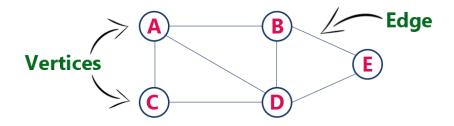
# Graphs

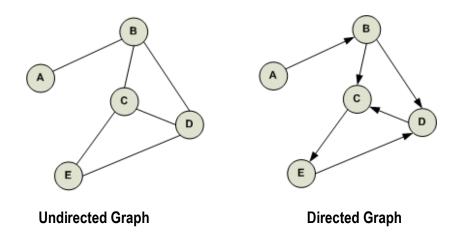
Department of Computer Science & Engineering The Pennsylvania State University

#### Graph

 A graph is a data structure with nodes (also called vertices) that are connected by edges

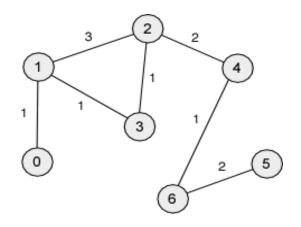


Graphs can be directed or undirected

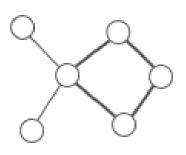


#### Graph

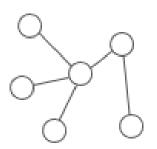
The edges could represent distance or weight



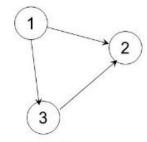
• A graph might contain cycles



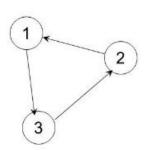
CYCLIC GRAPH



ACYCLIC GRAPI



acyclic



cyclic

#### **Key Terms**

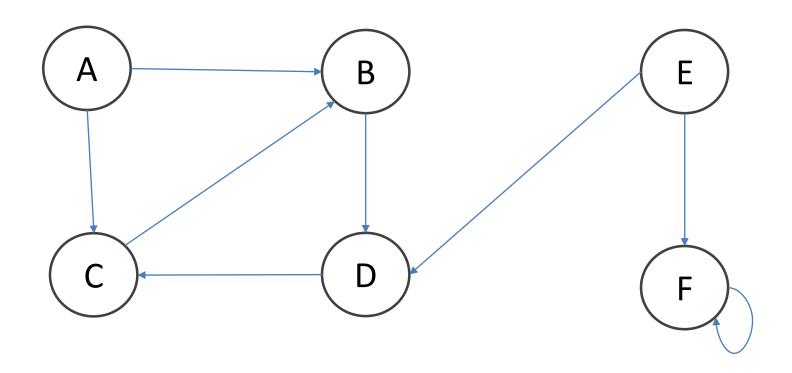
- Vertex (Node): a fundamental part of a graph. It can have a name and additional information
- **Edge**: connects two vertices to show that there is a relationship between them. Edges may be one-way or two-way
- Weight: edges may be weighted to show that there is a cost to go from one vertex to another
- Path: sequence of vertices that are connected by edges
- **Cycle**: A cycle in a directed graph is a path that starts and ends at the same vertex. A graph with no cycles is called an acyclic graph. A directed graph with no cycles is called a directed acyclic graph (DAG)

A graph can be represented as G=(V,E), where V is a set of vertices and E is a set of edges. Each edge is a tuple (v,w) where  $w,v \in V$ .

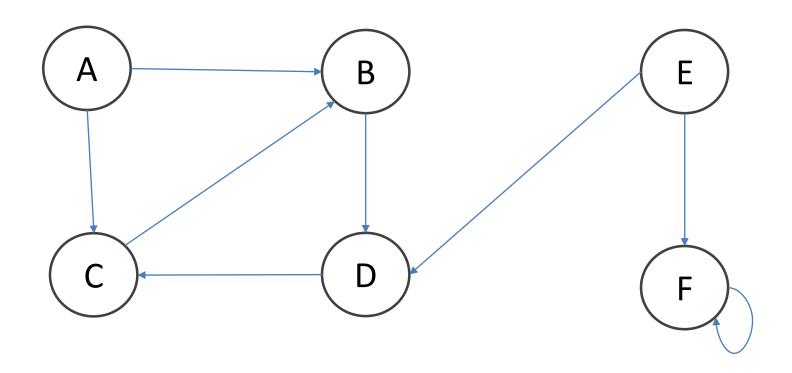
#### **Edges**

- Tree Edge: edges that we encounter while down one path of a graph
- Non-tree edge:
  - ✓ Forward Edge: it allows us to move "forward" through the graph, and could potentially be part of another path down the tree.
  - ✓ Backward edge: connects a node in a graph "back up" to one of its ancestors (its parent, grandparent or itself).
  - ✓ Cross edge: connects to sibling nodes that don't necessarily share an ancestor in a tree path, but connects them anyways.
- In an undirected graph, there are no forward edges or cross edges. Every single edge must be either a tree edge or a back edge

