



Week 7 Review



Let's test our understanding

Try these questions first:

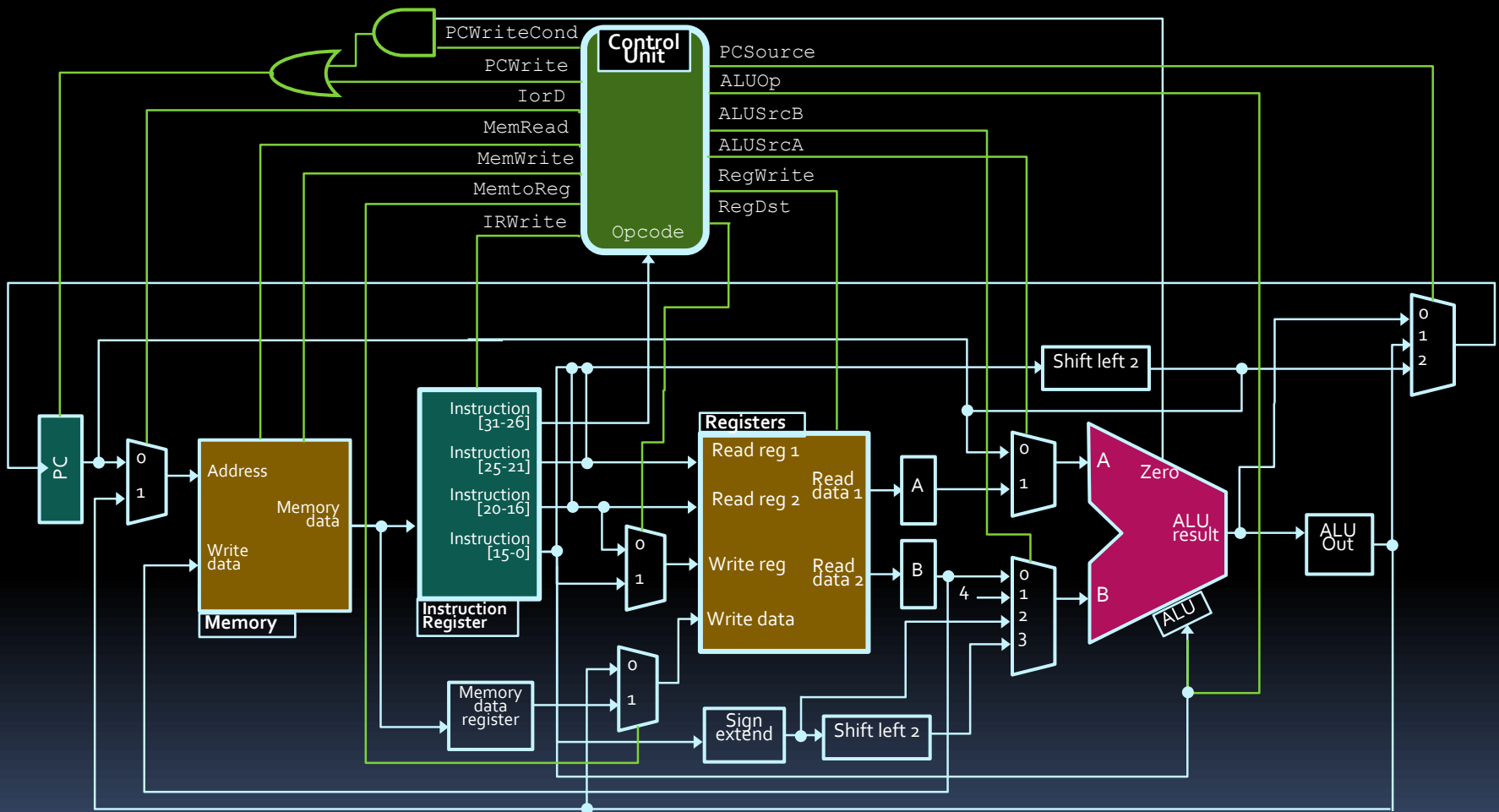
1. Where are instructions stored?
2. How long is a single instruction?
3. What is the role of the Program Counter (PC)?
4. What do we mean by “instruction fetch”?
5. Where does the processor keep the instruction that is currently being executed?

Let's test our understanding

1. Where are instructions stored?
 - In memory, along with the input data values
2. How long is a single instruction?
 - 4 bytes (32 bits)
3. What is the role of the Program Counter (PC)?
 - Store the location (address) of the current instruction.
4. What do we mean by “instruction fetch”?
 - Retrieve an instruction from memory.
5. Where does the processor keep the instruction that is currently being executed?
 - In the Instruction Register.

Storage

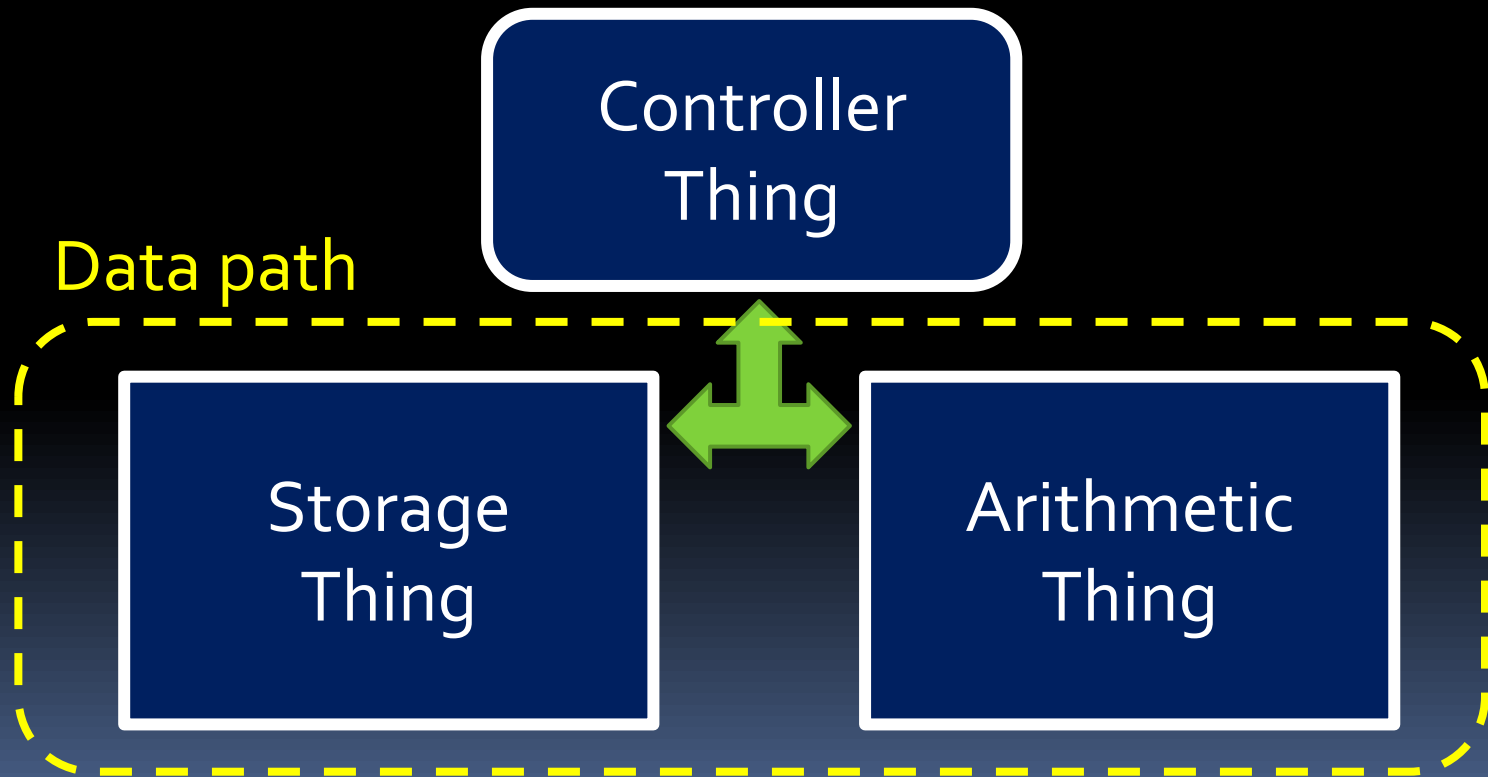
- **Register file**: small and fast
 - Used as temporary / scratch space for computations.
- **Memory**: large but slower
 - Stores program instructions and data
- Single registers like **PC** and **instruction register**
 - Used for controlling the execution process
- Datapath connects these to **ALU**.
- **Control unit** controls the data path.



Question

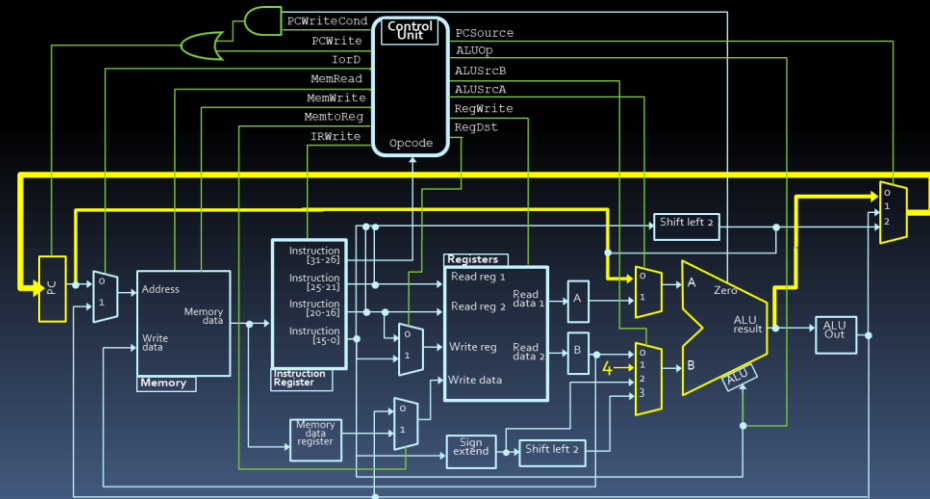
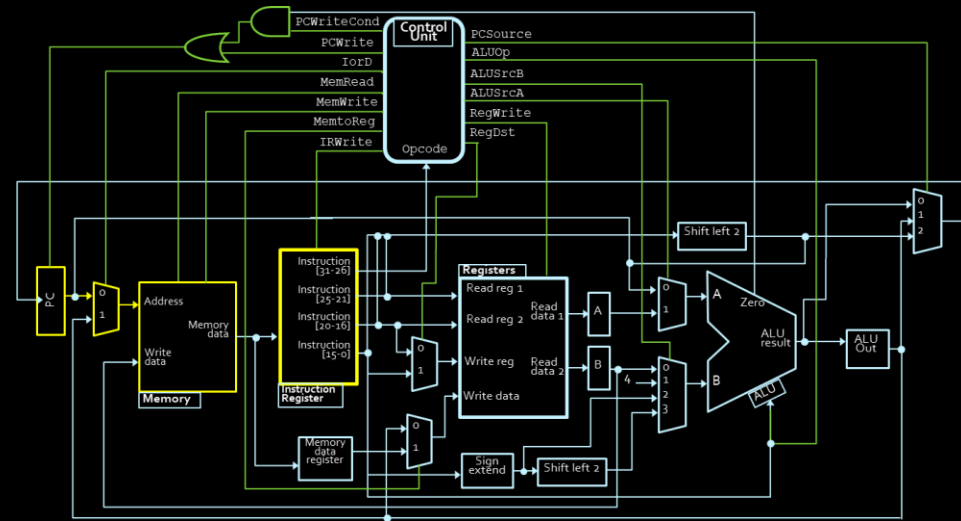
- Your RAM unit has 6 address bits going into it. Given a 32-bit architecture, how many integers (words) is your RAM unit able to store?
- Be careful here!
 - 6 address bits $\rightarrow 2^6$ memory slots = 64 bytes.
 - 32-bit architecture \rightarrow 4 bytes per integer.
 - RAM capacity = $64 / 4 = 16$ integers in memory.

