
Publications

- [1] **Li J**, Li S E, Duan J, et al. Relaxed policy iteration algorithm for nonlinear zero-sum games with application to H-infinity control[J]. IEEE Transactions on Automatic Control, 2024, 69(1): 426-433.
- [2] **Li J**, Nagamune R, Zhang Y, Li S E. Robust approximate dynamic programming for nonlinear systems with both model error and external disturbance[J]. IEEE Transactions on Neural Networks and Learning Systems, 2023.
- [3] Duan J*, **Li J***, Chen X, Zhao K, S. E. Li, Optimization landscape of policy gradient methods for discrete-time static output feedback[J]. IEEE Transactions on Cybernetics, 2023.
- [4] **Li J**, Wang J, Li S E, Li K. Learning optimal robust control of connected vehicles in mixed traffic flow[C]// 2023 Conference on Decision and Control (CDC). IEEE, 2023.
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- [6] **Li J**, Li S E, Tang K, et al. Reinforcement solver for H-infinity filter with bounded noise[C]//2020 15th IEEE International Conference on Signal Processing (ICSP). IEEE, 2020, 1: 62-67.
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- [13] Wang W, Zhang Y, Gao J, Jiang Y, Yang Y, Zheng Z, Zou W, **Li J**, et al. A general optimal control problem solver for industrial control applications[J]. Communications in Transportation Research, 2023, 3: 100096.