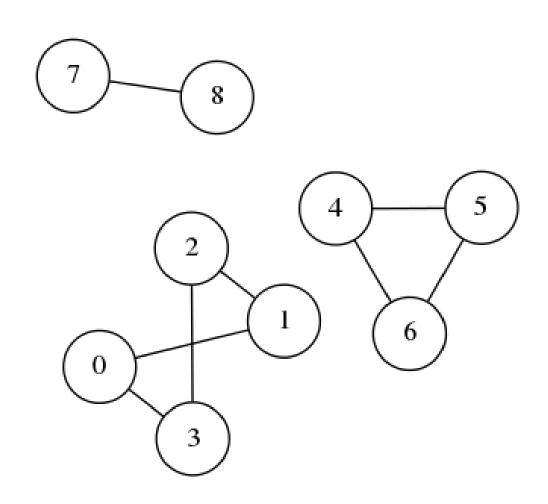
# **Edges**



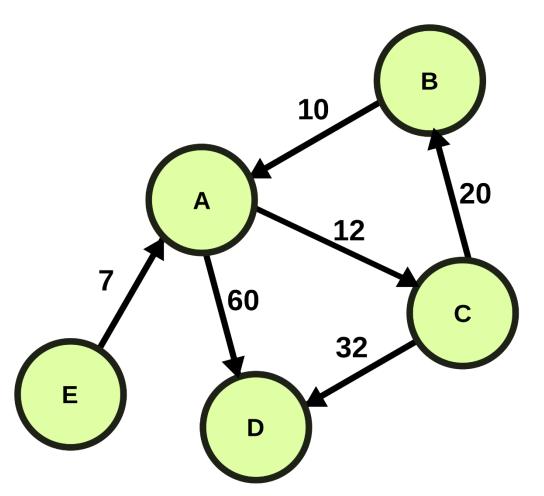
# **Edges**



# **Connected Components**



#### Graph



*G*=(*V*,*E*) where:

 $V = \{A, B, C, D, E\}$  $E = \{(A,C,12), (A,D,60), (B,A,10), (C,B,20), (C,D,32), (E,A,7)\}$ 

Path from A to B = (A, C, B)

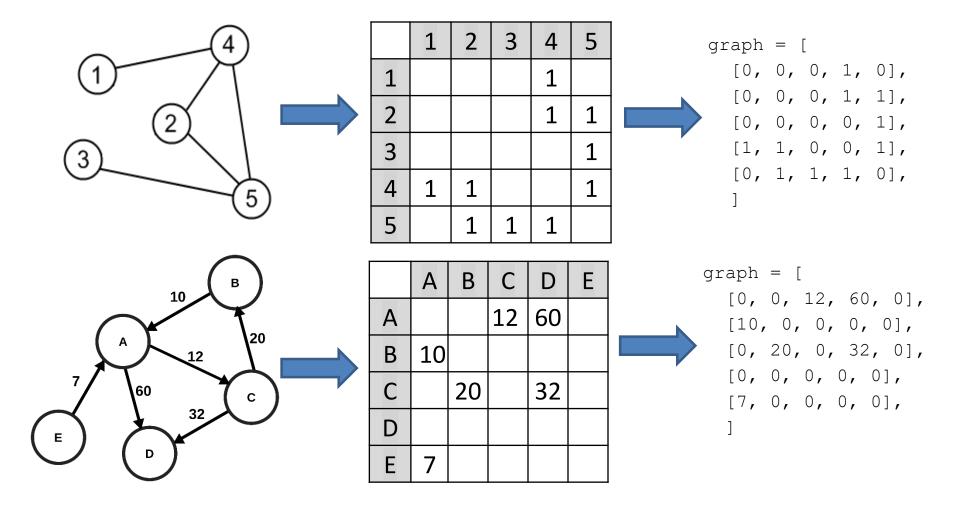
Cycle = (A, C, B, A)

