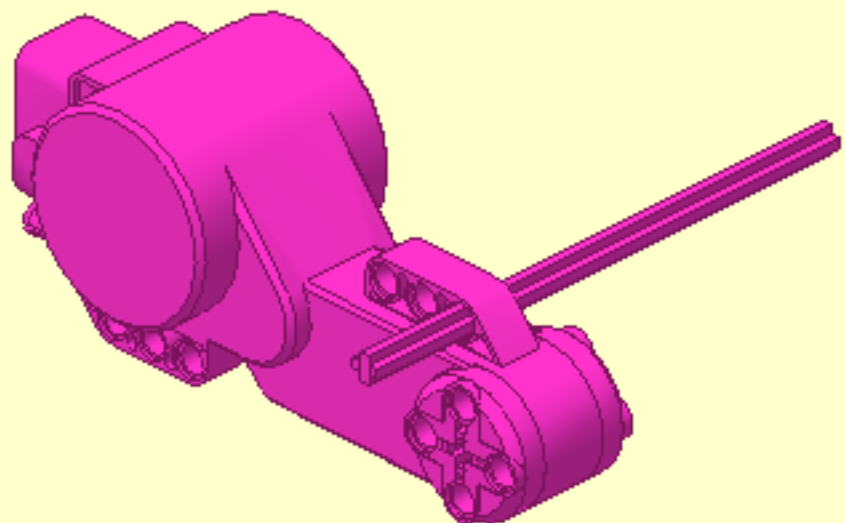
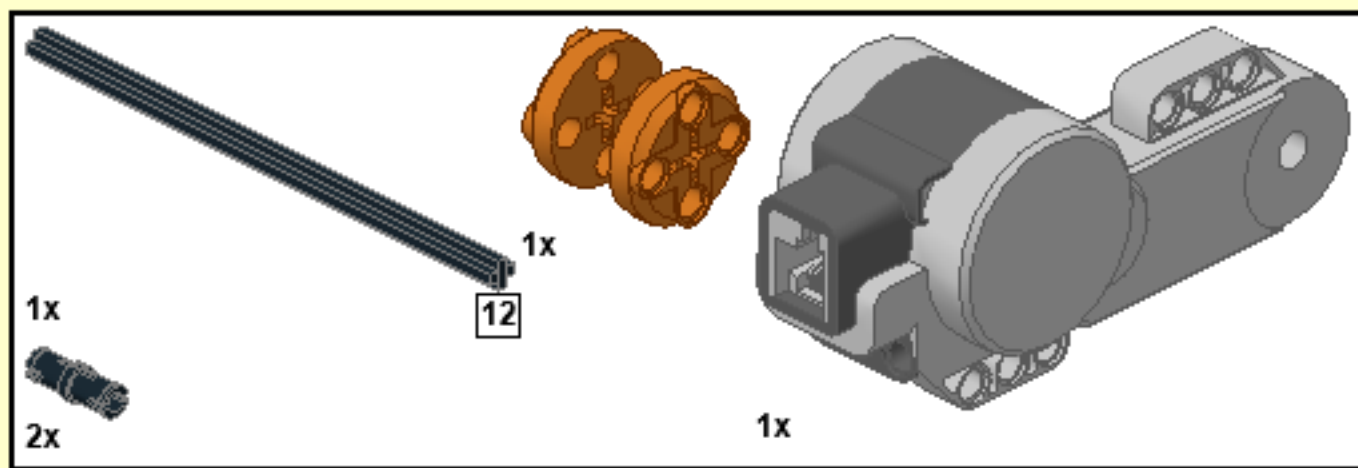
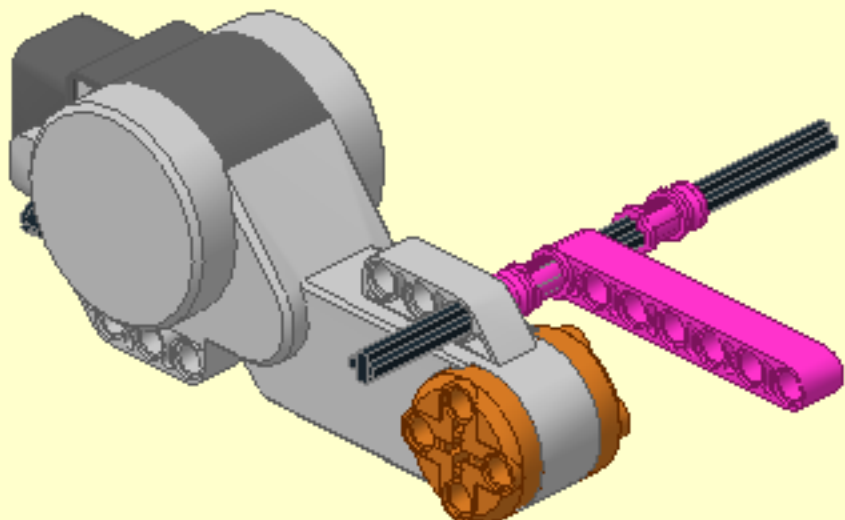
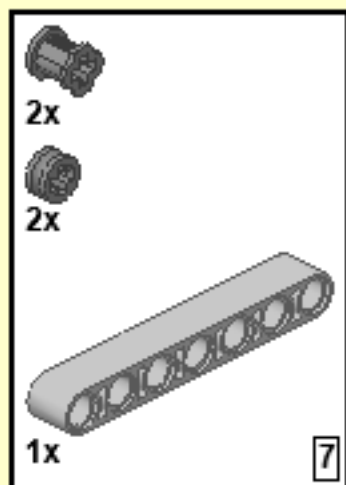


