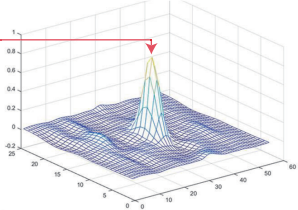


(a) Tracking scene



(b) Single peak confidence map