- We learned what the Arithmetic and Storage Things do
- And we can build a data path

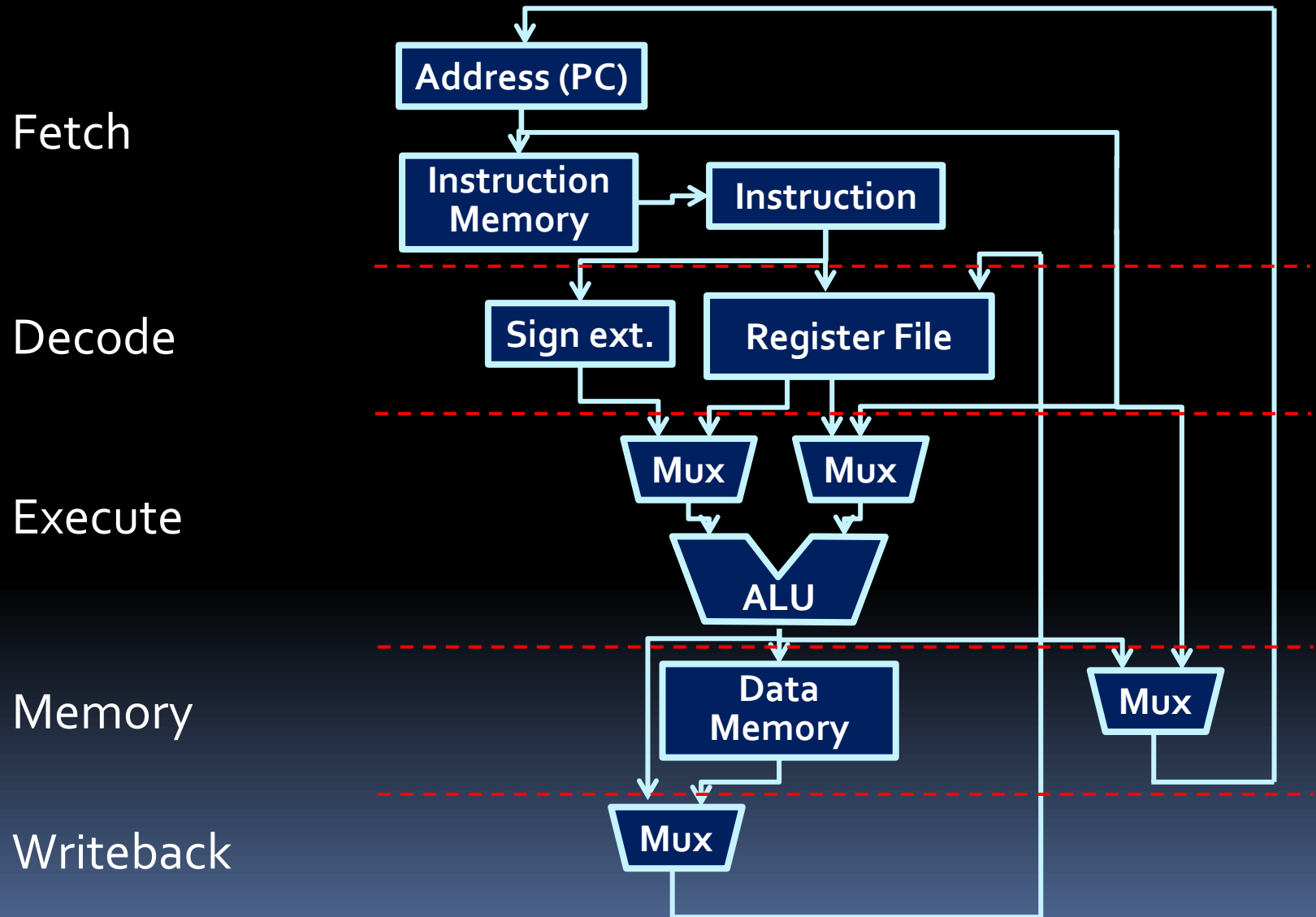


Control Unit

1. **Fetch** instruction from memory into instruction register
2. **Decode and execute** instruction.
 - Execution time can depend on instruction.
3. **Advance** to next instruction using one of:
 - PC \leftarrow PC + 4 or
 - PC \leftarrow from ALU

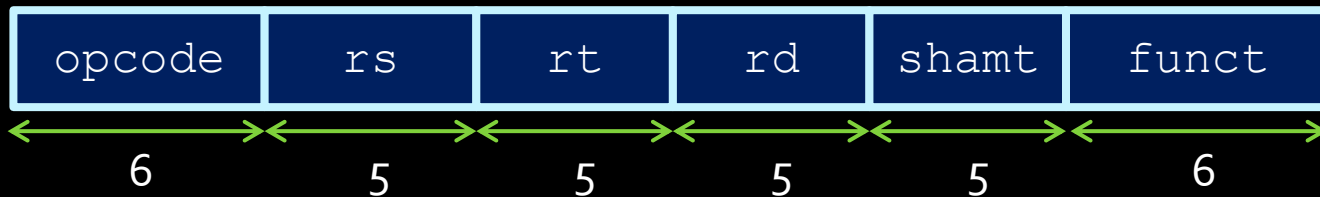


“Linear” Datapath



MIPS instruction types

- R-type:



- I-type:

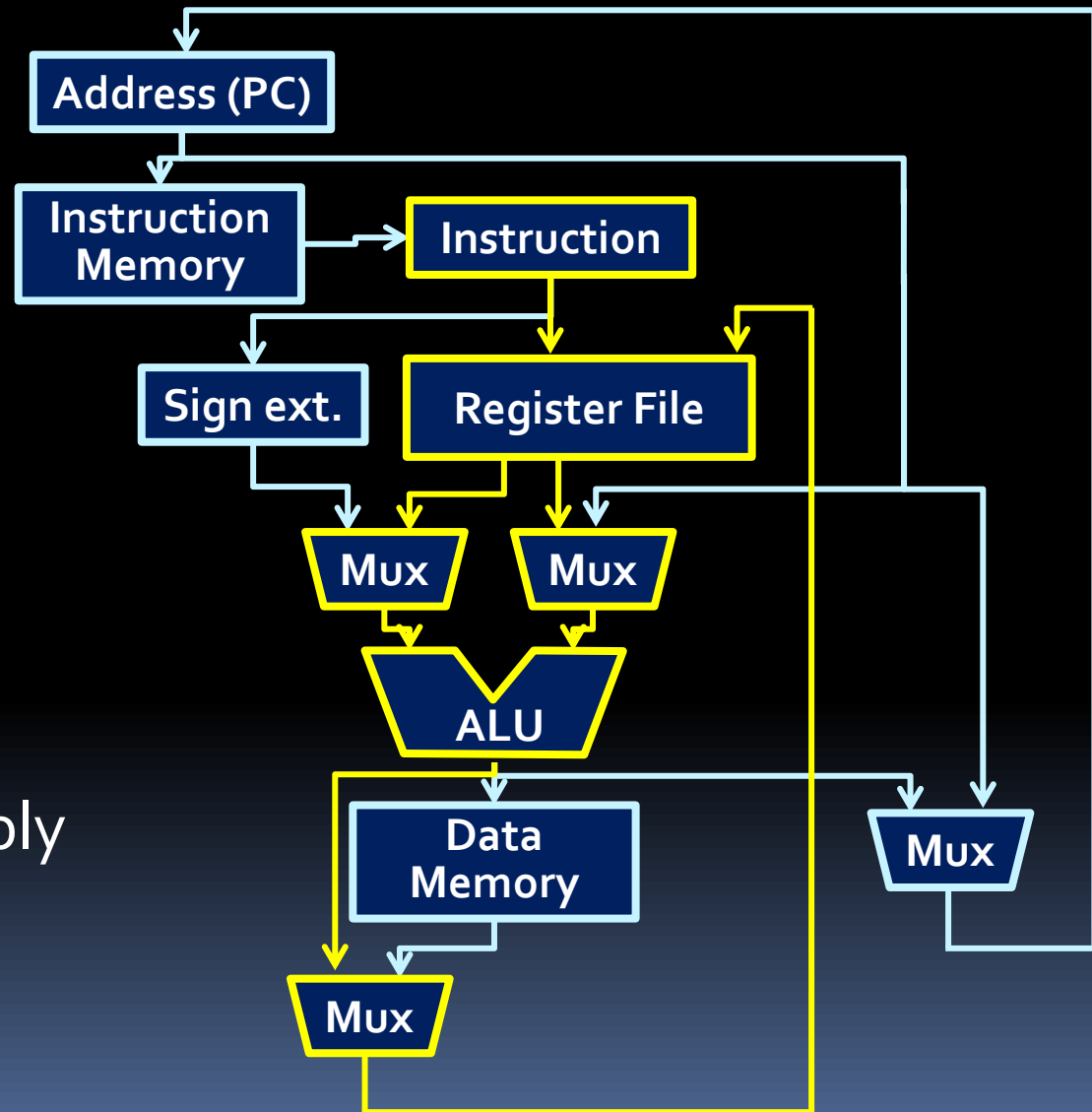


- J-type:



R-Type

- $R_d \leftarrow OP(R_s, R_t)$
- Sources: 2 reg.s
- Dest: reg.
- Examples:
 - ▣ add, subtract, multiply
 - ▣ shift left, shift right
 - ▣ and, not, xor, or,...



