

AI EXPERIMENT 4 - Hill Climbing

0

Output :

```

PS D:\SEM-5\AI\EXPERIMENTS> python -u "d:\SEM-5\AI\EXPERIMENTS\hillCimbing.py"
Current State: [[], [], [], ['B', 'C', 'D', 'A']]
Heuristic value for [[], [], [], ['B', 'C', 'D', 'A']] is -6
Heuristic value for [['A'], [], [], ['B', 'C', 'D']] is -3
Child chosen for exploration: [['A'], [], [], ['B', 'C', 'D']]

Current State: [['A'], [], [], ['B', 'C', 'D']]
Heuristic value for [['A'], [], [], ['B', 'C', 'D']] is -3
Heuristic value for [[], ['A'], [], ['B', 'C', 'D']] is -3
Heuristic value for [[], [], ['A'], ['B', 'C', 'D']] is -3
Heuristic value for [[], [], [], ['B', 'C', 'D', 'A']] is -6
Heuristic value for [['A', 'D'], [], [], ['B', 'C']] is -2
Child chosen for exploration: [['A', 'D'], [], [], ['B', 'C']]

Current State: [['A', 'D'], [], [], ['B', 'C']]
Heuristic value for [['A', 'D'], [], [], ['B', 'C']] is -2
Heuristic value for [['A'], ['D'], [], ['B', 'C']] is -1
Child chosen for exploration: [['A'], ['D'], [], ['B', 'C']]

Current State: [['A'], ['D'], [], ['B', 'C']]
Heuristic value for [['A'], ['D'], [], ['B', 'C']] is -1
Heuristic value for [[], ['D', 'A'], [], ['B', 'C']] is -2
Heuristic value for [[], ['D'], ['A'], ['B', 'C']] is -1
Heuristic value for [[], ['D'], [], ['B', 'C', 'A']] is -3
Heuristic value for [['A', 'D'], [], [], ['B', 'C']] is -2
Heuristic value for [['A'], [], ['D'], ['B', 'C']] is -1
Heuristic value for [['A'], [], [], ['B', 'C', 'D']] is -3
Heuristic value for [['A', 'C'], ['D'], [], ['B']] is -1
Heuristic value for [['A'], ['D', 'C'], [], ['B']] is -1
Heuristic value for [['A'], ['D'], ['C'], ['B']] is 0
Child chosen for exploration: [['A'], ['D'], ['C'], ['B']]

```

```

Current State: [['A'], ['D'], ['C'], ['B']]
Heuristic value for [['A'], ['D'], ['C'], ['B']] is 0
Heuristic value for [[''], ['D'], ['A'], ['C'], ['B']] is -1
Heuristic value for [[''], ['D'], ['C'], ['A'], ['B']] is -1
Heuristic value for [[''], ['D'], ['C'], ['B'], ['A']] is -1
Heuristic value for [['A'], ['D'], [''], ['C'], ['B']] is -1
Heuristic value for [['A'], [''], ['C'], ['D'], ['B']] is -1
Heuristic value for [['A'], [''], ['C'], ['B'], ['D']] is -1
Heuristic value for [['A'], ['C'], ['D'], [''], ['B']] is -1
Heuristic value for [['A'], ['D'], ['C'], [''], ['B']] is -1
Heuristic value for [['A'], ['D'], [''], ['B'], ['C']] is -1
Heuristic value for [['A'], ['B'], ['D'], ['C'], ['']] is 1
Child chosen for exploration: [['A'], ['B'], ['D'], ['C'], ['']]

```

```

Current State: [['A', 'B'], ['D'], ['C'], ['']]
Heuristic value for [['A', 'B'], ['D'], ['C'], ['']] is 1
Heuristic value for [['A'], ['D'], ['B'], ['C'], ['']] is 1
Heuristic value for [['A'], ['D'], ['C'], ['B'], ['']] is 1
Heuristic value for [['A'], ['D'], ['C'], ['B']] is 0
Heuristic value for [['A', 'B'], ['D'], [''], ['C'], ['']] is -1
Heuristic value for [['A', 'B'], [''], ['C'], ['D'], ['']] is 0
Heuristic value for [['A', 'B'], [''], ['C'], ['D']] is 1
Heuristic value for [['A', 'B', 'C'], ['D'], [''], ['']] is 3
Child chosen for exploration: [['A', 'B', 'C'], ['D'], [''], ['']]

```

```

Current State: [['A', 'B', 'C'], ['D'], [''], ['']]
Heuristic value for [['A', 'B', 'C'], ['D'], [''], ['']] is 3
Heuristic value for [['A', 'B'], ['D'], ['C'], [''], ['']] is 0
Heuristic value for [['A', 'B'], ['D'], ['C'], ['']] is 1
Heuristic value for [['A', 'B'], ['D'], [''], ['C']] is 1
Heuristic value for [['A', 'B', 'C', 'D'], [''], [''], ['']] is 6
Child chosen for exploration: [['A', 'B', 'C', 'D'], [''], [''], ['']]

