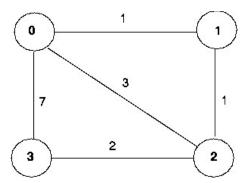
Programming Assignment 2: Distributed Asynchronous Distance Vector Routing

See text at end regarding the Java version of this assignment.

Overview

In this third programming assignment, you will be writing a ``distributed" set of procedures that implement a distributed asynchronous distance vector routing for the network shown below.



The Basic Assignment

The routines you will write For the basic part of the assignment, you are to write the following routines which will ``execute" asynchronously within the emulated environment that I have written for this assignment.

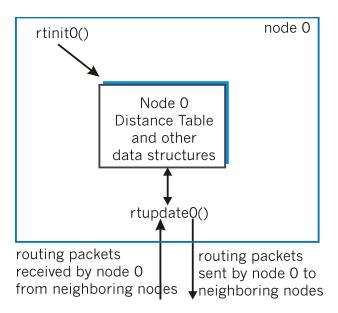
For node o, you will write the routines:

- rtinito() This routine will be called once at the beginning of the emulation. rtinito() has no arguments. It should initialize the distance table in node 0 to reflect the direct costs of 1, 3, and 7 to nodes 1, 2, and 3, respectively. In Figure 1, all links are bi-directional and the costs in both directions are identical. After initializing the distance table, and any other data structures needed by your node 0 routines, it should then send its directly-connected neighbors (in this case, 1, 2 and 3) the cost of it minimum cost paths to all other network nodes. This minimum cost information is sent to neighboring nodes in a *routing packet* by calling the routine tolayer2(), as described below. The format of the routing packet is also described below.
- rtupdate0 (struct rtpkt *rcvdpkt). This routine will be called when node o receives a routing packet that was sent to it by one if its directly connected neighbors. The parameter *rcvdpkt is a pointer to the packet that was received.

rtupdate0 () is the ``heart" of the distance vector algorithm. The values it receives in a routing packet from some other node i contain i's current shortest path costs to all other network nodes. rtupdate0 () uses these received values to update its own distance table (as specified by the distance vector algorithm). If its own minimum cost to another node changes as a result of the update, node 0 informs its directly connected neighbors of this change in minimum cost by sending them a routing packet. Recall that in the distance vector algorithm, only directly connected nodes will exchange routing packets. Thus nodes 1 and 2 will communicate with each other, but nodes 1 and 3 will node communicate with each other.

As we saw in class, the distance table inside each node is the principal data structure used by the distance vector algorithm. You will find it convenient to declare the distance table as a 4-by-4 array of int's, where entry [i,j] in the distance table in node o is node o's currently computed cost to node i via direct neighbor j. If o is not directly connected to j, you can ignore this entry. We will use the convention that the integer value 999 is ``infinity."

The figure below provides a conceptual view of the relationship of the procedures inside node o.



Similar routines are defined for nodes 1, 2 and 3. Thus, you will write 8 procedures in all: rtinit0(), rtinit1(), rtinit2(), rtinit3(), rtupdate0(), rtupdate1(), rtupdate2(), rtupdate3()

Software Interfaces

The procedures described above are the ones that you will write. I have written the following routines which can be called by your routines:

```
tolayer2 (struct rtpkt pkt2send)
where rtpkt is the following structure, which is already declared for you. The procedure tolayer2() is defined in the file prog3.c
```

Note that tolayer2() is passed a structure, not a pointer to a structure. printdt0()

will pretty print the distance table for node o. It is passed a pointer to a structure of type distance_table.printdt0() and the structure declaration for the node o distance table are declared in the file node0.c. Similar pretty-print routines are defined for you in the files node1.c, node2.c node3.c.

The simulated network environment

Your procedures rtinit(), rtinit(), rtinit(), rtinit(), rtinit(), and rtupdate(), rtupdate

When you compile your procedures and my procedures together and run the resulting program, you will be asked to specify only one value regarding the simulated network environment:

• **Tracing.** Setting a tracing value of 1 or 2 will print out useful information about what is going on inside the emulation (e.g., what's happening to packets and timers). A tracing value of 0 will turn this off. A tracing value greater than 2 will display all sorts of odd messages that are for my own emulator-debugging purposes.

A tracing value of 2 may be helpful to you in debugging your code. You should keep in mind that *real* implementors do not have underlying networks that provide such nice information about what is going to happen to their packets!

The Basic Assignment

You are to write the procedures rtinit0(), rtinit1(), rtinit2(), rtinit3() and rtupdate0(),

rtupdate1(), rtupdate2(), rtupdate3() which together will implement a distributed, asynchronous computation of the distance tables for the topology and costs shown in Figure 1.

You should put your procedures for nodes o through 3 in files called nodeo.c, node3.c. You are **NOT** allowed to declare any global variables that are visible outside of a given C file (e.g., any global variables you define in <code>node0.c</code>. may only be accessed inside <code>node0.c</code>). This is to force you to abide by the coding conventions that you would have to adopt is you were really running the procedures in four distinct nodes. To compile your routines: <code>cc_prog3.c_node0.c_node1.c_node2.c_node3.c</code>. Here are the links to the prototype version of the node files, and my emulator file, <code>prog3.c</code>:

```
http://gaia.cs.umass.edu/cs453/hwpa/prog3.chttp://gaia.cs.umass.edu/cs453/hwpa/node0.chttp://gaia.cs.umass.edu/cs453/hwpa/node1.chttp://gaia.cs.umass.edu/cs453/hwpa/node2.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/node3.chttp://gaia.cs.umass.edu/cs453/hwpa/pa/cs453/hwpa/pa/cs453/hwpa/pa/cs453/hwpa/pa/cs453/hwpa/pa/cs453/hwpa/pa/cs
```

This assignment can be completed on any machine supporting C. It makes no use of UNIX features.

As always, you should hand in a code listing, a design document (as described in the handout accompanying the first programming assignment), and sample output.

For your sample output, your procedures should print out a message whenever yourrtinit(), rtinit1(), rtinit2(), rtinit3() or rtupdate0(), rtupdate1(), rtupdate2(), rtupdate3() procedures are called, giving the time (available via my global variable clocktime). For rtupdate0(), rtupdate1(), rtupdate2(), rtupdate3() you should print the identity of the sender of the routing packet that is being passed to your routine, whether or not the distance table is updated, the contents of the distance table (you can use my pretty-print routines), and a description of any messages sent to neighboring nodes as a result of any distance table updates.

The sample output should be an output listing with a TRACE value of 2. Highlight the final distance table produced in each node. Your program will run until there are no more routing packets in-transit in the network, at which point my emulator will terminate.

JAVA version of Programming Assignment 3

The documentation above describes the project in detail. Here we provide a link to the code needed to do the assignment in JAVA. Make sure you understand the material above.

Here are the links to the JAVA code you'll need:

Entity.java, Entityo.java, Ent

You'll the write the constructors of Entityo.java, Entity1.java, Entity2.java, and Entity3.java which are analgous to rtinito(), rtinit1(), rtinit2() and rtinit3() in the C version. You will also need to write the update() methods for Entityo.java, Entity1.java, Entity2.java, and Entity3.java which are analgous to rtupdateo(), rtupdate1(), riupdate2() and rtupdate3() in the C version.

Note that the Java code will allow yu to hang yourself by sending incorrect packets via the toLayer2() method of NetworkSimulator. So please be extra careful there.