

# Nonparametric Self-Exciting Point Processes: Benefits and Uses

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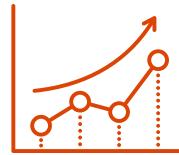
Slides: <https://github.com/jimmylovestea/wnar-2021-slides>





# Outline

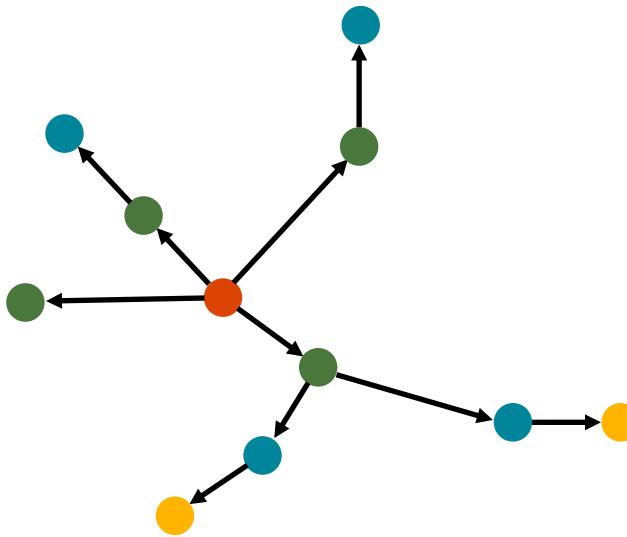
- Self-exciting phenomenon
- Self-exciting point processes
- Recent nonparametric innovations
- Application: Hector Mine earthquake sequence
- Closing thoughts



