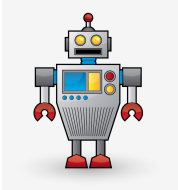
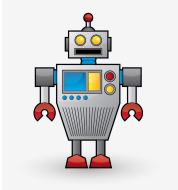
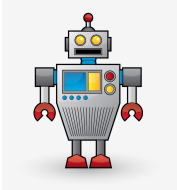
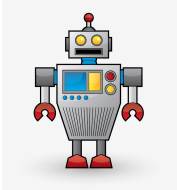


Configuration				
	WALK4	SNAKE6	CAR	DRIVER5
Components	BODY3 LEG3 $\times 4$	SNAKE3 $\times 2$	STEER3 DRIVER1 $\times 4$	STEER3 DRIVER1 $\times 2$
Behaviors	<i>Walk(t)</i>	<i>Slither()</i>	<i>DRIVE(v, t)</i> <i>TURN(θ)</i>	<i>DRIVE(v, t)</i> <i>TURN(θ)</i>