

Mining Data Streams (Part 2)

CS246: Mining Massive Datasets
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Today's Lecture

- **More algorithms for streams:**
 - **(1) Filtering a data stream: Bloom filters**
 - Select elements with property x from stream
 - **(2) Counting distinct elements: Flajolet-Martin**
 - Number of distinct elements in the last k elements of the stream
 - **(3) Estimating moments: AMS method**
 - Estimate std. dev. of last k elements
 - **(4) Counting frequent items**

(1) Filtering Data Streams

Filtering Data Streams

- Each element of data stream is a tuple
- Given a list of keys S
- Determine which tuples of stream are in S
- Obvious solution: Hash table
 - But suppose we do not have enough memory to store all of S in a hash table
 - E.g., we might be processing millions of filters on the same stream

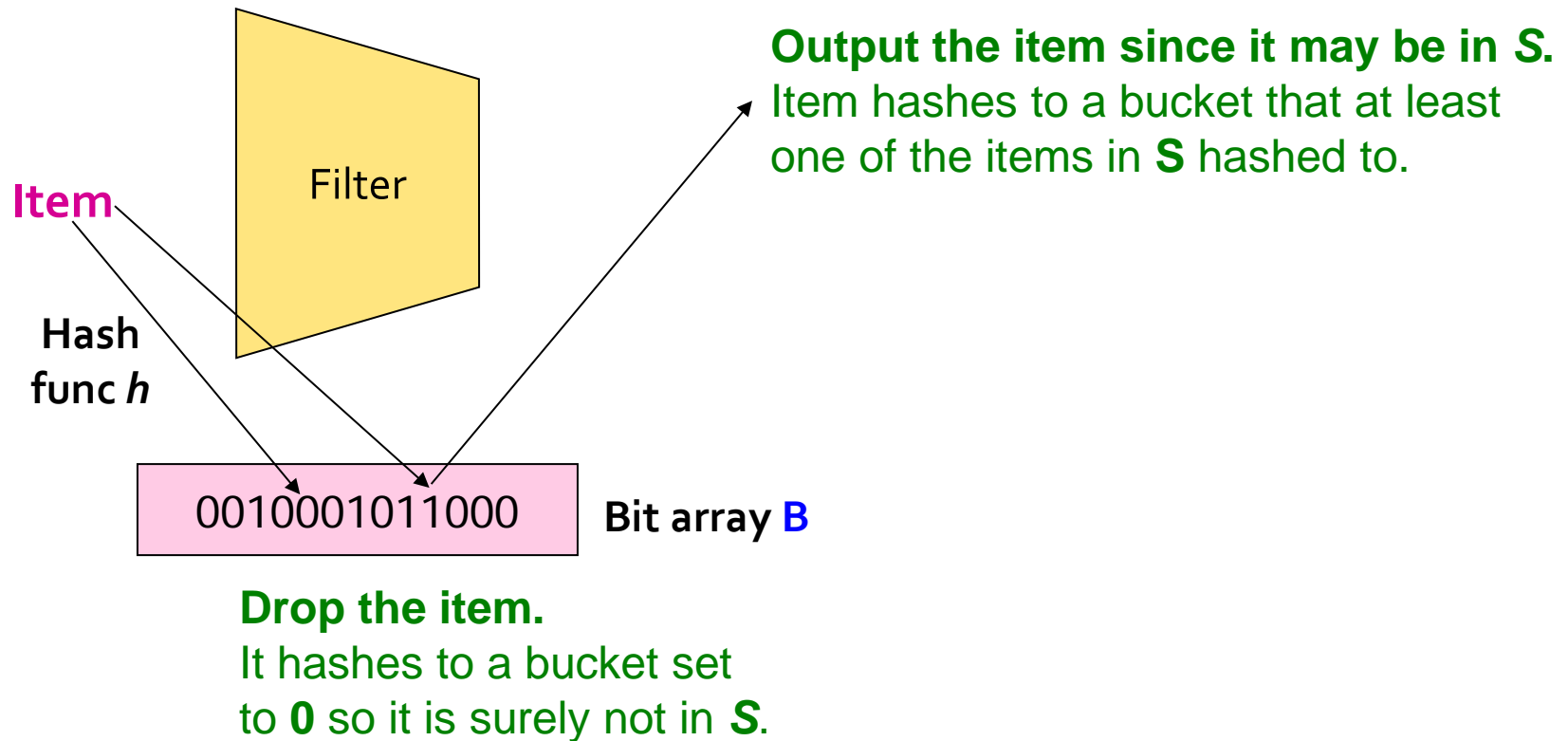
Applications

- **Example: Email spam filtering**
 - We know 1 billion “good” email addresses
 - If an email comes from one of these, it is **NOT** spam
- **Publish-subscribe systems**
 - You are collecting lots of messages (news articles)
 - People express interest in certain sets of keywords
