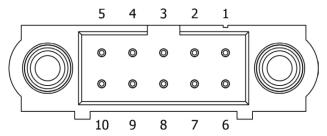
# IMU

#### 2.2 VN-100 Rugged Electrical

VN-100 Rugged Pin Assignments

Pin	Pin Name	Description		
1	VCC	+4.5V to +5.5V		
2	TX1	RS-232 voltage levels data output from the sensor. (Serial UART #1)		
3	RX1	RS-232 voltage levels data input to the sensor. (Serial UART #1)		
4	SYNC_OUT	Output signal used for synchronization purposes. Software configurable to pulse when ADC, IMU, or attitude measurements are available.		
5	GND	Ground		
6	TARE/RESTORE	Input signal used to zero the attitude of the sensor. If high at reset, the device will restore to factory default state. Internally held low with 10k resistor.		
7	SYNC_IN	Input signal for synchronization purposes. Software configurable to either synchronize the measurements or the output with an external device.		
8	TX2_TTL	Serial UART #2 data output from the device at TTL voltage level (3V).		
9	RX2_TTL	Serial UART #2 data into the device at TTL voltage level (3V).		
10	RESV	This pin should be left unconnected.		

VN-100 Rugged External Connector

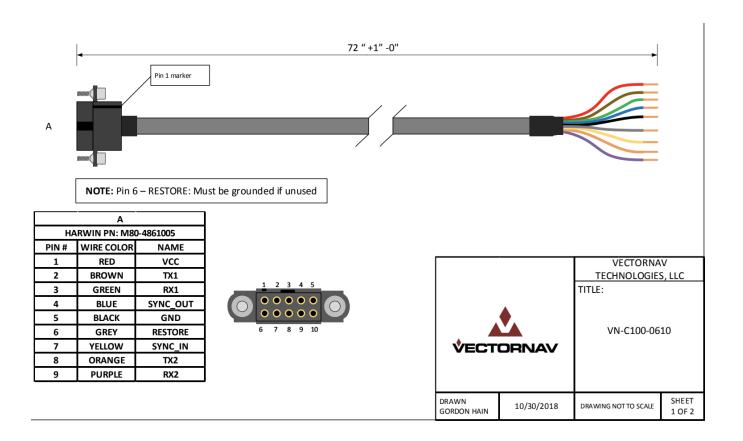


## **IMU**

- Digital Interface: Serial TTL, RS-232
- USB to TTL Serial Converter



## **IMU**



#### Camera

Mannual p34 https://www.ptgrey.com/support/downloads/10431/

#### 4.9.4 General Purpose Input/Output (GPIO)

Diagram	Color	Pin	Function	Description
	Red	1	$V_{EXT}$	Allows the camera to be powered externally 5 - 24 VDC
	Black	2	GND	Ground for Input/Output, V <sub>EXT</sub> , +3.3 V pins
	White	3	+3.3 V	Power external circuitry fused at 150 mA maximum
	Green	4	GPIO3 / Line3	Input/Output/Tx
	Purple	5	GPIO2 / Line2	Input/Output/Rx
	Black	6	GND	Ground for Input/Output, V <sub>EXT</sub> , +3.3 V pins
	Brown	7	OPTO_GND	Ground for opto-isolated IO pins
8	Orange	8	OPTO_OUT / Line1	Opto-isolated output
	Yellow	9	OPTO_IN / Line0	Opto-isolated input

