

# Building Neural Networks for Deep Learning Application

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Networks

Applications

PyTorch

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Summary

# CARC OnDemand

Web Address: <https://carc-ondemand.usc.edu>

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## User Guides

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## Getting Started with CARC OnDemand

The CARC OnDemand service is an online access point that provides users with web access to their CARC /home, /project, and /scratch directories and to the Discovery and Endeavour HPC clusters. OnDemand offers:

- Easy file management
- Command line shell access
- Slurm job management
- Access to interactive applications, including Jupyter notebooks and RStudio Server

OnDemand is available to all CARC users. To access OnDemand, you must belong to an active project in the [CARC User Portal](#).

[Intro to CARC OnDemand video](#)[Log in to CARC OnDemand](#)

Note: We recommend using OnDemand in a private browser to avoid potential permissions issues related to your browser's cache. If you're using a private browser and still encounter permissions issues, please [submit a help ticket](#).

[CARC OnDemand](#)[Files](#)[Jobs](#)[Clusters](#)[Interactive Apps](#)[My Interactive Sessions](#)[Help](#)[Logged in as haoji](#)[Log Out](#)

Advanced Research Computing  
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OnDemand provides an integrated, single access point for all of your HPC resources.

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OnDemand version: v1.8.18

# Using Anaconda on CARC

Anaconda: package and environment manager primarily used for open-source data science packages for the Python and R programming languages.

## Using Anaconda

**Anaconda** is a package and environment manager primarily used for open-source data science packages for the Python and R programming languages. It also supports other programming languages like C, C++, FORTRAN, Java, Scala, Ruby, and Lua.

### Using Anaconda on CARC systems

Begin by logging in. You can find instructions for this in the [Getting Started with Discovery](#) or [Getting Started with Endeavour](#) user guides.

To use Anaconda, first load the corresponding module:

```
module purge
module load conda
```

This module is based on the minimal Miniconda installer. Included in all versions of Anaconda, **Conda** is the package and environment manager that installs, runs, and updates packages and their dependencies. This module also provides **Mamba**, which is a drop-in replacement for most **conda** commands that enables faster package solving, downloading, and installing.

The next step is to initialize your shell to use Conda and Mamba:

```
mamba init bash
source ~/.bashrc
```

This modifies your `~/.bashrc` file so that Conda and Mamba are ready to use every time you log in (without needing to load the module).

If you want a newer version of Conda or Mamba than what is available in the module, you can also install them into one of your directories. We recommend installing either **mambaforge** or **Miniconda**.

Conda can also be configured with various options. Read more about Conda configuration [here](#).

### Installing Conda environments and packages

<https://www.carc.usc.edu/user-information/user-guides/software-and-programming/anaconda>

# Using Anaconda on CARC

## INSTALL PYTORCH

Select your preferences and run the install command. Stable represents the most currently tested and supported version of PyTorch. This should be suitable for many users. Preview is available if you want the latest, not fully tested and supported, 1.12 builds that are generated nightly. Please ensure that you have **met the prerequisites below (e.g., numpy)**, depending on your package manager. Anaconda is our recommended package manager since it installs all dependencies. You can also [install previous versions of PyTorch](#). Note that LibTorch is only available for C++.

Additional support or warranty for some PyTorch Stable and LTS binaries are available through the [PyTorch Enterprise Support Program](#).

PyTorch Build	Stable (1.11.0)		Preview (Nightly)		LTS (1.8.2)	
Your OS	Linux		Mac		Windows	
Package	Conda	Pip		LibTorch		Source
Language	Python			C++ / Java		
Compute Platform	CUDA 10.2	CUDA 11.3		ROCm 4.2 (beta)		CPU
Run this Command:	conda install pytorch torchvision torchaudio cudatoolkit=11.3 -c pytorch					

<https://pytorch.org>

# Creating Jupyter Kernel

A **Jupyter kernel** is a programming language-specific process that executes the code contained in a Jupyter notebook.

## User Guides

HPC Basics

Data Management

Software and Programming

Software Module System

Building Code With CMake

Using MPI

Using GPUs

Using Julia

Using Python

Using Anaconda

Using R

Using Stata

Using MATLAB

Using Rust

Using Launcher

Using Singularity

Using Tmux

Installing Jupyter Kernels

Project and Allocation

Management

Hybrid Cloud Computing

Secure Computing

## Installing Jupyter Kernels

This user guide provides instructions for installing Jupyter kernels when using **CARC OnDemand**. For more information about OnDemand and using Jupyter notebooks, see the **Getting Started with CARC OnDemand user guide**.

A **Jupyter kernel** is a programming language-specific process that executes the code contained in a Jupyter notebook. The following provides installation instructions for a few popular Jupyter kernels, which will be installed in your home directory at `~/local/share/jupyter/kernels`. Install the kernels when logged in to CARC systems before accessing them via the Jupyter OnDemand interactive app. To learn more about installing software on CARC systems using the software module system, see the **Software Module System user guide**.

When installing kernels, make sure to use descriptive names in order to distinguish among them. Once installed, when launching Jupyter on OnDemand, the kernels will show up on a Launcher tab (File > New Launcher) and when selecting kernels through other methods.

Many software kernels are available for use with Jupyter. See a full list here:  
<https://github.com/jupyter/jupyter/wiki/Jupyter-kernels>.

### Python

The default kernel is for Python 3.9.2, and this is ready to be used when Jupyter is launched. To use other versions of Python, enter a set of commands like the following:

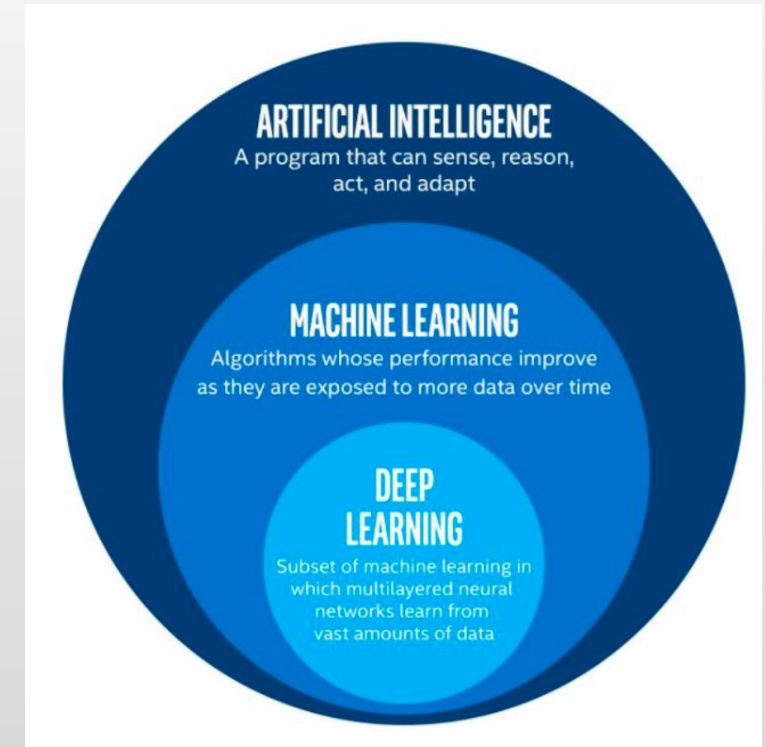
```
module load usc python/<version>
python -m ipykernel install --user --name py376 --display-name "Python 3.7.6"
```

<https://www.carc.usc.edu/user-information/user-guides/software-and-programming/jupyter-kernels>

# Introduction to Deep Learning

**Deep Learning:** subfield of traditional machine learning

- Inspired by the structure and function of the brain:  
Artificial Neural Networks
- Computer vision: Tesla recognizing items on a street
- Text Generation: An algorithm trained to create a new Shakespeare piece
- Speech recognition
- Computer Games: AlphaGo

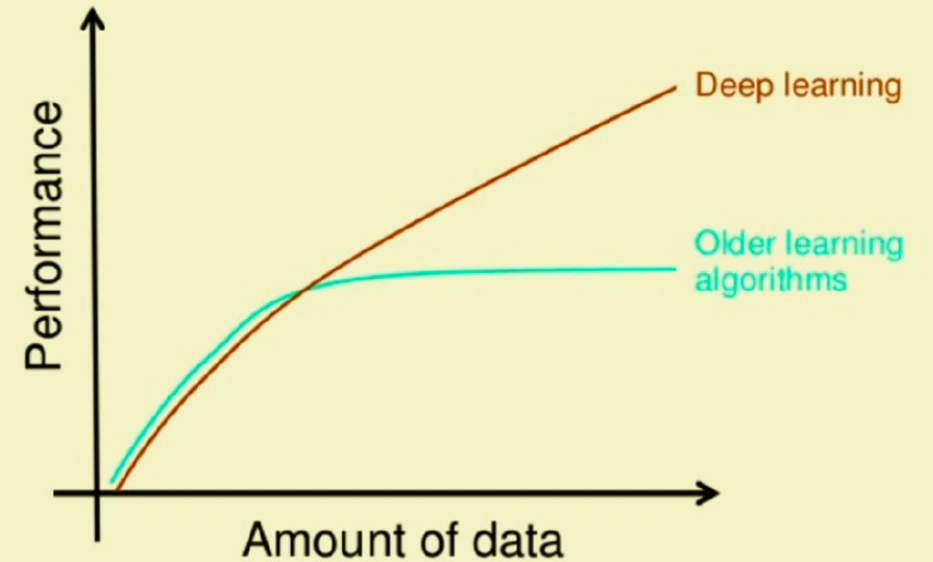


# Introduction to Deep Learning

## Why Deep Learning so hot recently?

- Performs better with larger amounts of data
- Requires strong computation units such as GPU's
- Data Storage