```

```

Current State: [['A', 'B', 'C', 'D'], [''], [''], ['']]
Heuristic value for [['A', 'B', 'C', 'D'], [''], [''], ['']] is 6
Heuristic value for [['A', 'B', 'C'], ['D'], [''], ['']] is 3
Heuristic value for [['A', 'B', 'C'], [''], ['D'], ['']] is 3
Heuristic value for [['A', 'B', 'C'], [''], [''], ['D']] is 3
No better heuristic value is obtained, declaring this as the goal state - [['A', 'B', 'C', 'D'], [''], [''], ['']]

```

```

PS D:\SEM 5\AI\EXPERIMENTS>

```

AI EXPERIMENT 5 - Genetic Algorithm

Output :

GENERATION 0					
Initial Population	X Value	Fitness Value(f(x))	Probability(Expected Count)	Actual Count	
000000	0	0	0.0	0	
111111	63	3969	1.8181	2	
101011	43	1849	0.847	1	
110110	54	2916	1.3358	1	
New Population 0					
Mate Pool	Mate	Crossover Points	New Population	x value	f(x)
111111	3	5	111110	62	3844
111111	2	5	111111	63	3969
101011	1	5	101011	43	1849
110110	0	5	110111	55	3025
GENERATION 1					
Initial Population	X Value	Fitness Value(f(x))	Probability(Expected Count)	Actual Count	
111110	62	3844	1.2122	1	
111111	63	3969	1.2517	1	
101011	43	1849	0.5831	1	
110111	55	3025	0.954	1	
New Population 1					
Mate Pool	Mate	Crossover Points	New Population	x value	f(x)
111110	3	1	110111	55	3025
111111	2	4	111111	63	3969
101011	1	4	101011	43	1849
110111	0	1	111110	62	3844
GENERATION 2					
Initial Population	X Value	Fitness Value(f(x))	Probability(Expected Count)	Actual Count	
110111	55	3025	0.954	1	
111111	63	3969	1.2517	1	
101011	43	1849	0.5831	1	
111110	62	3844	1.2122	1	
New Population 2					
Mate Pool	Mate	Crossover Points	New Population	x value	f(x)
110111	1	4	110111	55	3025
111111	0	4	111111	63	3969
101011	3	5	101010	42	1764
111110	2	5	111111	63	3969
GENERATION 3					
Initial Population	X Value	Fitness Value(f(x))	Probability(Expected Count)	Actual Count	
110111	55	3025	0.951	1	
111111	63	3969	1.2477	1	
101010	42	1764	0.5545	1	
111111	63	3969	1.2477	1	
New Population 3					
Mate Pool	Mate	Crossover Points	New Population	x value	f(x)
110111	3	3	110111	55	3025
111111	2	2	111010	58	3364
101010	1	2	101111	47	2209
111111	0	3	111111	63	3969