 - Determine whether each message matches user’s interest

First Cut Solution (1)

- Given a set of keys S that we want to filter
- Create a bit array B of n bits, initially all 0s
- Choose a hash function h with range $[0, n)$
- Hash each member of $s \in S$ to one of n buckets, and set that bit to 1, i.e., $B[h(s)] = 1$
- Hash each element a of the stream and output only those that hash to bit that was set to 1
 - Output a if $B[h(a)] == 1$

First Cut Solution (2)



- **Creates false positives but no false negatives**
 - If the item is in **S** we surely output it, if not we may still output it

First Cut Solution (3)

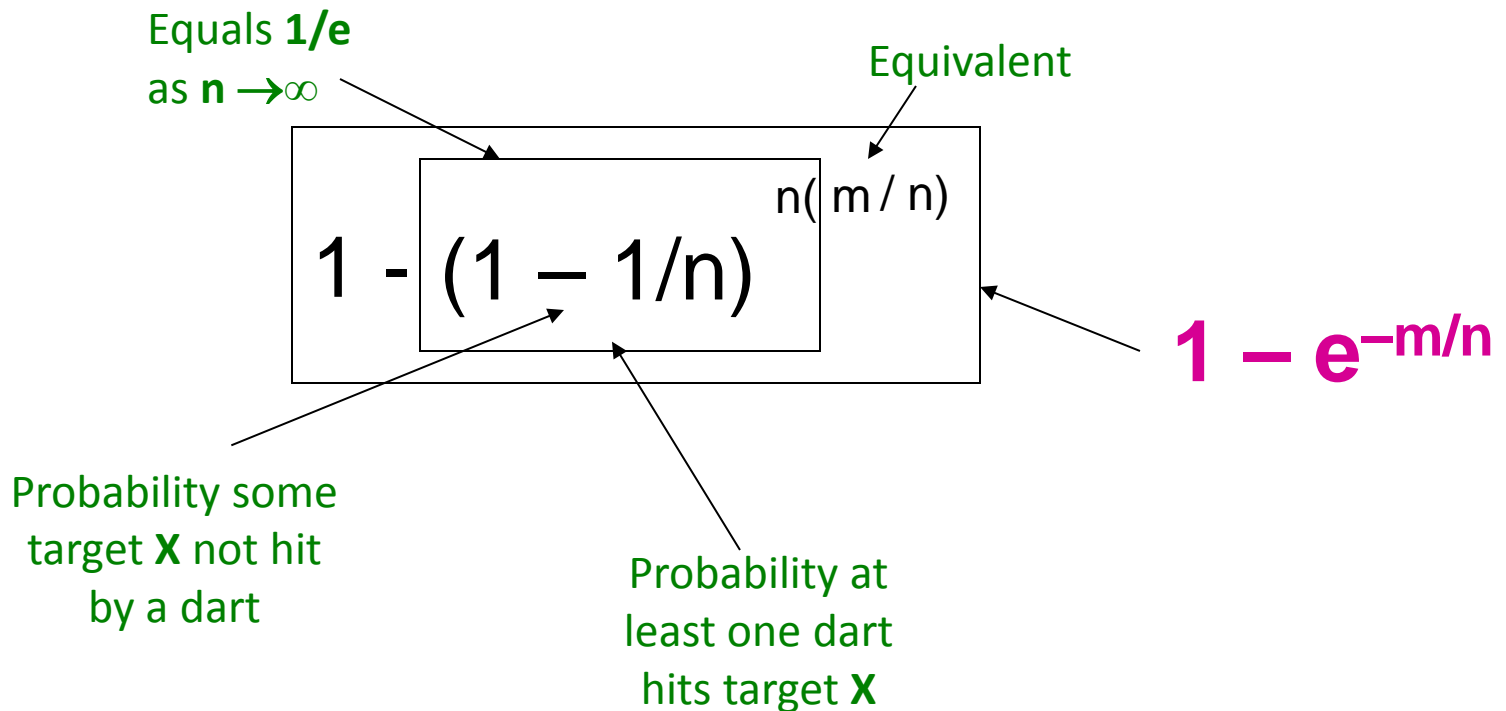
- $|S| = 1$ billion email addresses
 $|B| = 1\text{GB} = 8$ billion bits
- If the email address is in S , then it surely hashes to a bucket that has the bit set to **1**, so it always gets through (*no false negatives*)
- Approximately $1/8$ of the bits are set to **1**, so about $1/8^{\text{th}}$ of the addresses not in S get through to the output (*false positives*)
 - Actually, less than $1/8^{\text{th}}$, because more than one address might hash to the same bit

