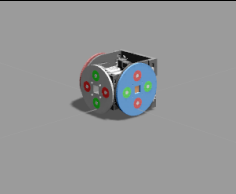
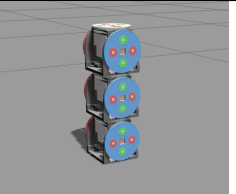
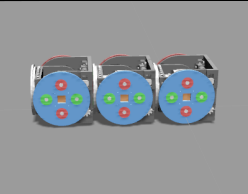
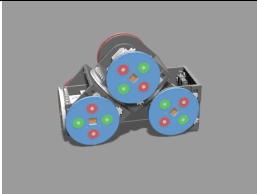
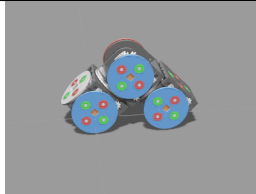


Configuration					
	DRIVER1	LEG3	BODY3	STEER3	SNAKE3
Behaviors	$Drive(v, t)$ $TiltMiddleUp()$	$Step()$	$HoldRigid()$	$Steer(\theta)$ $DriveSideWheels(v, t)$	$Wiggle()$ $AntiWiggle()$