PS D:\SEM 5\AI\EXPERIMENTS>

PS D:\SEM 5\AI\EXPERIMENTS>

AI EXPERIMENT 6 - Perceptron Learning

Output :

```
PS D:\SEM-5\AI\EXPERIMENTS> python -u "d:\SEM-5\AI\EXPERIMENTS\perceptron.py"
```

```
Iteration 1
```

```
W 0 [-2.  1. -1.  0.7 -1.  1.  1.  4.  3. ]
W 1 [-3.  1. -1. -0.3 -1.  1.  0.  3.  2. ]
W 2 [-3.  1. -1. -0.3 -1.  1.  0.  3.  2. ]
W 3 [-4.  1. -1. -1.3 -1.  1. -1.  2.  1. ]
W 4 [-3.  1. -1. -0.3 -1.  2.  0.  3.  2. ]
W 5 [-3.  1. -1. -0.3 -1.  2.  0.  3.  2. ]
W 6 [-2.  1.  0.  0.7  0.  2.  1.  3.  3. ]
W 7 [-3.  1. -1. -0.3  0.  1.  0.  3.  2. ]
W 8 [-3.  1. -1. -0.3  0.  1.  0.  3.  2. ]
W 9 [-3.  1. -1. -0.3  0.  1.  0.  3.  2. ]
```

```
W after 1 epochs [-3.  1. -1. -0.3  0.  1.  0.  3.  2. ]
```

```
Iteration 2
```

```
W 0 [-3.  1. -1. -0.3  0.  1.  0.  3.  2. ]
W 1 [-4.  1. -1. -1.3  0.  1. -1.  2.  1. ]
W 2 [-3.  2. -1. -0.3  0.  1.  0.  3.  2. ]
W 3 [-4.  2. -1. -1.3  0.  1. -1.  2.  1. ]
W 4 [-3.  2. -1. -0.3  0.  2.  0.  3.  2. ]
W 5 [-3.  2. -1. -0.3  0.  2.  0.  3.  2. ]
W 6 [-2.  2.  0.  0.7  1.  2.  1.  3.  3. ]
W 7 [-3.  2. -1. -0.3  1.  1.  0.  3.  2. ]
W 8 [-3.  2. -1. -0.3  1.  1.  0.  3.  2. ]
W 9 [-4.  1. -2. -1.3  0.  0. -1.  3.  1. ]
```

```
W after 2 epochs [-4.  1. -2. -1.3  0.  0. -1.  3.  1. ]
```

```
Iteration 3
```

```
W 0 [-3.  1. -1. -1.3  0.  0.  0.  4.  2. ]
W 1 [-4.  1. -1. -2.3  0.  0. -1.  3.  1. ]
W 2 [-3.  2. -1. -1.3  0.  0.  0.  4.  2. ]
W 3 [-4.  2. -1. -2.3  0.  0. -1.  3.  1. ]
W 4 [-3.  2. -1. -1.3  0.  1.  0.  4.  2. ]
W 5 [-3.  2. -1. -1.3  0.  1.  0.  4.  2. ]
W 6 [-2.  2.  0. -0.3  1.  1.  1.  4.  3. ]
W 7 [-3.  2. -1. -1.3  1.  0.  0.  4.  2. ]
W 8 [-3.  2. -1. -1.3  1.  0.  0.  4.  2. ]
W 9 [-3.  2. -1. -1.3  1.  0.  0.  4.  2. ]
```

```

W after 3 epochs [-3.  2. -1. -1.3 1.  0.  0.  4.  2. ]
Iteration 4
W 0 [-3.  2. -1. -1.3 1.  0.  0.  4.  2. ]
W 1 [-4.  2. -1. -2.3 1.  0. -1.  3.  1. ]
W 2 [-3.  3. -1. -1.3 1.  0.  0.  4.  2. ]
W 3 [-4.  3. -1. -2.3 1.  0. -1.  3.  1. ]
W 4 [-3.  3. -1. -1.3 1.  1.  0.  4.  2. ]
W 5 [-3.  3. -1. -1.3 1.  1.  0.  4.  2. ]
W 6 [-2.  3.  0. -0.3 2.  1.  1.  4.  3. ]
W 7 [-3.  3. -1. -1.3 2.  0.  0.  4.  2. ]
W 8 [-3.  3. -1. -1.3 2.  0.  0.  4.  2. ]
W 9 [-4.  2. -2. -2.3 1. -1. -1.  4.  1. ]

```

```

W after 4 epochs [-4.  2. -2. -2.3 1. -1. -1.  4.  1. ]
Iteration 5
W 0 [-3.  2. -1. -2.3 1. -1.  0.  5.  2. ]
W 1 [-4.  2. -1. -3.3 1. -1. -1.  4.  1. ]
W 2 [-3.  3. -1. -2.3 1. -1.  0.  5.  2. ]
W 3 [-4.  3. -1. -3.3 1. -1. -1.  4.  1. ]
W 4 [-3.  3. -1. -2.3 1.  0.  0.  5.  2. ]
W 5 [-3.  3. -1. -2.3 1.  0.  0.  5.  2. ]
W 6 [-2.  3.  0. -1.3 2.  0.  1.  5.  3. ]
W 7 [-3.  3. -1. -2.3 2. -1.  0.  5.  2. ]
W 8 [-3.  3. -1. -2.3 2. -1.  0.  5.  2. ]
W 9 [-3.  3. -1. -2.3 2. -1.  0.  5.  2. ]

```

```

W after 5 epochs [-3.  3. -1. -2.3 2. -1.  0.  5.  2. ]
Iteration 6
W 0 [-3.  3. -1. -2.3 2. -1.  0.  5.  2. ]
W 1 [-4.  3. -1. -3.3 2. -1. -1.  4.  1. ]
W 2 [-3.  4. -1. -2.3 2. -1.  0.  5.  2. ]
W 3 [-4.  4. -1. -3.3 2. -1. -1.  4.  1. ]
W 4 [-3.  4. -1. -2.3 2.  0.  0.  5.  2. ]
W 5 [-3.  4. -1. -2.3 2.  0.  0.  5.  2. ]
W 6 [-2.  4.  0. -1.3 3.  0.  1.  5.  3. ]
W 7 [-3.  4. -1. -2.3 3. -1.  0.  5.  2. ]
W 8 [-3.  4. -1. -2.3 3. -1.  0.  5.  2. ]
W 9 [-4.  3. -2. -3.3 2. -2. -1.  5.  1. ]

