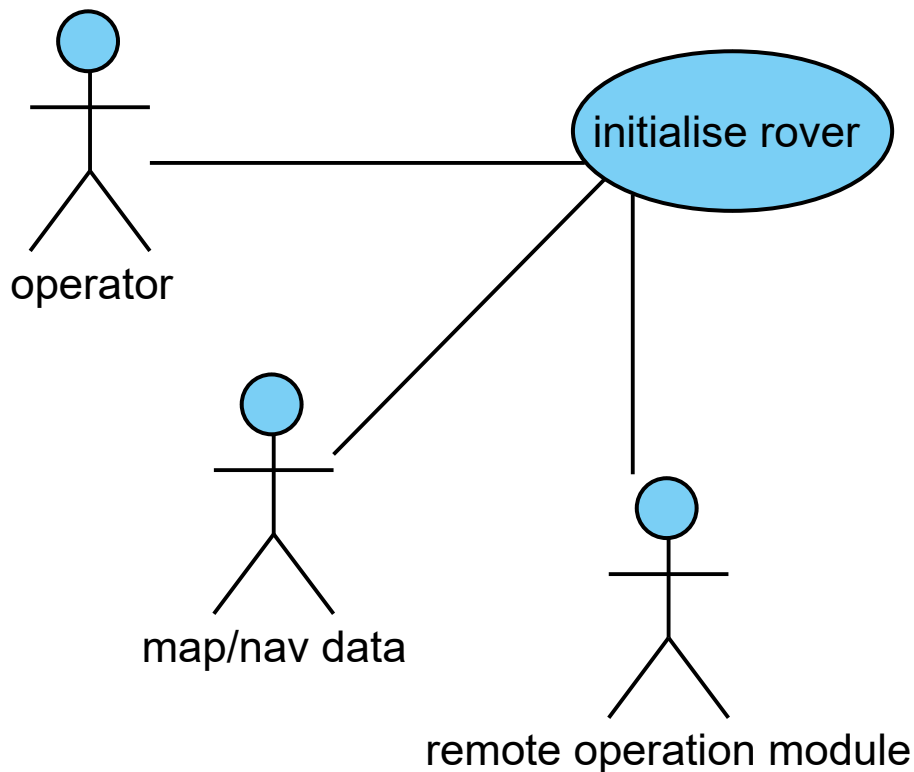


uc [initialise rover]



create rover
check power / fuel
check internal systems (engine check ?) ok
assign operating mode (manned /
unmanned)
assign / set map
set initial co-ords
check / assign load
? set up any limits that need checking prior
to ops (ex: can we move with x load?)