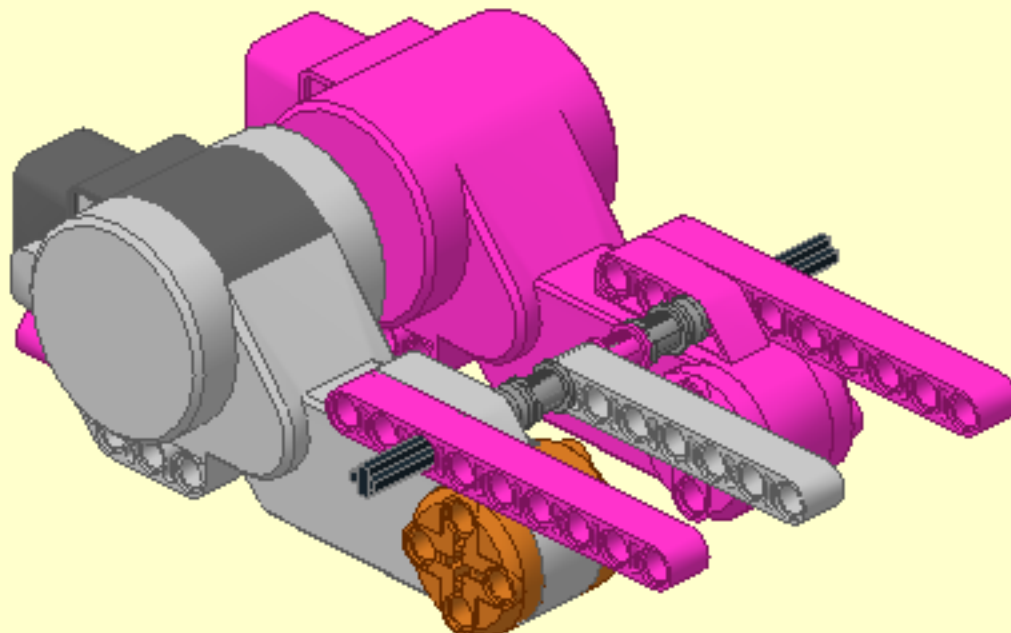
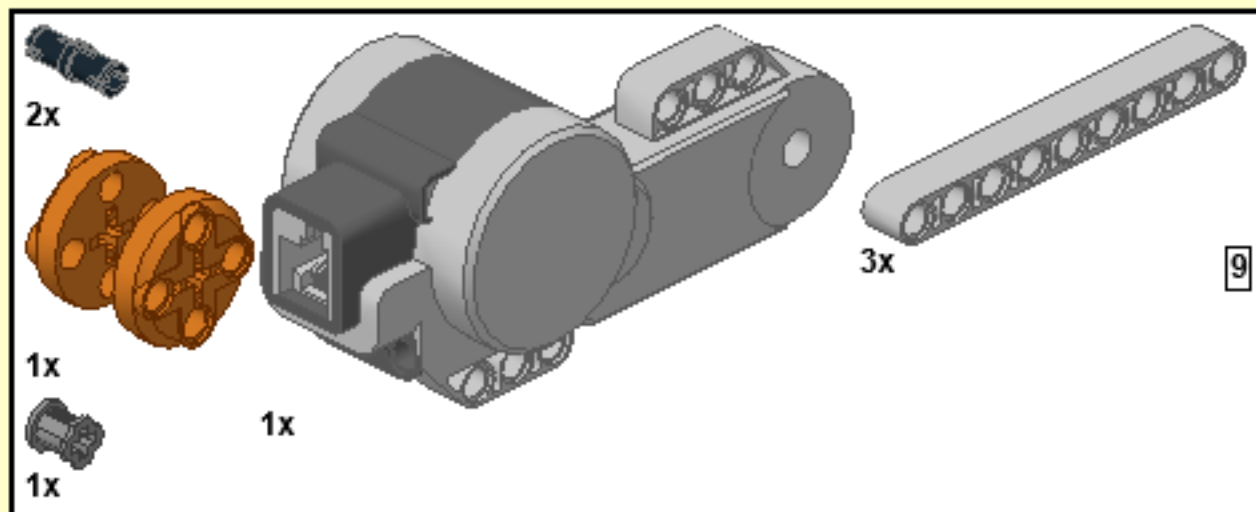
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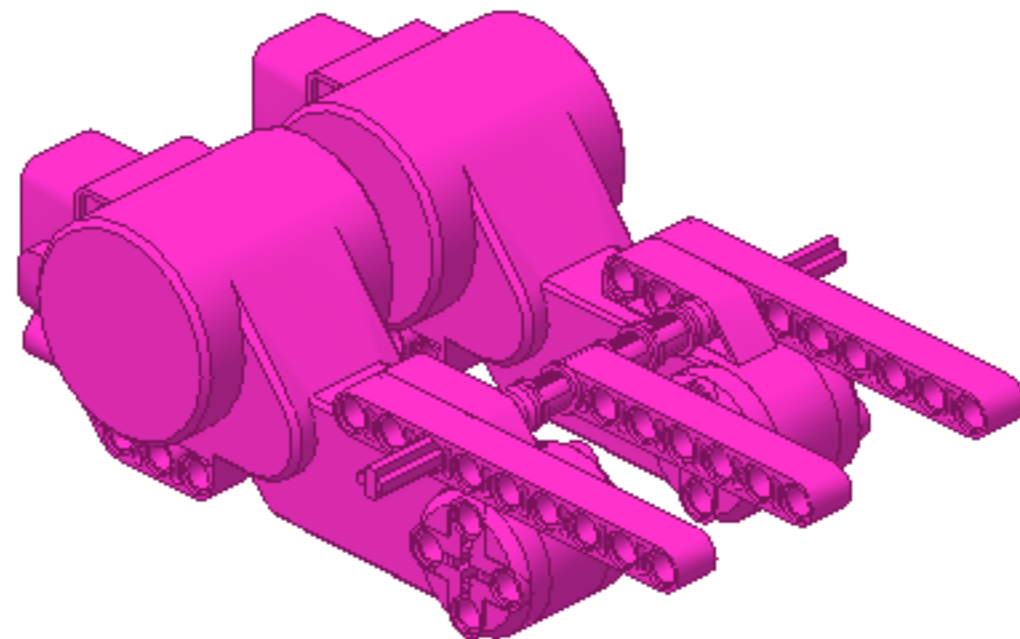
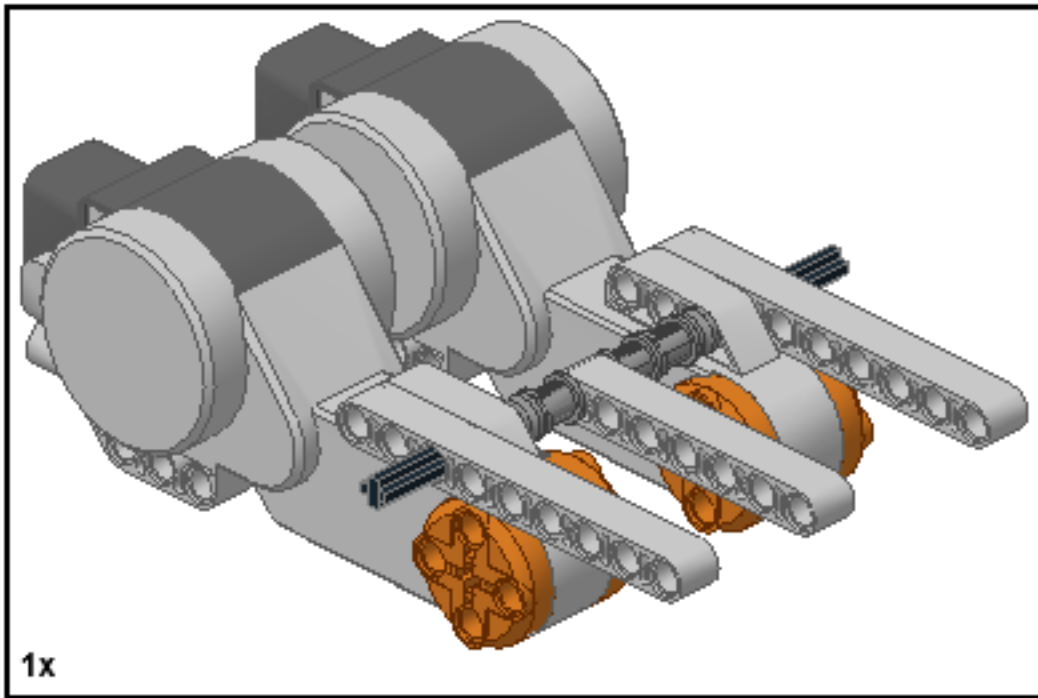
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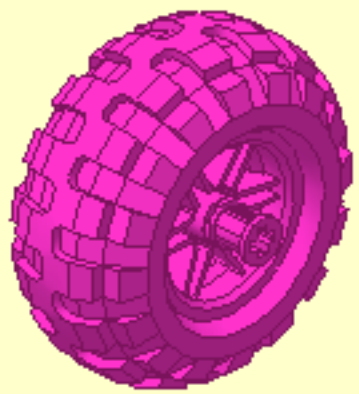
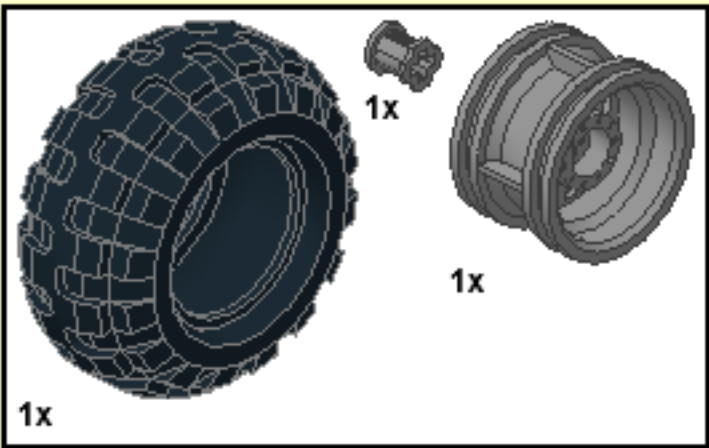
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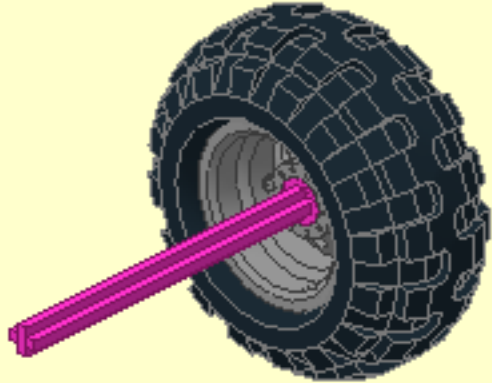
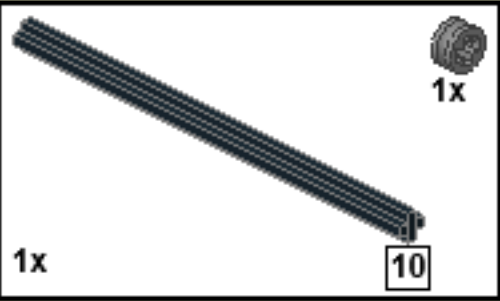
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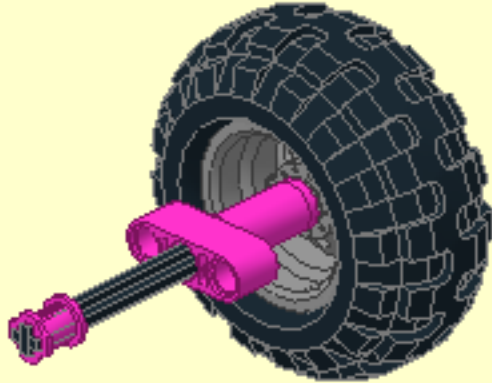
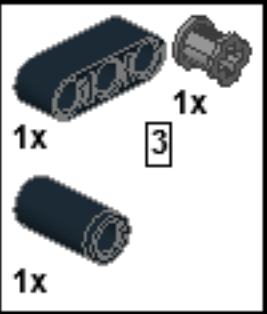
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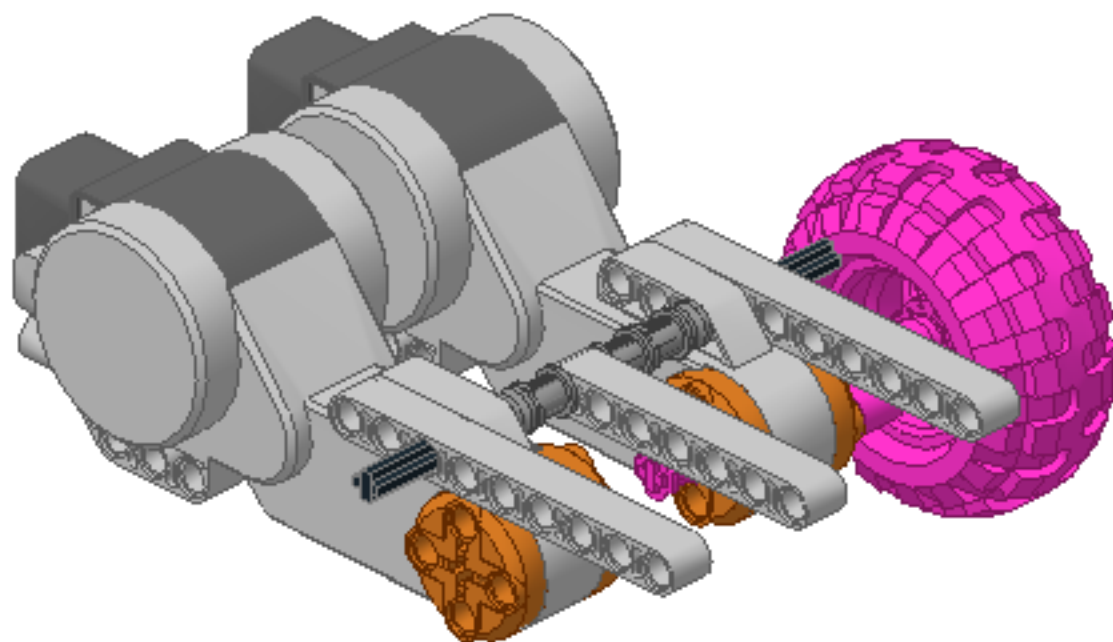
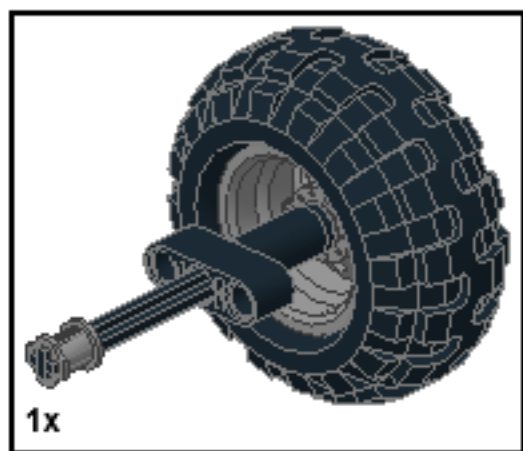
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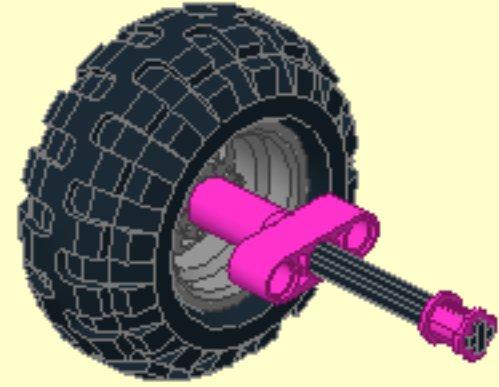
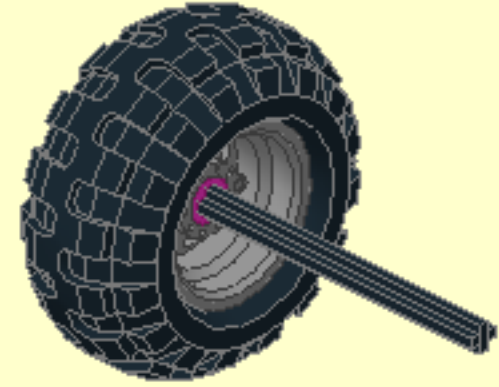
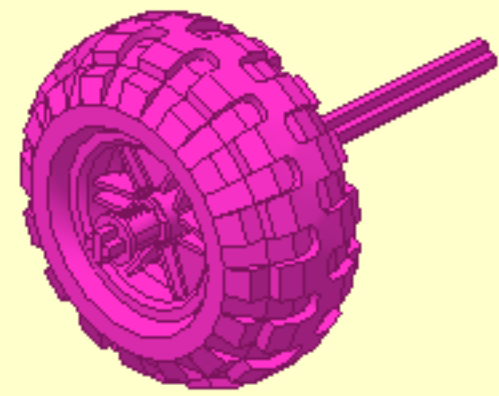
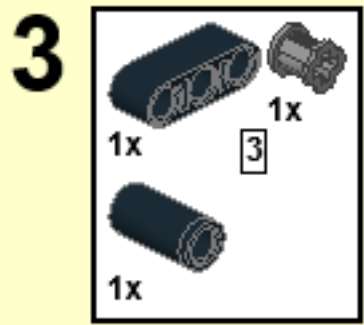
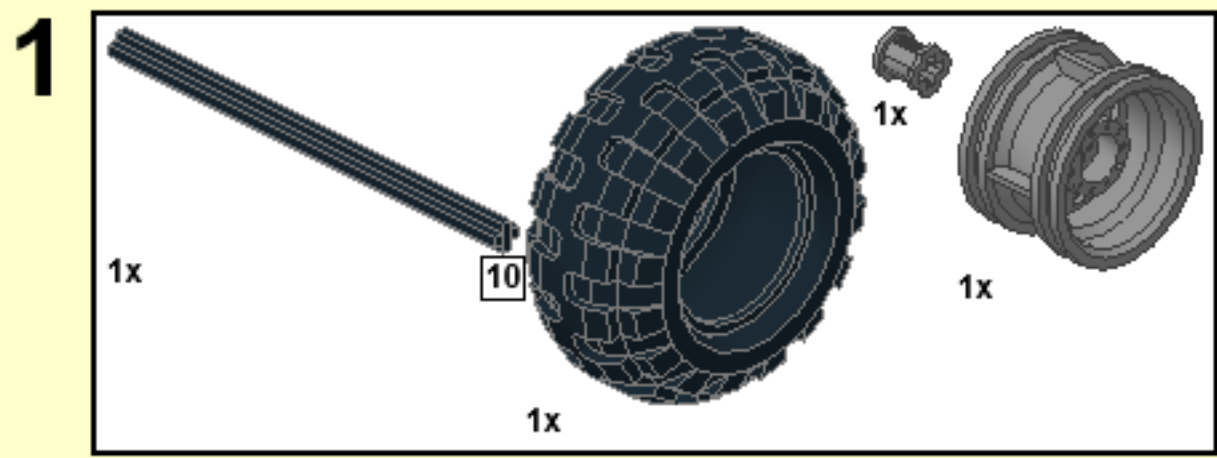