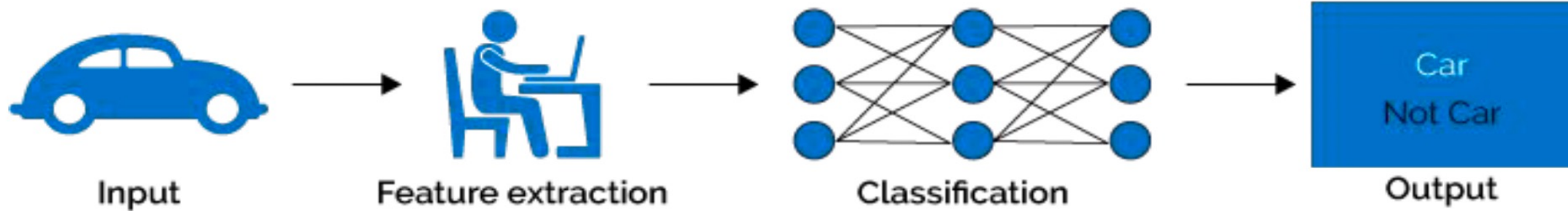
### Why deep learning



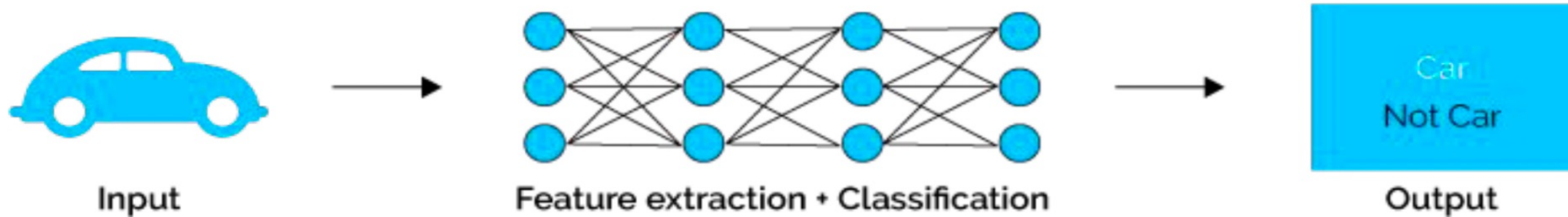


# Introduction to Deep Learning

## Machine Learning

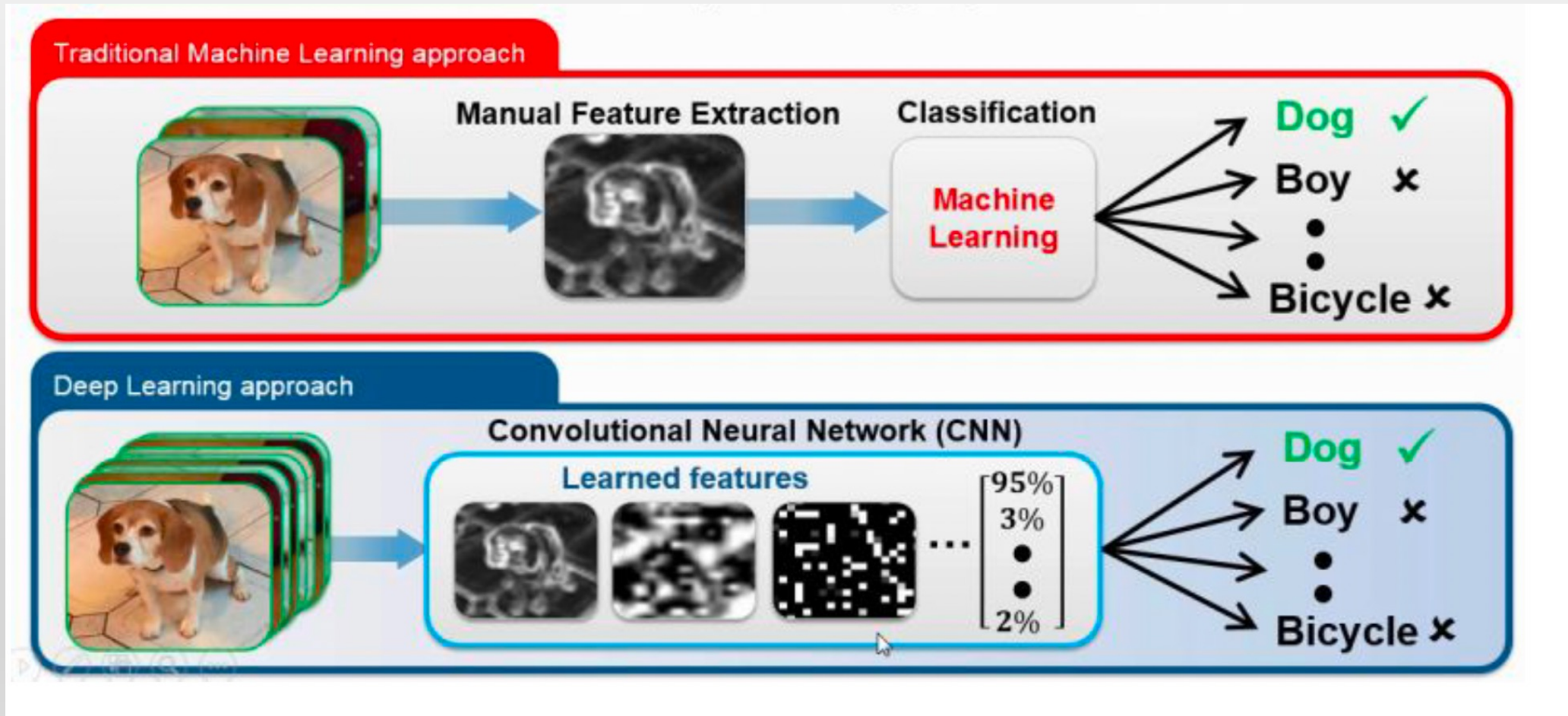


## Deep Learning

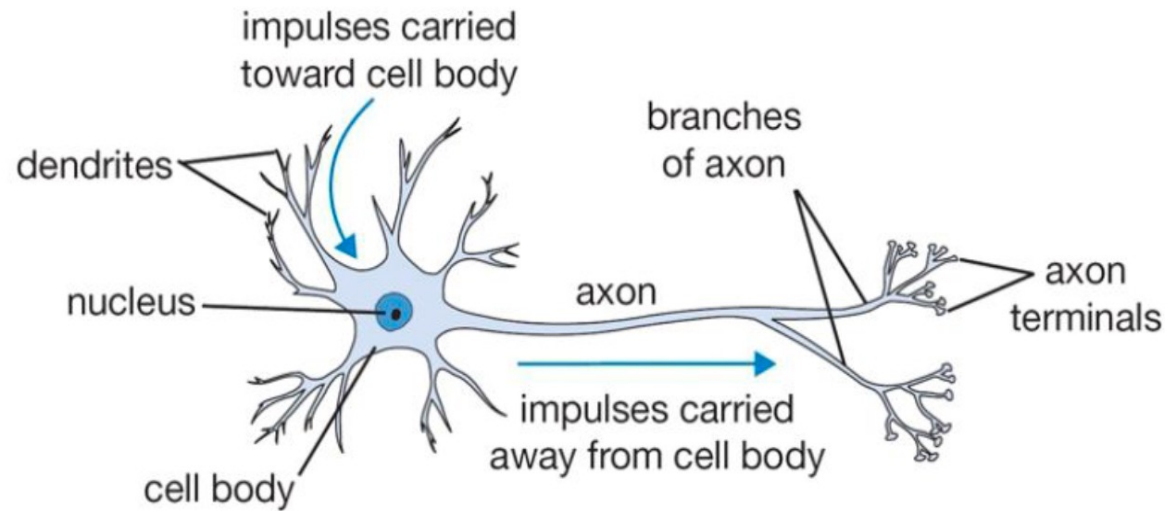


# Introduction to Deep Learning

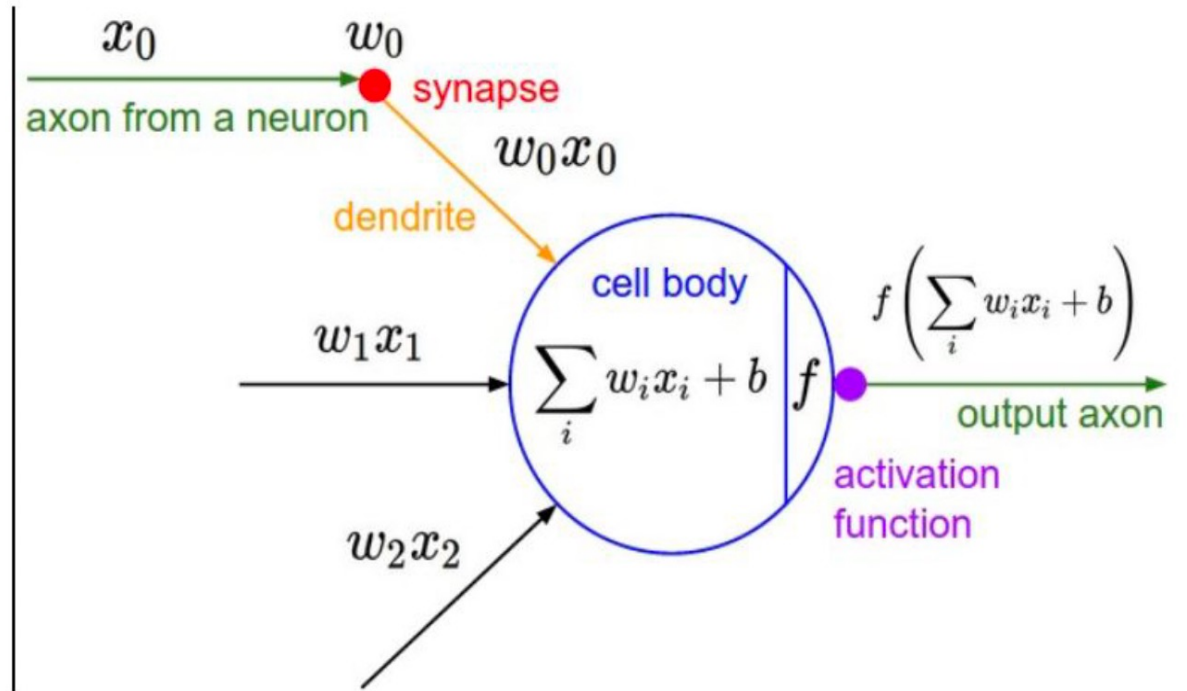
Deep Learning is a machine learning technique that can learn useful representations or features directly from images, text and sound



# Neural Networks



biological neuron

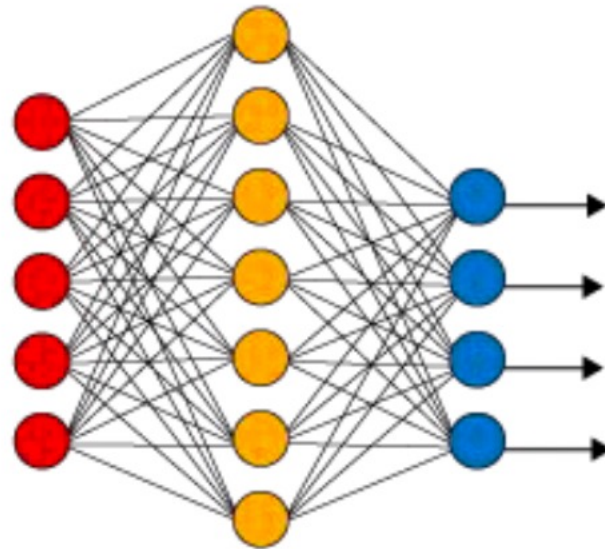


artificial neural networks

# Neural Networks

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## Simple Neural Network

