

# System FC and type inference

## Advanced functional programming - Lecture 9

Wouter Swierstra and Alejandro Serrano



# System FC or GHC Core

System  $F_\omega$  plus

- ▶ Algebraic data types and pattern matching
- ▶ `let` bindings as a primitive
- ▶ Coercions (build-in equality proofs)
- ▶ Promoted data types
- ▶ Roles (not discussed here)



Your usual  $\lambda$ -calculus where

- ▶ Abstractions are annotated with the type
- ▶ Type abstraction and application is explicit

e	::=	x	(variables)
		e e	(application)
		$\lambda (x : \tau) . e$	(abstraction)
		e @ $\tau$	(type application)
		$\Lambda (\alpha : \kappa) . e$	(type abstraction)

For example, here is how we define and use id

```
id =  $\Lambda (\alpha : *) . \lambda (x : \alpha) . x$   
> id @Bool True
```



# ADTs and pattern matching

```
e ::= ...  
    | case e of  
        K x1 ... xn -> e  
        ...  
        L y1 ... ym -> e
```

- ▶ Pattern matching is only allowed to look at one layer
  - ▶ Complex pattern have to be turned into a case-tree
- ▶ Operationally, case drives evaluation



# Coercions – the C in FC

Built-in version of Equal data type

$e ::= \dots$   
|  $e \mid > \gamma$  (coercion application - cast)

$\gamma ::= \text{refl}$  (reflexivity)  
|  $\text{sym } \gamma$  (symmetry)  
|  $\gamma_1 ; \gamma_2$  (transitivity)  
|  $K \gamma_1 .. \gamma_n$  (same constructor)  
|  $\dots$

$\tau ::= \dots$   
|  $\tau \sim \tau$  (type equality)



# Coercions – the C in FC

Take the following Haskell term

```
coerce :: a ~ b => a -> b  
coerce x = x
```

How does it look like in System FC?



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Take the following Haskell term

```
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How does it look like in System FC?

```
coerce =  $\Lambda$  (a : *).  $\Lambda$  (b : *).  
          $\lambda$  ( $\gamma$  : a ~ b).  
          $\lambda$  (x : a). x |>  $\gamma$ 
```



# Promoted data types and more kinds

We only need to enlarge the language of types and kinds

$\kappa$	$::=$	$*$	(ground <b>type</b> )
		<b>Constraint</b>	(constraint types)
		$\kappa \rightarrow \kappa$	( <b>type</b> constructor)
		<b>T</b> $\kappa \dots \kappa$	(promoted <b>type</b> constructor)
		$\forall \alpha . \kappa$	(polymorphic kind)

$\tau$	$::=$	$\dots$	
		$\forall (\alpha : \kappa) . \tau$	( <b>type</b> abstraction)
		$\forall \alpha . \tau$	(kind abstraction)
		$\tau \tau$	( <b>type</b> application)
		$\tau \kappa$	(kind application)
		<b>K</b> $\tau \dots \tau$	(promoted <b>data</b> constructor)





# TypeInType

There was a lot of duplication in the previous slide!

$\kappa, \tau$	$::=$	$*$	(ground <b>type</b> )
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		$\tau \ \tau$	(application)
		$\forall (\alpha : \kappa) . \tau$	(abstraction)



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How do we ever finish writing a type?

Just make  $*$  :  $*!$

- ▶ Breaks any possibility of using Haskell as a sound logic
- ▶ Dependent languages have a tower of universes instead



# Where are type classes?

Type classes are translated to *records*

- ▶ This is called the *dictionary translation*



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Type classes are translated to *records*

- This is called the *dictionary translation*

```
class Show a where
  show :: a -> String
==>
data ShowDict a = ShowDict { show :: a -> String }

shout :: Show a => a -> String
shout x = show x ++ "!"
==>
shout :: ShowDict a -> a -> String
shout sd a = show sd x ++ "!"
```



# Dictionary translation, arguments

```
shout :: ShowDict a -> a -> String  
shout sd a = show sd x ++ "!"
```

Try to write it as a System FC term!



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```
shout :: ShowDict a -> a -> String  
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Try to write it as a System FC term!