Analysis: Throwing Darts (1)

- More accurate analysis for the number of **false positives**
- **Consider:** If we throw m darts into n equally likely targets, **what is the probability that a target gets at least one dart?**
- **In our case:**
 - **Targets** = bits/buckets
 - **Darts** = hash values of items

Analysis: Throwing Darts (2)

- We have m darts, n targets
- **What is the probability that a target gets at least one dart?**



Analysis: Throwing Darts (3)

- **Fraction of 1s in the array B == probability of false positive == $1 - e^{-m/n}$**
- **Example: 10^9 darts, $8 \cdot 10^9$ targets**
 - Fraction of 1s in B = $1 - e^{-1/8} = 0.1175$
 - Compare with our earlier estimate: $1/8 = 0.125$

Bloom Filter

- Consider: $|S| = m, |B| = n$
- Use k independent hash functions h_1, \dots, h_k
- **Initialization:**
 - Set B to all 0s
 - Hash each element $s \in S$ using each hash function h_i , set $B[h_i(s)] = 1$ (for each $i = 1, \dots, k$) (note: we have a single array B !)
- **Run-time:**
 - When a stream element with key x arrives
 - If $B[h_i(x)] = 1$ for all $i = 1, \dots, k$ then declare that x is in S
 - That is, x hashes to a bucket set to 1 for every hash function $h_i(x)$
 - Otherwise discard the element x

Bloom Filter -- Analysis

- What fraction of the bit vector B are 1s?
 - Throwing $k \cdot m$ darts at n targets
 - So fraction of 1s is $(1 - e^{-km/n})$
- But we have k independent hash functions and we only let the element x through if all k hash element x to a bucket of value 1
- So, false positive probability = $(1 - e^{-km/n})^k$

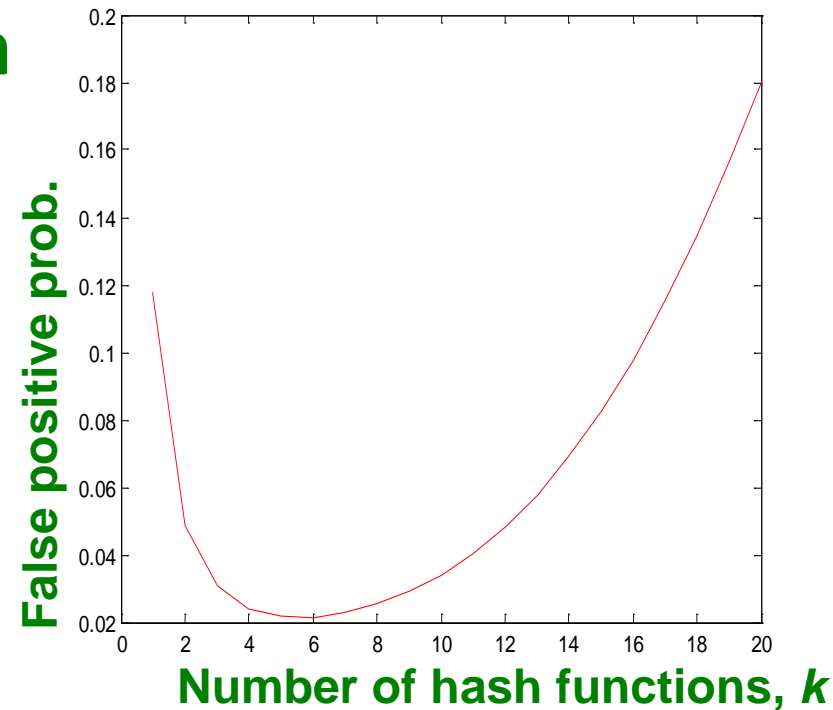
Bloom Filter – Analysis (2)

