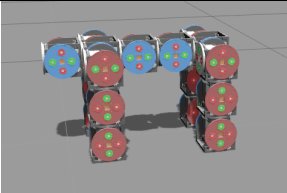
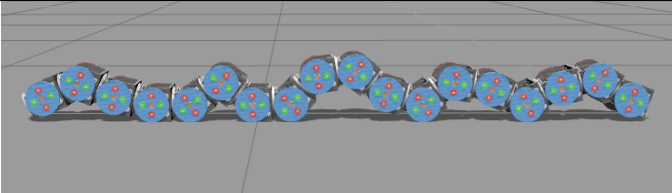
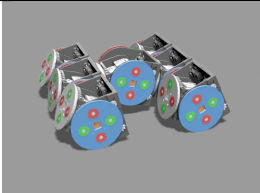
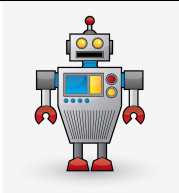


| | | | | |
|---------------|--|---|---|---|
| Configuration |  |  |  |  |
| | WALK4 | SNAKE18 | CAR | DRIVER5 |
| Components | BODY3 LEG3 \times 4 | SNAKE3 \times 6 | STEER3 DRIVER1 \times 4 | STEER3 DRIVER1 \times 2 |
| Behaviors | $Walk(t)$ | $Slither()$ | $DRIVE(v, t)$ $TURN(\theta)$ | $DRIVE(v, t)$ $TURN(\theta)$ |