#### **Graph Implementation**

#### Adjacency Matrix

ADJACENT NODES

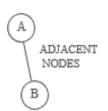
When two vertices are connected by an edge, we say that they are adjacent

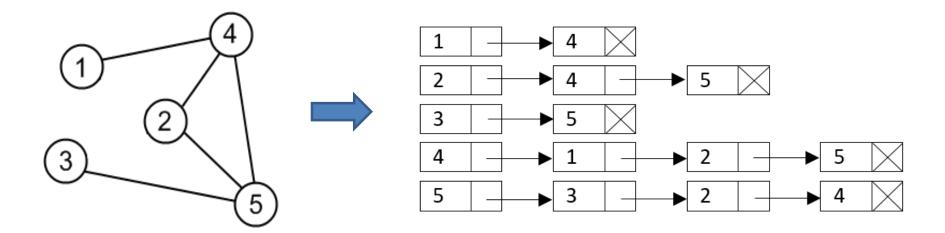


#### **Graph Implementation**

#### Adjacency List

When two vertices are connected by an edge, we say that they are adjacent

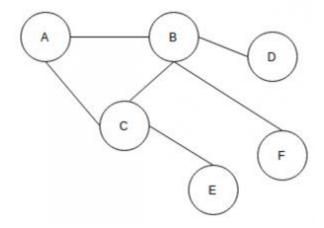






```
graph = {
    1: [4],
    2: [4, 5],
    3: [5],
    4: [1, 2, 5],
    5: [3, 2, 4],
}
```

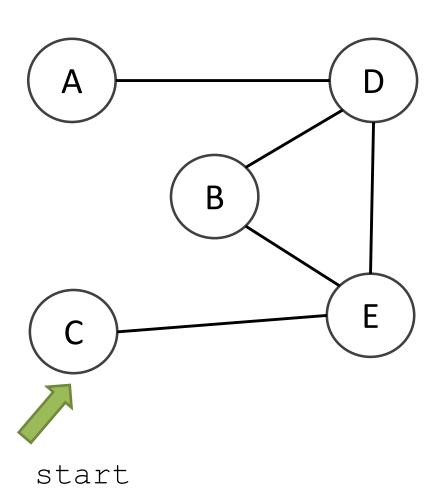
## **Graph Representation**



#### **Graph traversals**

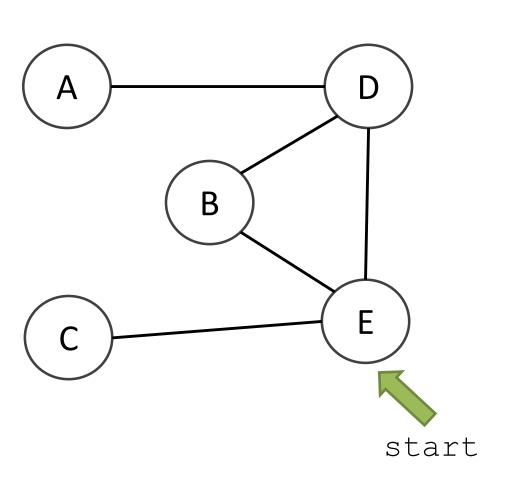
- Breadth First Search: It starts at some arbitrary node in a graph and explores all of the neighbor nodes at the present depth prior to moving on to the nodes at the next depth level.
- Depth First Search: It starts at some arbitrary node in a graph and explores as far as possible along each branch before backtracking.