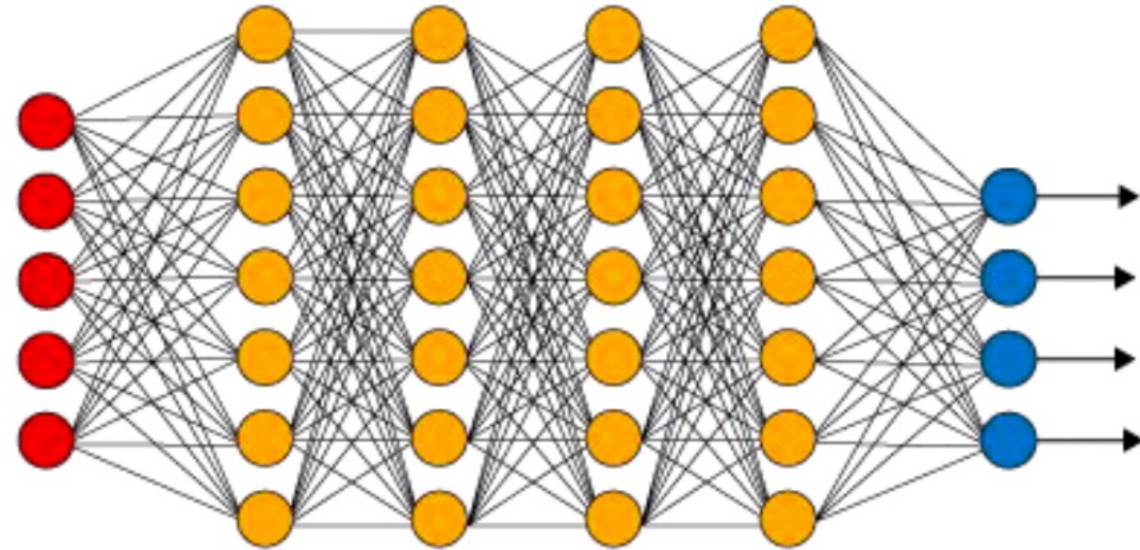


● Input Layer

● Hidden Layer

● Output Layer

## Deep Learning Neural Network



A neural network (NN) has 3 types of layers:  
Input layer Hidden layer Output layer

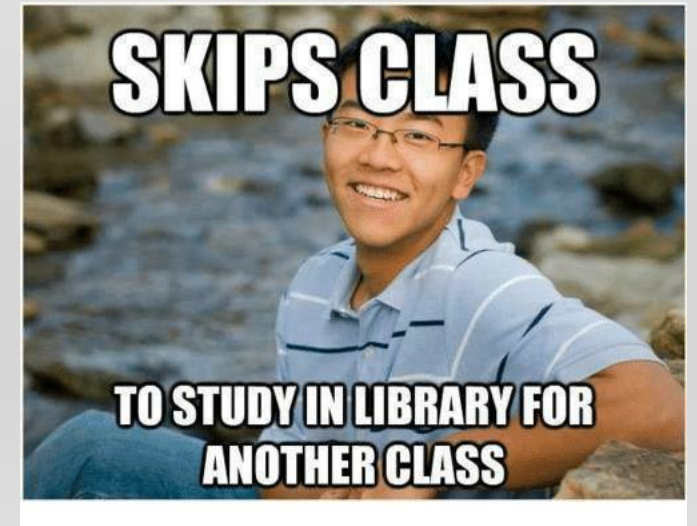
Deep neural networks (DNN) usually has more hidden layers  
Still has same 3 types of layers



# Building Neural Networks

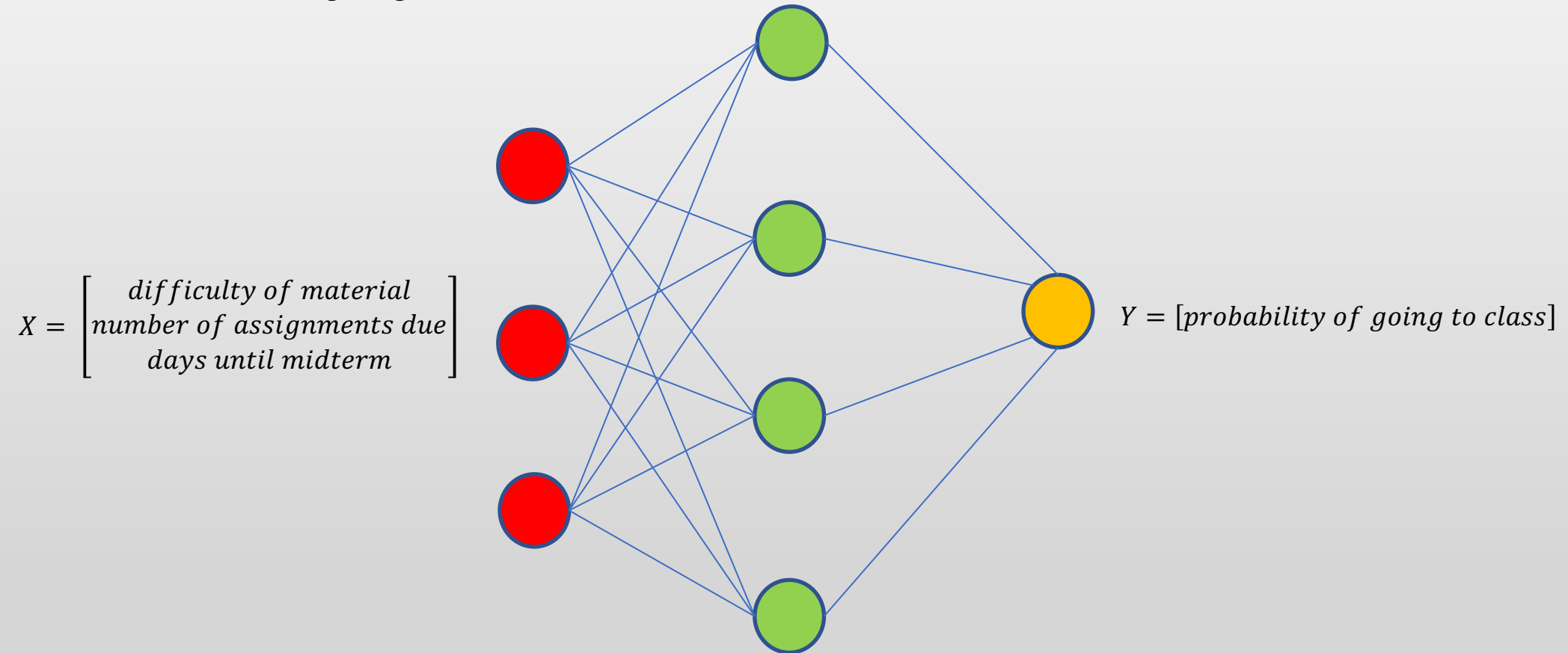
Task: Predict if it worth going to class or not

$$X = \begin{bmatrix} \text{difficulty of material} \\ \text{number of assignments due} \\ \text{days until midterm} \end{bmatrix} \quad Y = [\text{probability of going to class}]$$



