Neural Networks

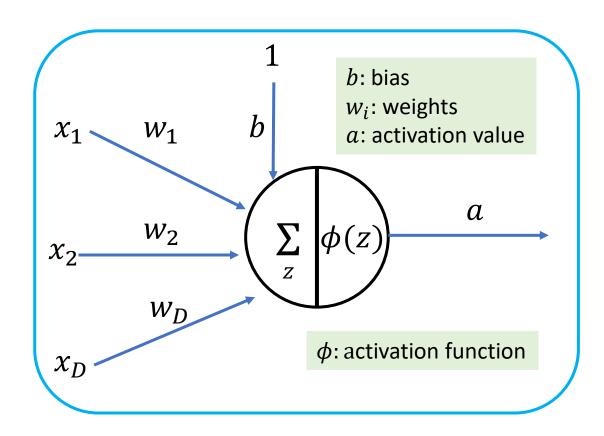
CSCC11 – Topic 5

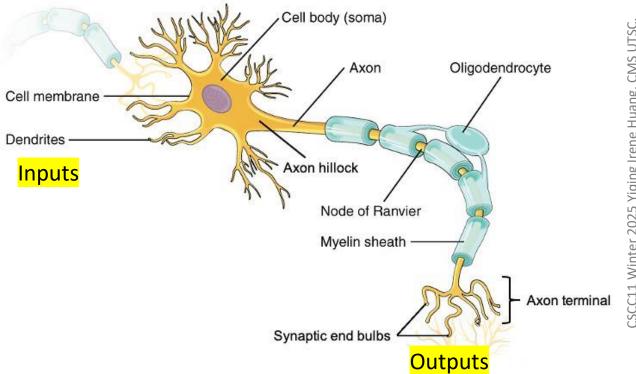


Learning Feature Mapping

- Feature engineering makes linear methods non linear by $\mathbf{x} \to \phi(\mathbf{x})$ mapping.
- We want to learn the feature mappings instead of manually crafting them.
- Neural networks, invented by Frank Rosenblatt in 1963, can be thought as a method to explicitly learn the feature map ϕ

Artificial Neuron





$$a = \phi(\sum_{j=1}^{D} w_j x_j + b) = \phi(\mathbf{w}^T \mathbf{x} + b)$$

Activation Function

 Sigmoid $\sigma(z) \equiv \frac{1}{1 + e^{-z}}$

ReLU: Rectified Linear Unit

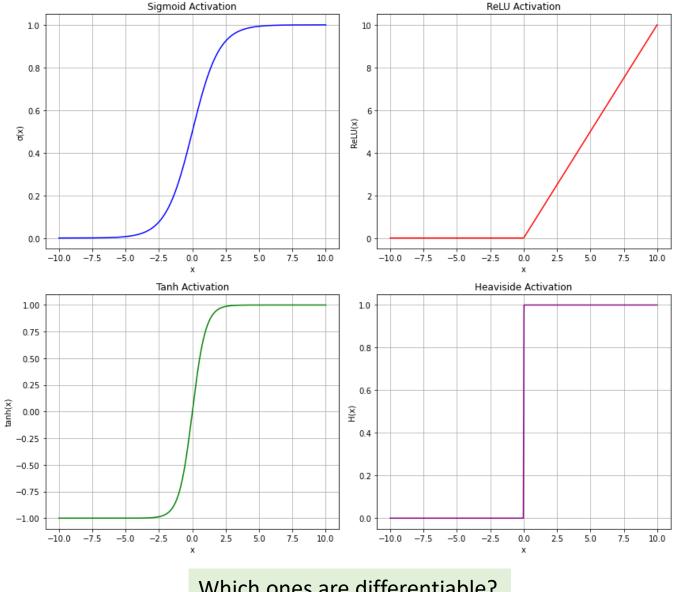
$$ReLU(z) \equiv max(z, 0)$$

Hyperbolic tangent

$$\tanh(z) \equiv \frac{e^z - e^{-z}}{e^z + e^{-z}}$$

Heaviside function

$$H(z) \equiv \begin{cases} 1, & \text{if } z \ge 0 \\ 0, & \text{if } z < 0 \end{cases}$$



