Config-			
uration	CHAIN18	CAR	CHAIN6
Compo- nents	CHAIN3 ×6	CHAIN3 MODULE ×4	CHAIN3 ×2
Beha- viors	Sine Gait 18 ()	$egin{aligned} Drive(v,t)\ Turn( heta) \end{aligned}$	$Drive(v,t), Turn(\theta) \ HoldRigid()$