CSCB09 Software Tools and Systems Programming Inter Processes Communication: Pipes

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Today's class

Today we will discuss the following topics:

- Quick recap about processes
- How processes communicate...
- Pipes

Acknowledgement Prof. Bianca Schroeder

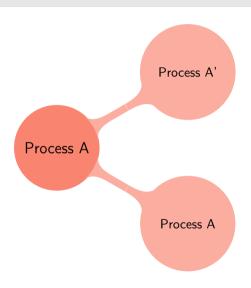
Processes Recap

Processes can create other processes

• The fork system call creates a child process:

```
#include <unistd.h>
pid_t fork(void);
```

- fork creates a duplicate of the currently running program.
- Both processes run concurrently and independently.
- After fork() both execute the next instruction after fork.



- What if a process wants to wait for a particular child (rather than any child)
- What if a process does not want to block when no child has terminated?
 pid_t waitpid(pid_t pid, int *status, int options);
- First parameter specifies PID of child to wait for
- If options is 0, waitpid blocks (just like wait)
- If options is WNOHANG, it immediately returns 0 instead of blocking when no terminated child

Processes Pathologies

How does a child become a zombie?

- When a child terminates, but its parent process is not waiting for it
- The child (its exit code) is kept around as a zombie until parent collects its exit code through wait – or until parent terminates
- Shows up as "Z" in ps



How does a child become an orphan?

- If the parent process terminates before the child
- Who is now the new parent?
 - Orphans get adopted by the init process
 - init is the first process started during booting
 - It's the root of the process hierarchy
 - init has a PID of 1
 - The PPID of orphans is 1

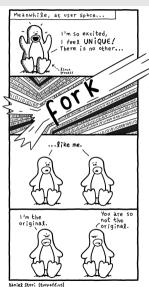
fork() VS exec()

Fork creates a *duplicate* of the current process How do we actually create a new process that runs a different program? fork() VS exec()

Fork creates a *duplicate* of the current process How do we actually create a new process that runs a different program?

- The fork system call creates a new process.
- The new process created by fork() is a copy of the current process except for the returned value.
- The exec() system call replaces the current process with a new program.

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exec Functions

• exec() is not one specific function, but a family of functions:

```
// execl: more convenient if there is a fixed number of arguments
execl(char *path, char *arg0, ..., (char *)NULL);
// execv: The last element of this array must be a null pointer
execv(char *path, char *argv[]);

// lp and vp versions use the same functionality that the shell
// would use in locating the program
execlp(char *file, char *arg0, ..., (char *)NULL);
execvp(char *file, char *argv[]);
```

- First parameter: name of executable; then commandline parameters for executable; these are passed as argv[0], argv[1], ..., to the main program of the executable.
- execl and execv differ from each other only in how the arguments for the new program are passed
- execlp and execvp differ from execl and execv only in that you don't have to specify full path to new program

Processes Communication

Processes often need to communicate

- E.g. the different worker processes of a parallel program need to exchange data and/or synchronize
- Options:
 - Exit code limited solution...
 - Cannot use variables, since after fork each process has separate copy of variables
 - Use files coordination is difficult

Processes often need to communicate

- E.g. the different worker processes of a parallel program need to exchange data and/or synchronize
- Options:
 - Exit code limited solution...
 - Cannot use variables, since after fork each process has separate copy of variables
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Other approaches:

- require different programming paradigms
- Shared memory programming, eg. OpenMP
- Message Passing, e.g. MPI
- Semaphores
 - ...