```
shout =  $\Lambda$  (a : *).  $\lambda$  (sd : ShowDict a).  $\lambda$  (x : a).  
    (++) @Char (show @a sd x)  
    ((:) @Char '!' ([] @Char))
```



# Dictionary translation, instances

- ▶ Simple instances are plain values

```
boolShow :: ShowDict Bool
boolShow = ShowDict $ \x ->
  case x of
    True  -> "True"
    False -> "False"
```

- ▶ Recursive instances are functions

```
maybeShow :: ShowDict a -> ShowDict (Maybe a)
maybeShow sd = ShowDict $ \x ->
  case x of
    Nothing -> "Nothing"
    Just y   -> "Just " ++ show sd y
```



# Dictionary translation, superclasses

Superclasses appear as fields of the child class

```
class Eq a => Ord a where
  compare :: a -> a -> Ordering
==>
data OrdDict a = OrdDict {
    eqDict  :: EqDict a,
    compare :: a -> a -> Ordering
}
```





# The need for inference

In surface Haskell many information is implicit

- ▶ Type abstraction and application
- ▶ Dictionaries for type class instances

On the other hand they are explicit in System FC

Inference is the process of obtaining that information



# Types and free variables

Question:

How do we assign a type to a term with free variables?

`plus x one`



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## Question:

How do we assign a type to a term with free variables?

`plus x one`

## Answer

We cannot unless we know the types of the free variables.



# Environments

We therefore do not assign types to terms, but types to terms in a certain *environment* (also called *context*).

## Environments

```
 $\Gamma ::= \varepsilon$            -- empty environment  
|  $\Gamma, x : \tau$       -- binding
```

Later bindings for a variable always shadow earlier bindings.



# The typing relation

A statement of the form  $\Gamma \vdash e : \tau$  means “in environment  $\Gamma$ , term  $e$  has type  $\tau$ ”.

This defines a ternary *relation* between an environment, a term and a type.

The  $\vdash$  (called turnstile) and the colon are just notation for making the relation look nice but carry no meaning. We could have chosen the notation  $T(\Gamma, e, \tau)$  for the relation as well, but  $\Gamma \vdash e : \tau$  is commonly used.



# Type rules

The relation is defined inductively, using *inference rules*.

## Variables

$$\frac{x : \tau \in \Gamma}{\Gamma \vdash x : \tau}$$

- ▶ Above the bar are the *premises*.
- ▶ Below the bar is the *conclusion*.
- ▶ If the premises hold, we can infer the conclusion.



# (Hindley-)Damas-Milner type inference

Mainly based on a paper by Milner (1978).

This algorithm is:

- ▶ the basis of the algorithm used for the ML family of languages as well as Haskell;
- ▶ allows type inference essentially for the simply-typed lambda calculus extended with a limited form of polymorphism (sometimes called *let*-polymorphism);
- ▶ is a “sweet spot” in the design space: some simple extensions are possible (and performed), but fundamental extensions are typically significantly more difficult.



# Monotypes and type schemes

Damas-Milner types can be polymorphic only on the outside.

That is why Haskell typically does not use an explicit universal quantifier.

## Monotypes

Monotypes  $\tau$  are types built from variables and type constructors.

## Type schemes (or polytypes)

```
 $\sigma ::= \tau$            -- monotypes  
      |  $\forall \alpha . s$   -- quantified type
```





# The key idea

The Damas-Milner algorithm distinguishes lambda-bound and let-bound (term) variables:

- ▶ lambda-bound variables are always assumed to have a monotype;
- ▶ let-bound variables, we know what they are bound to, therefore they can have polymorphic type.



# Inference variables

Whenever a lambda-bound variable is encountered, a *fresh* inference variable is introduced. The variable represents a monotype.

When we learn more about the types, inference variables can be substituted by types.

Inference variables are different from universally quantified variables that express polymorphism.



# Term language

```
e ::= x           -- variables
    | e e         -- application
    | \x -> e      -- abstraction
    | let x = e in e -- let binding
```

Only a simple language to start with, but we include `let` compared to plain lambda calculus.



# Example

Assume an environment  $\Gamma = \text{neg} : \text{Nat} \rightarrow \text{Nat}$ .

Consider inferring the type of the expression  $\lambda x \rightarrow \text{neg } x$ .

For  $x$ , we introduce an type variable  $v$  and assume  $x : v$ .



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We now unify  $\text{Nat}$  and  $v$ , introducing the substitution:

$v \mapsto \text{Nat}$ .



# Generalization and instantiation

```
let id = \x -> x in (id False, id 'x')
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Inference for  $\lambda x. \lambda y. x$  gives us the type  $v \rightarrow v$  for some inference variable  $v$ , and there are no further assumptions about  $v$ .