- $m = 1$ billion, $n = 8$ billion

- $k = 1: (1 - e^{-1/8}) = 0.1175$

- $k = 2: (1 - e^{-1/4})^2 = 0.0493$

- What happens as we keep increasing k ?



- “Optimal” value of k : $n/m \ln(2)$

- In our case: Optimal $k = 8 \ln(2) = 5.54 \approx 6$

Bloom Filter: Wrap-up

- Bloom filters guarantee no false negatives, and use limited memory
 - Great for pre-processing before more expensive checks
- Suitable for hardware implementation
 - Hash function computations can be parallelized
- Is it better to have 1 big B or k small Bs?
 - It is the same: $(1 - e^{-km/n})^k$ vs. $(1 - e^{-m/(n/k)})^k$
 - But keeping 1 big B is simpler

(2) Counting Distinct Elements

Counting Distinct Elements

■ Problem:

- Data stream consists of a universe of elements chosen from a set of size N
- Maintain a count of the number of distinct elements seen so far

■ Obvious approach:

Maintain the set of elements seen so far

- That is, keep a hash table of all the distinct elements seen so far

Applications

- **How many different words are found among the Web pages being crawled at a site?**
 - Unusually low or high numbers could indicate artificial pages (spam?)
- **How many different Web pages does each customer request in a week?**
- **How many distinct products have we sold in the last week?**

Using Small Storage

- Real problem: What if we do not have space to maintain the set of elements seen so far?
- Estimate the count in an unbiased way
- Accept that the count may have a little error, but limit the probability that the error is large

Flajolet-Martin Approach

- Pick a hash function h that maps each of the N elements to at least $\log_2 N$ bits
- For each stream element a , let $r(a)$ be the number of trailing 0s in $h(a)$
 - $r(a)$ = position of first 1 counting from the right
 - E.g., say $h(a) = 12$, then 12 is 1100 in binary, so $r(a) = 2$
- Record R = the maximum $r(a)$ seen
 - $R = \max_a r(a)$, over all the items a seen so far
- Estimated number of distinct elements = 2^R

Why It Works: Intuition

- Very very rough and heuristic intuition why Flajolet-Martin works:
 - $h(a)$ hashes a with equal prob. to any of N values
 - Then $h(a)$ is a sequence of $\log_2 N$ bits, where 2^{-r} fraction of all a s have a tail of r zeros
 - About 50% of a s hash to $***0$
 - About 25% of a s hash to $**00$
 - So, if we saw the longest tail of $r=2$ (i.e., item hash ending $*100$) then we have probably seen **about 4** distinct items so far
 - **So, it takes to hash about 2^r items before we see one with zero-suffix of length r**

Why It Works: More formally

- Now we show why Flajolet-Martin works
- Formally, we will show that **probability of finding a tail of r zeros:**
 - Goes to **1** if $m \gg 2^r$
 - Goes to **0** if $m \ll 2^r$

where m is the number of distinct elements seen so far in the stream

- **Thus, 2^R will almost always be around m !**

Why It Works: More formally

- What is the probability that a given $h(a)$ ends in at least r zeros is 2^{-r}
 - $h(a)$ hashes elements uniformly at random
 - Probability that a random number ends in at least r zeros is 2^{-r}
- Then, the probability of **NOT** seeing a tail of length r among m elements:

$$(1 - 2^{-r})^m$$

Prob. all end in fewer than r zeros.