# BFS for a graph



**BFS**:

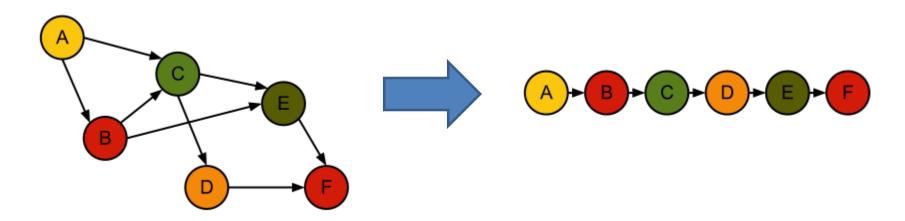
# DFS for a graph



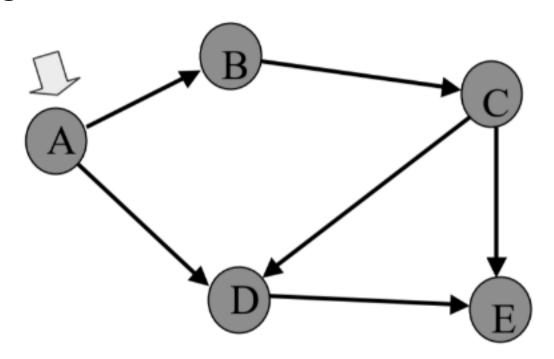
**DFS**:

#### **Topological Sorting**

- A topological sort takes DAG and produces a linear ordering of all its vertices such that if the graph *G* contains an edge (*v,w*) then the vertex *v* comes before the vertex *w* in the ordering
- Any linear ordering in which all the arrows go to the right is a valid solution
- Topological sorting for a graph is not possible if the graph is not a DAG

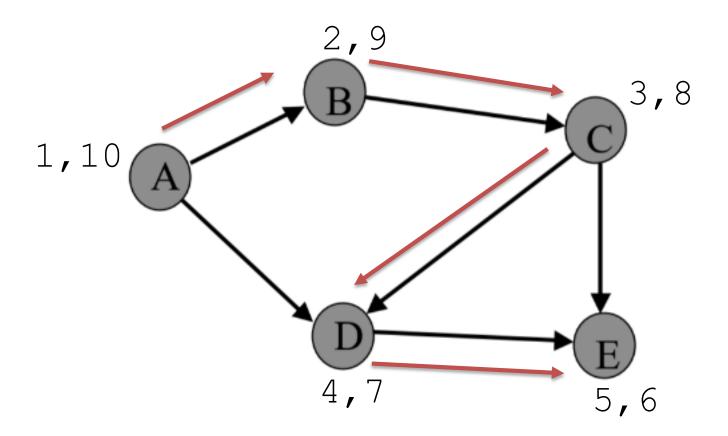


Step 1: Perform DFS for graph *G*, keeping track of starting and ending times



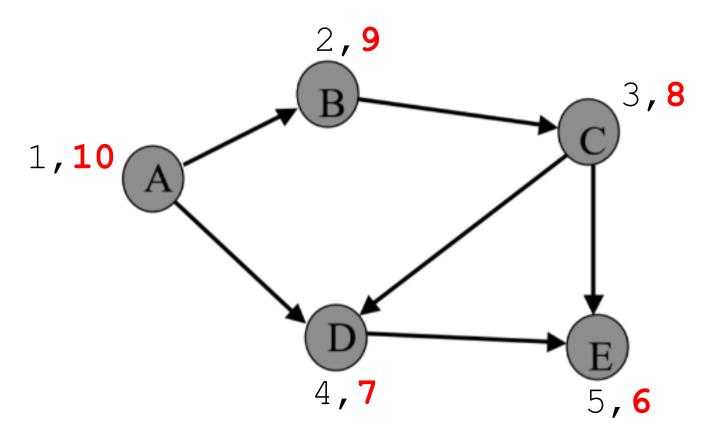
**DFS:** 

Step 1: Perform DFS for graph G

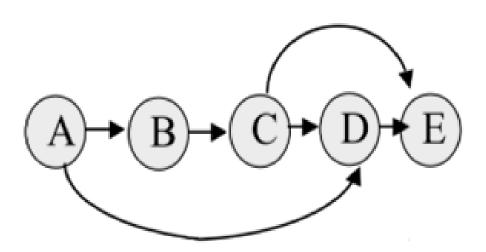


**DFS:** A, B, C, D, E

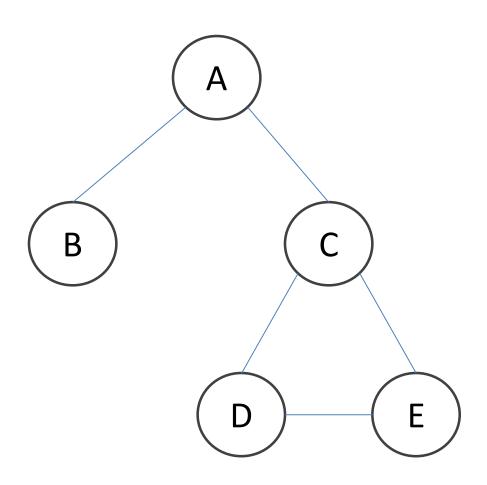
Step 2: Store the vertices in a list in decreasing order of finish time