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For every use, a polymorphic type is instantiated with fresh inference variables. For example, we get  $w \rightarrow w$  for the first call,  $u \rightarrow u$  for the second.



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For every use, a polymorphic type is instantiated with fresh inference variables. For example, we get  $w \rightarrow w$  for the first call,  $u \rightarrow u$  for the second.

The  $w$  gets unified with `Bool`, and  $u$  with `Char`.



# Generalization again

Assume: `singleton :  $\forall a . a \rightarrow [a]$`

`\ x -> (let y = singleton x in head y)`



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For  $x$ , an inference variable  $v$  is introduced.

Consequently, we infer the type `[v]` for `singleton x`.

But we must not generalize the type of  $y$  to  $\forall a . [a]$ .

We can only generalize if a variable is not mentioned in the environment.



# Motivation: unification

Question: What is the type of the following expressions?

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$u \mapsto \text{Char}, w \mapsto \text{Char}, v \mapsto \text{Bool}$

We are interested in the *minimal* substitution.

$v \mapsto w, u \mapsto \text{Char}$



# Preventing infinite types

What if we want to unify the types:

$u \quad u \rightarrow u$

A substitution  $u \mapsto u \rightarrow u$  would result in an infinite type. Most systems (including Haskell) reject infinite types, and make this a type error.



# Idea of the unification algorithm

We distinguish the following cases:

- ▶ if we have two equal variables, there is nothing to do;
- ▶ if we have an inference variable and another type that does not contain the inference variable (*occurs check* to prevent infinite types), we substitute the variable by the other type;
- ▶ if we have two function types, we recursively unify the domains and codomains;
- ▶ if we have any other situation, unification fails.



# Principal types

There is a similar notion for types as we had for unifications. One type can be more general than another:

$a \rightarrow b$   
 $(a, b) \rightarrow (b, a)$   
 $(a, a) \rightarrow (a, a)$   
 $(\text{Int}, \text{Int}) \rightarrow (\text{Int}, \text{Int})$

Damas-Milner type inference always infers the most general type (called the *principal type*).



# Everything is a lie

This is not how *modern* GHC does type inference



# Constraint-based type inference

Type checking and inference is a two-step process

## 1. *Constraint generation or gathering*

- ▶ Obtains a set of constraints which describe the relations between types in the program
- ▶ **Cannot** fail, except for ill-scoped variables

## 2. *Constraint solving*

- ▶ Finds a solution for the set of constraints
- ▶ Works by rewriting the constraints into simpler forms



# Constraint-based type inference, example

Take  $\Gamma = \text{neg} : \text{Nat} \rightarrow \text{Nat}$  and infer  $\lambda x. \text{neg } x$ .

1. We first assign a new fresh variable  $\alpha$  to  $x$ .
2. The type of  $\text{neg}$  is  $\text{Nat} \rightarrow \text{Nat}$  from the environment.
3. The type of  $x$  in the body is  $\alpha$  as introduced.
4. Since we have an application, we know that:
  - ▶ The type of the function must be  $\beta \rightarrow \gamma$ ;
  - ▶ The argument type  $\alpha$  has to coincide with  $\beta$ ;
  - ▶ The result type is  $\gamma$ .
5. The whole is an abstraction with a body of type  $\gamma$ .

In summary, we have the following two constraints,

$$\text{Nat} \rightarrow \text{Nat} \sim \beta \rightarrow \gamma \quad \alpha \sim \beta$$

and the inferred type of the expression is  $\alpha \rightarrow \gamma$ .





