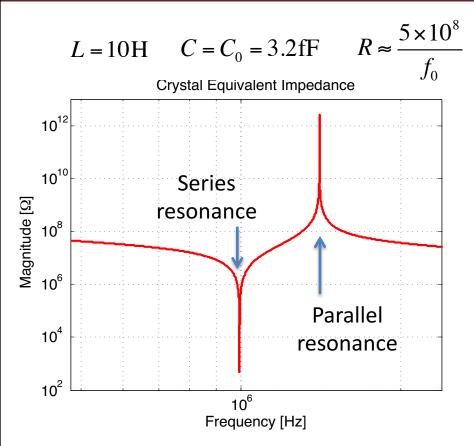
$$Z(s) = \frac{s^{2} + s\frac{R}{L} + \omega_{0}^{2}}{sC_{0} \left[s^{2} + s\frac{R}{L} + \left(\frac{C}{C_{0}} + 1 \right) \omega_{0}^{2} \right]}$$

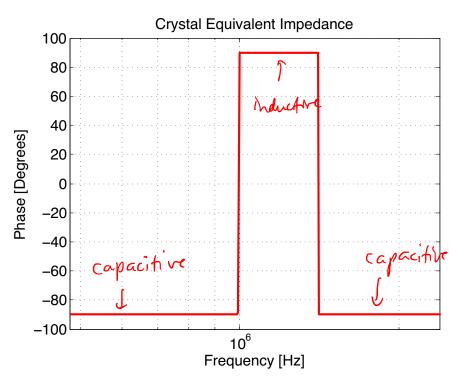


How can we use this to create an oscillator?



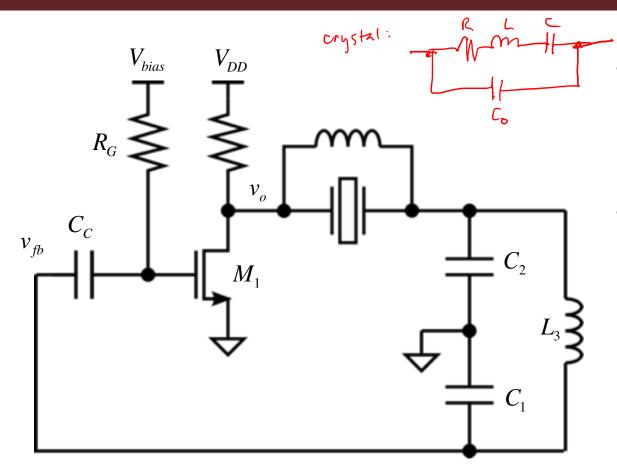
Crystal Equivalent Circuit





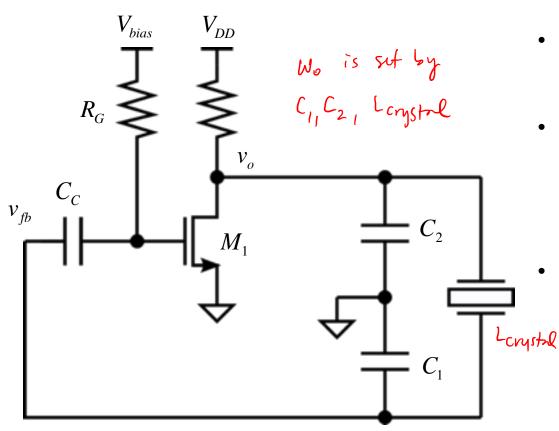
How can we use this to create an oscillator?

Direct Application: A Colpitts Crystal Oscillator



- The crystal is used to close the feedback loop only at the desired frequency
- The parallel inductance is used to cancel out the crystal parallel capacitance C₀
 - Only the series RLC branch controls the feedback path

Another Colpitts Crystal Oscillator



- The crystal is used as an inductance
- The oscillation frequency is set to be a little above series resonance
 - The crystal impedance is inductive
 - Note that the crystal series resonant frequency is not the same as the output oscillation frequency
 - Crystal is cut to oscillate at a specified load capacitance

Frequency Bands

Frequency Range	Designation	Wavelength	
3 kHz – 30 kHz	VLF	100 km – 10 km	Phase shift
30 kHz – 300 kHz	LF	10 km – 1 km	
300 kHz – 3 MHz	MF	1 km – 100 m	LC
3 MHz – 30 MHz	HF	100 m – 10 m	Crystal <
30 MHz – 300 MHz	VHF	10 m – 1 m	LC, ring oscillators, SAW, MEMS
300 MHz – 3 GHz	UHF	1 m – 0.1 m	
3 GHz – 30 GHz	SHF	0.1 m – 1 cm	
30 GHz – 300 GHz	EHF	1 cm – 1 mm	LC, distributed, MEMS

Next Meeting

Negative Resistance Oscillators