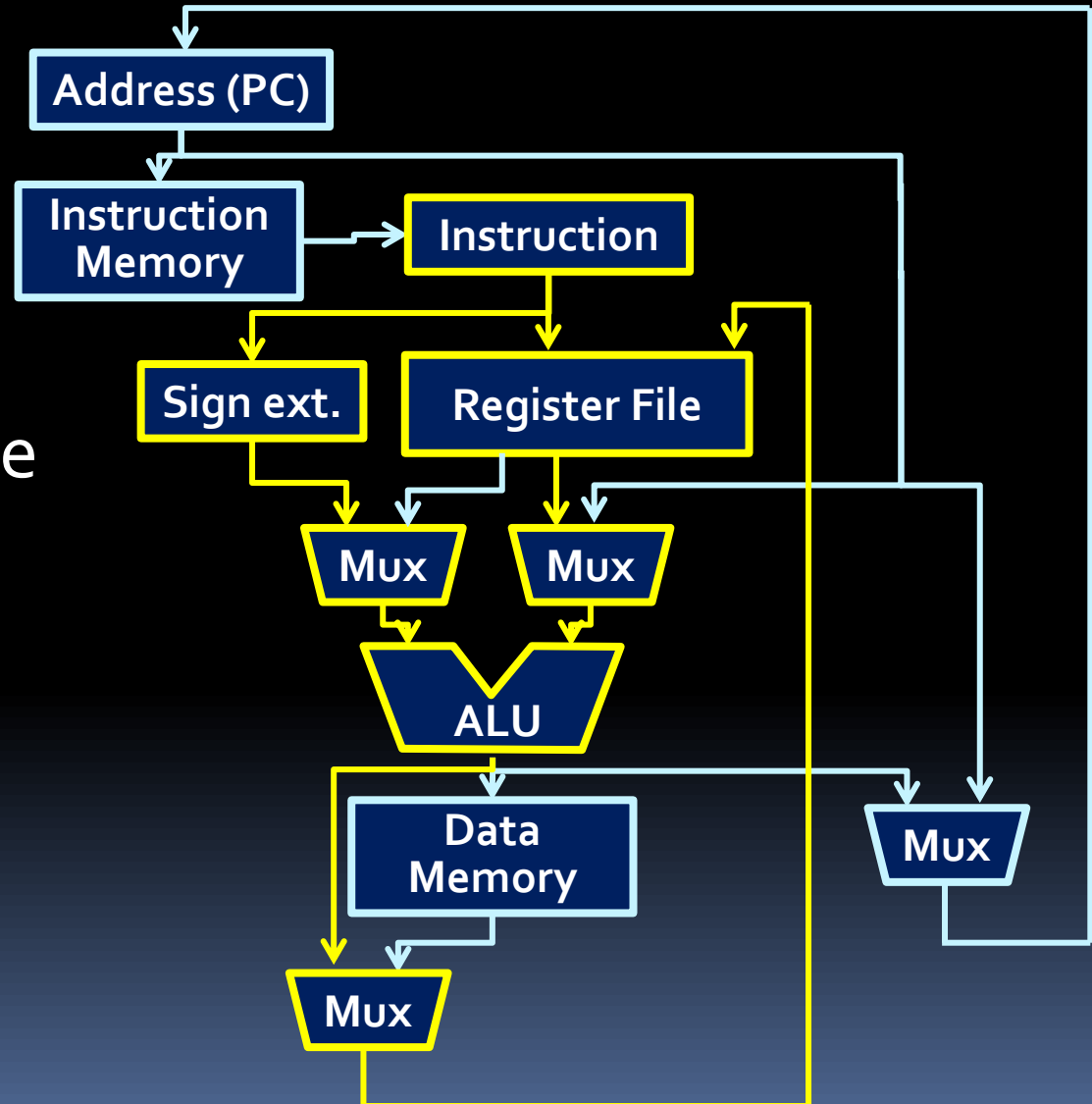
I-type instructions



- I-type instructions have a 16-bit **immediate** field.
- This field is a constant value, which is used for:
 - Arithmetic or other operations:
 - e.g., to compute $\$rt = \$rs + \text{<immediate>}$
 - a displacement (offset) for memory address.
 - e.g, write to memory address $\$rs + \text{<immediate>}$
 - a branch target offset to jump to another instruction
 - e.g., if $\$rt == \rs , branch to $\$pc + \text{<immediate>}$

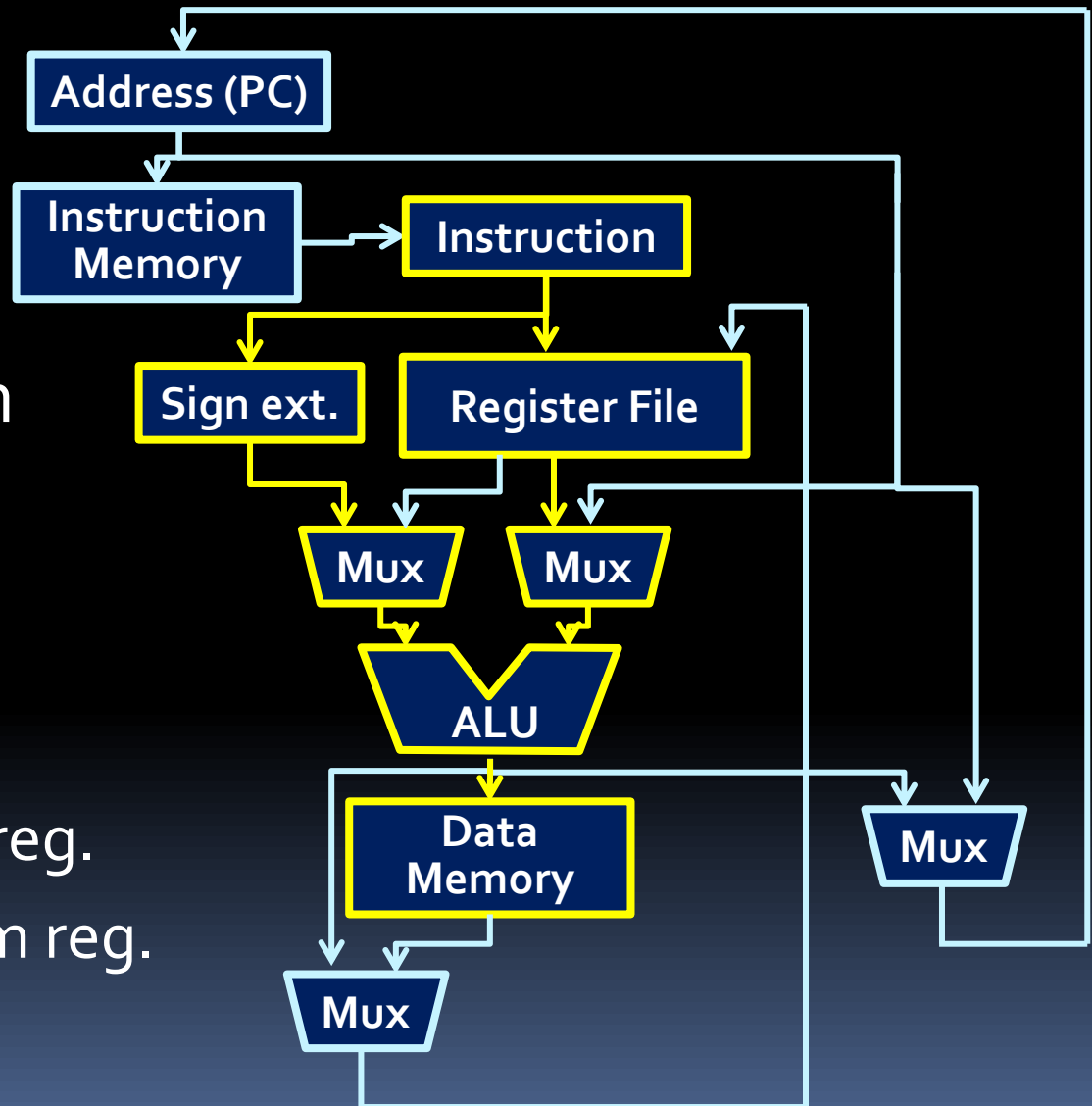
I-Type #1

- $R_t \leftarrow OP(R_s, IM)$
- Source 1: reg.
- Source 2: immediate (instruction reg.)
- Dest: reg.
- Examples:
 - ▣ addi, andi



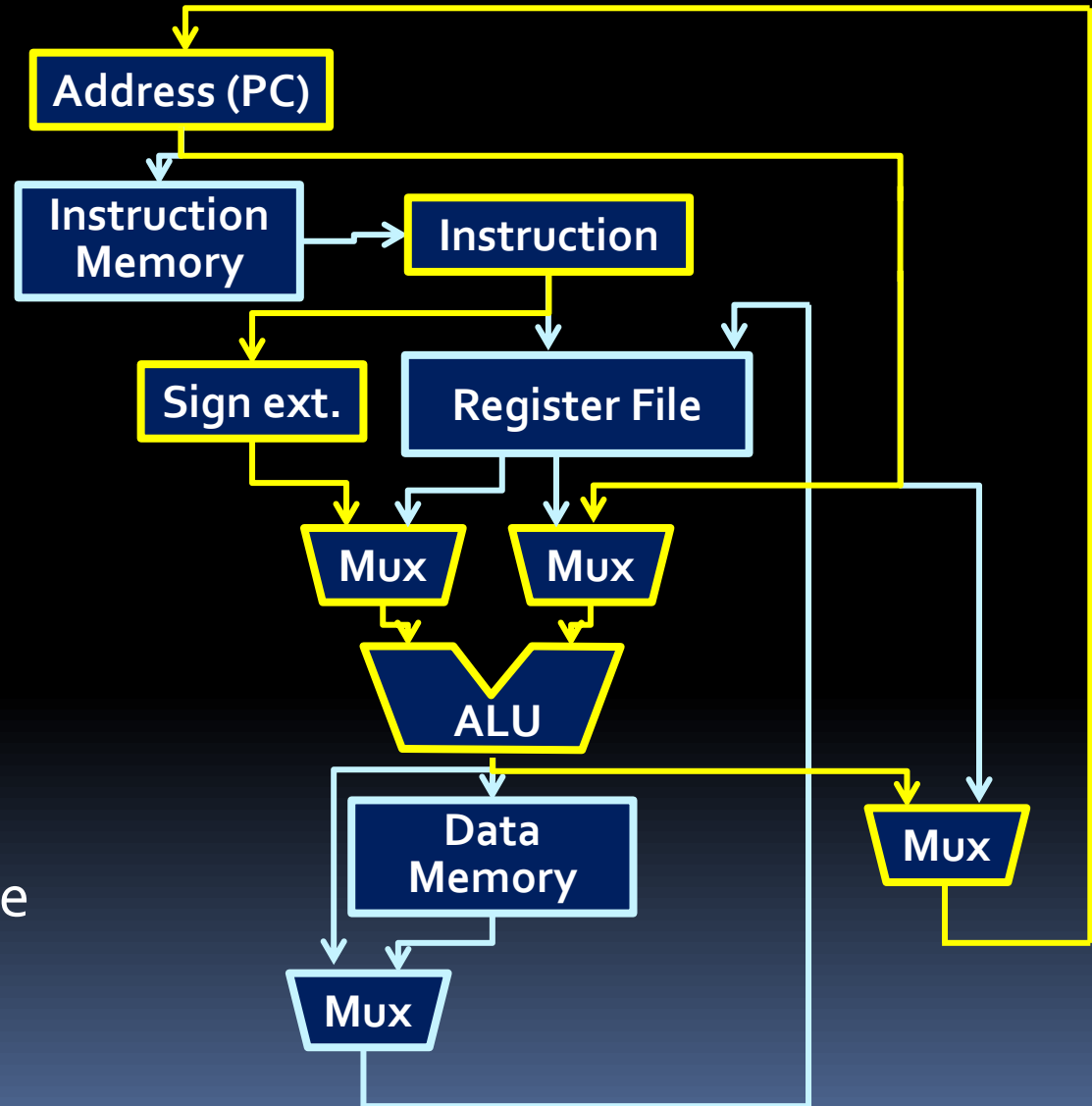
I-Type #2

- Load/Store
- Source: reg or mem
- Dest: mem or reg.
- Examples:
 - lw - load value into reg.
 - sw - store value from reg.