# Constraint gathering rules

$\Gamma \vdash e : \tau \rightsquigarrow C$  means “in the environment  $\Gamma$ , the expression  $e$  has type  $\tau$  whenever the constraints  $C$  are satisfied”.

$$\frac{x : \forall \bar{a}. \tau \in \Gamma \quad \bar{\alpha} \text{ fresh}}{\Gamma \vdash x : [\bar{a} \mapsto \bar{\alpha}] \tau \rightsquigarrow \top}$$



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$$\frac{\alpha \text{ fresh} \quad \Gamma, x : \alpha \vdash e : \tau \rightsquigarrow C}{\Gamma \vdash \lambda x. e : \alpha \rightarrow \tau \rightsquigarrow C}$$

$$\frac{\Gamma \vdash f : \tau_1 \rightsquigarrow C_1 \quad \Gamma \vdash e : \tau_2 \rightsquigarrow C_2 \quad \beta \text{ fresh}}{\Gamma \vdash f e : \beta \rightsquigarrow C_1 \wedge C_2 \wedge \tau_1 \sim \tau_2 \rightarrow \beta}$$



# Solving rules for equalities

Solving is done by rewriting constraints into simpler forms:

$\tau \sim \tau \implies$  -- remove it

$T \tau_1 \dots \tau_n \sim T \sigma_1 \dots \sigma_n$   
 $\implies \tau_1 \sim \sigma_1, \dots, \tau_n \sim \sigma_n$

$T \tau_1 \dots \tau_n \sim S \sigma_1 \dots \sigma_n$   
 $\implies$  error -- if  $T \neq S$

$\alpha \sim \tau \implies$  error -- if  $\alpha$  is free in  $\tau$

$\alpha \sim \tau, C \implies [\alpha \mapsto \tau]C$

We need some care to not end up in an infinite loop.



# Type signatures

There is no provision in the rules to handle:

```
duplicate :: [a] -> [a]  
duplicate xs = xs ++ xs
```

Using unification variables here is wrong. Why?



# Type signatures

There is no provision in the rules to handle:

```
duplicate :: [a] -> [a]  
duplicate xs = xs ++ xs
```

Using unification variables here is wrong. Why?

- ▶ This definition has to hold *for every* type  $a$ .
- ▶ A unification variable gets a type during solving.



# Rigid variables a.k.a. Skolems

A *rigid variable*  $a$  represents an type which exists but we cannot touch, assign or inspect.

$a \sim \tau \implies \text{error} \text{ -- if } \tau \neq a$

In the presence of type families, things get complicated.

- ▶ Keep working as much as you can.
- ▶ Check for wrong assignments after rewriting is finished.



# Type class constraints

Type signatures may have constraints,  $\forall \bar{a}. C \Rightarrow \tau$ .

- For example, show :: Show a => a -> String.

## Constraint generation

$$\frac{x : \forall \bar{a}. C \Rightarrow \tau \in \Gamma \quad \bar{a} \text{ fresh}}{\Gamma \vdash x : [\bar{a} \mapsto \bar{\alpha}] \tau \rightsquigarrow [\bar{a} \mapsto \bar{\alpha}] C}$$



# Type class constraints

## Constraint solving

What are the rewriting rules corresponding to these definitions?

1. `instance Eq Int`
2. `instance Eq a => Eq [a]`
3. `class Eq a => Ord a`





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```
Eq Int    ==>    -- remove it
Eq [τ]    ==>    Eq τ
Ord τ     ==>    Eq τ, Ord τ  -- keep Ord
```

See *Understanding Functional Dependencies via Constraint Handling Rules*



# Type class constraints and termination

```
instance C [a] => C a
```

```
C Int ==> C [Int] ==> C [[Int]] ==> ...
```



# Type class constraints and termination

```
instance C [a] => C a
```

```
C Int ==> C [Int] ==> C [[Int]] ==> ...
```

The compiler has an infinite loop!

We need conditions to prevent this situation

Caveat: this *is* the halting problem.

- ▶ Turing taught us that it is undecidable.
- ▶ Every heuristic is just an approximation.



# Classical termination conditions

1. Every instance must be of the form

`instance (C1, ..., Cn) => C (T a1 ... am)`

for a constructor T and distinct type variables a1 to am.  
If the class has multiple parameters, the constructor condition only has to apply to one of them.

2. The context in any type, class or instance declaration

`fn :: (C1, ..., Cn) => ...`

`class (C1, ..., Cn) => ...`

`instance (C1, ..., Cn) => ...`

must consist only of type classes applied to type variables (we say such contexts are *simple*).



# Patterson termination conditions

## FlexibleContexts and FlexibleInstances

For each class constraint  $C \text{ } t_1 \dots t_n$  in the context:

- ▶ No type variable has more occurrences in the constraint than in the head.
- ▶ The constraint has fewer constructors and variables (taken together and counting repetitions) than the head, in class and instance declarations.
- ▶ The constraint mentions no type families.

Intuitively, constraints *shrink* at every step of rewriting.



# Undecidable instances

Lifts the restrictions over termination of instances.

- ▶ *You* are responsible for checking termination.



# Assumptions

