gsvd

Generalized singular value decomposition

Syntax

```
[U,V,X,C,S] = gsvd(A,B)

[U,V,X,C,S] = gsvd(A,B,0)

sigma = gsvd(A,B)
```

Description

[U,V,X,C,S] = gsvd(A,B) returns unitary matrices U and V, a (usually) square matrix X, and nonnegative diagonal matrices C and S so that

```
A = U*C*X'
B = V*S*X'
C'*C + S'*S = I
```

A and B must have the same number of columns, but may have different numbers of rows. If A is m-by-p and B is n-by-p, then U is m-by-m, V is n-by-n, X is p-by-q, C is m-by-q and S is n-by-q, where q = min(m+n,p).

The nonzero elements of S are always on its main diagonal. The nonzero elements of C are on the diagonal diag(C, max(0, q-m)). If m >= q, this is the main diagonal of C.

[U,V,X,C,S] = gsvd(A,B,0), where A is m-by-p and B is n-by-p, produces the "economy-sized" decomposition where the resulting U and V have at most p columns, and C and S have at most p rows. The generalized singular values are diag(C)./diag(S) so long as m >= p and n >= p.

If A is m-by-p and B is n-by-p, then U is m-by-min(q,m), V is n-by-min(q,n), X is p-by-q, C is min(q,m)-by-q and S is min(q,n)-by-q, where q = min(m+n,p).

sigma = gsvd(A,B) returns the vector of generalized singular values, sqrt(diag(C'*C)./diag(S'*S)). When B is square and nonsingular, the generalized singular values, gsvd(A,B), correspond to the ordinary singular values, svd(A/B), but they are sorted in the opposite order. Their reciprocals are gsvd(B,A).

The vector sigma has length q and is in non-decreasing order.

Examples

Example 1

The matrices have at least as many rows as columns.

```
A = reshape(1:15,5,3)
B = magic(3)
A =
          1
                 6
                       11
          2
                 7
                       12
          3
                 8
                       13
          4
                 9
                       14
          5
                10
                       15
B =
          8
                 1
                        6
                        7
          3
                 5
                        2
          4
                 9
```

The statement

$$[U,V,X,C,S] = gsvd(A,B)$$

produces a 5-by-5 orthogonal U, a 3-by-3 orthogonal V, a 3-by-3 nonsingular X,

and

Since A is rank deficient, the first diagonal element of C is zero.

The economy sized decomposition,

$$[U,V,X,C,S] = gsvd(A,B,0)$$

produces a 5-by-3 matrix U and a 3-by-3 matrix C.

The other three matrices, V, X, and S are the same as those obtained with the full decomposition.

The generalized singular values are the ratios of the diagonal elements of C and S.

These values are a reordering of the ordinary singular values

```
svd(A/B)
ans =
5.0123
0.3325
0.0000
```

Example 2

The matrices have at least as many columns as rows.

```
A = reshape(1:15,3,5)
```

B = magic(5)

A =

1	4	7	10	13
2	5	8	11	14
3	6	9	12	15

B =

The statement

$$[U,V,X,C,S] = gsvd(A,B)$$

produces a 3-by-3 orthogonal U, a 5-by-5 orthogonal V, a 5-by-5 nonsingular X and

C =

0	0	0.0000	0	0
0	0	0	0.0439	0
0	0	0	0	0.7432

S =

0	0	0	0	1.0000
0	0	0	1.0000	0
0	0	1.0000	0	0
0	0.9990	0	0	0
0 6690	a	a	a	a

In this situation, the nonzero diagonal of C is diag(C, 2). The generalized singular values include three zeros.

0

0

0.0000

0.0439

1.1109

Reversing the roles of A and B reciprocates these values, producing two infinities.

```
gsvd(B,A)
ans =
1.0e+16 *
0.0000
0.0000
8.8252
Inf
Inf
```

Tips

In this formulation of the gsvd, no assumptions are made about the individual ranks of A or B. The matrix X has full rank if and only if the matrix [A;B] has full rank. In fact, svd(X) and cond(X) are equal to svd([A;B]) and cond([A;B]). Other formulations, eg. G. Golub and C. Van Loan [1], require that null(A) and null(B) do not overlap and replace X by inv(X) or inv(X').

Note, however, that when null(A) and null(B) do overlap, the nonzero elements of C and S are not uniquely determined.

Algorithms

The generalized singular value decomposition uses the C-S decomposition described in [1], as well as the built-in svd and qr functions. The C-S decomposition is implemented in a local function in the gsvd program file.

References

[1] Golub, Gene H. and Charles Van Loan, *Matrix Computations*, Third Edition, Johns Hopkins University Press, Baltimore, 1996

See Also

qr | svd

Introduced before R2006a