I-Type #3

- Branch:
 $PC \leftarrow PC + IM$
- Source 1: PC
- Source 2: Immediate
- Dest: PC
- Examples:
 - Branch if register value is equal to 0

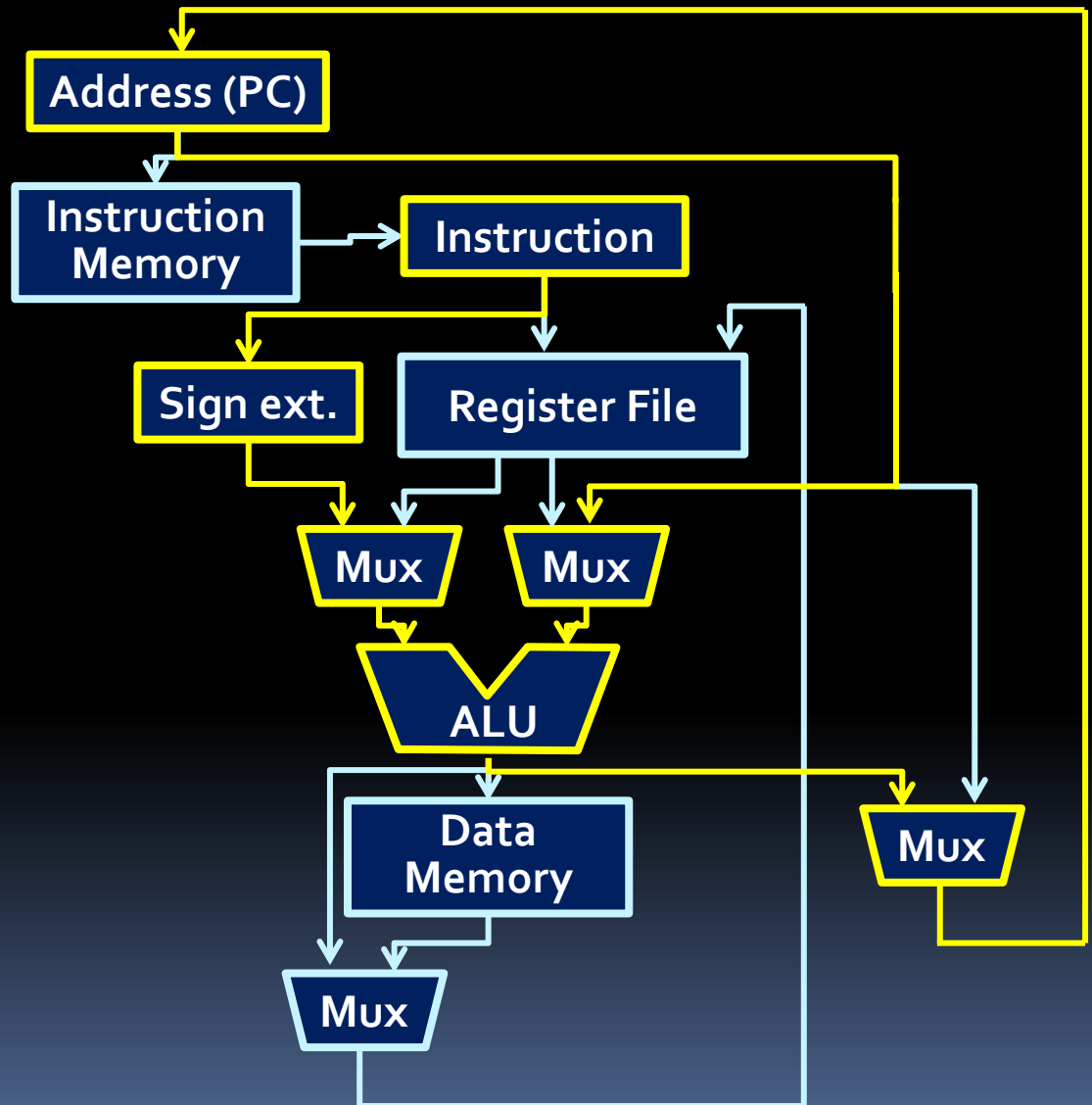


I-type: Branching

- Immediate field is only 16 bits.
 - We cannot store the address of the destination since it is 32 bits.
- In practice, branch targets tends to be close to origin.
- Store the **signed difference** between the address of current instruction (the current PC) and the address of the target instruction.
- Also, since instructions are 4 bytes and word-aligned, we this difference is a multiple of 4.
 - Don't store the lowest 2 bits of the difference – they are zero anyway! Use the extra space to store higher bits.
- So we actually encode a **18-bit signed difference**

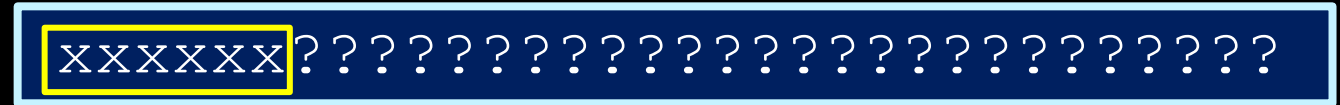
J-type

- Jump:
 $PC \leftarrow \text{address}$
- Source 1: PC
- Source 2: Address
- Dest: PC
- Examples:
 - ▣ j, jal

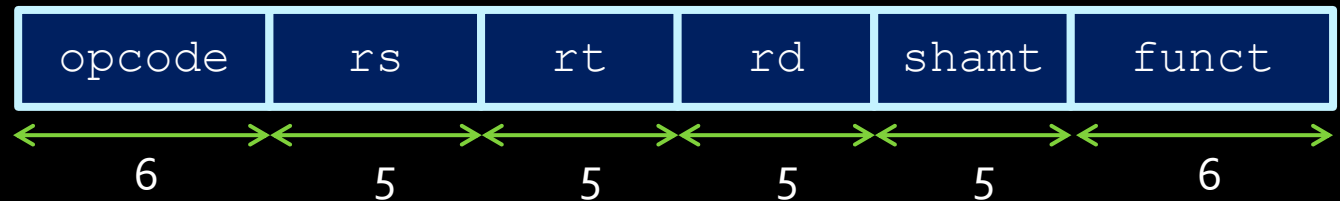


Decoding Instructions

1. Look at opcode (first 6 bits)



2. If 000000
→ R-type



3. Otherwise lookup opcode in table:
→ I-type



- J-type



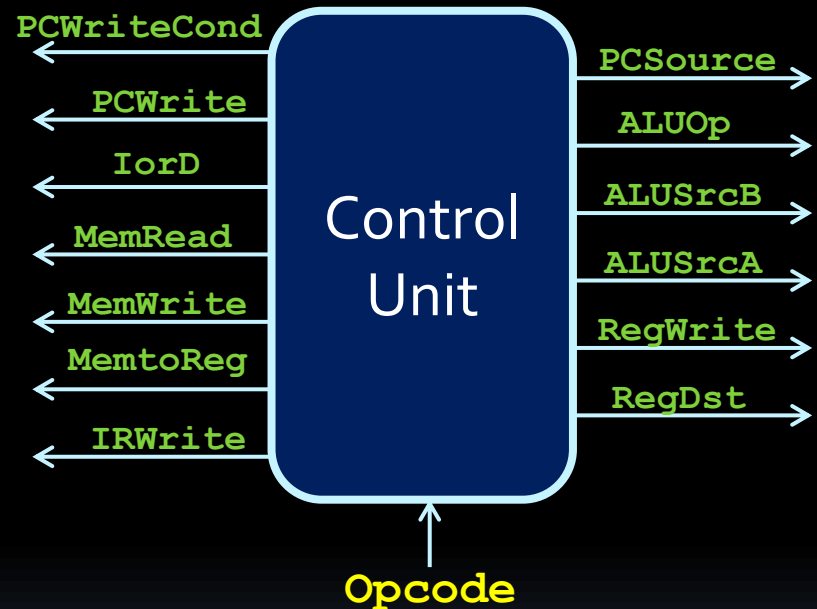
Opcodes

- First 6 bits of the instruction.
- I-type: white
- J-type: pink
 - Only j, jal.
- R-type opcode is 000000
 - Instead we list the function (last 6 bits of instruction)
 - Marked yellow

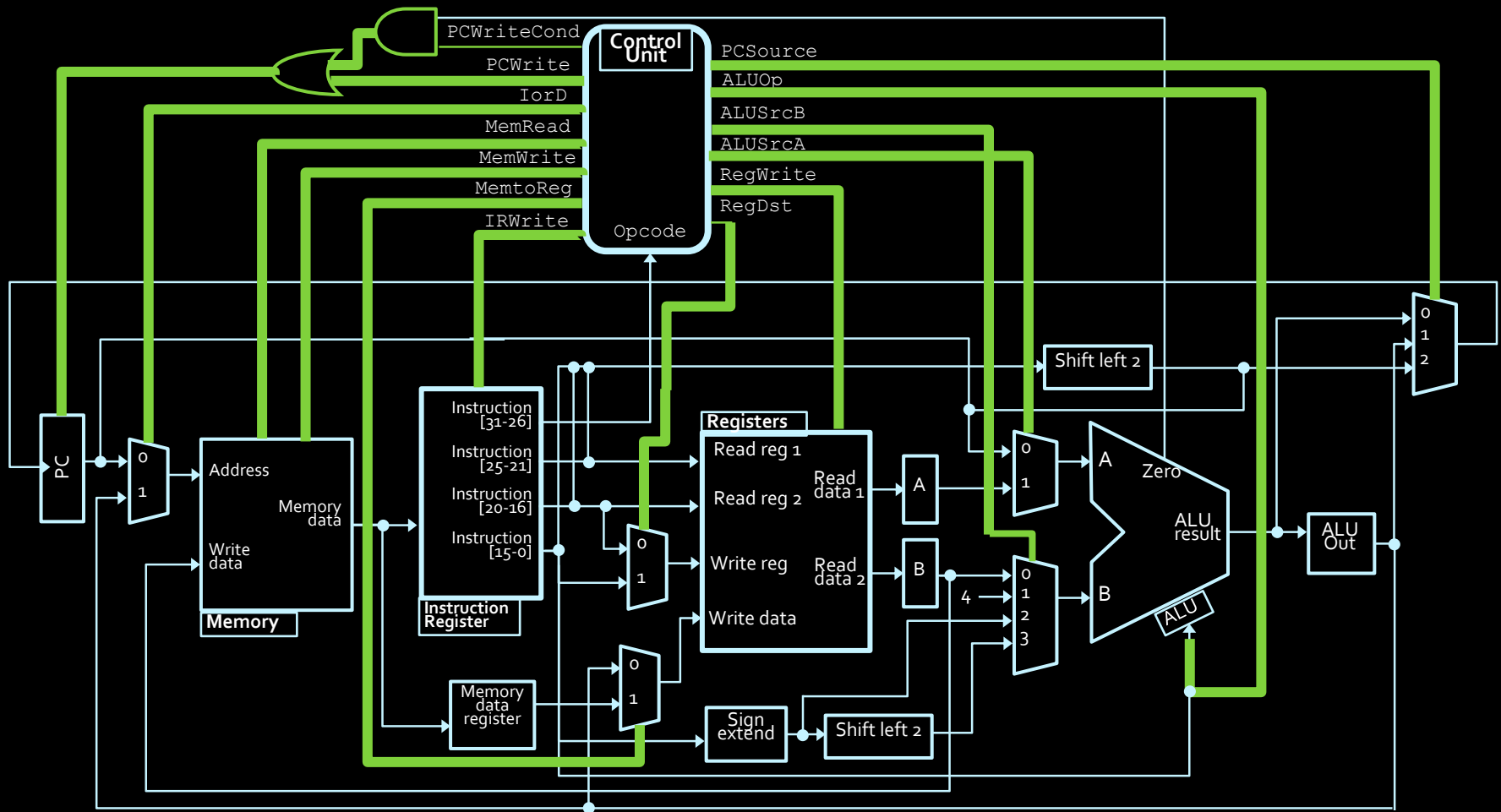
Instruction	Type	Op/Func	Instruction	Type	Op/Func
add	R	100000	srav	R	000111
addu	R	100001	srl	R	000010
addi	I	001000	srlv	R	000110
addiu	I	001001	beq	I	000100
div	R	011010	bgtz	I	000111
divu	R	011011	blez	I	000110
mult	R	011000	bne	I	000101
multu	R	011001	j	J	000010
sub	R	100010	jal	J	000011
subu	R	100011	jalr	R	001001
and	R	100100	jr	R	001000
andi	I	001100	lb	I	100000
nor	R	100111	lbu	I	100100
or	R	100101	lh	I	100001
ori	I	001101	lhu	I	100101
xor	R	100110	lw	I	100011
xori	I	001110	sb	I	101000
sll	R	000000	sh	I	101001
sllv	R	000100	sw	I	101011
sra	R	000011	mflo	R	010010

Control Signals

- The control unit makes computation happen.
- A Finite State Machine.
- Given **opcode**, send the right combination of **control signals** to execute the instruction.
 - Each instruction can take multiple cycles

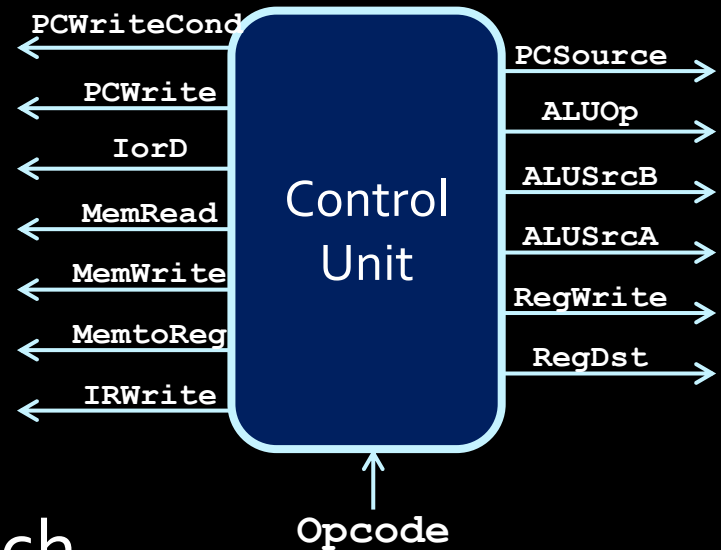


- The control unit sends signals (green lines) to various processor components to enact all possible operations.