Prob. that given $h(a)$ ends in fewer than r zeros

Why It Works: More formally

- **Note:** $(1 - 2^{-r})^m = (1 - 2^{-r})^{2^r (m2^{-r})} \approx e^{-m2^{-r}}$
- **Prob. of NOT finding a tail of length r is:**
 - If $m \ll 2^r$, then prob. tends to **1**
 - $(1 - 2^{-r})^m \approx e^{-m2^{-r}} = 1$ as $m/2^r \rightarrow 0$
 - So, the probability of finding a tail of length r tends to **0**
 - If $m \gg 2^r$, then prob. tends to **0**
 - $(1 - 2^{-r})^m \approx e^{-m2^{-r}} = 0$ as $m/2^r \rightarrow \infty$
 - So, the probability of finding a tail of length r tends to **1**
- **Thus, 2^R will almost always be around m !**

Why It Doesn't Work

- $E[2^R]$ is actually infinite
 - Probability halves when $R \rightarrow R+1$, but value doubles
- Workaround involves using many hash functions h_i and getting many samples of R_i
- How are samples R_i combined?
 - Average? What if one very large value 2^{R_i} ?
 - Median? All estimates are a power of 2
 - Solution:
 - Partition your samples into small groups
 - Take the median of groups
 - Then take the average of the medians

(3) Computing Moments

Generalization: Moments

- Suppose a stream has elements chosen from a set A of N values
- Let m_i be the number of times value i occurs in the stream
- The k^{th} *moment* is

$$\sum_{i \in A} (m_i)^k$$

Special Cases

$$\sum_{i \in A} (m_i)^k$$

- **0th moment** = number of distinct elements
 - The problem just considered
- **1st moment** = count of the numbers of elements = length of the stream
 - Easy to compute
- **2nd moment** = *surprise number S* =
a measure of how uneven the distribution is

Example: Surprise Number

- Stream of length 100
- 11 distinct values
- Item counts: 10, 9, 9, 9, 9, 9, 9, 9, 9, 9, 9
Surprise $S = 910$
- Item counts: 90, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1
Surprise $S = 8,110$

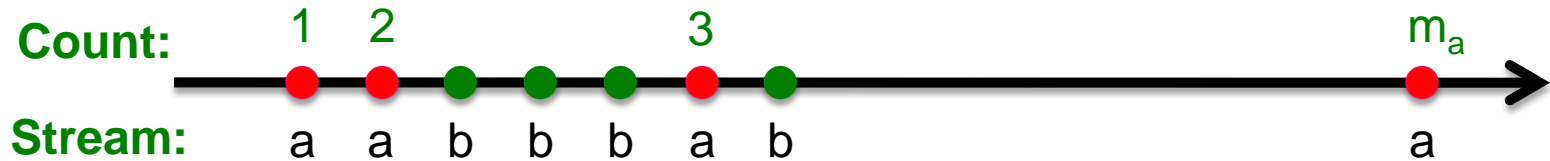
AMS Method

- AMS method works for all moments
- Gives an unbiased estimate
- We will just concentrate on the 2nd moment S
- We keep track of many variables X :
 - For each variable X we store $X.el$ and $X.val$
 - $X.el$ corresponds to the item i
 - $X.val$ corresponds to the **count** of item i
 - Note this requires a count in main memory, so number of X s is limited
- Our goal is to compute $S = \sum_i m_i^2$

One Random Variable (X)

- **How to set $X.val$ and $X.el$?**
 - Assume stream has length n (we relax this later)
 - Pick some random time t ($t < n$) to start, so that any time is equally likely
 - Let at time t the stream have item i . **We set $X.el = i$**
 - Then we maintain count c (**$X.val = c$**) of the number of i s in the stream starting from the chosen time t
- **Then the estimate of the 2nd moment ($\sum_i m_i^2$) is:**
$$S = f(X) = n(2 \cdot c - 1)$$
 - Note, we will keep track of multiple \mathbf{X} s, (X_1, X_2, \dots, X_k) and our final estimate will be **$S = 1/k \sum_j^k f(X_j)$**

Expectation Analysis



- **2nd moment is $S = \sum_i m_i^2$**
- **c_t ... number of times item at time t appears from time t onwards ($c_1=m_a, c_2=m_a-1, c_3=m_b$)**