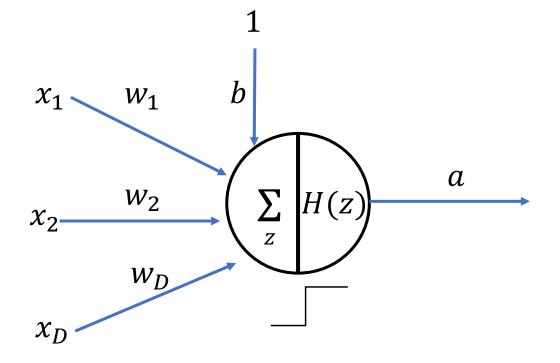
Which ones are differentiable?

CSCC11 Winter 2025 Yiqing Irene Huang, CMS UTSC.

Perceptron

- Theory was invented in 1958, realized in 1963 by Frank Rosenblatt
- A single neuron for binary classification
- Heaviside step function as the activation function.
- A Learning algorithm was created.

$$\hat{y} = \begin{cases} 1, & \text{if } \mathbf{w}^T \mathbf{x} + b \ge 0 \\ 0, & \text{if } \mathbf{w}^T \mathbf{x} + b < 0 \end{cases}$$



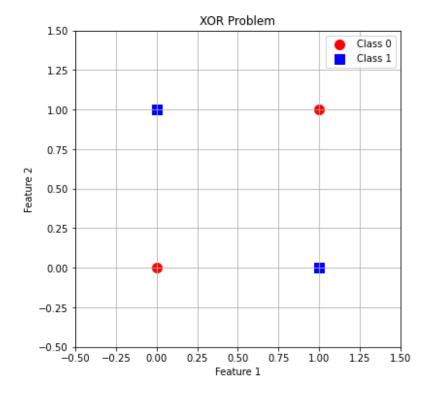
The XOR Problem

• In 1969, Minsky & Papert highlighted the limitations of the Perceptron, leading to a temporary decline in interest of NN.

• First Al winter: 1974-1980

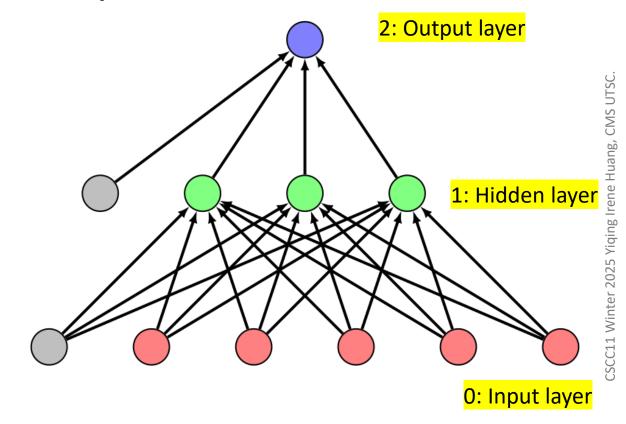
x_1	x_2	$y = x_1 \oplus x_2$
0	0	0
0	1	1
1	0	1
1	1	0

Linear decision boundary does not exist



Multi-layer Perceptron (MLP)

- Concept started in 1960s, before 1980s
 - No effective training algorithms
 - Single layer network was easy to implement and learn.
- 1980s: backpropagation algorithm by Rumelhart, Hinton, and Williams renewed research in MLP
- Single perceptron can learn AND, OR, NOT
- Stacking up layers of perceptrons to learn any binary function



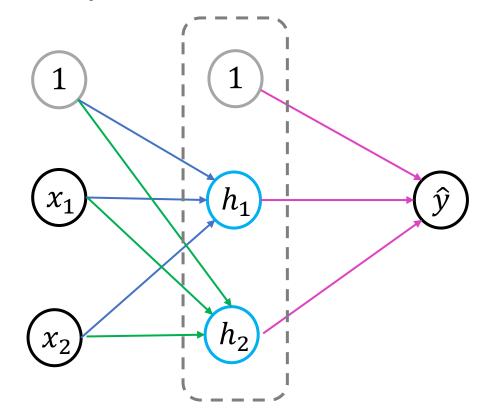
A 2-layer Neural Network
The input layer does not count as a layer
[Image Courtesy Wikipedia]

