

A

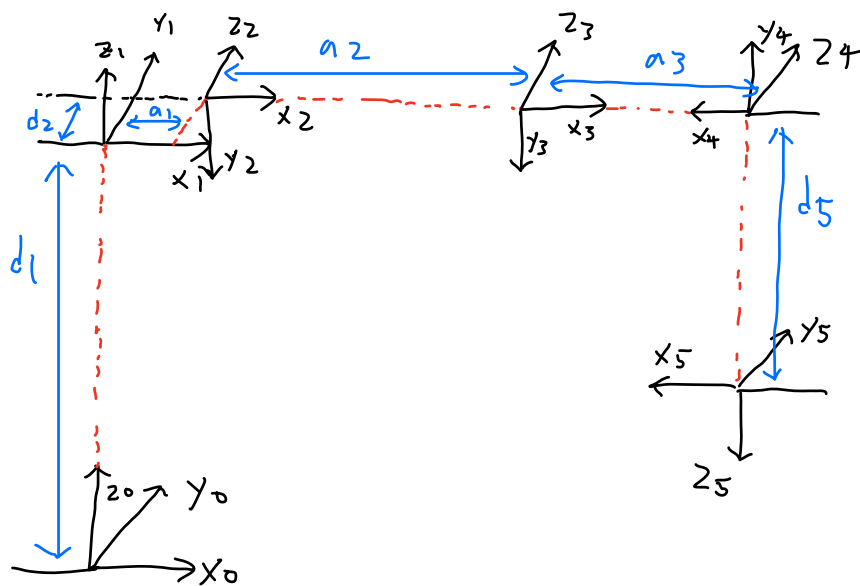
机械原理

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part A

(1)



(2)

| joint | $\alpha_{i-1} (^\circ)$ | $a_{i-1} (mm)$ | $d_i (mm)$ | θ_i |
|-------|-------------------------|----------------|------------|------------|
| 1 | 0 | 0 | 358.5 | θ_1 |
| 2 | -90 | 50 | 35.3 | θ_2 |
| 3 | 0 | 300 | 0 | θ_3 |
| 4 | 0 | 350 | 0 | θ_4 |
| 5 | 90 | 0 | 251 | θ_5 |

part B

$$T_0^1 = \begin{bmatrix} c_1 & -s_1 & 0 & 0 \\ s_1 & c_1 & 0 & 0 \\ 0 & 0 & 1 & 358.5 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$T_1^2 = \begin{bmatrix} c_2 & -s_2 & 0 & 50 \\ 0 & 0 & 1 & 35.3 \\ -s_2 & -c_2 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$T_2^3 = \begin{bmatrix} c_3 & -s_3 & 0 & 300 \\ s_3 & c_3 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$T_3^4 = \begin{bmatrix} c_4 & -s_4 & 0 & 350 \\ s_4 & c_4 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$T_4^5 = \begin{bmatrix} c_5 & -s_5 & 0 & 0 \\ 0 & 0 & -1 & -251 \\ s_5 & c_5 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$T_0^5 = T_0^1 T_1^2 T_2^3 T_3^4 T_4^5$$

$$\begin{bmatrix} c_1 c_{234} c_5 - s_1 s_5 & -c_1 c_{234} s_5 - s_1 c_5 & c_1 s_{234} & c_1 (251 s_{234} + 350 c_{23} + 300 c_2 + 50) \\ s_1 c_{234} c_5 + c_1 s_5 & -s_1 c_{234} s_5 + c_1 c_5 & s_1 s_{234} & s_1 (251 s_{234} + 350 c_{23} + 300 c_2 + 50) \\ -s_{234} c_5 & s_{234} s_5 & c_{234} & 251 c_{234} - 350 s_{23} - 300 s_2 + 358.5 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Part C

(1)

$$T_1^5 = [T_0^1]^{-1} T_0^5$$

$$= \begin{bmatrix} c_1 & s_1 & 0 & 0 \\ -s_1 & c_1 & 0 & 0 \\ 0 & 0 & 1 & -358.5 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} c\phi c\theta & c\phi s\theta s\psi - s\phi c\psi & c\phi s\theta c\psi + s\phi s\psi & x \\ s\phi c\theta & s\phi s\theta s\psi + c\phi c\psi & s\phi s\theta c\psi - c\phi s\psi & y \\ -s\theta & c\theta s\psi & c\theta c\psi & z \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} \cos(\theta_1 - \phi) c\theta & \cos(\theta_1 - \phi) s\theta s\psi + \sin(\theta_1 - \phi) c\psi & \cos(\theta_1 - \phi) s\theta c\psi - \sin(\theta_1 - \phi) s\psi & c_1 x + s_1 y \\ -\sin(\theta_1 - \phi) c\theta & -\sin(\theta_1 - \phi) s\theta s\psi + \cos(\theta_1 - \phi) c\psi & -\sin(\theta_1 - \phi) s\theta c\psi - \cos(\theta_1 - \phi) s\psi & -s_1 x + c_1 y \\ -s\theta & c\theta s\psi & c\theta c\psi & z - 358.5 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$-x s_1 + y c_1 = 35.3 \dots (1)$$

$$\text{let } x = p \cdot c\alpha \quad y = p \cdot s\alpha \quad p = \sqrt{px^2 + py^2} \quad \alpha = \arctan_2(y, x)$$