Controlling the signals

- Need to understand the role of each signal, and what value they need to have in order to perform the given operation.
- So, what's the best approach to make this happen?



Basic approach to datapath

1. Figure out the data **source(s)** and **destination**.
2. Determine the **path** of the data.
3. Deduce the signal values that **cause** this path:
 - a) Start with Read & Write signals
 - At most one ____Write signal should be high at a time.
 - b) Then, mux signals along the data path.
 - c) Non-essential signals get an X value.

Question

0000 0000 0110 0101 0100 0000 0010 0111

- What is the type of this instruction?
- What does it do?
- Which register stores the result?

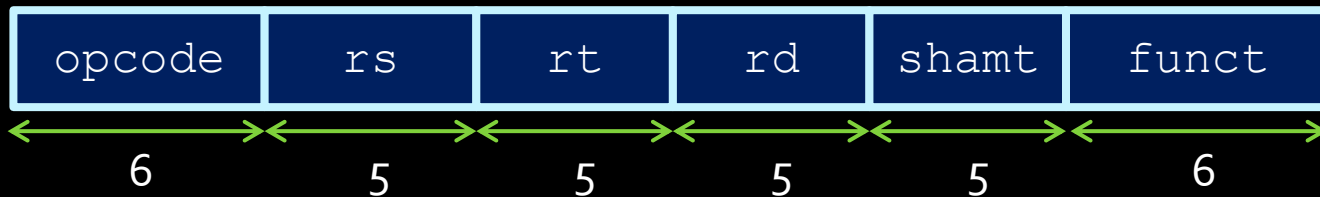
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divu	011011	blez	000110
mult	011000	bne	000101
multu	011001	j	000010
sub	100010	jal	000011
subu	100011	jalr	001001
and	100100	jr	001000
andi	001100	lb	100000
nor	100111	lbu	100100
or	100101	lh	100001
ori	001101	lhu	100101
xor	100110	lw	100011
xori	001110	sb	101000
sll	000000	sh	101001
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MIPS instruction types

- **R-type:**



- **I-type:**



- **J-type:**



Question

0000 0000 0110 0101 0100 0000 0010 0111

- What is the type of this instruction?
- What does it do?
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Question

opcode

0000 0000 0110 0101 0100 0000 0010 0111

- What is the type of this instruction?
 - R-type
- What does it do?
- Which register stores the result?

Question

opcode	rs	rt	rd	shamt	funct		
0000	0000	0110	0101	0100	0000	0010	0111

- What is the type of this instruction?
 - R-type
- What does it do?
 - `funct = 100111`
- Which register stores the result?

0000 0000 0110 0101
0100 0000 0010 0111

funct = 100111

<u>Instruction</u>	<u>Op/Func</u>	<u>Instruction</u>	<u>Op/Func</u>
add	100000	srav	000111
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mult	011000	bne	000101
multu	011001	j	000010
sub	100010	jal	000011
subu	100011	jalr	001001
and	100100	jr	001000
andi	001100	lb	100000
nor	100111	lbu	100100
or	100101	lh	100001
ori	001101	lhu	100101
xor	100110	lw	100011
xori	001110	sb	101000
sll	000000	sh	101001
sllv	000100	sw	101011
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Question

opcode	rs	rt	rd	shamt	funct
0000	0000	0110	0101	0100	0000
0010	0111				

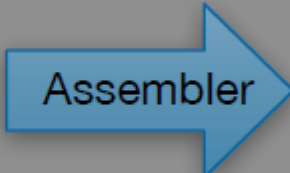
- What is the type of this instruction?
 - R-type
- What does it do?
 - nor
- Which register stores the result?
 - rd = 01000
 - register 8 (known as \$t0 in MIPS assembly)

Week 8:

Intro to Assembly

Programming

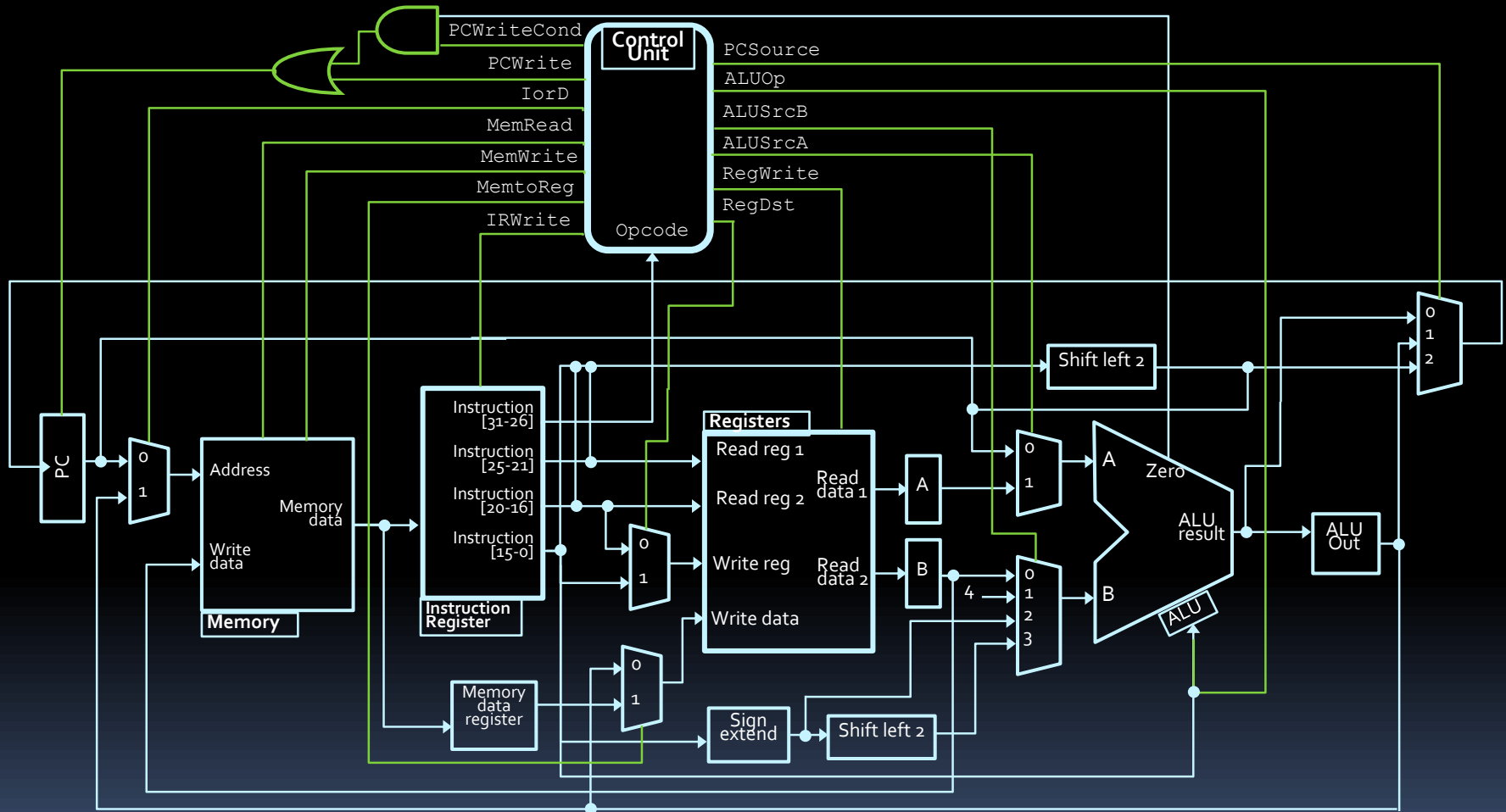
```
loop: lw    $t3, 0($t0)
      lw    $t4, 4($t0)
      add   $t2, $t3, $t4
      sw    $t2, 8($t0)
      addi  $t0, $t0, 4
      addi  $t1, $t1, -1
      bgtz  $t1, loop
```



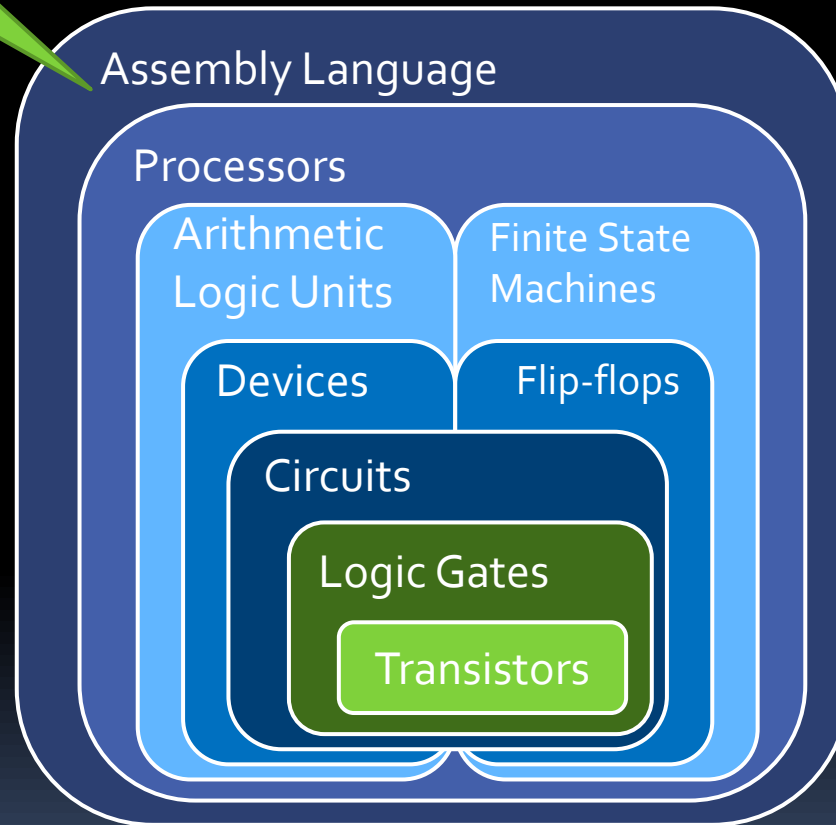
Assembler

```
0x8d0b0000
0x8d0c0004
0x016c5020
0xad0a0008
0x21080004
0x2129ffff
0x1d20fff9
```


The MIPS Microprocessor



Started from the
bottom now
we're here



Hello, World

Tale of a program

- Write code
- Compile code into machine code instructions
- Save instructions in an executable file
- Run the executable file
 - Load file into memory
 - Set PC
 - CPU loads instructions into instruction register
 - Control unit reads op-code
 - Signals turn on/off
 - Billions of transistors turning on/off
 - Trillions of electrons start flowing

Intro to Machine Code

- Now that we have a processor, operations are performed by:
 - Load instructions one by one to instruction register
 - The control unit reads and decodes instruction according to the **opcode** in the first 6 bits.
 - The control unit sends a sequence of signals to the datapath.
- A program is just a sequence of instructions in machine code

A program!