# Building Neural Networks

Task: Predict if it worth going to class or not

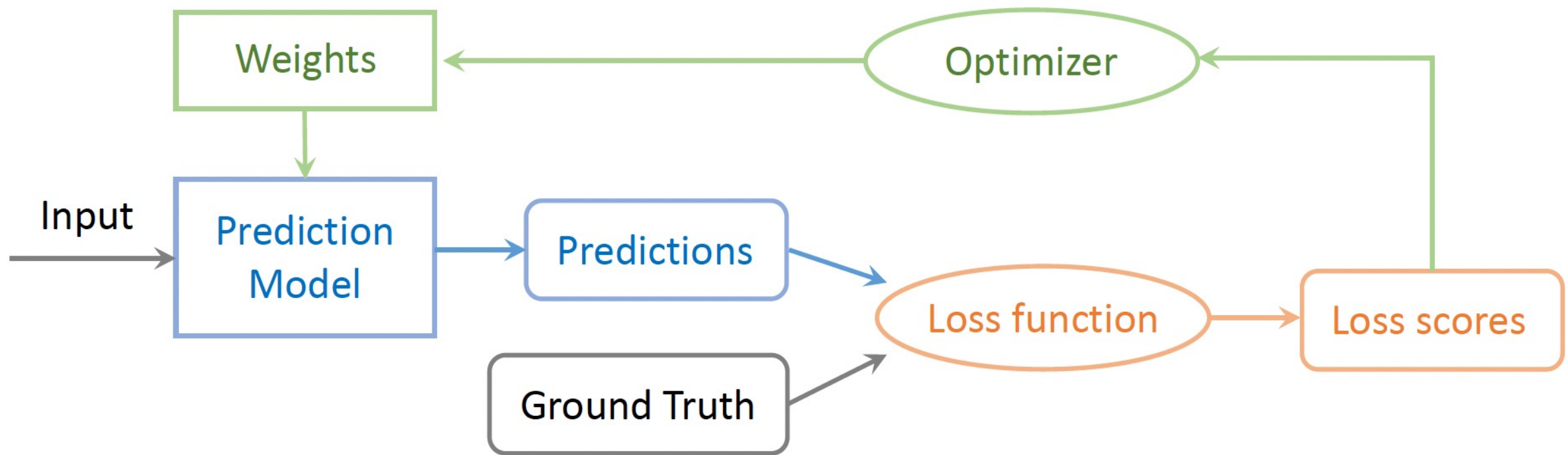


# Neural Networks

Three steps to training a neural network

- 1 Forward propagation: push example through the network to get a predicted output
- 2 Compute the cost: calculate the difference between predicted output and actual data
- 3 Backward propagation: push back the derivative of the error and apply to each weight, such that next time it will result in a lower error

# Training Pipeline



The training pipeline consists of choosing the prediction model, the loss function and the optimizer.

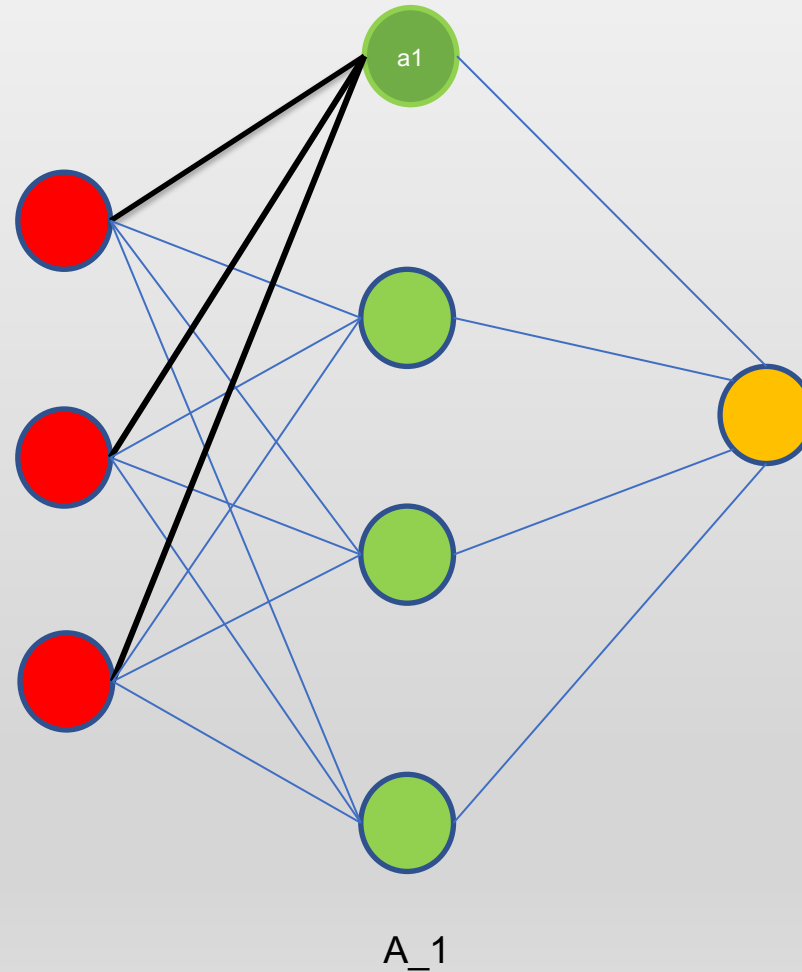
Once these choices are made, we can feed the input data and labels to start the training process.



# Building Neural Networks

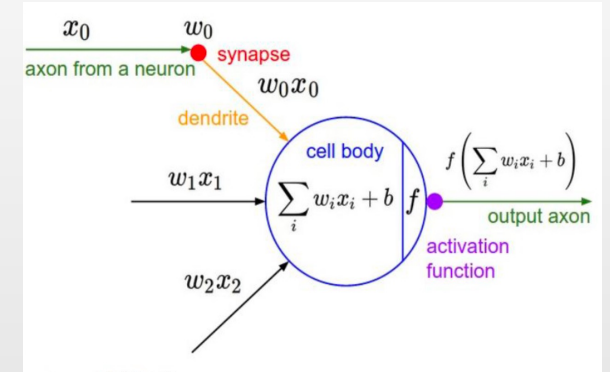
Task: Predict if it worth going to class or not

$$X = \begin{bmatrix} \text{difficulty of material} \\ \text{number of assignments due} \\ \text{days until midterm} \end{bmatrix}$$