AND, OR and NOT

• Exercise: Design Perceptron to represent logic operators

XOR under MLP

• A 2-layer Neural Network to compute XOR



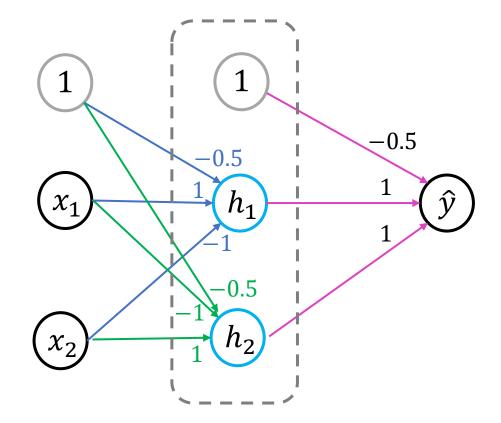
x_1	x_2	$y = x_1 \oplus x_2$
0	0	0
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Heaviside function

$$H(z) \equiv \begin{cases} 1, & \text{if } z \ge 0 \\ 0, & \text{if } z < 0 \end{cases}$$

XOR: a 2-layer NN Solution

$$x_1 \oplus x_2 = (x_1 \land \neg x_2) \lor (\neg x_1 \land x_2)$$



x_1	x_2	$y = x_1 \oplus x_2$
0	0	0
0	1	1
1	0	1
1	1	0

Heaviside function

$$H(z) \equiv \begin{cases} 1, & \text{if } z \ge 0 \\ 0, & \text{if } z < 0 \end{cases}$$

Universal Approximation Theorem

- A feedforward neural network with a single hidden layer containing a finite number of neurons can approximate any continuous function on compact subsets of \mathbb{R}^n , under some assumptions about the activation function (nonlinear).
 - Arbitrary width and bounded depth: 1989 by Cybenko and Hornik
 - Arbitrary depth and bounded width: 2017 by Lu et. al.
 - Bounded depth and width: 2022 by Maiorov and Pinkus
 - Two hidden layers are enough to approximate any functions.

Remarks

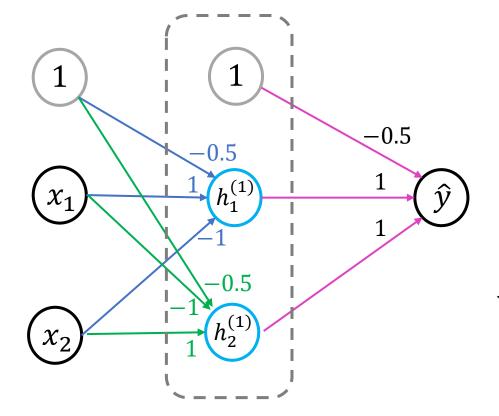
- It guarantees the representation power of neural networks for approximating virtually any continuous function to arbitrary precision
- It only states the existence, but does not provide a method to find it
- It does not address the learnability of the function or the computational efficiency of training

Changes to Revive NN

- ReLU activation function
 - The vanishing gradient problem
- GPU
 - Efficient matrix multiplication possible
- Stochastic Gradient Descent
- Rebranding
 - Deep Learning

XOR: a 2-layer NN Solution

$$x_1 \oplus x_2 = (x_1 \land \neg x_2) \lor (\neg x_1 \land x_2)$$



$$H(z) \equiv \begin{cases} 1, & \text{if } z \ge 0 \\ 0, & \text{if } z < 0 \end{cases}$$

$$\mathbf{w}_{1}^{(1)} = \begin{bmatrix} b_{1}^{(1)} \\ w_{1,1}^{(1)} \\ w_{1,2}^{(1)} \end{bmatrix}$$

$$x_1$$
 x_2
 $y = x_1 \oplus x_2$

 0
 0
 0

 0
 1
 1

 1
 0
 1

 1
 1
 0

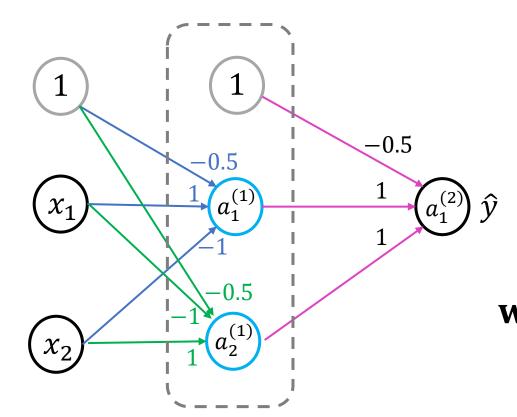
$$\mathbf{w}_{j}^{(l)}$$
 l^{th} layer j^{th} node