Step 3: Return the ordered list as the result of the topological sort



# **Cycle Detection using DFS**



#### Dijkstra's Algorithm

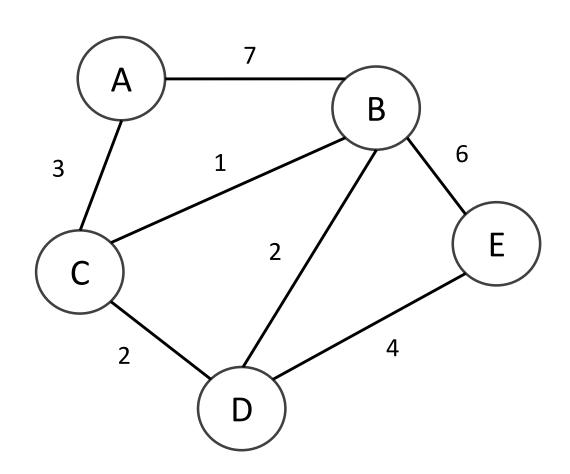
- Use to determine the shortest path from one node (or vertex) in a graph to every other node within the same graph data structure.
- The algorithm will run until all nodes in the graph have been visited, thus, the shortest path between any 2 nodes can be saved and look up after

#### Dijkstra's Algorithm

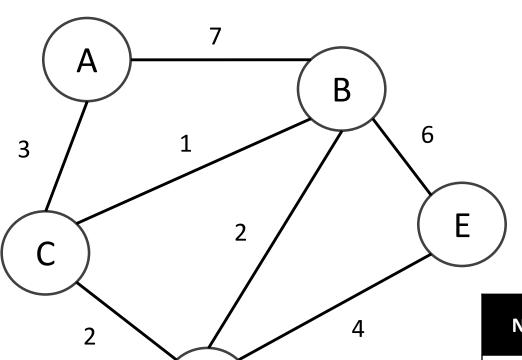
- From the starting node, visit the node with the smallest known distance
- Once you have moved to the smallest-distance node.
   Check each of its neighboring nodes
- For each neighboring node, compute the distance for the neighboring nodes by summing the distance of the edges leading from the start node
- If the distance to a node is less than a known distance, update the shortest distance for that node

#### Dijkstra's Algorithm

What is the shortest path between node A and E in the following weighted, undirected graph?



## Dijkstra's Algorithm Initialization

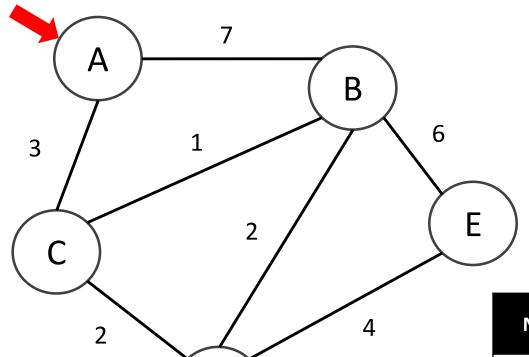


visited = []

unvisited = [A, B, C, D, E]

Node	Shortest distance from A	Previous node
Α	0	
В	∞	
С	∞	
D	∞	
Е	∞	

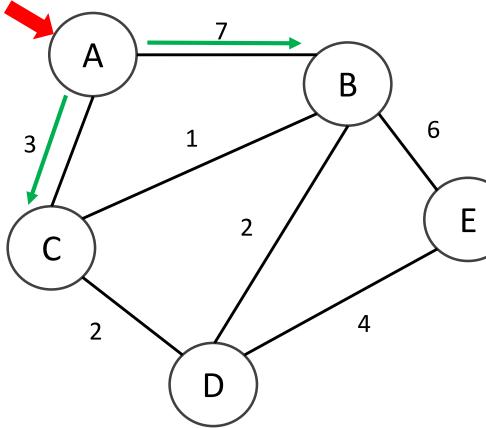
## Dijkstra's Algorithm Initialization



visited = []

unvisited = [A, B, C, D, E]