```

```

W after 6 epochs [-4.  3. -2. -3.3 2. -2. -1.  5.  1. ]
Final W after 6 epochs:
[-4.  3. -2. -3.3 2. -2. -1.  5.  1. ]
Output for test input [1, 0, 1, 1, 0, 0, 1, 1, 0]: 0
Output for test input [1, 0, 0, 1, 1, -1, 1, 1, 1]: 1
PS D:\SEM-5\AI\EXPERIMENTS>

```

AI - EXPERIMENT 7 - Family Tree in PROLOG

Output :

```
% c:/users/jsidd/dropbox/pc/desktop/exp7 compiled 0.00 sec, 0 clauses
|
|   parent(X,luffy).
false.

?-
|   parent(X,zoro).
X = nami ,

?-
|   mother(X,Y).
X = nami ,
Y = zoro ,

?- haschild(X).
X = nami ,

?- sister(X,Y).
X = hancock ,
Y = otama ■
```


AI EXPERIMENT 8 - AI based game

Output :

```
PS D:\SEM-5\AI\EXPERIMENTS> python -u "d:\SEM-5\AI\EXPERIMENTS\minesweeper.py"
Instructions:
1. Enter row and column number to select a cell, Example "2 3"
2. In order to flag a mine, enter F after row and column numbers, Example "2 3 F"
```

MINESWEEPER

	1	2	3	4
1				
2				
3				
4				

```
Enter row number followed by space and column number = 2 2
'clear' is not recognized as an internal or external command,
operable program or batch file.
```

MINESWEEPER

	1	2	3	4
1				
2		2		
3				
4				

```
Enter row number followed by space and column number = 4 4
```

MINESWEEPER

	1	2	3	4
1				
2		2		
3				
4				1

Enter row number followed by space and column number = 3 2
'clear' is not recognized as an internal or external command,
operable program or batch file.

MINESWEEPER

	1	2	3	4
1				
2		2		
3		4		
4				1

Enter row number followed by space and column number = 1 4
'clear' is not recognized as an internal or external command,
operable program or batch file.

MINESWEEPER

	1	2	3	4
1		1	0	0
2		2	0	0
3		4	2	1
4				1

Enter row number followed by space and column number = 4 1 F
'clear' is not recognized as an internal or external command,
operable program or batch file.
Flag set

MINESWEEPER

	1	2	3	4
1		1	0	0
2		2	0	0
3		4	2	1
4	F			1

Enter row number followed by space and column number = 4 2 F
'clear' is not recognized as an internal or external command,
operable program or batch file.
Flag set

MINESWEEPER

	1	2	3	4
1		1	0	0
2		2	0	0
3		4	2	1
4	F	F		1

Enter row number followed by space and column number = 4 3 F
 'clear' is not recognized as an internal or external command,
 operable program or batch file.
 Flag set

MINESWEEPER

	1	2	3	4
1		1	0	0
2		2	0	0
3		4	2	1
4	F	F	F	1

Enter row number followed by space and column number = 1 1 F
 'clear' is not recognized as an internal or external command,
 operable program or batch file.
 Flag set

MINESWEEPER

	1	2	3	4
1	F	1	0	0
2		2	0	0
3		4	2	1
4	F	F	F	1

Enter row number followed by space and column number = 2 1 F
 'clear' is not recognized as an internal or external command,
 operable program or batch file.
 Flags finished

MINESWEEPER

	1	2	3	4
1	F	1	0	0
2		2	0	0
3		4	2	1
4	F	F	F	1

Enter row number followed by space and column number = 2 1

MINESWEEPER

	1	2	3	4
1	F	1	0	0
2	M	2	0	0
3	M	4	2	1
4	F	M	M	1

Landed on a mine. GAME OVER!!!!
PS D:\SEM-5\AI\EXPERIMENTS>

AI EXPERIMENT 9 - Rule Based Expert System

Output :

```
PS D:\SEM-5\AI\EXPERIMENTS> python -u "d:\SEM-5\AI\EXPERIMENTS\EXP9.py"
```

```
Total Order Plan for Homemade Pizza:
```

```
Buy Pizza Dough
```

```
Preheat Oven
```

```
Roll Out Dough
```

```
Spread Pizza Sauce
```

```
Grate Cheese
```

```
Add Cheese to Dough
```

```
Chop Vegetables
```

```
Add Vegetables to Pizza
```

```
Bake Pizza
```

```
PS D:\SEM-5\AI\EXPERIMENTS> █
```