```
f :: Ord a => a -> a -> Bool
f x y = x == y
```

To handle this case we need to derive `Eq a` from `Ord a`.

- The solver takes an additional set of *assumptions*.

```
assu |- cons ==> new assu |- new cons
-- discharge rule
C      |- C      ==> C      |- -- remove
-- information may flow from assu to cons
α ~ τ |- C      ==> α ~ τ   |- [α ↦ τ]C
-- but not the other way around!
```

For GADTs we need *local* assumptions for each branch.



# Higher-rank types

## Question

What is the type of this expression?

```
\f -> (f 'a', f Bool)
```





# Higher-rank types

## Question

What is the type of this expression?

$\backslash f \rightarrow (f \text{ 'a'}, f \text{ Bool})$

A couple of non-comparable solutions

$(\forall a . a \rightarrow a) \rightarrow (\text{Int}, \text{Bool})$   
 $\forall r . (\forall a . a \rightarrow r) \rightarrow (r, r)$



# Higher-rank types

$(\forall a . a \rightarrow a) \rightarrow (\text{Int}, \text{Bool})$  is a *rank-2* type

- ▶ The  $\forall$  is buried one level deep at the *left* of an arrow.

## Question

Why do we insist on *left* on an arrow?

Why is  $(\text{Int}, \text{Bool}) \rightarrow (\forall a . a \rightarrow a)$  rank-1?



# Uses of higher-rank types

- ▶ Encapsulation of side effects:

`runST ::  $\forall$  v . ( $\forall$  s . ST s v) -> v`

- ▶ Dynamic types / Leibniz equality:

`data Equal a b = Equal ( $\forall$  f . f a -> f b)`

Roughly, a is equal to b if you can substitute one for the other in all contexts.

- ▶ Generic programming à la Scrap Your Boilerplate:

`everywhere :: ( $\forall$  b. Data b => b -> b)  
->  $\forall$  a. Data a => a -> a`



# Uses of higher-rank types

- ▶ van Laarhoven lenses:

```
type Lens s a =  $\forall$  f. Functor f  
              => (a -> f a) -> s -> f s  
type Prism s a =  $\forall$  f. Applicative f  
                => (a -> f a) -> s -> f s
```

- ▶ Dictionaries for higher-kinded types:

```
data MonadDict m where  
  MonadDict :: {  
    return ::  $\forall$  a . a -> m a  
    , (>=>) ::  $\forall$  a b . m a -> (a -> m b) -> m b  
  } -> MonadDict m
```



# Impredicative types

What if now we have a list with runST?

```
[runST]  ::  $\forall v . [(\forall s . \text{ST } s \ v) \rightarrow v]$   
          ::  $[\forall v . (\forall s . \text{ST } s \ v) \rightarrow v]$   
          -- the types are non-comparable
```

*Impredicativity* means that a type variable is instantiated with a polymorphic type.

- Damas-Milner restricts instantiation to monotypes.



# Impredicativity in the compiler

System FC is *fully impredicative*.

Type inference for System FC is *undecidable*.

- ▶ There is a good story for higher-rank types.
- ▶ We do not know yet how to do inference for impredicativity.

As a result, in current GHC:

- ▶ Higher-rank types are available with `RankNTypes`.
- ▶ `ImpredicativeTypes` is deprecated.
- ▶ If you really need impredicativity, you need to annotate *every* instantiation using `TypeApplications`.



# Summary

- ▶ GHC uses System FC as a target for compilation.
  - ▶ Typed lambda-calculus + data types + coercions
  - ▶ Type classes are translated to *dictionaries*.
  - ▶ Types are fully explicit.
- ▶ *Inference* obtains the explicit information from the source code.
  - ▶ Hindley-Damas-Milner is the classic approach.
  - ▶ Nowadays, inference uses constraints.