Inter-Process Communication

Method	Short Description	Provided by (operating systems or other environments)
File	A record stored on disk, or a record synthesized on demand by a file server, which can be accessed by multiple processes.	Most operating systems
Communications file	A unique form of IPC in the late-1960s that most closely resembles Plan 9's 9P protocol	Dartmouth Time-Sharing System
Signal; also Asynchronous System Trap	A system message sent from one process to another, not usually used to transfer data but instead used to remotely command the partnered process.	Most operating systems
Socket	Data sent over a network interface, either to a different process on the same computer or to another computer on the network. Stream-oriented (TCP; data written through a socket requires formatting to preserve message boundaries) or more rarely message-oriented (UDP, SCTP).	Most operating systems
Unix domain socket	Similar to an internet socket, but all communication occurs within the kernel. Domain sockets use the file system as their address space. Processes reference a domain socket as an inode, and multiple processes can communicate with one socket	All POSIX operating systems and Windows 10 ^[3]
Message queue	A data stream similar to a socket, but which usually preserves message boundaries. Typically implemented by the operating system, they allow multiple processes to read and write to the message queue without being directly connected to each other.	Most operating systems
Anonymous pipe	A unidirectional data channel using standard input and output. Data written to the write-end of the pipe is buffered by the operating system until it is read from the read-end of the pipe. Two-way communication between processes can be achieved by using two pipes in opposite "directions".	All POSIX systems, Windows
Named pipe	A pipe that is treated like a file. Instead of using standard input and output as with an anonymous pipe, processes write to and read from a named pipe, as if it were a regular file.	All POSIX systems, Windows, AmigaOS 2.0+
Shared memory	Multiple processes are given access to the same block of memory, which creates a shared buffer for the processes to communicate with each other.	All POSIX systems, Windows
Message passing	Allows multiple programs to communicate using message queues and/or non-OS managed channels. Commonly used in concurrency models.	Used in LPC, RPC, RMI, and Mf paradigms, Java RMI, CORBA, COM, DDS, MSMQ, MailSlots, QNX, others
Memory- mapped file	A file mapped to RAM and can be modified by changing memory addresses directly instead of outputting to a stream. This shares the same benefits as a standard file.	All POSIX systems, Windows

 ${\sf SRC:\ https://en.wikipedia.org/wiki/Inter-process_communication}$

Pipes

Pipes

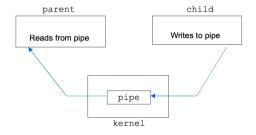
A pipe is a mechanism for interprocess communication data written to the pipe by one process can be read by another process.

The data is handled in a first-in, first-out (FIFO) order.

Neither pipes nor FIFO special files allow file positioning. Both reading and writing operations happen sequentially; reading from the beginning of the file and writing at the end.

Pipes

- Pipes are a one-way (half-duplex) communication channel
- Pipes are buffers managed by the OS
- Processes use low-level file descriptors for pipe operations



Recall: I/O mechanisms in C

- So far, we've used "File Pointers" (regular files):
 - You use a pointer to a file structure (FILE *) as handle to a file.
 - The file struct contains a file descriptor and a buffer.
 - Use for regular files

```
1 FILE *fp = fopen("my_file.txt", "w");
2 fprintf(fp, "Hello!\n");
3 fclose(fp);
```

- Now we need: File descriptors (low-level):
 - Each open file is identified by a small integer
 - Operations: open, close, read, write

File I/O with file descriptors

• int close(int fd):

Returns 0 on success, -1 on error

int open(const char *pathname, int flags);
Returns a file descriptor
Flags: O_RDONLY, O_WRONLY, or O_RDWR to open the file read-only, write-only, or read/write (and a few more, see man pages)
ssize_t read(int fd, void *buf, size_t count);
Returns # bytes read, 0 for EOF, -1 for error
ssize_t write(int fd, const void* buf, size_t count);
Returns # bytes actually written, -1 for error

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File I/O with file descriptors

```
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    Returns a file descriptor

    Flags: O_RDONLY, O_WRONLY, or O_RDWR to open the file read-only, write-only, or

       read/write (and a few more, see man pages)
• ssize_t read(int fd, void *buf, size_t count);

    Returns # bytes read, 0 for EOF, -1 for error

• ssize t write(int fd. const void* buf, size_t count);

    Returns # bytes actually written, -1 for error

• int close(int fd):

    Returns 0 on success. -1 on error

• Example (error checking ommitted...):
```

Handling Pipes with File Descriptors

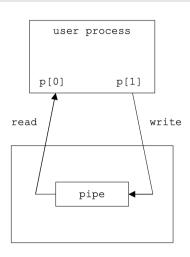
- How to open/create a pipe? int pipe(int pipefd[2]);
- pass a pointer to two integers (i.e. an array or a malloc of two ints) and pipe fills it with two newly opened FDs.
- Returns 0 on success, -1 on error

Handling Pipes with File Descriptors

- How to open/create a pipe? int pipe(int pipefd[2]);
- pass a pointer to two integers (i.e. an array or a malloc of two ints) and pipe fills it with two newly opened FDs.
- Returns 0 on success, -1 on error
- Example:

```
int p[2];
if ( pipe(p) == -1 ) {
    perror("pipe");
    exit(1);
}
```