- **$E[f(X)] = \frac{1}{n} \sum_{t=1}^n n(2c_t - 1)$**

$$= \frac{1}{n} \sum_i n (1 + 3 + 5 + \dots + 2m_i - 1)$$

m_i ... total count of item i in the stream (we are assuming stream has length n)

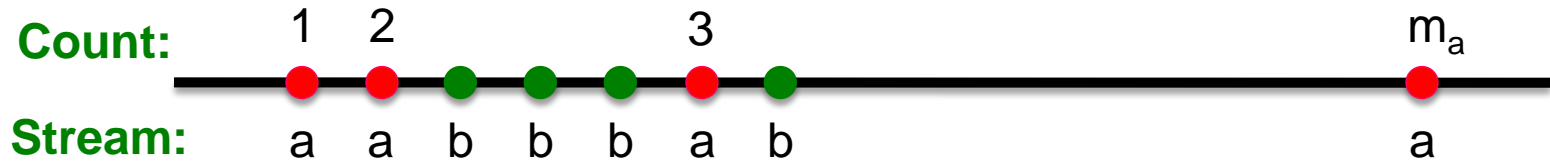
Group times by the value seen

Time t when the last i is seen ($c_t=1$)

Time t when the penultimate i is seen ($c_t=2$)

Time t when the first i is seen ($c_t=m_i$)

Expectation Analysis



- $E[f(X)] = \frac{1}{n} \sum_i n (1 + 3 + 5 + \dots + 2m_i - 1)$
 - Little side calculation: $(1 + 3 + 5 + \dots + 2m_i - 1) = \sum_{i=1}^{m_i} (2i - 1) = 2 \frac{m_i(m_i+1)}{2} - m_i = (m_i)^2$
- Then $E[f(X)] = \frac{1}{n} \sum_i n (m_i)^2$
- So, $E[f(X)] = \sum_i (m_i)^2 = S$
- We have the second moment (in expectation)!

Higher-Order Moments

- For estimating k^{th} moment we essentially use the same algorithm but change the estimate:
 - For $k=2$ we used $n (2 \cdot c - 1)$
 - For $k=3$ we use: $n (3 \cdot c^2 - 3c + 1)$ (where $c=X.\text{val}$)
- Why?
 - For $k=2$: Remember we had $(1 + 3 + 5 + \dots + 2m_i - 1)$ and we showed terms $2c-1$ (for $c=1, \dots, m$) sum to m^2
 - $\sum_{c=1}^m 2c - 1 = \sum_{c=1}^m c^2 - \sum_{c=1}^m (c - 1)^2 = m^2$
 - So: $2c - 1 = c^2 - (c - 1)^2$
 - For $k=3$: $c^3 - (c-1)^3 = 3c^2 - 3c + 1$
- Generally: Estimate = $n (c^k - (c - 1)^k)$

Combining Samples

■ In practice:

- Compute $f(X) = n(2c - 1)$ for as many variables X as you can fit in memory
- Average them in groups
- Take median of averages

■ Problem: Streams never end

- We assumed there was a number n , the number of positions in the stream
- But real streams go on forever, so n is a variable – the number of inputs seen so far