- Below is the content of an executable file “mystery.exe”,
- What does this program do?

```
10001110 00001000 01011010 11110001
10001110 00101001 11010010 00110010
00000001 00001001 01010000 00100000
10001110 01001011 11110011 00110111
00000000 00001100 00110001 00000000
00000010 01101010 10100000 00100010
10101101 11010100 00001111 01011010
```

Assembly vs Machine Code

- Machine code is hard to read.
- Represent instructions as user-readable code words.
 - User-friendly machine code: one line \leftrightarrow one instruction
 - Each processor architecture has its own version.
- Example: $C = A + B$
 - Assume A is stored in \$t1, B in \$t2, C in \$t3.
 - **Assembly language** instruction:

```
add $t3, $t1, $t2
```

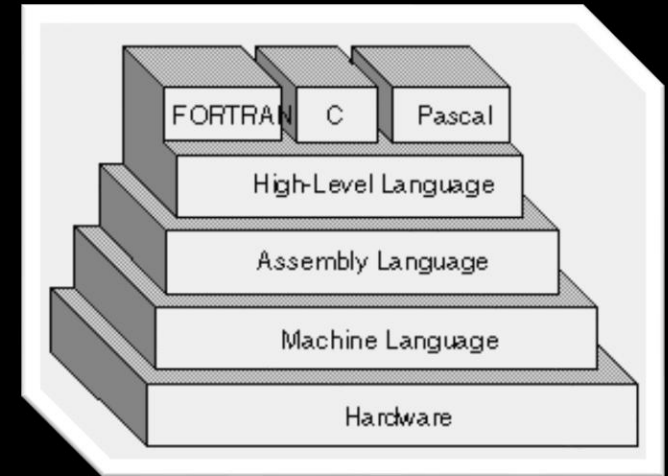
- **Machine code** instruction:

```
000000 01001 01010 01011 00000 100000
```

1-to-1 mapping
for all assembly
code and machine
code instructions!

Assembly language

- Assembly language is the lowest-level language that you'll ever program in.
- Many compilers translate their high-level program commands into assembly commands, which are then converted into machine code and used by the processor.
- Note: There are multiple types of assembly language, especially for different architectures!



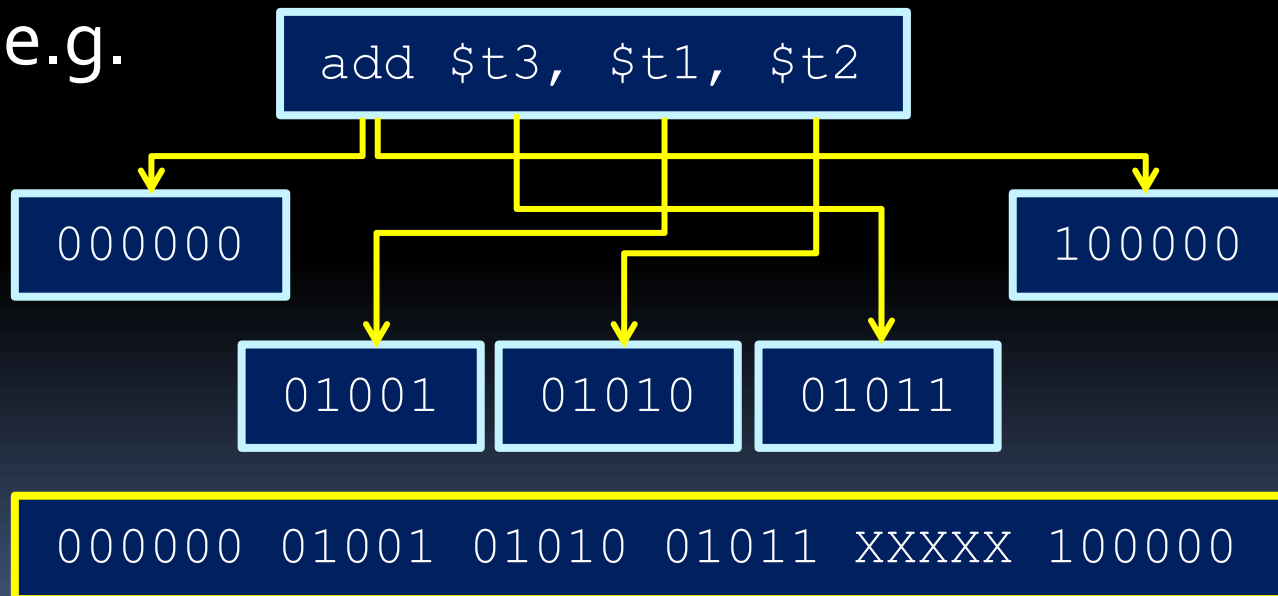
Why learn assembly?

- Understand how computers really work
- Understand how compilers really work
- Better analyze and debug code
 - ▣ Runtime, control flows, pointers, stack overflows
- Appreciate constructs of high-level languages
- Connect your high-level programming knowledge to hardware
- It's on the exam...

Assembly to Machine Code

- Encoding is reverse of decoding.
- We need to know how to encode the operation to perform, and the register values to operate on.

■ e.g.

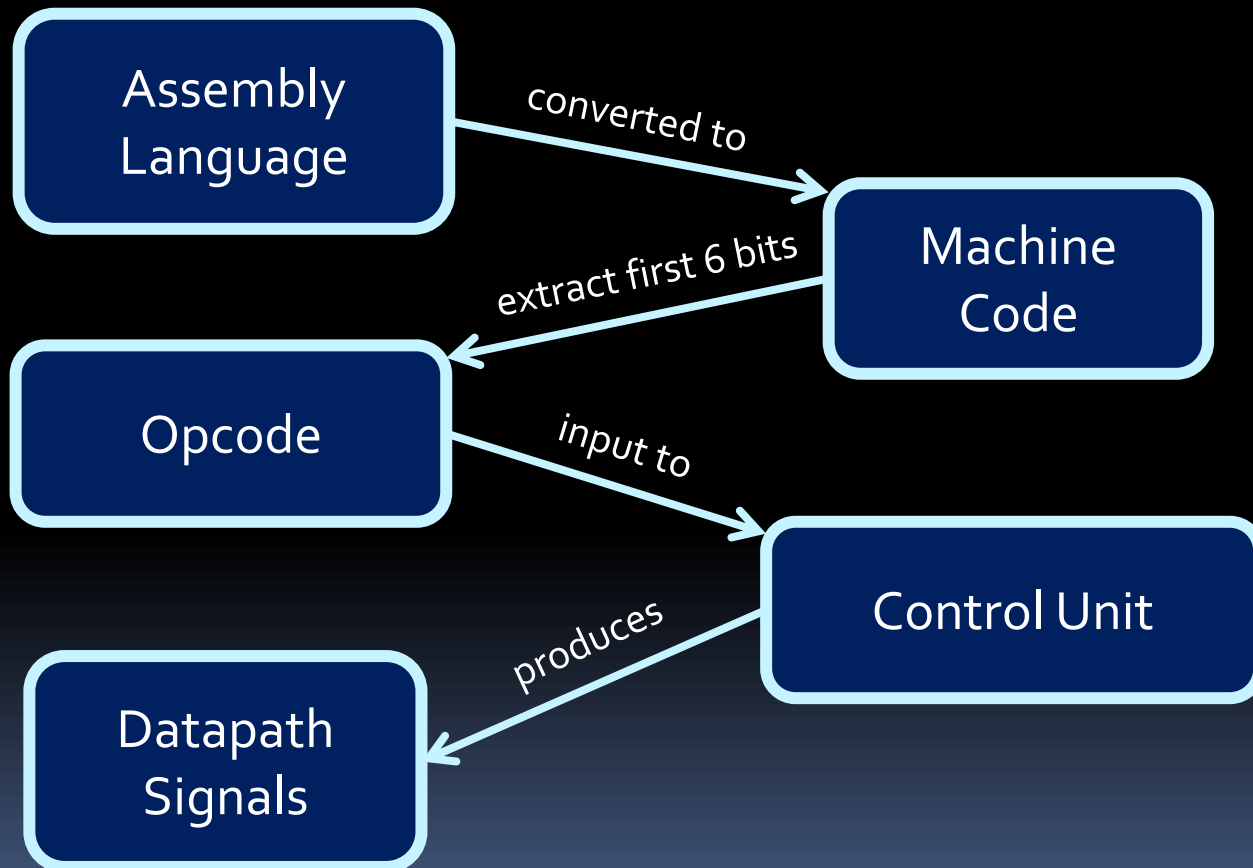


Assembler

- The program that converts assembly code to executable is **NOT** called a **compiler**.
- It's called an **assembler**, because there is no fancy complication needed, it just assembles the lines!
- Try to write a simple one for the processor you implement in Lab 4