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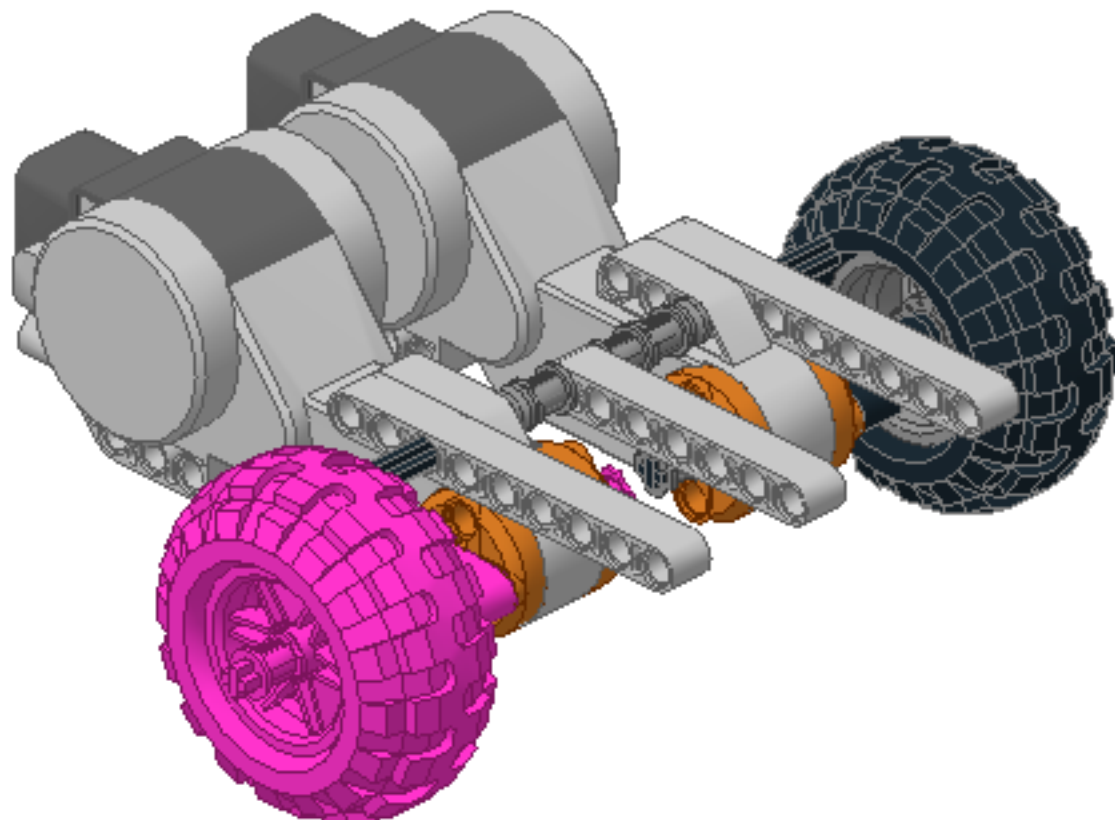
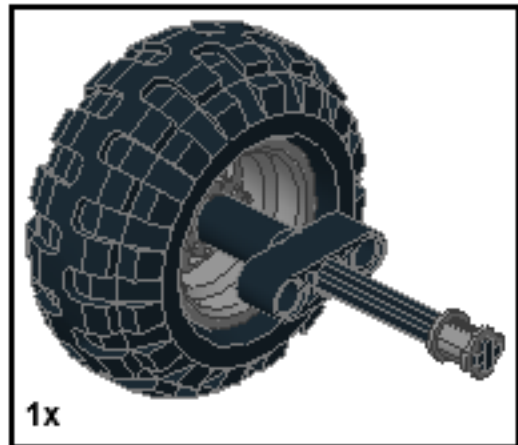


2






3



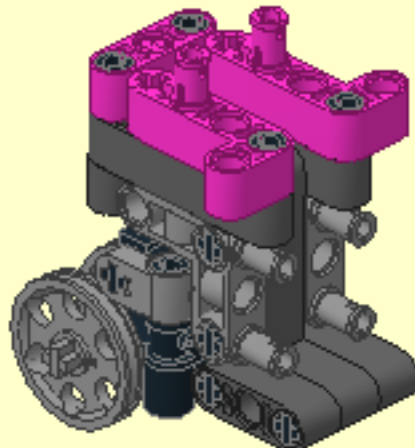
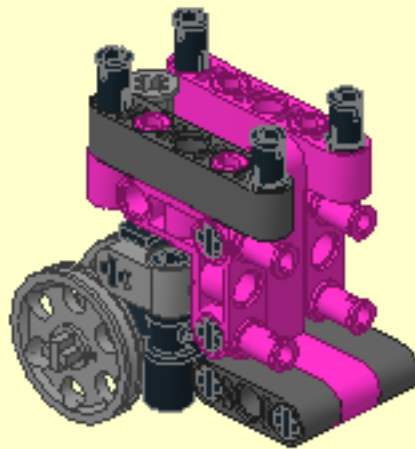
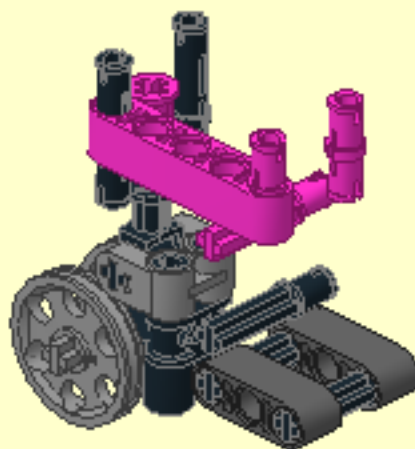
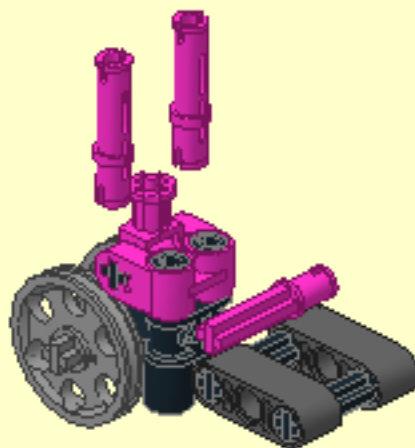
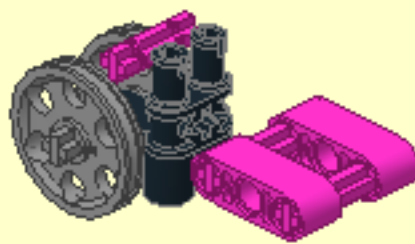
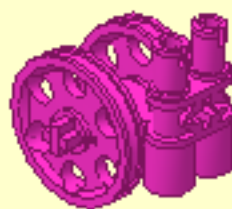
1x 2x 2x 3



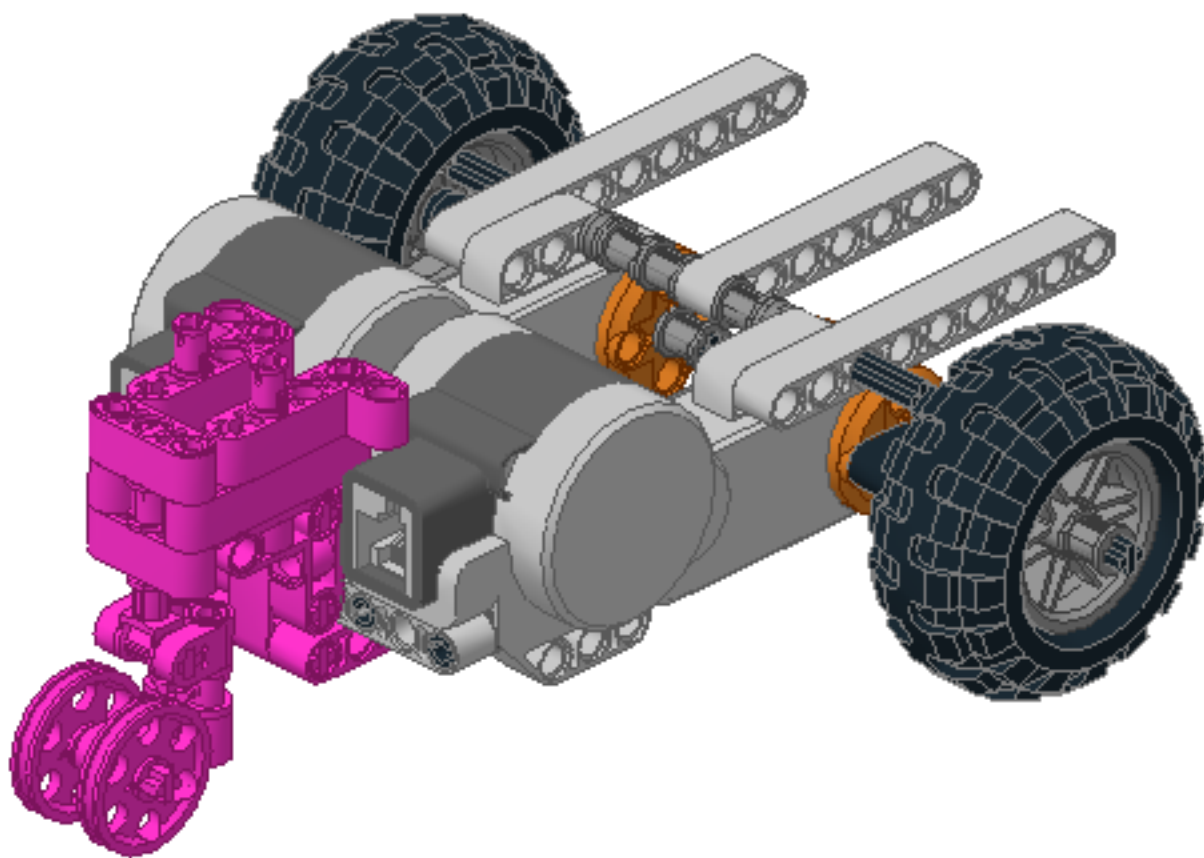
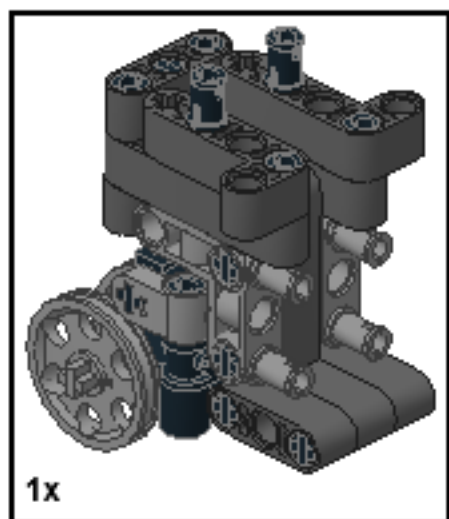
2x 1x3 Technic connector with 2 pins
1x 1x5 Technic beam
1x 1x5 Technic L-shaped beam
1x 1x3 Technic beam
1x 1x3 Technic L-shaped beam