• Heaviside function
$$H(z) \equiv \begin{cases} 1, & \text{if } z \geq 0 \\ 0, & \text{if } z < 0 \end{cases} \qquad \mathbf{W}_{j}^{(l)} \quad l^{th} \text{ layer} \\ y^{th} \text{ node} \end{cases}$$
• We will be a provided by the property of th

$$\mathbf{W}^{(2)} = \begin{bmatrix} b_1^{(2)} & w_{1,1}^{(2)} & w_{1,2}^{(2)} \end{bmatrix}$$

XOR: a 2-layer NN Solution

$$x_1 \oplus x_2 = (x_1 \land \neg x_2) \lor (\neg x_1 \land x_2)$$



$$H(z) \equiv \begin{cases} 1, & \text{if } z \ge 0 \\ 0, & \text{if } z < 0 \end{cases}$$

$$x_1$$
 x_2
 $y = x_1 \oplus x_2$

 0
 0
 0

 0
 1
 1

 1
 0
 1

 1
 1
 0

$$\mathbf{W}_{j}^{(l)}$$
 l^{th} layer j^{th} node

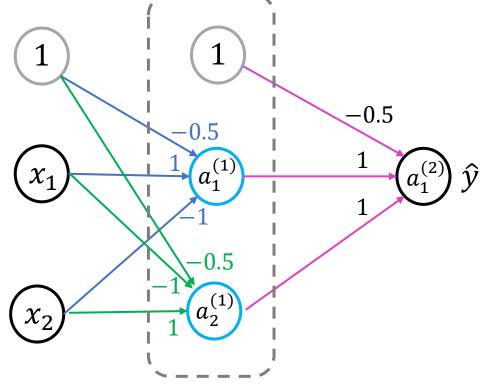
• Heaviside function
$$H(z) \equiv \begin{cases} 1, & \text{if } z \geq 0 \\ 0, & \text{if } z < 0 \end{cases} \qquad \mathbf{W}_{j}^{(l)} \quad \begin{array}{c} l^{th} \text{ layer} \\ j^{th} \text{ node} \end{array}$$

$$\mathbf{W}_{1}^{(1)} = \begin{bmatrix} b_{1}^{(1)} \\ w_{1,1}^{(1)} \\ w_{1,2}^{(1)} \end{bmatrix} \qquad \mathbf{W}^{(1)} = \begin{bmatrix} b_{1}^{(1)} & w_{1,1}^{(1)} & w_{1,2}^{(1)} \\ b_{2}^{(1)} & w_{2,1}^{(1)} & w_{2,2}^{(2)} \end{bmatrix}$$

$$\mathbf{W}^{(2)} = \begin{bmatrix} b_{1}^{(2)} & w_{1,1}^{(2)} & w_{1,2}^{(2)} \end{bmatrix}$$