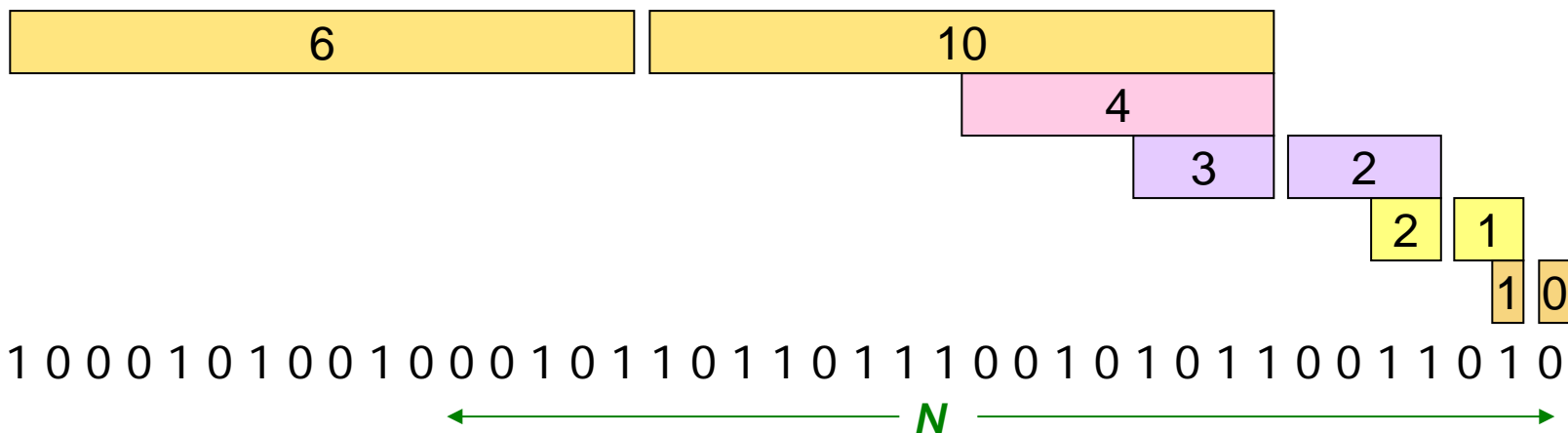
Streams Never End: Fixups

- (1) The variables X have n as a factor – keep n separately; just hold the count in X
- (2) Suppose we can only store k counts. We must throw some X s out as time goes on:
 - **Objective:** Each starting time t is selected with probability k/n
 - **Solution: (fixed-size sampling!)**
 - Choose the first k times for k variables
 - When the n^{th} element arrives ($n > k$), choose it with probability k/n
 - If you choose it, throw one of the previously stored variables X out, with equal probability

Counting Itemsets

Counting Itemsets

- New Problem: Given a stream, which items appear more than s times in the window?
- **Possible solution**: Think of the stream of baskets as one binary stream per item
 - **1** = item present; **0** = not present
 - Use **DGIM** to estimate counts of **1s** for all items



Extensions

- In principle, you could count frequent pairs or even larger sets the same way
 - One stream per itemset
- Drawbacks:
 - Only approximate
 - Number of itemsets is way too big