**Self-exciting  
phenomenon**



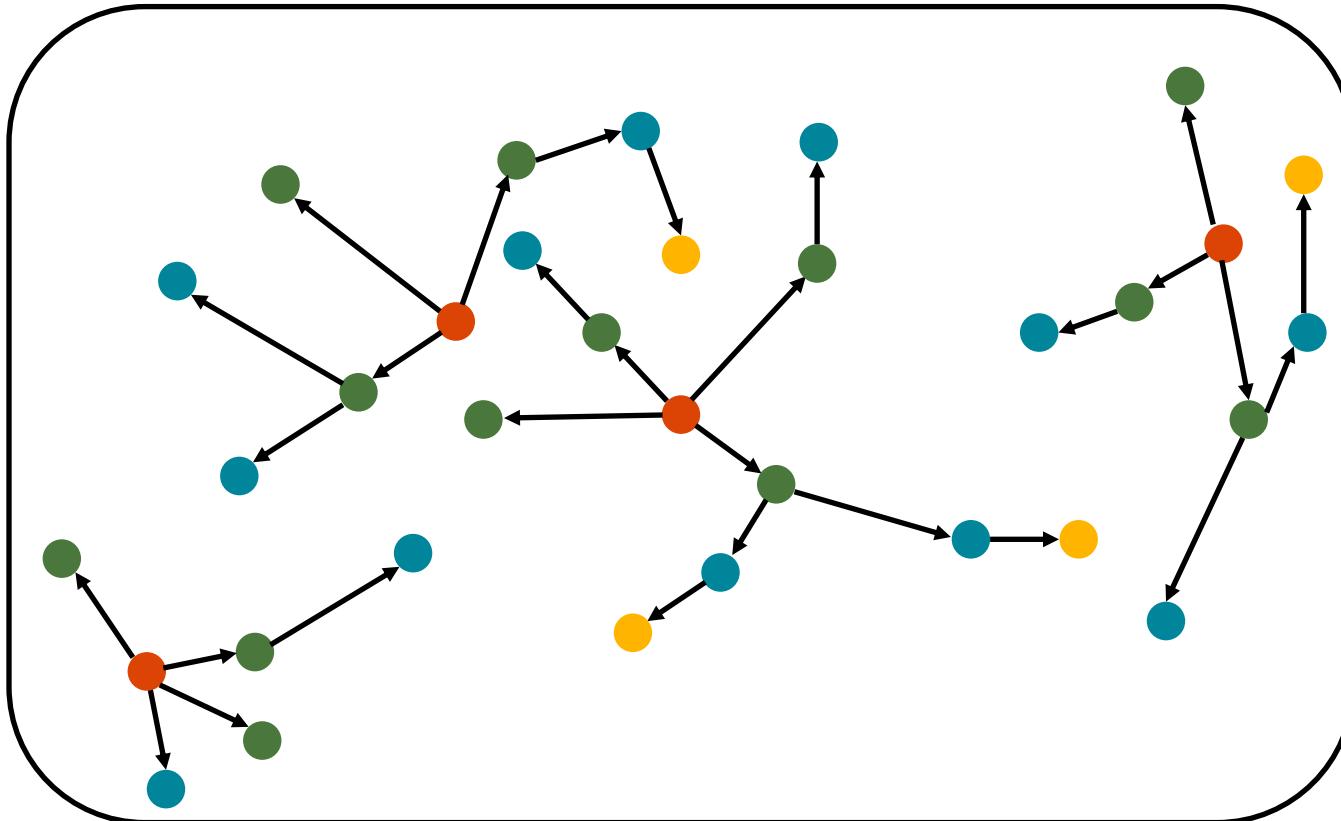
# Self-exciting phenomenon



Time:  $t_0 \rightarrow t_1 \rightarrow t_2 \rightarrow t_3 \rightarrow t_4 \rightarrow \dots \rightarrow T$