How things fit together



MIPS Assembly

```
00000000 01 00 FF FF 00 00 00 00 00 00 00 00 40 00 CC 80 .....@
00000010 0C 00 00 00 00 00 26 01 8F 00 00 00 00 00 53 00 .....&...S
00000020 65 00 6C 00 65 00 63 00 74 00 20 00 52 00 75 00 e.l.e.c.t...R.u
00000030 6C 00 65 00 00 00 08 00 00 00 00 01 4D 00 53 00 l.e.....M.S
00000040 20 00 53 00 68 00 65 00 6C 00 6C 00 20 00 44 00 .S.h.e.l.l...D
00000050 6C 00 67 00 00 00 00 00 00 00 00 00 00 02 00 00 l.g.....
00000060 03 01 A1 50 53 00 3A 00 C3 00 36 00 32 25 00 00 ...PS.....6.2%
00000070 FF FF 83 00 00 00 00 00 00 00 00 00 00 00 00 00 .....P.V.A...J&
00000080 03 00 01 50 0E 00 56 00 41 00 0A 00 4A 26 00 00 ...&A.p.p.l.y
00000090 FF FF 80 00 26 00 41 00 70 00 70 00 6C 00 79 00 .t.o...a.l.l...
000000a0 20 00 74 00 6F 00 20 00 61 00 6C 00 6C 00 00 00 .....P
000000b0 00 00 00 00 00 00 00 00 00 00 00 00 01 00 01 50 ~}.2.....
000000c0 7E 00 7D 00 32 00 0E 00 01 00 00 00 FF FF 80 00 O.K.....
000000d0 4F 00 4B 00 00 00 00 00 00 00 00 00 00 00 00 00 ...P}.2.....
000000e0 00 00 01 50 B4 00 7D 00 32 00 0E 00 02 00 00 00 ...C.a.n.c.e.l
000000f0 FF FF 80 00 43 00 61 00 6E 00 63 00 65 00 6C 00 .....P
00000100 00 00 00 00 00 00 00 00 00 00 00 00 00 01 50 ~}.2.....
00000110 EA 00 7D 00 32 00 0E 00 09 00 00 00 FF FF 80 00 &H.e.l.p.....
00000120 26 00 48 00 65 00 6C 00 70 00 00 00 00 00 00 00 80 08 81 50 0E 00 3A 00 .....P
00000130 00 00 00 00 00 00 00 00 80 08 81 50 0E 00 3A 00 .....%
00000140 3B 00 0E 00 2F 25 00 00 FF FF 81 00 00 00 00 00 ...P.O.
00000150 00 00 00 00 00 00 00 00 00 00 02 50 0E 00 30 00 .....%.....F.i
00000160 1E 00 08 00 EE 25 00 00 FF FF 82 00 46 00 69 00 l.e...T.y.p.e...
00000170 6C 00 65 00 20 00 54 00 79 00 70 00 65 00 00 00 00 00 00 00 00 00 02 50 .....P
00000180 00 00 00 00 00 00 00 00 EF 25 00 00 FF FF 82 00 T.O.....%
00000190 54 00 30 00 2C 00 08 00 69 00 6E 00 67 00 20 00 P.a.r.s.i.n.g...
000001a0 50 00 61 00 72 00 73 00 73 00 00 00 00 00 00 00 R.u.l.e.s.....
000001b0 52 00 75 00 6C 00 65 00 73 00 00 00 00 00 00 00 .....P
000001c0 00 00 00 00 00 00 00 00 07 00 00 50 06 00 07 00 .....q.%
000001d0 1A 01 71 00 ED 25 00 00 FF FF 80 00 00 00 00 00 .....P
000001e0 00 00 00 00 00 00 00 00 00 00 02 50 0E 00 11 00 >.....%.....S.e
000001f0 3E 00 08 00 EC 25 00 00 FF FF 82 00 53 00 65 00 l.e.c.t...R.u.l
00000200 6C 00 65 00 63 00 74 00 20 00 52 00 75 00 6C 00 e...F.o.r...F.i
00000210 65 00 20 00 46 00 6F 00 72 00 20 00 46 00 69 00 l.e.....%
00000220 6C 00 65 00 00 00 00 00 00 00 00 00 00 00 00 .....P.....%
00000230 80 08 81 50 0E 00 1B 00 08 01 0E 00 EB 25 00 00 ...P.a.7...k&
00000240 FF FF 81 00 00 00 00 00 00 00 00 00 00 00 00
00000250 00 00 02 50 19 00 61 00 37 00 08 00 6B 26 00 00
00000260 FF FF 82 00 00 00 00 00 |
```

```
00003e0 EE EE 85 00 00 00 00 00 |
00003e2 00 00 05 20 1a 00 e7 00 31 00 08 00 eb 5e 00 00 .....B...K
00003e4 EE EE 87 00 00 00 00 00 00 00 00 00 00 00 00 .....B...
00003e6 80 08 87 20 0E 00 1B 00 08 07 0E 00 EB 52 00 00 .....B...
00003e8 ec 00 e2 00 00 00 00 00 00 00 00 00 00 00 00 .....T...
00003ea e2 00 30 00 1e 00 ee 00 13 00 30 00 1e 00 e2 00 .....T...
00003ec ec 00 e2 00 e3 00 14 00 30 00 25 00 32 00 ec 00 .....T...
00003ee 3E 00 08 00 EC 32 00 00 EE EE 85 00 23 00 e2 00 .....T...
00003f0 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....B...
```

A little about MIPS

- MIPS
 - Short for **M**icroprocessor without **I**nterlocked **P**ipeline **S**tages
- Uses **RISC** architecture (**R**educed **I**nstruction **S**et **C**omputer).
 - Provide a set of simple and fast instructions
 - Compiler translates instructions into 32-bit instructions for instruction memory.
 - Complex instructions are built out of simple ones by the compiler and assembler.

MIPS Registers

- MIPS is a **register-to-register** (a.k.a. **load-store**) architecture
 - Source, destination of ALU operations are registers.
 - To operate on memory, need to load it into a register first, then store the result
- MIPS register file provides **32** registers: 0, 1, 2 , ... 31
- In assembly we want something more understandable
 - `$to, $t1`
 - `$vo, $v1`
 - `$zero`
 - Can still use `$0, $1, $2, ...`

MIPS Registers

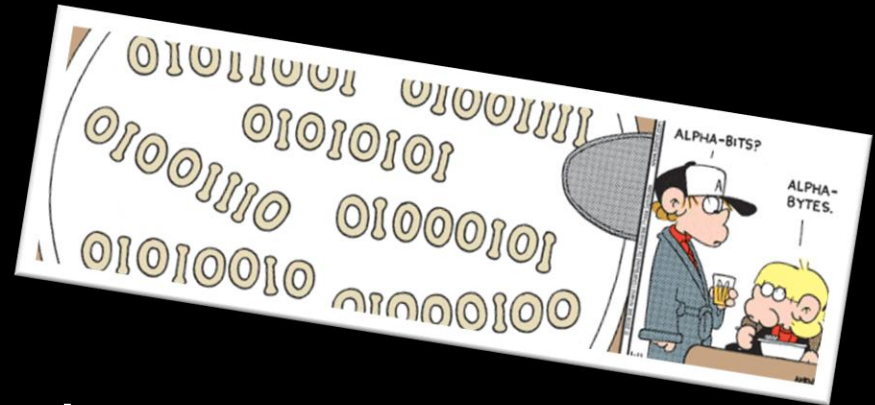
- MIPS register file provides 32 registers.
 - Most are used by programs to store values:
 - `$t0` – `$t9`: temporaries
 - `$s0` – `$s7`: saved temporaries
 - Some have special values:
 - **register 0 (`$zero`)** : always zero (writes to it are discarded)
 - `$at`: reserved for the assembler.
 - `$gp`, `$sp`, `$fp`, `$ra`: memory and function support
 - `$k0`, `$k1`: reserved for OS kernel
 - Some are used by programs as functions parameters:
 - `$v0`, `$v1`: return values
 - `$a0`–`$a3`: function arguments
- Additional special registers (**PC**, **HI**, **LO**) not in register file.
 - **HI** and **LO** are used in multiplication and division
 - These accessed by special instructions.

MIPS Register File Registers

Number	Name	Use
0	\$0, \$zero	Always the constant zero
1	\$at	reserved for assembler (pseudo instructions)
2 – 3	\$v0 - \$v1	function return values
4 – 7	\$a0 - \$a3	function arguments
8 – 15	\$t0 - \$t7	temporary variables
16 – 23	\$s0 - \$s7	saved temporaries
24 – 25	\$t8 - \$t9	temporary variables
26 – 27	\$k0 - \$k1	reserved for operating system kernel
28	\$gp	global pointer to data segment
29	\$sp	stack pointer to top of stack
30	\$fp	frame pointer to function frame start
31	\$ra	return address from function

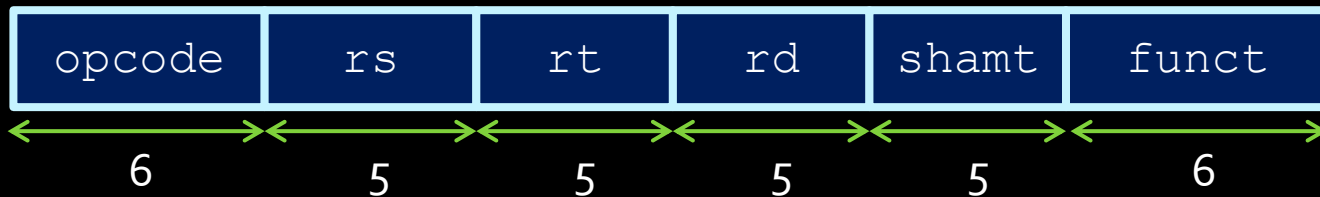
MIPS Memory and Instructions

- All memory is addressed in **bytes**.
- Instruction addresses too!
 - Starting from the instruction at address 0.
- All instructions are 32 bits (4 bytes) long
- Therefore:
all instruction addresses are divisible by 4.
- Also, all registers are 4 bytes long (one word)

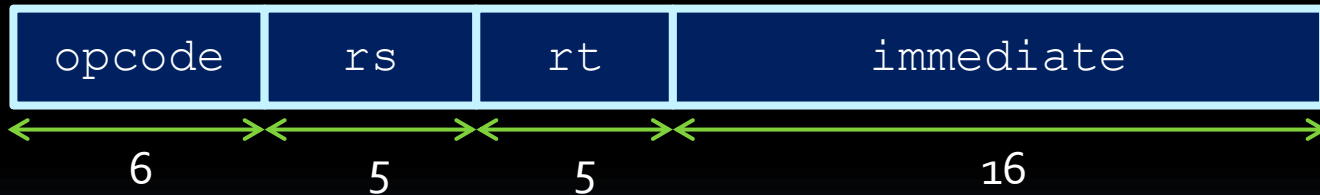


Recall: MIPS instruction types

- **R-type:**



- **I-type:**



- **J-type:**



Common Asm Instructions

Instruction Type	Examples	Usage	Integer Frequency	Floating point Frequency
Arithmetic	add, sub, addi	Operations in assignment statements	16%	48%
Data transfer	lw, sw, lb, lbu, lh, lhu, sb, lui	References to data structures, such as arrays	35%	36%
Logical	and, or, nor, andi, ori, sll, srl	operations in assignment statements	12%	4%
Conditional branch	beq, bne, slt, slti, sltiu	If statements and loops	34%	8%
Jump	j, jr, jal	Procedure calls, returns, and case/switch statements	2%	0%

Types of Asm Instructions

- Arithmetic add, mult, ...
- Logical and, or, ...
- Bit shifting sll, sra, ...
- Data movement mflo, mfhi, ...
- Branch beq, bgtz, ...
- Jump j, jr, ...
- Comparison slt, sltu, ...
- Memory lw, sw, ...

Microarchitecture vs. ISA

- Assembly has 8 types of instructions, yet we know there are 3 types of MIPS instructions?
- **Instruction Set Architecture (ISA)**
 - The set of instructions supported by a processor.
 - Registers, address and data formats, execution model, etc.
 - A “contract” between processor and programmer.
- **Microarchitecture**
 - The implementation of the ISA on a processor.
 - Cache, pipeline, branch prediction, datapath...
- **Computer architecture**: combination of both.

ALU Instructions



Arithmetic instructions

Instruction	Opcode/Function	Syntax	Operation
add	100000	\$d, \$s, \$t	\$d = \$s + \$t
addu	100001	\$d, \$s, \$t	\$d = \$s + \$t
addi	001000	\$t, \$s, i	\$t = \$s + SE(i)
addiu	001001	\$t, \$s, i	\$t = \$s + SE(i)
div	011010	\$s, \$t	lo = \$s / \$t; hi = \$s % \$t
divu	011011	\$s, \$t	lo = \$s / \$t; hi = \$s % \$t
mult	011000	\$s, \$t	hi:lo = \$s * \$t
multu	011001	\$s, \$t	hi:lo = \$s * \$t
sub	100010	\$d, \$s, \$t	\$d = \$s - \$t
subu	100011	\$d, \$s, \$t	\$d = \$s - \$t

Notes: "hi" and "lo" refer to the HI and LO registers (see register slide).
"SE" = "sign extend".