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Weight Matrices

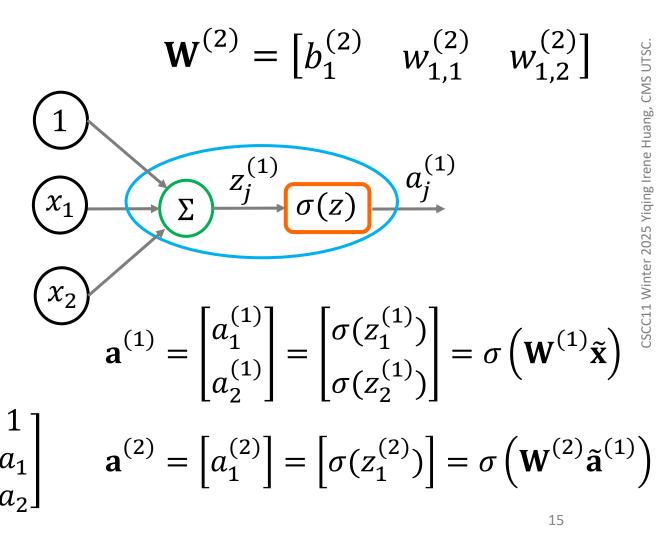


$$\Sigma$$
 $\sigma(z)$ α

$$\tilde{\mathbf{x}} = \begin{bmatrix} 1 \\ x_1 \\ x_2 \end{bmatrix}$$

$$\tilde{\mathbf{x}} = \begin{bmatrix} 1 \\ x_1 \\ x_2 \end{bmatrix} \quad \mathbf{W}^{(1)} = \begin{bmatrix} b_1^{(1)} & w_{1,1}^{(1)} & w_{1,2}^{(1)} \\ b_2^{(1)} & w_{2,1}^{(1)} & w_{2,2}^{(1)} \end{bmatrix}$$

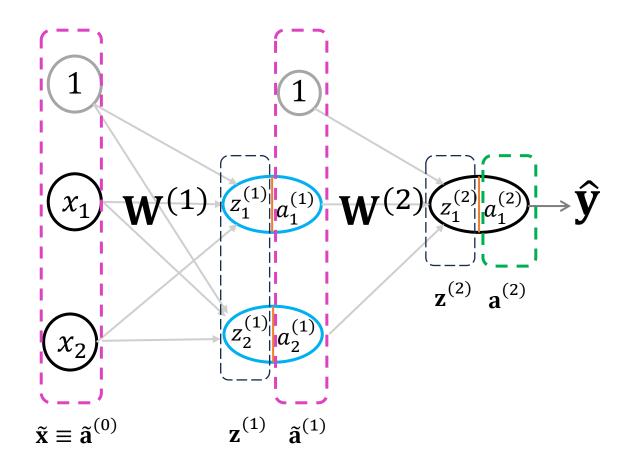
$$\mathbf{W}^{(2)} = \begin{bmatrix} b_1^{(2)} & w_{1,1}^{(2)} & w_{1,2}^{(2)} \end{bmatrix}$$



$$\mathbf{a}^{(1)} = \begin{bmatrix} a_1^{(1)} \\ a_2^{(1)} \end{bmatrix} = \begin{bmatrix} \sigma(z_1^{(1)}) \\ \sigma(z_2^{(1)}) \end{bmatrix} = \sigma\left(\mathbf{W}^{(1)}\tilde{\mathbf{x}}\right)$$

$$\tilde{\mathbf{a}} = \begin{bmatrix} 1 \\ a_1 \\ a_2 \end{bmatrix} \qquad \mathbf{a}^{(2)} = \left[a_1^{(2)} \right] = \left[\sigma(z_1^{(2)}) \right] = \sigma\left(\mathbf{W}^{(2)} \tilde{\mathbf{a}}^{(1)} \right)$$

Weight Matrices



$$\tilde{\sigma}(\mathbf{z}) \equiv \begin{bmatrix} 1 \\ \sigma(z_1) \\ \vdots \\ \sigma(z_m) \end{bmatrix} = \begin{bmatrix} 1 \\ \sigma(\mathbf{z}) \end{bmatrix}$$

$$\hat{\mathbf{y}} = \mathbf{a}^{(2)} = \begin{bmatrix} a_1^{(2)} \end{bmatrix} = \sigma(\mathbf{z}^{(2)})$$

$$= \sigma(\mathbf{W}^{(2)}\tilde{\mathbf{a}}^{(1)})$$

$$= \sigma(\mathbf{W}^{(2)}\tilde{\sigma}(\mathbf{W}^{(1)}\tilde{\mathbf{a}}^{(0)}))$$

$$= \sigma(\mathbf{W}^{(2)}\tilde{\sigma}(\mathbf{z}^{(1)}))$$
(2)

Learning Weights

- Define loss function $\mathcal{L}\left(\mathbf{y}_{k}, \hat{\mathbf{y}}_{k}; \left\{\mathbf{W}^{(l)}\right\}_{l=1:L}\right) \equiv \mathcal{L}_{k}\left(\left\{\mathbf{W}^{(l)}\right\}_{l=1:L}\right)$
- Cost function