$Y = [\text{probability of going to class}]$

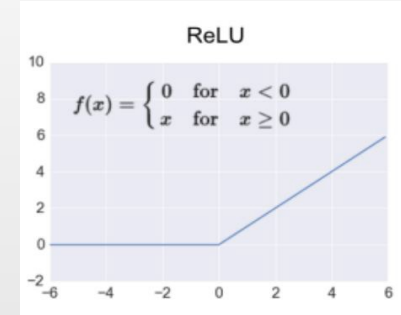
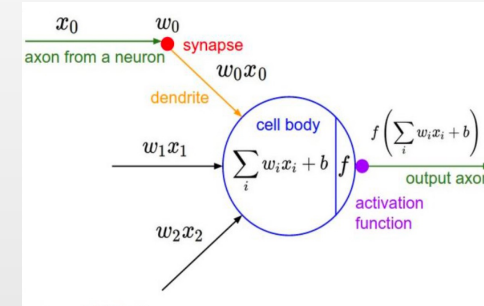
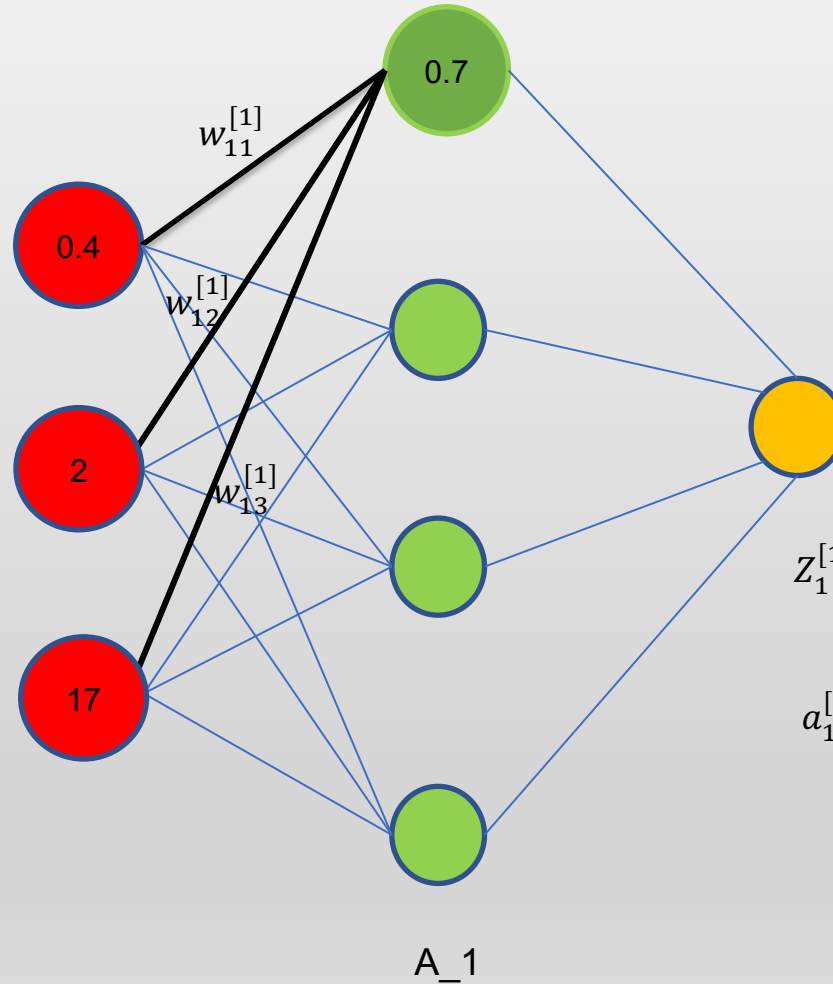
```
if y > 0.5:
    goto_class()
else:
    skip()
```



# Building Neural Networks

Task: Predict if it worth going to class or not

$$X = \begin{bmatrix} \text{difficulty of material} \\ \text{number of assignments due} \\ \text{days until midterm} \end{bmatrix}$$

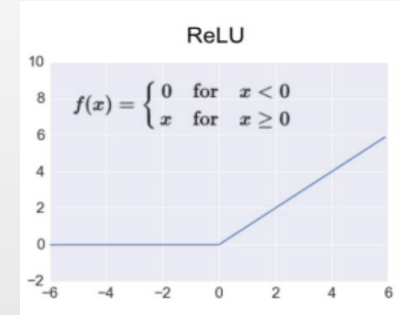
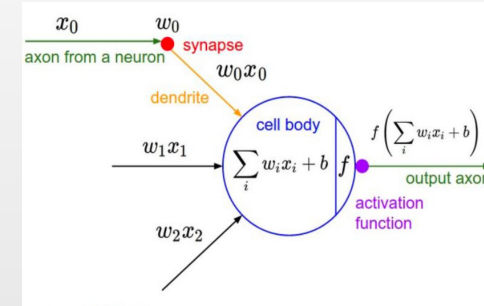
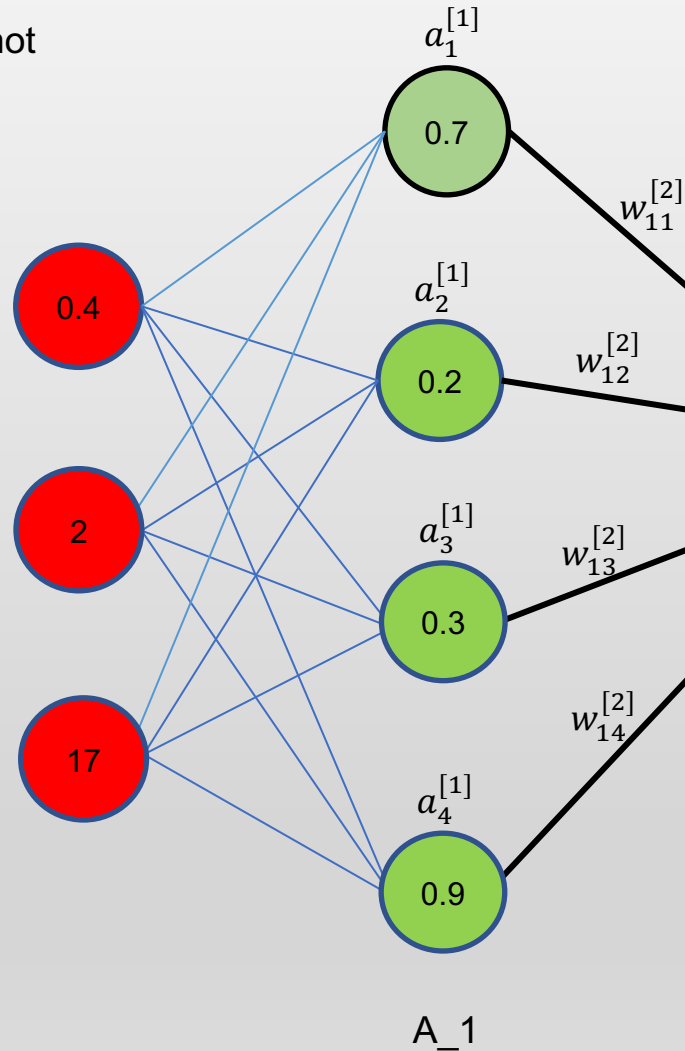


$$\begin{aligned} Z_1^{[1]} &= w_{11}^{[1]} x_1 + w_{12}^{[1]} x_2 + w_{13}^{[1]} x_3 + b_1^{[1]} \\ &= 0.5 * 0.4 + 0.1 * 2 + 0.0058 * 17 + 0.2 = 0.7 \\ a_1^{[1]} &= f(0.7) = \text{ReLU}(0.7) = 0.7 \end{aligned}$$

# Building Neural Networks

Task: Predict if it worth going to class or not

$$X = \begin{bmatrix} \text{difficulty of material} \\ \text{number of assignments due} \\ \text{days until midterm} \end{bmatrix}$$



$Y = [\text{probability of going to class}]$

$$\begin{aligned} Z_1^{[1]} &= w_{11}^{[1]}x_1 + w_{12}^{[1]}x_2 + w_{13}^{[1]}x_3 + b_1^{[1]} \\ &= 0.5 * 0.4 + 0.1 * 2 + 0.0058 * 17 + 0.2 = 0.7 \end{aligned}$$

$$a_1^{[1]} = f(0.7) = \text{ReLU}(0.7) = 0.7$$

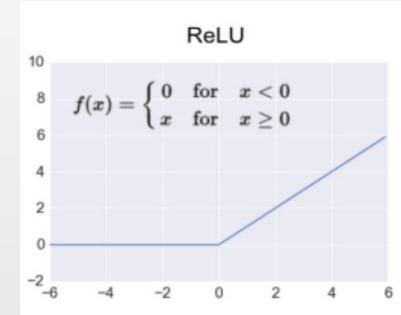
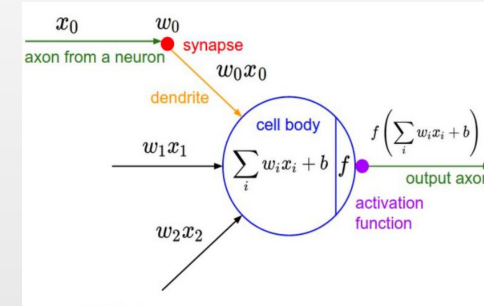
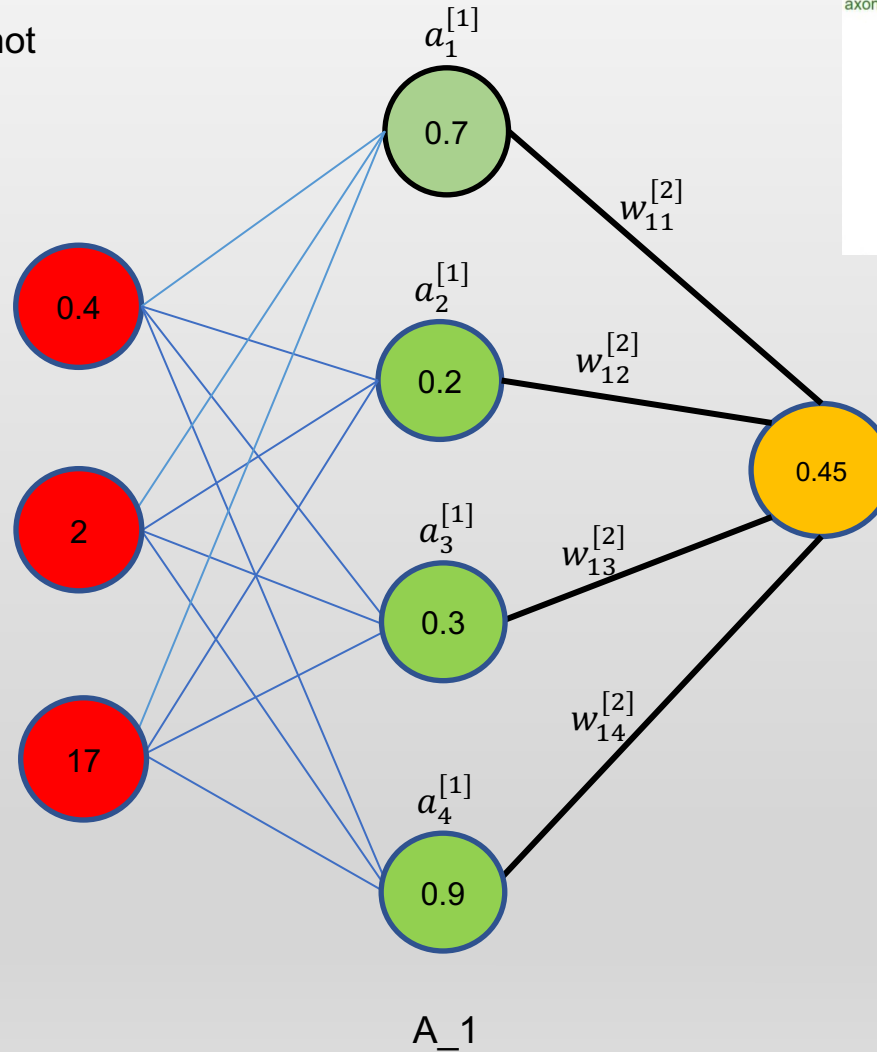
$$Z_1^{[2]} = w_{11}^{[2]}a_1^{[1]} + w_{12}^{[2]}a_2^{[1]} + w_{13}^{[2]}a_3^{[1]} + w_{14}^{[2]}a_4^{[1]} + b_1^{[2]}$$