1x
2x
2x
1x

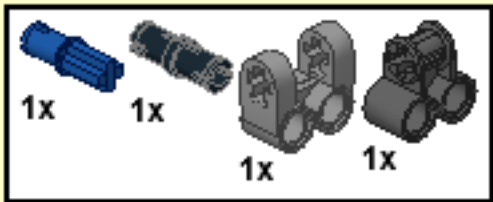
4
3



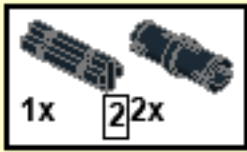
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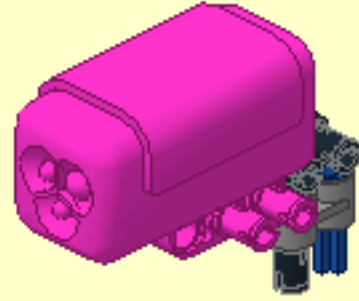
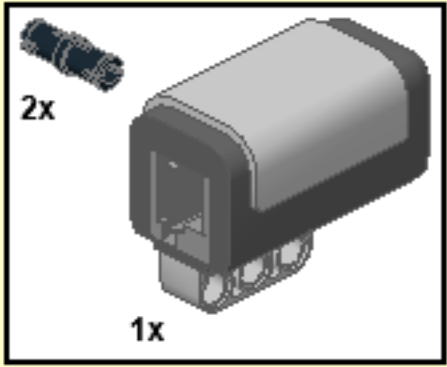
1



2

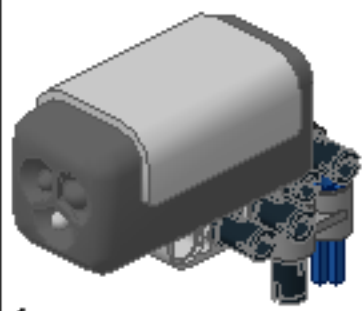


3

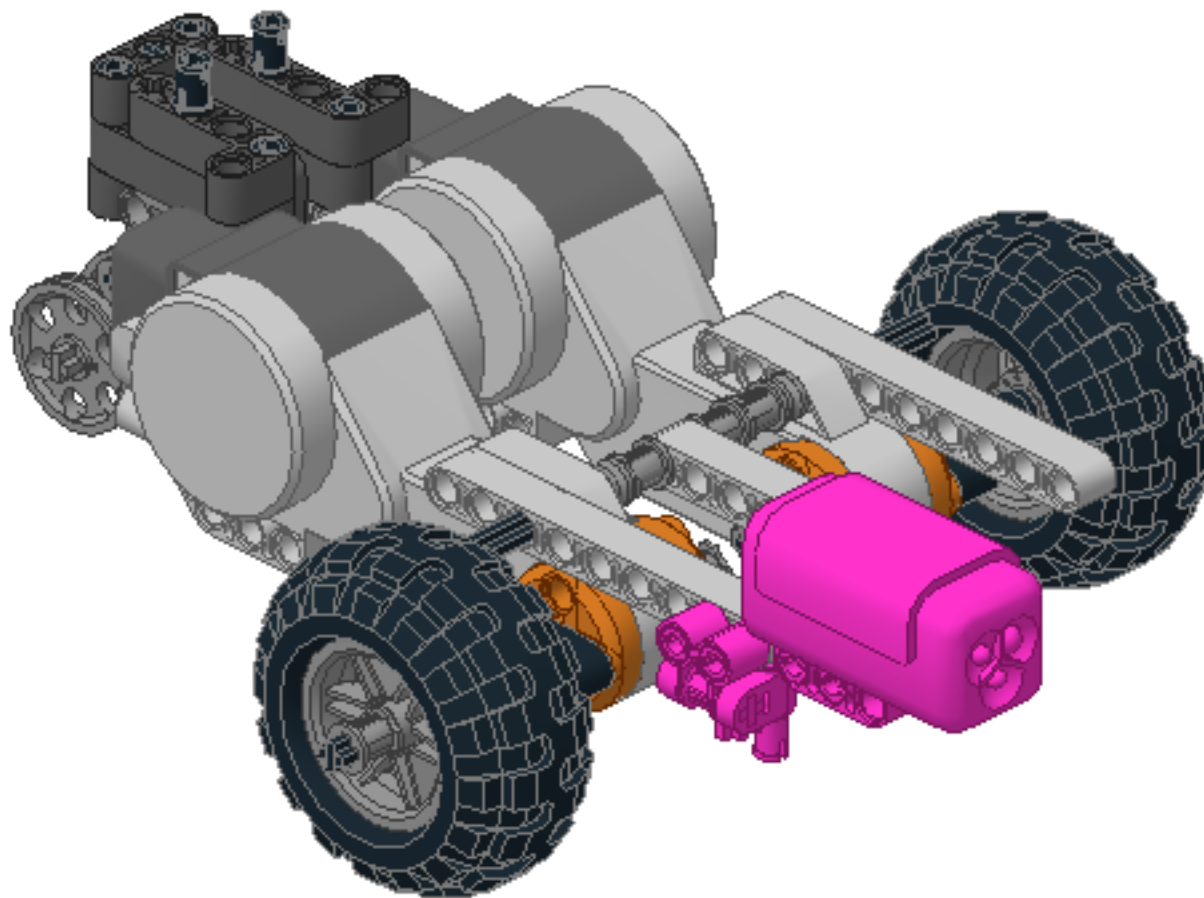


5

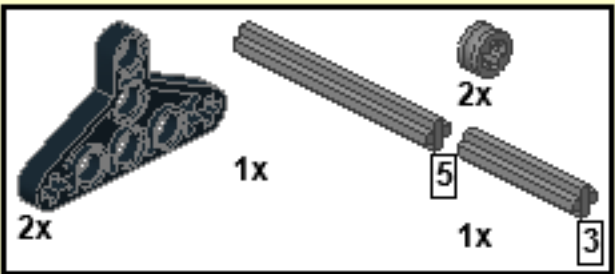
1x



1x



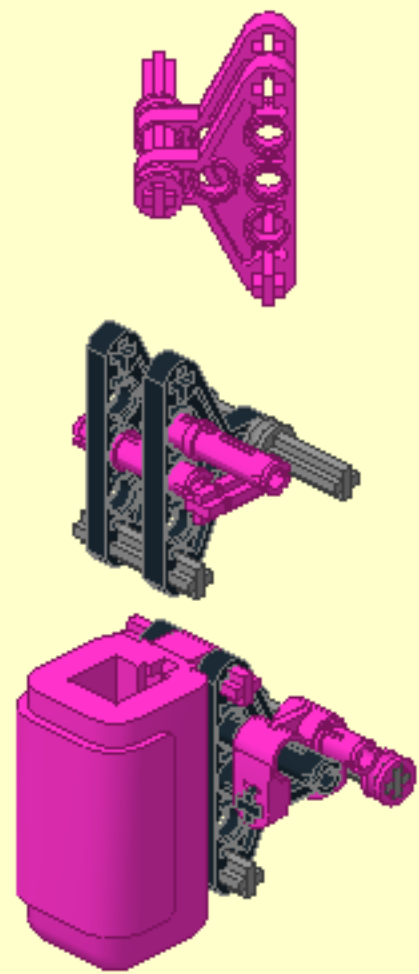
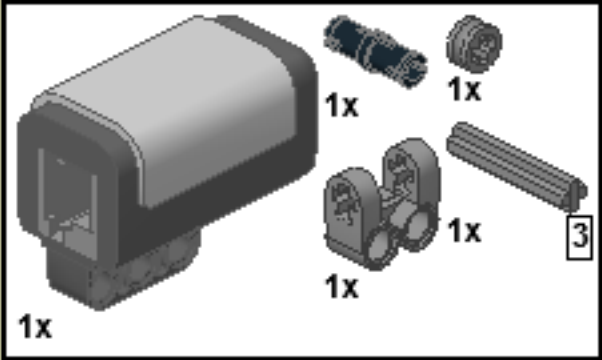
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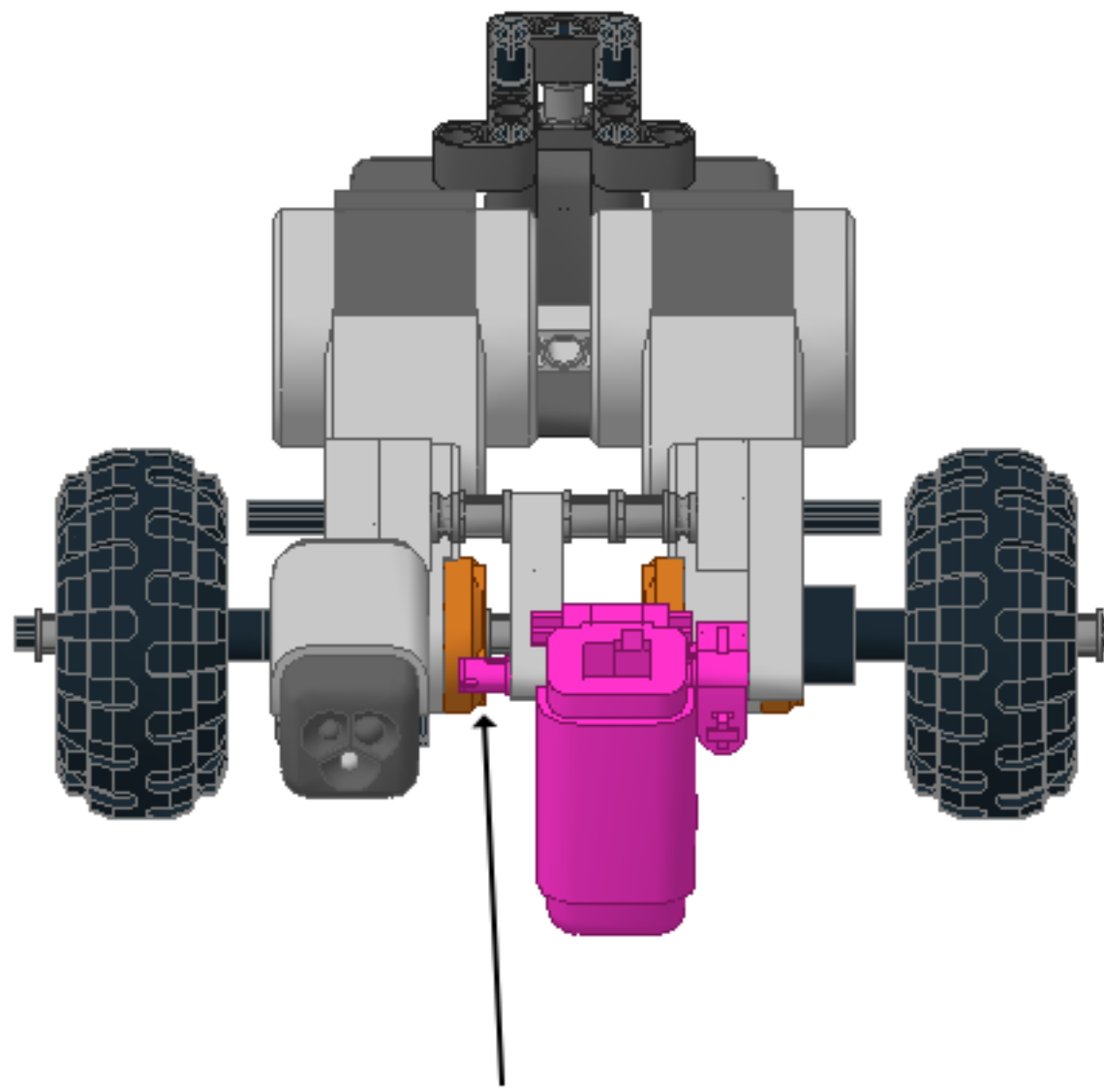
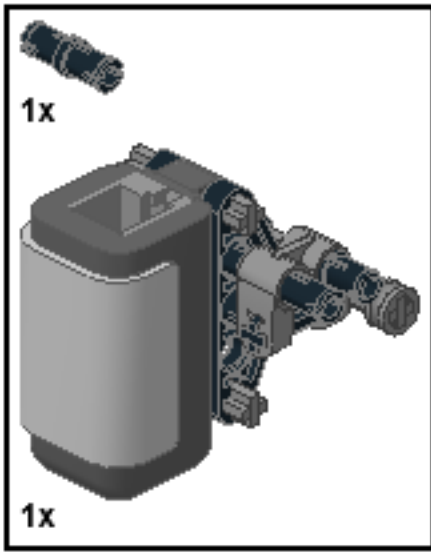
2