- p[0] is now open for reading
- p[1] is now open for writing

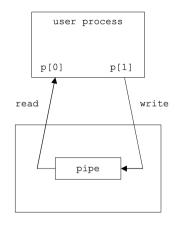


kernel

Example: Process talking to itself

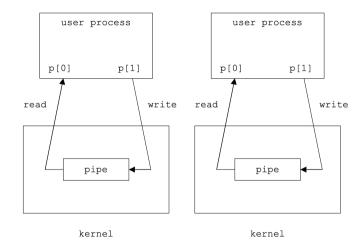
```
1 #include <unistd.h>
2 #include <stdio.h>
3 #include <stdlib.h>
5 #define MSG SIZE 13
7 int main(void) {
8
      char *msg = "hello, world\n";
      char buf[MSG_SIZE];
      int p[2];
      if (pipe(p) == -1) {
    perror("pipe");
14
    exit(1):
      write(p[1], msg, MSG_SIZE):
      read(p[0], buf, MSG_SIZE);
      write (STDOUT_FILENO, buf, MSG_SIZE);
      return 0:
```

First, write msg to the pipe Then, read from the pipe A process talking to itself is not very useful How do we get two processes talking to each other using pipes?

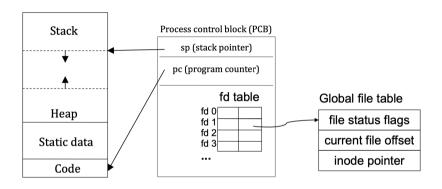


kernel

A process talking to itself is not very useful How do we get two processes talking to each other using pipes?



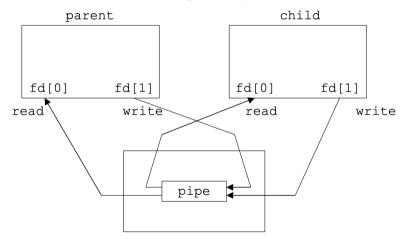
The OS manages file descriptors



- Per-process FD table has all open files of a process
- Global file table has all files open system-wide
- On fork, a child gets a copy of parent's FD table, so it will have same files open
- The FD table is preserved on exec

On fork, child gets copy of parent's file descriptors, including pipes

Qn: can we make the child send a message to the parent?



Example 1: Child talking to parent

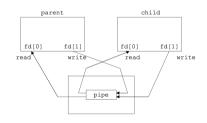
```
1 #include <unistd.h>
2 #include <stdio.h>
3 #include <stdlib.h>
5 #define MSG SIZE 13
7 int main(void) {
      char *msg = "hello, world\n";
      char buf[MSG_SIZE];
10
      int p[2];
11
    if (pipe(p) == -1) {
12
13
    perror("pipe");
14
    exit(1);
15
16
      if (fork() == 0) {
17
    // child writes
18
    write(p[1], msg, MSG_SIZE);
    } else {
    // parent read from pipe and prints
    read(p[0], buf, MSG_SIZE);
22
    write(STDOUT_FILENO, buf, MSG_SIZE);
23
24
25
26
      return 0:
27 }
```

Pipes and EOF

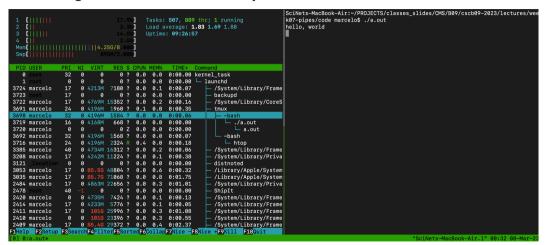
- What if the parent does not know beforehand when and how much data a child will write?
- If no writing end is open, read detects EOF and returns 0.
- read blocks until data is available in the pipe.
- All open pipes (and other FDs) are closed when a process exits.

Example 2: Child talking to parent

```
1 #include <unistd.h>
2 #include <stdio.h>
3 #include <stdlib.h>
5 #define BUF SIZE 4 // small
6 #define MSG SIZE 13
8 int main(void) {
      char *msg = "hello, world\n";
      char buf[BUF_SIZE];
      int p[2], nbytes:
11
      if (pipe(p) == -1) {
    perror("pipe"):
14
15
    exit(1);
16
      if (fork() == 0) {
18
    // child writes
    write(p[1], msg, MSG_SIZE);
     } else {
    // parent read from pipe and prints
    while ( (nbytes=read(p[0], buf, MSG_SIZE)) > 0 )
      write(STDOUT_FILENO. buf. MSG_SIZE):
24
26
27
      return 0:
28 }
```



Parent hangs, even after child exits. Why is EOF not detected?