Node	Shortest distance from A	Previous node
А	0	
В	∞	
С	∞	
D	∞	
E	∞	



visited = []

unvisited = [A, B, C, D, E]

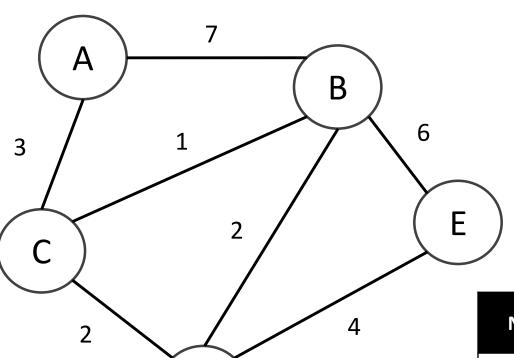
distance to B: 0+7=7

distance to C: 0+3=3

3 < ∞?

7 < ∞?

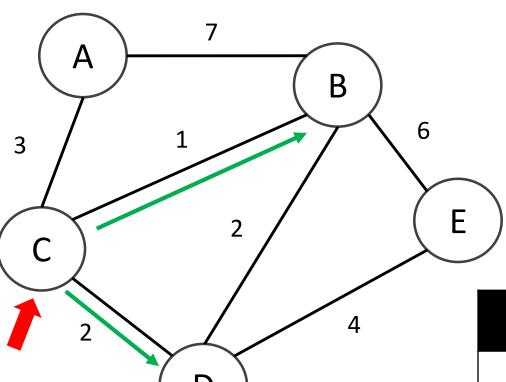
Node	Shortest distance from A	Previous node
Α	0	
В	8	
С	∞	
D	∞	
Е	∞	



visited = [A]

unvisited = [B, C, D, E]

Node	Shortest distance from A	Previous node
A	0	
В	7	А
С	3	А
D	∞	
E	∞	



visited = [A]

unvisited = [B, C, D, E]

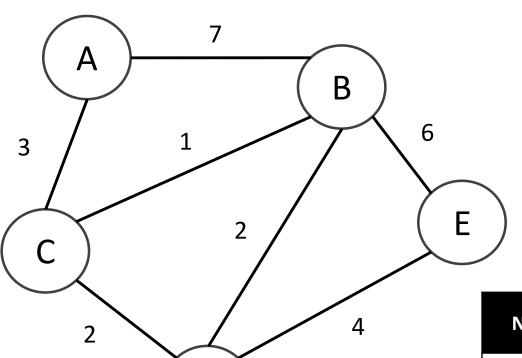
distance to B: 3+1=4

4 < 7?

distance to D: 3+2=5

5 < ∞?

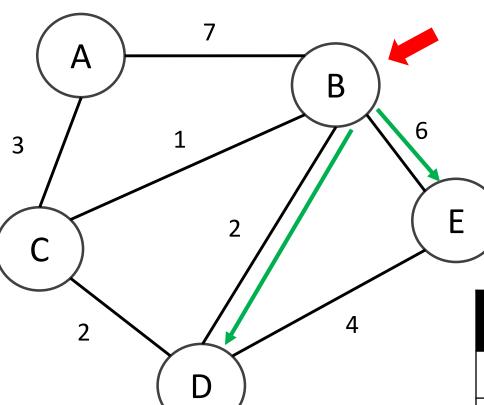
Node	Shortest distance from A	Previous node
Α	0	
В	7	Α
С	3	Α
D	8	
E	8	



visited = [A, C]

unvisited = [B, D, E]

Node	Shortest distance from A	Previous node
А	0	
В	4	С
С	3	Α
D	5	С
Е	∞	



visited = [A, C]

unvisited = [B, D, E]

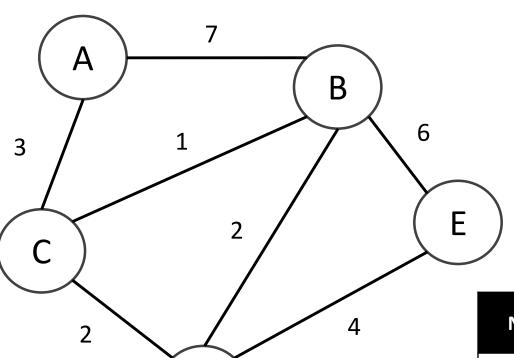
distance to D: 4+2=6

6 < 5?

distance to E: 4+6=10

10 < ∞?