3

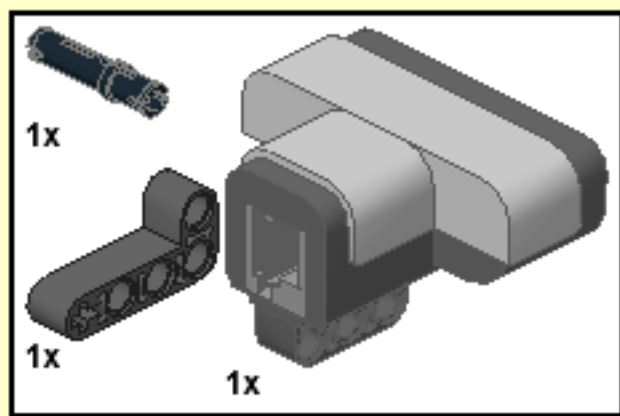


6

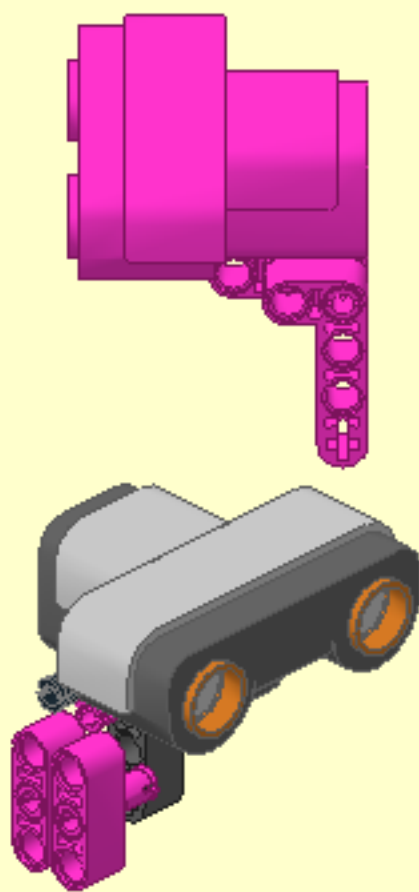
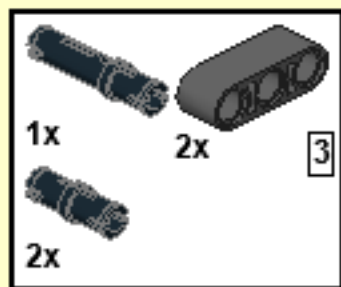


The correct position for this connector is between the 7x1 and the triangle shape. LDD rules did not allow it.

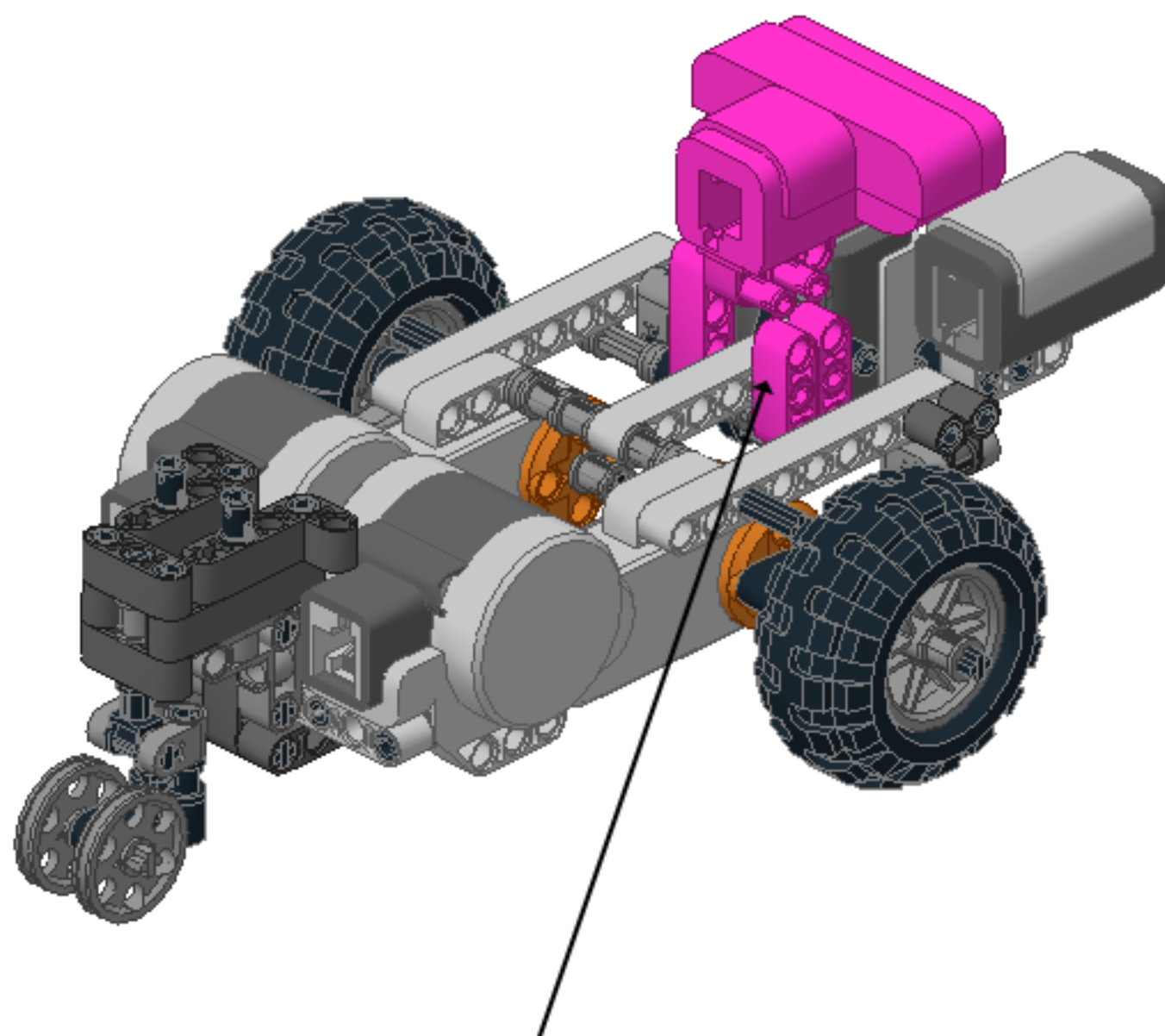
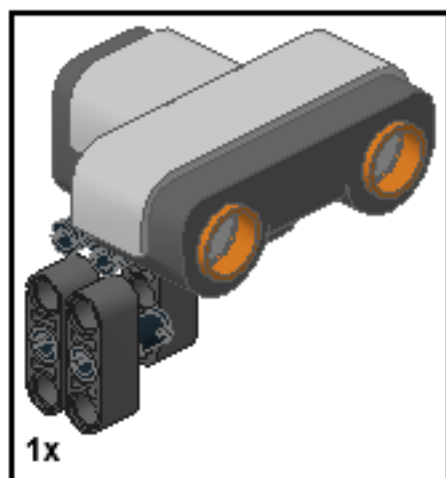
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2

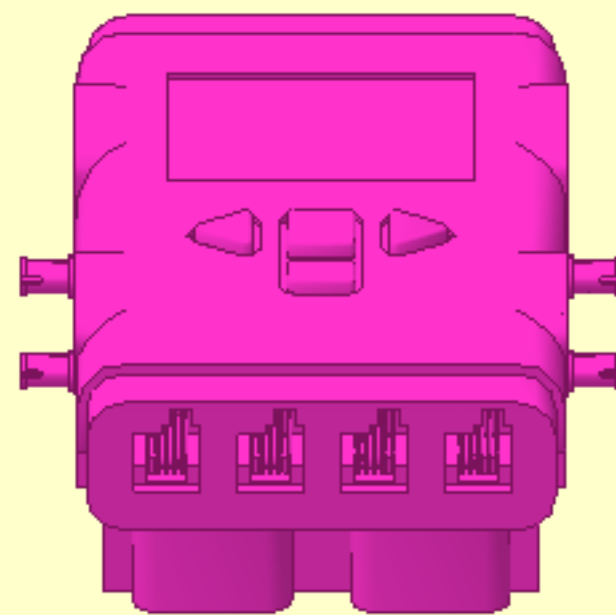
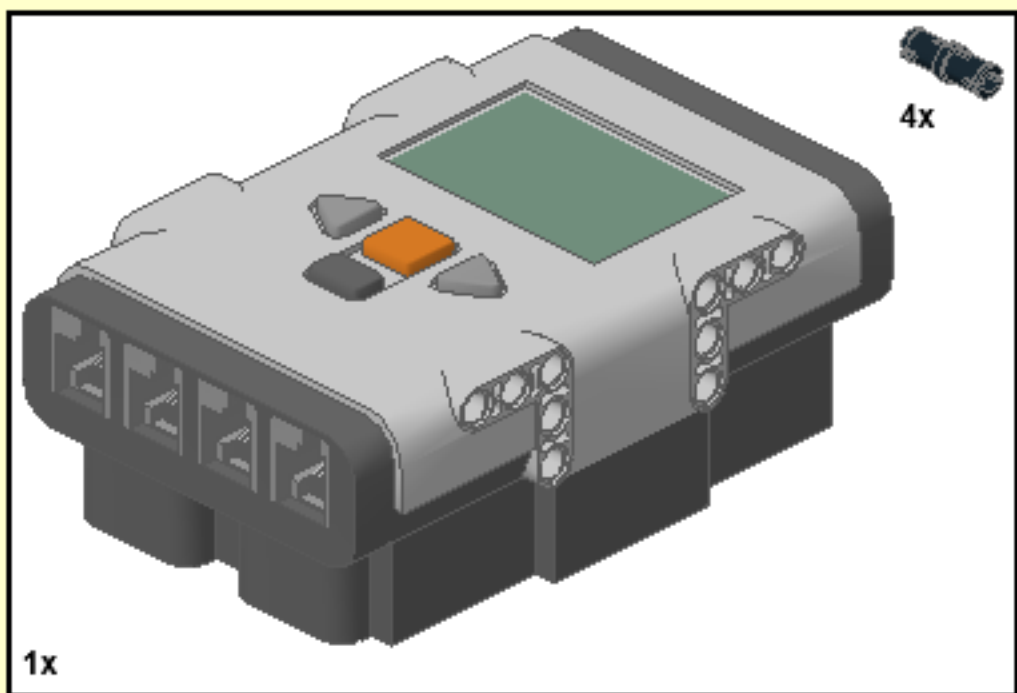