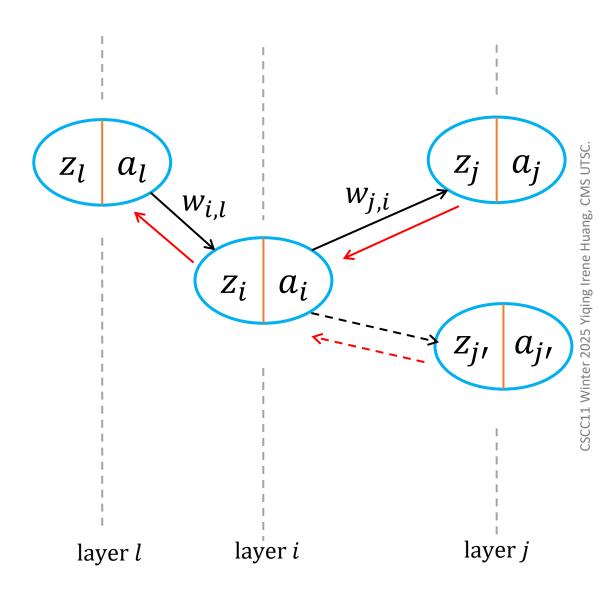
$$E\left(\{(\mathbf{y}_k, \hat{\mathbf{y}}_k)\}_{k=1:N}; \{\mathbf{W}^{(l)}\}_{l=1:L}\right) = c\sum_{k=1}^{N} \mathcal{L}_k\left(\{\mathbf{W}^{(l)}\}_{l=1:L}\right), \text{ e.g. } c = \frac{1}{N}$$

Gradient Descent

$$w_{j,i}^{(l)} \leftarrow w_{j,i}^{(l)} - \lambda \frac{\partial E}{\partial w_{j,i}^{(l)}}$$

$$\frac{\partial E}{\partial w_{j,i}^{(l)}} = \sum_{k=1}^{N} \frac{\partial \mathcal{L}_k \left(\left\{ \mathbf{W}^{(l)} \right\}_{l=1:L} \right)}{\partial w_{j,i}^{(l)}}$$

Backpropagation



Backpropagation

$$\frac{\partial \mathcal{L}}{\partial w_{i,l}} = \begin{bmatrix} \frac{\partial \mathcal{L}}{\partial z_i} \end{bmatrix} \times \begin{bmatrix} \frac{\partial z_i}{\partial w_{i,l}} \end{bmatrix}$$

$$\frac{\partial z_i}{\partial w_{i,l}} = \frac{\partial \sum_{l=1}^{m_l} w_{i,l} a_l}{\partial w_{i,l}} = a_l \qquad \frac{\partial z_i}{\partial a_l} = w_{i,l}$$

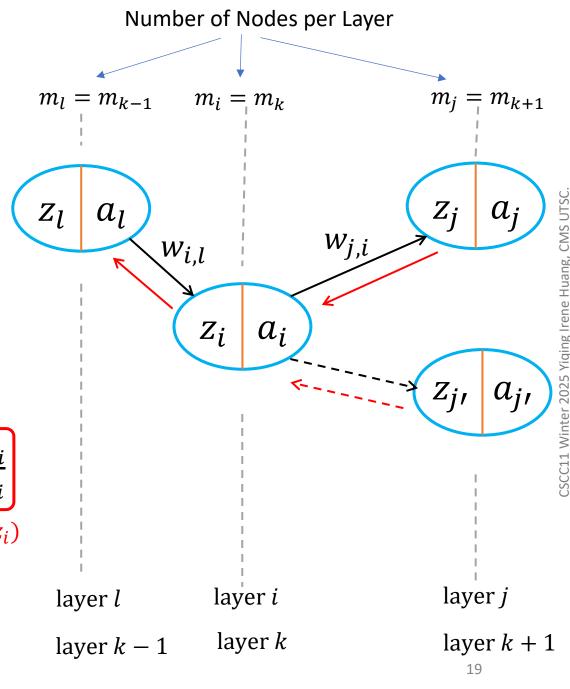
$$\delta_{i} = \frac{\partial \mathcal{L}}{\partial z_{i}} = \sum_{j=1}^{m_{j}} \frac{\partial \mathcal{L}}{\partial z_{j}} \times \frac{\partial z_{j}}{\partial z_{i}} = \sum_{j=1}^{m_{j}} \frac{\partial \mathcal{L}}{\partial z_{j}} \times \frac{\partial z_{j}}{\partial a_{i}} \times \frac{\partial a_{i}}{\partial z_{i}}$$