$$\hat{y} = a_1^{[2]} = f(Z_1^{[2]}) = 0.45$$

# Building Neural Networks

Task: Predict if it worth going to class or not

$$X = \begin{bmatrix} \text{difficulty of material} \\ \text{number of assignments due} \\ \text{days until midterm} \end{bmatrix}$$



$Y = [\text{probability of going to class}]$

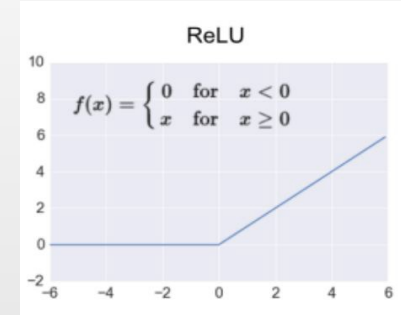
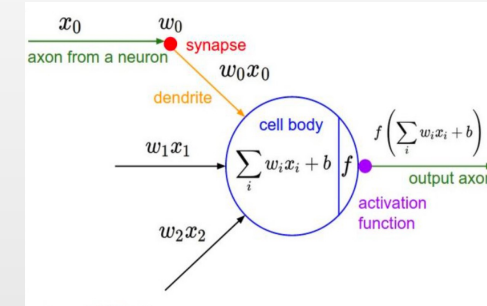
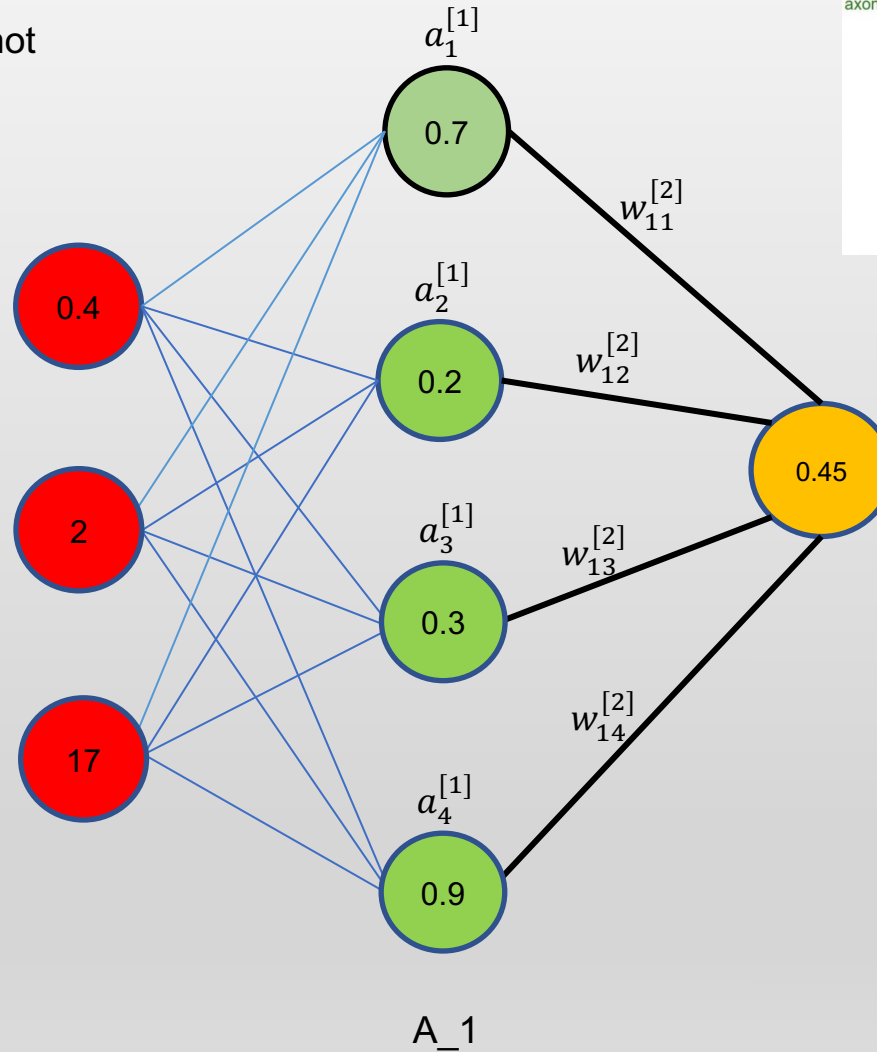
$$\hat{y} = a_1^{[2]} = f(Z_1^{[2]}) = 0.45$$

But it turns out midterm material was covered  
 $y = 1$

# Building Neural Networks

Task: Predict if it worth going to class or not

$$X = \begin{bmatrix} \text{difficulty of material} \\ \text{number of assignments due} \\ \text{days until midterm} \end{bmatrix}$$



$Y = [\text{probability of going to class}]$

$$\hat{y} = a_1^{[2]} = f(z_1^{[2]}) = 0.45, \quad y = 1$$

$$\begin{aligned} L(\hat{y}, y) &= -y \log \hat{y} - (1 - y) \log(1 - \hat{y}) \\ &= -1 * \log(0.45) - (1 - 1) \log(1 - 0.45) \\ &= 0.798508 \end{aligned}$$

Binary Cross Entropy

# Neural Networks

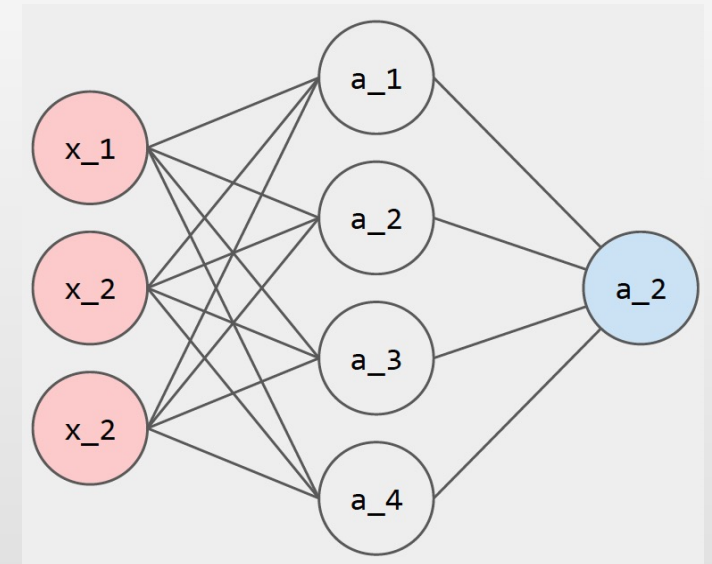
Forward Propagation:

for each sample  $i$ :

for each layer  $l$ :

for each activation  $j$ :

$$a_j^{[l]} = f^{[l]} \left( \sum_k w_{jk}^{[l]} a_k^{[l-1]} + b_j^{[l]} \right) = f^{[l]} \left( z_j^{[l]} \right)$$



# Neural Networks

Compute Cost: In order to train our neural network, we need some way to tell us how far off its estimate was from the actual value

We define the cost function,  $J(\hat{y}, y)$  as the sum of losses

$$J(\hat{y}, y) = \sum_{i=1}^m L(\hat{y}^{(i)}, y^{(i)}) \quad m: \text{number of examples}$$