7

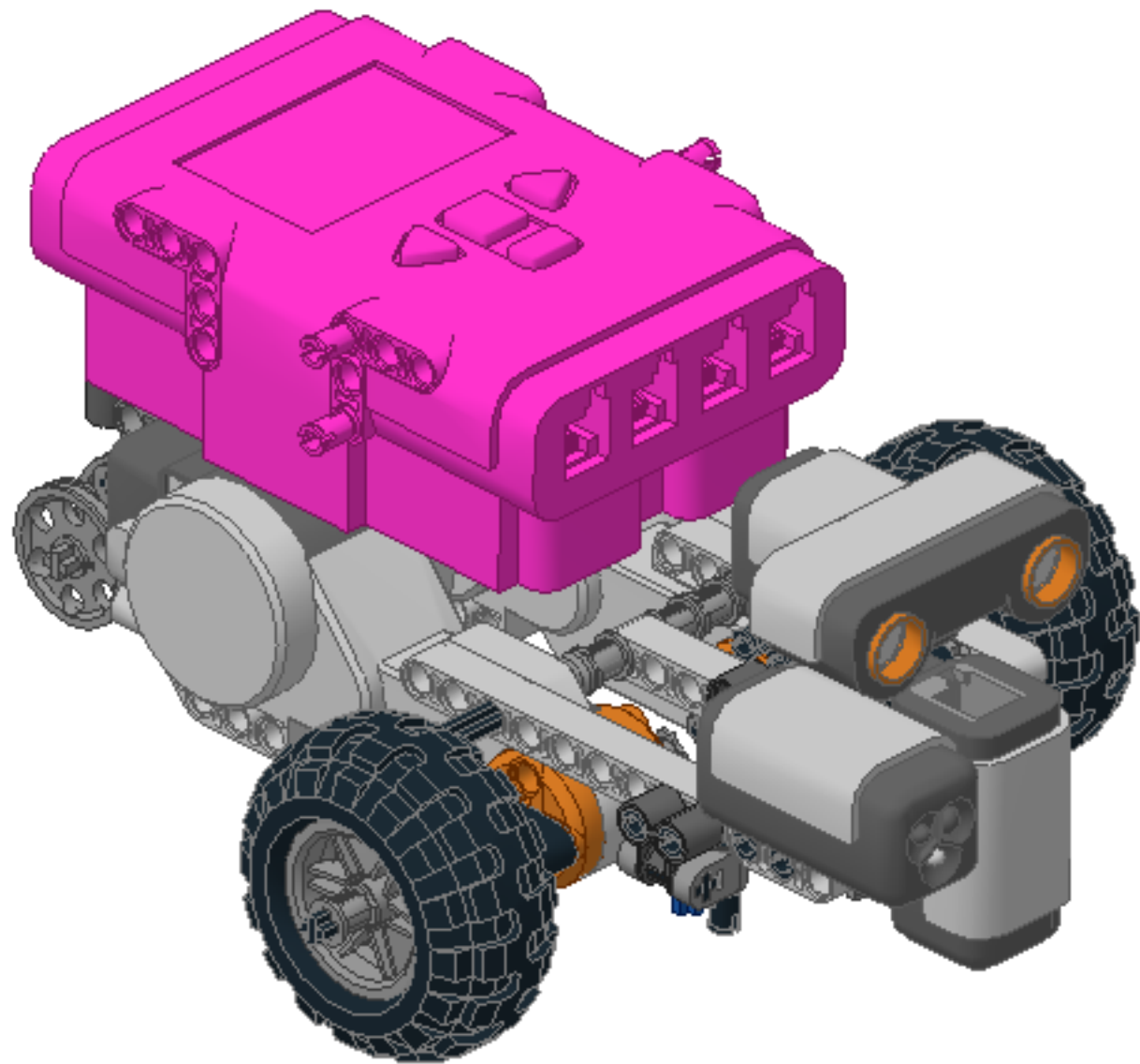
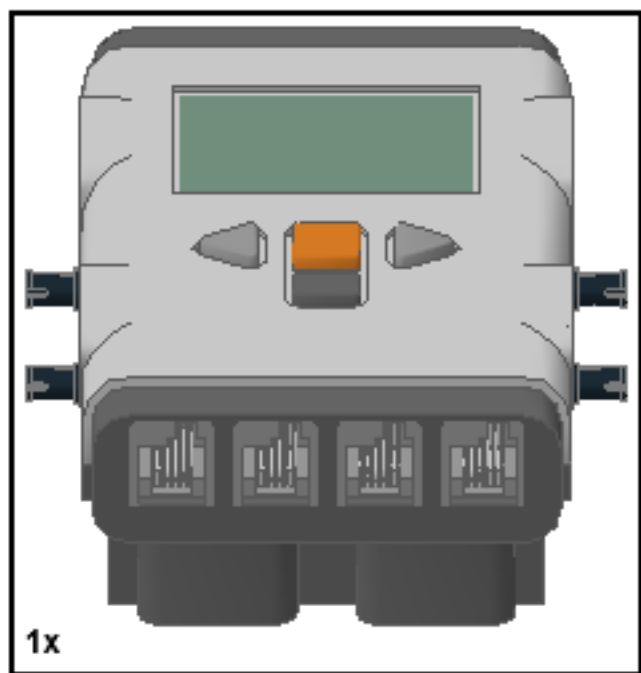


Move these two 3x1s up one unit. Picture is incorrect due to LDD rules

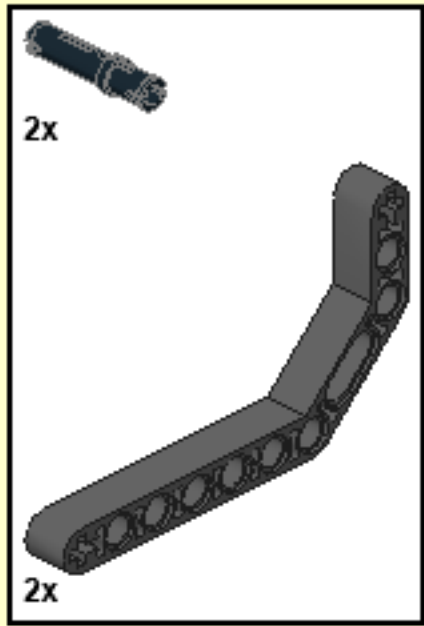
1



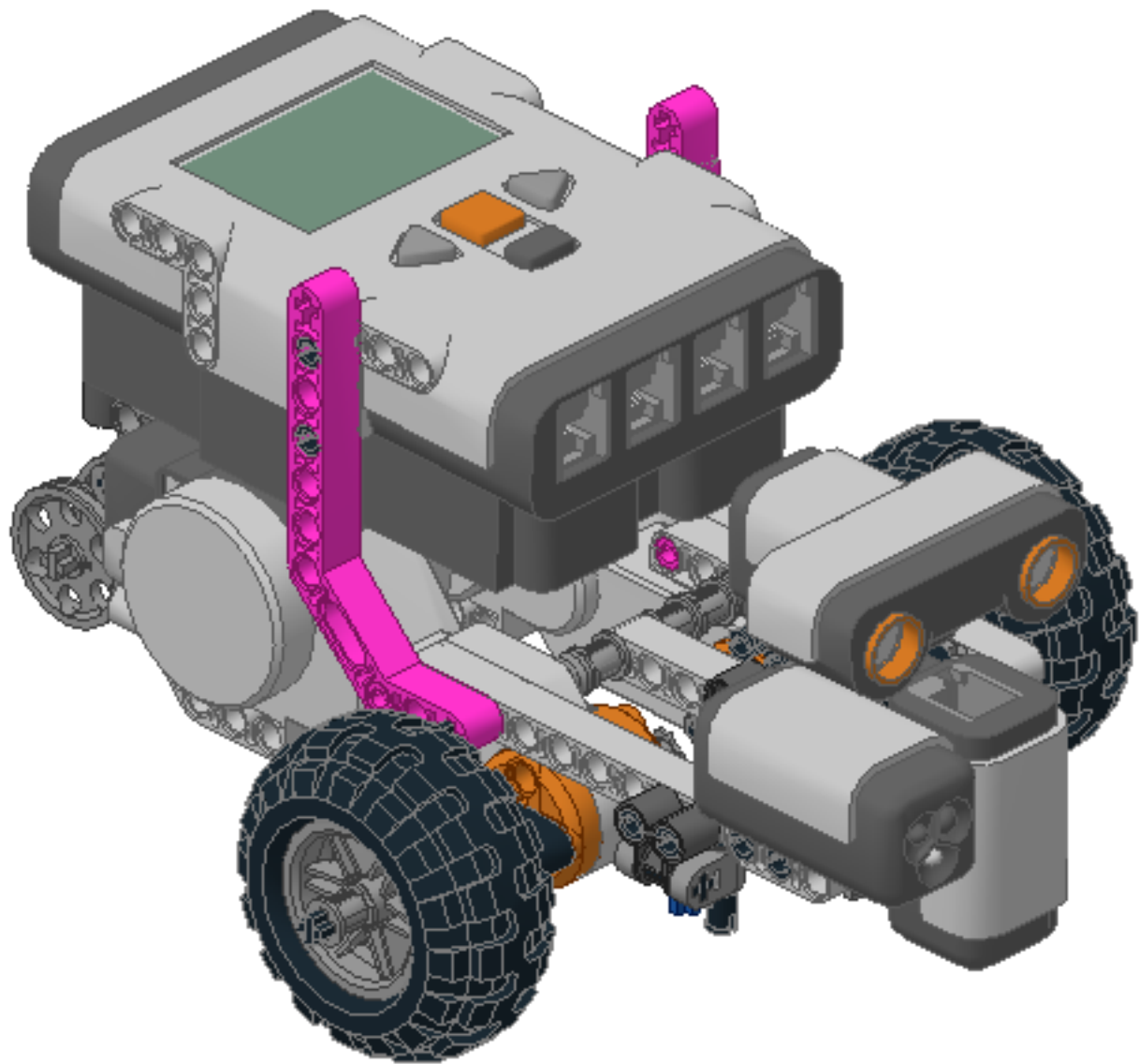
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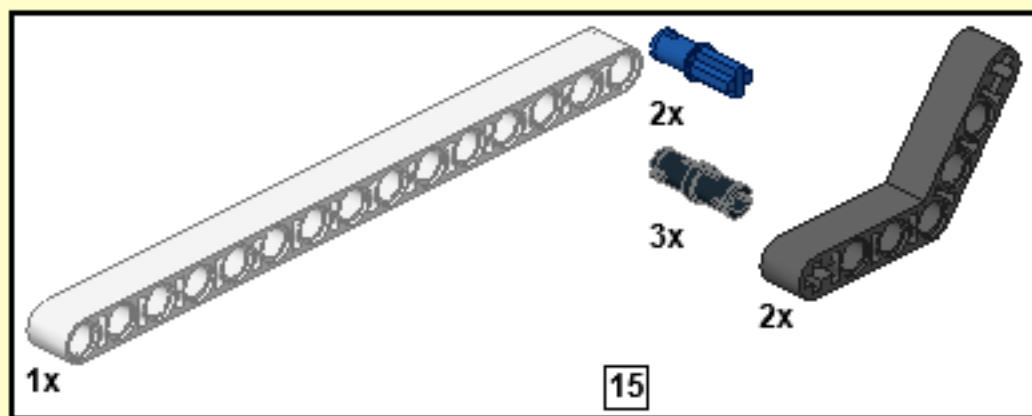
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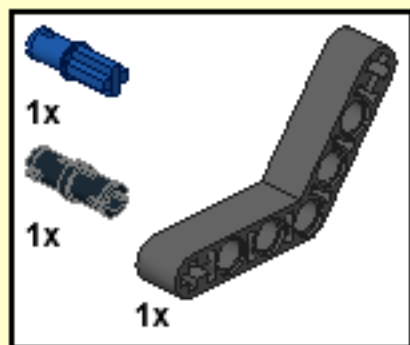
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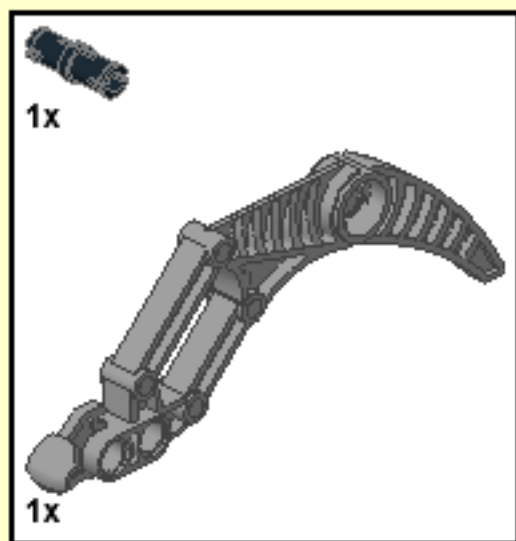
1