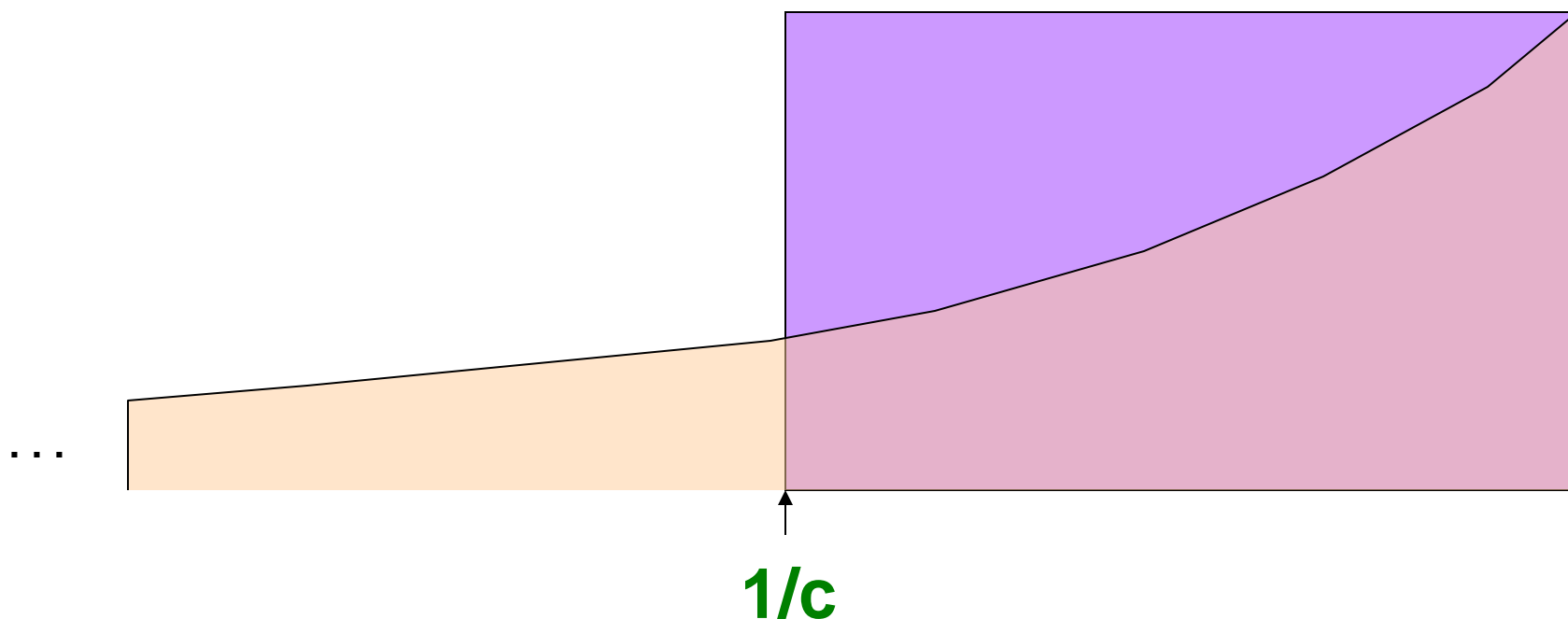
Exponentially Decaying Windows

- **Exponentially decaying windows: A heuristic for selecting likely frequent item(sets)**
 - **What are “currently” most popular movies?**
 - Instead of computing the raw count in last N elements
 - Compute a **smooth aggregation** over the whole stream
- If stream is a_1, a_2, \dots and we are taking the sum of the stream, take the answer at time t to be:
$$= \sum_{i=1}^t a_i (1 - c)^{t-i}$$
 - c is a constant, presumably tiny, like 10^{-6} or 10^{-9}
- **When new a_{t+1} arrives:**
Multiply current sum by $(1-c)$ and add a_{t+1}

Example: Counting Items

- If each a_i is an “item” we can compute the **characteristic function** of each possible item x as an Exponentially Decaying Window
 - That is: $\sum_{i=1}^t \delta_i \cdot (1 - c)^{t-i}$
where $\delta_i=1$ if $a_i=x$, and 0 otherwise
 - Imagine that for each item x we have a binary stream (1 if x appears, 0 if x does not appear)
 - **New item x arrives:**
 - Multiply all counts by $(1-c)$
 - Add $+1$ to count for element x
- **Call this sum the “weight” of item x**

Sliding Versus Decaying Windows



- **Important property:** Sum over all weights $\sum_t (1 - c)^t$ is $1/[1 - (1 - c)] = 1/c$

Example: Counting Items

- What are “currently” most popular movies?
- Suppose we want to find movies of weight $> \frac{1}{2}$
 - **Important property:** Sum over all weights $\sum_t (1 - c)^t$ is $1/[1 - (1 - c)] = 1/c$
- **Thus:**
 - There cannot be more than $2/c$ movies with weight of $\frac{1}{2}$ or more
- So, $2/c$ is a limit on the number of movies being counted at any time

Extension to Itemsets

- **Count (some) itemsets in an E.D.W.**
 - What are currently “hot” itemsets?
 - **Problem:** Too many itemsets to keep counts of all of them in memory
- **When a basket **B** comes in:**
 - Multiply all counts by **(1-c)**
 - For uncounted items in **B**, create new count
 - Add **1** to count of any item in **B** and to any **itemset** contained in **B** that is already being counted
 - **Drop counts $< \frac{1}{2}$**
 - Initiate new counts (next slide)

Initiation of New Counts

- Start a count for an itemset $S \subseteq B$ if every proper subset of S had a count prior to arrival of basket B
 - **Intuitively:** If all subsets of S are being counted this means they are “frequent/hot” and thus S has a potential to be “hot”
- **Example:**
 - Start counting $S=\{i, j\}$ iff both i and j were counted prior to seeing B
 - Start counting $S=\{i, j, k\}$ iff $\{i, j\}$, $\{i, k\}$, and $\{j, k\}$ were all counted prior to seeing B

How many counts do we need?

- Counts for single items $< (2/c) \cdot (\text{avg. number of items in a basket})$
- Counts for larger itemsets = ??
- But we are conservative about starting counts of large sets
 - If we counted every set we saw, one basket of **20** items would initiate **1M** counts