Config- uration		040			
	DRIVER1	LEG3	BODY3	STEER3	SNAKE3
Behaviors	$Drive(v,t) \ TiltMiddleUp()$	Step()	HoldRigid()	$egin{array}{c} Steer(heta) \ DriveSideWheels(v,t) \end{array}$	$Wiggle() \ AntiWiggle()$