# Self-exciting phenomenon

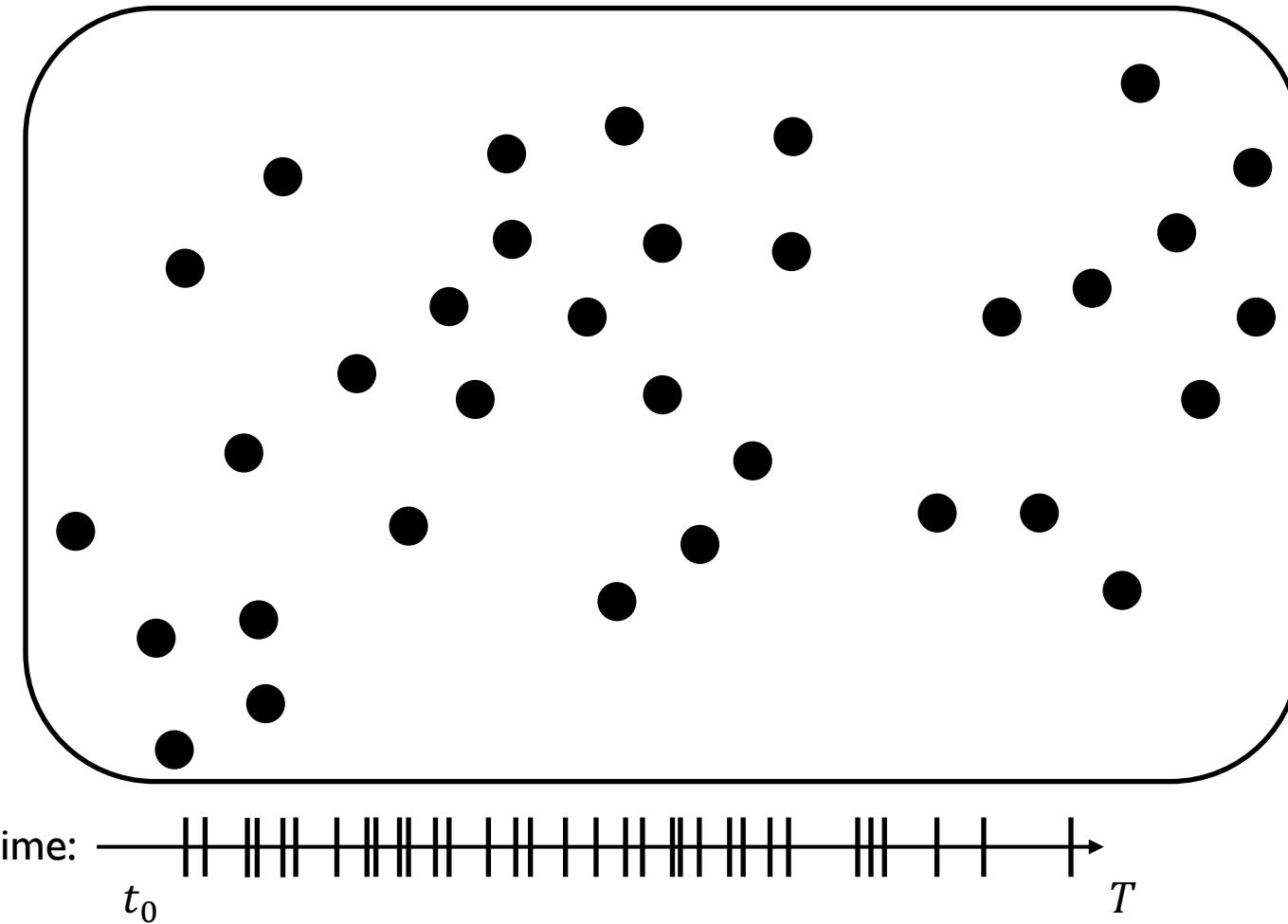


Time:





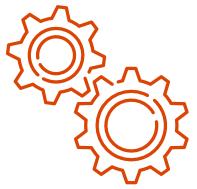
# Self-exciting phenomenon





# Self-exciting phenomenon

- Invasive Species ([Balderama, 2012](#))
  - Invasive species introduced by animals, floods, winds, people, etc.
  - Reproduce and spread
- Crime ([Mohler, 2011](#))
  - Successful burglary occurs in a neighborhood
  - Successive burglaries attempted nearby
- Disease Epidemics ([Park, 2020](#); [Bertozzi, 2020](#))
  - A person is infected with a disease
  - The disease spreads from person to person
- Earthquakes ([Ogata, 1999](#))
  - Mainshock earthquake occurs
  - Aftershocks occur afterwards



## **Self-exciting point processes**



# Self-exciting point processes

- Conditional Intensity :  $\lambda(x, y, t | \mathcal{H}_t)$ 
  - Describes the infinitesimal rate of occurrences at time  $t$  and location  $(x, y)$
- Background rate :  $\mu(x, y)$ 
  - Function which describes the rate of *background* events at location  $(x, y)$
- Triggering function :  $v(x - x_i, y - y_i, t - t_i)$ 
  - Function which describes the amount of *excitation* from previous events

$$\lambda(x, y, t | \mathcal{H}_t) = \mu(x, y) + \sum_{i: t_i < t} v(x - x_i, y - y_i, t - t_i)$$



# Self-exciting point processes

- In applications, we often let the triggering function be *separable*
- The triggering function,  $\nu(x - x_i, y - y_i, t - t_i)$ , is a product of:
  - 
  - 
  -

$$\lambda(x, y, t | \mathcal{H}_t) = \mu(x, y) + \sum_{i: t_i < t} \nu(x - x_i, y - y_i, t - t_i)$$



# Self-exciting point processes

- In applications, we often let the triggering function be *separable*
- The triggering function,  $\nu(x - x_i, y - y_i, t - t_i)$ , is a product of:
  - Time :  $g(t - t_i)$
  - 
  -

$$\lambda(x, y, t | \mathcal{H}_t) = \mu(x, y) + \sum_{i: t_i < t} g(t - t_i)$$



# Self-exciting point processes

- In applications, we often let the triggering function be *separable*
- The triggering function,  $v(x - x_i, y - y_i, t - t_i)$ , is a product of:
  - Time :  $g(t - t_i)$
  - Space :  $h(x - x_i, y - y_i)$
  -

$$\lambda(x, y, t | \mathcal{H}_t) = \mu(x, y) + \sum_{i: t_i < t} g(t - t_i) h(x - x_i, y - y_i)$$



# Self-exciting point processes

- In applications, we often let the triggering function be *separable*
- The triggering function,  $\nu(x - x_i, y - y_i, t - t_i)$ , is a product of:
  - Time :  $g(t - t_i)$
  - Space :  $h(x - x_i, y - y_i)$
  - Marks :  $k(m_i)$

$$\lambda(x, y, t | \mathcal{H}_t) = \mu(x, y) + \sum_{i: t_i < t} g(t - t_i) h(x - x_i, y - y_i) k(m_i)$$