$$(1) \Rightarrow c_1 s\alpha - s_1 c\alpha = 35.3 / p \quad \sin(\alpha - \theta_1) = 35.3 / p \quad \cos(\alpha - \theta_1) = \pm \sqrt{1 - \left(\frac{35.3}{p}\right)^2}$$

$$\theta_1 = \arctan_2(y, x) - \arctan_2(35.3, \pm \sqrt{x^2 + y^2 - 35.3^2})$$

$$\begin{cases} S_5 = -\sin(\theta_1 - \phi) \cos \theta \dots (2) \\ L_5 = -\sin(\theta_1 - \phi) \sin \theta \sin \psi + \cos(\theta_1 - \phi) \cos \psi \dots (3) \end{cases}$$

$$(2), (3) \Rightarrow \theta_5 = a \tan 2 (-\sin(\theta_1 - \phi) \cos \theta, -\sin(\theta_1 - \phi) \sin \theta \sin \psi + \cos(\theta_1 - \phi) \cos \psi)$$

$$\begin{cases} L_{234} L_5 = \cos(\theta_1 - \phi) \cos \theta \dots (4) \\ -S_{234} L_5 = -S_1 \dots (5) \end{cases}$$

$$(4), (5) \Rightarrow \theta_2 + \theta_3 + \theta_4 = a \tan 2 (S_1, \cos(\theta_1 - \phi) \cos \theta)$$

$$\begin{cases} 350 L_{23} + 300 L_2 = L_1 X + S_1 Y - 50 - 251 S_{234} = A \dots (6) \\ 350 L_{23} + 300 S_2 = 358.5 - 2 + 251 L_{234} = B \dots (7) \end{cases}$$

$$(6)^2 + (7)^2 \Rightarrow 350^2 + 300^2 + 2 \times 300 \times 350 \times L_3 = A^2 + B^2$$

$$\Rightarrow \theta_3 = a \tan 2 \left(\pm \sqrt{1 - \left(\frac{A^2 + B^2 - 350^2 - 300^2}{210000} \right)^2}, \frac{A^2 + B^2 - 350^2 - 300^2}{210000} \right)$$

$$350 (L_2 L_3 - S_2 S_3) + 300 L_2 = A$$

$$\Rightarrow L_2 (350 L_3 + 300) - S_2 (350 S_3) = A \dots (8)$$

$$350 (S_2 L_3 + L_2 S_3) + 300 S_2 = B$$

$$\Rightarrow S_2 (350 L_3 + 300) + L_2 (350 S_3) = B \dots (9)$$

$$(8) \cdot L_2 + (9) \cdot S_2 \Rightarrow 350 L_3 + 300 = A L_2 + B S_2$$

$$\Rightarrow \theta_2 = -a \tan 2 (A, B) + a \tan 2 (350 L_3 + 300, \pm \sqrt{A^2 + B^2 - 1350 (L_3 + 300)^2})$$

$$\Theta_4 = (\Theta_2 + \Theta_3 + \Theta_4) - \Theta_2 - \Theta_3$$

(2)

$$(a) (x, y, z, \phi, \theta, \psi) = (600, 100, 0, \frac{\pi}{4}, 0, \pi)$$

$$\theta_1 = 6.1354$$

$$\theta_2 = -20.8224$$

$$\theta_3 = 58.5446$$

$$\theta_4 = 142.2444$$

$$\theta_5 = 141.1354$$

$$(b) (x, y, z, \phi, \theta, \psi) = (600, 100, 100, \frac{\pi}{4}, 0, \pi)$$

$$\theta_1 = 6.1354$$

$$\theta_2 = -32.96118$$

$$\theta_3 = 62.1556$$

$$\theta_4 = 150.8055$$

$$\theta_5 = 141.1354$$

$$(c) (x, y, z, \phi, \theta, \psi) = (600, -100, 100, \frac{-\pi}{4}, 0, \pi)$$

$$\theta_1 = -12.789$$

$$\theta_4 = 150.805$$

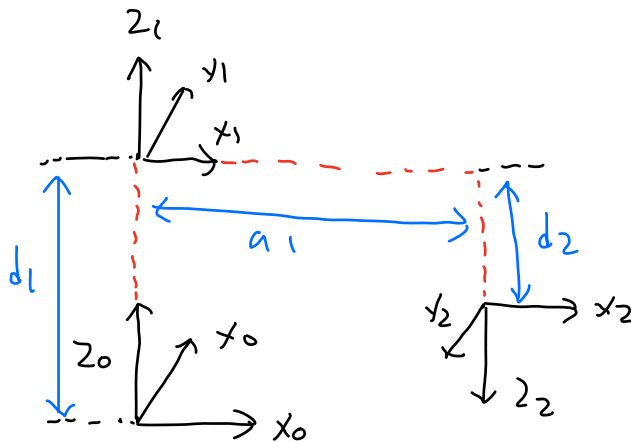
$$\theta_2 = -32.961$$

$$\theta_5 = -147.789$$

$$\theta_3 = 62.156$$

part D

(1)



| joint | $\alpha_{i-1} (^{\circ})$ | $a_{i-1} (\text{mm})$ | $d_i (\text{mm})$ | $\theta_i (^{\circ})$ |
|-------|---------------------------|-----------------------|-------------------|-----------------------|
| 1 | 0 | 0 | d_1 | θ_1 |
| 2 | π | a_1 | d_2 | 0 |

(2)

θ_1 and d_2