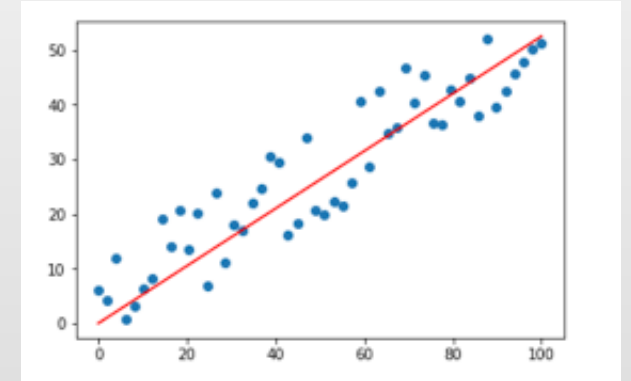
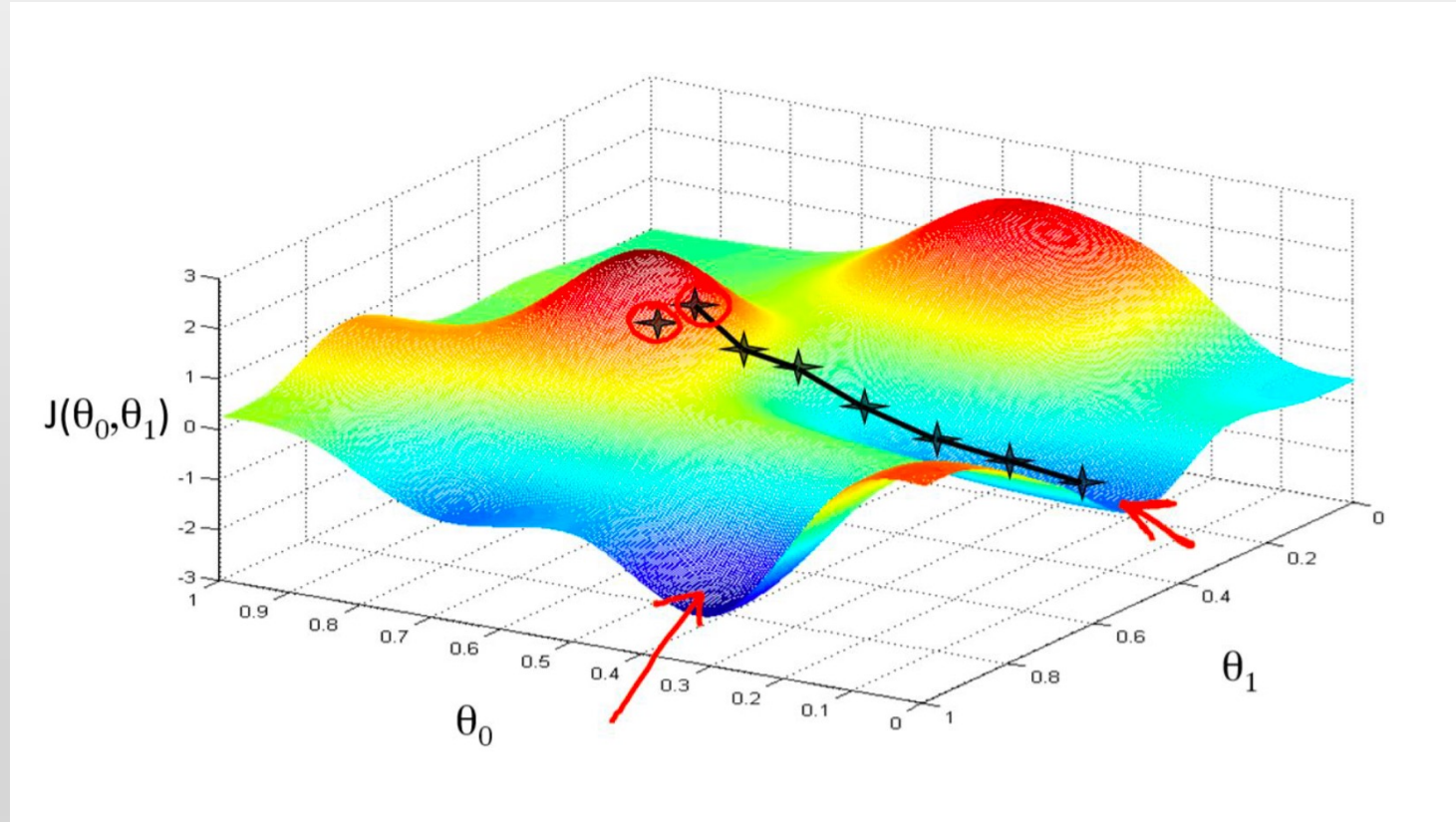
$$J(\theta) = \text{Cost Function}$$