# Self-exciting point processes

- In applications, we often let the triggering function be *separable*
- The triggering function,  $\nu(x - x_i, y - y_i, t - t_i)$ , is a product of:
  - Time :  $g(t - t_i)$
  - Space :  $h(x - x_i, y - y_i)$
  - Marks :  $k(m_i)$
- Marks can be some additional information about an event
  - Earthquake magnitudes
  - Crime types
  - Plant size

$$\lambda(x, y, t | \mathcal{H}_t) = \mu(x, y) + \sum_{i: t_i < t} g(t - t_i)h(x - x_i, y - y_i)k(m_i)$$



# Self-exciting point processes

- For earthquakes, the conditional intensity at time  $t$  and location  $(x, y)$  is:

- $\mu(x, y) = \tilde{\mu}(x, y)$

- $g(t - t_i) = (t - t_i + c)^{-p}$

- $h(x - x_i, y - y_i) = ((x - x_i)^2 + (y - y_i)^2 + d)^{-q}$

- $k(m_i) = K e^{\alpha(m_i - m_0)}$

- Estimate parameters  $\{\tilde{\mu}, c, p, d, q, K, \alpha\}$  using maximum likelihood estimation

$$\lambda(x, y, t | \mathcal{H}_t) = \tilde{\mu}(x, y) + \sum_{i: t_i < t} (t - t_i + c)^{-p} ((x - x_i)^2 + (y - y_i)^2 + d)^{-q} K e^{\alpha(m_i - m_0)}$$



**WHAT IF WE'RE UNSURE WE'VE  
SPECIFIED OUR MODEL CORRECTLY?**



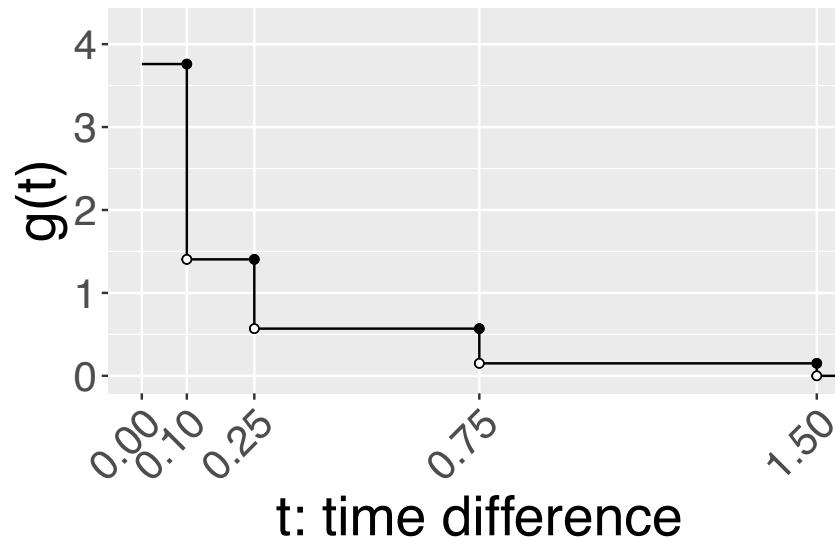
# Self-exciting point processes

- Formulate the model nonparametrically ([Marsan and Lengliné, 2008](#))
  - Introduce a latent variable,  $Z$ , which describes whether an event is a *background* event or a *triggered* event
    - Compute probability event  $i$  is a background event
    - Compute probability event  $i$  is triggered by previous event  $j$
  - Use probabilities to update  $\mu(x, y)$
  - Use probabilities to update *histogram estimators* of  $g(t - t_i)$ ,  $h(x - x_i, y - y_i)$ ,  $k(m_i)$



# Self-exciting point processes

- Histogram estimators:
  - Take domain of *pairwise* differences of points in time and space
  - Split the domains into disjoint sets of bins/intervals
  - Compute step functions (i.e. constant values) for each bin/interval based on the probabilities of points which fall into each bin/interval
  - Do something similar for the marks
- Example:





# Self-exciting point processes

- With estimated histogram estimators and estimated background rate,  $\mu(x, y)$ 
  - Update probability each event is a *background* event
  - Update probabilities each event was *triggered* by a previous event
- Iterate until convergence

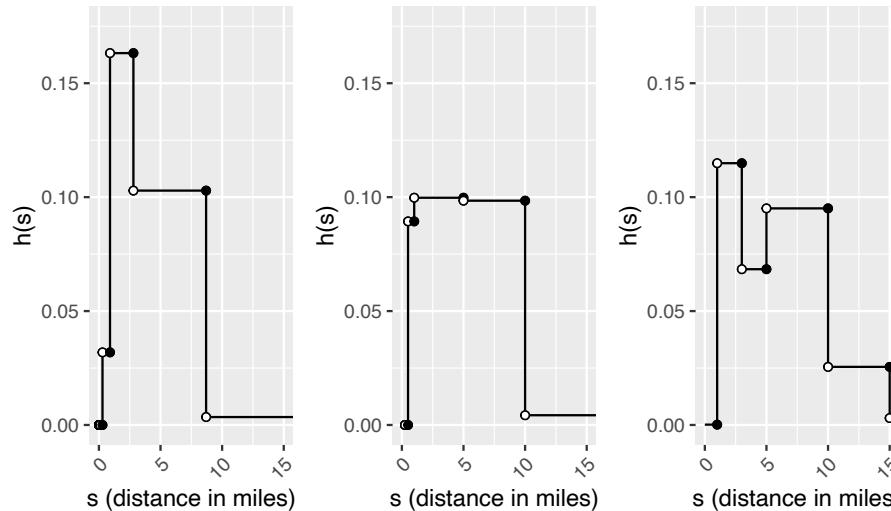


**Recent  
nonparametric  
innovations**



# Recent nonparametric innovations

- Peter Boyd, Ph.D. Candidate of Statistics, Oregon State University
- Does how we decide to break up the domains of our histogram estimators matter?
  - Spoiler alert: Yes



- Is there some way to resolve this issue which would also let us estimate the triggering functions in a less “clunky” manner?
  - Spoiler alert: Also yes



# Recent nonparametric innovations

- Rather than specify a set of fixed bins, what if we instead:
  - Generate lots of random bins of varying size
  - Use these random bins to estimate the expected rates of triggering which occurs in each bin
  - Smooth these estimated expected rates to give us a sense of what happens, on average
- Benefits:
  - No longer need for users to specify, and then justify, bins themselves
  - Random bins of varying sizes give us a better *overall* sense of the variability of the triggering
  - Still flexible enough to focus on where we think more/less triggering occurs