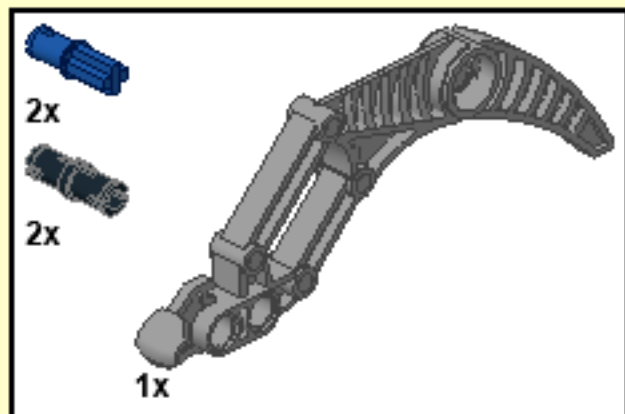
2



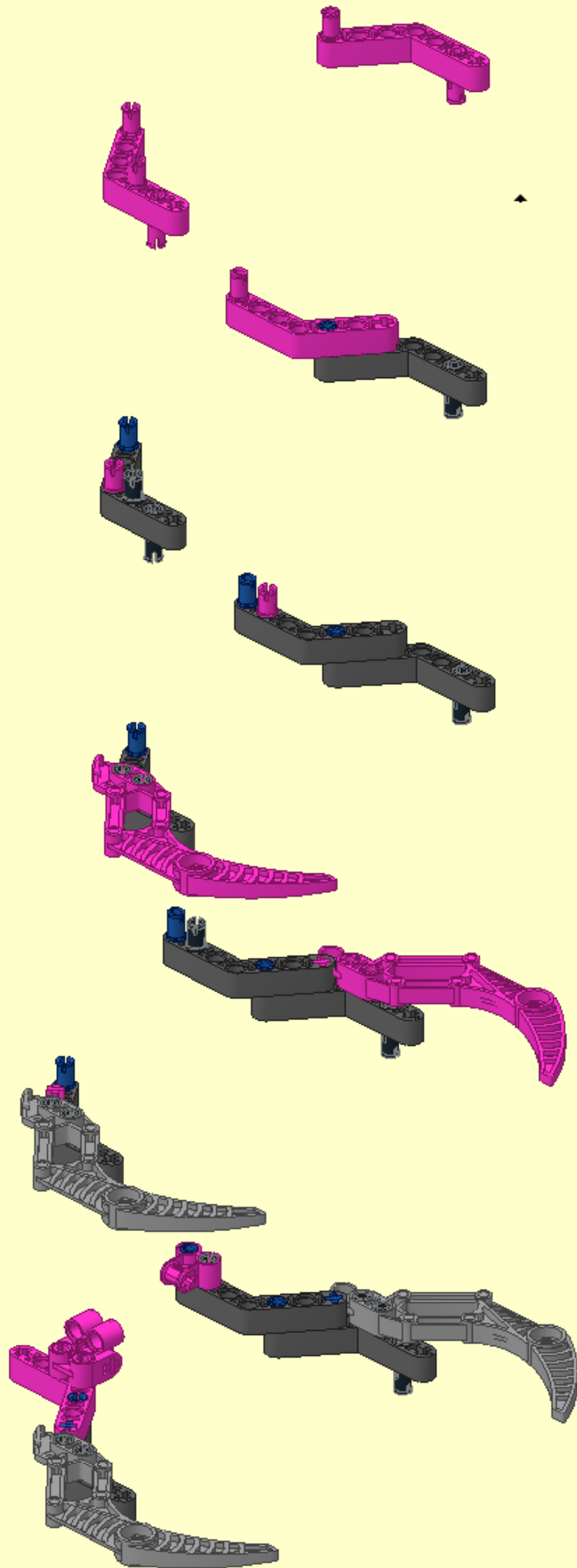
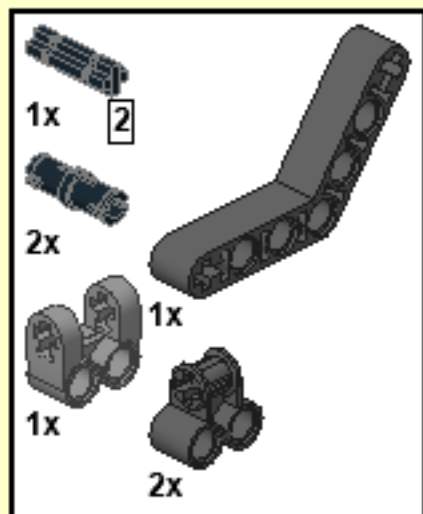
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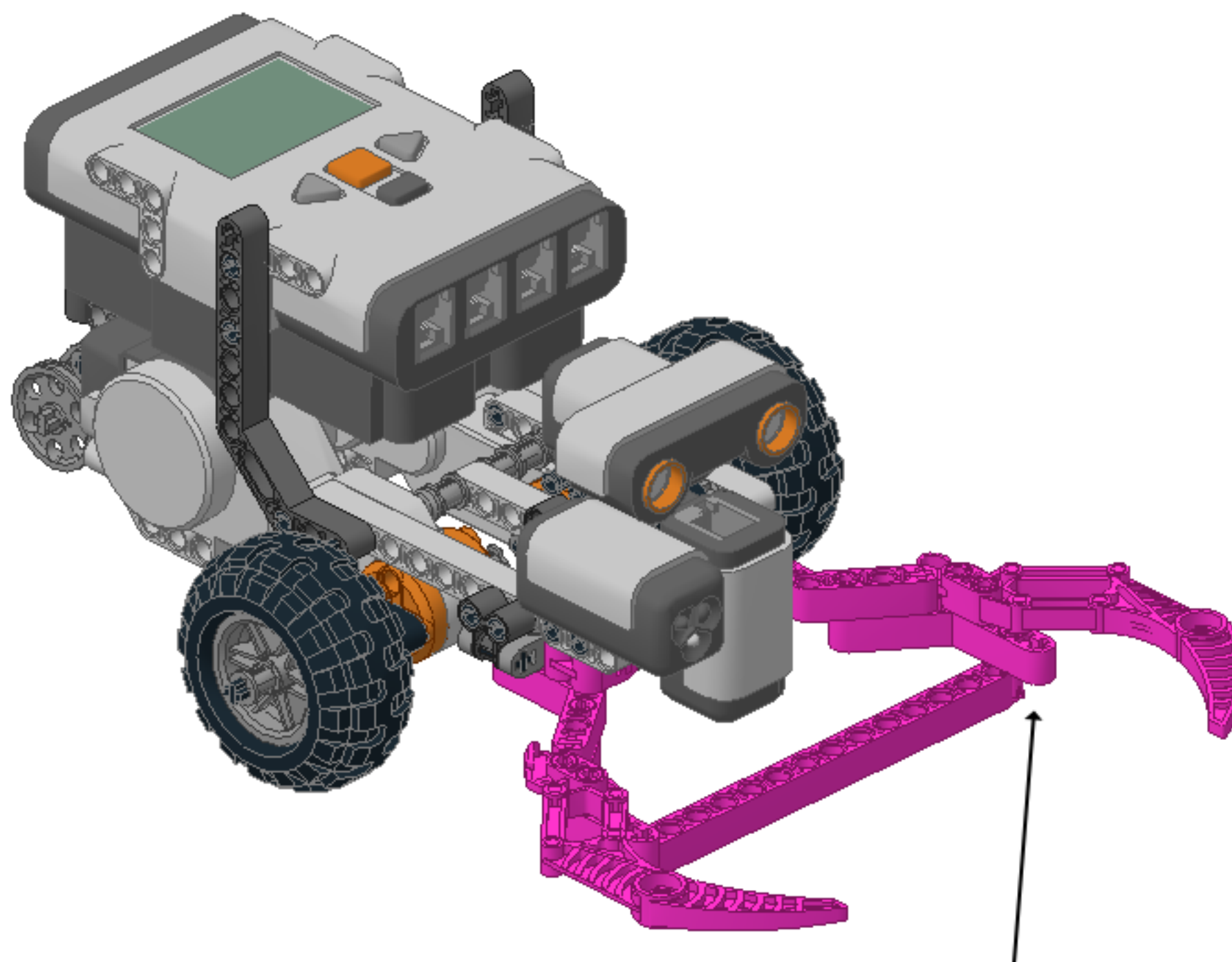
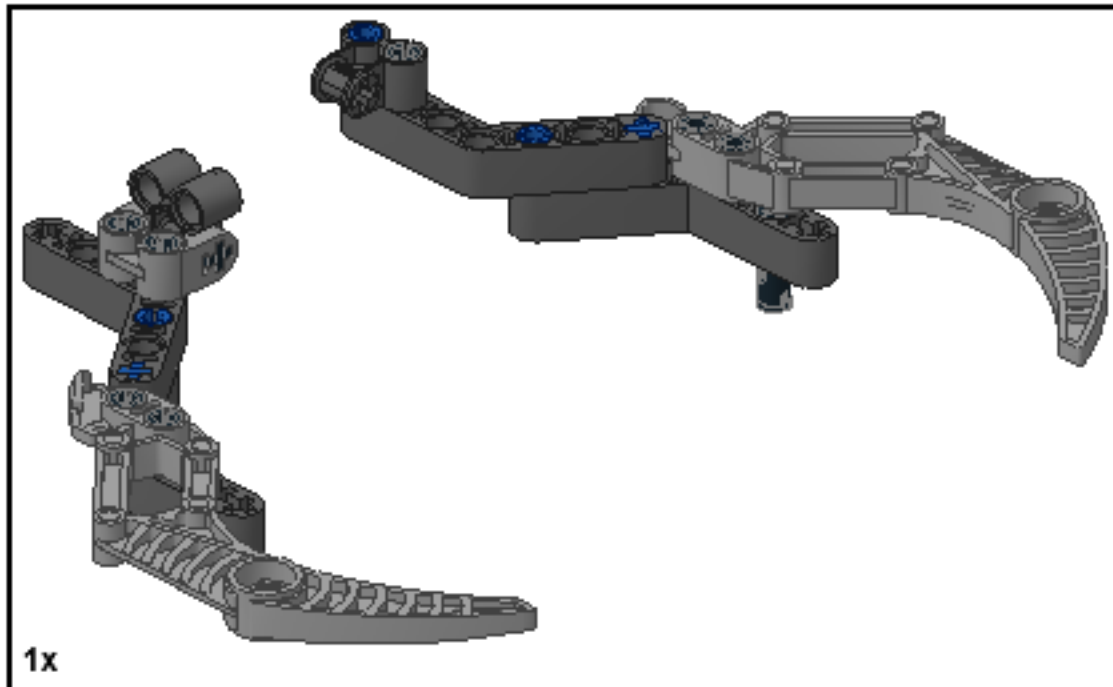