R-type vs I-type arithmetic

R-Type

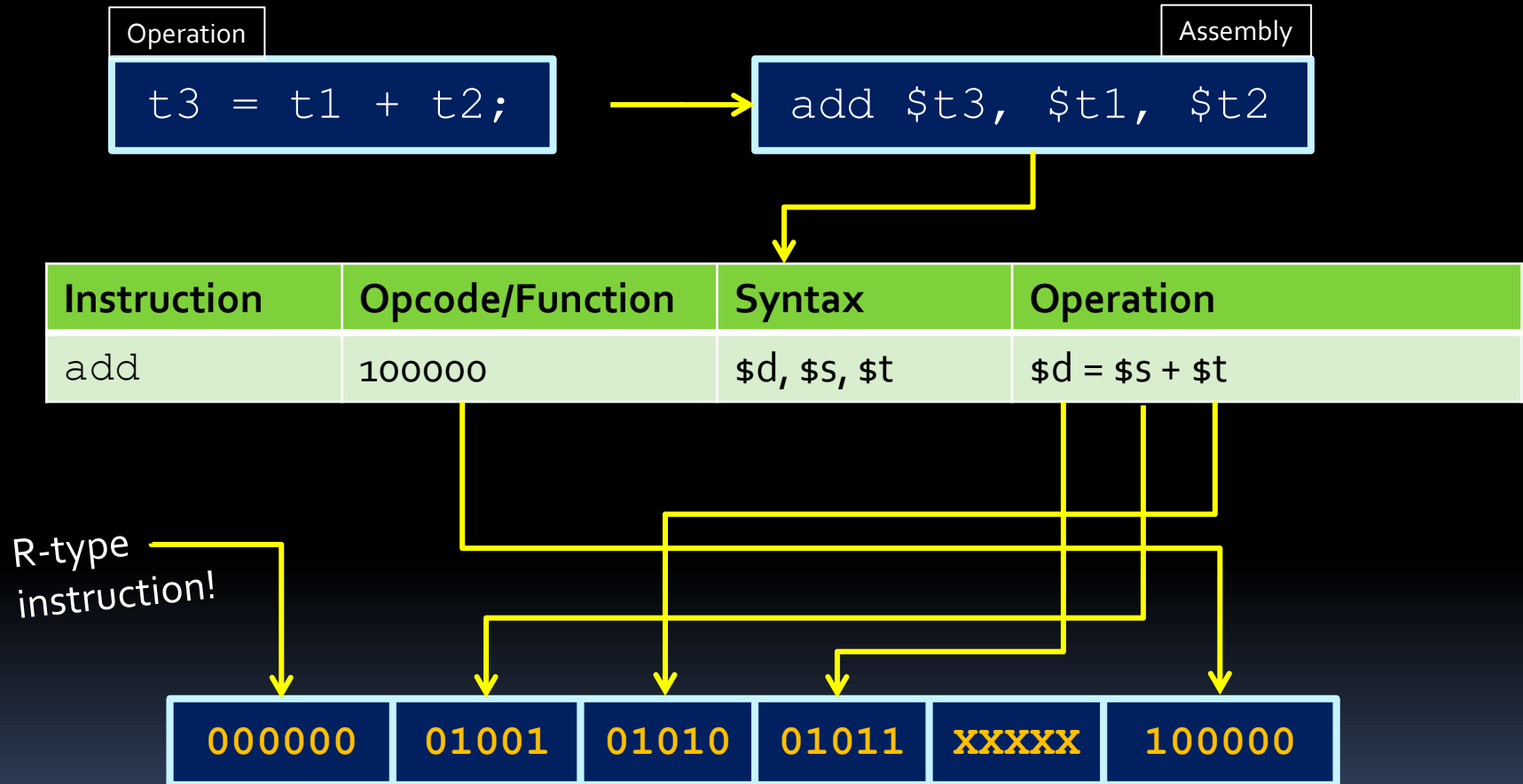
- `add, addu`
- `div, divu`
- `mult, multu`
- `sub, subu`

I-Type

- `addi`
- `addiu`

- In general, most instructions are R-type (meaning all operands are registers) and some are I-type (meaning they use an immediate/constant value in their operation).
- Can you recognize which of the following are R-type and I-type instructions? (Hint: “i” for “immediate”)

Assembly → Machine Code



Although we specify “don’t care” bits as X values, the assembler generally assigns some value (like 0).

Unsigned Instructions

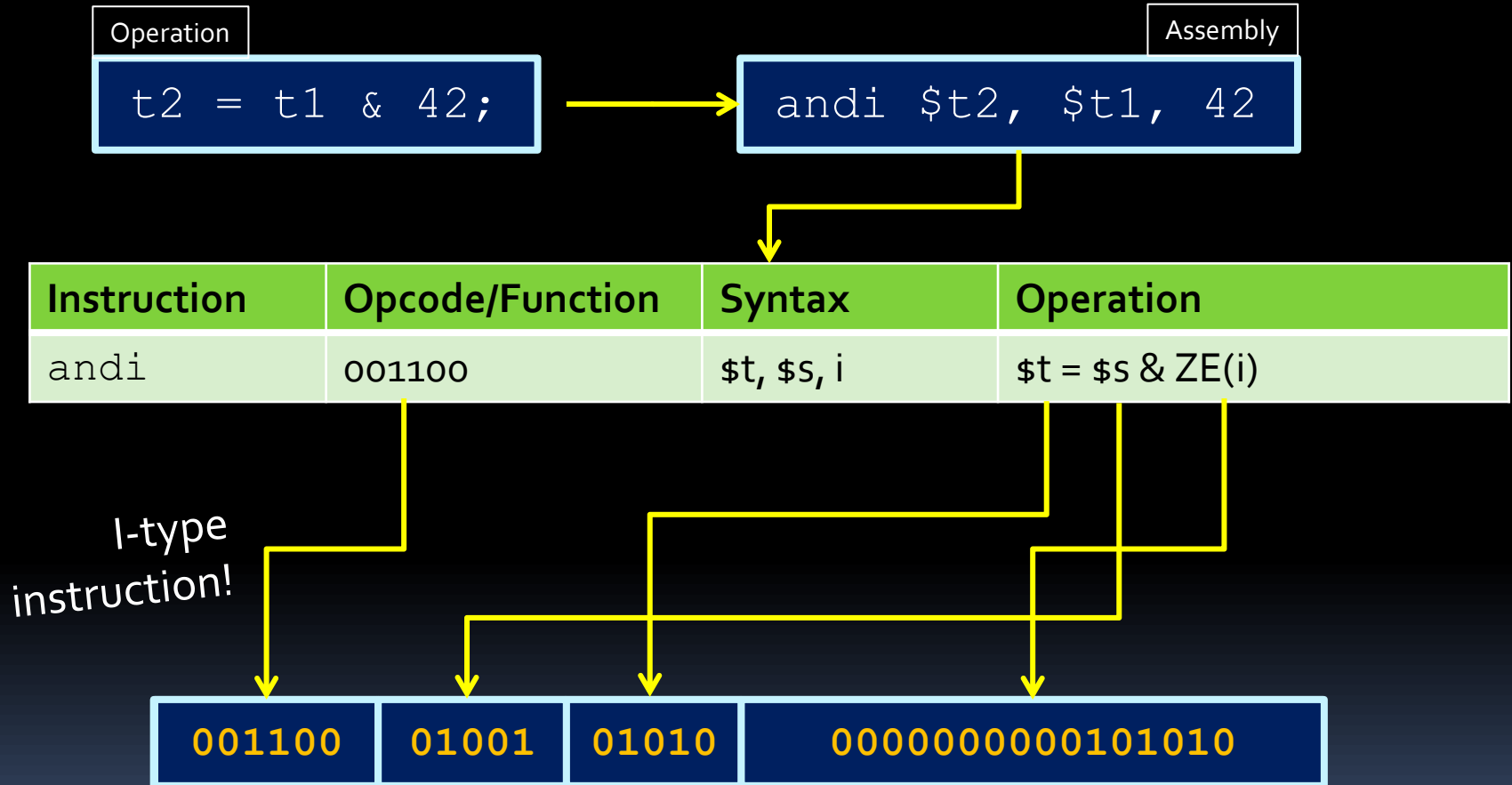
- What is the difference between **add** or **addu**?
 - Both do exactly same thing! Add numbers.
- “**u**” stands for “**unsigned**”
 - Causes a “trap” (a.k.a exception) if there is overflow
 - Stops execution of current code.
 - **addu** ignores this overflow
- **mult** and **multu** are not the same!
 - Slight difference in operation. Use the right one!
 - Neither check for overflow.

Logical instructions

Instruction	Opcode/Function	Syntax	Operation
and	100100	\$d, \$s, \$t	$\$d = \$s \& \$t$
andi	001100	\$t, \$s, i	$\$t = \$s \& \text{ZE}(i)$
nor	100111	\$d, \$s, \$t	$\$d = \sim(\$s \mid \$t)$
or	100101	\$d, \$s, \$t	$\$d = \$s \mid \$t$
ori	001101	\$t, \$s, i	$\$t = \$s \mid \text{ZE}(i)$
xor	100110	\$d, \$s, \$t	$\$d = \$s \wedge \$t$
xori	001110	\$t, \$s, i	$\$t = \$s \wedge \text{ZE}(i)$

Note: ZE = zero extend (pad upper bits with 0 value).

Assembly → Machine Code II



Shift instructions

Instruction	Opcode/Function	Syntax	Operation
sll	000000	\$d, \$t, a	\$d = \$t << a
sllv	000100	\$d, \$t, \$s	\$d = \$t << \$s
sra	000011	\$d, \$t, a	\$d = \$t >> a
srav	000111	\$d, \$t, \$s	\$d = \$t >> \$s
srl	000010	\$d, \$t, a	\$d = \$t >>> a
srlv	000110	\$d, \$t, \$s	\$d = \$t >>> \$s

Note: srl = "shift right logical"

sra = "shift right arithmetic".

The "v" denotes a variable number of bits, specified by \$s.

a is **shift amount**, and is stored in **shamt** when encoding the R-type machine code instructions.

Data movement instructions

Instruction	Opcode/Function	Syntax	Operation
mfhi	010000	\$d	\$d = hi
mflo	010010	\$d	\$d = lo
mthi	010001	\$s	hi = \$s
mtlo	010011	\$s	lo = \$s

- These are instructions for operating on the HI and LO registers described earlier (for multiplication and division)

lui – load upper immediate

Instruction	Opcode/Function	Syntax	Operation
lui	001111	\$t, i	\$t = i << 16

- Load 16-bit immediate into upper half of the register.
- The lower 16 bits of the register are set to zero.

iiiiiiiiiiiiiiii0000000000000000

ALU instructions in RISC

- Most ALU instructions are R-type instructions.
 - The six-digit codes in the tables are therefore the function codes (opcodes are 000000).
 - Exceptions are the I-type instructions (`addi`, `andi`, `ori`, etc.)
- Not all R-type instructions have an I-type equivalent.
 - RISC principle dictate that **an operation doesn't need an instruction if it can be performed through multiple existing operations.**
 - Example `addi + div` \rightarrow `divi`

Pseudoinstructions

- Move data from \$t4 to \$t5?

- `move $t5,$t4` →

```
add $t5,$t4,$zero
```

- Multiply and store in \$s1?

- `mul $s1, $t4, $t5` →

```
mult $t4,$t5  
mflo $s1
```

- Load a 32-bit immediate?

- `li $s0,0x1234ABCD` →

```
lui $s0,0x1234  
ori $s0,0xABCD
```

Pseudoinstructions

- Pseudo instructions **look** like assembly instructions...
- ...but don't have a dedicated machine code instruction.
- Provided by the assembler
 - ▣ Mapping ASM to machine code is more like a many-to-one mapping...
- If a temporary register is needed, use **\$at**

Making an assembly program

- Assembly language programs typically have structure similar to **simple** Python or C programs:
 - They set aside registers to store data.
 - They have sections of instructions that manipulate this data.
- It is always good to decide at the beginning which registers will be used for what purpose!
 - More on this later 😊