Loss = Error for a single training example

Cost = Sum of all losses

# Neural Networks

Train with gradient descent



Example:  $y = mx + b$

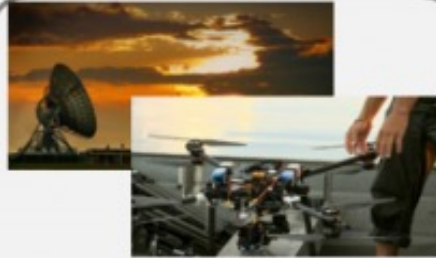


# Deep Learning Applications

## Aerospace, Defense and Communications



Communications devices,  
security



Multi-standard communications  
receivers, drone recognition

## Consumer Electronics and Digital Health



Voice assistants



Digital health

## Automotive



Voice control enabled  
Infotainment



Sensor processing,  
automated driving

## Industrial Automation



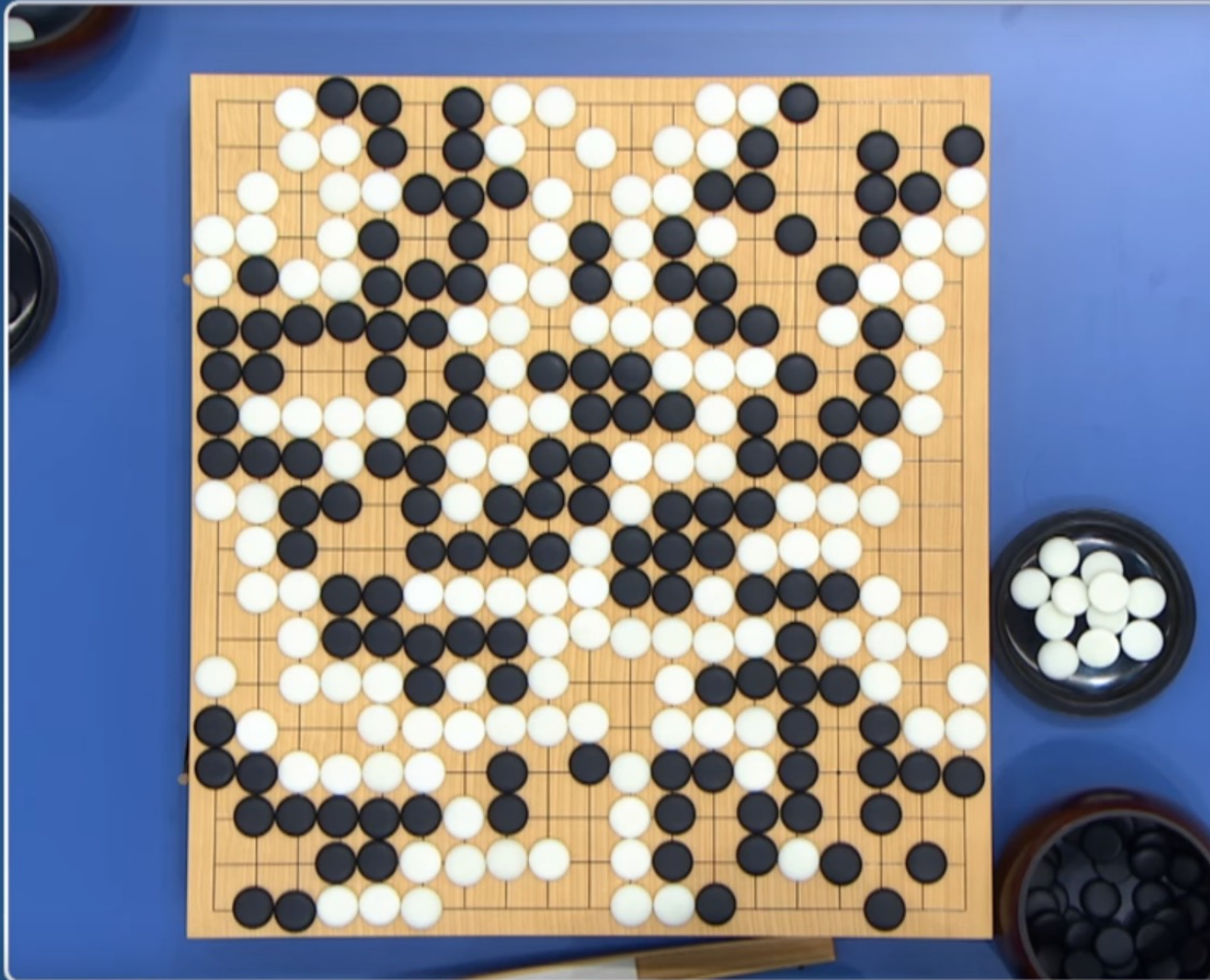
Condition monitoring



Predictive maintenance

# Deep Learning Applications

The Future of Go Summit, Match One: Ke Jie & AlphaGo



柯洁 KE JIE

00:13:20

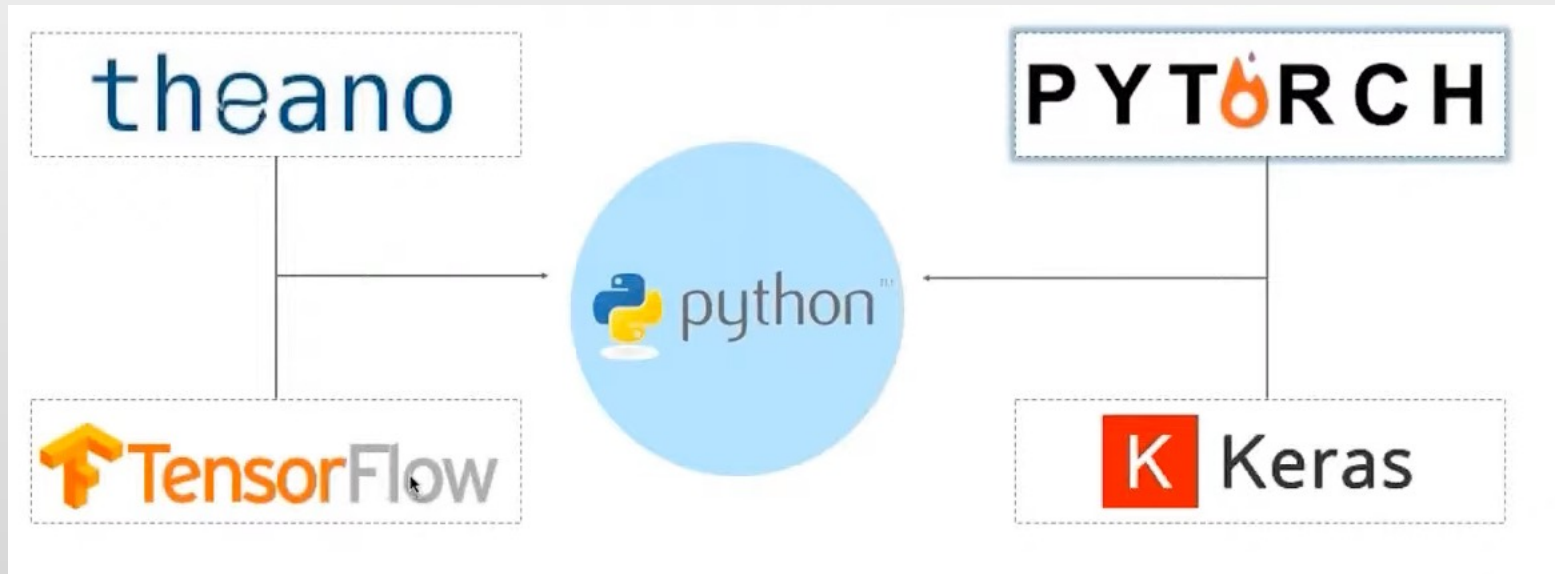


ALPHAGO

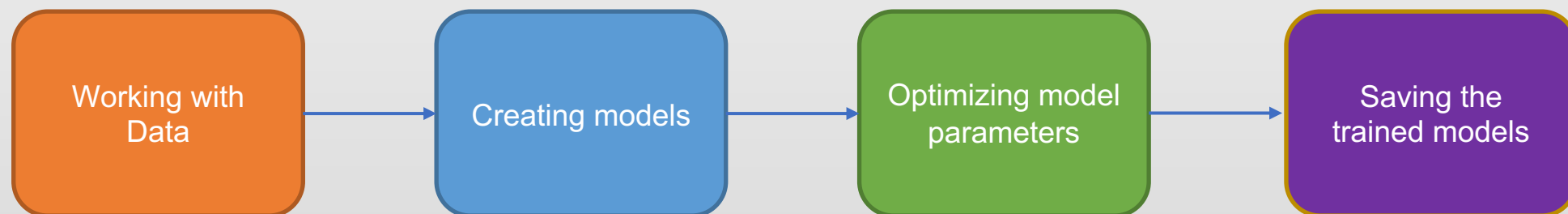
01:29:36



# Neural Networks Packages



## Machine Learning Workflows



# Pytorch Tutorial

Predict if an input image belongs to one of the following classes: T-shirt/top, Trouser, Pullover, Dress, Coat, Sandal, Shirt, Sneaker, Bag, or Ankle boot.



FasionMNIST Dataset

# Pytorch Tutorial: Working with Data

PyTorch

Dataset: stores the samples and their corresponding labels  
TorchText, TorchVision, and TorchAudio

torchvision.datasets: CIFAR, COCO, FashionMNIST

transform and target\_transform to modify the samples and labels respectively

DataLoader: wraps an iterable around the Dataset



# Working with Data

```
import torch
from torch import nn
from torch.utils.data import DataLoader
from torchvision import datasets
from torchvision.transforms import ToTensor
```

Importing Modules

```
# Download training data from open datasets.
training_data = datasets.FashionMNIST(
    root="data",
    train=True,
    download=True,
    transform=ToTensor(),
)

# Download test data from open datasets.
test_data = datasets.FashionMNIST(
    root="data",
    train=False,
    download=True,
    transform=ToTensor(),
)
```

Define Training and Test Dataset

# Working with Data

Pass the Dataset as an argument to DataLoader

Wraps an iterable over dataset and supports automatic batching, sampling, shuffling and multiprocessing data loading

```
batch_size = 64

# Create data loaders.
train_dataloader = DataLoader(training_data, batch_size=batch_size)
test_dataloader = DataLoader(test_data, batch_size=batch_size)

for X, y in test_dataloader:
    print(f"Shape of X [N, C, H, W]: {X.shape}")
    print(f"Shape of y: {y.shape} {y.dtype}")
    break
```

Define DataLoader



# Creating Models

```
# Get cpu or gpu device for training.  
device = "cuda" if torch.cuda.is_available() else "cpu"  
print(f"Using {device} device")
```

Check if GPU is Available

```
# Define model  
class NeuralNetwork(nn.Module):  
    def __init__(self):  
        super(NeuralNetwork, self).__init__()  
        self.flatten = nn.Flatten()  
        self.linear_relu_stack = nn.Sequential(  
            nn.Linear(28*28, 512),  
            nn.ReLU(),  
            nn.Linear(512, 512),  
            nn.ReLU(),  
            nn.Linear(512, 10)  
        )
```

Create Neural Networks Model

```
    def forward(self, x):  
        x = self.flatten(x)  
        logits = self.linear_relu_stack(x)  
        return logits
```

```
model = NeuralNetwork().to(device)  
print(model)
```

# Optimizing the Model Parameters

```
loss_fn = nn.CrossEntropyLoss()  
optimizer = torch.optim.SGD(model.parameters(), lr=1e-3)
```

# Define Training Loop

```
def train(dataloader, model, loss_fn, optimizer):
    size = len(dataloader.dataset)
    model.train()
    for batch, (X, y) in enumerate(dataloader):
        X, y = X.to(device), y.to(device)

        # Compute prediction error
        pred = model(X)
        loss = loss_fn(pred, y)

        # Backpropagation
        optimizer.zero_grad()
        loss.backward()
        optimizer.step()

    if batch % 100 == 0:
        loss, current = loss.item(), batch * len(X)
        print(f"loss: {loss:>7f}  [{current:>5d}/{size:>5d}"])
```

## Define Test Dataset

```
def test(dataloader, model, loss_fn):
    size = len(dataloader.dataset)
    num_batches = len(dataloader)
    model.eval()
    test_loss, correct = 0, 0
    with torch.no_grad():
        for X, y in dataloader:
            X, y = X.to(device), y.to(device)
            pred = model(X)
            test_loss += loss_fn(pred, y).item()
            correct += (pred.argmax(1) == y).type(torch.float).sum().item()
    test_loss /= num_batches
    correct /= size
    print(f"Test Error: \n Accuracy: {(100*correct):>0.1f}%, Avg loss: {test_loss:>8f} \n")
```

# Training Loop

```
epochs = 5
for t in range(epochs):
    print(f"Epoch {t+1}\n-----")
    train(train_dataloader, model, loss_fn, optimizer)
    test(test_dataloader, model, loss_fn)
print("Done!")
```

# Saving Models

```
torch.save(model.state_dict(), "model.pth")  
print("Saved PyTorch Model State to model.pth")
```

# Loading Models

```
model = NeuralNetwork()  
model.load_state_dict(torch.load("model.pth"))
```

# Make Predictions

```
classes = [  
    "T-shirt/top",  
    "Trouser",  
    "Pullover",  
    "Dress",  
    "Coat",  
    "Sandal",  
    "Shirt",  
    "Sneaker",  
    "Bag",  
    "Ankle boot",  
]  
  
model.eval()  
x, y = test_data[0][0], test_data[0][1]  
with torch.no_grad():  
    pred = model(x)  
    predicted, actual = classes[pred[0].argmax(0)], classes[y]  
    print(f'Predicted: "{predicted}", Actual: "{actual}"')
```



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