$$m_{i}$$

$$\delta_{i} \quad w_{j,i} \quad \sigma'(z_{i})$$

$$\delta_i = \sigma'(z_i) \sum_{j=1}^{m_j} \delta_j w_{j,i}$$

$$\delta_i^{(k)} = \sigma' \left(z_i^{(k)} \right) \sum_{j=1}^{m_{k+1}} \delta_j^{(k+1)} w_{j,i}^{(k+1)}$$



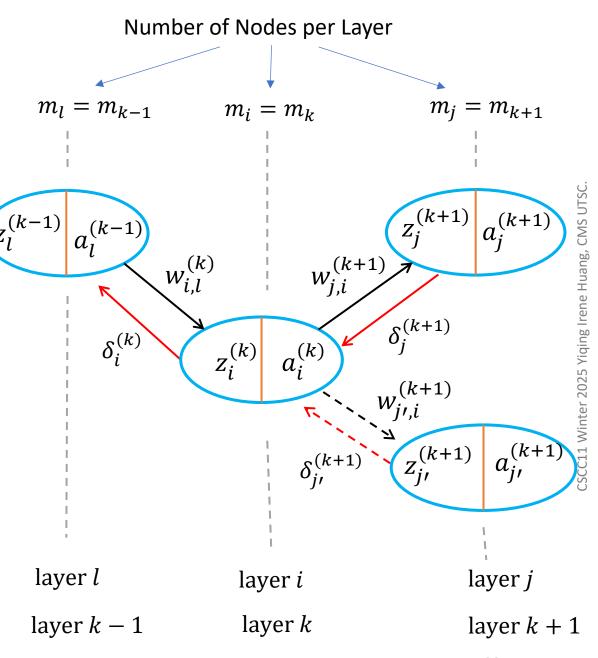
BackPropagation

$$\frac{\partial \mathcal{L}}{\partial w_{i,l}^{(k)}} = \delta_i^{(k)} a_l^{(k-1)}$$

$$\delta_i^{(k)} \equiv \frac{\partial \mathcal{L}}{\partial z_i^{(k)}} = \sigma' \left(z_i^{(k)} \right) \sum_{j=1}^{m_{k+1}} \delta_j^{(k+1)} w_{j,i}^{(k+1)}$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{W}^{(k)}} = \mathbf{\delta}^{(k)} \left(\tilde{\mathbf{a}}^{(k-1)} \right)^T \equiv \mathbf{\delta}^{(k)} \otimes \tilde{\mathbf{a}}^{(k-1)}$$

$$\boldsymbol{\delta}^{(k)} = ?$$



Backprop: Forward Pass

- 1. Random initialize the weights to small numbers (close to zeros)
- 2. Feed \mathbf{x} into the FFNN input layer and compute the outputs of all input neurons
- 3. Propagate the outputs of each hidden layer forward, one hidden layer at a time, and compute the outputs of all hidden neurons
- 4. Compute the final output neuron
- 5. Compute the loss function

Backprop: Backward Pass

- 1. Compute $\boldsymbol{\delta}^{(L)}$
- 2. Compute $\delta_i^{(k)} = \sigma'\left(z_i^{(k)}\right) \sum_{j=1}^{m_l} \delta_j^{(k+1)} w_{j,i}^{(k+1)}$ from k = L 1
- 3. Compute $\frac{\partial \mathcal{L}}{\partial \mathbf{W}^{(k-1)}}$
- 4. Update weights according to gradient based method

Acknowledgement

- Prof. David Fleet developed the course. He made his notes and courseware available to all of us.
- Prof. Francisco (Paco) Estrada shared his assignments and insights.
- Prof. Rawad A. Assi shared past assignments and advices.