Example 3: Child talking to parent

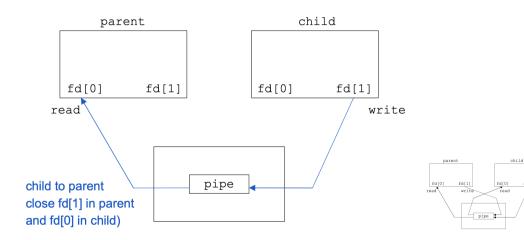
```
if (fork() == 0) {
1 #include <unistd.h>
                                                  // child writes
2 #include <stdio.h>
3 #include <stdlib.h>
                                                  write(p[1], msg, MSG_SIZE);
                                                   } else {
5 #define BUF_SIZE 4 // small
                                                  // parent needs to close its writing
6 #define MSG SIZE 13
                                                      end
                                                  close(p[1]);
8 int main(void) {
      char *msg = "hello, world\n";
                                                  // parent read from pipe and prints
      char buf[BUF SIZE]:
                                                  while ( (nbytes=read(p[0], buf,
                                             10
                                                      MSG_SIZE)) > 0
      int p[2], nbvtes:
12
                                                    write(STDOUT_FILENO, buf, MSG_SIZE)
                                             11
      if (pipe(p) == -1) {
13
    perror("pipe");
14
                                             12
    exit(1):
15
                                             13
16
                                                    return 0:
                                             14
                                             15 }
```

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Closing ends of pipes

- In general, each process will read or write a pipe (not both)
- Close the end you are not using
 - Before reading: close p[1]
 - Before writing: close p[0]

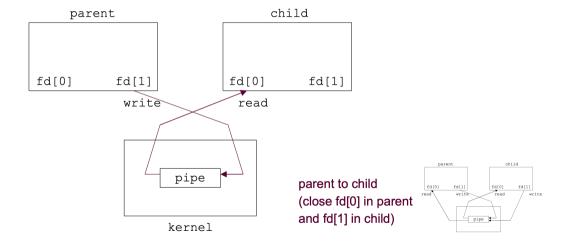
Direction of data flow?



fd[1]

write

Direction of data flow?



Pipes Communication-Types i

/* Self-comm. process */

Step 2 - Send a message to the pipe.

Step 3 - Retrieve the message from the pipe and write it to the standard output.

Step 4 - Send another message to the pipe.

Step 5 - Retrieve the message from the pipe and write it to the standard output.

Note - Retrieving messages can also be done after sending all messages.

/* Parent-Child comm. */

Step 2 - Create a child process.

Step 3 - Parent process writes to the pipe.

Step 4 - Child process retrieves the message from the pipe and writes it to the standard output.

Step 5 - Repeat step 3 and step 4 once

/* Two-way communication w/Pipes */

Step 1 - Create two pipes. First one is for the parent to write and child to read, say as pipe1. Second one is for the child to write and parent to read, say as pipe2.

Step 2 - Create a child process.

Step 3 - Close unwanted ends as only one end is needed for each communication.

Step 4 - Close unwanted ends in the parent process, read end of pipe1 and write end of pipe2.

Step 5 - Close the unwanted ends in the child process, write end of pipe1 and read end of pipe2.

Step 6 - Perform the communication as required.

Summary: Pipes and File Descriptors

- A forked child inherits file descriptors from its parent
- pipe() creates an OS internal system buffer and two file descriptors, one for reading and one for writing.
- After the pipe call, the parent and child should close the file descriptors for the opposite direction.

Summary: Pipes and File Descriptors

- A forked child inherits file descriptors from its parent
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- After the pipe call, the parent and child should close the file descriptors for the opposite direction.

```
ssize_t read(int fd, void *buf, size_t count);
  // Returns #bytes read, 0 for EOF, -1 for error

ssize_t write(int fd, const void *buf, size_t count);
  // Returns #bytes actually written, -1 for error

int close(int fd);
  // Returns 0 on success, -1 on error

int pipe(int pipefd[2]);
  // Returns 0 on success, -1 on error
```

References

References

- https: //www.gnu.org/software/libc/manual/html_node/Pipes-and-FIFOs.html
- https://man7.org/linux/man-pages/man7/pipe.7.html
- https://tldp.org/LDP/lpg/node11.html
- https://www.ibm.com/docs/en/aix/7.1?topic=io-working-pipes