4



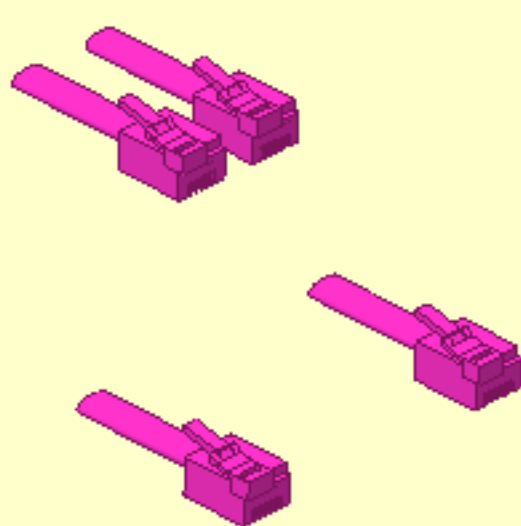
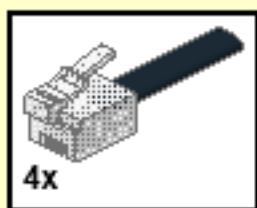
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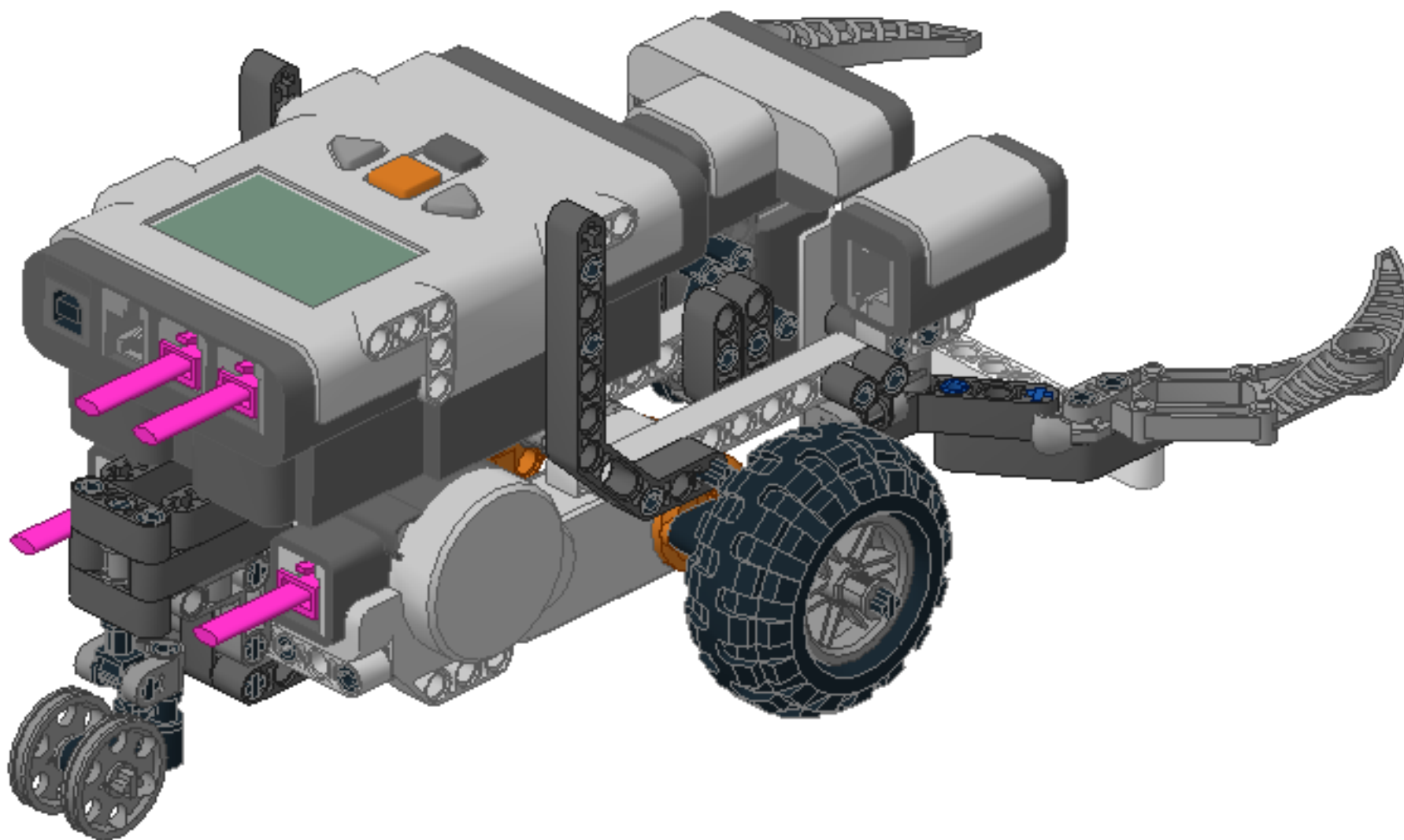
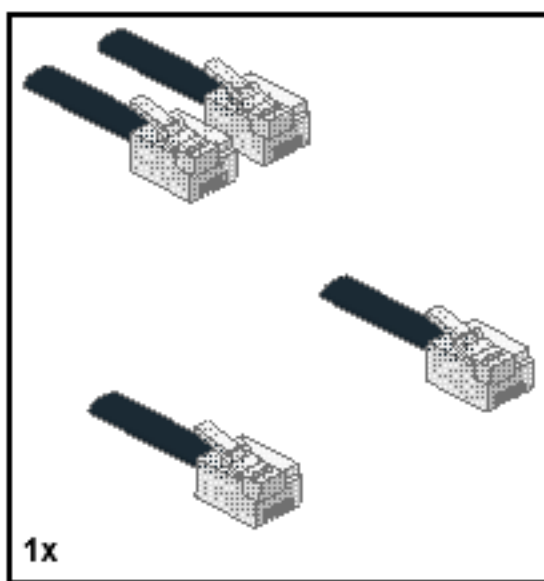




You'll have to bend the left claw arm a little to fit on to the crossbar.

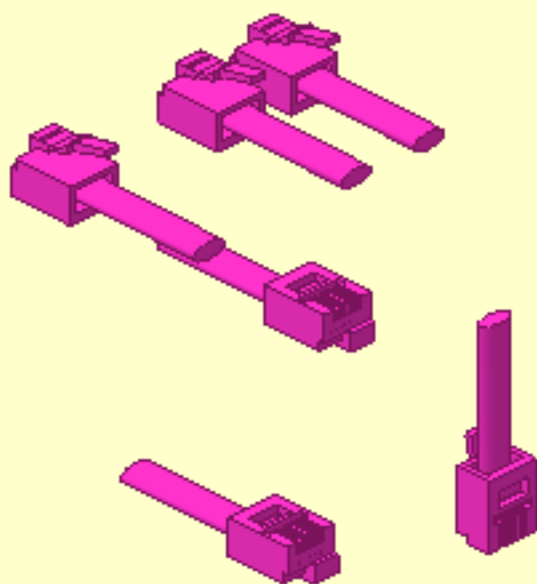
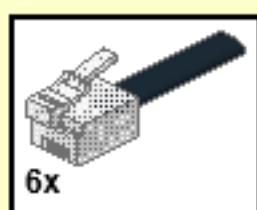
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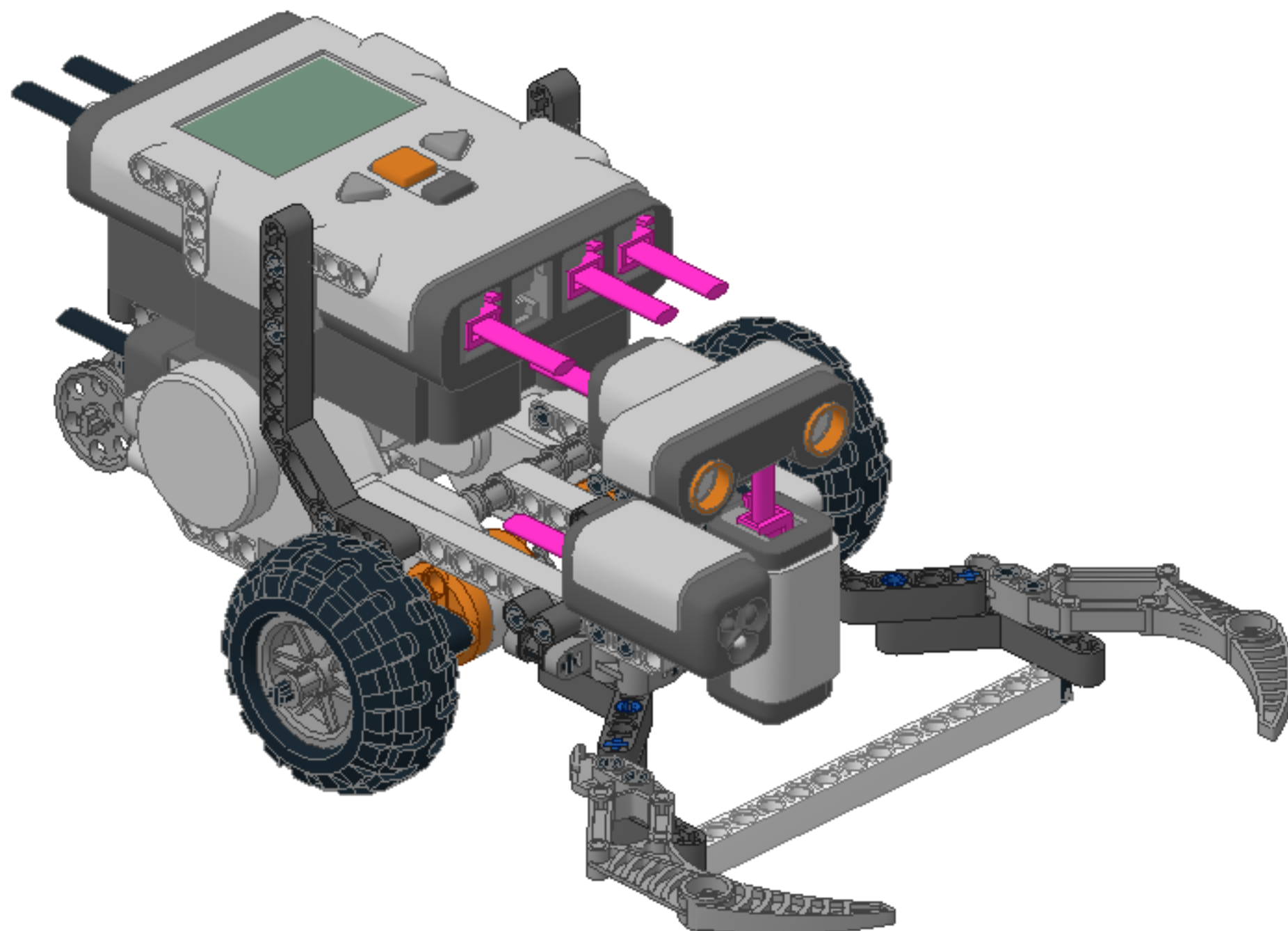
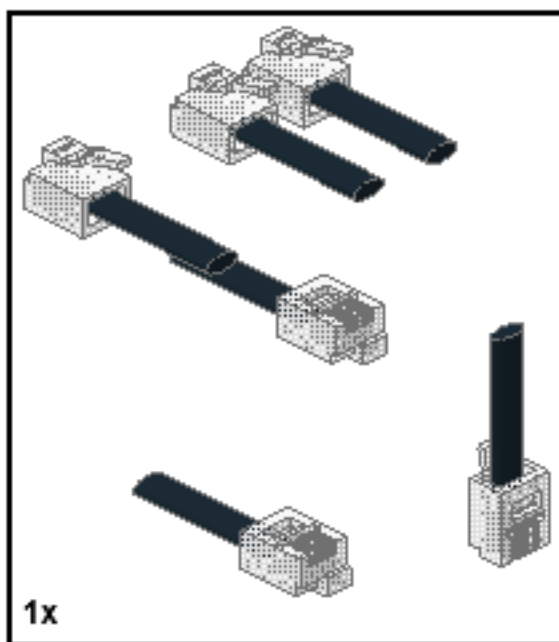




Wire B output to left motor and C output to right motor

1





Wire input 1 to RGB sensor, input 2 to ultrasonic sensor, and input 3 to light sensor



