

KAYMIE SHIOZAWA

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| Education | Massachusetts Institute of Technology (MIT) <i>Candidate for Bachelor of Science in Mechanical Engineering</i> GPA: 4.8/5.0 | Cambridge, MA June 2019 |
| Relevant Experience | <u>MIT D'Arbeloff Lab</u> <i>Undergraduate Researcher</i> <ul style="list-style-type: none">• Employing gaze tracking to distinguish a human operator's focus points; using Neural Networks to find trends• Designed a base, adding a degree of freedom, for current excavation arm model through 3D modeling (CAD), material selection, and manufacturing methods such as water jetting and milling• Selected as a scholar for SuperUROP, a competitive yearlong advanced research program, writing a paper <u>ISEE, Inc.</u> (Autonomous Vehicle Startup at The Engine) <i>Mechanical Design Engineer</i> <ul style="list-style-type: none">• Designing hardware components for sensors using CAD to be mounted on autonomous vehicles• Developing PID steering and speed control of unconventional autonomous vehicles <u>Lockheed Martin Advanced Technology Center</u> <i>Mechanical Structural/Robotics Engineer</i> <ul style="list-style-type: none">• Conducted vibration analysis verifying the integrity of 3 high value PCBs to withstand spacecraft launch• Implemented code to remotely control waypoint-navigating robots; designed 3D printed processor board mounts consisting of a clip, removing the need for fasteners• Presented findings to 30+ executives and coworkers <u>Haemonetics Corporation</u> (Medical Devices) <i>Mechanical Design Engineer</i> <ul style="list-style-type: none">• Devised optical sensor components to improve blood separation; worked in the blood-lab to test & characterize• Collaborated with software, mechanical, and systems engineering teams to explore costs and manufacturability of various sensing techniques, while gaining hands-on experience in rapid prototyping• Presented to managers of the project and executive members of the company, as well as 15 coworkers <u>CEA-LETI: Embedded Micro Batteries Laboratory</u> <i>Research Engineer</i> <ul style="list-style-type: none">• Determined properties of battery electrolytes using electrical impedance characterization for efficient batteries• Presented findings to lab of 40 people; cooperated and communicated with team of 5 members in French | Cambridge, MA Sept. 2017 – Present Cambridge, MA Sept. 2018 – Present Palo Alto, CA June – Aug. 2018 Braintree, MA June – Aug. 2017 Grenoble, France June – Aug. 2016 |
| Skills | Languages: English, Japanese, French Software Experience: SolidWorks, MATLAB, Python, Arduino, C++ Hardware Experience: Lathe and Mill, Welding, Laser Cutting, Water Jetting, 3D Printing | |
| Leadership | Pi Tau Sigma: National Mechanical Engineering Honor Society <i>Professional Development Coordinator</i> <ul style="list-style-type: none">• Top 25% of class eligible for membership• Organizing info sessions and student-faculty lunches using a budget of \$10,000+ Japanese Society of Undergraduates <i>Treasurer</i> <ul style="list-style-type: none">• Organizing cultural activities using a budget of \$700 every semester to involve entire campus with club Japan Karate Association/MIT Shotokan Karate Club <i>President of MIT Club</i> Freshman Pre-Orientation Program: Discover Product Design at MIT <i>Co-coordinator & Mentor</i> <ul style="list-style-type: none">• Mentored incoming students in a weeklong program introducing them to ideation, prototyping, and CAD• Managed a budget of \$7,000; Collaborated with MIT faculty to organize the entire program | Mar. 2018 – Present Aug. 2016 – Present Feb. 2016 – Present Aug. 2015 – 2018 |
| Awards/ Scholarship | John and Miyoko Davey Foundation Merit Scholarship <ul style="list-style-type: none">• One of 3 awardees for partial tuition coverage of \$20,000 2.12 Introduction to Robotics <ul style="list-style-type: none">• Designed, fabricated, and controlled a robotic arm and serial elastic actuator to aid hemiplegic patients• Awarded Most Valuable Engineer of the team by peers and professors; Team placed 2nd Manufacturing and Design Robotics Competition <ul style="list-style-type: none">• Placed Top 32/160 MIT Autonomous Robotics Competition <i>Mechanical Co-Lead</i> <ul style="list-style-type: none">• Designed mechanisms that consistently completed the task and cooperated with software and electrical leads• Placed 2nd, Won the Two Sigma Prize | 2018 – 2019 Sept. – Dec. 2017 Feb. – Apr. 2017 Jan. 2016 |