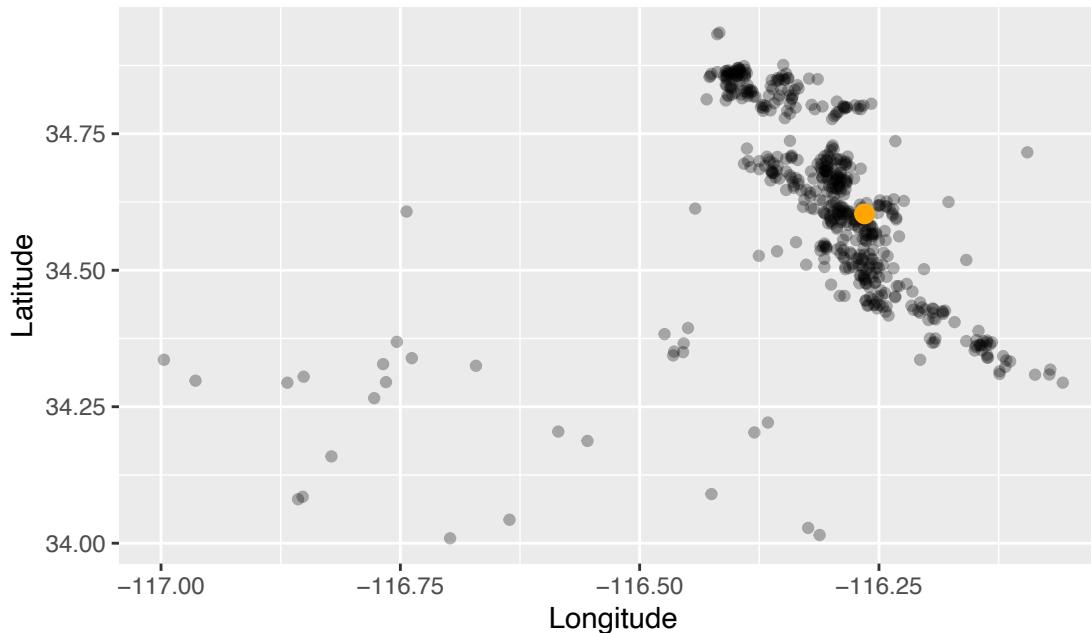


**Application: Hector  
Mine earthquake  
sequence**



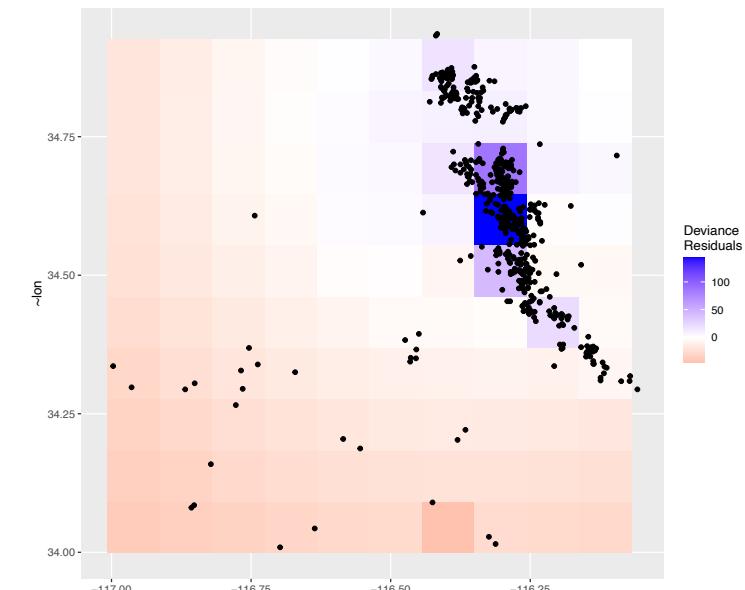
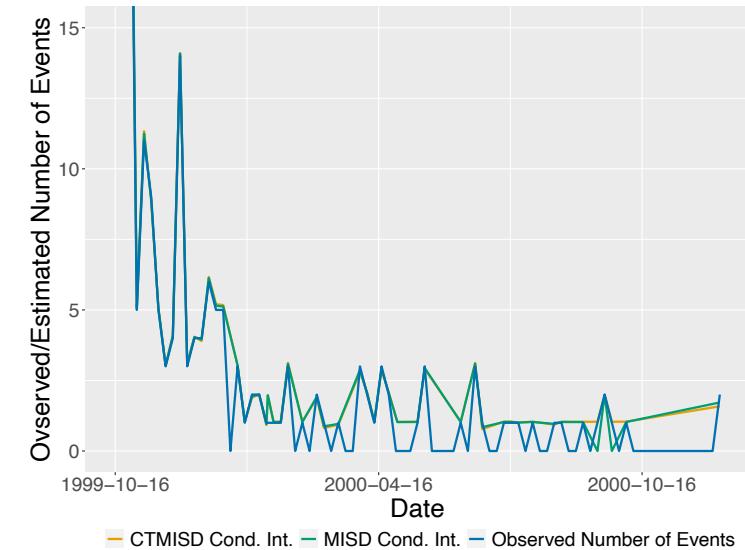
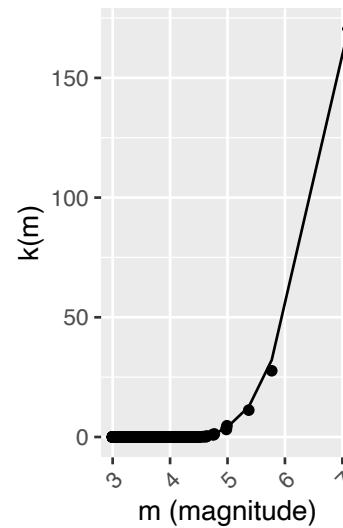
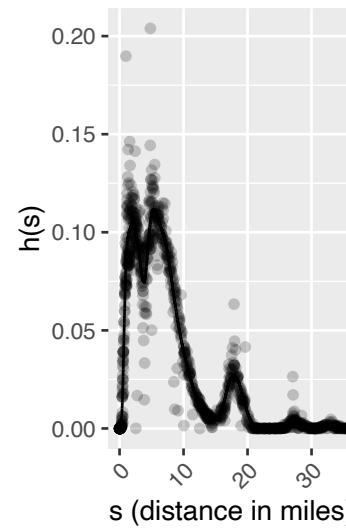
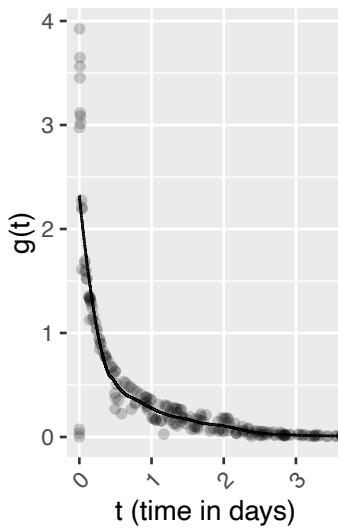
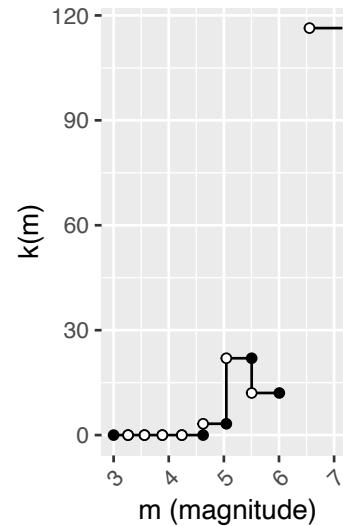
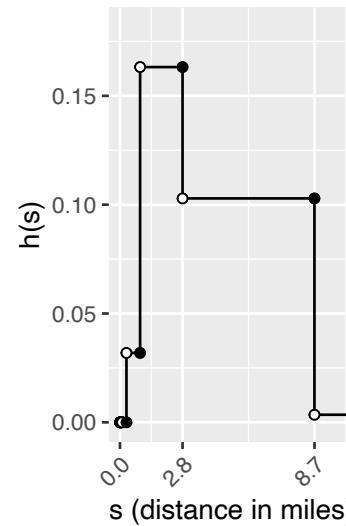
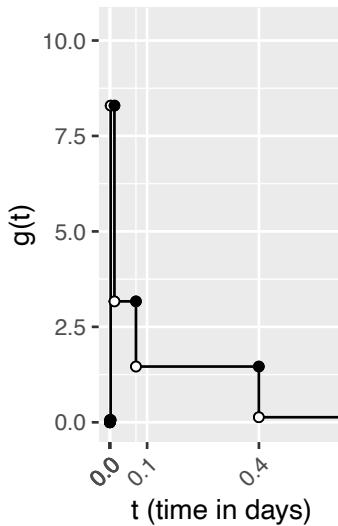
## Application: Hector Mine earthquake sequence

- Large, magnitude 7.1 earthquake which occurred on October 16, 1999
- ~50 miles southeast of Barstow, CA
- Felt throughout Southern California and Las Vegas
- A “fan favorite” for folks in statistical seismology





# Application: Hector Mine earthquake sequence





## Closing thoughts



# Closing thoughts

- Self-exciting point processes are great models for data where points cluster in time or space.
- Nonparametric methods alleviate need to specify functional forms of temporal/spatial decay.
- Recent advances make nonparametric methods less “clunky” to implement/use.
- Check out [Peter's Github](#) for:
  - An R package which implements the histogram estimator version of the model.
  - Soon: An R package which implements the new method.
- Be on the lookout for our article about the new method

# THANK YOU

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**Oregon State**  
University