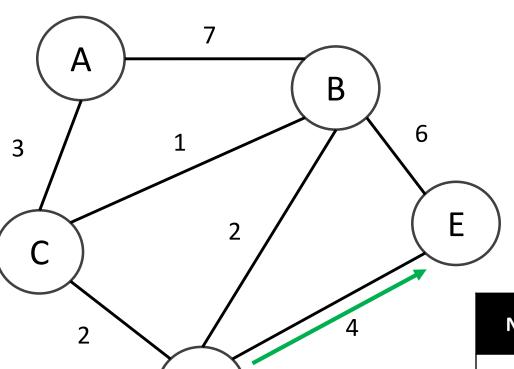
Node	Shortest distance from A	Previous node
А	0	
В	4	С
С	3	А
D	5	С
Е	∞	



visited = [A, C, B]

unvisited = [D, E]

Node	Shortest distance from A	Previous node
А	0	
В	4	С
С	3	Α
D	5	С
Е	10	В



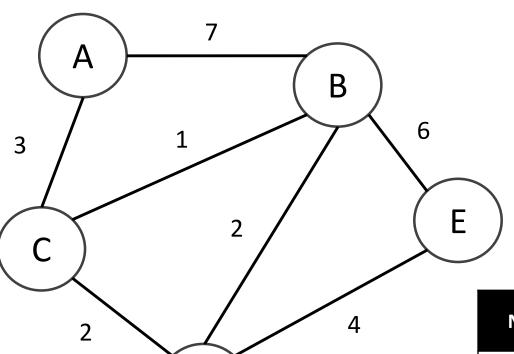
visited = [A, C, B]

unvisited = [D, E]

Node	Shortest distance from A	Previous node
Α	0	
В	4	С
С	3	А
D	5	С
Е	10	В

distance to E: 5+4=9

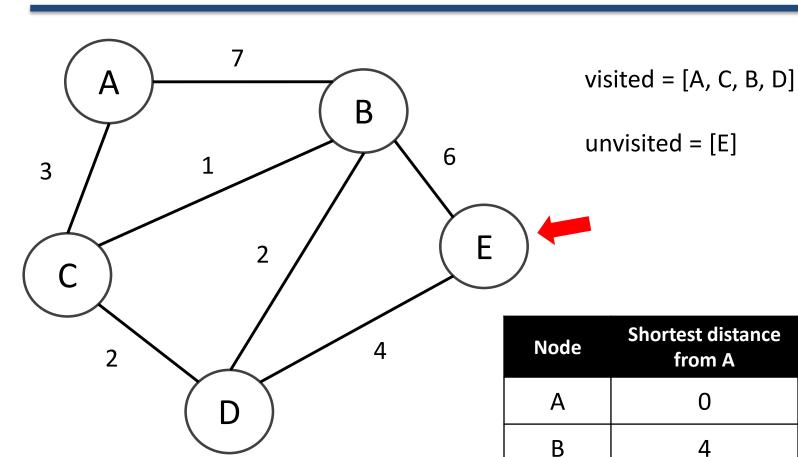
9 < 10?



visited = [A, C, B, D]

unvisited = [E]

Node	Shortest distance from A	Previous node
Α	0	
В	4	С
С	3	А
D	5	С
Е	9	D



**Previous** 

node

C

Α

D

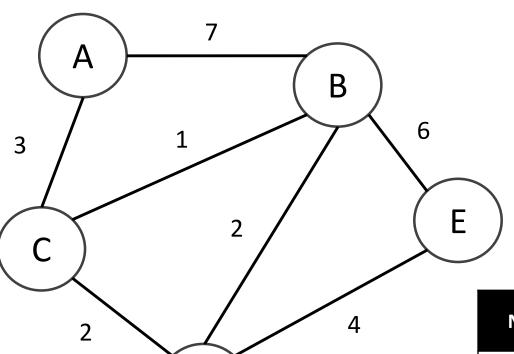
3

5

9

D

Ε



visited = [A, C, B, D, E]

unvisited = []

Node	Shortest distance from A	Previous node
А	0	
В	4	С
С	3	А
D	5	С
E	9	D