Neural Networks Brief History

- •1943: McCulloch & Pitts introduce the first artificial neural networks to
- •1958: Rosenblatt develops the Perceptron, a basic learning algorithm.
- •1969: Minsky & Papert highlight the limitations of the Perceptron, leading to a temporary decline in interest.
- •1980s: Backpropagation is popularized (Rumelhart, Hinton & Williams), sparking renewed research in multi-layer networks.
- •1990s: Alternative methods (e.g., Support Vector Machines) gain prominence; neural networks face skepticism.
- •2000s: Advancements in computing power and big data lead to the resurgence of neural networks (deep learning begins).
- •2012: AlexNet's breakthrough on the ImageNet competition demonstrates the power of deep CNNs.
- •2010s 2020s: Explosion of deep learning applications with RNNs, LSTMs, GANs, and Transformers driving AI innovations.

BackPropagation

$$\frac{\partial \mathcal{L}}{\partial w_{i,h}} = \begin{bmatrix} \frac{\partial \mathcal{L}}{\partial z_i} \\ \frac{\partial \mathcal{L}}{\partial w_{i,h}} \end{bmatrix} \times \begin{bmatrix} \frac{\partial \mathcal{L}}{\partial w_{i,h}} \\ \frac{\partial \mathcal{L}}{\partial w_{i,h}} \end{bmatrix}$$

$$\frac{\partial z_i}{\partial w_{i,h}} = \frac{\partial \sum_{h=1}^{m_{l-1}} w_{i,h} a_h}{\partial w_{i,h}} = a_h \qquad \frac{\partial z_i}{\partial a_h} = w_{i,h}$$

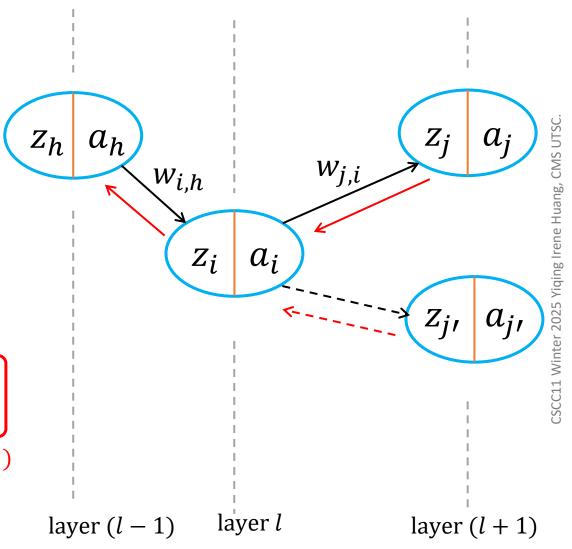
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$$m_{i}$$

$$\delta_{i} \quad w_{j,i} \quad \sigma'(z_{i})$$

$$\delta_i = \sigma'(z_i) \sum_{j=1}^{m_j} \delta_j w_{j,i}$$

$$\delta_i^{(l)} = \sigma' \left(z_i^{(l)} \right) \sum_{j=1}^{m_{l+1}} \delta_j^{(l+1)} w_{j,i}^{(l+1)}$$



BackPropagation

$$\frac{\partial \mathcal{L}}{\partial w_{i,l}^{(k)}} = \delta_i^{(k)} a_l^{(k-1)}$$

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$$\frac{\partial \mathcal{L}}{\partial \mathbf{W}^{(k)}} = \mathbf{\delta}^{(k)} \left(\tilde{\mathbf{a}}^{(k-1)} \right)^T \equiv \mathbf{\delta}^{(k)} \otimes \tilde{\mathbf{a}}^{(k-1)}$$

$$\boldsymbol{\delta}^{(k)} = \begin{bmatrix} \sigma'\left(z_1^{(k)}\right) & & \\ & \ddots & \\ & & \sigma'\left(z_k^{(k)}\right) \end{bmatrix} \left(\mathbf{W}[\mathbf{1}:]^{(k+1)}\right)^T \boldsymbol{\delta}^{(k+1)}$$
All rows after the first

laver *l*

Number of Nodes per Layer $m_l = m_{k-1}$ $m_i = m_{k+1}$ $m_i = m_k$ $a_i^{(k)}$ layer i layer *j* layer k-1layer *k* layer k+1